## Simple Energy

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When tangent-point energy was used evolve the curve, it turned out that in a discrete setting, it is minimized when the points are colinear.

Instead, it might be worth investigating the simplest of curve energies.

## 1 Simple Energy

For a closed curve  $C = \gamma(t)$  over  $t \in M$ , define **simple energy** as:

$$\mathcal{E}^{\alpha}(\gamma) := \iint_{M^2} \frac{1}{|\gamma(x) - \gamma(y)|^{\alpha}} \, \mathrm{d}\gamma_x \, \mathrm{d}\gamma_y \tag{1}$$

where  $\alpha > 0$ .

For  $\alpha \geq 1$ , this energy is ill-defined in an analytic framework. However, in a discrete scheme inspired by this, there is a natural way to make this well-defined.

## 2 Discrete Simple Energy

**Definition 1.** Given a closed, non-intersection polygonal curve  $\Gamma := (x_0, x_1, \dots, x_{J-1})$   $(x_0 = x_J)$  define **discrete simple energy of first kind** as:

$$E_1^{\alpha}(\Gamma) = \sum_{i=0}^{J-1} \sum_{j \neq i} \frac{1}{|x_i - x_j|^{\alpha}} |x_i - x_{i+1}| |x_j - x_{j+1}|$$
 (2)

where  $\alpha > 0$ .

This is the simplest energy to compute, but it may not be symmetric.

To address the issue of non-symmetricness, a simple modification can be

**Definition 2.** Given a closed, non-intersection polygonal curve  $\Gamma := (x_0, x_1, \dots, x_{J-1})$  ( $x_0 = x_J$ ) define **discrete simple energy of second kind** as:

$$E_2^{\alpha}(\Gamma) = \sum_{i=0}^{J-1} \sum_{|i-j|>1} k_{i,j}^{\alpha} |x_i - x_{i+1}| |x_j - x_{j+1}|$$
(3)

where

$$k_{i,j}^{\alpha} = \frac{1}{4} \left( \frac{1}{|x_i - x_j|^{\alpha}} + \frac{1}{|x_i - x_{j+1}|^{\alpha}} + \frac{1}{|x_{i+1} - x_j|^{\alpha}} + \frac{1}{|x_{i+1} - x_{j+1}|^{\alpha}} \right)$$
(4)

and  $\alpha > 0$ . Note that the indexing must be done cyclically, so |i - j| > 1 is modulo J.