#### WEEKLY REPORT and MEETING AGENDA

Report #:8	Project Name: Traffix Object/Lane Detection - 2A1	
Date:11/07/2022	Prepared by: Pavan Poladi	

## Agenda for the weekly meeting

- Talk about what we have accomplished thus far.
- 2. Ask about whether Instructor is happy with our progress.
- 3. Ask any clarifying questions we have about project success metrics/grading.
- Talk about what we aim to accomplish this week.
- Set up times with professor or instructor to get help if needed.

# Accomplishments during this period

- We completed a minimum viable product by being able to successfully run the BDD100K dataset using the HybridNets detection model in the ROS system.
- We created a step-by-step tutorial/documentation on how to run the image\_subscriber.py file which runs HybridNets on ROS.
- We were all able to set up our new organized environments apart from Viet because his laptop is currently having issues.
- 4. We made final changes to the CDR document and submitted it.
- We had a successful CDR presentation and received good feedback.
- Fixed the color filter differences between ROS and HybridNets models.

# Plans for next period

- Begin Debugging our codebase to enable roscore to work as intended.
- Add functionality to have output images display on ROS GUI.
- 3. Make the bounding boxes more apparent to the eye.
- Try implementing ONNX-HybridNets as alternative option for users.
- 5. Figure out how to retrieve the accuracy readings to create data comparisons.

## Project management status

- Schedule and milestones: We finally have a minimal viable product as we were able to run the BDD100K dataset using HybridNets on the ROS System.
- Teamwork: Team is working well but are having to adjust as Viet's laptop is not working.
- Purchases: No new purchases have been made beyond one Google Collab Subscription (\$10 a month)

Minutes from previous meeting
There was no team meeting with the professors last week because we had our CDR
presentations on Monday October 31st.