This set of notes aims to provide complete proofs of a number of asymptotic results regarding the Bootstrap [4] contained in Bickel and Freedman [1].

1 Bootstrap asymptotics for the I.I.D. sample mean

Theorem 1.1 (Bootstrap Central Limit Theorem for I.I.D. sample mean, Theorem 2.1 [1])

Let $(\Omega, \mathcal{A}, \nu)$ be a probability space. Let $X, X_1, X_2, \ldots : \Omega \longrightarrow \mathbb{R}$ be a sequence of independent and identically distributed \mathbb{R} -valued random variables defined on Ω with finite expectation value $\mu_X \in \mathbb{R}$ and variance $\sigma_X^2 < \infty$. For each $m \in \mathbb{N}$, define:

$$\overline{X}^{(m)}: \Omega \longrightarrow \mathbb{R}: \omega \longmapsto \frac{1}{m} \sum_{i=1}^{m} X_i(\omega).$$

For $n, m \in \mathbb{N}$, define $\mathcal{S}_n^{(m)}$ to be the set of all functions from $\{1, 2, \dots, m\} \longrightarrow \{1, 2, \dots, n\}$. Thus, each

$$s = (s(1), s(2), \dots, s(m)) \in \mathcal{S}_n^{(m)}$$

can be regarded as a length-m finite (ordered) sequence of positive integers between 1 and n, inclusive. Note that $S_n^{(m)}$ is a finite set with $|S_n^{(m)}| = n^m$. Endow $S_n^{(m)}$ with the probability space structure induced by the uniform probability function:

$$P_{\mathcal{S}_n^{(m)}}(s) := \frac{1}{n^m}, \text{ for each } s \in \mathcal{S}_n^{(m)}.$$

Let $\Omega \times \mathcal{S}_n^{(m)}$ be the product probability space of Ω and $\mathcal{S}_n^{(m)}$. Define:

$$\overline{X}_n^{(m)}: \Omega \times \mathcal{S}_n^{(m)} \longrightarrow \mathbb{R}: (\omega, s) \longmapsto \frac{1}{m} \sum_{j=1}^m X_{s(j)}(\omega).$$

For each $\omega \in \Omega$, define:

$$Y_{n,\omega}^{(m)}: \mathcal{S}_n^{(m)} \longrightarrow \mathbb{R}: s \longmapsto \sqrt{m} \left(\overline{X}_n^{(m)}(\omega, s) - \overline{X}_n(\omega) \right)$$

Then.

$$P\Big(\ Y_{n,\omega}^{(m)} \stackrel{d}{\longrightarrow} N(0,\sigma_X^2), \text{ as } n,m \to \infty \ \Big) \quad = \quad \nu\Big(\Big\{ \ \omega \in \Omega \ \left| \ Y_{n,\omega}^{(m)} \stackrel{d}{\longrightarrow} N(0,\sigma_X^2), \text{ as } n,m \to \infty \ \right\} \Big) \quad = \quad 1.$$

Remark 1.2

For each fixed $\omega \in \Omega$, $\left\{ Y_{n,\omega}^{(m)} : \mathcal{S}_n^{(m)} \longrightarrow \mathbb{R} \right\}_{n,m \in \mathbb{N}}$ is a doubly indexed sequence of \mathbb{R} -valued random variables. Note that their respective domains $\mathcal{S}_n^{(m)}$ are pairwise distinct probability spaces. The **Bootstrap Central Limit Theorem** for I.I.D. sample mean asserts that for almost every $\omega \in \Omega$, the doubly indexed sequence $\left\{ Y_{n,\omega}^{(m)} \right\}$ of \mathbb{R} -valued random variables converges in distribution to $N(0, \sigma_X^2)$ as $n, m \longrightarrow \infty$.

Remark 1.3 The following results are well known from classical asymptotic theory:

By the Weak Law of Large Numbers, \overline{X}_n converges in probability to μ_X , as $n \longrightarrow \infty$; in other words,

$$\lim_{n \to \infty} P(|\overline{X}_n - \mu_X| > \varepsilon) = \lim_{n \to \infty} \nu(\{\omega \in \Omega : |\overline{X}_n(\omega) - \mu_X| > \varepsilon\}) = 0, \text{ for each } \varepsilon > 0.$$

By the Strong Law of Large Numbers, \overline{X}_n converges almost surely to μ_X , as $n \to \infty$; in other words,

$$P\Big(\lim_{n\to\infty} \overline{X}_n = \mu_X\Big) = \nu\Big(\Big\{\omega\in\Omega \mid \lim_{n\to\infty} \overline{X}_n(\omega) = \mu_X\Big\}\Big) = 1.$$

By the Central Limit Theorem, $\sqrt{n}(\overline{X}_n - \mu_X)$ converges in distribution to $N(0, \sigma_X^2)$.

PROOF Let $\mathcal{M}_1(\mathbb{R}, \mathcal{B}(\mathbb{R}))$ denotes the set of probability measures on $(\mathbb{R}, \mathcal{B}(\mathbb{R}))$. Let

$$\mathcal{W}_1^2(\mathbb{R}, \mathcal{B}(\mathbb{R})) := \left\{ G \in \mathcal{M}_1(\mathbb{R}, \mathcal{B}(\mathbb{R})) \mid \int_{\mathbb{R}} x^2 dG(x) < \infty \right\}.$$

denote the Wasserstein space (Definition A.2) of order 2 of the measurable space $(\mathbb{R}, \mathcal{B}(\mathbb{R}))$, whose underlying topological space (1-dimensional Euclidean space) is a Polish space (i.e. separable complete metric space). Let

$$W_2\,:\,\mathcal{W}_1^2(\mathbb{R},\mathcal{B}(\mathbb{R}))\times\mathcal{W}_1^2(\mathbb{R},\mathcal{B}(\mathbb{R}))\,\longrightarrow\,\mathbb{R}\,:\,(G,G')\,\longmapsto\,\inf\left\{\begin{array}{c|c}\sqrt{E(\,|X-Y|^2\,)}&\big|&(X,Y)\in\Pi(G,G')\end{array}\right\}$$

denote the Wasserstein metric (Theorem A.3) on $\mathcal{W}_1^2(\mathbb{R},\mathcal{B}(\mathbb{R}))$.

For each $m \in \mathbb{N}$, let $F^{(m)} \in \mathcal{M}_1(\mathbb{R}, \mathcal{B}(\mathbb{R}))$ denote the distribution of

$$Y^{(m)}: \Omega \longrightarrow \mathbb{R}: \omega \longmapsto \sqrt{m} \left(\overline{X}^{(m)}(\omega) - \mu_X \right).$$

And, for each $\omega \in \Omega$, and each $m, n \in \mathbb{N}$, let $F_n^{(m)}(\omega) \in \mathcal{M}_1(\mathbb{R}, \mathcal{B}(\mathbb{R}))$ denote the distribution of

$$Y_{n,\omega}^{(m)}: \mathcal{S}_n^{(m)} \longrightarrow \mathbb{R}: s \longmapsto \sqrt{m} \left(\overline{X}_n^{(m)}(\omega, s) - \overline{X}^{(n)}(\omega) \right).$$

Note that $N(0, \sigma_X^2) \in \mathcal{W}_1^2(\mathbb{R}, \mathcal{B}(\mathbb{R}))$. By hypothesis, $F^{(m)} \in \mathcal{W}_1^2(\mathbb{R}, \mathcal{B}(\mathbb{R}))$ for each $m \in \mathbb{N}$. And, for each $\omega \in \Omega$, $m, n \in \mathbb{N}$, we have $F_n^{(m)}(\omega) \in \mathcal{W}_1^2(\mathbb{R}, \mathcal{B}(\mathbb{R}))$, since $\mathcal{S}_m^{(n)}$ is a finite probability space. Therefore, by Theorem A.3 and Claim 3 below, the following inequalities hold: For each $\omega \in \Omega$ and $m, n \in \mathbb{N}$,

$$\begin{split} W_2\Big(F_n^{(m)}(\omega), N(0, \sigma_X^2)\Big) & \leq & W_2\Big(F_n^{(m)}(\omega), F^{(m)}\Big) \, + \, W_2\Big(F^{(m)}, N(0, \sigma_X^2)\Big) \\ & \leq & W_2\big(F_n(\omega), F\big) \, + \, W_2\Big(F^{(m)}, N(0, \sigma_X^2)\Big) \, . \end{split}$$

Thus, the present Theorem follows by Theorem A.6 and the following two claims:

Claim 1: $W_2(F^{(m)}, N(0, \sigma_X^2))) \longrightarrow 0$, as $m \longrightarrow \infty$.

Claim 2:
$$\nu(\left\{\omega \in \Omega \mid W_2(F_n(\omega), F) \longrightarrow 0, \text{ as } n \longrightarrow \infty\right\}) = 1.$$

<u>Proof of Claim 1:</u> By the Classical Central Limit Theorem, $F^{(m)} \xrightarrow{w} N(0, \sigma_X^2)$. Since $E[Y^{(m)}] = 0$, we have

$$\int_{\mathbb{R}} y^2 dF^{(m)}(y) = E\left[\left(Y^{(m)}\right)^2\right] = \operatorname{Var}\left[Y^{(m)}\right] = m \cdot \operatorname{Var}\left[\left(\frac{1}{m}\sum_{i=1}^m X_i\right) - \mu_X\right]$$
$$= \frac{m}{m^2} \cdot \sum_{i=1}^m \operatorname{Var}[X_i] = \frac{1}{m} \cdot m \cdot \sigma_X^2 = \sigma_X^2,$$

which is the second moment of $N(0, \sigma_X^2)$. Hence, by Definition A.5, we have $F^{(m)} \xrightarrow{W_1^2} N(0, \sigma_X^2)$, and by Theorem A.6, we have $W_2(F^{(m)}, N(0, \sigma_X^2))) \longrightarrow 0$, as $m \longrightarrow \infty$. This completes the proof of Claim 1.

<u>Proof of Claim 2:</u> By hypothesis $\mu_X := E[X] \in \mathbb{R}$ and $\sigma_X^2 := \text{Var}[X] < \infty$. Hence $E[X^2] = \text{Var}[X] + E[X]^2 < \infty$. Thus, by the Strong Law of Large Numbers, we have:

$$\int_{\mathbb{R}} x^2 dF_n(\omega)(x) = \frac{1}{n} \sum_{i=1}^n X_i(\omega)^2 \xrightarrow{\text{a.e.}} E[X^2] = \int_{\mathbb{R}} x^2 dF(x),$$

equivalently,

$$\nu\left(\left\{ \omega \in \Omega \mid \int_{\mathbb{R}} x^2 dF_n(\omega)(x) \longrightarrow \int_{\mathbb{R}} x^2 dF(x) \right\} \right) = 1.$$

On the other hand, by the Glivenko-Cantelli Theorem, we have:

$$\nu \left(\left\{ \ \omega \in \Omega \ \left| \ \lim_{n \to \infty} \sup_{t \in \mathbb{R}} |F_n(\omega)(t) - F(t)| \ = \ 0 \ \right. \right\} \right) \ = \ 1,$$

which implies trivially

$$\nu\left(\left\{ \omega \in \Omega \mid \lim_{n \to \infty} F_n(\omega)(t) = F(t), \text{ for each } t \in \mathbb{R} \right\} \right) = 1,$$

which in turn implies

$$\nu\left(\left\{ \omega \in \Omega \mid F_n(\omega) \xrightarrow{w} F \right\}\right) = 1.$$

Note that in the above assertion, we used the slight abuse of notation that $F_n(\omega)$ represents both the distribution (measure) $F_n(\omega) \in \mathcal{M}_1(\mathbb{R}, \mathcal{B}(\mathbb{R}))$ as well as its cumulative distribution function defined on \mathbb{R} . Thus, we see that Theorem A.6, the Glivenko-Cantelli Theorem, and the Strong Law of Large Numbers together imply:

$$\nu\left(\left\{ \omega \in \Omega \mid W_{2}(F_{n}(\omega), F) \longrightarrow 0 \right\} \right)$$

$$= \nu\left(\left\{ \omega \in \Omega \mid F_{n}(\omega) \xrightarrow{W_{1}^{2}} F \right\} \right)$$

$$= \nu\left(\left\{ \omega \in \Omega \mid F_{n}(\omega) \xrightarrow{w} F \text{ and } \int_{\mathbb{R}} x^{2} dF_{n}(\omega)(x) \longrightarrow \int_{\mathbb{R}} x^{2} dF(x) \right\} \right)$$

$$= \nu\left(\left\{ \omega \in \Omega \mid F_{n}(\omega) \xrightarrow{w} F \right\} \bigcap \left\{ \omega \in \Omega \mid \int_{\mathbb{R}} x^{2} dF_{n}(\omega)(x) \longrightarrow \int_{\mathbb{R}} x^{2} dF(x) \right\} \right)$$

$$= 1.$$

This completes the proof of Claim 2.

Claim 3: Let $G \in \mathcal{W}_1^2(\mathbb{R}, \mathcal{B}(\mathbb{R}))$ and $m \in \mathbb{N}$. Suppose $Z_1^{(G)}, Z_2^{(G)}, \dots, Z_m^{(G)}$ are independent and identically distributed random variables, each having distribution G. Let $G^{(m)} \in \mathcal{M}_1(\mathbb{R}, \mathcal{B}(\mathbb{R}))$ be the (empirical) measure of the random variable

$$Y_m^{(G)} := \frac{1}{m^{1/2}} \sum_{i=1}^m \left(Z_i^{(G)} - \mu_G \right) : \Omega \longrightarrow \mathbb{R},$$

where $\mu_G := \int_{\mathbb{R}} x \, dG(x)$ is the expectation value of the distribution G. Then, for any $G, H \in \mathcal{W}_1^2(\mathbb{R}, \mathcal{B}(\mathbb{R}))$, we have

$$W_2(G^{(m)}, H^{(m)}) \leq W_2(G, H).$$

Proof of Claim 3:

A Wasserstein Spaces

Proofs of results mentioned in this section can be found in Chapters 1 and 6 of [6].

Suppose (S, \mathcal{S}) and (T, \mathcal{T}) are two measurable spaces. We will use the following notations:

- $(S \times T, S \otimes T)$ denotes their product measurable space (see Chapter 10, [5]).
- $\mathcal{M}_1(S, \mathcal{S})$, $\mathcal{M}_1(T, \mathcal{T})$, and $\mathcal{M}_1(S \times T, \mathcal{S} \otimes \mathcal{T})$ denote the sets of probability measures on the respective measurable spaces.
- $\Pi^S: S \times T \longrightarrow S: (s,t) \longmapsto s$ and $\Pi^T: S \times T \longrightarrow T: (s,t) \longmapsto t$ are the canonical projection maps, and

$$\Pi_*^S : \mathcal{M}_1(S \times T, \mathcal{S} \otimes \mathcal{T}) \longrightarrow \mathcal{M}_1(S, \mathcal{S}) : \pi \longmapsto (A \in \mathcal{S} \longmapsto \pi \lceil (\Pi^S)^{-1}(A) \rceil),$$

$$\Pi^T_* : \mathcal{M}_1(S \times T, \mathcal{S} \otimes \mathcal{T}) \longrightarrow \mathcal{M}_1(T, \mathcal{T}) : \pi \longmapsto (B \in \mathcal{T} \longmapsto \pi \lceil (\Pi^T)^{-1}(B) \rceil)$$

are the corresponding push-forward maps of measures.

Definition A.1 (Coupling measures and couplings (Definition 1.1, [6]))

Let (S, S) and (T, T) be two measurable spaces. Let $\mu \in \mathcal{M}_1(S, S)$ and $\nu \in \mathcal{M}_1(T, T)$.

• A coupling (probability) measure of μ and ν is a probability measure $\pi \in \mathcal{M}_1(S \times T, \mathcal{S} \otimes \mathcal{T})$ whose push-forwards under the canonical projection maps are μ and ν respectively; in other words $\pi \in \mathcal{M}_1(S \times T, \mathcal{S} \otimes \mathcal{T})$ is a coupling measure of $(\mu, \nu) \in \mathcal{M}_1(S, \mathcal{S}) \times \mathcal{M}_1(T, \mathcal{T})$ if π satisfies:

$$\Pi_*^S(\pi) = \mu$$
 and $\Pi_*^T(\pi) = \nu$.

In this case, μ and ν are called the **marginal (probability) measures** of π . We denote by $\Pi(\mu, \nu)$ the subset of $\mathcal{M}_1(S \times T, \mathcal{S} \otimes \mathcal{T})$ of all coupling probability measures of μ and ν .

• A coupling of μ and ν is an $(S \times T)$ -valued random variable

$$Z = (X,Y) : (\Omega, \mathcal{A}, P_{\Omega}) \longrightarrow (S \times T, \mathcal{S} \otimes \mathcal{T})$$

whose induced measure on $(S \times T, S \otimes T)$ is a coupling probability measure of μ and ν . More precisely,

$$\mu(A) = P_X(A) = P_{\Omega}(X^{-1}(A)) = P_{\Omega}((\Pi^S \circ Z)^{-1}(A)) = P_{\Omega}(Z^{-1}[(\Pi^S)^{-1}(A)]), \text{ for each } A \in \mathcal{S}$$

$$\nu(B) \ = \ P_Y(B) = P_\Omega \big(Y^{-1}(B) \big) = P_\Omega \big((\Pi^T \circ Z)^{-1}(B) \big) = P_\Omega \big(Z^{-1} \big[(\Pi^T)^{-1}(B) \big] \, \big) \,, \quad \text{for each } B \in \mathcal{T}$$

Definition A.2 (Wasserstein distances and Wasserstein spaces (Definitions 6.1 and 6.4, [6]))

Let $p \in [1, \infty)$. Let (S, ρ) be a Polish space (i.e. separable complete metric space), and S its Borel σ -algebra.

• The Wasserstein distance of order p is, by definition, the map $W_p : \mathcal{M}_1(S, \mathcal{S}) \times \mathcal{M}_1(S, \mathcal{S}) \longrightarrow \mathbb{R} \cup \{+\infty\}$ given by:

$$W_{p}(\mu,\nu) := \inf_{\pi \in \Pi(\mu,\nu)} \left\{ \left(\int_{S \times S} \rho(x,y)^{p} d\pi(x,y) \right)^{1/p} \right\}$$

$$= \inf_{\pi \in \Pi(\mu,\nu)} \left\{ \left(E[\rho(X,Y)^{p}] \right)^{1/p} \in \mathbb{R} \cup \{+\infty\} \middle| X, Y : (\Omega, \mathcal{A}, \pi) \longrightarrow (S, \mathcal{S}) \text{ are } S\text{-valued random variables with } X^{*}(\pi) = \mu, Y^{*}(\pi) = \nu \right\}.$$

• The Wasserstein space of order p is defined to be:

$$\mathcal{W}_1^p(S,\mathcal{S}) := \left\{ \mu \in \mathcal{M}_1(S,\mathcal{S}) \mid \int_S \rho(x_0,x)^p \, \mathrm{d}\mu(x) < \infty \right\},$$

where $x_0 \in S$ is an arbitrary point in S ($W_1^p(S, S)$ is independent of the choice of $x_0 \in S$). Thus, $W_1^p(S, S)$ is the set of probability measures on (S, S) with finite moment of order p.

Theorem A.3 (Wasserstein metrics (Definition 6.4 and Theorem 6.18, [6]))

- The Wasserstein space $W_1^p(S, S)$ is independent of the choice of the point $x_0 \in S$ in its definition.
- The Wasserstein distance W_p restricts to a metric on $\mathcal{W}_1^p(S,\mathcal{S}) \times \mathcal{W}_1^p(S,\mathcal{S})$.
- For a Polish space (i.e. separable complete metric space) (S, ρ) with Borel σ -algebra S, the Wassertein space $\mathcal{W}_1^p(S, \mathcal{S})$, when metrized by the Wasserstein metric W_p , is itself a Polish space.

Definition A.4 (Weak convergence in metric spaces (Chapter 1, [3]))

Suppose:

- (S, ρ) is a metric space and S is its Borel σ -algebra.
- $\mathcal{M}_1(S,\mathcal{S})$ denotes the set of probability measures defined on (S,\mathcal{S}) .
- $\mu \in \mathcal{M}_1(S, \mathcal{S})$ and $\{\mu_k\}_{k \in \mathbb{N}} \subset \mathcal{M}_1(S, \mathcal{S})$.

Then, $\{\mu_k\}_{k\in\mathbb{N}}$ is said to **converge weakly** to μ if, for each $f\in C_b(S,\mathbb{R})$,

$$\int_{S} f(x) d\mu_{k}(x) \longrightarrow \int_{S} f(x) d\mu(x), \text{ as } k \longrightarrow \infty,$$

where $C_b(S,\mathbb{R})$ denotes the set of all bounded continuous \mathbb{R} -valued functions on S. We write $\mu_k \xrightarrow{w} \mu$ for μ_k converging weakly to μ .

Definition A.5 (Weak convergence in Wassertein spaces (Definition 6.8, [6]))

Suppose:

- (X, ρ) is a Polish space, and S is its Borel σ -algebra.
- $p \in [1, \infty)$ and $W_1^p(S, S)$ is the corresponding Wasserstein space of order p.
- $\mu \in \mathcal{W}_1^p(S, \mathcal{S})$ and $\{\mu_k\}_{k \in \mathbb{N}} \subset \mathcal{W}_1^p(S, \mathcal{S})$.

Then, $\{\mu_k\}_{k\in\mathbb{N}}$ is said to converge weakly in $\mathcal{W}_1^p(S,\mathcal{S})$ to μ if, for some (hence any) $x_0\in S$, we have:

$$\mu_k \xrightarrow{w} \mu$$
 and $\int_S \rho(x_0, x)^p d\mu_k(x) \longrightarrow \int_S \rho(x_0, x)^p d\mu(x)$, as $k \longrightarrow \infty$.

We write $\mu_k \xrightarrow{\mathcal{W}_{1}^p} \mu$ for μ_k converging weakly to μ in $\mathcal{W}_{1}^p(S,\mathcal{S})$.

Theorem A.6 (Wasserstein metrics metrize weak convergence in Wassertein spaces (Theorem 6.9, [6])) Suppose:

- (X, ρ) is a Polish space, and S is its Borel σ -algebra.
- $p \in [1, \infty)$, $(W_1^p(S, S), W_p)$ is the corresponding Wasserstein space of order p, metrized by the Wasserstein metric W_p defined on it.
- $\mu \in \mathcal{W}_1^p(S, \mathcal{S})$ and $\{\mu_k\}_{k \in \mathbb{N}} \subset \mathcal{W}_1^p(S, \mathcal{S})$.

Then,

$$\mu_k \xrightarrow{\mathcal{W}_1^p} \mu$$
 if and only if $W_p(\mu_k, \mu) \longrightarrow 0$.

To conclude this Appendix, we present several technical results regarding $W_1^2(\mathbb{R},\mathcal{B}(\mathbb{R}))$ that are used in the main text.

Lemma A.7

Suppose:

- $m \in \mathbb{N}$ is a positive integer.
- $X_1, X_2, \ldots, X_m : \Omega_X \longrightarrow \mathbb{R}$ are independent and identically distributed \mathbb{R} -valued random variables defined on the same probability space Ω_X such that $E[X_i] = 0$, for each $i = 1, 2, \ldots, m$.
- $Y_1, Y_2, \ldots, Y_m : \Omega_Y \longrightarrow \mathbb{R}$ are independent and identically distributed \mathbb{R} -valued random variables defined on the same probability space Ω_Y such that $E[Y_i] = 0$, for each $i = 1, 2, \ldots, m$.
- $G^{(1)} \in \mathcal{W}_1^2(\mathbb{R}, \mathcal{B}(\mathbb{R}))$ denotes the common probability distribution of X_i , for i = 1, 2, ..., m, and $G^{(m)} \in \mathcal{W}_1^2(\mathbb{R}, \mathcal{B}(\mathbb{R}))$ denotes the probability distribution on $(\mathbb{R}, \mathcal{B}(\mathbb{R}))$ induced by:

$$\frac{1}{\sqrt{m}} \sum_{i=1}^{m} X_i : \Omega_X \longrightarrow \mathbb{R}.$$

• $H^{(1)} \in \mathcal{W}_1^2(\mathbb{R}, \mathcal{B}(\mathbb{R}))$ denotes the common probability distribution of Y_i , for i = 1, 2, ..., m, and $H^{(m)} \in \mathcal{W}_1^2(\mathbb{R}, \mathcal{B}(\mathbb{R}))$ denotes the probability distribution on $(\mathbb{R}, \mathcal{B}(\mathbb{R}))$ induced by:

$$\frac{1}{\sqrt{m}}\sum_{i=1}^m Y_i:\Omega_Y\longrightarrow\mathbb{R}.$$

Then,

$$W_2(G^{(m)}, H^{(m)}) \le W_2(G^{(1)}, H^{(1)})$$

Proof

$$\begin{split} &W_2\Big(G^{(m)},H^{(m)}\Big) \\ &= \inf \bigg\{ \int_{\mathbb{R}^2} (x-y)^2 \, \mathrm{d}\mu(x,y) \in [0,\infty) \ \bigg| \ \mu \in \Pi\Big(G^{(m)},H^{(m)}\Big) \, \bigg\} \\ &\leq \inf \left\{ \int_{\mathbb{R}^{2m}} \left(\frac{1}{\sqrt{m}} \sum_{i=1}^m x_i \ - \ \frac{1}{\sqrt{m}} \sum_{i=1}^m y_i \right)^2 \mathrm{d}\mu_1(x_1,y_1) \cdots \mathrm{d}\mu_m(x_m,y_m) \ \bigg| \ (\mu_1,\dots,\mu_m) \in \Pi\Big(G^{(1)},H^{(1)}\Big)^m \, \bigg\} \\ &\vdots \\ &= \dots \\ &\vdots \\ &= \inf \left\{ \left. \frac{1}{m} \sum_{i=1}^m \int_{\mathbb{R}^2} (x_i-y_i)^2 \, \mathrm{d}\mu_i(x_i,y_i) \ \bigg| \ (\mu_1,\dots,\mu_m) \in \Pi\Big(G^{(1)},H^{(1)}\Big)^m \, \right\} \\ &= \frac{1}{m} \cdot \sum_{i=1}^m \inf \left\{ \int_{\mathbb{R}^2} (x_i-y_i)^2 \, \mathrm{d}\mu_i(x_i,y_i) \ \bigg| \ \mu_i \in \Pi\Big(G^{(1)},H^{(1)}\Big) \, \right\} \\ &= \frac{1}{m} \cdot \sum_{i=1}^m W_2\Big(G^{(1)},H^{(1)}\Big) \\ &= W_2\Big(G^{(1)},H^{(1)}\Big) \, , \end{split}$$

where the inequality follows from ... the ellipses follow from the following arithmetic:

$$\int_{\mathbb{R}^{2m}} \left(\frac{1}{\sqrt{m}} \sum_{i=1}^{m} x_{i} - \frac{1}{\sqrt{m}} \sum_{i=1}^{m} y_{i} \right)^{2} d\mu_{1}(x_{1}, y_{1}) \cdots d\mu_{m}(x_{m}, y_{m})$$

$$= \frac{1}{m} \int_{\mathbb{R}^{2m}} \left[\sum_{i=1}^{m} (x_{i} - y_{i}) \right]^{2} d\mu_{1}(x_{1}, y_{1}) \cdots d\mu_{m}(x_{m}, y_{m})$$

$$= \frac{1}{m} \int_{\mathbb{R}^{2m}} \left[\sum_{i=1}^{m} (x_{i} - y_{i})^{2} + \sum_{i \neq j} (x_{i} - y_{i})(x_{j} - y_{j}) \right] d\mu_{1}(x_{1}, y_{1}) \cdots d\mu_{m}(x_{m}, y_{m})$$

$$= \frac{1}{m} \cdot \sum_{i=1}^{m} \int_{\mathbb{R}^{2}} (x_{i} - y_{i})^{2} d\mu_{i}(x_{i}, y_{i}) + \frac{1}{m} \cdot \sum_{i \neq j} \left(\int_{\mathbb{R}^{2}} (x_{i} - y_{i}) d\mu_{i}(x_{i}, y_{i}) \right) \cdot \left(\int_{\mathbb{R}^{2}} (x_{j} - y_{j}) d\mu_{j}(x_{j}, y_{j}) \right)$$

$$= \frac{1}{m} \sum_{i=1}^{m} \int_{\mathbb{R}^{2}} (x_{i} - y_{i})^{2} d\mu_{i}(x_{i}, y_{i}) + \frac{1}{m} \cdot \sum_{i \neq j} (E[X_{i}] - E[Y_{i}]) \cdot (E[X_{j}] - E[Y_{j}])$$

$$= \frac{1}{m} \sum_{i=1}^{m} \int_{\mathbb{R}^{2}} (x_{i} - y_{i})^{2} d\mu_{i}(x_{i}, y_{i}).$$

B A stochastic process $\{X_t : \Omega \longrightarrow V\}_{t \in T}$ and its equivalent V^T -valued random variable $X : \Omega \longrightarrow V^T$

Let Ω , T, and V be non-empty sets. Let $\{X_t : \Omega \longrightarrow V\}_{t \in T}$ be a T-index family of maps, each of which maps from Ω into V. Note that this family of maps is set-theoretically equivalent (in the sense that either one completely determines the other) to the following (V^T) -valued map defined on Ω :

$$X: \Omega \longrightarrow V^T: \omega \longmapsto (t \longmapsto X_t(\omega)),$$

where $V^T = \prod_{t \in T} V$ denotes the set of all (arbitrary) V-valued functions defined on T. In this section, we aim to establish the following two results:

• Suppose (Ω, \mathcal{A}) and (V, \mathcal{F}) are measurable space structures on Ω and V, respectively. Then, $X : \Omega \longrightarrow V^T$ is $(\mathcal{A}, \sigma[(V, \mathcal{F})^T])$ -measurable if and only if $X_t : \Omega \longrightarrow V$ is $(\mathcal{A}, \mathcal{F})$ -measurable for each $t \in T$. Here, $\sigma[(V, \mathcal{F})^T]$ denotes the product σ -algebra on V^T , which is by definition the smallest σ -algebra on V^T such that, for each $t \in T$, the projection map (or evaluation map)

$$\pi_t: V^T \longrightarrow V: x \longmapsto x(t)$$

is $(\sigma[(V, \mathcal{F})^T], \mathcal{F})$ -measurable.

• An immediate corollary of the above result is that: Suppose $(\Omega, \mathcal{A}, \mu)$ is a probability space structure on Ω , (V, \mathcal{F}) is a measurable space structure on V, and $\sigma[(V, \mathcal{F})^T]$ is the product σ -algebra on V^T . Then, $X: (\Omega, \mathcal{A}, \mu) \longrightarrow (V^T, \sigma[(V, \mathcal{F})^T])$ is V^T -valued random variable if and only if $\{X_t: (\Omega, \mathcal{A}, \mu) \longrightarrow (V, \mathcal{F})\}_{t \in T}$ is a stochastic process.

Definition B.1 (The product σ -algebra of a Cartesian product of measurable spaces)

Let T be an arbitrary non-empty set. For each $t \in T$, let (V_t, \mathcal{F}_t) be a measurable space (in particular, $V_t \neq \varnothing$). Let $\prod_{t \in T} V_t$ be the Cartesian product of $\{V_t\}_{t \in T}$. In other words,

$$\prod_{t \in T} V_t := \left\{ v : T \longrightarrow \bigsqcup_{t \in T} V_t \mid v(t) \in V_t, \text{ for each } t \in T \right\}.$$

That $\prod_{t \in T} V_t \neq \emptyset$ follows from the Axiom of Choice. For each $t \in T$, let

$$\pi_t : \prod_{\tau \in T} V_{\tau} \longrightarrow V_t : v \longmapsto v(t)$$

be the projection map from $\prod_{\tau \in T} V_{\tau}$ onto V_t . The **product** σ -algebra on $\prod_{t \in T} V_t$ is the following:

$$\sigma\!\left(\left\{\begin{array}{l} \pi_t^{-1}(F) \,\subset\, \prod_{\tau \in T} V_\tau \,\,\middle|\,\, F \in \mathcal{F}_t \,,\, t \in T \end{array}\right\}\right) \ \subset \ \operatorname{PowerSet}\!\left(\prod_{t \in T} V_t \right).$$

Clearly, it is the smallest σ -algebra on $\prod_{t \in T} V_t$ with respect to which each projection map $\pi_t : \prod_{t \in T} V_t \longrightarrow (V_t, \mathcal{F}_t)$ is measurable. We denote the product σ -algebra on $\prod_{t \in T} V_t$ by

$$\sigma \left(\prod_{t \in T} (V_t, \mathcal{F}_t) \right).$$

Theorem B.2

Suppose Ω , T, and V are non-empty sets. Let $\{X_t : \Omega \longrightarrow V\}_{t \in T}$ be a T-indexed family of V-valued maps defined on Ω . Then, the following statements are true:

1. The family $\{X_t : \Omega \longrightarrow V\}_{t \in T}$ of maps is set-theoretically equivalent (in the sense that either completely determines the other) to the following (V^T) -valued map defined on Ω :

$$X: \Omega \longrightarrow V^T: \omega \longmapsto (t \longmapsto X_t(\omega)),$$

where $V^T = \prod_{t \in T} V$ denotes the set of all (arbitrary) V-valued functions defined on T.

- 2. Suppose:
 - (Ω, A) and (V, \mathcal{F}) are measurable space structures on Ω and V, respectively.
 - $W \subset V^T$ is a subset of V^T such that $X(\Omega) = \bigcup_{t \in T} X_t(\Omega) \subset W$.
 - (W, \mathcal{G}) is a measurable space structure on W such that, for each $t \in T$, the projection map

$$\pi_t: W \longrightarrow V: w \longmapsto w(t)$$

is $(\mathcal{G}, \mathcal{F})$ -measurable.

Then, $(\mathcal{A}, \mathcal{G})$ -measurability of $X : \Omega \longrightarrow W$ implies $(\mathcal{A}, \mathcal{F})$ -measurability of $X_t : \Omega \longrightarrow V$ for each $t \in T$.

- 3. Suppose:
 - (Ω, \mathcal{A}) and (V, \mathcal{F}) are measurable space structures on Ω and V, respectively.
 - $\sigma[(V,\mathcal{F})^T]$ is the product σ -algebra on $V^T = \prod_{t \in T} V$ generated by the collection of projection maps

$$\left\{ \, \pi_t \, : \, V^T = \prod_{\tau \in T} V \, \longrightarrow \, V \, : \, w \, \longmapsto \, w(t) \, \right\}_{t \in T}.$$

Then, $X: \Omega \longrightarrow V^T$ is $(\mathcal{A}, \sigma[(V, \mathcal{F})^T])$ -measurable if and only if $X_t: \Omega \longrightarrow V$ is $(\mathcal{A}, \mathcal{F})$ -measurable for each $t \in T$.

Proof

- 1. The proof of this result is routine and we omit it.
- 2. Suppose $X: \Omega \longrightarrow W$ is $(\mathcal{A}, \mathcal{G})$ -measurable. Note that $X_t = \pi_t \circ X$, where

$$\pi_t : V^T = \prod_{t \in T} V \longrightarrow V : v \longrightarrow v(t)$$

is the projection from $V^T = \prod_{\tau \in T} V$ onto the t-th factor. By hypothesis, $\pi_t : W \longrightarrow V$ is $(\mathcal{G}, \mathcal{F})$ -measurable for each $t \in T$. This implies, for each $t \in T$, $X_t = \pi_t \circ X$ is $(\mathcal{A}, \mathcal{F})$ -measurable, being a composition of two measurable maps.

3. Since, for each $t \in T$, the projection map $\pi_t : V^T \longrightarrow V$ is $\left(\sigma[(V, \mathcal{F})^T], \mathcal{F}\right)$ -measurable (by construction of the σ -algebra $\sigma[(V, \mathcal{F})^T]$ on V^T), the preceding result immediately implies the following implication:

$$(\mathcal{A},\sigma[(V,\mathcal{F})^T])\text{-measurability of }X:\Omega\longrightarrow V^T\quad\Longrightarrow\quad (\mathcal{A},\mathcal{F})\text{-measurability of }X_t:\Omega\longrightarrow V\text{, for each }t\in T.$$

Conversely, suppose X_t is $(\mathcal{A}, \mathcal{F})$ -measurable for each $t \in T$. Recall that the product σ -algebra on V^T is generated by sets of the form:

$$\pi_t^{-1}(F)$$
, for some $t \in T$ and $F \in \mathcal{F}$.

It follows that, for each $t \in T$ and each $F \in \mathcal{F}$, we have

$$X^{-1}(\pi_t^{-1}(F)) = (X^{-1} \circ \pi_t^{-1})(F) = (\pi_t \circ X)^{-1}(F) = X_t^{-1}(F) \subset \Omega$$

is \mathcal{A} -measurable, since $X_t:(\Omega,\mathcal{A})\longrightarrow (V,\mathcal{F})$ is $(\mathcal{A},\mathcal{F})$ -measurable by hypothesis. This proves that $X:\Omega\longrightarrow V^T$ is $(\mathcal{A},\sigma[(V,\mathcal{F})^T])$ -measurable.

Definition B.3 (Stochastic processes)

A stochastic process is a family, indexed by some non-empty set T,

$$\{X_t: (\Omega, \mathcal{A}, \mu) \longrightarrow (V, \mathcal{F})\}_{t \in T}$$

of (A, \mathcal{F}) -measurable maps, where the common domain (Ω, A, μ) is a probability space and the common codomain (V, \mathcal{F}) is a measurable space. The common codomain (V, \mathcal{F}) is called the **state space** of the stochastic process.

Corollary B.4

Suppose:

- $(\Omega, \mathcal{A}, \mu)$ is a probability space and (V, \mathcal{F}) is a measurable space.
- T is a non-empty set and $W \subset V^T = \prod_{t \in T} V$.
- (W,\mathcal{G}) is a measurable space structure on W such that, for each $t \in T$, the projection map

$$\pi_t: W \longrightarrow V: w \longmapsto w(t)$$

is $(\mathcal{G}, \mathcal{F})$ -measurable.

If $X: (\Omega, \mathcal{A}, \mu) \longrightarrow (V^T, \sigma[(V, \mathcal{F})^T])$ is a V^T -valued random variable (i.e. X is $(\mathcal{A}, \sigma[(V, \mathcal{F})^T])$ -measurable), then its set-theoretically equivalent T-indexed family of V-valued maps defined on Ω

$$\left\{ \begin{array}{ccc} X_t & : & (\Omega, \mathcal{A}, \mu) & \longrightarrow & (V, \mathcal{F}) \\ & \omega & \longmapsto & (\pi_t \circ X)(\omega) = \pi_t(X(\omega)) = X(\omega)(t) \end{array} \right\}_{t \in T}$$

is a stochastic process (i.e. X_t is (A, \mathcal{F}) -measurable for each $t \in T$).

Corollary B.5

Suppose:

- T, Ω , V are non-empty sets.
- $(\Omega, \mathcal{A}, \mu)$ is a probability space structure on Ω , (V, \mathcal{F}) is a measurable space structure on V.
- $\sigma[(V, \mathcal{F})^T]$ denotes the corresponding product σ -algebra on $V^T = \prod_{t \in T} V$.

Let $\{X_t : \Omega \longrightarrow V\}_{t \in T}$ be a T-indexed family of V-valued maps defined on Ω , and let

$$X: \Omega \longrightarrow V^T: \omega \longmapsto (t \longmapsto X_t(\omega))$$

be its set-theoretically equivalent (V^T) -valued map defined on Ω . Then,

$$\{X_t: (\Omega, \mathcal{A}, \mu) \longrightarrow (V, \mathcal{F})\}_{t \in T}$$

is a stochastic process if and only if

$$X: (\Omega, \mathcal{A}, \mu) \longrightarrow (V^T, \sigma[(V, \mathcal{F})^T])$$

is a (V^T) -valued random variable.

C Uniqueness of the "full distribution" of a stochastic process $\{X_t : \Omega \longrightarrow V\}_{t \in T}$ given its finite-dimensional distributions

Definition C.1 (Finite-dimensional distributions of a stochastic process)

Let $\{X_t : (\Omega, \mathcal{A}, \mu) \longrightarrow (V, \mathcal{F})\}_{t \in T}$ be a stochastic process. Let $n \in \mathbb{N}$ and $t_1, t_2, \dots, t_n \in T$ be distinct elements of T. Let $\mathcal{P}_{(X_{t_1}, \dots, X_{t_n})} \in \mathcal{M}_1(V^n, \mathcal{F}^{\otimes n})$ denote the probability measure induced on the product measurable space $(V^n, \mathcal{F}^{\otimes n})$ by the random variable

$$(X_{t_1}, X_{t_2}, \dots, X_{t_n}) : (\Omega, \mathcal{A}, \mu) \longrightarrow (V^n, \mathcal{F}^{\otimes n})$$

 $\mathcal{P}_{\left(X_{t_1},...,X_{t_n}\right)}$ is called a **finite-dimensional distribution** of the stochastic process.

Theorem C.2

Let (V, \mathcal{F}) be a measurable space, and $\sigma[(V, \mathcal{F})^T]$ the product σ -algebra on $V^T = \prod_{t \in T} V$. Let

$$\{X_t: (\Omega_X, \mathcal{A}_X, \mu_X) \longrightarrow (V, \mathcal{F})\}_{t \in T} \text{ and } \{Y_t: (\Omega_Y, \mathcal{A}_Y, \mu_Y) \longrightarrow (V, \mathcal{F})\}_{t \in T}$$

be two stochastic processes with the same index set T and the same state space (V, \mathcal{F}) . Let

$$X: (\Omega_X, \mathcal{A}_X, \mu_X) \longrightarrow \left(V^T, \sigma\left[\left(V, \mathcal{F}\right)^T\right]\right) \quad \text{and} \quad Y: \left(\Omega_Y, \mathcal{A}_Y, \mu_Y\right) \longrightarrow \left(V^T, \sigma\left[\left(V, \mathcal{F}\right)^T\right]\right)$$

be their respective $(V^T, \sigma[(V, \mathcal{F})^T])$ -valued random variables. Let \mathcal{P}_X , $\mathcal{P}_Y \in \mathcal{M}_1(V^T, \sigma[(V, \mathcal{F})^T])$ be the probability measures induced on $(V^T, \sigma[(V, \mathcal{F})^T])$ by X and Y, respectively. Then,

$$\mathcal{P}_X = \mathcal{P}_Y \in \mathcal{M}_1\left(V^T, \sigma\Big[(V, \mathcal{F})^T\Big]\right)$$

if and only if

 $\mathcal{P}_{\left(X_{t_1},X_{t_2},\ldots,X_{t_n}\right)} = \mathcal{P}_{\left(Y_{t_1},Y_{t_2},\ldots,Y_{t_n}\right)} \in \mathcal{M}_1\left(V^n,\mathcal{F}^{\otimes n}\right), \text{ for each } n \in \mathbb{N} \text{ and pairwise distinct } t_1,t_2,\ldots,t_n \in T.$

Proof

D Existence of a stochastic process given its finite-dimensional distributions: Komolgorov's Existence Theorem

Definition D.1 (Stochastic processes)

Suppose $(\Omega, \mathcal{A}, \mu)$ is a probability space, (V, \mathcal{F}) is a measurable space, and T is an arbitrary non-empty set. A **stochastic process** indexed by T defined on Ω with codomain V is a family $\{X_t : \Omega \longrightarrow V\}_{t \in T}$ indexed by T of V-valued random variables defined on Ω .

Definition D.2 (Finite-dimensional distributions of a stochastic processes)

Let $\{X_t : \Omega \longrightarrow (V, \mathcal{F})\}_{t \in T}$ be a stochastic process. Let $n \in \mathbb{N}$ and $t_1, t_2, \ldots, t_n \in T$ be distinct elements of T. The probability distribution induced on the product measurable space $(V^n, \mathcal{F}^{\otimes n})$ by $(X_{t_1}, X_{t_2}, \ldots, X_{t_n}) : \Omega \longrightarrow V^n$ is called a **finite-dimensional distribution** of the stochastic process.

Definition D.3 (Komolgorov systems of finite-dimensional distributions & Komolgorov consistency)

Let T be an arbitrary non-empty set, and $\mathcal{D}(T)$ the set of all finite ordered sequences of elements of T whose elements are pairwise distinct; in other words,

$$\mathcal{D}(T) := \left\{ (t_1, t_2, \dots, t_n) \in \bigcup_{k=1}^{\infty} T^k \mid n \in \mathbb{N}, \ t_i \neq t_j, \text{ whenever } i \neq j \right\}.$$

For each $n \in \mathbb{N}$, let $\mathcal{M}_1(\mathbb{R}^n, \mathcal{B}(\mathbb{R}^n))$ be the set of all probability measures defined on the product measurable space $(\mathbb{R}^n, \mathcal{B}(\mathbb{R}^n))$. A **Komolgorov system of finite-dimensional distributions** is a $\mathcal{D}(T)$ -indexed family \mathcal{P} of probability measures of the following form:

$$\mathcal{P} = \left\{ P_{(t_1, \dots, t_n)} \in \mathcal{M}_1(\mathbb{R}^n, \mathcal{B}(\mathbb{R}^n)) \mid (t_1, \dots, t_n) \in \mathcal{D}(T) \right\}.$$

Furthermore, \mathcal{P} is said to be **Komolgorov consistent** if it satisfies both of the following conditions:

• permutation invariance: For any $n \in \mathbb{N}$, any $(t_1, \ldots, t_n) \in \mathcal{D}(T)$, any $B_1, \ldots, B_n \in \mathcal{B}(\mathbb{R})$, and any permutation $\pi : \{1, \ldots, n\} \longrightarrow \{1, \ldots, n\}$, the following equality holds:

$$P_{(t_1,...,t_n)}(B_1 \times \cdots \times B_n) = P_{(t_{\pi(1)},...,t_{\pi(n)})}(B_{\pi(1)} \times \cdots \times B_{\pi(n)}).$$

• projection invariance: For any $n \in \mathbb{N}$, any $(t_1, \ldots, t_{n+1}) \in \mathcal{D}(T)$, and any $B_1, \ldots, B_n \in \mathcal{B}(\mathbb{R})$, the following equality holds:

$$P_{(t_1,\ldots,t_n,t_{n+1})}(B_1\times\cdots\times B_n\times\mathbb{R}) = P_{(t_1,\ldots,t_n)}(B_1\times\cdots\times B_n).$$

Remark D.4

It is obvious that the collection of finite-dimensional distributions of any \mathbb{R} -valued stochastic process is a Komolgorov consistent Komolgorov system of finite-dimensional distributions.

Definition D.5

Let $\{X_t : \Omega \longrightarrow \mathbb{R}\}_{t \in T}$ be an \mathbb{R} -valued stochastic process, and

$$\mathcal{P} = \left\{ P_{(t_1,\dots,t_n)} \in \mathcal{M}_1(\mathbb{R}^n,\mathcal{B}(\mathbb{R}^n)) \mid (t_1,\dots,t_n) \in \mathcal{D}(T) \right\}$$

be a Komolgorov system of finite-dimensional distributions. We say that the stochastic process $\{X_t\}$ admits \mathcal{P} as its collection of finite-dimensional distributions if, for each $n \in \mathbb{N}$ and any $(t_1, t_2, \ldots, t_n) \in \mathcal{D}(T)$, the probability distribution induced on $(\mathbb{R}^n, \mathcal{B}(\mathbb{R}^n))$ by the map

$$(X_{t_1},\ldots,X_{t_n}):\Omega\longrightarrow\mathbb{R}^n$$

equals $P_{(t_1,\ldots,t_n)} \in \mathcal{P}$.

Theorem D.6 (Komolgorov's Existence Theorem, Theorem 36.2, [2])

Let

$$\mathcal{P} = \left\{ P_{(t_1, \dots, t_n)} \in \mathcal{M}_1(\mathbb{R}^n, \mathcal{B}(\mathbb{R}^n)) \mid (t_1, \dots, t_n) \in \mathcal{D}(T) \right\}.$$

be a Komolgorov system of finite-dimensional distributions. Then, there exists a stochastic process

$$\{X_t: (\Omega, \mathcal{A}, \mu) \longrightarrow (\mathbb{R}, \mathcal{B}(\mathbb{R}))\}_{t \in T}$$

which admits \mathcal{P} as its collection of finite-dimensional distributions if and only if \mathcal{P} is Komolgorov consistent.

E Gaussian Processes

Definition E.1 (Gaussian processes)

An \mathbb{R} -valued stochastic process $\{X_t : \Omega \longrightarrow \mathbb{R}\}_{t \in T}$ is said to be **Gaussian** if each of its finite-dimensional distribution is a (univariate or multivariate) Gaussian distribution.

Definition E.2 (Mean and covariance functions of R-valued stochastic processes)

Let $\{X_t : \Omega \longrightarrow \mathbb{R}\}_{t \in T}$ be an \mathbb{R} -valued stochastic process.

• If, for each $t \in T$, we have $E(X_t) \in \mathbb{R}$, then the function

$$a_X: T \longrightarrow \mathbb{R}: t \longmapsto E(X_t)$$

is called the **mean** function of the \mathbb{R} -valued stochastic process $\{X_t\}$.

• In addition, if, for each $t_1, t_2 \in T$, we have $0 \leq \text{Cov}(X_{t_1}, X_{t_2}) < \infty$, then the function

$$\Sigma_X : T \times T \longrightarrow \mathbb{R} : (t_1, t_2) \longmapsto \operatorname{Cov}(X_{t_1}, X_{t_2})$$

is called the **covariance** function of the \mathbb{R} -valued stochastic process $\{X_t\}$.

Theorem E.3

Let T be an arbitrary non-empty set, $a: T \longrightarrow \mathbb{R}$ an arbitrary \mathbb{R} -valued function defined on T, and $\Sigma: T \times T \longrightarrow [0, \infty)$ a non-negative \mathbb{R} -valued function defined on $T \times T$. Then, there exists a Gaussian process whose mean and covariance functions are a and Σ , respectively.

Theorem E.4

The mean and covariance functions of a Gaussian process together completely determine its collection of finite-dimensional distributions.

Definition E.5 (Brownian motion, a.k.a. Wiener process)

A Brownian motion, or Wiener process, is a stochastic process $\{W_t : (\Omega, \mathcal{A}, \mu) \longrightarrow \mathbb{R}\}_{t \geq 0}$ indexed by the non-negative real line satisfying the following conditions:

• At t = 0, the process takes value 0 with probability 1; more precisely:

$$P(W_0 = 0) = \mu(\{ \omega \in \Omega \mid W_0(\omega) = 0 \}) = 1.$$

• The process $\{W_t\}$ has independent increments; more precisely: for any $0 \le t_1 \le t_2 \le \cdots \le t_n < \infty$,

$$W_{t_n} - W_{t_{n-1}}, \quad W_{t_{n-1}} - W_{t_{n-2}}, \quad \dots , \quad W_{t_2} - W_{t_1} : \Omega \longrightarrow \mathbb{R}$$

are independent random variables.

• For $0 \le t_1 < t_2 < \infty$, the increment $W_{t_2} - W_{t_1}$ follows a Gaussian distribution with mean 0 and variance $t_2 - t_1$.

Some Asymptotic Theory for the Bootstrap

Study Notes July 9, 2015 Kenneth Chu

Definition E.6 (Brownian bridge)

- A Brownian bridge is a Gaussian process $\{W_t^{\circ}: (\Omega, \mathcal{A}, \mu) \longrightarrow \mathbb{R}\}_{t \in [0,1]}$ indexed by the closed unit interval in \mathbb{R} satisfying the following conditions:
 - For each $t \in [0,1]$, we have $E(W_t^{\circ}) = 0$.
 - $\bullet \ \ \textit{For any} \ t_1,t_2 \in [0,1], \ \textit{we have} \ \mathrm{Cov}\big(W^0_{t_1},W^\circ_{t_2}\big) = \min\{t_1,t_2\} t_1t_2.$

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