This set of notes aims to provide complete proofs of a number of asymptotic results regarding the Bootstrap [4] contained in Bickel and Freedman [1].

1 Bootstrap asymptotics for sample mean

Theorem 1.1 (Bootstrap Central Limit Theorem for I.I.D. sample mean, Theorem 2.1 [1])

Let $(\Omega, \mathcal{A}, \nu)$ be a probability space. Let $X, X_1, X_2, \ldots : \Omega \longrightarrow \mathbb{R}$ be a sequence of independent and identically distributed \mathbb{R} -valued random variables defined on Ω with finite expectation value $\mu_X \in \mathbb{R}$ and variance $\sigma_X^2 < \infty$. For each $n \in \mathbb{N}$, define:

$$\overline{X}_n : \Omega \longrightarrow \mathbb{R} : \omega \longmapsto \frac{1}{n} \sum_{i=1}^n X_i(\omega).$$

For $n, m \in \mathbb{N}$, define $\mathcal{S}_m^{(n)}$ to be the set of all functions from $\{1, 2, \dots, m\} \longrightarrow \{1, 2, \dots, n\}$. Thus, each

$$s = (s(1), s(2), \dots, s(m)) \in \mathcal{S}_m^{(n)}$$

can be regarded as a length-m finite (ordered) sequence of positive integers between 1 and n, inclusive. Note that $\mathcal{S}_m^{(n)}$ is a finite set with $|\mathcal{S}_m^{(n)}| = n^m$. Endow $\mathcal{S}_m^{(n)}$ with the probability space structure induced by the uniform probability function:

$$P_{\mathcal{S}_m^{(n)}}(s) := \frac{1}{n^m}, \text{ for each } s \in \mathcal{S}_m^{(n)}.$$

Let $\Omega \times \mathcal{S}_m^{(n)}$ be the product probability space of Ω and $\mathcal{S}_m^{(n)}$. Define:

$$\overline{X}_m^{(n)}: \Omega \times \mathcal{S}_m^{(n)} \longrightarrow \mathbb{R}: (\omega, s) \longmapsto \frac{1}{m} \sum_{i=1}^m X_{s(j)}(\omega).$$

For each $\omega \in \Omega$, define:

$$\Phi_{m,\omega}^{(n)}: \mathcal{S}_m^{(n)} \longrightarrow \mathbb{R}: s \longmapsto \sqrt{m} \left(\overline{X}_m^{(n)}(\omega, s) - \overline{X}_n(\omega) \right)$$

Then.

$$P\Big(\ \Phi_{m,\omega}^{(n)} \stackrel{d}{\longrightarrow} N(0,\sigma_X^2), \text{ as } n,m \to \infty \ \Big) \ \ = \ \ \nu\Big(\Big\{ \ \omega \in \Omega \ \ \Big| \ \Phi_{m,\omega}^{(n)} \stackrel{d}{\longrightarrow} N(0,\sigma_X^2), \text{ as } n,m \to \infty \ \Big\} \Big) \ \ = \ \ 1.$$

Remark 1.2

For each fixed $\omega \in \Omega$, $\left\{\Phi_{m,\omega}^{(n)} : \mathcal{S}_m^{(n)} \longrightarrow \mathbb{R}\right\}_{n,m\in\mathbb{N}}$ is a doubly indexed sequence of \mathbb{R} -valued random variables. Note that their respective domains $\mathcal{S}_m^{(n)}$ are pairwise distinct probability spaces. The **Bootstrap Central Limit Theorem** for I.I.D. sample mean asserts that for almost every $\omega \in \Omega$, the doubly indexed sequence $\left\{\Phi_{m,\omega}^{(n)}\right\}$ of \mathbb{R} -valued random variables converges in distribution to $N(0,\sigma_X^2)$ as $n,m \longrightarrow \infty$.

Remark 1.3 The following results are well known from classical asymptotic theory:

By the Weak Law of Large Numbers, \overline{X}_n converges in probability to μ_X , as $n \longrightarrow \infty$; in other words,

$$\lim_{n \to \infty} P(|\overline{X}_n - \mu_X| > \varepsilon) = \lim_{n \to \infty} \nu(\{\omega \in \Omega : |\overline{X}_n(\omega) - \mu_X| > \varepsilon\}) = 0, \text{ for each } \varepsilon > 0.$$

By the Strong Law of Large Numbers, \overline{X}_n converges almost surely to μ_X , as $n \to \infty$; in other words,

$$P\Big(\lim_{n\to\infty} \overline{X}_n = \mu_X\Big) = \nu\Big(\Big\{\omega\in\Omega \mid \lim_{n\to\infty} \overline{X}_n(\omega) = \mu_X\Big\}\Big) = 1.$$

By the Central Limit Theorem, $\sqrt{n}(\overline{X}_n - \mu_X)$ converges in distribution to $N(0, \sigma_X^2)$.

PROOF Let $\mathcal{M}_1(\mathbb{R}, \mathcal{B}(\mathbb{R}))$ denotes the collection of probability measures on $(\mathbb{R}, \mathcal{B}(\mathbb{R}))$. Define

$$\Gamma_2 := \left\{ G \in \mathcal{M}_1(\mathbb{R}, \mathcal{B}(\mathbb{R})) \mid \int_{\mathbb{R}} x^2 dG(x) < \infty \right\}.$$

Define the **Wasserstein metric** on Γ_2 :

$$d_2: \Gamma_2 \times \Gamma_2 \longrightarrow \mathbb{R}: (G, G') \longmapsto \inf \left\{ \sqrt{E[\rho(X, Y)^2]} \mid (X, Y) \in C(G, G') \right\}$$

Claim 1: d_2 is indeed a metric on Γ_2 .

Claim 2: For $G, G_1, G_2, \ldots \in \Gamma_2$,

$$G_n \xrightarrow{d_2} G$$
 if and only if $G_n \longrightarrow G$ weakly and $\int_{\mathbb{R}} x^2 dG_n(x) \longrightarrow \int_{\mathbb{R}} x^2 dG(x)$

Claim 3: For $G \in \Gamma_2$ and $m \in \mathbb{N}$, let $G^{(m)}$ be the *m*-fold empirical measure of G, i.e. $G^{(m)}$ is the (empirical) measure of the random variable

$$S_m^{(G)} := \frac{1}{m^{1/2}} \sum_{i=1}^m \left(Z_i^{(G)} - \mu_G \right),$$

where $\mu_G := \int_{\mathbb{R}} x \, dG(x)$ is the expectation value of the measure G, and $Z_1^{(G)}, Z_2^{(G)}, \dots, Z_m^{(G)}$ are independent and identically distributed random variables with distribution G. Then, for any $G, H \in \Gamma_2$, we have

$$d_2\Big(G^{(m)}, H^{(m)}\Big) \leq d_2(G, H)$$

Claim 4:

$$\nu\left(\left\{ \ \omega \in \Omega \ \middle| \ F_n(\omega) \xrightarrow{\mathbf{w}} F \ \right\} \right) = 1$$

Claim 4 follows from the Glivenko-Cantelli Theorem, which states that:

$$\nu\left(\left\{ \omega \in \Omega \mid \lim_{n \to \infty} \sup_{t \in \mathbb{R}} |F_n(\omega)(t) - F(t)| = 0 \right\} \right) = 1,$$

which implies trivially

$$\nu\Big(\Big\{\;\omega\in\Omega\;\Big|\;\lim_{n\to\infty}F_n(\omega)(t)=F(t),\;\;\text{for each}\;t\in\mathbb{R}\;\Big\}\Big)\;\;=\;\;1,$$

which, in turn, is equivalent to Claim 4.

Claim 5:

$$\nu\left(\left\{ \ \omega \in \Omega \ \middle| \ \int_{\mathbb{R}} x^2 \, \mathrm{d}F_n(\omega)(x) \longrightarrow \int_{\mathbb{R}} x^2 \, \mathrm{d}F(x) \ \right\} \right) = 1$$

By the Strong Law of Large Numbers, we have

$$\int_{\mathbb{R}} x^2 dF_n(\omega)(x) = \frac{1}{n} \sum_{i=1}^n X_i(\omega)^2 \xrightarrow{\text{a.e.}} E[X^2] = \int_{\mathbb{R}} x^2 dF(x)$$

Claim 6:

$$\nu\left(\left\{ \ \omega \in \Omega \ \middle| \ F_n(\omega) \xrightarrow{d_2} F \ \right\}\right) \ = \ \nu(\left\{ \ \omega \in \Omega \ \middle| \ d_2(F_n(\omega), F) \longrightarrow 0 \ \right\}) \ = \ 1$$

Immediate by Claims 2, 4, and 5.

Let $\omega \in \Omega$ be fixed.

$$d_2\Big(F_n^{(m)}(\omega), N(0, \sigma_X^2)\Big) \leq d_2\Big(F_n^{(m)}(\omega), F^{(m)}\Big) + d_2\Big(F^{(m)}, N(0, \sigma_X^2)\Big)$$

$$\leq d_2(F_n(\omega), F) + d_2\Big(F^{(m)}, N(0, \sigma_X^2)\Big)$$

Now, $d_2(F^{(m)}, N(0, \sigma_X^2))) \longrightarrow 0$ by the classical Central Limit Theorem.

$$d_2(F_n(\omega), F) + d_2(F^{(m)}, N(0, \sigma_X^2)) \longrightarrow 0, \quad \text{as } n, m \longrightarrow \infty$$

$$\Longrightarrow \quad d_2(F_n^{(m)}(\omega), N(0, \sigma_X^2)) \longrightarrow 0, \quad \text{as } n, m \longrightarrow \infty$$

$$\Longrightarrow \quad F_n^{(m)}(\omega) \qquad \stackrel{\text{w}}{\longrightarrow} \quad N(0, \sigma_X^2), \quad \text{as } n, m \longrightarrow \infty$$

A Wasserstein Spaces

Proofs of results mentioned in this section can be found in Chapters 1 and 6 of [6].

Suppose (S, S) and (T, T) are two measurable spaces. We will use the following notations:

- $(S \times T, S \otimes T)$ denotes their product measurable space (see Chapter 10, [5]).
- $\mathcal{M}_1(S, \mathcal{S})$, $\mathcal{M}_1(T, \mathcal{T})$, and $\mathcal{M}_1(S \times T, \mathcal{S} \otimes \mathcal{T})$ denote the sets of probability measures on the respective measurable spaces.
- $\Pi^S: S \times T \longrightarrow S: (s,t) \longmapsto s, \Pi^T: S \times T \longrightarrow T: (s,t) \longmapsto t$ are the canonical projection maps, and

$$\Pi^S_* \ : \ \mathcal{M}_1(S \times T, \mathcal{S} \otimes \mathcal{T}) \ \longrightarrow \ \mathcal{M}_1(S, \mathcal{S}) \ : \ \pi \ \longmapsto \ \left(\ A \in \mathcal{S} \longmapsto \pi \big[(\Pi^S)^{-1}(A) \big] \ \right),$$

$$\Pi^T_* : \mathcal{M}_1(S \times T, \mathcal{S} \otimes \mathcal{T}) \longrightarrow \mathcal{M}_1(T, \mathcal{T}) : \pi \longmapsto \left(B \in \mathcal{T} \longmapsto \pi \left[(\Pi^T)^{-1}(B) \right] \right)$$

are the corresponding push-forward maps of measures.

Definition A.1 (Coupling measures and couplings)

Let (S, \mathcal{S}) and (T, \mathcal{T}) be two measurable spaces. Let $\mu \in \mathcal{M}_1(S, \mathcal{S})$ and $\nu \in \mathcal{M}_1(T, \mathcal{T})$.

• A coupling (probability) measure of μ and ν is a probability measure $\pi \in \mathcal{M}_1(S \times T, \mathcal{S} \otimes \mathcal{T})$ whose push-forwards under the canonical projection maps are μ and ν respectively; in other words $\pi \in \mathcal{M}_1(S \times T, \mathcal{S} \otimes \mathcal{T})$ is a coupling measure of $(\mu, \nu) \in \mathcal{M}_1(S, \mathcal{S}) \times \mathcal{M}_1(T, \mathcal{T})$ if π satisfies:

$$\Pi_*^S(\pi) = \mu$$
 and $\Pi_*^T(\pi) = \nu$.

In this case, μ and ν are called the **marginal (probability) measures** of π . We denote by $\Pi(\mu, \nu)$ the subset of $\mathcal{M}_1(S \times T, \mathcal{S} \otimes \mathcal{T})$ of all coupling probability measures of μ and ν .

• A coupling of μ and ν is an $(S \times T)$ -valued random variable

$$Z = (X, Y) : (\Omega, \mathcal{A}, P_{\Omega}) \longrightarrow (S \times T, \mathcal{S} \otimes \mathcal{T})$$

whose induced measure on $(S \times T, S \otimes T)$ is a coupling probability measure of μ and ν . More precisely,

$$\mu(A) = P_X(A) = P_{\Omega}(X^{-1}(A)) = P_{\Omega}((\Pi^S \circ Z)^{-1}(A)) = P_{\Omega}(Z^{-1}[(\Pi^S)^{-1}(A)]), \text{ for each } A \in \mathcal{S}$$

$$\nu(B) = P_Y(B) = P_{\Omega}(Y^{-1}(B)) = P_{\Omega}((\Pi^T \circ Z)^{-1}(B)) = P_{\Omega}(Z^{-1}[(\Pi^T)^{-1}(B)]), \text{ for each } B \in \mathcal{T}$$

Definition A.2 (Wasserstein distances and Wasserstein spaces)

Let $p \in [1, \infty)$. Let (S, ρ) be a Polish space (i.e. separable complete metric space), and S its Borel σ -algebra.

• The Wasserstein distance of order p is, by definition, the map $W_p : \mathcal{M}_1(S, \mathcal{S}) \times \mathcal{M}_1(S, \mathcal{S}) \longrightarrow \mathbb{R} \cup \{+\infty\}$ given by:

$$W_{p}(\mu,\nu) := \inf_{\pi \in \Pi(\mu,\nu)} \left\{ \left(\int_{S \times S} \rho(x,y)^{p} d\pi(x,y) \right)^{1/p} \right\}$$

$$= \inf_{\pi \in \Pi(\mu,\nu)} \left\{ \left(E[\rho(X,Y)^{p}] \right)^{1/p} \in \mathbb{R} \cup \{+\infty\} \middle| \begin{array}{c} X, Y : (\Omega,\mathcal{A},\pi) \longrightarrow (S,\mathcal{S}) \text{ are } S\text{-valued random variables with } X^{*}(\pi) = \mu, Y^{*}(\pi) = \nu \end{array} \right\}.$$

• The Wasserstein space of order p is defined to be:

$$\mathcal{W}_1^p(S,\mathcal{S}) := \left\{ \mu \in \mathcal{M}_1(S,\mathcal{S}) \mid \int_S \rho(x_0,x)^p \, \mathrm{d}\mu(x) < \infty \right\},$$

where $x_0 \in S$ is an arbitrary point in S ($W_1^p(S, S)$) is independent of the choice of $x_0 \in S$). Thus, $W_1^p(S, S)$ is the set of probability measures on (S, S) with finite moment of order p.

Theorem A.3 (Wasserstein metrics)

- The Wasserstein space $\mathcal{W}_1^p(S,\mathcal{S})$ is independent of the choice of the point $x_0 \in S$ in its definition.
- The Wasserstein distance W_p restricts to a metric on $W_1^p(S,\mathcal{S}) \times W_1^p(S,\mathcal{S})$.
- For a Polish space (i.e. separable complete metric space) (S, ρ) with Borel σ -algebra S, the Wassertein space $W_1^p(S, S)$, when metrized by the Wasserstein metric W_p , is itself a Polish space.

Definition A.4 (Weak convergence in metric spaces (Chapter 1, [3]))

Suppose:

- (S, ρ) is a metric space and S is its Borel σ -algebra.
- $\mathcal{M}_1(S,\mathcal{S})$ denotes the set of probability measures defined on (S,\mathcal{S}) .
- $\mu \in \mathcal{M}_1(S, \mathcal{S})$ and $\{\mu_k\}_{k \in \mathbb{N}} \subset \mathcal{M}_1(S, \mathcal{S})$.

Then, $\{\mu_k\}_{k\in\mathbb{N}}$ is said to converge weakly to μ if, for each $f\in C_b(S,\mathbb{R})$,

$$\int_{S} f(x) d\mu_{k}(x) \longrightarrow \int_{S} f(x) d\mu(x), \text{ as } k \longrightarrow \infty,$$

where $C_b(S,\mathbb{R})$ denotes the set of all bounded continuous \mathbb{R} -valued functions on S. We write $\mu_k \xrightarrow{w} \mu$ for μ_k converging weakly to μ .

Definition A.5 (Weak convergence in Wassertein spaces (Definition 6.8, [6]))

Suppose:

- (X, ρ) is a Polish space, and S is its Borel σ -algebra.
- $p \in [1, \infty)$ and $W_1^p(S, S)$ is the corresponding Wasserstein space of order p.
- $\mu \in \mathcal{W}_1^p(S, \mathcal{S})$ and $\{\mu_k\}_{k \in \mathbb{N}} \subset \mathcal{W}_1^p(S, \mathcal{S})$.

Then, $\{\mu_k\}_{k\in\mathbb{N}}$ is said to converge weakly in $\mathcal{W}_1^p(S,\mathcal{S})$ to μ if, for some (hence any) $x_0\in S$, we have:

$$\mu_k \xrightarrow{w} \mu$$
 and $\int_S \rho(x_0, x)^p d\mu_k(x) \longrightarrow \int_S \rho(x_0, x)^p d\mu(x)$, as $k \longrightarrow \infty$.

We write $\mu_k \xrightarrow{W_{1}^p} \mu$ for μ_k converging weakly to μ in $W_1^p(S, \mathcal{S})$.

Theorem A.6 (Wasserstein metrics metrize weak convergence in Wassertein spaces (Theorem 6.9, [6])) Suppose:

- (X, ρ) is a Polish space, and S is its Borel σ -algebra.
- $p \in [1, \infty)$, $(W_1^p(S, S), W_p)$ is the corresponding Wasserstein space of order p, metrized by the Wasserstein metric W_p defined on it.
- $\mu \in \mathcal{W}_1^p(S, \mathcal{S})$ and $\{\mu_k\}_{k \in \mathbb{N}} \subset \mathcal{W}_1^p(S, \mathcal{S})$.

Then,

$$\mu_k \xrightarrow{\mathcal{W}_1^p} \mu$$
 if and only if $W_p(\mu_k, \mu) \longrightarrow 0$.

B A stochastic process $\{X_t : \Omega \longrightarrow V\}_{t \in T}$ and its equivalent V^T -valued random variable $X : \Omega \longrightarrow V^T$

Let Ω , T, and V be non-empty sets. Let $\{X_t : \Omega \longrightarrow V\}_{t \in T}$ be a T-index family of maps, each of which maps from Ω into V. Note that this family of maps is set-theoretically equivalent (in the sense that either one completely determines the other) to the following (V^T) -valued map defined on Ω :

$$X: \Omega \longrightarrow V^T: \omega \longmapsto (t \longmapsto X_t(\omega)),$$

where $V^T = \prod_{t \in T} V$ denotes the set of all (arbitrary) V-valued functions defined on T. In this section, we aim to establish the following two results:

• Suppose (Ω, \mathcal{A}) and (V, \mathcal{F}) are measurable space structures on Ω and V, respectively. Then, $X : \Omega \longrightarrow V^T$ is $(\mathcal{A}, \sigma[(V, \mathcal{F})^T])$ -measurable if and only if $X_t : \Omega \longrightarrow V$ is $(\mathcal{A}, \mathcal{F})$ -measurable for each $t \in T$. Here, $\sigma[(V, \mathcal{F})^T]$ denotes the product σ -algebra on V^T , which is by definition the smallest σ -algebra on V^T such that, for each $t \in T$, the projection map (or evaluation map)

$$\pi_t: V^T \longrightarrow V: x \longmapsto x(t)$$

is $(\sigma[(V, \mathcal{F})^T], \mathcal{F})$ -measurable.

• An immediate corollary of the above result is that: Suppose $(\Omega, \mathcal{A}, \mu)$ is a probability space structure on Ω , (V, \mathcal{F}) is a measurable space structure on V, and $\sigma[(V, \mathcal{F})^T]$ is the product σ -algebra on V^T . Then, $X: (\Omega, \mathcal{A}, \mu) \longrightarrow (V^T, \sigma[(V, \mathcal{F})^T])$ is V^T -valued random variable if and only if $\{X_t: (\Omega, \mathcal{A}, \mu) \longrightarrow (V, \mathcal{F})\}_{t \in T}$ is a stochastic process.

Definition B.1 (The product σ -algebra of a Cartesian product of measurable spaces)

Let T be an arbitrary non-empty set. For each $t \in T$, let (V_t, \mathcal{F}_t) be a measurable space (in particular, $V_t \neq \varnothing$). Let $\prod_{t \in T} V_t$ be the Cartesian product of $\{V_t\}_{t \in T}$. In other words,

$$\prod_{t \in T} V_t \ := \ \left\{ \ v : T \longrightarrow \bigsqcup_{t \in T} V_t \ \middle| \ v(t) \in V_t, \text{ for each } t \in T \ \right\}.$$

That $\prod_{t \in T} V_t \neq \emptyset$ follows from the Axiom of Choice. For each $t \in T$, let

$$\pi_t \,:\, \prod_{\tau \in T} V_\tau \,\longrightarrow\, V_t \,:\, v \,\longmapsto\, v(t)$$

be the projection map from $\prod_{\tau \in T} V_{\tau}$ onto V_t . The **product** σ -algebra on $\prod_{t \in T} V_t$ is the following:

$$\sigma \left(\left\{ \left. \pi_t^{-1}(F) \, \subset \, \prod_{\tau \in T} V_\tau \, \right| \, F \in \mathcal{F}_t \,, \, t \in T \, \right\} \right) \, \subset \, \operatorname{PowerSet} \left(\prod_{t \in T} V_t \, \right).$$

Clearly, it is the smallest σ -algebra on $\prod_{t \in T} V_t$ with respect to which each projection map $\pi_t : \prod_{t \in T} V_t \longrightarrow (V_t, \mathcal{F}_t)$ is measurable. We denote the product σ -algebra on $\prod_{t \in T} V_t$ by

$$\sigma \left(\prod_{t \in T} (V_t, \mathcal{F}_t) \right).$$

Theorem B.2

Suppose Ω , T, and V are non-empty sets. Let $\{X_t : \Omega \longrightarrow V\}_{t \in T}$ be a T-indexed family of V-valued maps defined on Ω . Then, the following statements are true:

1. The family $\{X_t : \Omega \longrightarrow V\}_{t \in T}$ of maps is set-theoretically equivalent (in the sense that either completely determines the other) to the following (V^T) -valued map defined on Ω :

$$X: \Omega \longrightarrow V^T: \omega \longmapsto (t \longmapsto X_t(\omega)),$$

where $V^T = \prod_{t \in T} V$ denotes the set of all (arbitrary) V-valued functions defined on T.

- 2. Suppose:
 - (Ω, A) and (V, \mathcal{F}) are measurable space structures on Ω and V, respectively.
 - $W \subset V^T$ is a subset of V^T such that $X(\Omega) = \bigcup_{t \in T} X_t(\Omega) \subset W$.
 - (W, \mathcal{G}) is a measurable space structure on W such that, for each $t \in T$, the projection map

$$\pi_t: W \longrightarrow V: w \longmapsto w(t)$$

is $(\mathcal{G}, \mathcal{F})$ -measurable.

Then, $(\mathcal{A}, \mathcal{G})$ -measurability of $X : \Omega \longrightarrow W$ implies $(\mathcal{A}, \mathcal{F})$ -measurability of $X_t : \Omega \longrightarrow V$ for each $t \in T$.

- 3. Suppose:
 - (Ω, A) and (V, \mathcal{F}) are measurable space structures on Ω and V, respectively.
 - $\sigma[(V,\mathcal{F})^T]$ is the product σ -algebra on $V^T = \prod_{t \in T} V$ generated by the collection of projection maps

$$\left\{ \pi_t : V^T = \prod_{\tau \in T} V \longrightarrow V : w \longmapsto w(t) \right\}_{t \in T}.$$

Then, $X: \Omega \longrightarrow V^T$ is $(\mathcal{A}, \sigma[(V, \mathcal{F})^T])$ -measurable if and only if $X_t: \Omega \longrightarrow V$ is $(\mathcal{A}, \mathcal{F})$ -measurable for each $t \in T$.

Proof

- 1. The proof of this result is routine and we omit it.
- 2. Suppose $X: \Omega \longrightarrow W$ is $(\mathcal{A}, \mathcal{G})$ -measurable. Note that $X_t = \pi_t \circ X$, where

$$\pi_t : V^T = \prod_{t \in T} V \longrightarrow V : v \longrightarrow v(t)$$

is the projection from $V^T = \prod_{\tau \in T} V$ onto the t-th factor. By hypothesis, $\pi_t : W \longrightarrow V$ is $(\mathcal{G}, \mathcal{F})$ -measurable for each $t \in T$. This implies, for each $t \in T$, $X_t = \pi_t \circ X$ is $(\mathcal{A}, \mathcal{F})$ -measurable, being a composition of two measurable maps.

3. Since, for each $t \in T$, the projection map $\pi_t : V^T \longrightarrow V$ is $\left(\sigma[(V, \mathcal{F})^T], \mathcal{F}\right)$ -measurable (by construction of the σ -algebra $\sigma[(V, \mathcal{F})^T]$ on V^T), the preceding result immediately implies the following implication:

$$(\mathcal{A},\sigma[(V,\mathcal{F})^T])\text{-measurability of }X:\Omega\longrightarrow V^T\quad\Longrightarrow\quad (\mathcal{A},\mathcal{F})\text{-measurability of }X_t:\Omega\longrightarrow V\text{, for each }t\in T.$$

Conversely, suppose X_t is $(\mathcal{A}, \mathcal{F})$ -measurable for each $t \in T$. Recall that the product σ -algebra on V^T is generated by sets of the form:

$$\pi_t^{-1}(F)$$
, for some $t \in T$ and $F \in \mathcal{F}$.

It follows that, for each $t \in T$ and each $F \in \mathcal{F}$, we have

$$X^{-1}\big(\pi_t^{-1}(F)\big) \; = \; (X^{-1}\circ\pi_t^{-1})(F) \; = \; (\pi_t\circ X)^{-1}(F) \; = \; X_t^{-1}(F) \; \subset \; \Omega$$

is \mathcal{A} -measurable, since $X_t:(\Omega,\mathcal{A})\longrightarrow (V,\mathcal{F})$ is $(\mathcal{A},\mathcal{F})$ -measurable by hypothesis. This proves that $X:\Omega\longrightarrow V^T$ is $(\mathcal{A},\sigma[(V,\mathcal{F})^T])$ -measurable.

Definition B.3 (Stochastic processes)

A stochastic process is a family, indexed by some non-empty set T,

$$\{X_t: (\Omega, \mathcal{A}, \mu) \longrightarrow (V, \mathcal{F})\}_{t \in T}$$

of (A, \mathcal{F}) -measurable maps, where the common domain (Ω, A, μ) is a probability space and the common codomain (V, \mathcal{F}) is a measurable space. The common codomain (V, \mathcal{F}) is called the **state space** of the stochastic process.

Corollary B.4

Suppose:

- $(\Omega, \mathcal{A}, \mu)$ is a probability space and (V, \mathcal{F}) is a measurable space.
- T is a non-empty set and $W \subset V^T = \prod_{t \in T} V$.
- (W,\mathcal{G}) is a measurable space structure on W such that, for each $t \in T$, the projection map

$$\pi_t: W \longrightarrow V: w \longmapsto w(t)$$

is $(\mathcal{G}, \mathcal{F})$ -measurable.

If $X: (\Omega, \mathcal{A}, \mu) \longrightarrow (V^T, \sigma[(V, \mathcal{F})^T])$ is a V^T -valued random variable (i.e. X is $(\mathcal{A}, \sigma[(V, \mathcal{F})^T])$ -measurable), then its set-theoretically equivalent T-indexed family of V-valued maps defined on Ω

$$\left\{ \begin{array}{ccc} X_t & : & (\Omega, \mathcal{A}, \mu) & \longrightarrow & (V, \mathcal{F}) \\ & \omega & \longmapsto & (\pi_t \circ X)(\omega) = \pi_t(X(\omega)) = X(\omega)(t) \end{array} \right\}_{t \in T}$$

is a stochastic process (i.e. X_t is (A, \mathcal{F}) -measurable for each $t \in T$).

Corollary B.5

Suppose:

- T, Ω , V are non-empty sets.
- $(\Omega, \mathcal{A}, \mu)$ is a probability space structure on Ω , (V, \mathcal{F}) is a measurable space structure on V.
- $\sigma[(V, \mathcal{F})^T]$ denotes the corresponding product σ -algebra on $V^T = \prod_{t \in T} V$.

Let $\{X_t : \Omega \longrightarrow V\}_{t \in T}$ be a T-indexed family of V-valued maps defined on Ω , and let

$$X: \Omega \longrightarrow V^T: \omega \longmapsto (t \longmapsto X_t(\omega))$$

be its set-theoretically equivalent (V^T) -valued map defined on Ω . Then,

$$\{X_t: (\Omega, \mathcal{A}, \mu) \longrightarrow (V, \mathcal{F})\}_{t \in T}$$

is a stochastic process if and only if

$$X: (\Omega, \mathcal{A}, \mu) \longrightarrow (V^T, \sigma[(V, \mathcal{F})^T])$$

is a (V^T) -valued random variable.

C Uniqueness of the "full distribution" of a stochastic process $\{X_t : \Omega \longrightarrow V\}_{t \in T}$ given its finite-dimensional distributions

Definition C.1 (Finite-dimensional distributions of a stochastic process)

Let $\{X_t : (\Omega, \mathcal{A}, \mu) \longrightarrow (V, \mathcal{F})\}_{t \in T}$ be a stochastic process. Let $n \in \mathbb{N}$ and $t_1, t_2, \dots, t_n \in T$ be distinct elements of T. Let $\mathcal{P}_{(X_{t_1}, \dots, X_{t_n})} \in \mathcal{M}_1(V^n, \mathcal{F}^{\otimes n})$ denote the probability measure induced on the product measurable space $(V^n, \mathcal{F}^{\otimes n})$ by the random variable

$$(X_{t_1}, X_{t_2}, \dots, X_{t_n}) : (\Omega, \mathcal{A}, \mu) \longrightarrow (V^n, \mathcal{F}^{\otimes n})$$

 $\mathcal{P}_{\left(X_{t_1},\ldots,X_{t_n}
ight)}$ is called a **finite-dimensional distribution** of the stochastic process.

Theorem C.2

Let (V, \mathcal{F}) be a measurable space, and $\sigma[(V, \mathcal{F})^T]$ the product σ -algebra on $V^T = \prod_{t \in T} V$. Let

$$\{X_t: (\Omega_X, \mathcal{A}_X, \mu_X) \longrightarrow (V, \mathcal{F})\}_{t \in T} \text{ and } \{Y_t: (\Omega_Y, \mathcal{A}_Y, \mu_Y) \longrightarrow (V, \mathcal{F})\}_{t \in T}$$

be two stochastic processes with the same index set T and the same state space (V, \mathcal{F}) . Let

$$X: (\Omega_X, \mathcal{A}_X, \mu_X) \longrightarrow \left(V^T, \sigma\Big[(V, \mathcal{F})^T\Big]\right) \quad \text{and} \quad Y: (\Omega_Y, \mathcal{A}_Y, \mu_Y) \longrightarrow \left(V^T, \sigma\Big[(V, \mathcal{F})^T\Big]\right)$$

be their respective $(V^T, \sigma[(V, \mathcal{F})^T])$ -valued random variables. Let \mathcal{P}_X , $\mathcal{P}_Y \in \mathcal{M}_1(V^T, \sigma[(V, \mathcal{F})^T])$ be the probability measures induced on $(V^T, \sigma[(V, \mathcal{F})^T])$ by X and Y, respectively. Then,

$$\mathcal{P}_X = \mathcal{P}_Y \in \mathcal{M}_1\left(V^T, \sigma\left[\left(V, \mathcal{F}\right)^T\right]\right)$$

if and only if

$$\mathcal{P}_{\left(X_{t_1},X_{t_2},\dots,X_{t_n}\right)} = \mathcal{P}_{\left(Y_{t_1},Y_{t_2},\dots,Y_{t_n}\right)} \in \mathcal{M}_1\left(V^n,\mathcal{F}^{\otimes n}\right), \text{ for each } n \in \mathbb{N} \text{ and pairwise distinct } t_1,t_2,\dots,t_n \in T.$$

PROOF

D Existence of a stochastic process given its finite-dimensional distributions: Komolgorov's Existence Theorem

Definition D.1 (Stochastic processes)

Suppose $(\Omega, \mathcal{A}, \mu)$ is a probability space, (V, \mathcal{F}) is a measurable space, and T is an arbitrary non-empty set. A **stochastic process** indexed by T defined on Ω with codomain V is a family $\{X_t : \Omega \longrightarrow V\}_{t \in T}$ indexed by T of V-valued random variables defined on Ω .

Definition D.2 (Finite-dimensional distributions of a stochastic processes)

Let $\{X_t : \Omega \longrightarrow (V, \mathcal{F})\}_{t \in T}$ be a stochastic process. Let $n \in \mathbb{N}$ and $t_1, t_2, \ldots, t_n \in T$ be distinct elements of T. The probability distribution induced on the product measurable space $(V^n, \mathcal{F}^{\otimes n})$ by $(X_{t_1}, X_{t_2}, \ldots, X_{t_n}) : \Omega \longrightarrow V^n$ is called a **finite-dimensional distribution** of the stochastic process.

Definition D.3 (Komolgorov systems of finite-dimensional distributions & Komolgorov consistency)

Let T be an arbitrary non-empty set, and $\mathcal{D}(T)$ the set of all finite ordered sequences of elements of T whose elements are pairwise distinct; in other words,

$$\mathcal{D}(T) := \left\{ (t_1, t_2, \dots, t_n) \in \bigcup_{k=1}^{\infty} T^k \mid n \in \mathbb{N}, \ t_i \neq t_j, \text{ whenever } i \neq j \right\}.$$

For each $n \in \mathbb{N}$, let $\mathcal{M}_1(R^n, \mathcal{B}(\mathbb{R}^n))$ be the set of all probability measures defined on the product measurable space $(\mathbb{R}^n, \mathcal{B}(\mathbb{R}^n))$. A **Komolgorov system of finite-dimensional distributions** is a $\mathcal{D}(T)$ -indexed family \mathcal{P} of probability measures of the following form:

$$\mathcal{P} = \left\{ P_{(t_1,\dots,t_n)} \in \mathcal{M}_1(\mathbb{R}^n,\mathcal{B}(\mathbb{R}^n)) \mid (t_1,\dots,t_n) \in \mathcal{D}(T) \right\}.$$

Furthermore, \mathcal{P} is said to be **Komolgorov consistent** if it satisfies both of the following conditions:

• permutation invariance: For any $n \in \mathbb{N}$, any $(t_1, \ldots, t_n) \in \mathcal{D}(T)$, any $B_1, \ldots, B_n \in \mathcal{B}(\mathbb{R})$, and any permutation $\pi : \{1, \ldots, n\} \longrightarrow \{1, \ldots, n\}$, the following equality holds:

$$P_{(t_1,\ldots,t_n)}(B_1\times\cdots\times B_n) = P_{(t_{\pi(1)},\ldots,t_{\pi(n)})}(B_{\pi(1)}\times\cdots\times B_{\pi(n)}).$$

• projection invariance: For any $n \in \mathbb{N}$, any $(t_1, \ldots, t_{n+1}) \in \mathcal{D}(T)$, and any $B_1, \ldots, B_n \in \mathcal{B}(\mathbb{R})$, the following equality holds:

$$P_{(t_1,\ldots,t_n,t_{n+1})}(B_1\times\cdots\times B_n\times\mathbb{R}) = P_{(t_1,\ldots,t_n)}(B_1\times\cdots\times B_n).$$

Remark D.4

It is obvious that the collection of finite-dimensional distributions of any \mathbb{R} -valued stochastic process is a Komolgorov consistent Komolgorov system of finite-dimensional distributions.

Definition D.5

Let $\{X_t : \Omega \longrightarrow \mathbb{R}\}_{t \in T}$ be an \mathbb{R} -valued stochastic process, and

$$\mathcal{P} = \left\{ P_{(t_1, \dots, t_n)} \in \mathcal{M}_1(\mathbb{R}^n, \mathcal{B}(\mathbb{R}^n)) \mid (t_1, \dots, t_n) \in \mathcal{D}(T) \right\}$$

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be a Komolgorov system of finite-dimensional distributions. We say that the stochastic process $\{X_t\}$ admits \mathcal{P} as its collection of finite-dimensional distributions if, for each $n \in \mathbb{N}$ and any $(t_1, t_2, \ldots, t_n) \in \mathcal{D}(T)$, the probability distribution induced on $(\mathbb{R}^n, \mathcal{B}(\mathbb{R}^n))$ by the map

$$(X_{t_1},\ldots,X_{t_n}):\Omega\longrightarrow\mathbb{R}^n$$

equals $P_{(t_1,\ldots,t_n)} \in \mathcal{P}$.

Theorem D.6 (Komolgorov's Existence Theorem, Theorem 36.2, [2]) Let

$$\mathcal{P} = \left\{ P_{(t_1, \dots, t_n)} \in \mathcal{M}_1(\mathbb{R}^n, \mathcal{B}(\mathbb{R}^n)) \mid (t_1, \dots, t_n) \in \mathcal{D}(T) \right\}.$$

be a Komolgorov system of finite-dimensional distributions. Then, there exists a stochastic process

$$\{X_t: (\Omega, \mathcal{A}, \mu) \longrightarrow (\mathbb{R}, \mathcal{B}(\mathbb{R}))\}_{t \in T}$$

which admits \mathcal{P} as its collection of finite-dimensional distributions if and only if \mathcal{P} is Komolgorov consistent.

E Gaussian Processes

Definition E.1 (Gaussian processes)

An \mathbb{R} -valued stochastic process $\{X_t : \Omega \longrightarrow \mathbb{R}\}_{t \in T}$ is said to be **Gaussian** if each of its finite-dimensional distribution is a (univariate or multivariate) Gaussian distribution.

Definition E.2 (Mean and covariance functions of R-valued stochastic processes)

Let $\{X_t : \Omega \longrightarrow \mathbb{R}\}_{t \in T}$ be an \mathbb{R} -valued stochastic process.

• If, for each $t \in T$, we have $E(X_t) \in \mathbb{R}$, then the function

$$a_X: T \longrightarrow \mathbb{R}: t \longmapsto E(X_t)$$

is called the **mean** function of the \mathbb{R} -valued stochastic process $\{X_t\}$.

• In addition, if, for each $t_1, t_2 \in T$, we have $0 \leq \text{Cov}(X_{t_1}, X_{t_2}) < \infty$, then the function

$$\Sigma_X : T \times T \longrightarrow \mathbb{R} : (t_1, t_2) \longmapsto \operatorname{Cov}(X_{t_1}, X_{t_2})$$

is called the **covariance** function of the \mathbb{R} -valued stochastic process $\{X_t\}$.

Theorem E.3

Let T be an arbitrary non-empty set, $a: T \longrightarrow \mathbb{R}$ an arbitrary \mathbb{R} -valued function defined on T, and $\Sigma: T \times T \longrightarrow [0, \infty)$ a non-negative \mathbb{R} -valued function defined on $T \times T$. Then, there exists a Gaussian process whose mean and covariance functions are a and Σ , respectively.

Theorem E.4

The mean and covariance functions of a Gaussian process together completely determine its collection of finite-dimensional distributions.

Definition E.5 (Brownian motion, a.k.a. Wiener process)

A Brownian motion, or Wiener process, is a stochastic process $\{W_t : (\Omega, \mathcal{A}, \mu) \longrightarrow \mathbb{R}\}_{t \geq 0}$ indexed by the non-negative real line satisfying the following conditions:

• At t = 0, the process takes value 0 with probability 1; more precisely:

$$P(W_0 = 0) = \mu(\{ \omega \in \Omega \mid W_0(\omega) = 0 \}) = 1.$$

• The process $\{W_t\}$ has independent increments; more precisely: for any $0 \le t_1 \le t_2 \le \cdots \le t_n < \infty$,

$$W_{t_n} - W_{t_{n-1}}, \quad W_{t_{n-1}} - W_{t_{n-2}}, \quad \dots , \quad W_{t_2} - W_{t_1} : \Omega \longrightarrow \mathbb{R}$$

are independent random variables.

• For $0 \le t_1 < t_2 < \infty$, the increment $W_{t_2} - W_{t_1}$ follows a Gaussian distribution with mean 0 and variance $t_2 - t_1$.

Definition E.6 (Brownian bridge)

A Brownian bridge is a Gaussian process $\{W_t^{\circ}: (\Omega, \mathcal{A}, \mu) \longrightarrow \mathbb{R}\}_{t \in [0,1]}$ indexed by the closed unit interval in \mathbb{R} satisfying the following conditions:

- For each $t \in [0,1]$, we have $E(W_t^{\circ}) = 0$.
- For any $t_1, t_2 \in [0, 1]$, we have $Cov(W_{t_1}^0, W_{t_2}^\circ) = min\{t_1, t_2\} t_1t_2$.

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