trait impl PSRN for TulapPSRN

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This proof resides in "contrib" because it has not completed the vetting process.

Proves soundness of TulapPSRN.

edge accepts parameter self, containing the state of the Tulap sampler and R specifying the rounding mode.

This implementation is susceptible to floating-point vulnerabilities.

Warning 1 (Code is not constant-time). The implementation of edge uses procedures that are vulnerable to timing attacks.

PR History

• Pull Request #1126

1 Hoare Triple

Preconditions

- Variable self is of type TulapPSRN.
- Generic R denotes the rounding mode, one of "up" or "down".

Pseudocode

```
from math import exp
  class TulapPSRN(object):
      def __init__(self, shift, epsilon, delta) -> None:
          self.shift = shift
          self.epsilon = epsilon
          self.delta = delta
          self.uniform = UniformPSRN()
          self.precision = 50
11
      def q_cnd(self, u, c, R): # CND quantile function for f
12
          if u < c:
13
              return self.q_cnd(1 - self.f(u, R), self.f(u, R), c) - 1
14
          elif c \le u \le 1 - c: # the linear function
             return (u - 1 / 2) / (1 - 2 * c)
```

```
17
               return self.q_cnd(self.f(1 - u, R), self.f(u, R), c) + 1
18
19
20
      def f(self, u, _R):
           epsilon, delta = self.epsilon, self.delta
21
           return max(0, 1 - delta - exp(epsilon) * u, exp(-epsilon) * (1 - delta - u))
22
23
      def edge(self, R):
24
           epsilon, delta = self.epsilon, self.delta
           unif = self.uniform.edge(R)
26
27
           c = (1 - delta) / (1 + exp(epsilon))
           if c == 0.5:
28
               return None
29
30
           return self.q_cnd(unif, c, R)
31
32
      def refine(self):
33
           self.precision += 1
34
35
           self.uniform.refine()
36
37
      def refinements(self):
           return self.precision
```

Postcondition

edge returns an estimate of the true Tulap sample, a distribution with CDF defined in make_tulap. This mechanism is not implemented in a fashion that accurately samples from the Tulap distribution, so it may be subject to artifacts.

2 Proof

Proof. The cdf of Tulap(0, b, q) is

$$F_N(x) = \begin{cases} 0 & F_{N_0}(x) < q/2\\ \frac{F_{N_0}(x) - q/2}{1 - q} & q/2 \le F_{N_0}(x) \le 1 - q/2\\ 1 & F_{N_0}(x) > 1 - q/2. \end{cases}$$

By inspection, the fixed point of $f_{\epsilon,\delta}$ is $c = \frac{1-\delta}{1+e^{\epsilon}}$. It is easy to verify that $F_N(x) = c(1/2-x) + (1-c)(x+1/2)$ for $x \in (-1/2, 1/2)$.

The function then uses the inverse transform of a sample of a uniform RV to sample a Tulap RV centered at zero. The function then returns the value, shifted by self.shift.