

Show all work clearly and in order. Please box your answers. 10 minutes.

1. Let $X = \{\vec{x}_1, \vec{x}_2, \dots, \vec{x}_k\}$ be a collection of vectors in \mathbb{R}^n . Give the definition of $\text{Span}(X)$:

$$\text{Span}(X) = \left\{ \alpha_1 \vec{x}_1 + \alpha_2 \vec{x}_2 + \dots + \alpha_k \vec{x}_k \mid \alpha_1, \dots, \alpha_k \in \mathbb{R}, \vec{x}_1, \dots, \vec{x}_k \in X \right\}$$

OR

$\text{Span}(X)$ is the set of all linear combinations of vectors in X

2. Let $X = \{\vec{x}_1, \vec{x}_2, \vec{x}_3\}$ where

$$\vec{x}_1 = \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}, \vec{x}_2 = \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix}, \vec{x}_3 = \begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix}$$

Is the vector $\vec{u} = \begin{bmatrix} 1 \\ -2 \\ -2 \end{bmatrix}$ in $\text{Span}(X)$? If so, write \vec{u} as a linear combination of \vec{x}_1, \vec{x}_2 , and \vec{x}_3 .

using the "membership test" discussed in class (and on p 122 of the book)

$$\vec{u} \in \text{Span}(X) \iff \text{there is a linear combination } \vec{u} = c_1 \vec{x}_1 + c_2 \vec{x}_2 + c_3 \vec{x}_3$$

$$= \underbrace{\begin{bmatrix} \vec{x}_1 & \vec{x}_2 & \vec{x}_3 \end{bmatrix}}_A \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix}$$

(so $\begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix}$ is a solution of the equation $A \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = \vec{u}$)

so for this problem:

$$\left[\begin{array}{ccc|c} 1 & 0 & 1 & 1 \\ -1 & 1 & 0 & -2 \\ 0 & 2 & 2 & -2 \end{array} \right] \xrightarrow{R_2 \rightarrow R_2 + R_1} \left[\begin{array}{ccc|c} 1 & 0 & 1 & 1 \\ 0 & 1 & 1 & -1 \\ 0 & 2 & 2 & -2 \end{array} \right] \xrightarrow{R_3 \rightarrow R_3 - 2R_2} \left[\begin{array}{ccc|c} 1 & 0 & 1 & 1 \\ 0 & 1 & 1 & -1 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

so $\vec{x}_1 + \vec{x}_3 = \vec{u}$

$c_2 + c_3 = -1$

$c_3 = \text{anything}$

so in parametric form $\begin{cases} c_1 = 1 - t \\ c_2 = -1 - t \\ c_3 = t \end{cases}$

so pick some t value to get a linear combination (or keep general form)

for example if $t=0$ then $c_1=1, c_2=-1, c_3=0$ so

$$\vec{u} = \vec{x}_1 - \vec{x}_2$$

(NOTE: there are infinitely many solutions?)