

# Paul Sammut

ROBOTICS ENGINEER

706 Washington St. Hoboken, NJ, 07030

☎ 646-421-5751 | ✉ paul.c.sammut@gmail.com | 🏠 www.paulsammut.com | 📷 paulsammut | 🌐 paul-sammut

## Summary

Paul is a robotics engineer that has worked on underwater rockets, has started a consumer product hardware company and a robotics consulting company making marine research robots. He was born with a passion for anything with wires, software, and moving parts. He has over a decade of experience building many combinations of those three things. These projects have taken him on a never-ending learning journey spanning designing ROS autonomous systems, real-time control, embedded electronics, mechatronics, and software/hardware project management.

## Education

### Stevens Institute of Technology

BACHELOR OF ENGINEERING IN MECHANICAL ENGINEERING (AEROSPACE CONCENTRATION)

Hoboken, NJ

May. 2009

### Stevens Institute of Technology

MASTER OF ENGINEERING IN MECHANICAL ENGINEERING (ROBOTICS CONCENTRATION)

Hoboken, NJ

May. 2014

## Work Experience

### Stocker Freight

FOUNDER

New York, NY

2017 - 2018

- Raised FF seed round and founded Stocker, dedicated to creating an autonomous freight service for cities.
- Worked with product co-founder to create company strategy and build supporting technology prototype.

### Robotics Constuling | Rockefeller University

ROBOTICS ENGINEER

New York, NY

2016 - 2017

- Acquired, managed and executed a robotics project to create a 16' autonomous catamaran to aide in dolphin vocalization research. Project culminated with successful field test in Belize.

### Ramos Alarm Clock | Sammut Tech LLC

FOUNDER

Hoboken, NJ

2012 - 2016

- Invented a novel alarm clock that forced users up by use of a remote keypad. Clock inducted in the US National Clock Museum's collection.
- Created a successful Kickstarter and pre-order campaign raising \$200K in pre-orders.
- Setup a factory in New Jersey, managed 2 engineers and labor hires to manufacture product.
- Managed capital acquisitions, supply chain, manufacturing plans, inventory forecast schedules, and product strategy.

### Davidson Lab | Stevens Institute of Technology

SENIOR RESEARCH ENGINEER

Hoboken, NJ

2009 - Present

- Managed new technology projects from the specification phase to testing and validation.
- Conducted fundamental physics research on High Speed Supercavitating Vehicles (underwater rockets).
- Created instrumentation and control apparatus utilizing various sensors, pneumatic systems, still and video photography systems interfaced to separate RTOS and standard computers on a custom distributed network.
- Operated, maintained, and upgraded a fleet of UUVs operating in the Hudson River.
- Created HIL testing apparatus utilizing mathematical models to validate system performance.
- Designed electronic wiring systems for power, analog and digital comms and connector solutions.
- Wrote and supported mission critical launch control software for rocket systems.
- Designed and managed the creation of a control surface subsystem with humming bird level dynamic response.

### Institute Machine Shop | Stevens Institute of Technology

MACHINE SHOP APPRENTICE

Hoboken, NJ

2007 - 2009

- Machined parts based on provided drawings and learned fundamental concepts of Design For Manufacture

## Publications

2012 **Planing-Hull Forces and Moments on a Cylindrical Body in a Cavity**, 8th Int. Symp. on Cavitation 2012  
2010 **Remote Control and Monitoring of MOOS Vehicles through Cellular Modems**, MOOS-DAWG at MIT  
2010 **Guidance of a UUV Using a Passive Acoustic Threat Detection System**, IEEE, WSS

*Singapore*  
*Cambridge, MA*  
*Carrara, Italy*

## Skills

---

<b>Software</b>	C, C++, Python, ROS, OpenCV, RealTime Programming, Linux, VCS (Git, SVN), Mixed Signal DAQ Programming, LabVIEW, LabVIEW RT, LabVIEW FPGA, cRIO, Vim 4 Life
<b>Hardware</b>	PCB Layout (Altium, Eagle), MPLAB IDE, Logic Analyzers, Digital-comms (CAN, Serial, I <sup>2</sup> C, SPI), RF SoCs, uProcs, Power Circuits, Sensors (LiDARs, FTs, GNSS, IMUs, AHRS, 2D Cameras, Stereo Cameras, RGBD Cameras)
<b>Mechanical</b>	Solidworks (16 years exp.), Complex Tolerance Stacks, Underwater Systems, Precision Actuation Design (Ballscrews, Linear Rails), Materials and Coatings Selection
<b>Personal</b>	US Security Clearance, USA and Maltese Citizen, Avid Rockclimber