Information Theory

Chapter I: Discrete information sources

Block diagram of a communication system

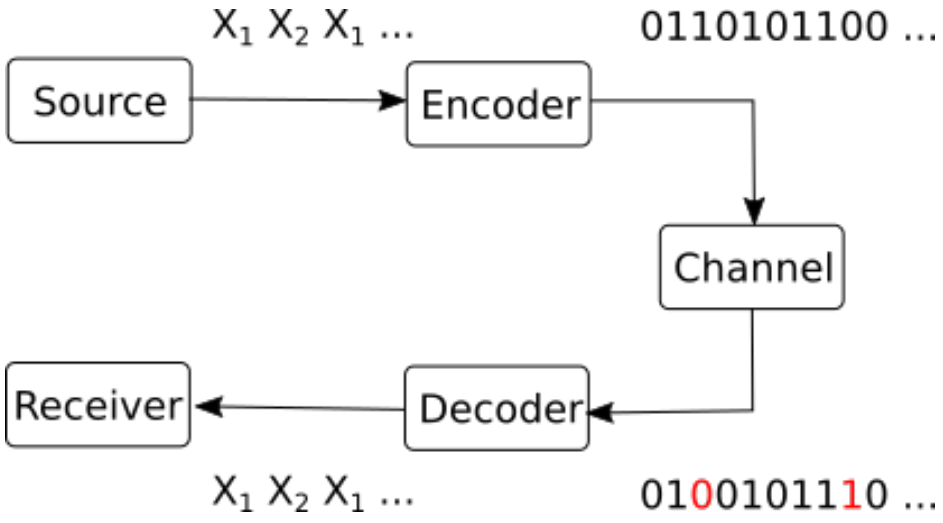

Figure 1: Block diagram of a communication system

- Source: creates information messages
- Encoder: converts messages into symbols for transmission (i.e bits)
- Channel: delivers the symbols, introduces errors
- Decoder: detects/corrects the errors, rebuilds the information messages

What is information?

Example:

- Suppose I roll a dice and tell you the result:

  "The value is 6"

- Does this message carry information? How, why, how much?
- Consider the following facts:
  - the message carries information only when you don't already know the result
  - if you already known the result, the message is useless (brings no information)
  - if the result was to be expected, there is little information. If the result is highly unusual, there is more information in this message.

Information and events

- We define the notion of **information** for a **probabilistic event**
- Information brought by an event depends on the **probability** of the event
- Rule of thumb: if you can guess something most of the times, it has little information
- Questions:
  - does a sure event ($p = 1$) bring any information?
  - does an almost sure event (e.g. $P = 0.9999$) bring little or much information?
  - does a rare event (e.g. $P = 0.0001$) bring a little or much information?

Information

- The information attached to a particular event (known as "message") s_i is rigorously defined as:

$$i(s_i) = -\log_2(p(s_i))$$

- Consequences:
  - $i(s_i) \geq 0$
  - lower probability (rare events) means higher information
  - higher probability (frequent events) means lower information
  - a certain event brings no information: $-\log(1) = 0$
  - an event with probability 0 brings infinite information (but it never happens...)
  - for two independent events, their information gets added

$$i(s_i) \cap s_j) = i(s_i) + i(s_j)$$

- Information is mathematical. It does not depend on how you encode the message (letters, bits, language) and neither on what you use it for.

The choice of logarithm

- Any base of logarithm can be used in the definition.
- Usual convention: use binary logarithm $\log_2()$. In this case, the information $i(s_i)$ is measured in **bits**
- If using natural logarithm $\ln()$, it is measured in *nats*.
- Logarithm bases can be converted to/from one another:

$$\log_b(x) = \frac{\log_a(x)}{\log_a(b)}$$

- Information defined using different logarithms differ only in scaling:

$$i_b(s_i) = \frac{i_a(s_i)}{\log_a(b)}$$

Information source

- A probabilistic event is always part of a set of multiple events (options)
  - e.g: a football team can win/lose/draw a match (3 possible events)
  - each event has a certain probability. All probabilities are known beforehand
  - at a given time, only one of the events can happen
- An **information source** = the set of all events together with their probabilities
- One event is called a **message**
- Each message carries the information that **it** happened. The amount of information depends on its probability.
- An information source creates a **sequence of messages**
  - e.g. like throwing a coin or a dice several times in a row

Discrete memoryless source

- A **discrete memoryless source** (DMS) is an information source which produces a sequence of **independent** messages
  - i.e. the choice of a message at one time does not depend on the previous messages
- The probabilities of the messages are known and fixed. The set of probabilities is the **distribution** of the source:

$$S : \begin{pmatrix} s_1 & s_2 & s_3 \\ \frac{1}{2} & \frac{1}{4} & \frac{1}{4} \end{pmatrix}$$

- Each time, a new message is randomly selected according to the probabilities

Discrete memoryless source

$$S : \begin{pmatrix} s_1 & s_2 & s_3 \\ \frac{1}{2} & \frac{1}{4} & \frac{1}{4} \end{pmatrix}$$

- Terminology:
  - Discrete: it can take a value from a discrete set ("alphabet")
  - Complete: $\sum p(s_i) = 1$
  - Memoryless: succesive values are independent of previous values (e.g. successive throws of a coin)
- A message from a DMS is also called a **random variable** in probabilistics.

Examples

- A coin is a discrete memoryless source (DMS) with two messages:

$$S : \begin{pmatrix} \mathit{heads} & \mathit{tails} \\ \frac{1}{2} & \frac{1}{2} \end{pmatrix}$$

- A dice is a discrete memoryless source (DMS) with six messages:

$$S : \begin{pmatrix} s_1 & s_2 & s_3 & s_4 & s_5 & s_6 \\ \frac{1}{6} & \frac{1}{6} & \frac{1}{6} & \frac{1}{6} & \frac{1}{6} & \frac{1}{6} \end{pmatrix}$$

- Playing the lottery can be modeled as DMS:

$$S : \begin{pmatrix} s_1 & s_2 \\ 0.9999 & 0.0001 \end{pmatrix}$$

Examples

- An extreme type of DMS containing the certain event:

$$S : \begin{pmatrix} s_1 & s_2 \\ 1 & 0 \end{pmatrix}$$

- Receiving an unknown *bit* (0 or 1) with equal probabilities:

$$S : \begin{pmatrix} 0 & 1 \\ \frac{1}{2} & \frac{1}{2} \end{pmatrix}$$

Sequence of messages from DMS

- A DMS produces a sequence of messages by randomly selecting a message every time, with the same fixed probabilities
  - e.g. throwing a dice in a row you can get a sequence $4, 2, 3, 2, 1, 6, 1, 5, 4, 5, \ldots$
- If the sequence is very long (has N messages, N very large), each message s_k appears approximately $p(s_k) \cdot N$ times in the sequence
  - this gets more precise as $N \to \infty$
- The total information in the sequence is the sum for all messages:

$$I \approx \sum_k i(s_k) \cdot p(s_k) \cdot N = N \cdot \sum_k i(s_k) \cdot p(s_k)$$

- We are interested in the *average* information of a message from a DMS:

$$\sum_k i(s_k) \cdot p(s_k)$$

Entropy of a DMS

- Definition: the **entropy** of a DMS source S is **the average information of a message**:

$$H(S) = \sum_k p(s_k) i(s_k) = -\sum_k p(s_k) \log_2(p_k)$$

  where $p(s_k)$ is the probability of message k

- Since information of a message is measured in bits, entropy is measured in **bits** (or **bits / message**, to indicate it is an average value)

- Entropies using information defined with different logarithms $\log_a(), \log_b()$ differ only in scaling:

$$H_b(S) = \frac{H_a(S)}{\log_a(b)}$$

Examples

- Coin: $H(S) = 1 bit/message$
- Dice: $H(S) = \log(6) bits/message$
- Lottery: $H(S) = -0.9999 \log(0.9999) - 0.0001 \log(0.0001)$
- Receiving 1 bit: $H(S) = 1 bit/message$ (hence the name!)

Interpretation of the entropy

All the following interpretations of entropy are true:

- H(S) is the *average uncertainty* of the source S
- H(S) is the *average information* of the messages from source S
- A long sequence of N messages from S has total information $\approx N \cdot H(S)$
- H(S) is the minimum number of bits (0,1) required to uniquely represent an average message from source S

Properties of entropy

We prove the following **properties of entropy**:

1. $H(S) \geq 0$ (non-negative)

   Proof: via definition

2. $H(S)$ is maximum when all n messages have equal probability $\frac{1}{n}$. The maximum value is $\max H(S) = \log(n)$

   Proof: only for the case of 2 messages, use derivative in definition

3. *Diversification* of the source always increases the entropy

   Proof: compare entropies in both cases

The entropy of a binary source

- Consider a general DMS with two messages (a **binary** source):

$$S : \begin{pmatrix} s_1 & s_2 \\ p & 1-p \end{pmatrix}$$

- It's entropy is:

$$H(S) = -p \cdot \log(p) - (1-p) \cdot \log(1-p)$$

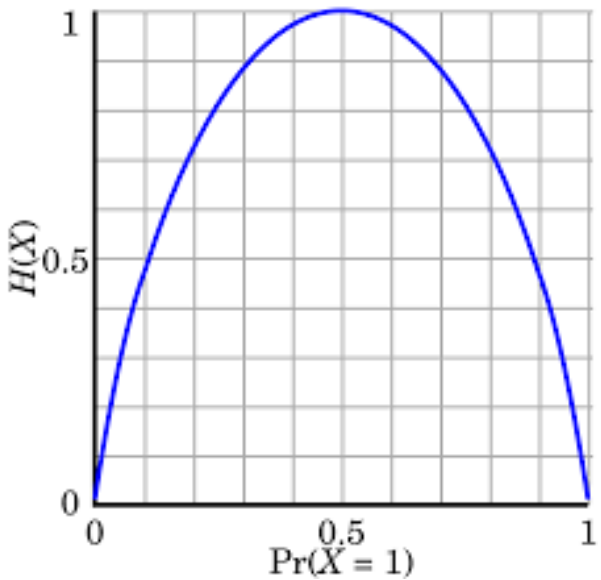

Figure 2: Entropy of a binary source

The entropy of a binary source

- When $p = \frac{1}{2}$, the entropy is maximum: $H(S) = 1 bit/message$
- Definition of **1 bit of information**:
  - it is the amount of information of by a message having probability $\frac{1}{2}$
  - it is the entropy of a binary source with equal probabilities $\frac{1}{2}$, $\frac{1}{2}$

Example - Game

Game: I think of a number between 1 and 8. You have to guess it by asking yes/no questions.

- How much uncertainty does the problem have?
- How is the best way to ask questions? Why?
- What if the questions are not asked in the best way?
- On average, what is the number of questions required to find the number?

Example - Game v2

- Suppose I choose a number according to the following distribution:

$$S : \begin{pmatrix} s_1 & s_2 & s_3 & s_4 \\ \frac{1}{2} & \frac{1}{4} & \frac{1}{8} & \frac{1}{8} \end{pmatrix}$$

  - On average, what is the number of questions required to find the number?
  - What questions would you ask?

- What if the distribution is:

$$S : \begin{pmatrix} s_1 & s_2 & s_3 & s_4 \\ 0.14 & 0.29 & 0.4 & 0.17 \end{pmatrix}$$

- In general:

  - What distribution makes guessing the number the most difficult?
  - What distribution makes guessing the number the easiest?

Optimal decision tree

- An **optimal decision tree** is the best way to ask questions in a game like the one above, i.e. the tree-like structure of questions that minimizes the average number of questions needed to find the number
- Examples: at whiteboard

Efficiency and redundancy

- Efficiency of a DMS:

$$\eta = \frac{H(S)}{H_{max}} = \frac{H(S)}{\log(n)}$$

- Absolute redundancy of a DMS:

$$R = H_{max} - H(S)$$

- Relative redundancy of a DMS:

$$\rho = \frac{H_{max} - H(S)}{H_{max}} = 1 - \eta$$

- They tell us how close is the source to having maximum entropy

Information flow of a DMS

- Suppose that message s_i takes time t_i to be transmitted via some channel.
- Definition: the **information flow** of a DMS S is the average information transmitted per unit of time:

$$H_\tau(S) = \frac{H(S)}{\bar{t}}$$

where $\bar{t}$ is the average duration of transmitting a message:

$$\bar{t} = \sum_i p_i t_i$$

- Measured in **bps** (bits per second)
- Important for data communication

Distance between distributions

- How to measure how similar / how different are two distributions?
  - must have the same number of messages
  - example: $p(s_1), ...p(s_n)$ and $q(s_1), ...q(s_n)$
- **Definition**: the **Kullback–Leibler distance** of two distributions P and Q is

$$D_{KL}(P||Q) = \sum_i p(s_i) \log(\frac{p(s_i)}{q(s_i)})$$

- It is a way to measure the **distance (difference)** between two distributions
- Also known as *cross-entropy*, *relative entropy*, or the Kullback-Leibler *divergence*

Properties of Kullback-Leibler distance

- Properties:
  - $D_{KL}(P||Q)$ is always ≥ 0, and is equal to 0 only when P and Q are the same
  - the higher $D_{KL}(P||Q)$ is, the more different the distributions are
  - it is **not commutative**: $D_{KL}(P||Q) \neq D_{KL}(Q||P)$
- Example: at whiteboard
- Example usage: classification systems (cross-entropy loss)

Usage in machine learning classification tasks

- Cross-entropy is used to measure the output of a classification algorithm against the ground truth

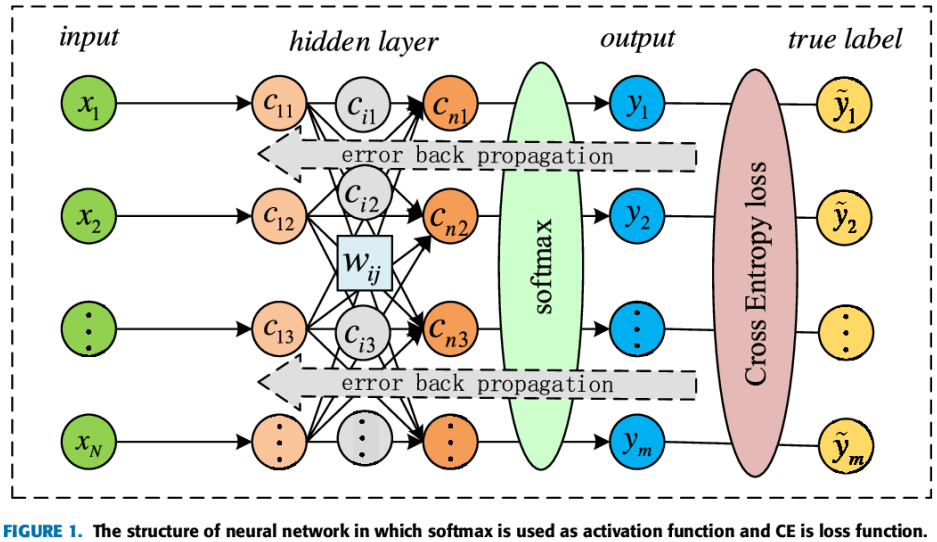

FIGURE 1. The structure of neural network in which softmax is used as activation function and CE is loss function.

Figure 3: Cross-entropy in neural networks [1]

- See PyTorch documentation: https://pytorch.org/docs/stable/generated/torch.nn.CrossEntropyLoss.html

[1] Image from *Y. Zhou, X. Wang, M. Zhang, J. Zhu, R. Zheng and Q. Wu, "MPCE: A Maximum Probability Based Cross Entropy Loss Function for Neural Network Classification," 2019, IEEE Access*

Computing probability of a sequence

- Suppose we have a DMS source

$$S : \begin{pmatrix} s_1 & s_2 & s_3 & s_4 \\ \frac{1}{2} & \frac{1}{4} & \frac{1}{8} & \frac{1}{8} \end{pmatrix}$$

- What is the probability that the source S generates a sequence $U = s_1 s_3 s_2 s_4 s_4 s_1$?
- Answer:

$$P(U) = P(s_1) \cdot P(s_3) \cdot P(s_2) \cdot P(s_4) \cdot P(s_4) \cdot P(s_1)$$

Comparing sequence probabilities for different sources

- Suppose we have two DMS sources:

$$S_A : \begin{pmatrix} s_1 & s_2 & s_3 & s_4 \\ \frac{1}{2} & \frac{1}{4} & \frac{1}{8} & \frac{1}{8} \end{pmatrix} \qquad S_B : \begin{pmatrix} s_1 & s_2 & s_3 & s_4 \\ \frac{1}{4} & \frac{1}{8} & \frac{1}{2} & \frac{1}{8} \end{pmatrix}$$

- Which is the most likely source to have generated a sequence $U = s_1 s_3 s_2 s_4 s_4 s_1$?
- Answer: Compare the probability of the sequence with source S_A, $P(U|S_A)$, with the one for the second source, $P(U|S_B)$
- We decide between sources based on which is more likely to have generated the sequence

Maximum Likelihood principle

- **Maximum Likelihood** decision: Choose the variant which has a higher probability of having generated the results
- More of this in DEDP course in 3rd year...
- Application: Decide which is the language of a given text, given two DMS sources for the letters, with the probabilities of the letters in Romanian and in English.

Extended DMS

- Definition: the **n-th order extension** of a DMS S, S^n is a source which has as messages all the combinations of n messages of S:

$$\sigma_i = \underbrace{s_j s_k \ldots s_l}_{n}$$

- If S has k messages, S^n has k^n messages
- Since S is DMS, probabilities multiply:

$$p(\sigma_i) = p(s_j) \cdot p(s_k) \cdot \ldots \cdot p(s_l)$$

- Proof: at whiteboard

Extended DMS - Example

- Examples:

$$S : \begin{pmatrix} s_1 & s_2 \\ \frac{1}{4} & \frac{3}{4} \end{pmatrix}$$

$$S^2 : \begin{pmatrix} \sigma_1 = s_1 s_1 & \sigma_2 = s_1 s_2 & \sigma_3 = s_2 s_1 & \sigma_4 = s_2 s_2 \\ \frac{1}{16} & \frac{3}{16} & \frac{3}{16} & \frac{9}{16} \end{pmatrix}$$

$$S^3 : \begin{pmatrix} s_1 s_1 s_1 & s_1 s_1 s_2 & s_1 s_2 s_1 & s_1 s_2 s_2 & s_2 s_1 s_1 & s_2 s_1 s_2 & s_2 s_2 s_1 & s_2 s_2 s_2 \\ \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots \end{pmatrix}$$

Extended DMS - Another example

- Long sequence of binary messages:

  01001100111001010 0...

  - Can be grouped in bits, half-bytes, bytes, 16-bit words, 32-bit long words, and so on
  - Can be considered:
    - N messages from a binary source (with 1 bit), or
    - N/2 messages from a source with 4 messages (with 2 bits)...
    - etc

Property of DMS

- Theorem: The entropy of a n-th order extension is n times larger than the entropy of the original DMS

$$H(S^n) = nH(S)$$

- Interpretation: grouping messages from a long sequence in blocks of n does not change total information (e.g. groups of 8 bits = 1 byte)

An example [memoryless is not enough]

- The distribution (frequencies) of letters in English:

letter	probability	letter	probability
A	.082	*N*	.067
B	.015	*O*	.075
C	.028	*P*	.019
D	.043	*Q*	.001
E	.127	*R*	.060
F	.022	*S*	.063
G	.020	*T*	.091
H	.061	*U*	.028
I	.070	*V*	.010
J	.002	*W*	.023
K	.008	*X*	.001
L	.040	*Y*	.020
M	.024	*Z*	.001

- Text generated by a memoryless source with these probabilities:

OCRO HLI RGWR NMIELWIS EU LL NBNESEBYA TH EEI
ALHENHTTPA OOBTTVA NAH BRL

(taken from Elements of Information Theory, Cover, Thomas)

- Are they similar? No
- What's wrong? **Memoryless**. Langauge has memory, our model has not.

Sources with memory

- **Definition**: A source has **memory of order** m if the probability of a message depends on the last m messages.
- The last m messages $=$ the **state** of the source (notation S_i).
- A source with n messages and memory m $=>$ has n^m states in all.
- For every state, messages can have a different set of probabilities. Notation: $p(s_i|S_k) =$ *"probability of* s_i *in state* S_k*"*.
- Also known as *Markov sources*.

Example

- A source with $n = 4$ messages and memory $m = 1$
  - if last message was s_1, choose next message with distribution

$$S_1 : \begin{pmatrix} s_1 & s_2 & s_3 & s_4 \\ 0.4 & 0.3 & 0.2 & 0.1 \end{pmatrix}$$

  - if last message was s_2, choose next message with distribution

$$S_2 : \begin{pmatrix} s_1 & s_2 & s_3 & s_4 \\ 0.33 & 0.37 & 0.15 & 0.15 \end{pmatrix}$$

  - if last message was s_3, choose next message with distribution

$$S_3 : \begin{pmatrix} s_1 & s_2 & s_3 & s_4 \\ 0.2 & 0.35 & 0.41 & 0.04 \end{pmatrix}$$

  - if last message was s_4, choose next message with distribution

$$S_4 : \begin{pmatrix} s_1 & s_2 & s_3 & s_4 \\ 0.1 & 0.2 & 0.3 & 0.4 \end{pmatrix}$$

Transitions

- When a new message is provided, the source **transitions** to a new state:

$$\ldots \underbrace{s_i s_j s_k}_{\text{old state}} \; s_l$$

$$\ldots s_i \; \underbrace{s_j s_k s_l}_{\text{new state}}$$

- The message probabilities = the probabilities of transitions from some state S_u to another state S_v

Transition matrix

- The transition probabilities are organized in a **transition matrix** $[T]$

$$[T] = \begin{bmatrix} p_{11} & p_{12} & \cdots & p_{1N} \\ p_{21} & p_{22} & \cdots & p_{2N} \\ \cdots & \cdots & \cdots & \cdots \\ p_{N1} & p_{N2} & \cdots & p_{NN} \end{bmatrix}$$

- p_{ij} is the transition probability from state S_i to state S_j
- N is the total number of states

Graphical representation

At whiteboard: draw states and transitions for previous example (source with $n = 4$ messages and memory $m = 1$)

Entropy of sources with memory

- What entropy does s source with memory have?
- Each state S_k has a different distribution –> each state has a different entropy $H(S_k)$

$$H(S_k) = -\sum_i p(s_i|S_k) \cdot \log(p(s_i|S_k))$$

- Global entropy = average entropy

$$H(S) = \sum_k p_k H(S_k)$$

where p_k = probability that the source is in state S_i

  - (i.e. after a very long sequence of messages, the fraction of time when the source was in state S_k)

Ergodic sources

- How to find out the weights p_k?
- They are known as the **stationary probabilities**
- p_k = probability that the source is in state S_i, after running for a very long time
  - (i.e. after a very long sequence of messages, the fraction of time when the source was in state S_k)
- We need to answer the following question:

  If we know the state S_k at time n, what will be the state at time $n+1$?

Ergodic sources

- Let $p_i^{(n)}$ = the probability that source S is in state S_i at time n.
- In what state will it be at time $n+1$? (after one more message)
  - i.e. what are the probabilities of the states at time $n+1$?
- Just multiply with T

$$[p_1^{(n)}, p_2^{(n)}, ..., p_N^{(n)}] \cdot [T] = [p_1^{(n+1)}, p_2^{(n+1)}, ..., p_N^{(n+1)}]$$

- After one more message:

$$[p_1^{(n)}, p_2^{(n)}, ..., p_N^{(n)}] \cdot [T] \cdot [T] = [p_1^{(n+2)}, p_2^{(n+2)}, ..., p_N^{(n+2)}]$$

- For every new moment of time, one more multiplication with T

Ergodic sources

- In general, starting from time 0, after n messages the probabilities that the source is in a certain state are:

$$[p_1^{(0)}, p_2^{(0)}, ..., p_N^{(0)}] \cdot [T]^n = [p_1^{(n)}, p_2^{(n)}, ..., p_N^{(n)}]$$

Ergodicity

- A source is called **ergodic** if every state can be reached from every state, in a finite number of steps.
- Property of ergodic sources:
  - After many messages, the probabilities of the states *become stationary* (converge to some fixed values), irrespective of the initial probabilities (no matter what state the source started from initially)

$$\lim_{n\to\infty}[p_1^{(n)}, p_2^{(n)}, \ldots p_N^{(n)}] = [p_1, p_2, \ldots p_N]$$

Finding the stationary probabilties

- How to find the value of the stationary probabilities?
- When n is very large, after n messages and after $n+1$ messages the probabilities are the same:

$$[p_1, p_2, ...p_N] \cdot [T] = [p_1, p_2, ...p_N]$$

- This is an equation system in matrix form
- One line should be removed (linear combination), and replaced with:

$$p_1 + p_2 + ... + p_N = 1$$

- Solve the resulting system of equations, find values of p_k

Entropy of ergodic sources with memory

- The entropy of an ergodic source with memory is

$$H(S) = \sum_k p_k H(S_k) = -\sum_k p_k \sum_i p(s_i|S_k) \cdot \log(p(s_i|S_k)$$

Exercise

1. Consider a discrete source with memory, with the graphical representation given below. The states are defined as follows: $S_1 : s_1 s_1$, $S_2 : s_1 s_2$, $S_3 : s_2 s_1$, $S_4 : s_2 s_2$.

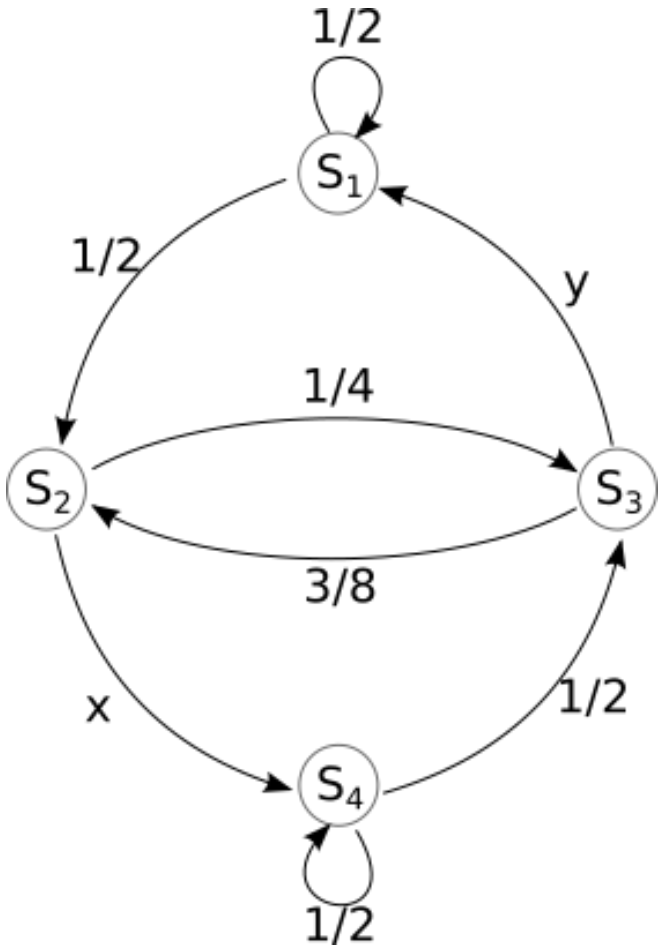

Figure 4: Graphical representation of the source

Exercise (continued)

Questions:

a. What are the values of x and y?
b. Write the transition matrix $[T]$;
c. Compute the entropy in state S_4;
d. Compute the global entropy of the source;
e. What are the memory order, m, and the number of messages of the source, n?
f. If the source is initially in state S_2, in what states and with what probabilities will the source be after 2 messages?

Example English text as sources with memory

(taken from Elements of Information Theory, Cover, Thomas)

- Memoryless source, equal probabilities:

XFOML RXKHRJFFJUJ ZLPWCFWKCYJ
FFJEYVKCQSGXYD QPAAMKBZAACIBZLHJQD

- Memoryless source, probabilities of each letter as in English:

OCRO HLI RGWR NMIELWIS EU LL NBNESEBYA TH EEI
ALHENHTTPA OOBTTVA NAH BRL

- Source with memory $m = 1$, frequency of pairs as in English:

ON IE ANTSOUTINYS ARE T INCTORE ST BE S DEAMY
ACHIN D ILONASIVE TUCOOWE AT TEASONARE FUSO
TIZIN ANDY TOBE SEACE CTISBE

Example English text as sources with memory

- Source with memory $m = 2$, frequency of triplets as in English:

IN NO IST LAT WHEY CRATICT FROURE BERS GROCID PONDENOME OF DEMONSTURES OF THE REPTAGIN IS REGOACTIONA OF CRE

- Source with memory $m = 3$, frequency of 4-plets as in English:

THE GENERATED JOB PROVIDUAL BETTER TRAND THE DISPLAYED CODE, ABOVERY UPONDULTS WELL THE CODERST IN THESTICAL IT DO HOCK BOTHE MERG. (INSTATES CONS ERATION. NEVER ANY OF PUBLE AND TO THEORY. EVENTIAL CALLEGAND TO ELAST BENERATED IN WITH PIES AS IS WITH THE)

Example application

- Suppose we receive a text with random missing letters
- We need to fill the blanks with the appropriate letters
- How?
  - build a model: source with memory of some order
  - fill the missing letter with the most likely letter given by the model

Chapter summary

- Information of a message: $i(s_k) = -\log_2(p(s_k))$
- Entropy of a memoryless source:
  $H(S) = \sum_k p_k i(s_k) = -\sum_k p_k \log_2(p_k)$
- Properties of entropy:
  1. $H(S) \geq 0$
  2. Is maximum when all messages have equal probability ($H_{max}(S) = \log(n)$)
  3. *Diversfication* of the source always increases the entropy
- Sources with memory: definition, transitions
- Stationary probabilities of ergodic sources with memory:
  $[p_1, p_2, ...p_N] \cdot [T] = [p_1, p_2, ...p_N]$, $\sum_i p_i = 1$.
- Entropy of sources with memory:

$$H(S) = \sum_k p_k H(S_k) = -\sum_k p_k \sum_i p(s_i|S_k) \cdot \log(p(s_i|S_k)$$