

fn make_gaussian

Michael Shoemate

This proof resides in “**contrib**” because it has not completed the vetting process.

Proves soundness of the implementation of `make_gaussian` in `mod.rs` at commit `f5bb719` (outdated¹). Perturbative noise mechanisms may be parameterized along many different axes:

- domain: scalar or vector
- domain dtype: i8, i16, i32, i64, u8, u16, u32, u64, f32, f64, UBig, IBig, RBig
- metric: absolute distance, l1 distance, modular distance
- metric dtype: i8, i16, i32, i64, u8, u16, u32, u64, f32, f64, UBig, IBig, RBig
- measure: max divergence, zero concentrated divergence
- distribution: laplace, gaussian

All parameterizations reduce to a single core mechanism that perturbs a vector of signed big integers with noise sampled from the appropriate discrete distribution.

The implementation of this function constructs a random variable denoting the noise distribution to add, and then dispatches to the `MakeNoise<DI, MI, MO>` trait which constructs the core mechanism and wraps it in pre-processing transformations and post-processors to match the desired parameterization.

1 Hoare Triple

Precondition

Compiler-Verified

- generic DI implements trait `NoiseDomain`
- generic MI implements trait `Metric`
- generic MO implements trait `Measure`
- type `DI_Atom_RV2` (the random variable associated with the atom data type) implements trait `MakeNoise<DI, MI, MO>` This trait bound constrains the choice of input domain, input metric and output measure to those that can form valid measurements.
- type `(DI, MI)` implements trait `MetricSpace`

User-Verified

None

¹See new changes with `git diff f5bb719..7e67449 rust/src/measurements/noise/distribution/gaussian/mod.rs`

Pseudocode

```
1 def make_gaussian(  
2     input_domain: DI,  
3     input_metric: MI,  
4     scale: f64,  
5     k: Option[i32],  
6 ) -> Measurement[DI, DI_Carrier, MI, MO]:  
7     return DiscreteGaussian(scale, k).make_noise((input_domain, input_metric))
```

Postcondition

Theorem 1.1. For every setting of the input parameters (`input_domain`, `input_metric`, `scale`, `k`, `DI`, `MI`, `MO`) to `make_gaussian` such that the given preconditions hold, `make_gaussian` raises an exception (at compile time or run time) or returns a valid measurement. A valid measurement has the following properties:

1. (Data-independent runtime errors). For every pair of elements x, x' in `input_domain`, `function(x)` returns an error if and only if `function(x')` returns an error.
2. (Privacy guarantee). For every pair of elements x, x' in `input_domain` and for every pair (d_in, d_out) , where `d_in` has the associated type for `input_metric` and `d_out` has the associated type for `output_measure`, if x, x' are `d_in`-close under `input_metric`, `privacy_map(d_in)` does not raise an exception, and `privacy_map(d_in) ≤ d_out`, then `function(x), function(x')` are `d_out`-close under `output_measure`.

Proof. We first construct a random variable `DiscreteGaussian` representing the desired noise distribution. Since `MakeNoise.make_noise` has no preconditions, the postcondition follows, which matches the postcondition for this function. \square