Comments for Lecture 24 3.12.2010

Examples!

Example 1: Consider the (ordered) set

$$X = \left(\begin{bmatrix} 1\\1\\0 \end{bmatrix}, \begin{bmatrix} -1\\1\\1 \end{bmatrix}, \begin{bmatrix} -3\\5\\4 \end{bmatrix} \right)$$

- 1. Is X linearly indepdent? If not find a depdence relation on X.
- 2. Does X span \mathbb{R}^3 (i.e., is $\text{Span}(X) = \mathbb{R}^3$)?
- 3. Is X a (ordered) basis of \mathbb{R}^3 ?

Solution:

1. Using the "test for linear independece" (p129):

Let
$$A = \begin{bmatrix} 1 & -1 & -3 \\ 1 & 1 & 5 \\ 0 & 1 & 4 \end{bmatrix}$$

Putting A into reduced row echelon form we obtain:

$$A = \begin{bmatrix} 1 & -1 & -3 \\ 1 & 1 & 5 \\ 0 & 1 & 4 \end{bmatrix} \xrightarrow{\text{putting } A \text{ in RREF}} \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 4 \\ 0 & 0 & 0 \end{bmatrix}$$

So the rank(A)=2 (number of pivot columns). So rank(A)= $2\neq 3$ (the number of columns). Hence the answer is n_0 , and X must be linearly dependent.

To find a dependence relation on X we need to find a nontrivial solution to the homogeneous system $A\mathbf{x} = \mathbf{0}$. Well we did all of the work actually, but if you did this from scratch you would set up an augmented matrix for the system and reduce:

$$\begin{bmatrix} 1 & -1 & -3 & 0 \\ 1 & 1 & 5 & 0 \\ 0 & 1 & 4 & 0 \end{bmatrix} \xrightarrow{\text{putting into RREF}} \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 4 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

This has a parametric solution of the form:

$$x_1 = -t$$
$$x_2 = -4t$$
$$x_3 = t$$

So to get an example of a nontrival solution to the homogenous system $A\mathbf{x} = \mathbf{0}$ would could set t = 1 and so $x = \begin{bmatrix} -1 \\ -4 \\ 1 \end{bmatrix}$ is a solution. So we have a dependence relation on X:

$$(-1)\begin{bmatrix} 1\\1\\0 \end{bmatrix} + (-4)\begin{bmatrix} -1\\1\\1 \end{bmatrix} + (1)\begin{bmatrix} -3\\5\\4 \end{bmatrix} = \begin{bmatrix} 0\\0\\0 \end{bmatrix} = \mathbf{0}$$

- 2. Using 1. We have $\operatorname{rank}(A) = 2 \neq 3 = (\text{the number of rows})$. Hence the answer is no, and X does not span all of \mathbb{R}^3 .
- 3. Using 1. or 2. the answer is no. Don't forget the definition of a basis!

Example 2: Let
$$A = \begin{bmatrix} 1 & -1 & -3 \\ 1 & 1 & 5 \\ 0 & 1 & 4 \end{bmatrix}$$

- 1. Find a basis X for the column space of A.
- 2. What is the dimension of the column space of A?
- 3. Find a basis Y for the null space of A.
- 4. What is the dimension of the null space of A?
- 5. Find a basis Z for the row space of A.
- 6. What is the dimension of the row space of A?

Solution:

1. We put A into reduced row ecchelon form (RREF):

$$A = \begin{bmatrix} 1 & -1 & -3 \\ 1 & 1 & 5 \\ 0 & 1 & 4 \end{bmatrix} \xrightarrow{\text{putting } A \text{ in RREF}} \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 4 \\ 0 & 0 & 0 \end{bmatrix} = A'$$

So this means that columns 1 and 2 are the pivot columns. The set of pivot columns of A form a basis of the column space of A. Hence,

$$X = \left(\begin{bmatrix} 1\\1\\0 \end{bmatrix}, \begin{bmatrix} -1\\1\\1 \end{bmatrix} \right)$$

- 2. The dimension of the column space is the number of elements in X hence 2. (Remember we also have that the dimension of the column space $= \operatorname{rank}(A) = 2$)
- 3. We find the vector parametric form of the solution set to the homogenous system $A\mathbf{x} = \mathbf{0}$:

$$\begin{bmatrix} 1 & -1 & -3 & 0 \\ 1 & 1 & 5 & 0 \\ 0 & 1 & 4 & 0 \end{bmatrix} \xrightarrow{\text{putting into RREF}} \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 4 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

This has a parametric solution of the form:

$$x_1 = -t$$
$$x_2 = -4t$$
$$x_3 = t$$

or we could write:

$$x_1 = -x_3$$
$$x_2 = -4x_3$$
$$x_3 = x_3$$

So the vector parametric form would be:

$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -x_3 \\ -4x_3 \\ x_3 \end{bmatrix} = x_3 \begin{bmatrix} -1 \\ -4 \\ 1 \end{bmatrix}$$

The set of vectors in the vector parametric form of the solution set of $A\mathbf{x} = \mathbf{0}$ form a basis for the null space of A. Hence,

$$Y = \left(\begin{bmatrix} -1 \\ -4 \\ 1 \end{bmatrix} \right)$$

- 4. The dimension of the null space is the number of elements in Y hence 1. (remember we also have that the dimension of the null space = number of non pivot columns = 3 rank(A) = 3 2 = 1)
- 5. Using the work from 1. we have that a basis for the row space can be made from the nonzero rows of A' (the reduced row echelon form of A). Hence,

$$Z = (\begin{bmatrix} 1 & 0 & 1 \end{bmatrix}, \begin{bmatrix} 0 & 1 & 4 \end{bmatrix})$$

6. The dimension of the row space is the number of elements in Z hence 2. (Remember we also have that the dimension of the row space = $\operatorname{rank}(A) = 2$)