SE(3) WNOA Interp Jacobians

$$\begin{split} \hat{\boldsymbol{\varpi}} &= \mathcal{J}(\ln(\hat{\mathbf{T}}(\tau)\hat{\mathbf{T}}_{k}^{-1})^{\vee})(\boldsymbol{\Lambda}_{2}(\tau)\hat{\boldsymbol{\gamma}}_{k}(t_{k}) + \boldsymbol{\Psi}_{2}(\tau)\hat{\boldsymbol{\gamma}}_{k}(t_{k+1})) \\ &= \mathcal{J}(\boldsymbol{\Lambda}_{1}(\tau)\hat{\boldsymbol{\gamma}}_{k}(t_{k}) + \boldsymbol{\Psi}_{1}(\tau)\hat{\boldsymbol{\gamma}}_{k}(t_{k+1})) \left[\underline{\boldsymbol{\Lambda}_{2}(\tau)\hat{\boldsymbol{\gamma}}_{k}(t_{k}) + \boldsymbol{\Psi}_{2}(\tau)\hat{\boldsymbol{\gamma}}_{k}(t_{k+1})} \right] \\ &\hat{\boldsymbol{\gamma}}_{k}(t_{k}) = \begin{bmatrix} \mathbf{0} \\ \hat{\boldsymbol{\varpi}}_{k} \end{bmatrix}, \quad \hat{\boldsymbol{\gamma}}_{k}(t_{k+1}) = \begin{bmatrix} \ln(\hat{\mathbf{T}}_{k+1,k})^{\vee} \\ \mathcal{J}(\ln(\hat{\mathbf{T}}_{k+1,k})^{\vee})^{-1}\hat{\boldsymbol{\varpi}}_{k+1} \end{bmatrix} \\ \hat{\boldsymbol{\gamma}}_{k}(t_{k+1}) \approx \begin{bmatrix} \ln(\hat{\mathbf{T}}_{\mathrm{op},k+1,k})^{\vee} + \mathcal{J}_{\mathrm{op},k+1,k}^{-1}(\boldsymbol{\epsilon}_{k+1} - \mathcal{T}_{\mathrm{op},k+1,k}\boldsymbol{\epsilon}_{k}) \\ \left(\mathcal{J}_{\mathrm{op},k+1,k}^{-1} - \frac{1}{2} \left(\mathcal{J}_{\mathrm{op},k+1,k}^{-1}(\boldsymbol{\epsilon}_{k+1} - \mathcal{T}_{\mathrm{op},k+1,k}\boldsymbol{\epsilon}_{k}) \right)^{\wedge} \right) (\boldsymbol{\varpi}_{\mathrm{op},k+1} + \boldsymbol{\eta}_{k+1}) \end{bmatrix} \\ &\frac{\partial \hat{\boldsymbol{\varpi}}(\tau)}{\partial \mathbf{x}} = \mathcal{J}_{\mathrm{op},\tau,k} \frac{\partial}{\partial \mathbf{x}} \left[\boldsymbol{\Lambda}_{2}(\tau)\hat{\boldsymbol{\gamma}}_{k}(t_{k}) + \boldsymbol{\Psi}_{2}(\tau)\hat{\boldsymbol{\gamma}}_{k}(t_{k+1}) \right] \\ &- \frac{1}{2} \boldsymbol{\varpi}_{\mathrm{op},\tau}^{\wedge} \frac{\partial}{\partial \mathbf{x}} \left[\boldsymbol{\Lambda}_{1}(\tau)\hat{\boldsymbol{\gamma}}_{k}(t_{k}) + \boldsymbol{\Psi}_{1}(\tau)\hat{\boldsymbol{\gamma}}_{k}(t_{k+1}) \right] \\ &\frac{\partial \boldsymbol{\varpi}_{\tau}}{\partial \boldsymbol{\epsilon}_{k+1}} = \boldsymbol{\Psi}_{21} \mathcal{J}_{\mathrm{op},k+1,k}^{-1} + \frac{1}{2} \boldsymbol{\Psi}_{22} \boldsymbol{\varpi}_{\mathrm{op},k+1}^{\wedge} \mathcal{J}_{\mathrm{op},k+1,k}^{-1} \\ &\frac{\partial \boldsymbol{\varpi}_{\tau}}{\partial \boldsymbol{\epsilon}_{k}} = -\boldsymbol{\Psi}_{21} \mathcal{J}_{\mathrm{op},k+1,k}^{-1} \mathcal{T}_{\mathrm{op},k+1,k} - \frac{1}{2} \boldsymbol{\Psi}_{22} \boldsymbol{\varpi}_{\mathrm{op},k+1}^{\wedge} \mathcal{J}_{\mathrm{op},k+1,k}^{-1} \mathcal{J}_{\mathrm{op},k$$

Note: the Jacobians for $\left[\mathbf{\Lambda}_1(\tau) \hat{\boldsymbol{\gamma}}_k(t_k) + \mathbf{\Psi}_1(\tau) \hat{\boldsymbol{\gamma}}_k(t_{k+1}) \right]$ look the same, you just need to use the appropriate interpolation constants: $\mathbf{\Lambda}_1, \mathbf{\Psi}_1$.