



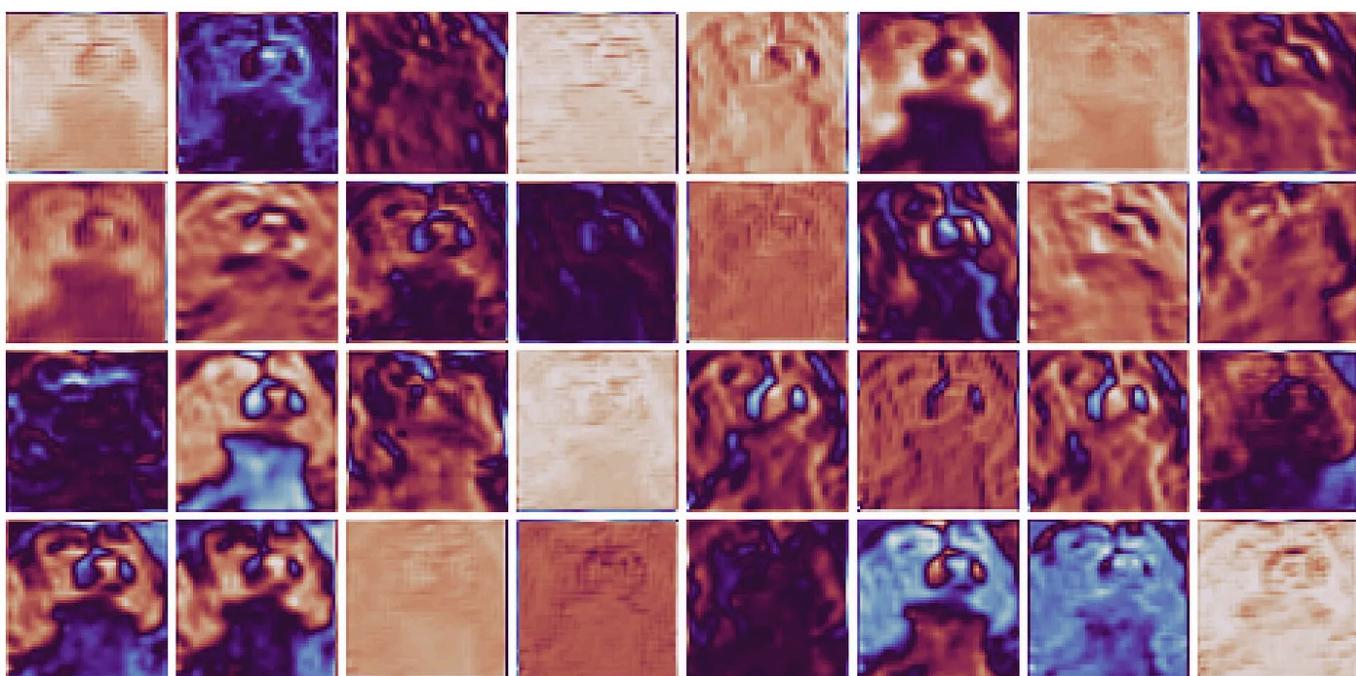
# How to Visualize Layer Activations in PyTorch

Reza Kalantar · [Follow](#)

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This tutorial will demonstrate how to visualize layer activations in a pretrained ResNet model using the CIFAR-10 dataset in PyTorch. CIFAR-10 is a well-known dataset consisting of 60,000 32x32 color images categorized into 10 classes, making it a popular choice for developing and testing image recognition algorithms. Visualizing activations, the outputs of various layers within the model, is crucial for understanding how deep neural networks process visual information, which can help diagnose model behavior and inspire improvements.



## Environment Setup

Ensure your environment is prepared with the necessary libraries:

```
pip install torch torchvision matplotlib
```

## Load and Visualize CIFAR-10 Data

First, load the CIFAR-10 dataset and visualize some of the images. This helps in understanding the input that the model processes.

```

import torchvision
import torchvision.transforms as transforms
import matplotlib.pyplot as plt

# Transformations for the images
transform = transforms.Compose([
    transforms.Resize(256),
    transforms.CenterCrop(224),
    transforms.ToTensor(),
    transforms.Normalize(mean=[0.485, 0.456, 0.406], std=[0.229, 0.224, 0.225])
])

# Load CIFAR-10 dataset
trainset = torchvision.datasets.CIFAR10(root='./data', train=True, download=True, transform=transform)
trainloader = torch.utils.data.DataLoader(trainset, batch_size=4, shuffle=True)

# Function to show images
def imshow(img):
    img = img.numpy().transpose((1, 2, 0))
    mean = np.array([0.485, 0.456, 0.406])
    std = np.array([0.229, 0.224, 0.225])
    img = std * img + mean # unnormalize
    plt.imshow(img)
    plt.show()

# Get some images
dataiter = iter(trainloader)
images, labels = next(dataiter)

# Display images
imshow(torchvision.utils.make_grid(images))

```



Sample images from the CIFAR-10 dataset

## Load Pretrained Model and Set Up Hooks

Load a pretrained ResNet model from PyTorch’s model zoo and set up hooks on specific layers to capture activations during the forward pass.

```

import torch
from torchvision.models import resnet18

# Load pretrained ResNet18
model = resnet18(pretrained=True)
model.eval() # Set the model to evaluation mode

# Hook setup
activations = {}
def get_activation(name):
    def hook(model, input, output):
        activations[name] = output.detach()
    return hook

# Register hooks

```

```
model.layer1[0].conv1.register_forward_hook(get_activation('layer1_0_conv1'))
model.layer4[0].conv1.register_forward_hook(get_activation('layer4_0_conv1'))
```

## Run Data Through the Model

Process the images through the model to capture activations.

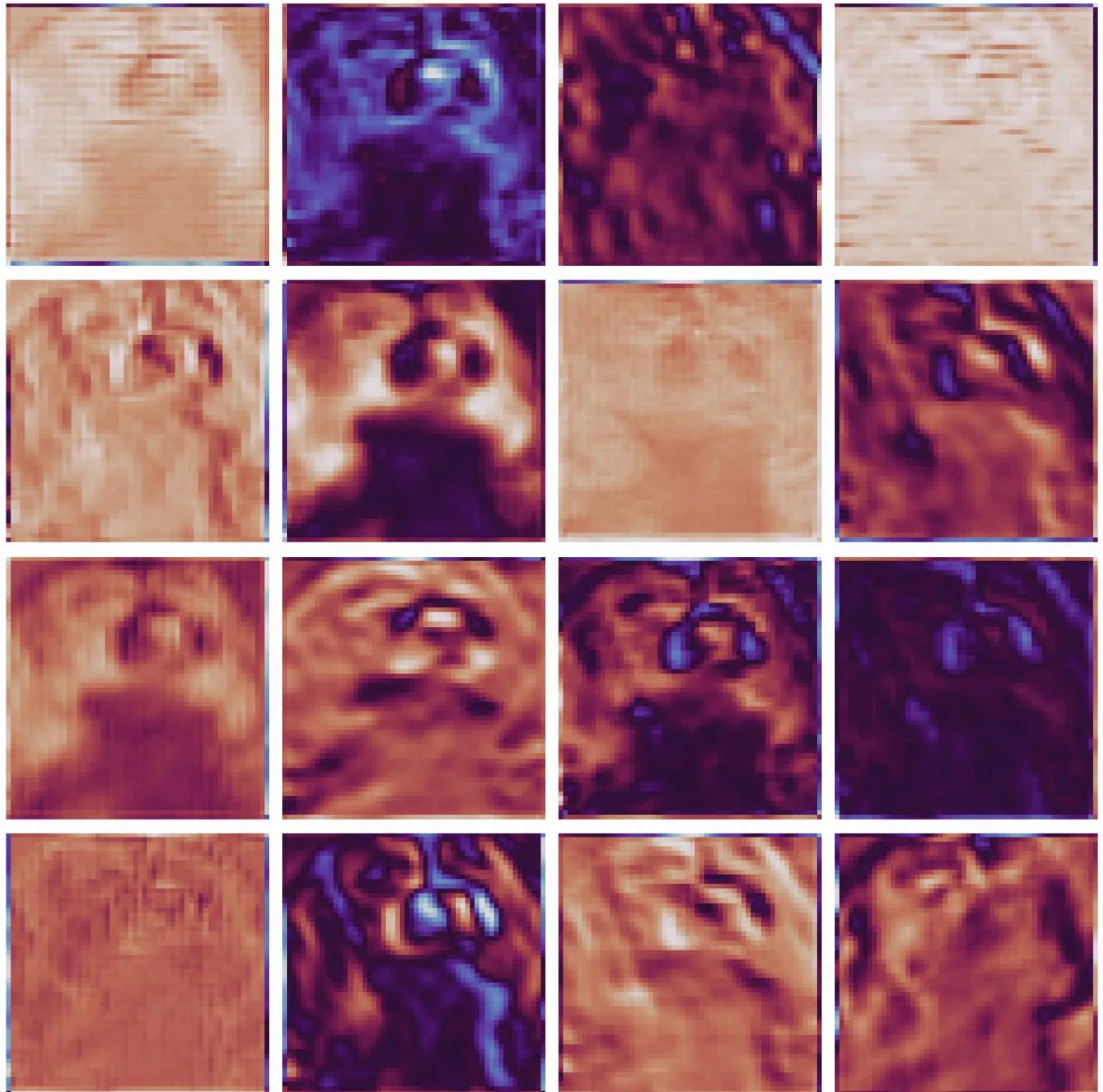
```
# Run the model
with torch.no_grad():
    output = model(images)
```

## Visualize Activations

Using the hooks set up in Step 3, visualize the activations to gain insight into what features each layer is extracting.

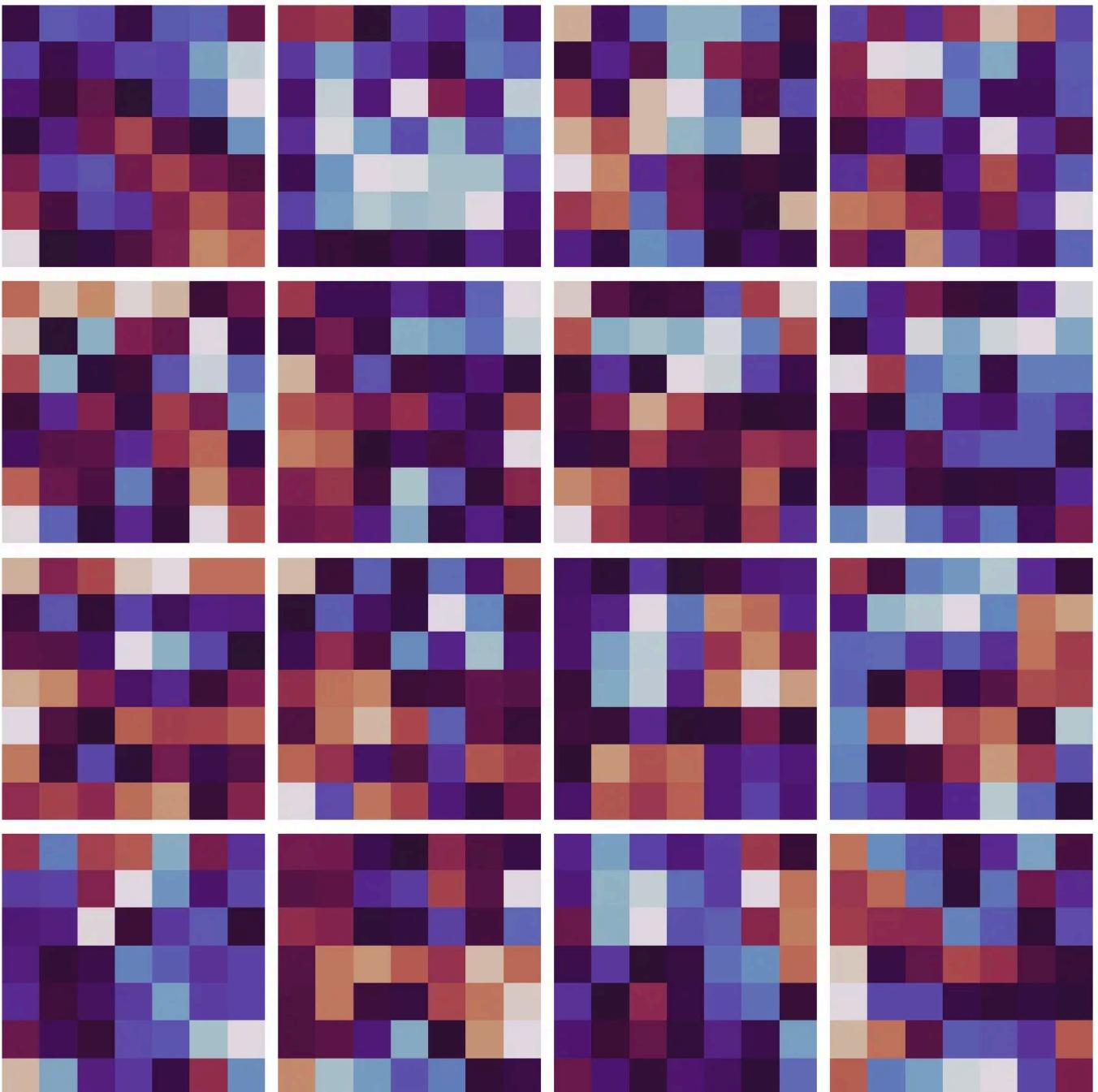
```
# Visualization function for activations
def plot_activations(layer, num_cols=4, num_activations=16):
    num_kernels = layer.shape[1]
    fig, axes = plt.subplots(nrows=(num_activations + num_cols - 1) // num_cols, ncols=num_cols, figsize=(12, 8))
    for i, ax in enumerate(axes.flat):
        if i < num_kernels:
            ax.imshow(layer[0, i].cpu().numpy(), cmap='twilight')
            ax.axis('off')
    plt.tight_layout()
    plt.show()
```

```
# Display a subset of activations
plot_activations(activations['layer1_0_conv1'], num_cols=4, num_activations=16)
```



Visualize 16 activations from layer 'layer1\_0\_conv1'

```
plot_activations(activations['layer4_0_conv1'], num_cols=4, num_activations=16)
```



Visualize 16 activations from layer 'layer4\_0\_conv1'

## Conclusion

Visualizing activations helps in understanding how various layers in a convolutional neural network respond to different features in the input images. This method provides insights into the internal workings of the model, highlighting which features are most influential for the classification task and where the model might be focusing incorrectly, thus informing potential improvements. By visualizing different layers, you can assess whether early layers capture basic features like edges and textures, while deeper layers capture more complex features. This knowledge is invaluable for diagnosing issues, tweaking layer architectures, and improving the overall model performance.

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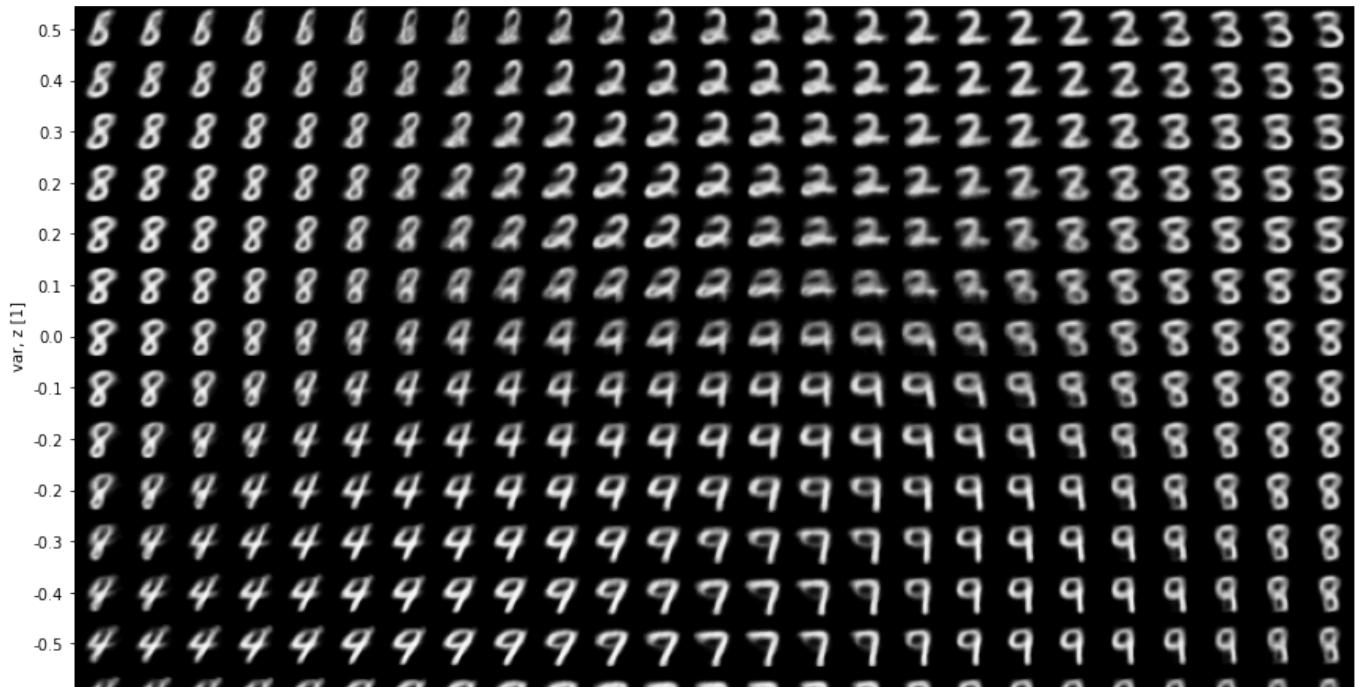
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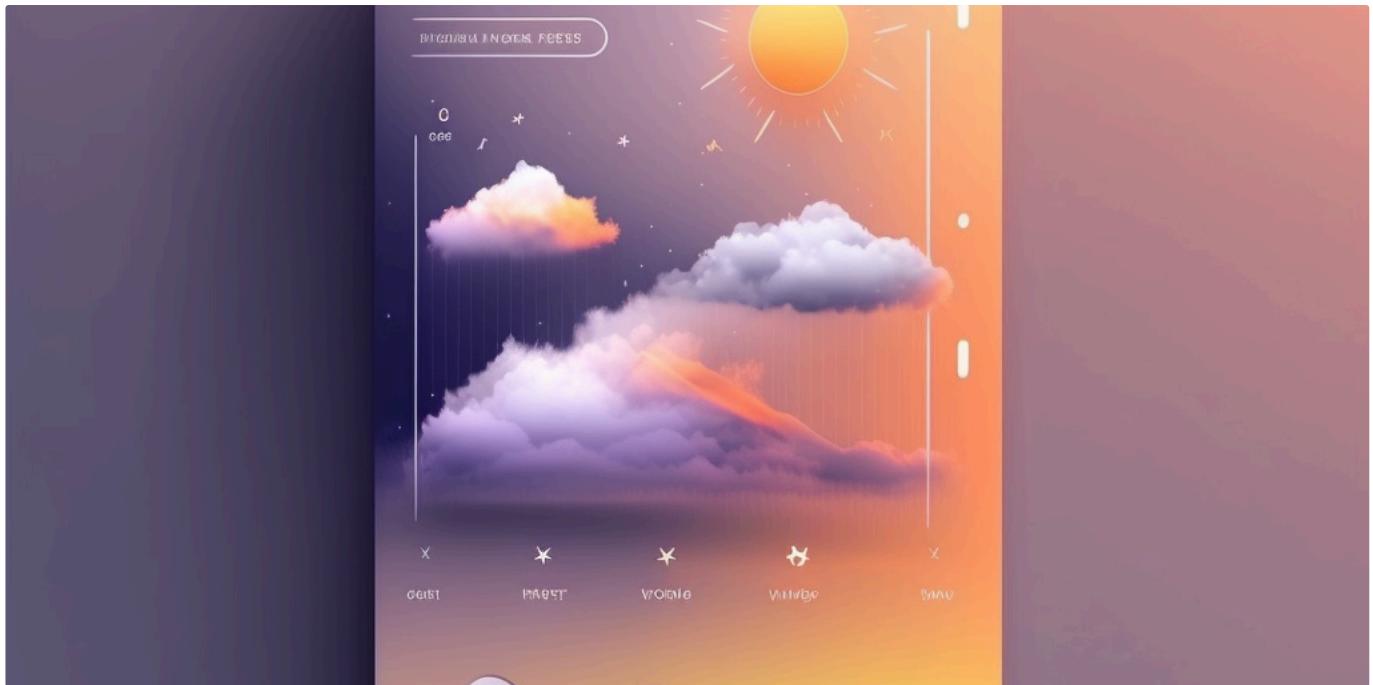
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```
if !exist('scanIdx') || isempty(c), numel(c));
    scanIdx{1} = tmp(scanIdx);
end

nScans = numel([scanIdx{:}]);

days = struct('Day', string(), 'Id', string(), 'ImageLabel', string(), ...
    'ScanLabel', false, 'Pan', cell(nScans, 1), ...
    'Range', cell(nScans, 1));
for i = 1:nScans
    days(i).Day = 'Day' + num2str(i);
    days(i).Id = scanIdx{i};
    if exist('ProgressBar')
        progressbar1 = ProgressBar(nScans, 'Spinner');
        progressbar1.start;
    end
    for j = 1:10
        id = scanIdx{i}(j);
        % ...
    end
end
```

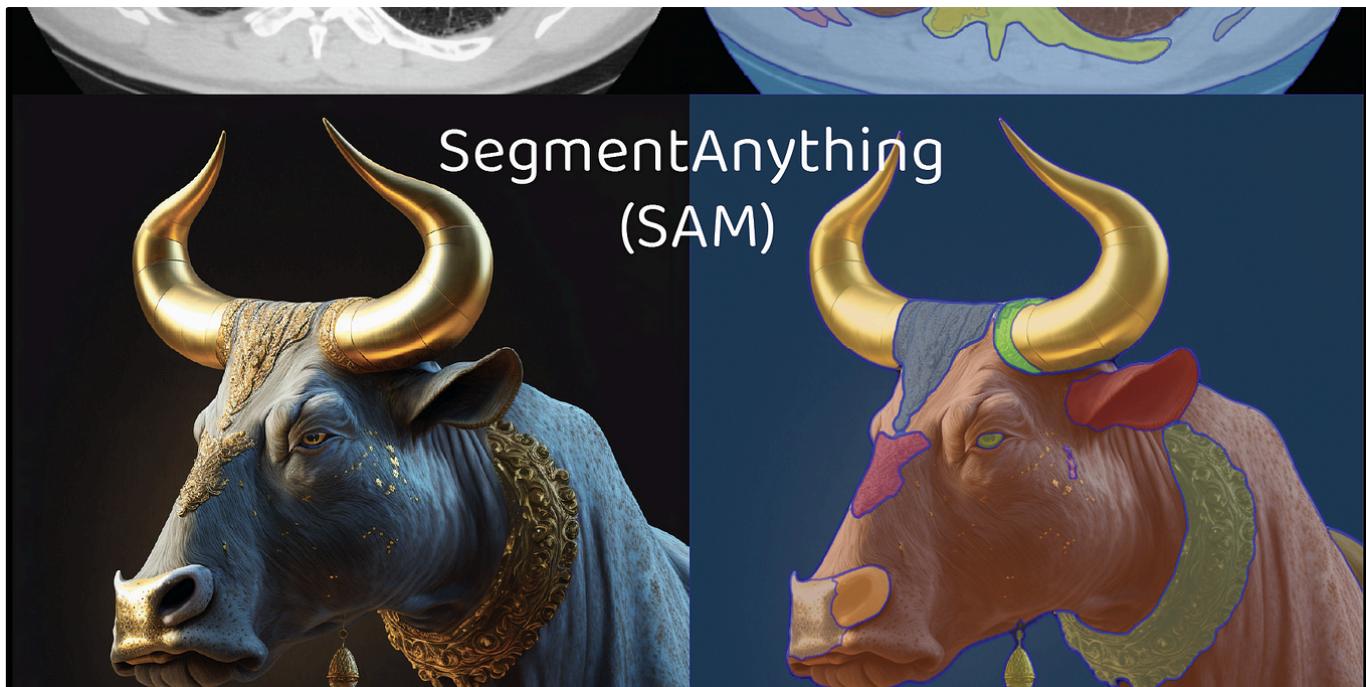
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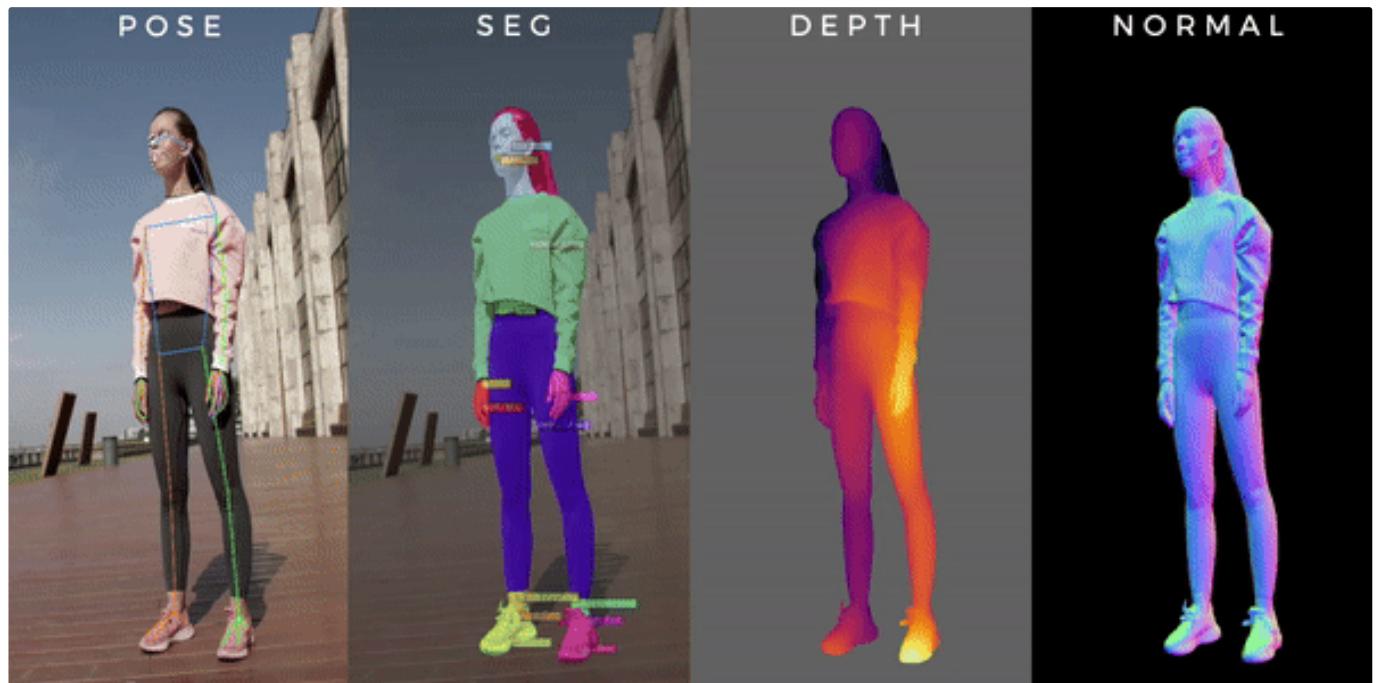
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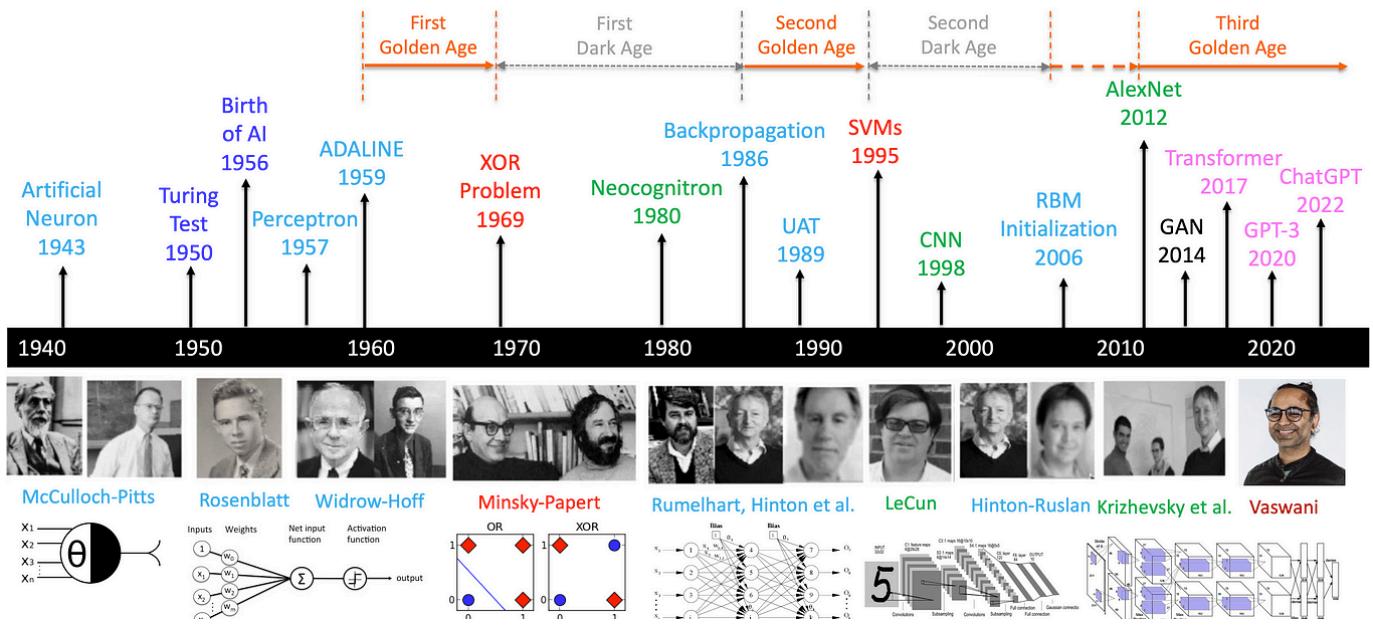
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