

# SuperPoint 转 onnx

目的：方便 tensorRT 加速部署

参考 :pytorch 转 onnx [https://blog.csdn.net/qq\\_39967751/article/details/124932242](https://blog.csdn.net/qq_39967751/article/details/124932242)

pytorch 源码链接：<https://github.com/magicleap/SuperGluePretrainedNetwork>

1) 要点：

- 在模型推理一次后执行 `torch.onnx.export`，具体含义参见上述链接；

demo\_superglue.py

```
last_data = matching.superpoint(frame_tensor)
torch.onnx.export(matching.superpoint, frame_tensor, f='SuperPoint.onnx', export_params=True,
verbose=True,
                    input_names=None,
                    output_names=None, do_constant_folding=True, dynamic_axes=None,
opset_version=11)
exit()
```

- SuperPoint 原始推理代码中包含后处理部分，此部分不能被正确导出，只能导出网络的原始输出，包括描述子（desc）和特征相应图（scores），后处理需要自己根据 python 代码进行实现，修改如下：

superpoint.py

```
def forward(self, data):
    """ Compute keypoints, scores, descriptors for image """
    # Shared Encoder
    x = self.relu(self.conv1a(data)) #['image']
    x = self.relu(self.conv1b(x))
    x = self.pool(x)
    x = self.relu(self.conv2a(x))
    x = self.relu(self.conv2b(x))
    x = self.pool(x)
    x = self.relu(self.conv3a(x))
    x = self.relu(self.conv3b(x))
    x = self.pool(x)
    x = self.relu(self.conv4a(x))
    x = self.relu(self.conv4b(x))

    # Compute the dense keypoint scores
    cPa = self.relu(self.convPa(x))
```

```

scores = self.convPb(cPa)

scores = torch.nn.functional.softmax(scores, 1)[:,-1]

b, _, h, w = scores.shape

scores = scores.permute(0, 2, 3, 1).reshape(b, h, w, 8, 8)

scores = scores.permute(0, 1, 3, 2, 4).reshape(b, h*8, w*8)

# scores = simple_nms(scores, self.config['nms_radius'])

#
#
# # Extract keypoints
# keypoints = [

#     torch.nonzero(s | self.config['keypoint_threshold'])
#     for s in scores]
# scores = [s[tuple(k.t())] for s, k in zip(scores, keypoints)]
#
# # Discard keypoints near the image borders
# keypoints, scores = list(zip(*[

#     remove_borders(k, s, self.config['remove_borders'], h*8, w*8)
#     for k, s in zip(keypoints, scores)]))
#
# # Keep the k keypoints with highest score
# if self.config['max_keypoints'] != 0:
#     keypoints, scores = list(zip(*[

#         top_k_keypoints(k, s, self.config['max_keypoints'])
#         for k, s in zip(keypoints, scores)]))
#
# # Convert (h, w) to (x, y)
# keypoints = [torch.flip(k, [1]).float() for k in keypoints]

# Compute the dense descriptors
cDa = self.relu(self.convDa(x))
descriptors = self.convDb(cDa)
descriptors = torch.nn.functional.normalize(descriptors, p=2, dim=1)

# Extract descriptors
# descriptors = [sample_descriptors(k[None], d[None], 8)[0]

#         for k, d in zip(keypoints, descriptors)]

return scores, descriptors

```

- onnx 转换时不支持词典类型的数据输入，修改如下：

superpoint.py

```
x = self.relu(self.conv1a(data)) #['image']
```

同时其他地方的输入也需要修改，如  
demo\_superglue.py

```
last_data = matching.superpoint(frame_tensor)
```

2)

运行：

● 代码 SuperGluePretrainedNetwork，按 ReadME 安装依赖

电脑有摄像头，运行：./demo\_superglue.py --resize 640 480

无摄像头：./demo\_superglue.py --input images\_dir --output\_dir output\_dir --resize 640 480

可在 SuperGluePretrainedNetwork 下找到 onnx 文件