fn make_vec

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Proves soundness of the implementation of `make_vec` in `mod.rs` at commit f5bb719 (outdated[1]).

This transformation simply wraps an input scalar in a singleton vec. The output metric then becomes an Lp distance.

1   Hoare Triple

Precondition

Compiler-Verified

- Generic `T` implements trait `Number`

- Generic `Q` implements trait `Number`

User-Verified

None

Pseudocode

```
1  def make_vec(
2      input_space: tuple[AtomDomain[T], AbsoluteDistance[Q]],
3  ) -> Transformation[
4      AtomDomain[T], VectorDomain[AtomDomain[T]], AbsoluteDistance[Q], LpDistance[P, Q]
5  ]:
6      input_domain, input_metric = input_space
7      return Transformation.new(
8          input_domain,
9          VectorDomain.new(input_domain).with_size(1),
10         lambda arg: [arg],
11         input_metric,
12         LpDistance.default(),
13         lambda d_in: d_in
14     )
```

Postcondition

Theorem 1.1.

Theorem 1.2. For every setting of the input parameters (`input_space, T, Q`) to `make_vec` such that the given preconditions hold, `make_vec` raises an exception (at compile time or run time) or returns a valid transformation. A valid transformation has the following properties:

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[1]See new changes with `git diff f5bb719..71f962a6 rust/src/transformations/scalar_to_vector/mod.rs`

1. (Appropriate output domain). For every element x in `input_domain`, `function`(x) is in `output_domain` or raises a data-independent runtime exception.

2. (Stability guarantee). For every pair of elements x, x' in `input_domain` and for every pair $(\texttt{d\_in}, \texttt{d\_out})$, where `d_in` has the associated type for `input_metric` and `d_out` has the associated type for `output_metric`, if x, x' are `d_in`-close under `input_metric`, `stability_map(d_in)` does not raise an exception, and `stability_map(d_in)` $\leq$ `d_out`, then `function`(x), `function`(x') are `d_out`-close under `output_metric`.

Proof. The function is infallible, and the output domain trivially follows, since all output vectors are length-one. The function is 1-stable because:

$$\max_{x \sim x'} d_{Lp}(f(x), f(x')) \tag{1}$$

$$= \max_{x \sim x'}(\sum_i (x_i - x_i')^p)^{1/p} \tag{2}$$

$$= \max_{x \sim x'}((x_1 - x_1')^p)^{1/p} \tag{3}$$

$$= \max_{x \sim x'} |x_1 - x_1'| \tag{4}$$

$$= \max_{x \sim x'} d_{Abs}(x_1, x_1') \tag{5}$$

$$= 1 \cdot \texttt{d\_in} \tag{6}$$

$\square$