

# ochin\_CM4 Hardware test number 8 CSI cameras test

### **Devices used for tests**

- 1. ochin CM4 carrier board
- 2. Raspberry Pi CM4 module with eMMC
- 3. Power Supply 0-30Vdc
- 4. CSI camera

## **Test description**

the purpose of this test is to verify the proper functioning of the two CSI interfaces, available on the ochin board. To test the CSI cameras we will use a software called mjpg-streamer, able to display the stream of the cameras on a web page.

## Preliminary configuration

The ochin CM4 board allow to connect 2 CSI camera at the same time.

Since every camera needs a I2C interface, one I2C interface is shared between the Camera0 (the one on the side of the board)

and one of the GHS connectors (for external i2c devices).

To be able to use the Camera0 is needed to short the two smd jumper (SCL1 and SDA1) close to the Camera0 connector.

Please look at the ochin\_cm4 manual at page 6.

To enable the CSI Cameras interfaces is also needed to load the proper device tree at boot. The dt-blob.bi, present in the "files" folder of this github repository, enables both cameras. To load it at boot it must be copied inside of the "/boot" folder of the CM4.

After placed the device tree within the "/boot" folder shut down the CM4 and mount the cameras to the board.

Once rebooted, if the cameras have been found, you should be able to find them as "/dev/video0" and "/dev/video1".

issuing:

Is /dev/video\*

you should receive:

/dev/video0 /dev/video10 /dev/video12 /dev/video14 /dev/video16

/dev/video1 /dev/video13 /dev/video15 /dev/video18

and issuing:

vcgencmd get\_camera

you should receive (with 2 camera connected):

supported=2 detected=2

Installation of mjpg-streamer:

sudo apt-get update

sudo apt-get upgrade

sudo apt-get install cmake libjpeg8-dev imagemagick git

we clone the jacksonlian branch because is compatible with raspicam

```
git clone https://github.com/jacksonliam/mjpg-streamer
      cd mjpg-streamer/mjpg-streamer-experimental
open the file "utils.c" and comment out the following lines:
//#include ux/stat.h>
//#include <sys/stat.h>
compile teh software issuing:
      make
after compiled you're ready to stream the camera to a webpage.
find the cm4 ip address (for later use):
      ifconfig
Test execution
Start streaming issuing:
      ./mjpg_streamer -i "./input_uvc.so -d /dev/video0 -f 30 -r 1280x720" -o
"./output_http.so -w ./www"
modify /dev/video0 to /dev/video1 to change the camera
```

To watch the camera stream, open a browser on a pc (in the same subnet of the CM4):

http://CM4\_ipaddress:8080

and select "stream" on the left menu

#### Test result

Test passed for both cameras