

PHYSICAL COMPUTING 4: ANDROID + ARDUINO BLE

CSE 590 Ubiquitous Computing | Lecture 6 | May 3

Jon Froehlich • **Liang He** (TA)

SCHEDULE TODAY: 6:30-9:20

06:30-06:55: Discussion of required reading led by Joe Wandyez

06:55-07:00: Optional discussion led by Abhay Rijhwani ([link](#))

07:00-08:10: Physical Computing 3: Sensors

08:10-08:15: Break

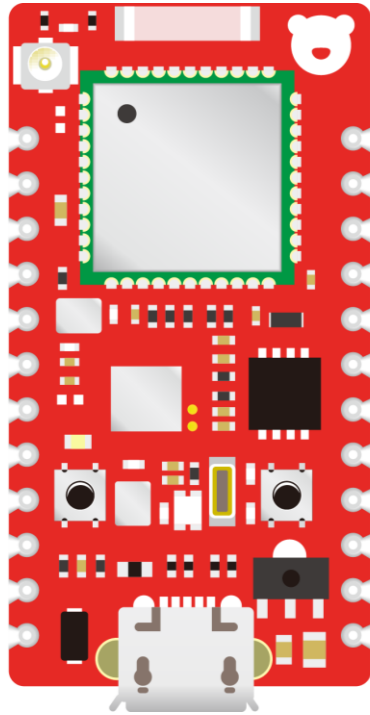
08:15-09:20: Physical Computing 4: Android + Arduino via BLE

ARDUINO + ANDROID BLE: LEARNING GOALS

How to setup **basic unidirectional communication** between
Android -> Arduino using BLE

How to setup basic **bidirectional communication** using BLE

ARDUINO + ANDROID BLE: OVERVIEW



RedBear Duo (Peripheral)

1 BLE initialization
Configuration
Set advertising data (name)

2 Register callbacks (receive
& send) and services (UUIDs)
Start advertising

3 Receive data from Android and
process the data

4 Send data to Android

1 Scan all BLE-enabled devices

2 Find target device by **UUID** and
NAME and establish the connection

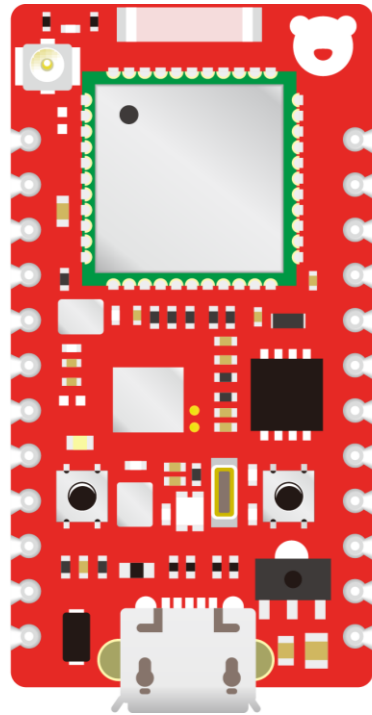
3 Send data to Duo

4 Receive data from Duo
and process the data



Android App (Central)

ARDUINO + ANDROID BLE: OVERVIEW (CODE LEVEL)



RedBear Duo (Peripheral)

```
ble.init();  
configureBLE();  
ble.setAdvertisementData()
```

1 BLE initialization
Configuration
Set advertising data (name)

2 Register callbacks (receive
& send) and services (UUIDs)
Start advertising

3 Receive data from Android and
process the data

4 Send data to Android

```
send_notify()
```

```
scanLeDevice()
```

1 Scan all BLE-enabled devices

```
BluetoothAdapter.LeScanCallback()
```

2 Find target device by **UUID** and
NAME and establish the connection

```
ble.onDataWriteCallback()  
ble.addService  
ble.startAdvertising
```

3 Send data to Duo

```
mBluetoothLeService.writeCharacteristic()
```

```
bleWriteCallback()
```

4 Receive data from Duo
and process the data

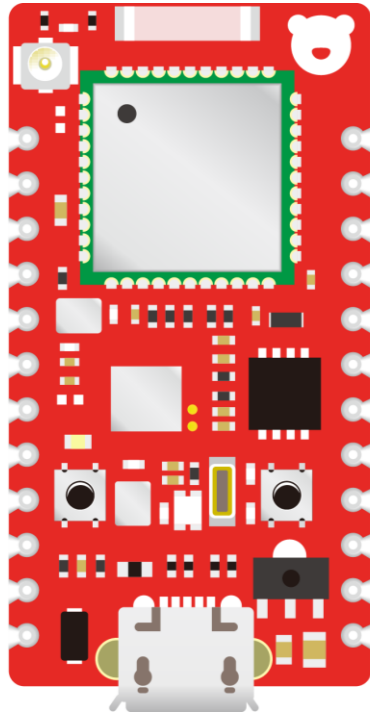
```
intent.getByteArrayExtra()
```

Customized functions (e.g., readAnalogInValue())



Android App (Central)

ARDUINO + ANDROID BLE: OVERVIEW (CODE LEVEL)



RedBear Duo (Peripheral)

UUID (universally Unique identifier)
Device Name
The Length of the Name
Message (3 bytes)

TX UUID & callback (bleWriteCallback)

RX UUID & callback (send_notify)



Android App (Central)

SKELETON CODE

AndroidBLEBasic (one-way) and RedBearDuoBLEAdvanced (two-way)

Open the notes doc: <https://goo.gl/3A9Q9M>

DUO SKETCH

```
#define BLE_SHORT_NAME_LEN 0x08 // must be in the range of [0x01, 0x09]
#define BLE_SHORT_NAME 'B','L','E','D','e','m','o' // define each char but the number of char should be BLE_SHORT_NAME_LEN-1
/* Define the pins on the Duo board
 * TODO: change the pins here for your applications
 */
#define PWM_PIN                D0
#define ANALOG_IN_PIN          A0

// UUID is used to find the device by other BLE-abled devices
static uint8_t service1_uuid[16] = { 0x71,0x3d,0x00,0x00,0x50,0x3e,0x4c,0x75,0xba,0x94,0x31,0x48,0xf1,0x8d,0x94,0x1e };
static uint8_t service1_tx_uuid[16] = { 0x71,0x3d,0x00,0x03,0x50,0x3e,0x4c,0x75,0xba,0x94,0x31,0x48,0xf1,0x8d,0x94,0x1e };
static uint8_t service1_rx_uuid[16] = { 0x71,0x3d,0x00,0x02,0x50,0x3e,0x4c,0x75,0xba,0x94,0x31,0x48,0xf1,0x8d,0x94,0x1e };

int bleWriteCallback(uint16_t value_handle, uint8_t *buffer, uint16_t size)
static void send_notify(btstack_timer_source_t *ts)
```

Android App → Duo

Duo → Android App

SKELETON CODE

AndroidBLEBasic (one-way) and RedBearDuoBLEAdvanced (two-way)

Open the notes doc: <https://goo.gl/3A9Q9M>

ANDROID PROGRAM

```
// Define the device name and the length of the name
// Note the device name and the length should be consistent with the ones defined in the Duo sketch
private String mTargetDeviceName = "BLEDemo";
private int mNameLen = 0x08;
```

```
@Override
public void onProgressChanged(SeekBar seekBar, int progress,
                             boolean fromUser) {
    byte[] buf = new byte[] { (byte) 0x02, (byte) 0x00, (byte) 0x00 };

    buf[1] = (byte) mPWMSeekBar.getProgress();

    mCharacteristicTx.setValue(buf);
    mBluetoothLeService.writeCharacteristic(mCharacteristicTx);
}
```

```
// Process the Gatt and get data if there is data coming from Duo board. Created by the RedBear Team
private final BroadcastReceiver mGattUpdateReceiver = (context, intent) -> {
    final String action = intent.getAction();

    if (RBLService.ACTION_GATT_DISCONNECTED.equals(action)) {
        Toast.makeText(getApplicationContext(), text: "Disconnected",
            Toast.LENGTH_SHORT).show();
        setButtonDisable();
    } else if (RBLService.ACTION_GATT_SERVICES_DISCOVERED
        .equals(action)) {
        Toast.makeText(getApplicationContext(), text: "Connected",
            Toast.LENGTH_SHORT).show();

        getGattService(mBluetoothLeService.getSupportedGattService());
    } else if (RBLService.ACTION_DATA_AVAILABLE.equals(action)) {
        mData = intent.getByteArrayExtra(RBLService.EXTRA_DATA);

        readAnalogInValue(mData);
    } else if (RBLService.ACTION_GATT_RSSI.equals(action)) {
        displayData(intent.getStringExtra(RBLService.EXTRA_DATA));
    }
};
```


EXERCISE 1: TURN ON AN LED VIA ANDROID APP

For this exercise, you will use AndroidBLEBasic and RedBearDuoBLEBasic

Open both code sets (in Android Studio and Arduino IDE respectively)

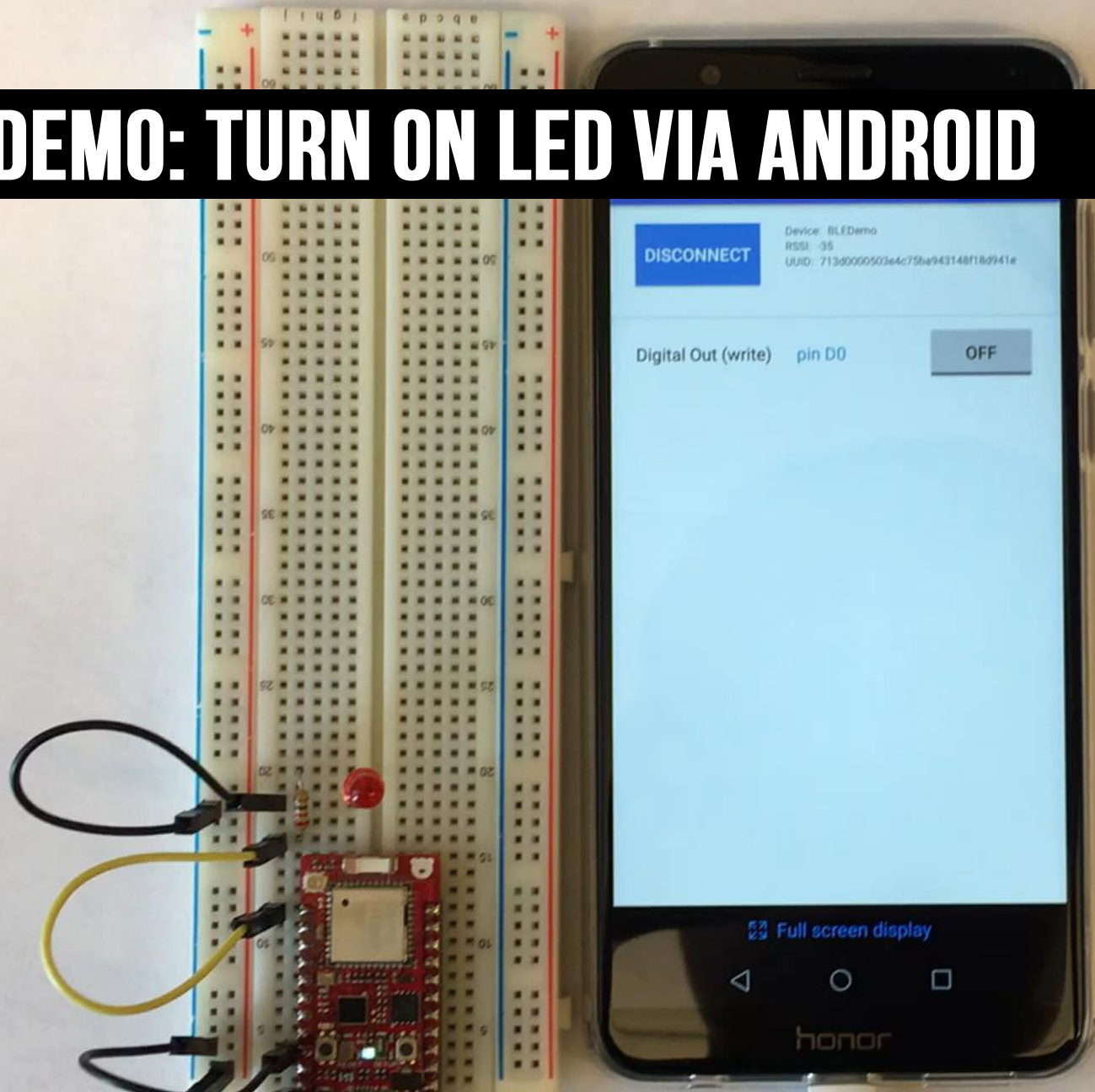
You have to change the device name

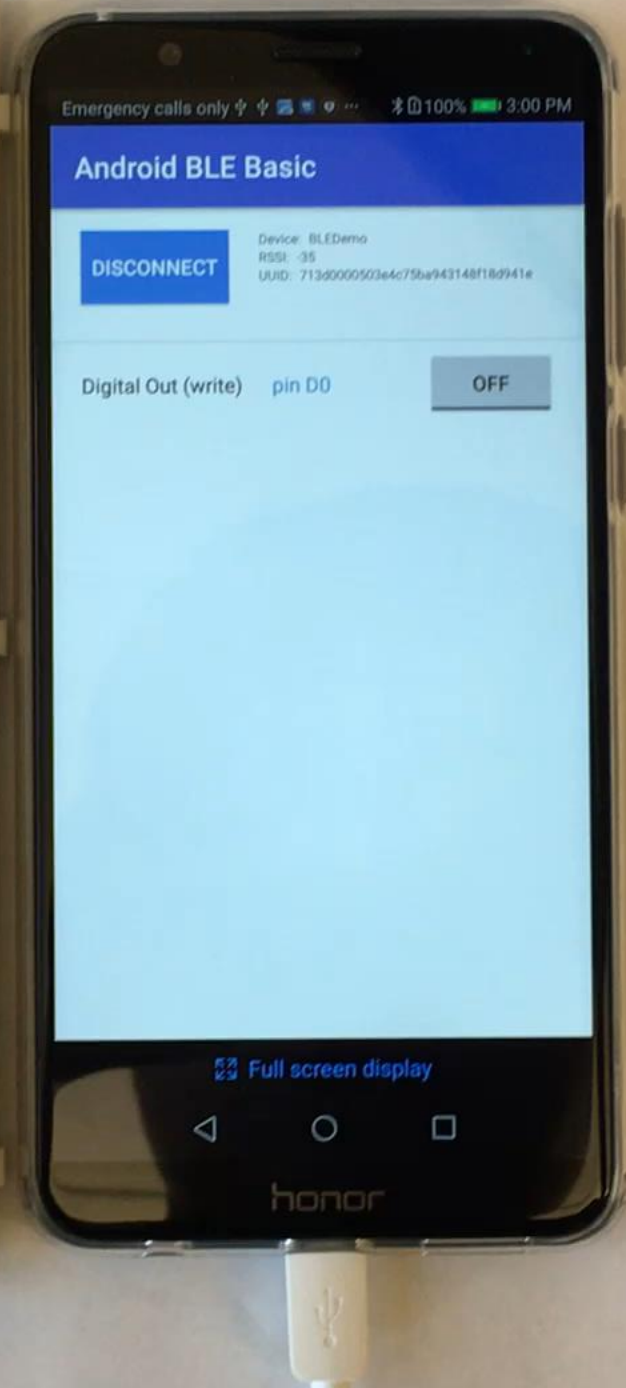
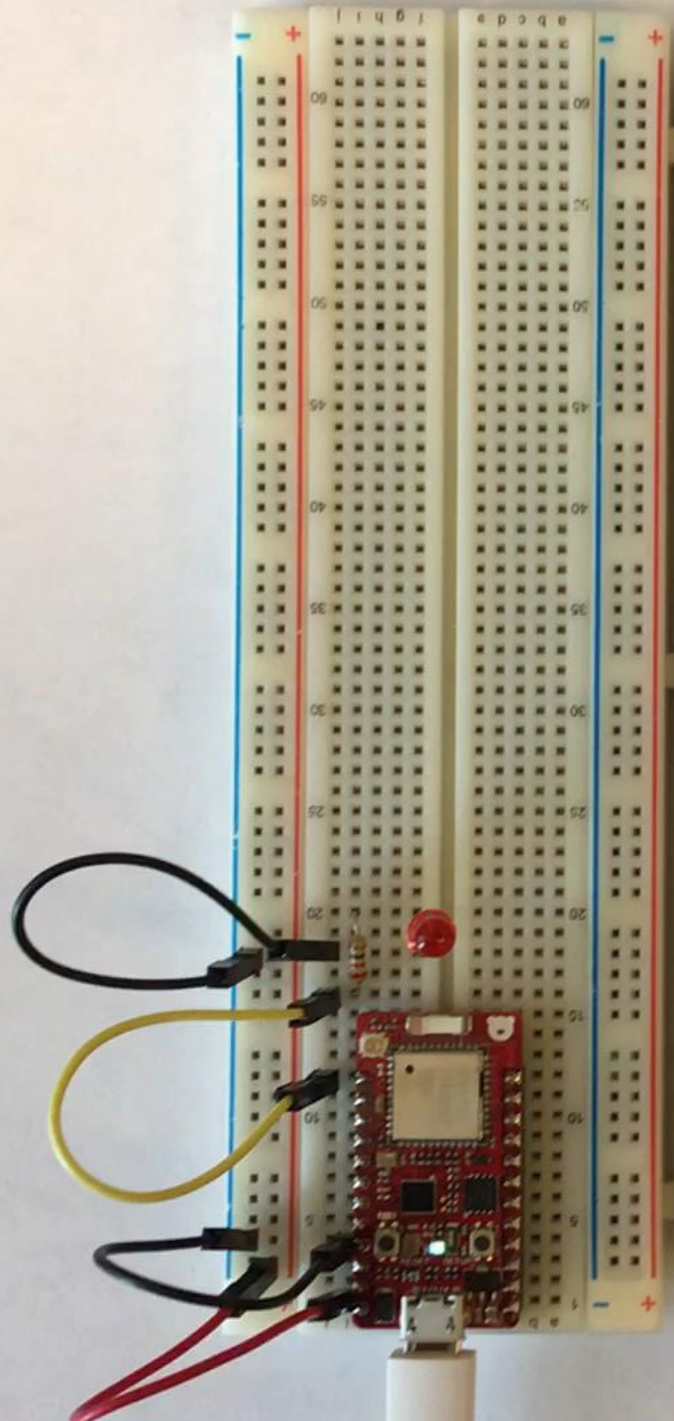
Change the pin number to the pin that you want to use

Experiment and play!

EXERCISE 1

VIDEO DEMO: TURN ON LED VIA ANDROID





EXERCISE 2: FADE AN LED VIA ANDROID APP

Again, use `AndroidBLEBasic` and `RedBearDuoBLEBasic`

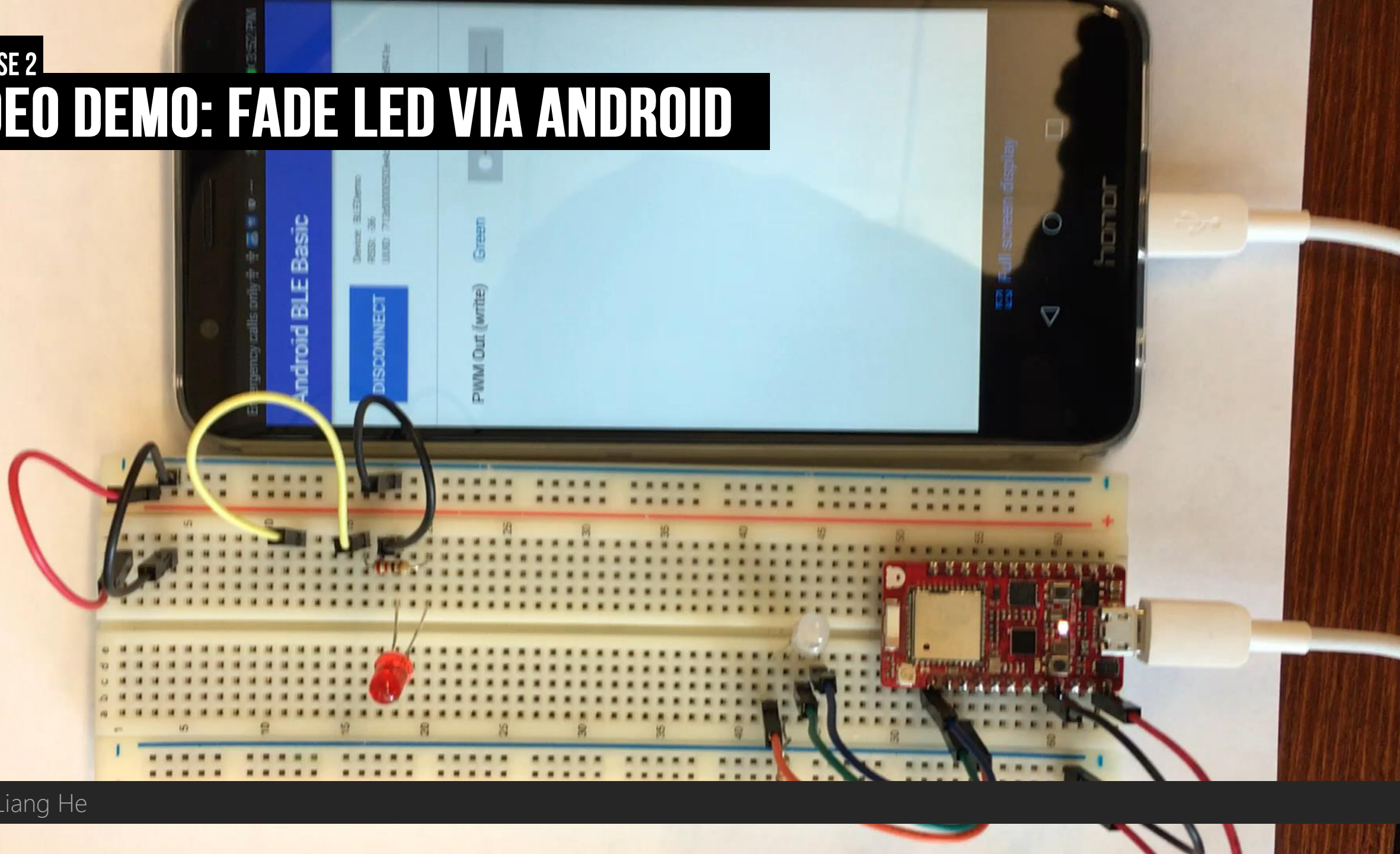
For this, make sure your circuit has the LED hooked up to a PWM pin

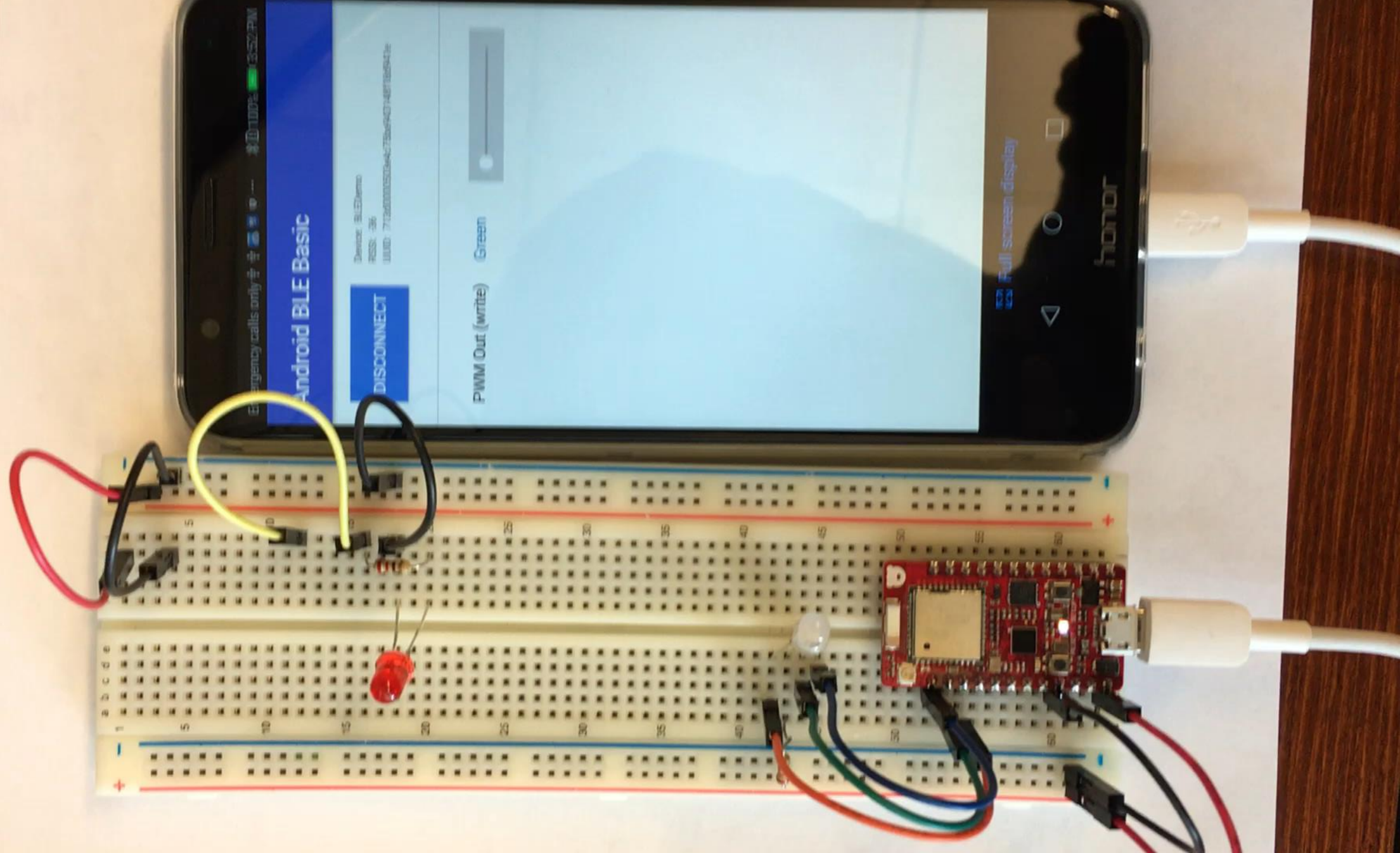
Modify Arduino code to use `analogWrite` (refer to the `RedBearDuoBLEAdvanced`)

Update Android app to use a `SeekBar` or some other continuous widget

EXERCISE 2

VIDEO DEMO: FADE LED VIA ANDROID





EXERCISE 3: 2-WAY COM BETWEEN ANDROID & ARDUINO

For this, start with AndroidBLEAdvanced and RedBearDuoBLEAdvanced

Fade the LED from Android

Fade the LED from Arduino (and update Android to properly reflect state)

EXERCISE 3

VIDEO DEMO: 2-WAY COMM BETWEEN ANDROID & ARDUINO

