fn make_float_to_bigint

Michael Shoemate

This proof resides in "contrib" because it has not completed the vetting process.

Proves soundness of the implementation of make_float_to_bigint in mod.rs at commit f5bb719 (out-dated¹).

1 Hoare Triple

Precondition

Compiler-Verified

• Generic T implements trait SaturatingCast<IBig>

User-Verified

None

Pseudocode

```
def make_float_to_bigint(
      input_space: tuple[VectorDomain[AtomDomain[T]], LpDistance[P, QI]],
  ) -> Transformation[
      VectorDomain[AtomDomain[T]],
      VectorDomain[AtomDomain[IBig]],
      LpDistance[P, QI],
      LpDistance[P, RBig],
  ]:
9
      input_domain, input_metric = input_space
10
11
      if input_domain.element_domain.nullable():
          raise "input_domain may not contain NaN elements"
13
      size = input_domain.size
14
      rounding_distance = get_rounding_distance(k, size, T)
16
      def elementwise_function(x_i): #
17
          x_i = RBig.try_from(x_i).unwrap_or(RBig.ZERO)
18
          return find_nearest_multiple_of_2k(x_i, k) #
19
20
      def stability_map(d_in):
21
22
               d_in = RBig.try_from(d_in)
23
24
          except:
               raise f"d_in ({d_in}) must be finite"
25
          return x_mul_2k(d_in + rounding_distance, -k) #
```

 $^{^1\}mathrm{See}$ new changes with git diff f5bb719..be04bf3f rust/src/measurements/noise/nature/float/mod.rs

```
27
       return Transformation.new(
28
           input_domain,
29
30
           VectorDomain(#
               element_domain=AtomDomain.default(IBig),
31
               size=size,
33
           Function.new(lambda x: [elementwise_function(x_i) for x_i in x]),
34
           input_metric,
35
           LpDistance.default(),
36
37
           StabilityMap.new_fallible(stability_map),
38
```

Postcondition

Theorem 1.1.

Theorem 1.2. For every setting of the input parameters (T) to make_float_to_bigint such that the given preconditions hold, make_float_to_bigint raises an exception (at compile time or run time) or returns a valid transformation. A valid transformation has the following properties:

- 1. (Appropriate output domain). For every element x in input_domain, function(x) is in output_domain or raises a data-independent runtime exception.
- 2. (Stability guarantee). For every pair of elements x, x' in input_domain and for every pair (d_{in}, d_{out}) , where d_in has the associated type for input_metric and d_out has the associated type for output_metric, if x, x' are d_in-close under input_metric, stability_map(d_in) does not raise an exception, and stability_map(d_in) \leq d_out, then function(x), function(x') are d_out-close under output_metric.

Proof. In the definition of the function on line 17, RBig.try_from is infallible when the input is non-nan making the function infallible. There are no other sources of error in the function, so the function cannot raise data-dependent errors.

The function also always returns a vector of IBigs, of the same length as the input, meaning the output of the function is always a member of the output domain, as defined on line 30.

The stability argument breaks down into three parts:

- The casting from float to rational on line 18 is 1-stable, because the real values of the numbers remain un-changed, meaning the distance between adjacent inputs always remains the same.
- The rounding on line 19 can cause an increase in the sensitivity equal to 2^k .

$$\max_{x \sim x'} d_{Lp}(f(x), f(x')) \tag{1}$$

$$= \max_{x \in x'} |r_k(x) - r_k(x')|_p \tag{2}$$

$$= \max_{x \sim x'} |r_k(x) - r_k(x')|_p$$

$$\leq \max_{x \sim x'} |(x + 2^{k-1}) - (x' - 2^{k-1})|_p$$
(2)

$$\leq \max_{x \sim x'} |x - x'|_p + 2^k \tag{4}$$

$$= \max_{x \sim x'} d_{Lp}(x, x') + 2^k \tag{5}$$

$$=1\cdot d_{in}+2^{k} \tag{6}$$

This increase in the sensitivity is reflected in on line 26, where the rounding distance is added to the sensitivity.

• The discarding of the denominator on line 19 is 2^k -stable, as the denominator is 2^k . This increase in sensitivity is also reflected on line 26, where the sensitivity is increased by a factor of 2^k .

Therefore, it is shown that the stability of the function is governed by the stability map.