

Designing a traffic light controller

Lab 2, ESDM

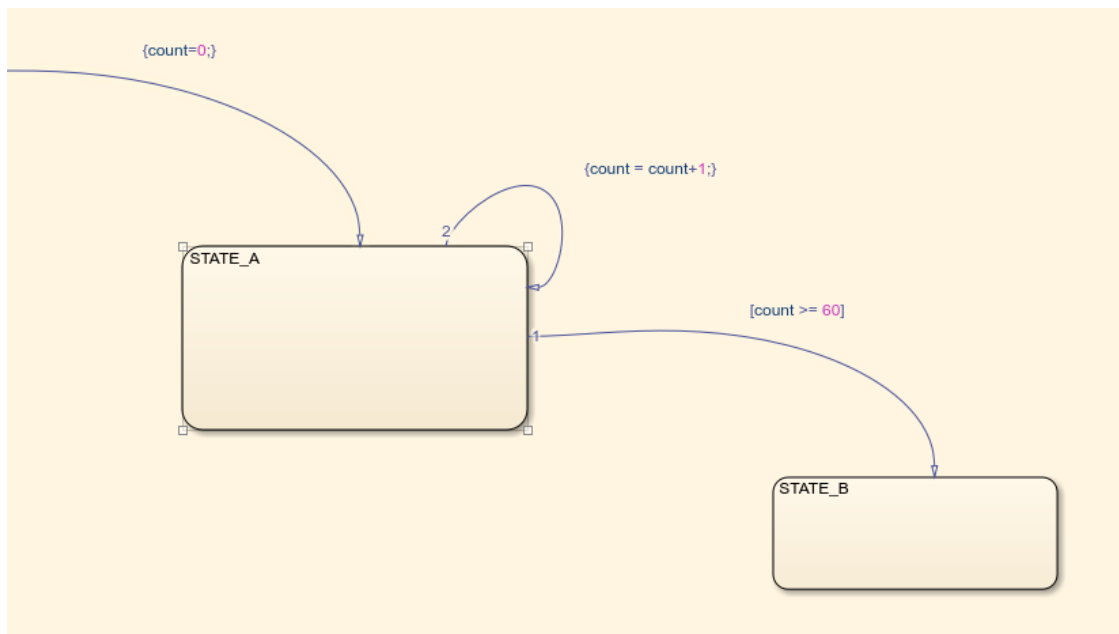
Objective

Introducing students to the Simulink environment and the Stateflow component.

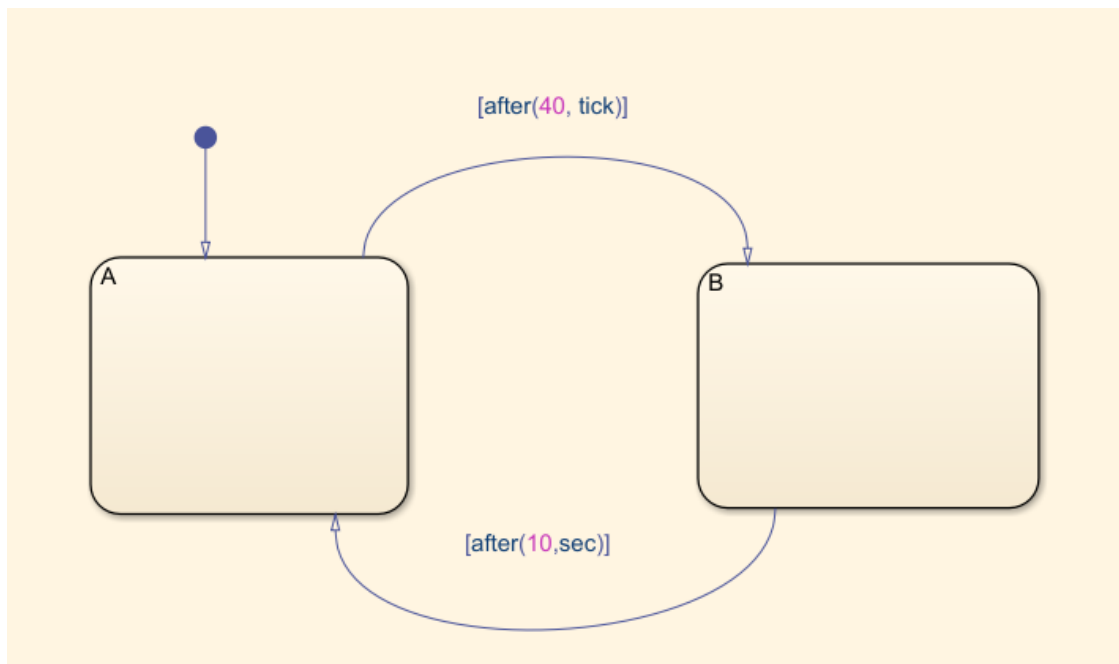
Theoretical aspects

How to measure time in a Stateflow model:

1. Use a counter variable:



2. Use one of the special temporal operators: `after()`, `on()`, etc.



The special variables used with temporal operators:

- use `sec` to count **seconds** (`[after(5,sec)]`)
- use `msec` to count **milliseconds** (`[after(250,msec)]`)
- use `tick` to count **ticks**, i.e. **time steps** (`[after(30,tick)]`). The time step is configured in the Model Settings.

Exercises

1. Create a model for a car traffic light controller, according to the specifications below.

Model specifications

The model shall control the light of a car traffic light.

Inputs:

- `button`: boolean. Button available for pedestrians to press, when they want to cross the street

Outputs:

- `sigR`: boolean. Control RED light. TRUE to turn on red light, FALSE to turn it off.

- sigY: boolean. Control YELLOW light. TRUE to turn on yellow light, FALSE to turn it off.
- sigG: boolean. Control GREEN light. TRUE to turn on green light, FALSE to turn it off.

Requirements:

- Red light lasts for 30 seconds.
 - Red light is followed by green light.
 - Green light lasts at least 60 seconds.
 - If no pedestrian presses the button, green light lasts indefinitely.
 - If a pedestrian presses the button, green is followed by yellow:
 - If the button is pressed during the first 60 seconds of green, yellow happens after the 60 seconds expire
 - If the button is pressed after the first 60 seconds, yellow happens immediately
 - Yellow light lasts for 5 seconds, and is followed by red
 - Upon initialization, the system defaults to red
2. Extend the model in the following way:
- Add two new outputs for the pedestrian traffic light as well. The pedestrians are shown only red and green: they have when cars have green or yellow, and green when cars have green.
 - Make the yellow light blinking (1 second on, 1 second off).
 - Make the last 8 seconds of pedestrian green blinking.

General requirements

- Model Settings: Set the Solver type to “Fixed-step”, “discrete (no continuous states)”, and fixed step size to 0.1 (see Fig.1)
- Run the model for 120 seconds, use “Simulation Pacing” to have simulation time 3-4x faster than normal time (see Fig.2)
- Put all inputs and outputs into a Scope block, for visualization (see Fig.3)
- Attach a “Push Button” from the Dashboard group as the input button (see Fig.3)
- Attach three “Lamp” blocks from the Dashboard group as the output (see Fig.3)

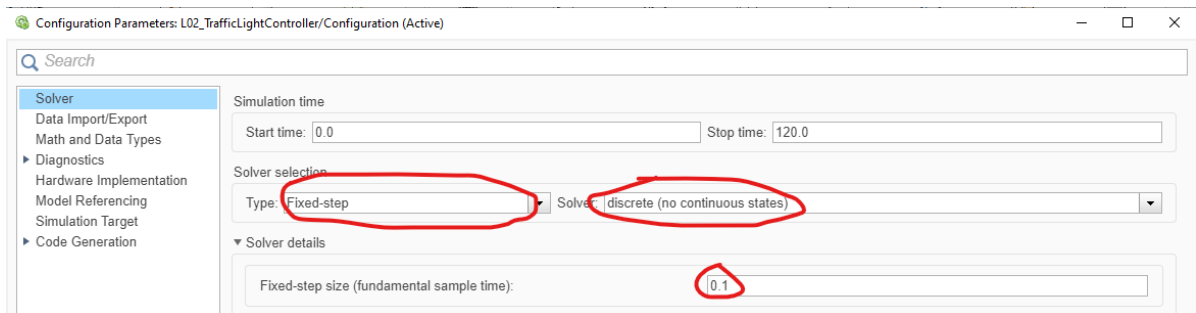


Figure 1: Model Settings

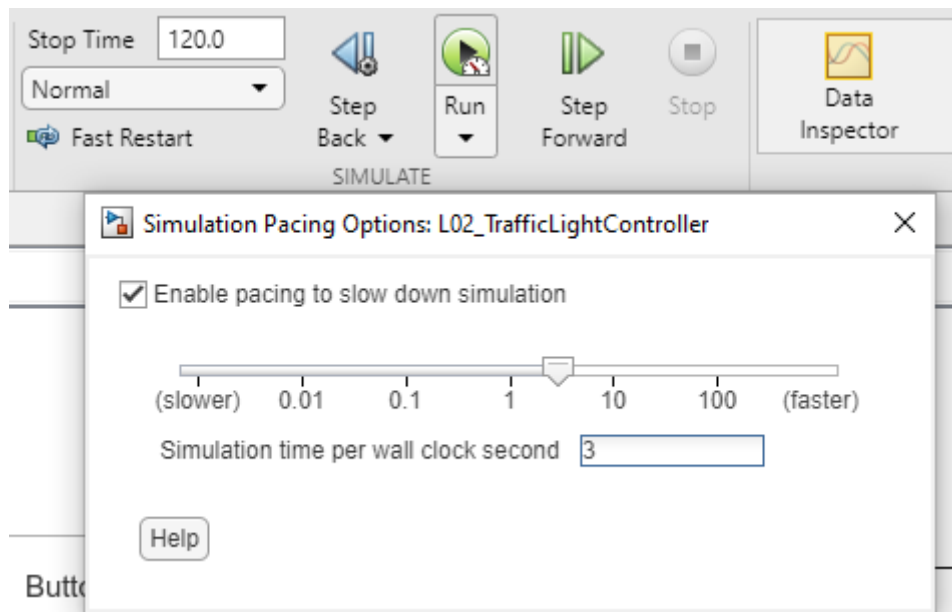


Figure 2: Simulation time

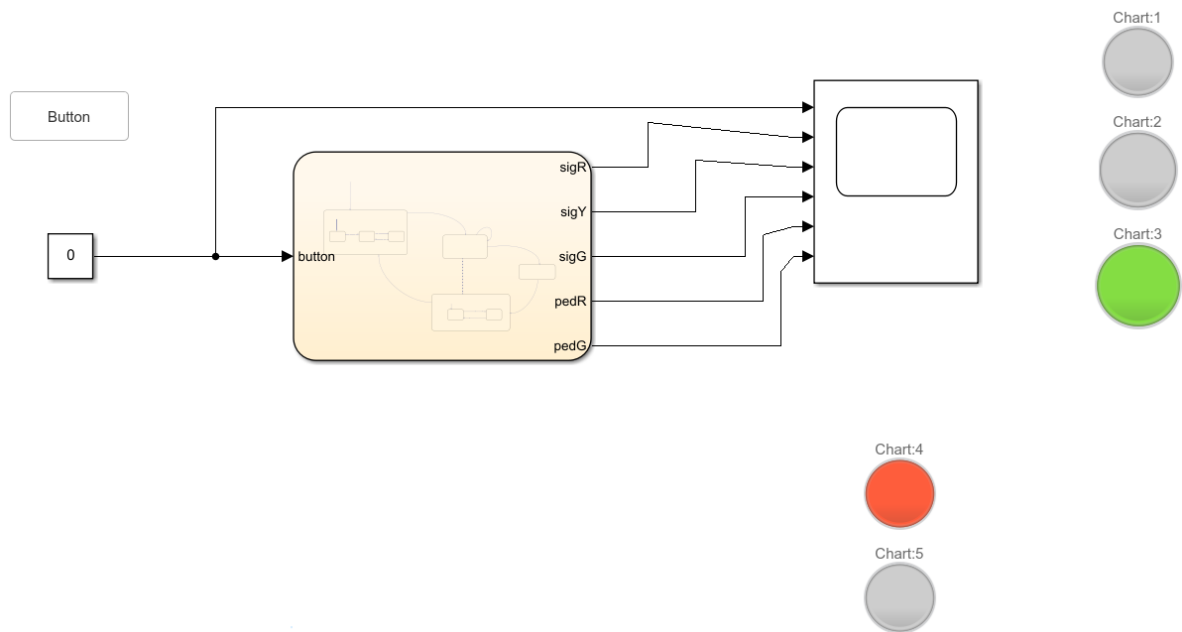


Figure 3: Desired overview

Final questions

1. TBD