

Assignment 5

Q1 a)

b)

2 (i) Part 1 discussed in class

$$\text{minimize } J(A_r) = \|A - A_r\|_F^2$$

given $A_{m \times n}$ $S(A) > r$
 A_r is a rank r matrix
 $r < \min(m, n)$

Find SVD of A

$$A = U \Sigma V^T$$

 $A_{m \times n}$ $V_{n \times n}$, $U_{m \times m}$: Orthogonal Matrix Σ : $m \times n$ diagonal entries whose entries are non-negative (Singular Values)Columns of U & V are called left singular and right singular ^{vectors} of M .Consider the r largest singular values & corresponding singular vectors

$$A_r = U_r S_r V_r^T \quad \text{sol}^n \quad \square$$

A rank- k approximation to the covariance matrix is used in PCA

Proof: (for completeness, adapted from wikipedia)

 ~~Σ $m \times n$ diagonal matrix with entries $(\sigma_1, \sigma_2, \dots, \sigma_m)$ such that~~

~~$$\sigma_1 \geq \sigma_2 \geq \sigma_3 \geq \dots \geq \sigma_m \geq 0$$~~

Claim: Best k rank approximation given by.

~~$$A_k = \sum_{i=1}^k \sigma_i u_i v_i^T$$~~

If \vec{v}_{oxi} is ^{$i=1$} vectorised image and d is large, then dimensionality reduction is performed to reduce number of dimensions to k ($\ll d$) with minimal loss in image properties. For this best k rank approx. is required. With this matrix operations can be carried out in computationally efficient manner.

$$(2) \min_{R \text{ s.t. } R^T R = I} J(R) = \|RB - A\|_F^2$$

$$A_{n \times m} \quad B_{n \times m} \quad R_{n \times n}$$

Rigid Transform Estimation (Orthogonal Procrustes Problem)

~~$E(R)$~~

$$\text{Sol}^n \quad AB^T = USV^T \quad (\text{SVD})$$

$$R^T = UV^T$$

Application:

Learning the Bases: Method 3- Union of Ortho-Normal Bases (Dictionary Learning)

Algo

for $m = 1:M$

{

$$X_m = X - \sum_{j \neq m} A_j S_j;$$

$$S_m X_m^T = U \Lambda V^T;$$

$$A_m = V U^T$$

}

→ Orthogonal Procrustes

$$\text{Updating } S_m: S_m = \arg \min_{S^*} \|X_m - A_m S^*\|^2 + \lambda \|S^*\|_1$$

because we are solving

$$\min_A \|X_m - A S_m\|^2 \quad \text{s.t. } A A^T = I$$

$$S = \begin{pmatrix} S_1 \\ S_2 \\ \vdots \\ S_m \end{pmatrix}$$

Coefficient Matrix

\vec{S}_m

A: dictionary.

$$(X_m)_{p \times k}$$