Dirichlet Energy in Different Spaces

December 3, 2022

1 Relevant Definitions

Definition 1 (Gradient Flow). Given an energy (functional) $\mathcal{E}(f)$, gradient flow is:

$$\frac{d}{dt}f = -\operatorname{grad}\mathcal{E}(f) \tag{1}$$

Definition 2 (Differential). Differential $d\mathcal{E}$ describes change in \mathcal{E} due to u:

$$d\mathcal{E}|_{f}(u) = \lim_{\epsilon \to 0} \frac{1}{\epsilon} \left(\mathcal{E}(f + \epsilon u) - \mathcal{E}(f) \right) \tag{2}$$

Definition 3 (Gradient). Gradient of \mathcal{E} is the unique function grad \mathcal{E} such that,

$$\langle \langle \operatorname{grad} \mathcal{E}, u \rangle \rangle_V = d\mathcal{E}(u)$$
 (3)

2 Dirichlet Energy Example

Definition 4 (Dirichlet Energy). Dirichlet Energy is defined as:

$$\mathcal{E}_D(f) := \frac{1}{2} \int_{\Omega} |\operatorname{grad} f(x)|^2 dx = \frac{1}{2} \langle \langle \nabla f, \nabla f \rangle \rangle_{L^2} = -\frac{1}{2} \langle \langle \Delta f, f \rangle \rangle_{L^2}$$
 (4)

Computing the differential $d\mathcal{E}_D|_f(u)$ of Dirichlet energy using (2),

$$d\mathcal{E}_D|_f(u) = -\frac{1}{2} \lim_{\epsilon \to 0} \frac{1}{\epsilon} \left(\langle \langle \Delta(f + \epsilon u), f + \epsilon u \rangle \rangle_{L^2} - \langle \langle \Delta f, f \rangle \rangle_{L^2} \right)$$
 (5)

$$= -\frac{1}{2} \lim_{\epsilon \to 0} \frac{1}{\epsilon} \left(\epsilon \langle \langle \Delta f, u \rangle \rangle_{L^2} + \epsilon \langle \langle \Delta u, f \rangle \rangle_{L^2} + \epsilon^2 \langle \langle u, u \rangle \rangle_{L^2} \right)$$
 (6)

$$= -\frac{1}{2} (\langle \langle \Delta f, u \rangle \rangle_{L^2} + \langle \langle \Delta u, f \rangle \rangle_{L^2}) \tag{7}$$

$$= -\frac{1}{2} (\langle \langle \Delta f, u \rangle \rangle_{L^2} + \langle \langle \Delta f, u \rangle \rangle_{L^2})$$
 (8)

$$= -\langle\langle \Delta f, u \rangle\rangle_{L^2} \tag{9}$$

where the last step is by integration by parts $(twice)^2$.

 $^{^{1}{\}rm analogous}$ in traditional vector space would be "in the direction of" u

 $^{^2{}m This}$ trick will be used all over the place when constructing gradients. See 4.1 in the Appendix

2.1 Gradient Flow in L^2

By (3), we may spot from (9) that the gradient can be written as

$$\operatorname{grad} \mathcal{E}_{L^2} = -\Delta f \tag{10}$$

Hence, the gradient flow equation (1) can be written as:

$$\frac{d}{dt}f = \Delta f \tag{11}$$

which is the heat equation.

2.2 Gradient Flow in H^1

We may express the differential (9) as

$$d\mathcal{E}_D|_f(u) = -\langle\langle\Delta f, u\rangle\rangle_{L^2} \tag{12}$$

$$= \langle \langle \nabla f, \nabla u \rangle \rangle_{L^2} \tag{13}$$

$$= \langle \langle f, u \rangle \rangle_{H^1} \tag{14}$$

So by (3), the gradient in H^1 can be written as

$$\operatorname{grad} \mathcal{E}_{H^1} = f \tag{15}$$

The gradient flow equation (1) can be written as

$$\frac{d}{dt}f = -f \tag{16}$$

which describes exponential decay.

2.3 Gradient Flow in H^{-1}

We may express the differential (9) as

$$d\mathcal{E}_D|_f(u) = -\langle\langle \Delta f, u \rangle\rangle_{L^2} \tag{17}$$

$$= \langle \langle \nabla f, \nabla u \rangle \rangle_{L^2} \tag{18}$$

$$= \langle \langle \nabla^3 f, \nabla^{-1} u \rangle \rangle_{L_2} \tag{19}$$

$$= \langle \langle \Delta f, \Delta^{-1} u \rangle \rangle_{H^1} \tag{20}$$

$$= \langle \langle \Delta^2 f, u \rangle \rangle_{H^{-1}} \tag{21}$$

So by (3), the gradient in H^{-1} can be written as

$$\operatorname{grad} \mathcal{E}_{H^{-1}} = \Delta^2 f \tag{22}$$

The gradient flow equation (1) can be written as

$$\frac{d}{dt}f = -\Delta^2 f \tag{23}$$

2.4 Gradient Flow in H^2

We may express the differential (9) as

$$d\mathcal{E}_D|_f(u) = -\langle\langle \Delta f, u \rangle\rangle_{L^2} \tag{24}$$

$$= -\langle \langle f, \Delta u \rangle \rangle_{L^2} \tag{25}$$

$$= -\langle \langle \Delta^{-1} f, u \rangle \rangle_{H^2} \tag{26}$$

So by (3), the gradient in H^2 can be written as

$$\operatorname{grad} \mathcal{E}_{H^2} = -\Delta^{-1} f \tag{27}$$

The gradient flow equation (1) can be written as

$$\frac{d}{dt}f = \Delta^{-1}f\tag{28}$$

3 Numerically Solving Gradient Flow Equations

3.1 Gradient Flow in L^2 , H^1

For L^2 , given the gradient flow equation (11), we may write down explicit Euler scheme:

$$\frac{f_j^{m+1} - f_j^m}{\Delta t} = \frac{f_{j+1}^m - 2f_j^m + f_{j-1}^m}{(\Delta x)^2}$$
 (29)

which can be rewritten as

$$f_j^{m+1} = f_j^m + \mu \left(f_{j+1}^m - 2f_j^m + f_{j-1}^m \right)$$
 (30)

where $\mu := \frac{\Delta t}{(\Delta x)^2}$ is called the *CFL number*.

Similar construction can be done for H^1 .

This method is known to have consistency error

$$T_j^m = \mathcal{O}\left(\left(\Delta x\right)^2 + \Delta t\right) \tag{31}$$

3.2 Gradient Flow in H^1

Given the gradient flow equation (16), we may write down explicit Euler scheme:

$$\frac{f_j^{m+1} - f_j^m}{\Delta t} = -f_j^m \tag{32}$$

which can be rewritten as

$$f_j^{m+1} = f_j^m - (\Delta t) f_j^m$$
 (33)

3.3 Gradient Flow in H^{-1}

Given the gradient flow equation (23), it can be rewritten as

$$\frac{d}{dt}\Delta f = f \tag{34}$$

we may write down explicit Euler scheme:

$$\frac{1}{\Delta t} \left(\frac{f_{j+1}^{m+1} - 2f_j^{m+1} + f_{j-1}^{m+1}}{(\Delta x)^2} - \frac{f_{j+1}^m - 2f_j^m + f_{j-1}^m}{(\Delta x)^2} \right) = f_j^m$$
 (35)

which can be rewritten as

$$\begin{pmatrix} 1 & -2 & 1 \end{pmatrix} \begin{pmatrix} f_{j-1}^{m+1} \\ f_{j+1}^{m+1} \end{pmatrix} = \begin{pmatrix} 1 & -2 + \Delta t (\Delta x)^2 & 1 \end{pmatrix} \begin{pmatrix} f_{j-1}^m \\ f_{j}^m \\ f_{j+1}^m \end{pmatrix}$$
(36)

This method has consistency error

$$T_j^m = \mathcal{O}\left(\left(\Delta x\right)^2 + \left(\Delta t\right)^2\right) \tag{37}$$

4 Appendix

4.1 A (Somewhat) Careful Justification for IBP

Suppose we are concerned with the integral $I := \langle \langle \Delta u, f \rangle \rangle_{L^2} = \int_R (\Delta u) f \, d\mathbf{x}$, where R is a bounded region with boundary ∂R .

4.1.1 IBP (on Gradient Operator)

One could show that

$$\langle \langle \Delta u, f \rangle \rangle_{L^2} = -\langle \langle \nabla u, \nabla f \rangle \rangle_{L^2} = -\int_R \nabla u \cdot \nabla f \, d\mathbf{x}$$
 (38)

using the identity 3 :

$$\nabla \cdot (\phi \nabla \psi) = \phi \nabla^2 \psi + \nabla \phi \cdot \nabla \psi \tag{39}$$

Note that

$$\langle\langle \Delta u, f \rangle\rangle_{L^2} = -\int_R \nabla u \cdot \nabla f \, d\mathbf{x}$$
 (40)

$$= \int_{R} \nabla \cdot (f \nabla u) \, d\mathbf{x} - \int_{R} \nabla u \cdot \nabla f \, d\mathbf{x}$$
 (41)

$$= \oint_{\partial R} f \frac{du}{dn} \, \mathrm{d}s - \int_{R} \nabla u \cdot \nabla f \, \mathrm{d}\mathbf{x} \tag{42}$$

(Need the first term of last line to be zero...)

³This is also known as Green's Identity in some literature