

Let $Y : \Omega \rightarrow \mathbb{R}^n$ be an \mathbb{R}^n -valued random variable defined on the probability space Ω . We assume that the expected value $E[Y]$ of Y exists. Then, trivially, we have $E[Y] \in \mathbb{R}^n$.

1 Assumption on the expected value of the response variable Y

The most fundamental assumption of the General Linear Model is that the expected value of the response variable Y lies in a model-specific subspace of \mathbb{R}^n (this subspace will be called the *estimation space* of the model), in the following sense: One of the “components” of a general linear model is its *model matrix* $X \in \mathbb{R}^{n \times p}$, and the expected value of the response variable Y is assumed to lie in the column space $\mathcal{C}(X) \subset \mathbb{R}^n$.

In other words:

The Estimation Space Assumption

$$E[Y] \in \mathcal{C}(X); \text{ equivalently, } E[Y] = X\beta, \text{ for some (unknown) } \beta \in \mathbb{R}^p, \quad (1.1)$$

where $\mathcal{C}(X) \subset \mathbb{R}^n$ is the column space of the model matrix $X \in \mathbb{R}^{n \times p}$.

We will call \mathbb{R}^n the *observation space*, and $\mathcal{C}(X)$ the *estimation space* of the model.

2 Assumption of the distribution of the response variable Y

In order to make estimation and hypothesis testing computationally feasible, we need to make certain assumptions on the distribution of the response variable Y .

Assumptions on the distribution of Y :

1. The response variable Y has a multivariate normal distribution.
2. The components of Y are independent \mathbb{R} -valued random variables.
3. The variances of the components of Y are all equal.

The assumptions on the expected value and distribution on Y together are equivalent to the following:

$$Y \sim N(X\beta, \sigma^2 I_n), \text{ for some (unknown but fixed) } \beta \in \mathbb{R}^p, \text{ and some (unknown but fixed) } \sigma > 0. \quad (2.1)$$

Define $\varepsilon := Y - X\beta$. Then, $\varepsilon : \Omega \rightarrow \mathbb{R}^n$ is also an \mathbb{R}^n -valued random variable, with

$$\varepsilon \sim N(0, \sigma^2 I_n), \text{ for some } \sigma > 0. \quad (2.2)$$

Proposition 2.1 (Distribution of the full-model error sum-of-squares)

Let $P_{\mathcal{C}(X)^\perp} : \mathbb{R}^n \rightarrow \mathbb{R}^n$ denote the orthogonal projection operator onto the subspace $\mathcal{C}(X)^\perp$. Then,

$$\frac{\|P_{\mathcal{C}(X)^\perp}(Y)\|^2}{\sigma^2} \sim \chi^2(\text{rank}(\mathcal{C}(X)^\perp))$$

3 Testing the hypothesis that $H_0 : E[Y] \in \mathcal{C}(X_0) \subset \mathcal{C}(X)$

Proposition 3.1

Let $P_{\mathcal{C}(X_0)^\perp \cap \mathcal{C}(X)} : \mathbb{R}^n \rightarrow \mathbb{R}^n$ denote the orthogonal projection operator onto the subspace $\mathcal{C}(X_0)^\perp \cap \mathcal{C}(X)$. Then,

$$\frac{\|P_{\mathcal{C}(X_0)^\perp \cap \mathcal{C}(X)}(Y)\|^2}{\sigma^2} \sim \chi^2\left(\text{rank}(\mathcal{C}(X_0)^\perp \cap \mathcal{C}(X)), \frac{\|P_{\mathcal{C}(X_0)^\perp \cap \mathcal{C}(X)}X\beta\|^2}{2\sigma^2}\right)$$

Corollary 3.2 (Distribution of F -statistics under validity of full model)

$$\frac{\|P_{\mathcal{C}(X_0)^\perp \cap \mathcal{C}(X)}(Y)\|^2 / \text{rank}(\mathcal{C}(X_0)^\perp \cap \mathcal{C}(X))}{\|P_{\mathcal{C}(X)^\perp}(Y)\|^2 / \text{rank}(\mathcal{C}(X)^\perp)} \sim F\left(\text{rank}(\mathcal{C}(X_0)^\perp \cap \mathcal{C}(X)), \text{rank}(\mathcal{C}(X)^\perp); \frac{\|P_{\mathcal{C}(X_0)^\perp \cap \mathcal{C}(X)}X\beta\|^2}{2\sigma^2}\right)$$

Corollary 3.3 (Distribution of F -statistics under validity of reduced model)

$$\frac{\|P_{\mathcal{C}(X_0)^\perp \cap \mathcal{C}(X)}(Y)\|^2 / \text{rank}(\mathcal{C}(X_0)^\perp \cap \mathcal{C}(X))}{\|P_{\mathcal{C}(X)^\perp}(Y)\|^2 / \text{rank}(\mathcal{C}(X)^\perp)} \sim F(\text{rank}(\mathcal{C}(X_0)^\perp \cap \mathcal{C}(X)), \text{rank}(\mathcal{C}(X)^\perp); 0)$$

4 Model adequacy checking

Model adequacy checking is large done via examination of the residuals of the model fit. Recall that the least-squares estimator $\hat{Y} : \Omega \rightarrow \mathcal{C}(X)$ of the response variable $Y : \Omega \rightarrow \mathbb{R}^n$ is given by:

$$\hat{Y} = X \cdot (X^t \cdot X)^{-1} \cdot X^t \cdot Y = H \cdot Y,$$

where $H := X \cdot (X^t \cdot X)^{-1} \cdot X^t$ is called the **hat matrix** of the model. Recall also that, geometrically speaking, the hat matrix H is simply the orthogonal projection operator, defined on \mathbb{R}^n (the observation space), onto the column space $\mathcal{C}(X)$ of X (the estimation space, or the model space). The **residual** $\mathbf{e} : \Omega \rightarrow \mathcal{C}(X)^\perp$ is defined to be:

$$\mathbf{e} := Y - \hat{Y} = (I_n - H) \cdot Y,$$

where $I - H$ is the orthogonal projection operator defined on \mathbb{R}^n (the observation space) onto the orthogonal complement $\mathcal{C}(X)^\perp$ of $\mathcal{C}(X)$. Note that $\mathcal{C}(X)^\perp$ can be regarded as the **error space** of the model. Recall that our model assumption is:

$$Y = X \cdot \beta + \varepsilon,$$

with $\varepsilon \sim N(0, \sigma^2 I_n)$; see (2.2). Note that in general, the codomain of the error term $\varepsilon : \Omega \rightarrow \mathbb{R}^n$ is NOT $\mathcal{C}(X)^\perp$ but all of the observation space \mathbb{R}^n . On the other hand, observe that

$$\mathbf{e} = (I_n - H) \cdot Y = (I_n - H) \cdot (X \cdot \beta + \varepsilon) = (I_n - H) \cdot \varepsilon,$$

since $I_n - H$ is the orthogonal projection operator onto $\mathcal{C}(X)^\perp$, which maps $X \cdot \beta \in \mathcal{C}(X)$ to zero. We thus see that the residual $\mathbf{e} : \Omega \rightarrow \mathcal{C}(X)^\perp$ is the orthogonal projection of the error term $\varepsilon : \Omega \rightarrow \mathbb{R}^n$ onto the error space $\mathcal{C}(X)^\perp$. Or, more strictly speaking, the residual $\mathbf{e} : \Omega \rightarrow \mathcal{C}(X)^\perp$ is the composition

$$\mathbf{e} : \Omega \xrightarrow{\varepsilon} \mathbb{R}^n \xrightarrow{I_n - H} \mathcal{C}(X)^\perp$$

Furthermore, note that

$$\begin{aligned} \text{Var}(\mathbf{e}) &= \text{Var}[(I_n - H) \cdot \varepsilon] = (I_n - H) \cdot \text{Var}[\varepsilon] \cdot (I_n - H)^t = (I_n - H) \cdot \text{Var}[\varepsilon] \cdot (I_n - H) \\ &= (I_n - H) \cdot \sigma^2 I_n \cdot (I_n - H) = \sigma^2 \cdot (I_n - H) \cdot (I_n - H) \\ &= \sigma^2 \cdot (I_n - H), \end{aligned}$$

where the symmetry and idempotence of the orthogonal projection operator $I_n - H$ is used in the above derivation. The above observations lead to the following “model adequacy checks”:

- Generate the scatter plot of the observed residuals \mathbf{e} against the fitted values \hat{y} . Examine this scatter plot for trends between the observed residuals and the fitted values; any trend between the observed residuals and the fitted values may indicate violations of model assumptions.

This adequacy check is based on the following fact:

$$\text{Cov}(\hat{Y}, \mathbf{e}) = \text{Cov}(H \cdot Y, (I_n - H) \cdot Y) = H \cdot \text{Cov}(Y, Y) \cdot (I_n - H) = H \cdot \sigma^2 I_n \cdot (I_n - H) = 0_{n \times n}$$

- Generate the scatter plot of the observed residuals \mathbf{e} against the observed values of each of the predictor variables (columns of the model matrix X). Any trends in any of these scatter plots may indicate violations of model assumptions.
- Generate the QQ-plot of the **Studentized residuals** against the theoretical quantiles of the standard Gaussian distribution, where the Studentized residuals are defined as follows:

$$r_i := \frac{e_i}{\sqrt{\text{MS}_{\text{error}}(1 - h_{ii})}}$$

where e_i is the i^{th} component of the observed residual \mathbf{e} , h_{ii} is the i^{th} diagonal element of the hat matrix $H := X \cdot (X^t \cdot X)^{-1} \cdot X^t$, and MS_{error} is the mean squared error of the model fit, which is defined as follows:

$$\text{MS}_{\text{error}} := \frac{1}{n - p} \sum_{i=1}^n (y_i - \hat{y}_i)^2$$

Large deviations of the data points on this QQ-plot from the $y = x$ line may indicate violations of model assumptions. This model adequacy check is based on the observations that (1) MS_{error} is an unbiased estimator of σ^2 , and (2):

$$\mathbf{e} \sim N(0, \sigma^2(I_n - H)) ,$$

which in turn implies that, for each $i = 1, \dots, n$,

$$\frac{e_i}{\sqrt{\sigma^2(1 - h_{ii})}} \sim N(0, 1)$$