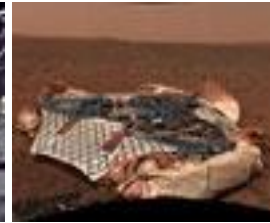


ENG 4550 – Introduction to Control Systems

Lab 1



SRV02 Modeling Part 1 – Frequency Response Experiment

Try to identify K and τ

1.1.2.1 Frequency Response

the generic first-order system form given in Equation 1.1.1. By substituting $s = j\omega$ in this equation, we can find the frequency response of the system as:

$$\frac{\Omega_l(\omega j)}{V_m(\omega j)} = \frac{K}{\tau\omega j + 1} \quad (1.1.30)$$

Then, the magnitude of it equals

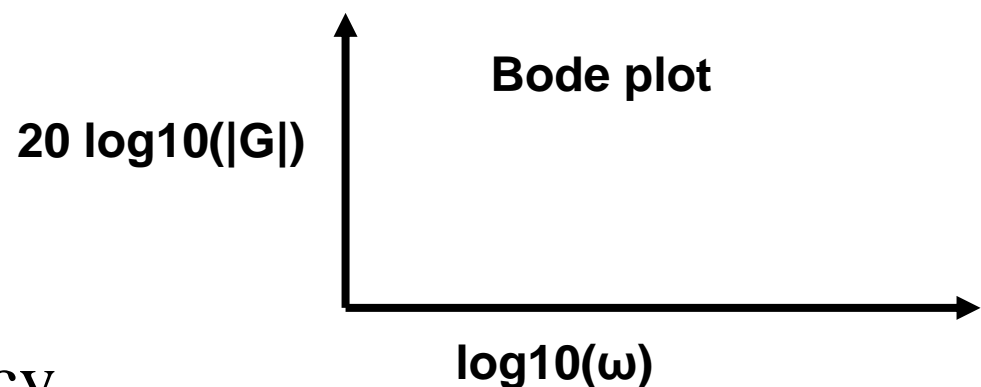
$$|G_{wl,v}(\omega)| = \frac{K}{\sqrt{1 + \tau^2 \omega^2}} \quad (1.1.31)$$

Let's call the frequency response model parameters $K_{e,f}$ and $\tau_{e,f}$ to differentiate them from the nominal model parameters, K and τ , used previously. The steady-state gain or the DC gain (i.e. gain at zero frequency) of the model is:

$$K_{e,f} = |G_{wl,v}(0)| \quad (1.1.32)$$

If $\omega = 1/\tau$?

ω is the input frequency.



1. Read **Quick Start Guide: Rotary Servo Base Unit.**

Connect SRV02, DAQ board and amplifier.

- Only Tachometer is needed (why?). The default channel in [q_srv02 mdl.mdl](#) is 1.
- If you are using VoltPAQ X2, replace **6. 5-pin DIN to 4x RCA cable** with **RCA to RCA cable**.
- An additional power supply is needed for Q8-USB.
- **ASK YOUR TA DOUBLE-CHECK THE CONNECTION BEFORE TURNING ON THE POWER.**

2. Configuring the SRV02 according to Section 1.4.2 in Workbook.

3. Setup [q_srv02 mdl.mdl](#)

- Double-click on the QUARC HIL Initialize block. Select the data acquisition device you are using. Click on the Defaults and **OK** button.
- Before building the model, click QUARC -> Set Default Options to avoid the possible target error.

4. Follow the Steps in Section 1.3.1 to conduct experiments.

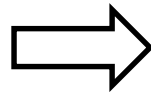
- Pay attention to the difference between $f(\text{Hz})$ and $\omega(\text{rad/s})$

5. Turn off the power and clean up your desk.

Typos

1. In Section 1.3.1.1, Step 1.

- Wave form: sine
- Amplitude: 1.0
- Frequency: 0.0
- Units: Hertz



- Wave form: sine
- Amplitude: 1.0
- Frequency: any value
- Units: Hertz

2. Figure 1.7 is not correct with 2 V input.