fn then_saturating_cast

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> This proof resides in **"contrib"** because it has not completed the vetting process.

Proves soundness of the implementation of `then_saturating_cast` in `mod.rs` at commit f5bb719 (outdated[1]).

1 Hoare Triple

Precondition

Compiler-Verified

- Generic `T` implements trait `SaturatingCast<IBig>`

User-Verified

None

Pseudocode

```
1  def then_saturating_cast() -> Function[Vec[IBig], Vec[T]]:
2      return Function.new(lambda x: [T.saturating_cast(x_i) for x_i in x])
```

Postcondition

Theorem 1.1. For every setting of the input parameters (`T`) to `then_saturating_cast` such that the given preconditions hold, `then_saturating_cast` raises an exception (at compile time or run time) or returns a valid postprocessor. A valid postprocessor has the following property:

1. (Data-independent errors). For every pair of elements x, x' in `input_domain`, $\texttt{function}(x), \texttt{function}(x')$ either neither or both raise an error. If both raise an error, then they both raise the same error.

Proof. Since `T.saturating_cast` is infallible, the function is infallible, meaning that the function cannot raise data-dependent errors. Therefore the function is a valid postprocessor. □

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[1]See new changes with `git diff f5bb719..71f962a6 rust/src/measurements/noise/nature/integer/mod.rs`