

fn make_row_by_row_fallible

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Proves soundness of `make_row_by_row_fallible` in `mod.rs` at commit `f5bb719` (outdated¹).

`make_row_by_row_fallible` returns a Transformation that applies a user-specified function to each record in the input dataset. The function is permitted to return a data-independent error.

Vetting History

- [Pull Request #562](#)

1 Hoare Triple

Precondition

Compiler-verified

- Generic DI (input domain) is a type with trait `RowByRowDomain<D0>`.
- Generic D0 (output domain) is a type with trait `DatasetDomain`. `DatasetDomain` is used to define the type of the row domain.
- Generic M (metric) is a type with trait `DatasetMetric`. `DatasetMetric` is used to restrict the set of valid metrics to those which measure distances between datasets.
- `MetricSpace` is implemented for (DI, M). Therefore M is a valid metric on DI.
- `MetricSpace` is implemented for (D0, M).
- Argument `input_domain` is of type DI
- Argument `input_metric` is of type M
- Argument `output_row_domain` is of type `DI::ElementDomain`, as defined by `DatasetDomain`.
- Argument `row_function` is an immutable thread-safe function taking in a value of the carrier type of the element domain associated with `input_domain`, and returning a value of the carrier type of `output_row_domain` or an error.

User-verified

- `row_function` has no side-effects.
- If the input to `row_function` is a member of `input_domain`'s element domain, then the output is a member of `output_row_domain`, or a data-independent error.

¹See new changes with `git diff f5bb719..52d86bbb rust/src/transformations/manipulation/mod.rs`

Pseudocode

```

1 def make_row_by_row_fallible(
2     input_domain: DI,
3     input_metric: M,
4     output_row_domain: DO_RowDomain,
5     # a function from input domain's row type to output domain's row type
6     row_function: Callable([[DI_RowDomain_Carrier], DO_RowDomain_Carrier])
7 ) -> Transformation:
8
9     # where .translate is defined by the RowByRowDomain trait
10    output_domain = input_domain.translate(output_row_domain)
11
12    def function(data: DI_Carrier) -> DO_Carrier:
13        # where .apply_rows is defined by the RowByRowDomain trait
14        return DI.apply_rows(data, row_function)
15
16    stability_map = new_stability_map_from_constant(1) #
17
18    return Transformation(
19        input_domain, output_domain, function,
20        input_metric, input_metric, stability_map)

```

Postcondition

Theorem 1.1. For every setting of the input parameters (`input_domain`, `input_metric`, `output_row_domain`, `row_function`, `DI`, `DO`, `M`) to `make_row_by_row` such that the given preconditions hold, `make_row_by_row` raises an exception (at compile time or run time) or returns a valid transformation. A valid transformation has the following properties:

1. (Appropriate output domain). For every element x in `input_domain`, `function(x)` is in `output_domain` or raises a data-independent runtime exception.
2. (Stability guarantee). For every pair of elements x, x' in `input_domain` and for every pair (d_{in}, d_{out}) , where d_{in} has the associated type for `input_metric` and d_{out} has the associated type for `output_metric`, if x, x' are d_{in} -close under `input_metric`, `stability_map(d_in)` does not raise an exception, and `stability_map(d_in) ≤ d_out`, then `function(x), function(x')` are d_{out} -close under `output_metric`.

2 Proofs

Proof. (Part 1 – appropriate output domain). By the definition of `RowByRowDomain`, `DI.apply_rows(data, row_function)` returns a dataset in `input_domain.translate(output_row_domain)`, if `row_function` is a mapping between `input_domain`'s row domain to `output_row_domain`. This is satisfied by the precondition on `row_function`. Thus, for all settings of input arguments, the function returns a dataset in the output domain. \square

Before proceeding with proving the validity of the stability map, we first provide a lemma.

Lemma 2.1. Let f denote the `row_function`. For any choice x, x' of input arguments in the input domain, and any choice M for which `DatasetMetric` is implemented for, $d_M([f(x_1), f(x_2), \dots], [f(x'_1), f(x'_2), \dots]) \leq d_M([x_1, x_2, \dots], [x'_1, x'_2, \dots])$.

Proof. Assume WLOG that any source of randomness is fixed when f is computed on u vs v . Given this assumption, and the precondition that f has no side-effects, if $x_i = x'_i$, then $f(x_i) = f(x'_i)$. That is, the row function cannot increase the distance between corresponding rows in any adjacent dataset. On the other hand, it is possible for $f(x_i) = f(x'_i)$, even if $x_i \neq x'_i$. For example, if f is a constant function, then

$f(x_i) = f(x'_i)$ for all i . Therefore, by any of the metrics that `DatasetMetric` is implemented for, f can only make datasets more similar. \square

Proof. (Part 2 – stability map). Take any two elements x, x' in the `input_domain` and any pair (d_in, d_out) , where `d_in` has the associated type for `input_metric` and `d_out` has the associated type for `output_metric`. Assume u, v are `d_in`-close under `input_metric` and that `stability_map(d_in) ≤ d_out`.

$$\begin{aligned}
 d_M(\text{function}(x), \text{function}(x')) &= d_M([f(x_1), f(x_2), \dots], [f(x'_1), f(x'_2), \dots]) && \text{since } D0 \text{ is a } \text{DatasetDomain} \\
 &\leq d_M([x_1, x_2, \dots], [x'_1, x'_2, \dots]) && \text{by } 2.1 \\
 &= d_M(x, x') && \text{since } DI \text{ is a } \text{DatasetDomain} \\
 &= d_in && \text{by the first assumption} \\
 &\leq T0.\text{inf_cast}(d_in) && \text{by } \text{InfCast} \\
 &\leq T0.\text{one}().\text{inf_mul}(T0.\text{inf_cast}(d_in)) && \text{by } \text{InfMul} \\
 &= \text{stability_map}(d_in) && \text{by pseudocode line } 16 \\
 &\leq d_out && \text{by the second assumption}
 \end{aligned}$$

It is shown that `function(x), function(x')` are `d_out`-close under `output_metric`. \square