fn make_vec

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This proof resides in "contrib" because it has not completed the vetting process.

Proves soundness of the implementation of make_vec in mod.rs at commit f5bb719 (outdated1).

This transformation simply wraps an input scalar in a singleton vec. The output metric then becomes an Lp distance.

1 Hoare Triple

Precondition

Compiler-Verified

- Generic T implements trait Number
- Generic Q implements trait Number

User-Verified

None

Pseudocode

```
def make_vec(
      input_space: tuple[AtomDomain[T], AbsoluteDistance[Q]],
   -> Transformation[
      AtomDomain[T], VectorDomain[AtomDomain[T]], AbsoluteDistance[Q], LpDistance[P, Q]
5]:
      input_domain, input_metric = input_space
      return Transformation.new(
          input_domain,
          VectorDomain.new(input_domain).with_size(1),
          lambda arg: [arg],
11
          input_metric,
          LpDistance.default()
12
          lambda d_in: d_in
13
```

Postcondition

Theorem 1.1.

Theorem 1.2. For every setting of the input parameters (input_space, T, Q) to make_vec such that the given preconditions hold, make_vec raises an exception (at compile time or run time) or returns a valid transformation. A valid transformation has the following properties:

 $^{^1\}mathrm{See}$ new changes with git diff f5bb719..fa860379 rust/src/transformations/scalar_to_vector/mod.rs

- 1. (Appropriate output domain). For every element x in input_domain, function(x) is in output_domain or raises a data-independent runtime exception.
- 2. (Stability guarantee). For every pair of elements x, x' in input_domain and for every pair (d_in, d_out) , where d_in has the associated type for input_metric and d_out has the associated type for output_metric, if x, x' are d_in-close under input_metric, stability_map(d_in) does not raise an exception, and stability_map(d_in) \leq d_out, then function(x), function(x') are d_out-close under output_metric.

Proof. The function is infallible, and the output domain trivially follows, since all output vectors are lengthone. The function is 1-stable because:

$$\max_{x \sim x'} d_{Lp}(f(x), f(x')) \tag{1}$$

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$$= \max_{x \sim x'} (\sum_{i} (x_i - x_i')^p)^{1/p} \tag{2}$$

$$= \max_{x \sim x'} ((x_1 - x_1')^p)^{1/p} \tag{3}$$

$$= \max_{x \sim x'} |x_1 - x_1'| \tag{4}$$

$$= \max_{x \sim x'} d_{Abs}(x_1, x_1') \tag{5}$$

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