fn make_np_sum

Michael Shoemate

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This proof resides in "contrib" because it has not completed the vetting process.

Proves soundness of make_np_sum in __init__.py at commit f5bb719 (outdated¹). make_np_sum accepts an input_domain and input_metric, and returns a stable Transformation that computes the vector-valued sum with bounded L_p sensitivity.

1 Hoare Triple

Preconditions

None

Pseudocode

```
def make_np_sum(input_domain: Domain, input_metric: Metric) -> Transformation:
      """Construct a Transformation that computes a sum over the row axis of a 2-dimensional
      array.
      :param input_domain: instance of 'array2_domain(size=_, num_columns=_)'
      :param input_metric: instance of 'symmetric_distance()
      :return: a Measurement that computes the DP sum
      import opendp.prelude as dp
      np = import_optional_dependency('numpy')
11
12
      dp.assert_features("contrib", "floating-point")
13
14
      if not str(input_domain).startswith("NPArray2Domain"): #
15
          raise ValueError(f"input_domain ({input_domain}) must be NPArray2Domain") # pragma:
       no cover
17
18
      if input_domain.descriptor.nan:
          raise ValueError(f"input_domain ({input_domain}) must not permit NaN elements") #
19
      pragma: no cover
20
      if input_metric != dp.symmetric_distance(): #
21
          raise ValueError("input_metric must be the symmetric distance")
22
23
      input_desc = input_domain.descriptor
24
      norm = input_desc.norm
25
      if norm is None: #
```

 $^{^{1}\}mathrm{See}\ \mathrm{new}\ \mathrm{changes}\ \mathrm{with}\ \mathrm{git}\ \mathrm{diff}\ \mathrm{f5bb719..7690fd67}\ \mathrm{python/src/opendp/extras/numpy/_make_np_sum/__init__.py}$

```
raise ValueError(f"input_domain ({input_domain}) must have bounds. See make_np_clamp
27
          # pragma: no cover
28
29
      output_metric = {1: dp.l1_distance, 2: dp.l2_distance}[input_desc.p] #
30
      if input_desc.size is None:
31
          origin = np.atleast_1d(input_desc.origin)
32
          norm += np.linalg.norm(origin, ord=input_desc.p)
33
           stability = lambda d_in: d_in * norm
34
35
           stability = lambda d_in: d_in // 2 * 2 * norm
36
37
      return _make_transformation(
38
          input_domain,
39
40
          input metric.
          dp.vector_domain(dp.atom_domain(T=input_desc.T, nan=False)),
```

Postcondition

Theorem 1.1. For every setting of the input parameters (input_domain, input_metric) to make_np_sum such that the given preconditions hold,

make_np_sum raises an exception (at compile time or run time) or returns a valid transformation. A valid transformation has the following properties:

- 1. (Appropriate output domain). For every element x in input_domain, function(x) is in output_domain or raises a data-independent runtime exception.
- 2. (Stability guarantee). For every pair of elements x, x' in input_domain and for every pair (d_in, d_out), where d_in has the associated type for input_metric and d_out has the associated type for output_metric, if x, x' are d_in-close under input_metric, stability_map(d_in) does not raise an exception, and stability_map(d_in) \leq d_out, then function(x), function(x') are d_out-close under output_metric.

2 Proof

Proof. Let x and x' be datasets that are d_in-close with respect to input_metric. By 15, the input domain is NPArray2Domain, and by 21 input metric is the SymmetricDistance. By 26 and 29, the input data has row-p-norm bounded by at most norm, which we'll refer to as R, centered at origin, which we'll refer to as Q.

2.1 Appropriate Output Domain

The input domain consists of 2-dimensional numpy arrays. Since the sum operation eliminates axis zero, only axis one remains, resulting in a 1-dimensional numpy array of the same type. The data loader then reads this numpy array as a vector. Therefore the output is a member of the output vector domain.

2.2 Stability Guarantee

Now consider two cases: when the data set size is known, and when it is not known.

2.2.1 Known Size

Under the floating-point feature flag, we do not consider numerical instability in this analysis. Without numerical instability, addition is commutative and associative, so reordering rows in the data will not affect the outcome. By this logic then, without loss of generality, assume x, x' only differ on the leading $\lfloor d_{in}/2 \rfloor$ rows.

$$\max_{x \sim x'} d_{Lp}(\text{sum}(x), \text{sum}(x'))$$
 by definition of stability (1)

$$= \max_{x \sim x'} \left\| \sum_{i=1}^{N} x_i - \sum_{i=1}^{N} x_i' \right\|_p$$
 substitute the function and metric (2)

$$= \max_{x \sim x'} \left\| \sum_{i=1}^{\lfloor d_{in}/2 \rfloor} x_i - \sum_{i=1}^{\lfloor d_{in}/2 \rfloor} x_i' \right\|_p \qquad \text{all trailing terms cancel}$$
 (3)

$$\leq \max_{x \sim x'} \sum_{i=1}^{\lfloor d_{in}/2 \rfloor} \|x_i - x_i'\|_p$$
 by triangle inequality (4)

$$\leq \sum_{i=1}^{\lfloor d_{in}/2 \rfloor} 2 \cdot R$$
 each row has bounded p-norm of R (5)

$$= |d_{in}/2| \cdot 2 \cdot R \tag{6}$$

Therefore we've shown that for every pair of elements $x, x' \in \text{input_domain}$ and every $d_{Sym}(x, x') \leq d_{in}$, if x, x' are d_{in} -close then function(x), function(x') are $\text{privacy_map}(d_{in})$ -close under output_metric (the L^p distance).

2.2.2 Unknown Size

By similar ordering logic as in 2.2.1, then without loss of generality, assume x' has an additional d_{in} trailing rows.

$$\max_{x \sim x'} d_{Lp}(\text{sum}(x), \text{sum}(x'))$$
 by definition of stability (7)

$$= \max_{x \sim x'} \left\| \sum_{i=1}^{N} x_i - \sum_{i=1}^{N'} x_i' \right\|_p$$
 substitute the function and metric (8)

$$= \max_{x \sim x'} \|\sum_{i=1}^{d_{in}} x'_{N+i}\|_p \qquad \text{all but the last terms cancel}$$
 (9)

$$\leq \max_{x \sim x'} \sum_{i=1}^{d_{in}} ||x'_{N+i}||_p$$
 by triangle inequality (10)

$$\leq \sum_{i=1}^{d_{in}} (\|O\|_p + R)$$
 each row has bounded p-norm of R at O (11)

$$= d_{in} \cdot (\|O\|_p + R) \tag{12}$$

Therefore we've shown that for every pair of elements $x, x' \in \text{input_domain}$ and every $d_{Sym}(x, x') \leq \texttt{d_in}$, if x, x' are $\texttt{d_in}$ -close then function(x), function(x') are $\text{privacy_map}(\texttt{d_in})$ -close under output_metric (the L^p distance).