SH-ToF: Micro Resolution Time-of-flight Imaging with Super-heterodyne Interferometry

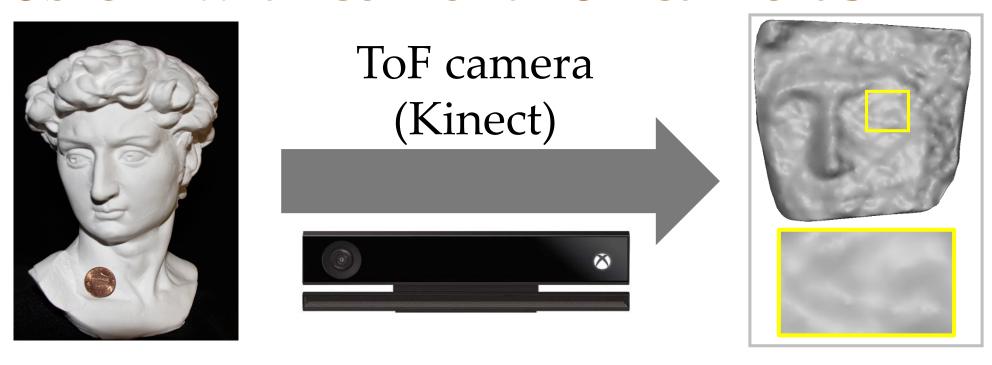
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MOTIVATION

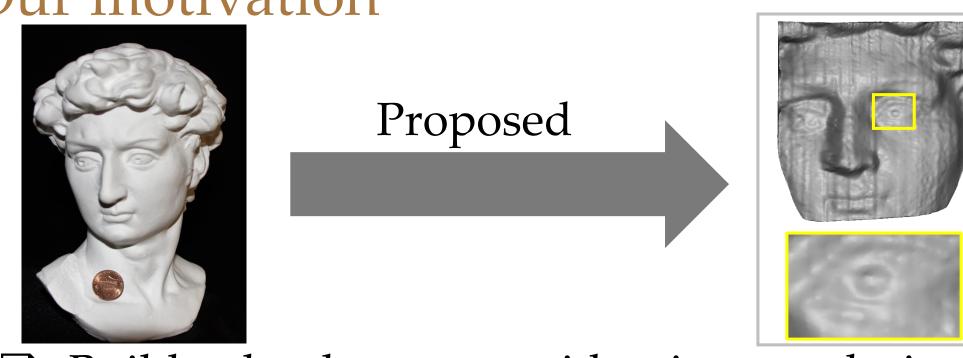
Why ToF cameras for 3D imaging?

- ☐ Large baseline for comparable depth resolution (Triangulation based 3D imaging e.g. structure light camera)
- ☐ ToF camera's compact size

Problem with current ToF cameras



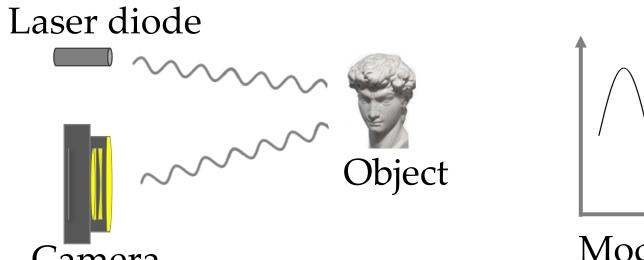
Our motivation



☐ Build a depth camera with micro resolution

BACKGROUND & PROPOSED

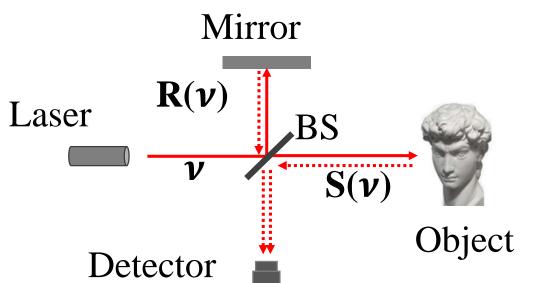
ToF camera

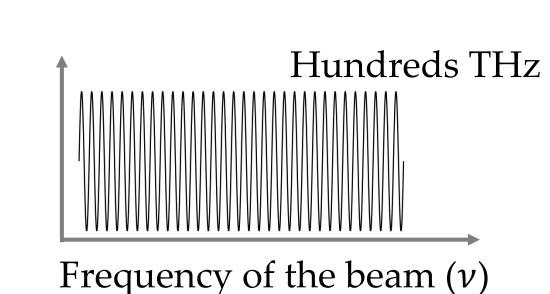


Tens MHz Modulation frequency (f_t)

☐ Meters image range but centimeters depth resolution

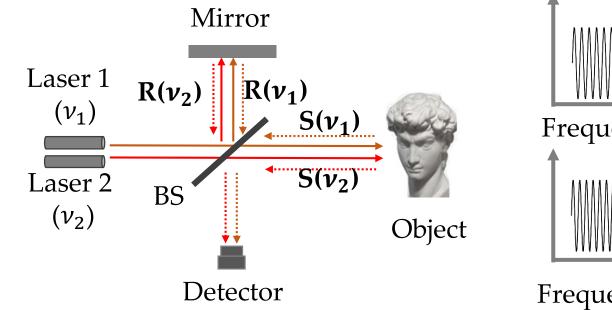
Michelson Interferometry (MI)

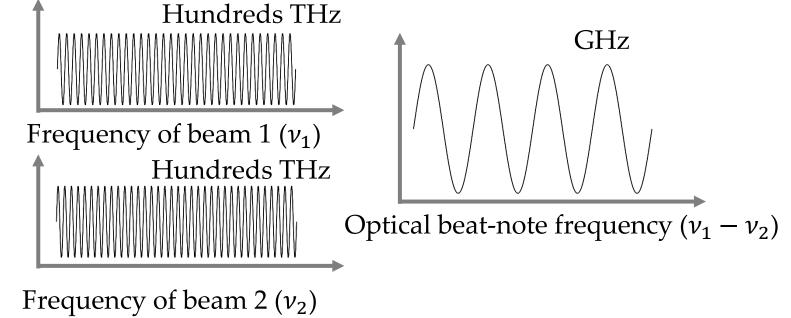




- ☐ Micro depth resolution but micro image range
- □ **Not** able to image optical rough surface (laser speckle)

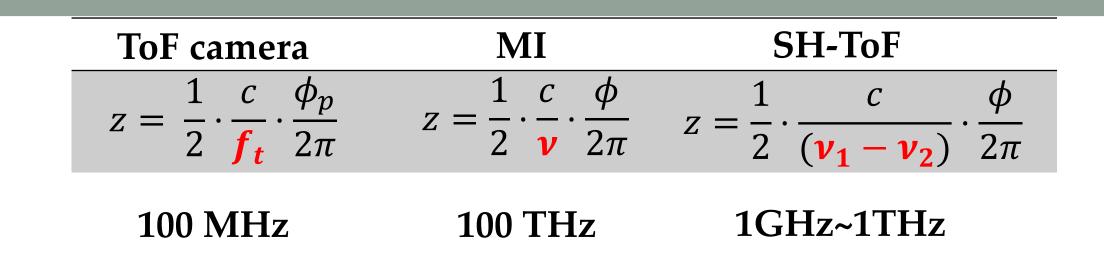
SH-ToF (Our propose)

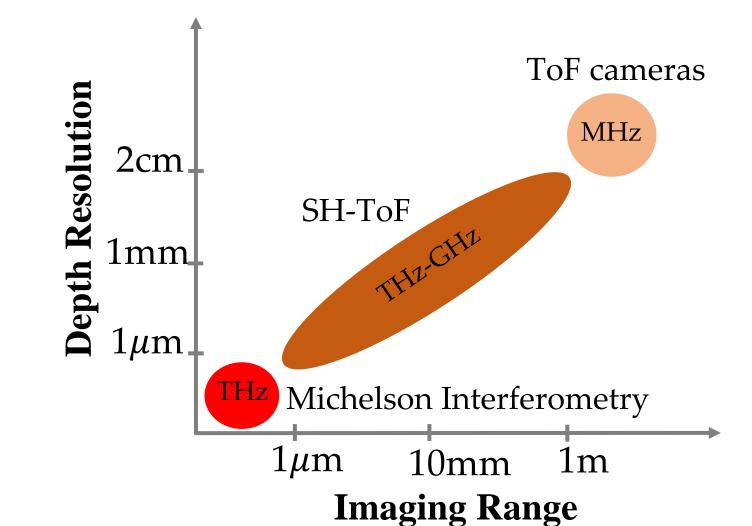




- ☐ Micro depth resolution but tunable image range (micro to meters)
- ☐ **Able** to image optical rough surface (laser speckle)

COMPARISON & CONTRIBUTIONS



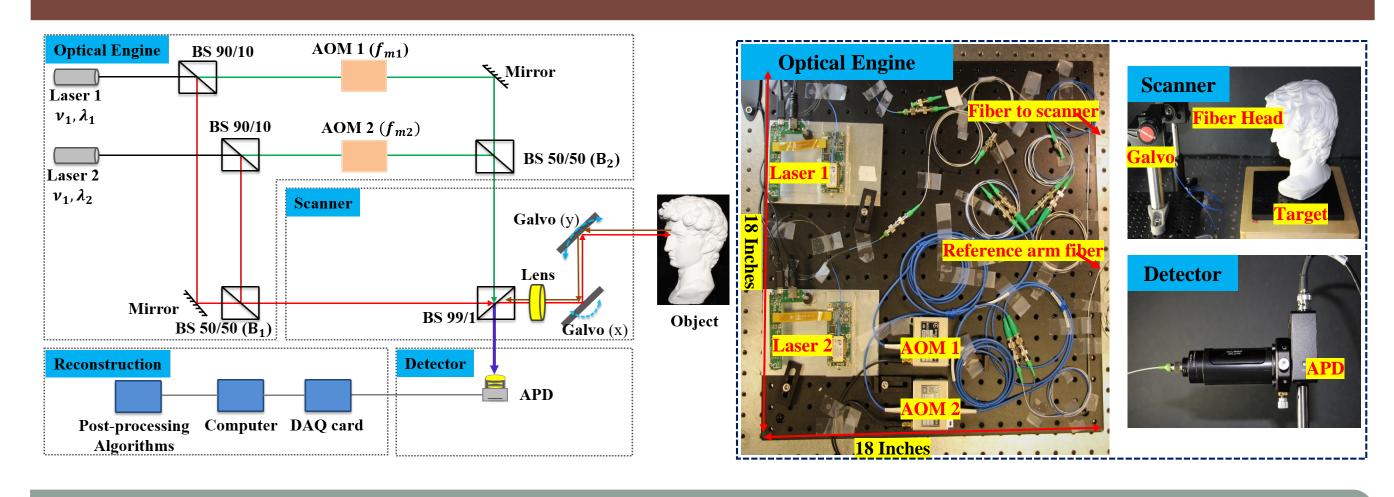


Our Contributions

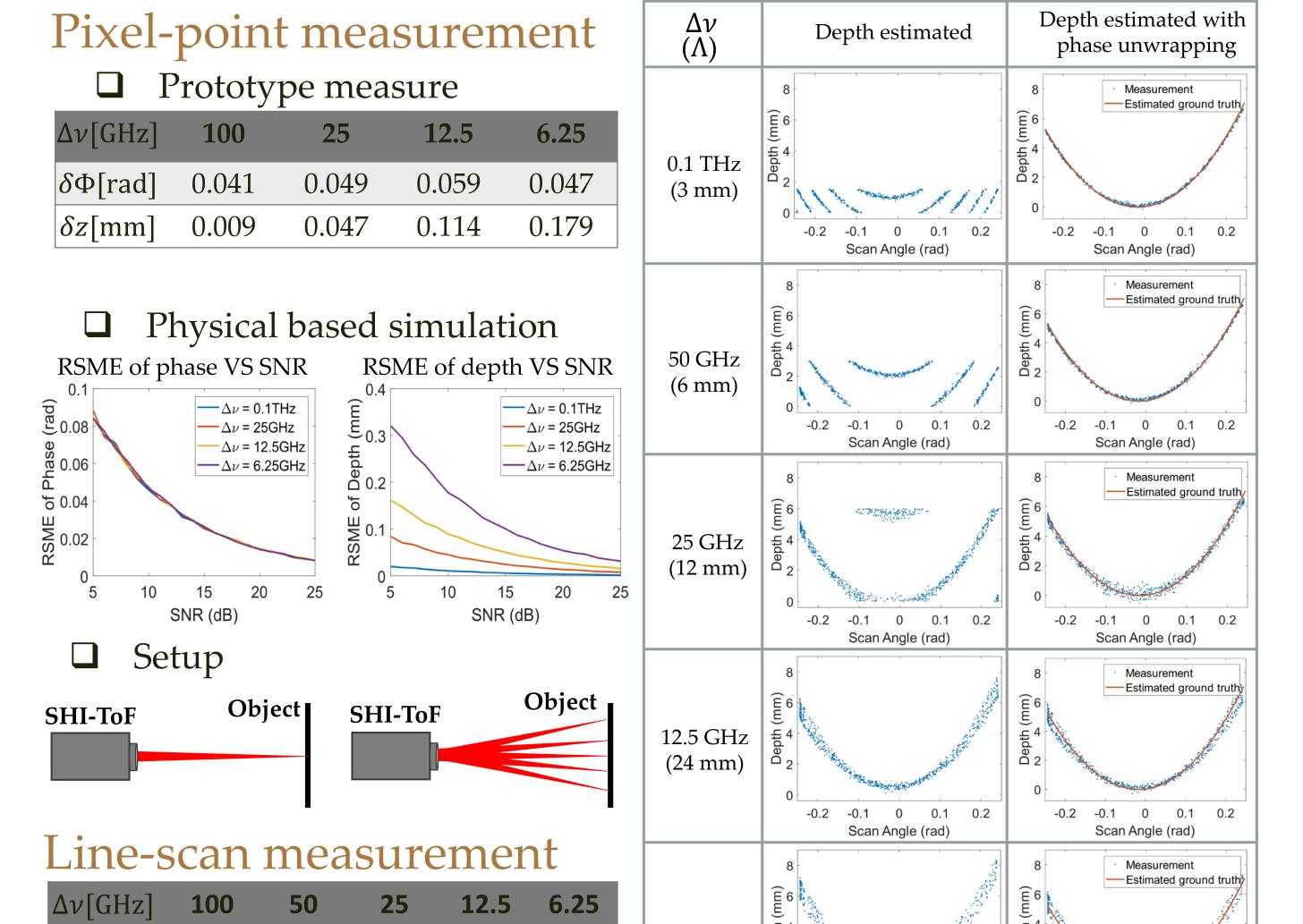
- Micro resolution
- ☐ Tunability between depth resolution and depth range
- ☐ 3D scanning on rough surface

PROTOTYPE

 $\delta z [\text{mm}]$ 0.070 0.093 0.221 0.274 0.437



QUANTITATIVE EVALUATION



6.25 GHz

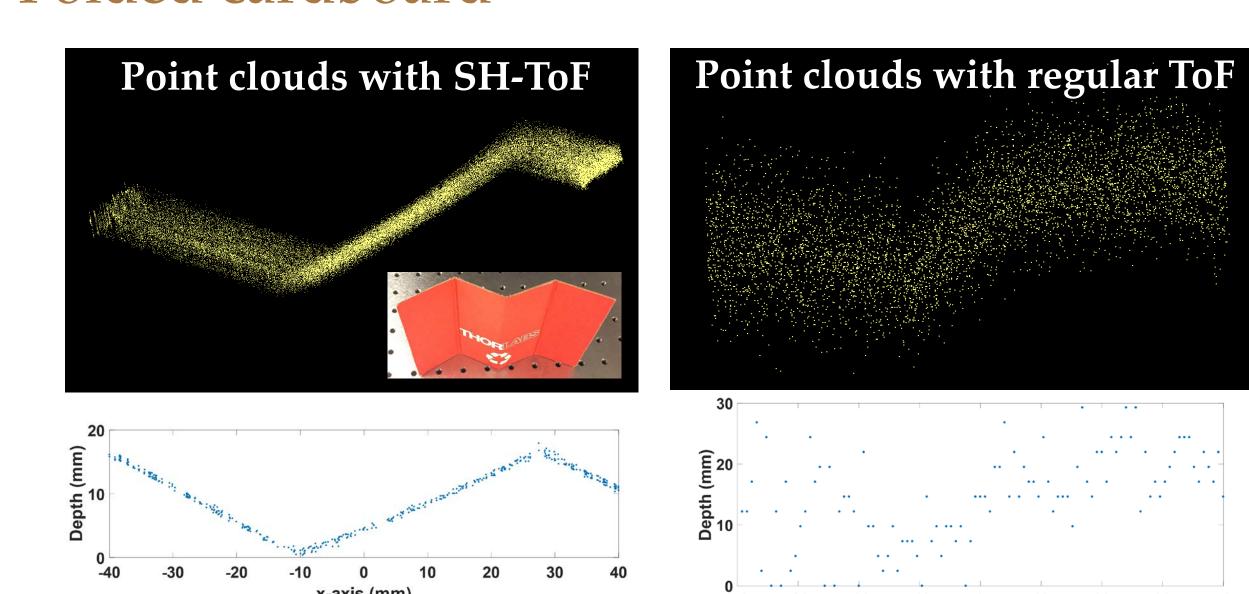
-0.2 -0.1 0 0.1

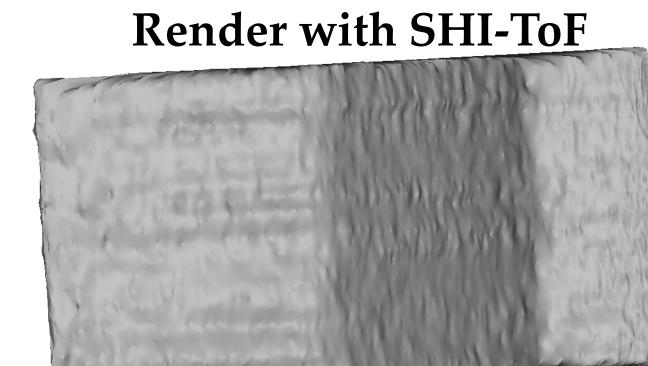
Scan Angle (rad)

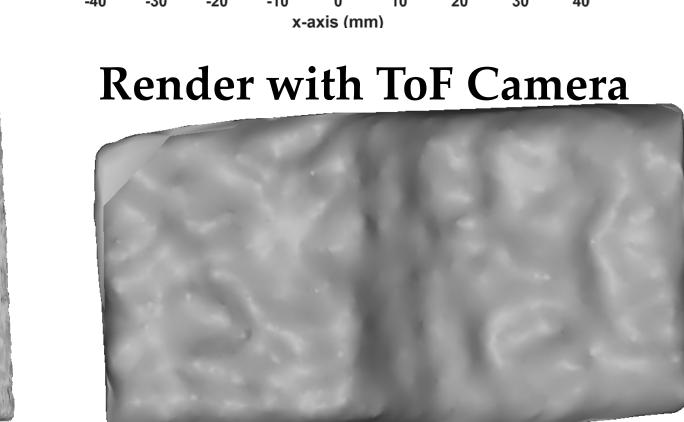
-0.2 -0.1 0 0.1 0.2

3D SCANNING

Folded cardboard



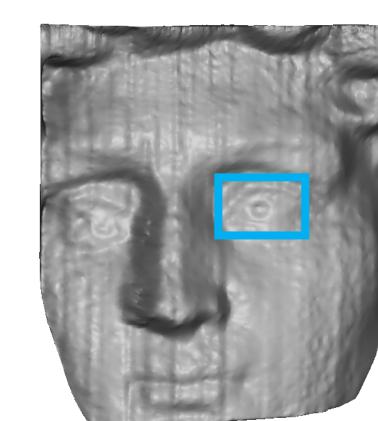


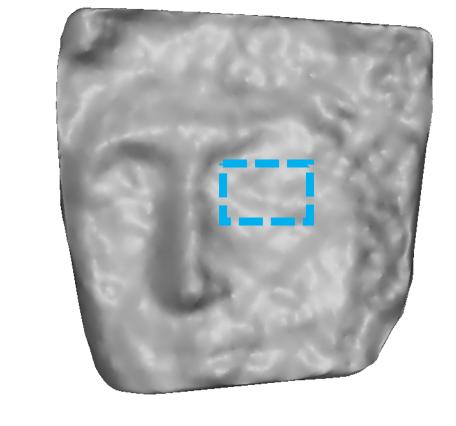


Plaster bust

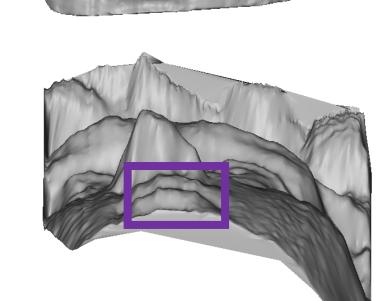
Regular ToF camera scan SH-ToF scan

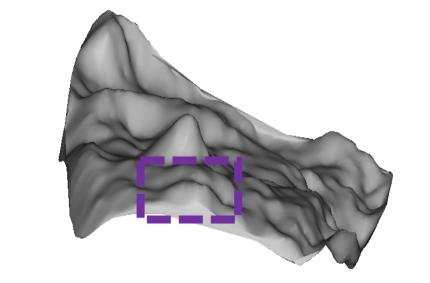


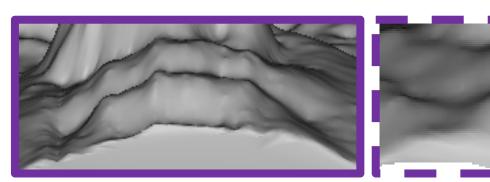


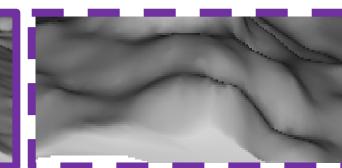




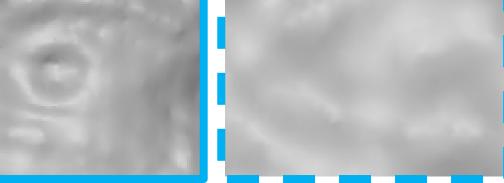












ACKNOWLEDGEMENT





