

Comments for Lecture 13

2.17.2010

Here is another example problem using methods from section 2.6.

Example: Consider the linear transformation $T:\mathbb{R}^2 \rightarrow \mathbb{R}^2$ defined as:

$$T(\mathbf{x}) = T\left(\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}\right) = \begin{bmatrix} x_2 \\ x_1 \end{bmatrix}$$

where $\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$ is in \mathbb{R}^2 .

Consider also the linear transformation $S:\mathbb{R}^2 \rightarrow \mathbb{R}^2$ defined as:

$$S(\mathbf{y}) = S\left(\begin{bmatrix} y_1 \\ y_2 \end{bmatrix}\right) = y_2$$

where $\mathbf{y} = \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}$ is in \mathbb{R}^2 .

Questions:

- (1) Find the associated matrix A such that $T\mathbf{x} = A\mathbf{x}$ for any \mathbf{x} in \mathbb{R}^2 .
- (2) Find the associated matrix B such that $S\mathbf{y} = B\mathbf{y}$ for any \mathbf{y} in \mathbb{R}^2 .
- (3) Does the composition $S(T(\mathbf{x}))$ exist? If so find the associated matrix C such that $S(T(\mathbf{x})) = C\mathbf{x}$ for any \mathbf{x} in \mathbb{R}^2 .
- (4) Does the composition $T(S(\mathbf{y}))$ exist? If so find the associated matrix D such that $T(S(\mathbf{y})) = D\mathbf{y}$ for any \mathbf{y} in \mathbb{R}^2 .

Solutions:

- (1) We did this in the comments from lecture 12.

$$A = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

- (2) We did this in the comments from lecture 12.

$$B = \begin{bmatrix} 0 & 1 \end{bmatrix}$$

- (3) Using **Theorem 2.6.2** the composition $S(T(\mathbf{x}))$ exists and we have $C = BA$.

$$C = BA = \begin{bmatrix} 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 \end{bmatrix}$$

(Notice that you could also find this by the method used to solve (1) and (2) but I wanted you to see how we can use theorem 2.6.2 to solve this problem.)

(4) This composition does not exist. The domain of T is \mathbb{R}^2 and the codomain of S is \mathbb{R} (so anything in the image of S will be in \mathbb{R} and cannot be an “input” for T). To convince even more look at what would happen:

$$T(S(\mathbf{y})) = T\left(S\left(\begin{bmatrix} y_1 \\ y_2 \end{bmatrix}\right)\right) = T(\underbrace{y_2}_{\text{in } \mathbb{R}}) = \text{Does not exist}$$

The domain of T is \mathbb{R}^2 and y_2 is just a real number and not a vector in \mathbb{R}^2 so we cannot make sense of $T(y_2)$.