

# fn make\_scalar\_float\_laplace\_cks20

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This proof resides in “**contrib**” because it has not completed the vetting process.

Proves soundness of `make_scalar_float_laplace_cks20` in `mod.rs` at commit `f5bb719` (outdated<sup>1</sup>). The function on the resulting measurement takes in a data set `x` (a single float), and returns a sample from the Discrete Laplace Distribution centered at `x`, with a fixed noise scale.

## PR History

- [Pull Request #490](#)

## 1 Hoare Triple

### Preconditions

- Variable `input_domain`, of type `AtomDomain<T>`
- Variable `input_metric`, of type `AbsoluteDistance<T>`
- Variable `scale`, of type `Q0`
- Variable `k`, of type `Option<i32>`
- Type `T` must have trait `Float` and `CastInternalRational`
- Type `i32` must be constructable from the bit representation of `T` (used to calibrate relaxation)

### Pseudocode

```
1 def make_scalar_float_laplace_cks20(input_domain, input_metric, scale: Q0, k):
2     if scale.is_sign_negative():
3         raise ValueError("scale must not be negative")
4
5     k, relaxation = get_discretization_consts(k)
6
7     if scale.is_zero():
8         def function(x: T):
9             return x
10    else:
11        def function(x: T):
12            return sample_discrete_laplace_Z2k(x, scale, k)
13
14    return Measurement(
```

---

<sup>1</sup>See new changes with `git diff f5bb719..0ede89a5 rust/src/measurements/laplace/continuous/mod.rs`

```

15     input_domain,
16     function,
17     input_metric,
18     MaxDivergence(Q0),
19     privacy_map=laplace_map(scale, relaxation=relaxation)
20 )

```

## Postcondition

For every setting of the input parameters (`input_domain`, `input_metric`, `scale`, `k`, `T`) to `make_scalar_float_laplace_cks20` such that the given preconditions hold, `make_scalar_float_laplace_cks20` raises an exception (at compile time or run time) or returns a valid measurement. A valid measurement has the following property:

1. (Privacy guarantee). For every pair of elements  $x, x'$  in `input_domain` and for every pair (`d_in`, `d_out`), where `d_in` has the associated type for `input_metric` and `d_out` has the associated type for `output_measure`, if  $x, x'$  are `d_in`-close under `input_metric`, `privacy_map(d_in)` does not raise an exception, and `privacy_map(d_in) ≤ d_out`, then `function(x), function(x')` are `d_out`-close under `output_measure`.

## 2 Proof

*Proof.* (Privacy guarantee.)

The proof assumes the following lemma.

**Lemma 2.1.** `get_discretization_consts`, `sample_discrete_laplace_Z2k` and `laplace_map` each satisfy their postcondition.

This mechanism can be thought of as a stable transformation from a floating-point number to a rational number, followed by a mechanism that adds noise to the rational number.

### 2.1 Rounding Transformation

The transformation rounds the input to the nearest rational number where the denominator is no greater than  $2^k$ . By the postcondition of `get_discretization_consts`, this rounding changes the input by at most `relaxation`.

$$\begin{aligned}
& \max_{x \sim x'} d_{Abs}(round(x), round(x')) \\
&= \max_{x \sim x'} |round(x) - round(x')| \\
&\leq \max_{x \sim x'} |x - x'| + \text{relaxation} && \text{by postcondition of } \text{get\_discretization\_consts} \\
&\leq \text{d\_in} + \text{relaxation} && \text{by definition of absolute distance}
\end{aligned}$$

Therefore the rounding transformation is `d_in + relaxation`-close under the absolute distance.

### 2.2 Noise Measurement

`sample_discrete_laplace_Z2k` can only fail due to lack of system entropy. This is usually related to the computer's physical environment and not the dataset. The rest of this proof is conditioned on the assumption that this function does not raise an exception.

Let  $x$  and  $x'$  be datasets that are  $d_{in}$ -close with respect to `input_metric`. Here, the metric is `AbsoluteDistance<T>`. By the postcondition of `sample_discrete_laplace_Z2k`, the output of the function follows the Discrete Laplace Distribution with scale `scale`.

$$\begin{aligned}
& \max_{x \sim x'} D_{\infty}(M(x), M(x')) \\
&= \max_{x \sim x'} \max_{z \in \text{supp}(M(\cdot))} \ln \left( \frac{\Pr[M(x) = z]}{\Pr[M(x') = z]} \right) && \text{substitute } D_{\infty} \\
&= \max_{x \sim x'} \max_{z \in \mathbb{Z}} \ln \left( \frac{\Pr[\text{DLap}(x, b) = z]}{\Pr[\text{DLap}(x', b) = z]} \right) && \text{where } b \text{ is the noise scale} \\
&= \max_{x \sim x'} \max_{z \in \mathbb{Z}} \ln \left( \frac{\frac{\exp^{1/b} - 1}{\exp^{1/b} + 1} \exp\left(-\frac{|x-z|}{b}\right)}{\frac{\exp^{1/b} - 1}{\exp^{1/b} + 1} \exp\left(-\frac{|x'-z|}{b}\right)} \right) && \text{use pdf of Discrete Laplace} \\
&= \max_{x \sim x'} \max_{z \in \mathbb{Z}} \ln \left( \frac{\exp\left(-\frac{|x-z|}{b}\right)}{\exp\left(-\frac{|x'-z|}{b}\right)} \right) \\
&= \max_{x \sim x'} \max_{z \in \mathbb{Z}} \frac{|x' - z| - |x - z|}{b} && \text{exp and ln cancel} \\
&\leq \frac{\max_{x \sim x'} |x - x'|}{b} && \text{by reverse triangle inequality} \\
&= \frac{d_{in}}{b} && \text{by definition of absolute distance}
\end{aligned}$$

Therefore it has been shown that for every pair of elements  $x, x' \in \text{input\_domain}$  and every  $d_{L1}(x, x') \leq d_{in}$  with  $d_{in} \geq 0$ , if  $x, x'$  are  $d_{in}$ -close then `function(x), function(x')` are `privacy_map(d_in)`-close under `output_measure` (the Max-Divergence).

### 2.3 Chained Measurement

The chained map provides a guarantee that the output distributions are at most  $\frac{d_{in} + \text{relaxation}}{b}$ -close under the max-divergence. This is consistent with the postcondition of `laplace_map`.

Therefore it has been shown that for every pair of elements  $x, x' \in \text{input\_domain}$  and every  $d_{Abs}(x, x') \leq d_{in}$  with  $d_{in} \geq 0$ , if  $x, x'$  are  $d_{in}$ -close then `function(x), function(x')` are `privacy_map(d_in)`-close under `output_measure` (the Max-Divergence).

□