

Chapter structure

Chapter structure

- 1. General presentation
- 2. Analyzing linear block codes with the Hamming distance
- 3. Analyzing linear block codes with matrix algebra
- 4. Hamming codes
- 5. Cyclic codes

What is error control coding?

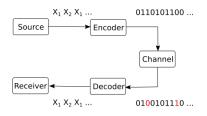


Figure 1: Communication system

- ▶ The second main task of coding: error control
- Protect information against channel errors

The need for error control coding

- ▶ In a transmission, the bits go through a transmission channel
 - ▶ The transmission channel is not ideal, it introduces some bit errors
 - Usually it is required that all bits are received correctly, no errors are allowed
- So what do to? Error control coding

Modelling the errors on the channel

- ightharpoonup We consider only binary codes/ channels (symbols = $\{0,1\}$)
- ► An **error** = a bit that has changed from 0 to 1 or viceversa while going through channel
- Errors can appear:
 - independently: sporadic errors, each bit has a random chance of error, independent of all the others
 - in packets of errors: groups of consecutive errors

Modelling the errors on the channel

- ► Changing the value of a bit = modulo-2 sum with 1
- ▶ Value of a bit remains the same = modulo-2 sum with 0

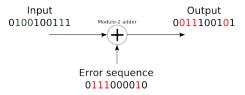


Figure 2: Channel error model

- Channel model we use (simple):
 - ► The transmitted sequence is summed modulo-2 with an **error sequence**

Modelling the errors on the channel

- ► Channel model we use (simple):
 - ▶ The transmitted sequence is summed modulo-2 with an **error sequence**
 - ► Error sequence has same length as the transmitted sequence
 - ▶ Where the error sequence is 1, there is a bit error
 - ▶ Where the error sequence is 0, there is no error

$$\mathbf{r} = \mathbf{c} \oplus \mathbf{e}$$

Mathematical properties of modulo-2 arithmetic

- ▶ Product is the same as for normal arithmetic
- Multiplication is distributive just like in normal case

$$a(b \oplus c) = ab \oplus ac$$

► Subtraction = addition. There is no negativation. Each number is its own negative

$$a \oplus a = 0$$

Error detection vs correction

What can we do about errors?

- **Error detection**: find out if there is any error in the received sequence
 - don't know exactly where, so cannot correct the bits, but can discard whole sequence
 - perhaps ask the sender to retransmit (examples: TCP/IP, internet communication etc)
 - easier to do
- ▶ Error correction: find out exactly which bits have errors, if any
 - ▶ locating the error = correcting error (for binary channels)
 - can correct all errored bits by inverting them
 - useful when can't retransmit (data is stored: on HDD, AudioCD etc.)
 - harder to do than mere detection

Overview of error control coding process

The process of error control:

1. Want to send a sequence of k bits = **information word**

$$\mathbf{i} = i_1 i_2 ... i_k$$

2. For each possible information word, the coder assigns a **codeword** of length n > k:

$$\mathbf{c} = c_1 c_2 ... c_n$$

- 3. The codeword is sent on the channel instead of the original information word
- 4. The receiver receives a sequence $\hat{\mathbf{c}} \approx \mathbf{c}$, with possible errors:

$$\hat{\mathbf{c}} = \hat{c_1}\hat{c_2}...\hat{c_n}$$

5. The decoding algorithm detects/corrects the errors in $\hat{\mathbf{c}}$

Definitions

- An error correcting code is an association between the set of all possible information words to a set of codewords
 - Each possible information word i has a certain codeword c
- ► The association can be done:
 - randomly: codewords are selected and associated randomly to the information words
 - based on a certain rule: the codeword is computed with some algorithm from the information word
- ► A code is a **block code** if it operates with words of *fixed size*
 - Size of information word i = k, size of codeword c = n, n > k
 - Otherwise it is a non-block code
- A code is linear if any linear combination of codewords is also a codeword

Definitions

- ➤ A code is called **systematic** if the codeword contains all the information bits explicitly, unaltered
 - coding merely adds supplementary bits besides the information bits
 - codeword has two parts: the information bits and the parity bits
 - example: parity bit added after the information bits
- ▶ Otherwise the code is called **non-systematic**
 - ▶ the information bits are not explicitly visible in the codeword
- ► The **coding rate** of a code is:

$$R = k/n$$

Definitions

- ► A code *C* is an *t*-**error**-**detecting** code if it is able to **detect** *t* or less errors
- ► A code *C* is an *t*-**error-correcting** code if it is able to **correct** *t* or less errors
- Examples: at blackboard

A first example: parity bit

- Add parity bit to a 8-bit long information word, before sending on a channel
 - ightharpoonup coding rate R = 8/9
 - can detect 1 error in a 9-bit codeword
 - detection algorithm: check if parity bit matches data
 - ▶ fails for 2 errors
 - cannot correct error (don't know where it is located)
- Add more parity bits to be able to locate the error
 - Example at blackboard
 - ightharpoonup coding rate R = 8/12
 - can detect and correct 1 error in a 9-bit codeword

A second example: repetition code

- Repeat same block of data n times
 - want to send a k-bit information word
 - ightharpoonup codeword to send = the information word repeated n = 5 times
 - ightharpoonup coding rate R = k/n = 1/5
 - can detect and correct 2 errors, and maybe even more if they do not affect the same bit
 - error correcting algorithm = majority rule
 - not very efficient

Redundancy

- Merriam-Webster: "redundant" definition:
 - a. exceeding what is necessary or normal: superfluous
 - b. characterized by or containing an excess; specifically : using more words than necessary
- \triangleright Because k < n, error control coding introduces **redundancy**
 - \blacktriangleright to transmit k bits of information we actually send more bits (n)

Redundancy

- ► Error control coding adds redundancy, while source coding aims to reduce redundancy. Contradiction?
- No:
 - Source coding reduces existing redundancy from the data, which served no purpose
 - Error control coding adds redundancy in a controlled way, with a purpose
- Source coding and error control coding in practice: do sequentially, independently
 - First perform source coding, eliminating redundancy in representation of data
 - 2. Then perform error control coding, adding redundancy for protection

Transmission channels preview

- ► In Chapter IV we will study Transmission Channels = mathematical model of how information is handled from the sender to the receiver
- ► Each channel has a certain **capacity** value = the maximum amount of information than can be sent over the channel
 - ightharpoonup e.g. a channel may have capacity C=0.8 bits
- More about this in Chapter IV

Shannon's noisy channel theorem (second theorem, channel coding theorem)

▶ A coding rate is called **achievable** for a channel if, for that rate, there exists a coding and decoding algorithm guaranteed to correct all possible errors on the channel

Shannon's noisy channel coding theorem (second theorem)

For a given channel, all rates below capacity R < C are achievable. All rates above capacity, R > C, are not achievable.

Channel coding theorem explained

In layman terms:

- For all coding rates R < C, there is a way to recover the transmitted data perfectly (decoding algorithm will detect and correct all errors)
- ▶ For all coding rates R > C, there is no way to recover the transmitted data perfectly

Channel coding theorem example

- ▶ We send bits on a channel with capacity 0.7 bits/message
- ightharpoonup For any coding rate R < 0.7 there exists an error correction code that allows fixing of all errors
 - ho R < 0.7 means we send more than 10 bits for every 7 information bits, on average
- ▶ With less than 10 bits for every 7 information bits => no code exists that can fix all errors
- ► The theorem makes it clear when it is possible to fix all errors, and guarantees that a code exists in this case

Ideas behind channel coding theorem

- The rigorous proof of the theorem is too complex to present
- ► Key ideas of the proof:
 - ▶ Use very long information words, $k \to \infty$
 - Use random codes, compute the probability of having error after decoding
 - If R < C, in average for all possible codes, the probability of error after decoding goes to 0
 - ▶ If the average for all codes goes to 0, there exists at least on code better than the average
 - ► That is the code we should use

Ideas behind channel coding theorem

- ► The theorem does not tell what code to use, only that some code exists
 - ▶ There is no clue of how to actually find the code in practice
 - Only some general principles:
 - using longer information words is better
 - random codewords are generally good
- ▶ In practice, we cannot use infinitely long codewords, so we will only get a good enough code

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Distance between codewords

Practical ideas for error correcting codes:

- ▶ If a codeword c₁ has errors and thus becomes identical to another codeword c₂ ==> cannot detect any errors
 - \blacktriangleright Receiver will think it received a correct codeword $c_2,$ but actually it was c_1
- ▶ We want codewords as different as possible from each other
- ▶ How to measure this difference? **Hamming distance**

Hamming distance

▶ The **Hamming distance** of two binary sequences \mathbf{a} , \mathbf{b} of length n = the total number of bit differences between them

$$d_H(\mathbf{a},\mathbf{b})=\sum_{i=1}^N a_i\oplus b_i$$

- We need at least $d_H(a, b)$ bit changes to convert one sequence into another
- Example at blackboard

Hamming distance

- ▶ It satisfies the 3 properties of a metric function:
 - 1. $d_H(\mathbf{a}, \mathbf{b}) \ge 0 \quad \forall \mathbf{a}, \mathbf{b}$, with $d_H(\mathbf{a}, \mathbf{b}) = 0 \Leftrightarrow \mathbf{a} = \mathbf{b}$
 - 2. $d_H(\mathbf{a}, \mathbf{b}) = d_H(\mathbf{b}, \mathbf{a}), \forall \mathbf{a}, \mathbf{b}$
 - 3. $d_H(\mathbf{a}, \mathbf{c}) \leq d_H(\mathbf{a}, \mathbf{b}) + d_H(\mathbf{b}, \mathbf{c}), \forall \mathbf{a}, \mathbf{b}, \mathbf{c}$
- ▶ The minimum Hamming distance of a code, $d_{Hmin} = \text{the}$ minimum Hamming distance between any two codewords $\mathbf{c_1}$ and $\mathbf{c_2}$

Nearest-neighbor decoding scheme

Coding:

- ▶ Design a code with large d_{Hmin}
- ► Send a codeword **c** of the code

Decoding:

- Receive a word **r**, that may have errors
- Error detecting:
 - check if r is part of the codewords of the code C:
 - ▶ if *r* is part of the code, decide that there have been no errors
 - if r is not a codeword, decide that there have been errors
- Error correcting:
 - if **r** is a codeword, decide there are no errors
 - else, choose codeword nearest to the received r, in terms of Hamming distance
 - this is known as nearest-neighbor decoding

Performance of nearest neighbor decoding

Theorem:

- ▶ If the minimum Hamming distance of a code is d_{Hmin} , then:
 - 1. the code can detect up to $d_{H_{min}} 1$ errors
 - 2. the code can *correct* up to $\left\lfloor \frac{d_{Hmin}-1}{2} \right\rfloor$ errors using nearest-neighbor decoding

Consequence:

- ▶ It is good to have $d_{H_{min}}$ as large as possible
 - ► This implies longer codewords, i.e. smaller coding rate, i.e. more redundancy

Performance of nearest neighbor decoding

Proof:

- 1. at least d_{Hmin} binary changes are needed to change one codeword into another, $d_{Hmin} 1$ is not enough => the errors are detected
- 2. the received word \mathbf{r} is closer to the original codeword than to any other codeword => nearest-neighbor algorithm will find the correct one
 - ightharpoonup because $\left\lfloor \frac{d_{Hmin}-1}{2} \right\rfloor =$ less than half the distance to another codeword

Note: if the number of errors is higher, can fail:

- ▶ Detection failure: decide that there were no errors, even if they were (more than $d_{Hmin} 1$)
- Correction failure: choose a wrong codeword

Example: blackboard

Computational complexity

- Computational complexity = the amount of computational resources required by an algorithm
 - only refers to the order of magnitude of the dominant term
 - neglects the other terms
 - neglects actual coefficient values in front
- ▶ Computational complexity with respect to number of information bits k, of the search-based nearest neighbor decoding (as presented earlier), is

$$\mathcal{O}(k) = 2^k$$

Proof: Requires comparing with all codewords, and there are 2^k codewords in total

Computational complexity

- ► This implementation is very inefficient
 - k doubles => the amount of computations is squared
 - \triangleright k increases 10 times => computations are raised to a power of 10
 - \blacktriangleright k increases 100 times => computations are raised to a power of 1000
 - for k = 256 you'd need all the energy of the Sun
- Need to find ways to make it simpler

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Review of basic algebra

Informal definitions:

- ▶ **Vector space** = a set such that:
 - a. one element + another element = still an element from the set
 - b. one element \times a constant = still an element from the set
 - Examples: Euclidian vector spaces: a line, points in 2D, 3D
 - Elements are called "vectors"
- **Basis** = a set of n independent vectors $\mathbf{e_1}, ... \mathbf{e_n}$
 - Any vector v can be expressed as a linear combination of the basis elements

$$\mathbf{v} = \mathbf{e_1} \cdot \alpha_1 + \dots + \mathbf{e_n} \cdot \alpha_n$$

Review of basic algebra

- ➤ **Subspace** = a smaller dimensional vector space inside a larger vector space
 - Examples: a line in a plane
 - sum of two vectors on a line = still on the line
 - ▶ size of subspace = 1
 - ▶ size of larger space = 2
 - A plane in 3D space
 - sum of two vectors from the plane = still on the plane
 - ▶ size of subspace = 2
 - ► size of larger space = 3

Binary sequences form a vector space

- ightharpoonup The set of all binary sequences of size n is a vector space of size n
 - \triangleright sum of two sequences of size n is still a sequence of size n
- ▶ The sum operation = modulo-2 sum \oplus
- ightharpoonup Multiplication with 0 and 1 = as in usual arithmetic

How to look at matrix-vector multiplications

- Matrix-vector multiplication
 - ▶ Output vector = linear combination of the matrix columns
- ► Vector-matrix multiplication
 - Output vector = linear combination of the matrix rows
- Explain at the blackboard, draw picture

How to look at matrix-vector multiplications

- Vector spaces can be perfectly described with matrix-vector multiplications
 - ► Matrix columns/rows = elements of the basis
 - ► The output vector = the vector
 - ▶ The multiplicated vector = the coefficients of the linear combination
- ► Any vector **v** can be expressed as a linear combination of the basis elements

$$\mathbf{v} = \mathbf{e_1} \cdot \alpha_1 + \ldots + \mathbf{e_n} \cdot \alpha_n$$

$$\mathbf{v} = \begin{bmatrix} \mathbf{e_1} & \mathbf{e_2} & \dots & \mathbf{e_n} \end{bmatrix} \begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \dots \\ \alpha_n \end{bmatrix}$$

- ► e₁,...e_n are column vectors
- ► Equation can be transposed => all vectors become row vectors

Codewords form a vector space

- ► The set of all binary codewords of a linear block code is a vector subspace of dimension *k*
- ► Proof:
 - code is linear => because sum (XOR) of two codewords is still a codeword
 - ightharpoonup codeword imes a constant (0 or 1) => still a codeword
 - \blacktriangleright total number of codewords is $2^k =>$ dimension is k
- ▶ Length of codewords is n, but size of space is k => they form a subspace of the larger space of all binary sequences of length n

Codewords form a vector space

- ➤ Since all codewords form a (sub)space => all codewords can be expressed as matrix-vector multiplications
- ▶ Need to find a basis for the codewords

Generator matrix

► All codewords for a linear block code can be generated via a matrix-vector multiplication:

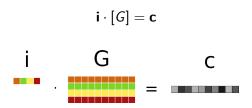


Figure 3: Codeword construction with generator matrix

- ▶ [G] = **generator matrix** of size $k \times n$ ("fat" matrix, k < n)
 - it is fixed, it fully defines the whole code

Generator matrix

- Row-wise interpretation:
 - Any codeword $\mathbf{c} = \mathbf{a}$ linear combination of rows in [G]
 - ightharpoonup The rows of [G] = a basis for the linear block code
 - Could also be transposed, i.e. use column vectors instead
- ▶ All operations are done in modulo-2 arithmetic
- ► There exists a separate codeword for all possible information words i

Proof of linearity

▶ Prove that a codeword + another codeword = also codeword:

$$\begin{aligned} \textbf{i}_1\cdot[\textit{G}] &= \textbf{c}_1\\ \textbf{i}_2\cdot[\textit{G}] &= \textbf{c}_2\\ \textbf{c}_1\oplus\textbf{c}_2 &= (\textbf{i}_1\oplus\textbf{i}_2)\cdot[\textit{G}] = \textit{codeword} \end{aligned}$$

Parity check matrix

Every generator matrix [G] has a related parity-check matrix [H] such that

$$\mathbf{0} = [H] \cdot [G]^T$$

- also known as control matrix
- ▶ size of [H] is $(n k) \times n$
- ▶ [G] and [H] are related, one can be deduced from the other
- ► [H] is very useful to check if a binary word is a codeword or not (i.e. for nearest neighbor error detection)

Using the parity check matrix

▶ Theorem: every codeword \mathbf{c} generated with [G] ($\mathbf{i} \cdot [G] = \mathbf{c}$) will produce a 0 vector when multiplied with the corresponding [H] matrix:

$$\mathbf{0} = [H] \cdot \mathbf{c}^T$$

► Proof:

$$\mathbf{i} \cdot [G] = \mathbf{c}$$

$$[G]^T \cdot \mathbf{i}^T = \mathbf{c}^T$$

$$[H] \cdot \mathbf{c}^T = [H] \cdot [G]^T \cdot \mathbf{i}^T = \mathbf{0}$$

- ► All codewords generated with [G] will produce 0 when multiplied with [H]
- ▶ All binary sequences that are not codewords will produce \neq 0 when multiplied with [H]

Relation between [G] and [H]

- ► [G] and [H] are related
 - ► The codewords form a k-dimensional subspace inside the larger n-dimensional vector space
 - ► The rows of [H] are the "missing" dimensions of the subspace (the "orthogonal complement")
- ▶ Together [G] and [H] form a full square matrix $n \times n$, which is a basis for the full n-dimensional vector space
 - ▶ size of [H] is $(n-k) \times n$
 - ightharpoonup size of [G] is $k \times n$
- Examples:
 - line in a 2D plane, has one orthogonal dimension
 - plane in 3D space, has one orthogonal dimension
 - line in 3D space, has 2 orthogonal dimension

Standard [G] and [H] for systematic codes

- For systematic codes, [G] and [H] have special forms (known as "standard" forms)
- Generator matrix
 - ► first part = identity matrix
 - second part = some matrix Q

$$[G]_{k\times n}=[I_{k\times k}\ Q_{k\times (n-k)}]$$

- Parity-check matrix
 - first part = same Q, but transposed
 - second part = identity matrix

$$[H]_{(n-k)\times n} = [Q_{(n-k)\times k}^T \ I_{(n-k)\times (n-k)}]$$

- ► Can easily compute one from the other
- Example at blackboard

Interpretation as parity bits

- ightharpoonup Multiplication with G in standard form produces the codeword as
 - first part = information bits (since first part of [G] is identity matrix)
 - ▶ additional bits = combinations of information bits = parity bits
- ▶ The additional bits added by coding are actually just parity bits
 - Proof: write the generation equations (example)
- ▶ Parity-check matrix in standard form [H] checks if parity bits correspond to information bits
 - ▶ Proof: write down the parity check equation (see example)
- ightharpoonup If all parity bits match the data, the result of multiplying with [H] is 0
 - ightharpoonup otherwise it is $\neq 0$

Interpretation as parity bits

- Generator & parity-check matrices are just mathematical tools for easy computation and checking of parity bits
- We're still just computing and checking parity bits, but we do it easier with matrices

Syndrome

- Nearest neighbor error detection = check if received word r is a codeword
- ▶ We do this easily by multiplying with [H]
- ▶ The resulting vector $z = [H] \cdot [r]^T$ is known as **syndrome**
- Column-wise interpretation of multiplication:

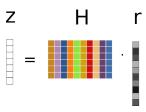


Figure 4: Codeword checking with parity-check matrix

Nearest neighbor error detection with matrices

Nearest neighbor error **detection** with matrices:

1. generate codewords with generator matrix:

$$\mathbf{i} \cdot [G] = \mathbf{c}$$

- 2. send codeword \mathbf{c} on the channel
- 3. a random error word e is applied on the channel
- 4. receive word $\mathbf{r} = \mathbf{c} \oplus \mathbf{e}$
- 5. compute **syndrome** of **r**:

$$\mathbf{z} = [H] \cdot \mathbf{r}^T$$

- 6. Decide:
 - ightharpoonup If z = 0 = r has no errors
 - ▶ If $\mathbf{z} \neq 0 = \mathbf{r}$ has errors

Nearest neighbor error correction with matrices

Nearest neighbor error **correction** with matrices:

- Syndrome $\mathbf{z} \neq 0 = \mathbf{r}$ has errors, we need to locate them
- ▶ The syndrome is the effect only of the error word:

$$z = [H] \cdot r^T = [H] \cdot (c^T \oplus e^T) = [H] \cdot e^T$$

- 7. Create a syndrome lookup table:
 - for every possible error word **e**, compute the syndrome $\mathbf{z} = [H] \cdot \mathbf{e}^T$
 - ▶ start with error words with 1 error (most likely), then with 2 errors (less likely), and so on
- 8. Locate the syndrome ${\bf z}$ in the table, read the corresponding error word $\widehat{{\bf e}}$
- 9. Find the correct word:
 - adding the error word again will invert the errored bits back to the originals

$$\hat{\mathbf{c}} = \mathbf{r} \oplus \hat{\mathbf{e}}$$

Example

Example: at blackboard

Computational complexity

- Computational complexity for error detection
 - ► Error detection = multiplication with [H]
 - ▶ Complexity is $\mathcal{O}(n^2)$ (size of [H] is $(n-k) \times n$
 - ► Much more efficient!
- Computational complexity for error correction
 - ▶ Need to check all possible error words => bad performance
 - In practice, other tricks are used to make it much faster (see Hamming codes for example)

Conditions on [H] for error detection and correction

- ► How to design a good matrix [H]?
- Conditions on [H] for successful error detection:
 - ▶ We can detect errors if the syndrome is **non-zero**
 - ► To detect a single error: every column of [H] must be non-zero
 - ► To detect two error: sum of any two columns of [H] cannot be zero
 - that means all columns are different
 - ▶ To detect n errors: sum of any n or less columns of [H] cannot be zero

Conditions on [H] for error detection and correction

- Conditions for syndrome-based error correction:
 - ▶ We can correct errors if the syndrome is **unique**
 - ▶ To correct a single error: all columns of [H] are different
 - ▶ so the syndromes, for a single error, are all different
 - To correct n errors: sum of any n or less columns of [H] are all different
 much more difficult to obtain than for decoding
- ► Conditions for error correction are more demanding than for detection
- ▶ Note: Rearranging the columns of [H] (the order of bits in the codeword) does not affect performance

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Hamming codes

- ► A particular class of linear error-correcting codes
- ▶ Definition: a **Hamming code** is a linear block code where the columns of [H] are the binary representation of all numbers from 1 to $2^r 1$, $\forall r \geq 2$
- Example (blackboard): (7,4) Hamming code
- ➤ Systematic: arrange the bits in the codeword, such that the control bits correspond to the columns having a single 1
 - no big difference from the usual systematic case, just a rearrangement of bits
 - makes implementation easier

Properties of Hamming codes

- ► From definition of [*H*] it follows:
 - 1. Codeword has length $n = 2^r 1$
 - 2. r bits are parity bits (also known as control bits)
 - 3. $k = 2^r r 1$ bits are information bits
- ► Notation: (n,k) Hamming code
 - ightharpoonup n = codeword length = $2^r 1$,
 - \triangleright k = number of information bits = $2^r r 1$
 - Example: (7,4) Hamming code, (15,11) Hamming code, (127, 120) Hamming code

Structure of a Hamming codeword

- ▶ The codeword contains information bits and parity (control) bits
- ► The control bits correspond to the columns of the parity-check matrix [H] which have a single 1 (i.e. columns which form the identity matrix)
- ► The information bits are placed in the remaining positions, where the columns of [H] have two or more 1s
- Codeword for Hamming(7,4):

$$c_1 c_2 i_3 c_4 i_5 i_6 i_7$$

Codeword for Hamming(15,11):

 $c_1c_2i_3c_4i_5i_6i_7c_8i_9i_{10}i_{11}i_{12}i_{13}i_{14}i_{15}$

Construction of Hamming codewords

- Every Hamming code has a generator matrix [G], but we don't provide it explicitly, because it is hard to remember
- Instead, we deduce the values from the equation system of the parity-check matrix [H], $\mathbf{0} = [H] \cdot \mathbf{c}^T$
- ► For example, for Hamming(7,4), we have:

$$\begin{cases} 0 = c_4 \oplus i_5 \oplus i_6 \oplus i_7 \\ 0 = c_2 \oplus i_3 \oplus i_5 \oplus i_6 \\ 0 = c_1 \oplus i_3 \oplus i_5 \oplus i_7 \end{cases}$$

which means:

$$\begin{cases} c_4 = i_5 \oplus i_6 \oplus i_7 \\ c_2 = i_3 \oplus i_5 \oplus i_6 \\ c_1 = i_3 \oplus i_5 \oplus i_7 \end{cases}$$

Properties of Hamming codes

- Can detect two errors
 - ► All columns are different => can detect 2 errors
 - ▶ Sum of two columns equal to a third => cannot correct 3

OR

- Can correct one error
 - All columns are different => can correct 1 error
 - Sum of two columns equal to a third => cannot correct 2
 - ► Non-systematic: syndrome = error position

BUT

- Not simultaneously!
 - same non-zero syndrome can be obtained with 1 or 2 errors, can't distinguish

Coding rate of Hamming codes

Coding rate of a Hamming code:

$$R = \frac{k}{n} = \frac{2^r - r - 1}{2^r - 1}$$

The Hamming codes can correct 1 OR detect 2 errors in a codeword of size n

- \triangleright (7,4) Hamming code: n=7
- ▶ (15,11) Hamming code: n = 15
- ▶ (31,26) Hamming code: n = 31

Longer Hamming codes are progressively weaker:

- weaker error correction capability
- better efficiency (higher coding rate)
- more appropriate for smaller error probabilities

Encoding & decoding example for Hamming(7,4)

See whiteboard.

In this example, encoding is done without the generator matrix G, directly with the matrix H, by finding the values of the parity bits c_1 , c_2 , c_4 such that

$$\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} = [H] \begin{vmatrix} c_1 \\ c_2 \\ i_3 \\ c_4 \\ i_5 \\ i_6 \\ i_7 \end{bmatrix}$$

For a single error, the syndrome is the binary representation of the location of the error.

Circuit for encoding Hamming(7,4)

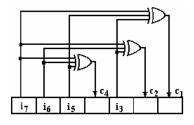


Figure 5: Hamming Encoder

- Components:
 - A shift register to hold the codeword
 - Logic OR gates to compute the parity bits

Circuit for decoding Hamming(7,4)

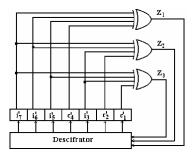


Figure 6: Hamming Encoder

- Components:
 - A shift register to hold the received word
 - ▶ Logic OR gates to compute the bits of the syndrome (z_i)
 - ▶ **Binary decoder**: activates the output corresponding to the binary input value, fixing the error

SECDED Hamming codes

- ► Hamming codes can correct 1 error OR can detect 2 errors, but we cannot differentiate the two cases
- Example:
 - ▶ the syndrome $\mathbf{z} = [H] \cdot \mathbf{r}^T = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$ can be caused by:
 - ightharpoonup a single error in location 3 (bit i_3)
 - two errors in location 1 and 2 (bits c_1 , bits c_2)
 - if we know it is a single error, we can go ahead and correct it, then use the corrected data
 - ▶ if we know there are two errors, we should NOT attempt to correct them, because we cannot locate the errors correctly
- Unfortunately, it is not possible to differentiate between the two cases.
- **Solution?** Add additional parity bit \rightarrow SECDED Hamming codes

SECDED Hamming codes

- Add an additional parity bit to differentiate the two cases
 - $ightharpoonup c_0 = \operatorname{sum} \operatorname{of} \operatorname{all} n \operatorname{bits} \operatorname{of} \operatorname{the codeword}$
- ► For (7,4) Hamming codes:

The parity check matrix is extended by 1 row and 1 column

$$\tilde{H} = \begin{bmatrix} 1 & 1 \\ 0 & \mathbf{H} \end{bmatrix}$$

- Known as SECDED Hamming codes
 - ► Single Error Correction Double Error Detection

Encoding and decoding of SECDED Hamming codes

- Encoding:
 - ightharpoonup compute codeword using $ilde{H}$
 - ightharpoonup alternatively, prepend $c_0 = \text{sum of all other bits}$

Encoding and decoding of SECDED Hamming codes

- Decoding
 - lacktriangle Compute syndrome of the received word using $ilde{H}$

$$\tilde{\mathbf{z}} = \begin{bmatrix} z_0 \\ \mathbf{z} \end{bmatrix} = [\tilde{H}] \cdot \mathbf{r}^T$$

- $ightharpoonup z_0$ is an additional bit in the syndrome corresponding to c_0
- z₀ tells us whether the received c₀ matches the parity of the received word
 - z₀ = 0: the additional parity bit c₀ matches the parity of the received word
 - z₀ = 1: the additional parity bit c₀ does not match the parity of the received word

Encoding and decoding of SECDED Hamming codes

- Decoding (continued):
 - Decide which of the following cases happened:
 - ▶ If no error happened: $z_1 = z_2 = z_3 = 0, z_0 = \forall$
 - ▶ If 1 error happened: syndrome is non-zero, $z_0 = 1$ (does not match)
 - ▶ If 2 errors happened: syndrome is non-zero, $z_0 = 0$ (does match, because the two errors cancel each other out)
 - ▶ If 3 errors happened: same as 1, can't differentiate
- Now can simultaneously differentiate between:
 - ightharpoonup 1 error: ightharpoonup perform correction
 - 2 errors: → detect, but do not perform correction
- ▶ Also, if correction is never attempted, can detect up to 3 errors
 - minimum Hamming distance = 4 (no proof given)
 - don't know if 1 error, 2 errors or 3 errors, so can't try correction

Summary until now

- Systematic codes: information bits + parity bits
- ► Generator matrix: use to generate codeword

$$\mathbf{i} \cdot [G] = \mathbf{c}$$

Parity-check matrix: use to check if a codeword

$$0 = [H] \cdot \mathbf{c}^T$$

Syndrome:

$$\mathbf{z} = [H] \cdot \mathbf{r}^T$$

- Syndrome-based error detection: syndrome non-zero
- ► Syndrome-based error correction: lookup table
- ▶ Hamming codes: [H] contains all numbers $1...2^r 1$
- SECDED Hamming codes: add an extra parity bit

Chapter structure

Chapter structure

- 1. General presentation
- 2. Analyzing linear block codes with the Hamming distance
- 3. Analyzing linear block codes with matrix algebra
- 4. Hamming codes
- 5. Cyclic codes

Cyclic codes

Definition: **cyclic codes** are a particular class of linear block codes for which *every cyclic shift of a codeword is also a codeword*

- Cyclic shift: cyclic rotation of a sequence of bits (any direction)
- Are a particular class of linear block codes, so all the theory up to now still applies
 - they have a generator matrix, parity check matrix etc.
- But they can be implemented more efficient than general linear block codes (e.g. Hamming)
- Used everywhere under the common name CRC (Cyclic Redundancy Check)
 - Network communications (Ethernet), data storage in Flash memory

Usage example: Ethernet frame

► CRC codes are used in Ethernet frames:

	802.3 Ethernet packet and frame structure									
Layer	Preamble	Start of frame delimiter	MAC destination	MAC source	802.1Q tag (optional)	Ethertype (Ethernet II) or length (IEEE 802.3)	Payload	Frame check sequence (32-bit CRC)	Interpacket gap	
	7 octets	1 octet	6 octets	6 octets	(4 octets)	2 octets	46-1500 octets	4 octets	12 octets	
Layer 2 Ethernet frame		← 64-1522 octets →								
Layer 1 Ethernet packet & IPG	← 72-1530 octets →								← 12 oct. →	

Figure 7: CRC value in an Ethernet frame

Binary polynomials

ightharpoonup Every binary sequence **a** corresponds to a polynomial **a**(**x**) with binary coefficients

$$a_0 a_1 ... a_{n-1} \to \mathbf{a}(\mathbf{x}) = a_0 \oplus a_1 x \oplus ... \oplus a_{n-1} x^{n-1}$$

Example:

$$10010111 \rightarrow 1 \oplus x^3 \oplus x^5 \oplus x^6 \oplus x^7$$

- From now on, by "codeword" we also mean the corresponding polynomial.
- Can perform all mathematical operations with these polynomials:
 - addition, multiplication, division etc. (examples)
- ▶ There are efficient circuits for performing multiplications and divisions.

Generator polynomial

Theorem:

All the codewords of a cyclic code are multiples of a certain polynomial g(x), known as **generator polynomial**.

Properties of generator polynomial

The generator polynomial g(x) must satisfy the following:

- \triangleright g(x) must have first and last coefficient equal to 1
- ightharpoonup g(x) must be a factor of $X^n \oplus 1$
- ▶ The *degree* of g(x) is n k, where:
 - ightharpoonup n = the size of codeword (codeword polynomial has degree n-1)
 - ightharpoonup k = the size of the information word (information polynomial has degree k-1)

$$(k-1) + (n-k) = n-1$$

▶ The degree of g(x) is the number of parity bits of the code.

Example of generator polynomials

Example:

$$1 \oplus x^7 = (1 \oplus x)(1 \oplus x + \oplus x^3)(1 \oplus x^2 \oplus x^3)$$

Each factor can generate a code:

- ▶ $1 \oplus x$ generates a (7,6) cyclic code
- ▶ $1 \oplus x \oplus x^3$ generates a (7,4) cyclic code
- ▶ $1 \oplus x^2 \oplus x^3$ generates a (7,4) cyclic code

Popular polynomials

Figure 8: Popular generator polynomials g(x)

- ► Image from http://www.ross.net/crc/download/crc_v3.txt
- ▶ Your turn: write the polynomials in mathematical form

Proving the cyclic property

Theorem:

▶ Any cyclic shift of a codeword is also a codeword.

Proof:

- ▶ It is enough to consider a cyclic shift by 1 position
- Original codeword

$$c_0c_1c_2...c_{n-1} \to \mathbf{c}(\mathbf{x}) = c_0 \oplus c_1x \oplus ... \oplus c_{n-1}x^{n-1}$$

Cyclic shift to the right by 1 position

$$c_{n-1}c_0c_1...c_{n-2} \rightarrow \mathbf{c}'(\mathbf{x}) = c_{n-1} \oplus c_0x \oplus ... \oplus c_{n-2}x^{n-1}$$

▶ We can rewrite:

$$\mathbf{c}'(\mathbf{x}) = x \cdot \mathbf{c}(\mathbf{x}) \oplus c_{n-1}x^n \oplus c_{n-1}$$
$$= x \cdot \mathbf{c}(\mathbf{x}) \oplus c_{n-1}(x^n \oplus 1)$$

Proving the cyclic property

Proof (continued):

- ▶ Since c(x) is a multiple of g(x), so is $x \cdot c(x)$
- ▶ Also $(x^n \oplus 1)$ is always a multiple of g(x)
- ▶ => It follows that their sum $\mathbf{c}'(\mathbf{x})$ is a also a multiple of g(x), which means it is a codeword.

QED

- ▶ Note that we relied on two properties mentioned before:
 - ▶ that a codeword c(x) is always a multiple of g(x)
 - ▶ that g(x) is a factor of $(x^n \oplus 1)$

Coding and decoding of cyclic codes

- Cyclic codes can be used for detection or correction
- In practice, they are used mostly for **detection only** (e.g. in Ethernet)
 - because there are other codes with better performance for correction
- Can be systematic / non-systematic
 - ▶ In practice, the systematic variant is much preferred
- ▶ We study coding/decoding from 3 perspectives:
 - ► The mathematical way, with polynomials
 - ► The programming way, e.g. as a programming algorithm
 - ► The hardware way, via schematics

1. Coding and decoding - The mathematical way

Reminder: polynomial multiplication and division

- ▶ Two polynomials a(x) and b(x) can be multiplied
 - ▶ the result has degree = degree of a(x) + degree of b(x)
- ▶ A polynomials a(x) can be divided to another polynomial b(x):

$$a(x) = b(x)q(x) \oplus r(x)$$

- ightharpoonup r(x) =the remainder ("restul")
- ▶ the degree of r(x) is strictly smaller than the degree of b(x)

1. Coding and decoding - The mathematical way

Coding

▶ We want to encode the **information word** with *k* bits

$$i_0 i_1 i_2 ... i_{k-1} \to i(x) = i_0 \oplus i_1 x \oplus ... \oplus i_{k-1} x^{k-1}$$

▶ Non-systematic codeword generation:

$$c(x) = i(x) \cdot g(x)$$

- The degrees match:
 - ightharpoonup i(x) has degree k-1 (k bits)
 - ightharpoonup g(x) has degree n-k (n-k+1 bits)
 - c(x) has degree n-1 = (n-k) + (k-1) (*n* bits)

Systematic coding - The mathematical way

Systematic codeword generation:

$$c(x) = x^{n-k} \cdot i(x) \oplus b(x)$$

▶ b(x) is the remainder of dividing $x^{n-k}i(x)$ to g(x):

$$x^{n-k}i(x) = a(x)g(x) \oplus b(x)$$

- \blacktriangleright b(x) is known as "the CRC value"
- ls this c(x) really a multiple of g(x)? Yes, because:

$$c(x) = x^{n-k} \cdot i(x) \oplus b(x) = a(x)g(x) \oplus b(x) \oplus b(x) = a(x)g(x)$$

Interpretation

- Why is the code systematic?
- Let's analyze the systematic codeword generation step by step
- Consider the information word/polynomial

$$\mathbf{i} = [\underbrace{i_0 i_1 ... i_{k-1}}_{k}] \rightarrow i(x) = i_0 \oplus i_1 x \oplus ... \oplus i_{k-1} x^{k-1}$$

▶ Multiplying $x^{n-k} \cdot i(x)$ shifts all bits to the right with (n-k) positions

$$[\underbrace{00...0}_{n-k}\underbrace{i_0i_1...i_{k-1}}_{i_k}] \rightarrow i(x) = i_0x^{n-k} \oplus i_1x^{n-k+1} \oplus ... \oplus i_{k-1}x^{n-1}$$

Interpretation (continued)

- ▶ The remainder b(x) has degree strictly less than n k (degree of g(x)), so at most n k bits
- ▶ Therefore adding b(x) will not overlap with $x^{n-k} \cdot i(x)$
 - ▶ the (n k) bits of b(x) will fit in the first n k locations

$$\mathbf{c} = \underbrace{[b_0 b_1 \dots b_{n-k} \underbrace{i_0 i_1 \dots i_{k-1}}]}_{n-k} \to$$

$$\to c(x) = b_0 \oplus b_1 x \oplus \dots \oplus b_{n-k-1} x^{n-k-1} \oplus i_0 x^{n-k} \oplus i_1 x^{n-k+1} \oplus \dots \oplus i_k$$

- ▶ Hence the code is systematic: the information bits are in the codeword
- ▶ The code adds b(x) (the remainder) = the **CRC value**

Interpretation

- Systematic cyclic codeword = compute a CRC value and append it to the data
- Different writing conventions:
 - when writing the codewords from LSB -> MSB (increasing order of degrees), the CRC appears in front
 - like in lecture slides
 - when writing the codewords from MSB -> LSB (decreasing order of degrees), the CRC appears at the end
 - like in laboratory
 - same thing, just bit ordering is reversed
 - ► (LSB = Least Significant Bit, MSB = Most Significant Bit)

Decoding - The mathematical way

Decoding

- ▶ We receive $\mathbf{r} = r_0 r_1 r_2 ... r_{n-1} \to \mathbf{r}(\mathbf{x}) = r_0 \oplus r_1 x \oplus ... \oplus r_{n-1} x^{n-1}$ \$
- **Error detection**: check if r(x) is a codeword or not
- ▶ Check if the received $\mathbf{r}(\mathbf{x})$ still is a multiple of g(x)
 - ▶ Divide $\mathbf{r}(\mathbf{x})$ to g(x):
 - If remainder of r(x): g(x) is 0 = it is a codeword, no errors present
 - ▶ If remainder is non-zero => it's not a true codeword, **errors detected**
- Computing the remainder = computing the CRC of the received data
 - ▶ Remember lab: decoding = compute CRC of all coded data, if 0 => OK, if non-zero => NOK

Decoding - The mathematical way

- Error correction: use a lookup table (just like with matrices)
 - build a lookup table for all possible error words (like with matrix codes)
 - for each error code, divide by g(x) and compute the remainder
 - when the remainder is identical to the remainder obtained with r(x), we found the error word => correct errors
- Example: at blackboard

2. Coding and decoding - The programming way

- Only for systematic codes (mostly used)
- ► Steps:
 - 1. Compute the CRC = b(x) = remainder of $x^{n-k}i(x)$ divided to g(x)
 - Put the CRC in front of the information word, mirrored
- Good reference: "A Painless Guide to CRC Error Detection Algorithms", Ross N. Williams
 - http://www.ross.net/crc/download/crc_v3.txt

Coding

- The mathematical polynomial division = just like XOR-ing succesively with g(x)
 - ightharpoonup align the binary sequence of g(x) under the leftmost 1
 - XOR the sequences
 - repeat
 - iust like in the lab
- See example at blackboard / lab

Example

```
11010110110000
10011,,.,,...
----,,,,,,,,,,
 10011,.,,....
 10011,.,,...
 ----,.,,....
 00001.,,....
  00000.,,....
  -----
  00010,,....
   00000,,....
   ----,,....
   00101....
    00000,....
    ----,....
    01011....
     00000....
     -----...
      10110...
      10011...
```

Figure 9: Polynomial division = XORing succesively with g(x)

Decoding

- ▶ We receive $\mathbf{r} = r_0 r_1 r_2 ... r_{n-1} \to \mathbf{r}(\mathbf{x}) = r_0 \oplus r_1 x \oplus ... \oplus r_{n-1} x^{n-1}$
- ▶ Step 1: Mirror the sequence **r** (CRC must be at the end!)
- Error detection:
 - compute the CRC of all sequence r
 - ▶ If the remainder is 0 => no errors
 - ▶ If the remainder is non-zero => errors detected!
- Error correction:
 - use a lookup table (just like with matrices)
 - build a lookup table for all possible error words (same as with matrix codes)
 - for each error word, compute the CRC
 - when the resulting remainder is identical to the remainder obtained with r, we found the error word => correct errors

Skip next slides for 2018-2019

The remaining slides in this file are skipped for the class of 2018-2019.

3. Coding and encoding - The hardware way

- ► Coding = based on polynomial multiplications and divisions
- Efficient circuits for multiplication / division exist, that can be used for systematic or non-systematic codeword generation (draw on blackboard)

Circuits for multiplication of binary polynomials

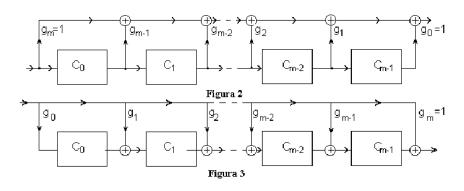


Figure 10: Circuits for polynomial multiplication

Operation of multiplication circuits

- ▶ The circuits multiply an input polynomial a(x) with a polynomial g(x) defined by their structure
- ► The input polynomial is applied at the input, 1 bit at a time, starting from highest degree
- ► The output polynomial is obtained at the output, 1 bit at a time, starting from highest degree
- ▶ Because output polynomial has larger degree, the circuit needs to operate a few more samples until the final result is obtained. During this time the input is 0.
- Examples: at the whiteboard

Circuits for division binary polynomials

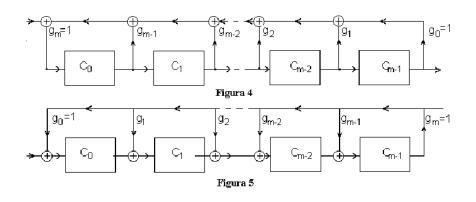


Figure 11: Circuits for polynomial division

Operation of division circuits

- ▶ The circuits divide an input polynomial a(x) to a polynomial g(x) defined by their structure
- ► The input polynomial is applied at the input, 1 bit at a time, starting from highest degree
- ► The output polynomial is obtained at the output, 1 bit at a time, starting from highest degree
- ▶ Because output polynomial has smaller degree, the circuit first outputs some zero values, until starting to output the result.
- ▶ If the remainder is 0, all the cells remain with 0 at the end
- Examples: at the whiteboard

Non-systematic cyclic encoder circuit

- Non-systematic cyclic encoder circuit:
 - simply a polynomial multiplication circuit
 - ightharpoonup input is i(x), output is c(x)

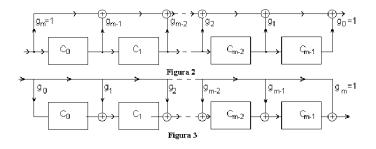


Figure 12: Circuits for polynomial multiplication

Systematic cyclic encoder circuit

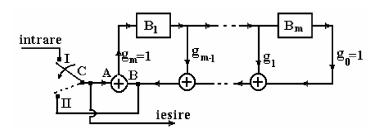


Figure 13: Systematic cyclic encoder circuit

▶ It contains inside a division circuit (upper right part)

Systematic cyclic encoder circuit

Operation of the cyclic encoder circuit:

- Initially all cells are 0
- Switch in position I:
 - information bits are applied to the output and to the division circuit
 - first bits of the output are the information bits => indeed systematic
 - the input bits are applied to the division circuit
- Switch in position II:
 - some output bits are put at the ouput
 - the same output bits are also applied to the input of the division circuit
- In the end all cells end up with value 0
 - ▶ because in phase II we add the input (A) with itself (B) at the input of the division circuit, so they cancel each other

Systematic cyclic encoder circuit

- ▶ Why is the output c(x) the desired codeword? Because:
 - 1. has the information bits in the first part (systematic)
 - 2. is a multiple of g(x)
- ▶ Why is it a multiple of g(x)? Because:
 - ▶ the output c(x) is always applied also to the input of the division circuit ▶ in both phases of operation
 - after division, the cells end up in 0, which means there is no remainder of division
- Side note: we haven't really explained why the output c(x) is a codeword, we just showed that it is so

The parity-check matrix for systematic cyclic codes

 Requires a more in-depth analysis of Linear Feedback Shift Registers (LFSR)

Linear-Feedback Shift Registers (LFSR)

- ► A **flip-flop** = a cell holding a bit value (0 or 1)
 - called "bistabil" in Romanian
 - operates on the edges of a clock signal
- ► A **register** = a group of flip-flops, holding multiple bits
 - example: an 8-bit register
- ▶ A **shift register** = a register where the output of a flip-flop is connected to the input of the next one
 - the bit sequence is shifted to the right
 - has an input (for the first cell)
- ▶ A linear feedback shift register (LFSR) = a shift register for which the input is a computed as a linear combination of the flip-flops values
 - input = usually a XOR of some cells from the register
 - like a division circuit without any input
 - feedback = all flip-flops, with coefficients g_i in general
 - example at whiteboard

States and transitions of LFSR

- ▶ **State** of the LFSR = the sequence of bit values it holds at a certain moment (in order: right to left)
- ▶ The state at the next moment, S(k+1), can be computed by multiplication of the current state S(k) with the **companion matrix** (or **transition matrix**) [T]:

$$S(k+1) = [T] * S(k)$$

▶ The companion matrix is defined based on the feedback coefficients g_i :

$$T = \begin{bmatrix} 0 & 1 & 0 & \dots & 0 \\ 0 & 0 & 1 & \dots & 0 \\ \vdots & \vdots & \ddots & \dots & \vdots \\ 0 & 0 & 0 & \dots & 1 \\ g_0 & g_1 & g_2 & \dots & g_{m-1} \end{bmatrix}$$

- ▶ Note: reversing the order of bits in the state => transposed matrix
- \triangleright Starting at time 0, then the state at time k is:

Period of LFSR

- ▶ The number of states is finite => they must repeat at some moment
- ► The state equal to 0 must not be encountered (in this case the LFSR will remain 0 forever)
- ► The **period** of the LFSR = number of time moments until the state repeats
- ▶ If period is N, then state at time N is same as state at time 0:

$$S(N) = [T]^N S(0) = S(0),$$

which means:

$$[T]^N = I_m$$

Maximum period is $N_{max} = 2^m - 1$ (excluding state 0), in this case the polynomial g(x) is called **primitive polynomial**

LFSR with inputs

- What if the LFSR has an input added to the feedback (XOR)?
 - exactly like a division circuit
 - ▶ assume the input is a sequence $a_{N-1},...a_0$
- ► Since a LFSR is a **linear circuit**, the effect is added:

$$S(1) = [T] \cdot S(0) \oplus \begin{bmatrix} 0 \\ 0 \\ ... \\ a_{N-1} \end{bmatrix}$$

In general:

$$S(k_1) = [T] \cdot S(k) \oplus a_{N-k} \cdot [U],$$

where [U] is:

$$[U] = \begin{bmatrix} 0 \\ 0 \\ ... \\ 1 \end{bmatrix}$$

The parity-check matrix for systematic cyclic codes

- Cyclic codes are linear block codes, so they have a parity-check and a generator matrix
 - but it is more efficient to implement them with polynomial multiplication / division circuits
- ► The parity-check matrix [H] can be deduced by analyzing the states of the LFSR (divider) inside the encoder:
 - it is a LFSR with feedback and input
 - \blacktriangleright the input is the codeword c(x)
 - do computations at whiteboard . . .
 - ▶ ... arrive at expression for matrix [H]

The parity-check matrix for systematic cyclic codes

▶ The parity check matrix [H] has the form

$$[H] = [U, TU, T^2U, ...T^{n-1}U]$$

The cyclic codeword satisfies the usual relation

$$S(n) = 0 = [H]\mathbf{c}^\mathsf{T}$$

▶ In case of an error, the state at time n will be the syndrome (non-zero):

$$S(n) = [H]\mathbf{r}^{\mathsf{T}} \neq 0$$

Error detection and correction capability

Theorem:

Any (n,k) cyclic code with g(x) being a primitive polynomial is capable of detecting 2 errors, or of correcting 1 error

- ► Proof:
 - g(x) is primitive polynomial => the LSFR cycles through all possible states (non-zero)
 - ▶ therefore all the columns of [H] are distinct
 - Use the conditions based on the columns of [H] from first part of chapter
 - ▶ sum of any two columns is non-zero => can detect 2 errors
 - any two columns are distinct => can correct 1 error

Packets of errors

- Until now, we considered a single error (i.e errors appear independently)
- ▶ In real life, many times the errors appear in groups
- A packet of errors (an error burst) is a sequence of two or more consecutive errors
 - examples: fading in wireless channels
- ▶ The **length** of the packet = the number of consecutive errors

Condition on columns of [H] for packets of errors

- Conditions for packets of e errors are less restrictive than for e independent errors
- ► Error **detection** of *e* independent errors:
 - sum of **any** *e* or fewer columns is **non-zero**
- Error detection of a packet of e errors
 - sum of any consecutive e or fewer columns is non-zero
- Error correction of e independent errors
 - sum of any e or fewer columns is unique
- Error correction of a packet of e errors
 - sum of any consecutive e or fewer columns is unique

Detection of packets of errors

Theorem:

Any (n,k) cyclic code is capable of detecting any error packet of length n-k or less

- ▶ A large fraction of longer bursts can also be detected (but not all)
- No proof (too complicated)

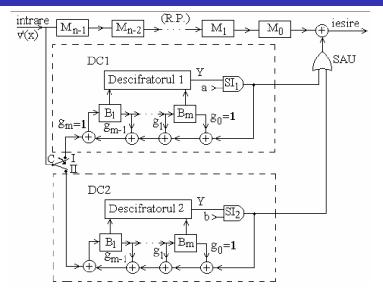


Figure 14: Cyclic decoder circuit

- Consists of:
 - main shift register MSR
 - main switch SW
 - \triangleright 2 LFSRs (divider circuits), built based on g(x)
 - ▶ 2 error locator blocks, one for each divider
 - 2 validation gates V1, V2, for each divider
 - output XOR gate for correcting errors

- Operation phases:
- 1. Input phase: SW on position I, validation gate V1 blocked
 - The received codeword r(x) is received one by one, starting with largest power of x^n
 - ► The received codeword enters the MSR and first LFSR (divider)
 - ▶ The first divider computes r(x) : g(x)
 - ▶ The validation gate V1 is blocked, no output
- ▶ Input phase ends after *n* moments, the switch SW goes into position II
- ▶ If the received word has no errors, all LFSR cells are 0 (no remainder), will remain 0, the error locator will always output 0,
 - the MSR will output the received bits unchanged

- 2. Decoding phase: SW on position II, validation gate V1 open
 - ► LFSR keeps running with no input for *n* more moments
 - ▶ the MSR provides the received bits at the output, one by one
 - exactly when the erroneous bit is at the main output of MSR, the error locator will output 1, and the output XOR gate will correct the bit (TO BE PROVEN)
 - during this time the next codeword is loaded into MSR and into second LFSR (input phase for second LFSR)
- ▶ After *n* moments, the received word is fully decoded and corrected
- ➤ SW goes back into position I, the second LFSR starts decoding phase, while the first LFSR is loading the new receiver word, and so on
- ► **To prove:** error locator outputs 1 exactly when the erroneous bit is at the main output

Theorem: if the k-th bit r_{n-k} from r(x) has an error, the error locator will output 1 exactly after k-1 moments

► That's exactly when the erroneous *k*-th bit will be output from MSR => will be changed back to the good value

Proof:

- 1. assume error on position r_{n-k}
- 2. the state of the LFSR at end of phase I = syndrome = column (n k) from [H]

$$S(n) = [H]\mathbf{r}^T = [H]\mathbf{e}^T = T^{n-k}U$$

3. after another k-1 moments, the state will be

$$T^{k-1}T^{n-k}U = T^{n-1}U$$

- 4. since $T^n = I_n -> T^{n-1} = T^{-1}$
- 5. $T^{-1}U$ is the state preceding state U, which is state

- Step 5 above can be shown in two ways:
 - reasoning on the circuit
 - ightharpoonup using the definition of T^{-1}

$$T = \begin{bmatrix} g_1 & g_2 & \dots g_{m-1} & 1 \\ 1 & 0 & \dots & 0 & 0 \\ 0 & 1 & \dots & 0 & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \dots & 1 & 0 \end{bmatrix}$$

- ▶ The error locator is designed to detect this state $T^{-1}U$, i.e. it is designed as shown on blackboard
- Therefore, the error locator will correct an error
- ▶ This works only for 1 error, due to proof (1 column from [H])

Summary of cyclic codes

- lacktriangle Generated using a generator polynomial g(x)
- Non-systematic:

$$c(x) = i(x) \cdot g(x)$$

Systematic:

$$c(x) = b(x) \oplus X^{n-k}i(x)$$

- ▶ b(x) is the remainder of dividing $X^{n-k}i(x)$ to g(x)
- ightharpoonup A codeword is always a multiple of g(x)
- **Error** detection: divide by g(x), look at remainder
- Schematics:
 - Cyclic encoder
 - Cyclic decoder with LFSR
 - ► Thresholding cyclic decoder
 - Encoder/decoder for packets of up to 2 errors