$$f(0) = \frac{1}{n} \sum_{i=1}^{n} f_i(0) \rightarrow \min_{\Theta \in \mathbb{R}^{P}} G(0)$$

$$G_{k+1} = G_k - \mathcal{L}_k \nabla f(\theta_k) G(0)$$

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 $\frac{\partial \mathcal{L}}{\partial \mathcal{L}} = \left[-\frac{1}{\sqrt{(0)}} - \sqrt{\sqrt{(0)}} \right] \cdot \frac{1}{\sqrt{2}}$ Order $\frac{1}{2} = -\sqrt{1}(4)$

$$C_{1}(1) - \Theta(1) = \frac{t^{2}}{2} [g_{1}, g_{2}] \theta_{0} + O(t^{3})$$

$$[g_{1}, g_{2}] = \frac{3g_{1}}{3g_{2}} g_{2} - \frac{3g_{2}g_{1}}{3g_{1}} + O(t^{3})$$

I:
$$Q_{I}(h) = Q_{A}(h) \circ Q_{A}($$

$$G_{II}(t) - G(t) = t^{3} \left(\frac{1}{12} \left[g_{2}, g_{3}, g_{3} \right] - \frac{1}{24} \left[g_{1}, g_{1}, g_{3}, g_{3} \right] - \frac{1}{24} \left[g_{1}, g_{1}, g_{2}, g_{3} \right] + G(t^{4}) \right)$$

 $\Theta_{K+1} = \Theta_{K} - A G_{1}(\Theta_{K})$ OK+2 = OK+1 & G2 (OKM) porder

$$G_{K+1} = G_K - \lambda g_1(G_K)$$

$$G_{K+2} = G_{K+1} - \lambda g_2(G_{K+1})$$

$$G_{K+3} = G_{K+2} - \lambda g_2(G_{K+2})$$

$$G_{K+4} = G_{K+3} - \lambda g_1(G_{K+2})$$

$$\frac{d\theta}{dt} = -g_1(\theta) - g_0(\theta)$$

$$0^* - \text{Steady state} \left(\frac{d\theta}{dt} = 0\right)$$

$$\frac{d\theta}{dt} = -g_1(\theta) \longrightarrow g_1(\theta^*) + g_2(\theta^*) = 0$$

016 = - G1 + C - G2 - C $\frac{d}{dt} - \frac{1}{3} + \frac{1}{3} = \frac{$ $\frac{g_1(\theta^*) = g_1(\theta^*) + \frac{1}{2}(g_2(\theta^*) - g_1(\theta^*)) = g_1(\theta^*) = g_1(\theta^*) + \frac$

.

SAG $\frac{1}{n} = f_i(\theta) \rightarrow min$ $\frac{SGD}{O_{K+1}} = \frac{1}{O_K} - \frac{1}{A_K} = \frac{1}{O_K} - \frac{1}{A_K} = \frac{1}{A_K}$

