

PHYSICAL COMPUTING 2: ARDUINO

CSE 590 Ubiquitous Computing | Lecture 5 | April 26

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INTRO TO ARDUINO: LEARNING GOALS

What is **Arduino** and how to use it

Difference between **analog** and **digital**

How to use **digital output** (*i.e.*, turning on/off an LED using digitalWrite)

How to use **analog output** (*i.e.*, fading an LED using analogWrite)

What is **Pulse Width Modulation** (PWM)?

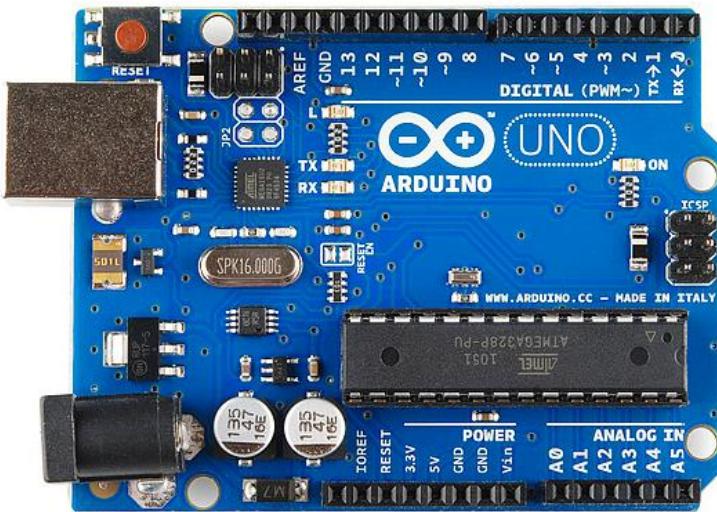
How to use **analog input** (*i.e.*, hooking up a POT and using analogRead)

How to use **digital input** (*i.e.*, hooking up a button and using digitalRead)

WHAT IS ARDUINO?

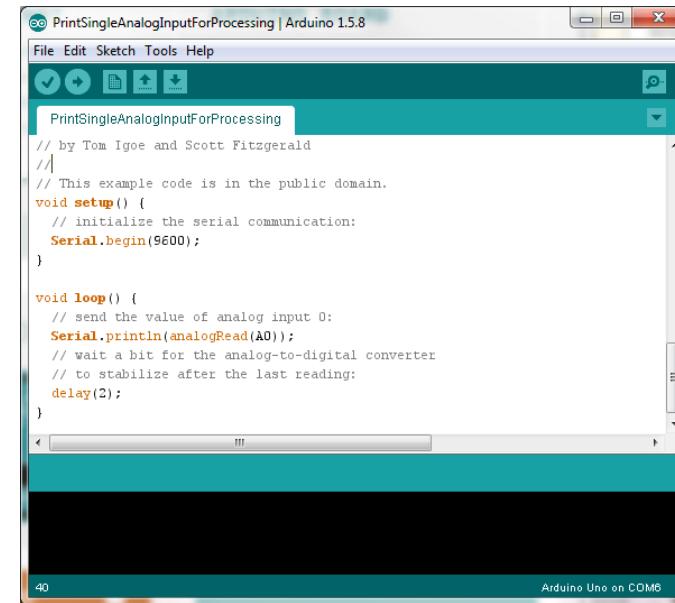
Arduino is an **open-source electronics platform** based on easy-to-use hardware and software. It's intended to enable designers, artists, hobbyists, engineers, and even children to (rapidly) create new interactive experiences.

Arduino Hardware



The Arduino board contains a microcontroller (small computer) and is used to sense the environment (or people, animals, things) by receiving inputs from many sensors, and affects its surroundings by controlling lights, motors, and other actuators.

Arduino Software

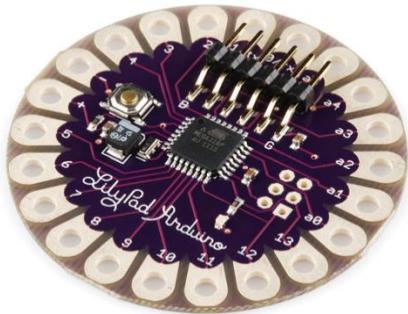


The Arduino is programmed via the Arduino programming language and using the Arduino development environment.

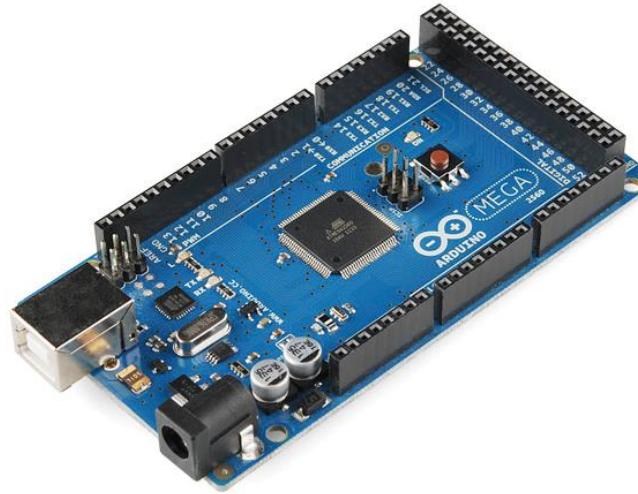
POPULAR ARDUINO MODELS

**Arduino Uno (R3)**

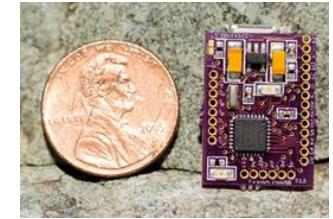
14 digital input/output pins (of which 6 can be used as PWM outputs), 6 analog inputs, a USB connection, a power jack, a reset button

**LilyPad Arduino**

Very similar to the Arduino Uno but built for wearable e-textiles. The LilyPad also has its own family of input, output, power, and sensors built specifically for e-textiles.

**Arduino Mega (R3)**

The Arduino Mega is like the UNO's big brother. It has lots (54!) of digital input/output pins (14 can be used as PWM outputs), 16 analog inputs, a USB connection, a power jack, and a reset button

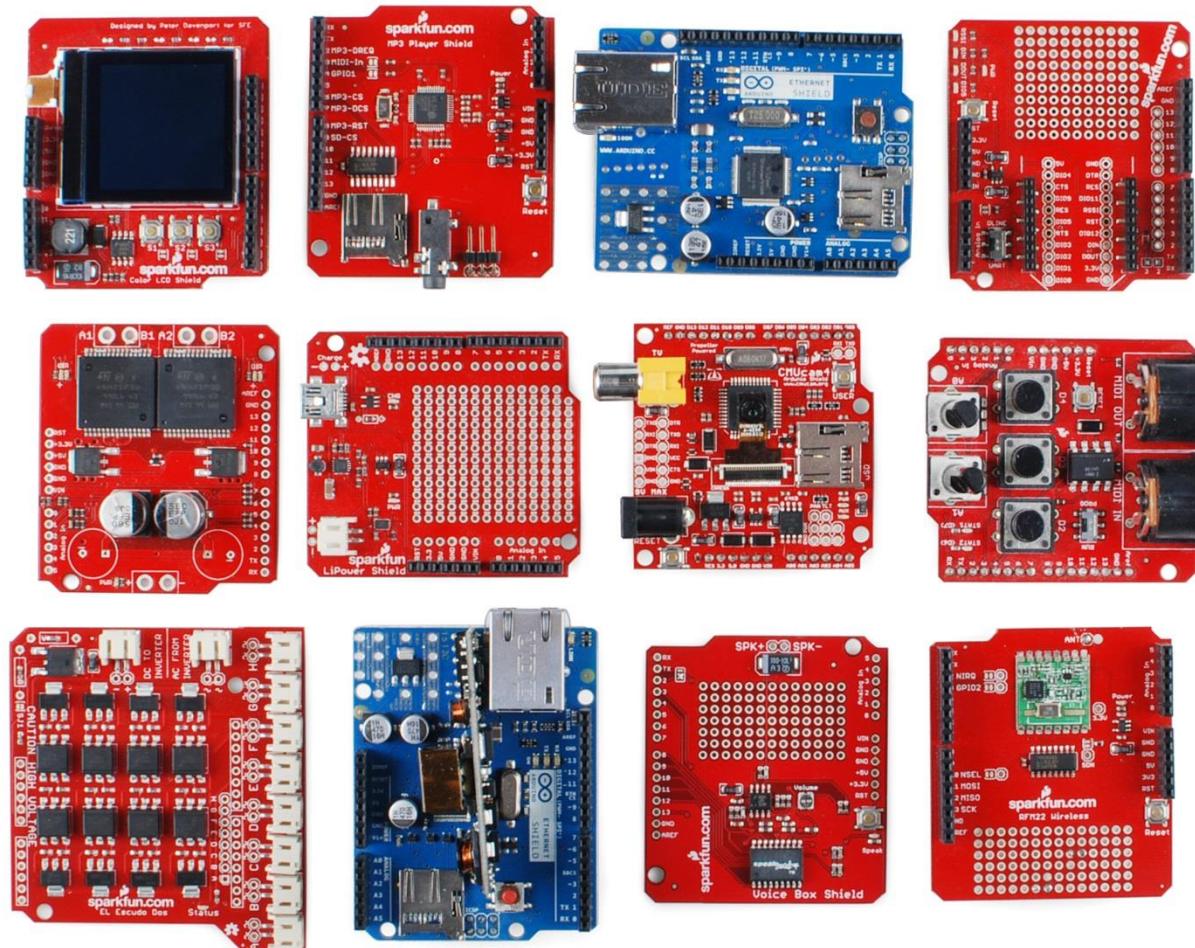
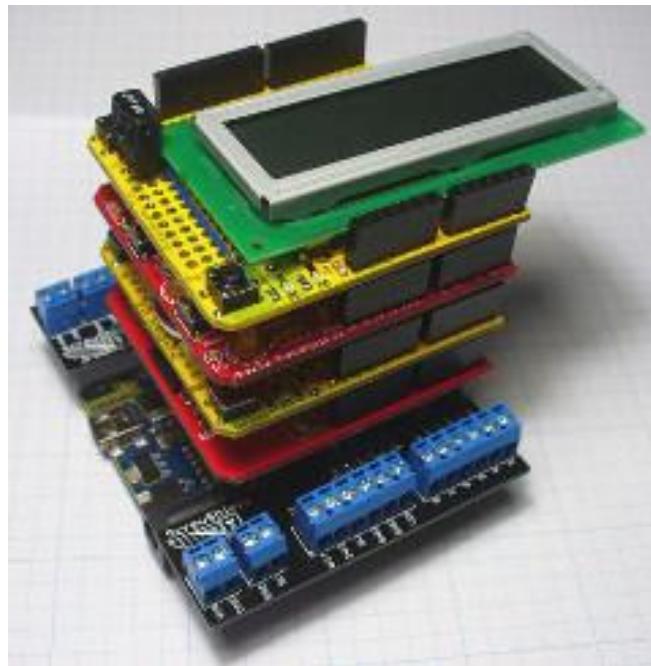
**FemtoduinoUSB**

The smallest Arduino board with micro-USB, a voltage regulator, same power and pin count as an Arduino UNO

ARDUINO

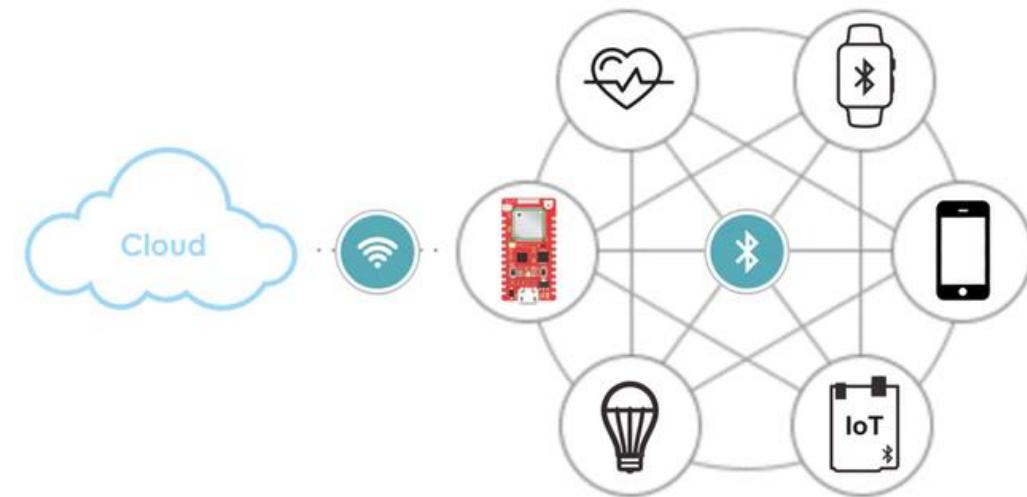
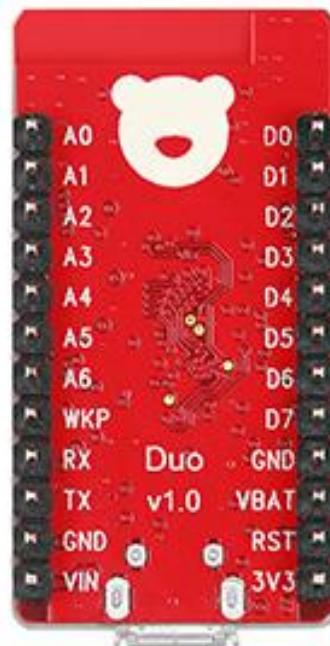
ARDUINO UNO STACKABLE SHIELDS

You can purchase stackable shields that give your Arduino more features such as WiFi, controlling motors, cellular modems, controlling LCD screens, etc.

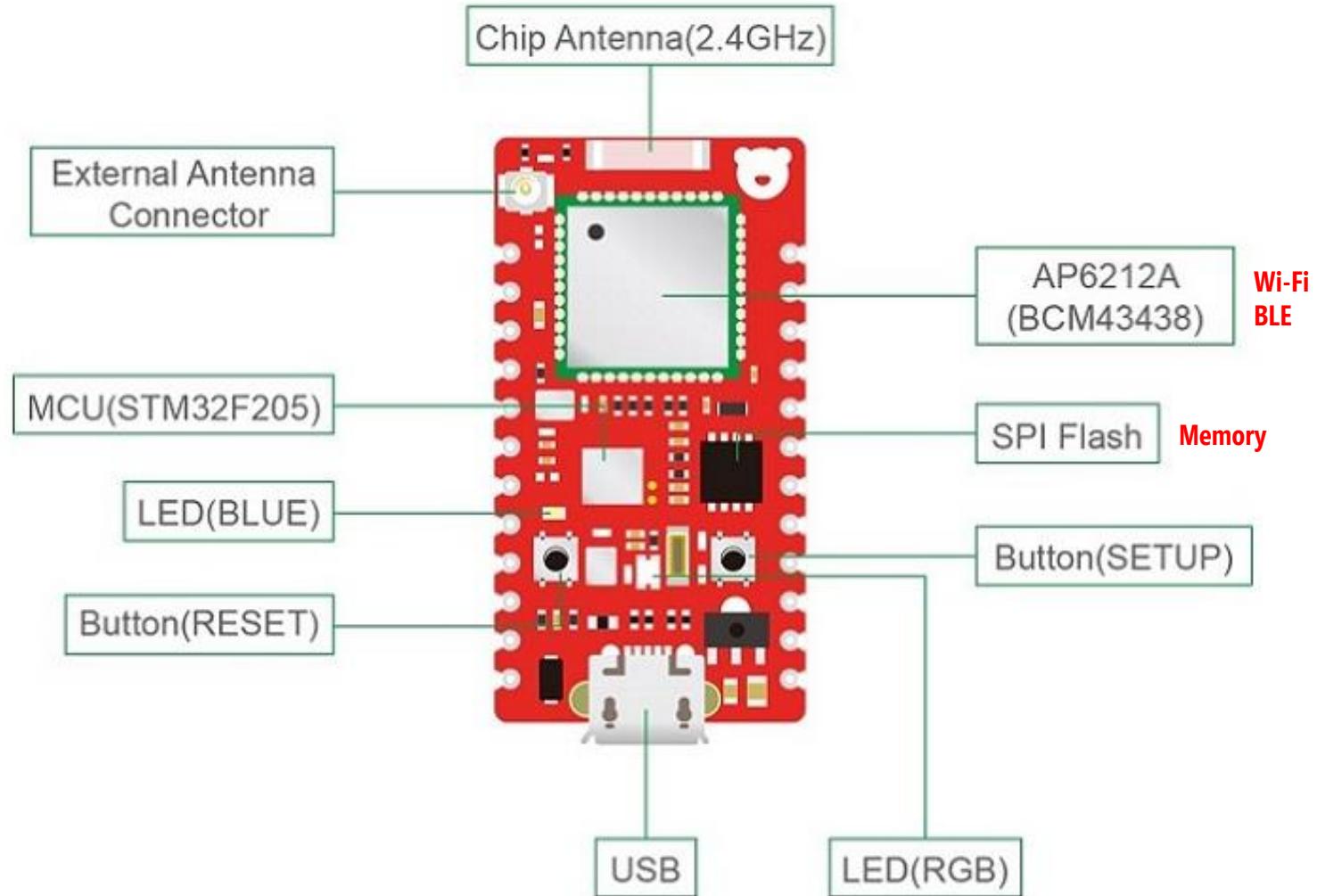


ARDUINO

REDBEAR DUO: BLE + WIFI BOARD



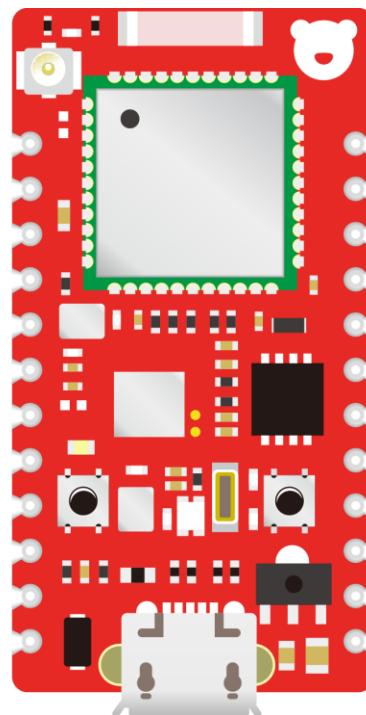
REDBEAR DUO: BLOCK DIAGRAM



ARDUINO

REDBEAR DUO: PIN LAYOUT

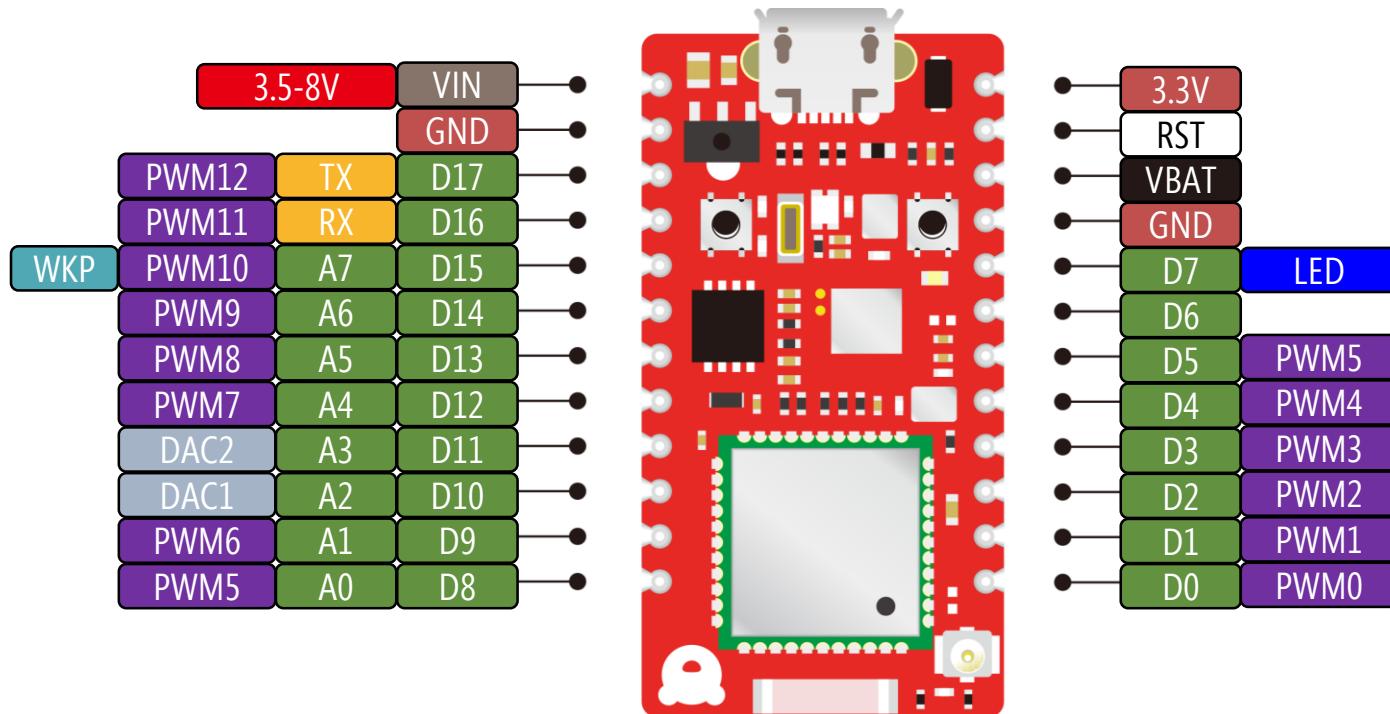
PB7	I2C1_SDA	PWM0	D0
PB6	I2C1_SCL	CAN2_TX	PWM1
PB5	SPI3_MOSI	I2S3_SD	CAN2_RX
PB4	SPI3_MISO	JTAG_TRST	PWM2
PB3	SPI3_SCK	I2S3_SCK	JTAG_TDO
PA15	SPI3_NSS	I2S3_WS	JTAG_TDI
PA14			JTAG_TCK
PA13			JTAG_TMS
		LED	D7
		GND	
		VBAT	
		RST	
		3V3	



D8	A0	PWM5	UART2_RX	PA3
D9	A1	PWM6	UART2_TX	PA2
D10	A2	DAC1	SPI1 NSS	PA4
D11	A3	DAC2	SPI1 SCK	PA5
D12	A4	PWM7	SPI1 MISO	PA6
D13	A5	PWM8	SPI1 MOSI	PA7
D14	A6	PWM9	UART2 RTS	PA1
D15	A7	PWM10	WKP	UART2 CTS
D16	RX	PWM11	UART1 RX	PA10
D17	TX	PWM12	UART1 TX	PA9
GND				
VIN		3.5 - 8v		

REDBEAR DUO: PIN LAYOUT

I've simplified the pin layout chart and flipped it around (I tend to program with the USB facing away from me)



Legend

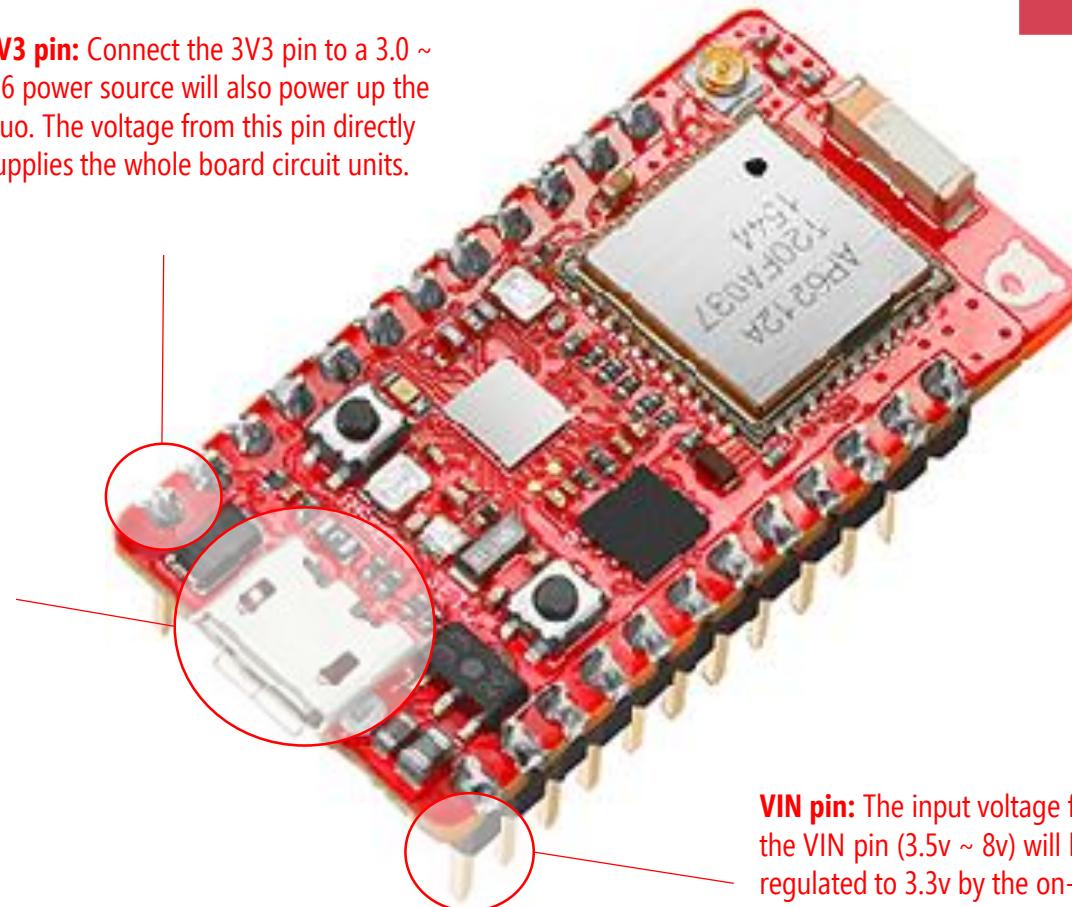
- AX Analog Input Pin
- DX Digital Input/output Pin
- PWM Supports Analog Out via Pulse Width Modulation

REDBEAR DUO: POWER

Use only one power source as the main power supply at a time, otherwise you will damage the board!

3V3 pin: Connect the 3V3 pin to a 3.0 ~ 3.6 power source will also power up the Duo. The voltage from this pin directly supplies the whole board circuit units.

Micro USB: The Micro USB allows you to communicate with your computer to program the Arduino and also supplies power (3.3V). Easiest option for rapid prototyping.



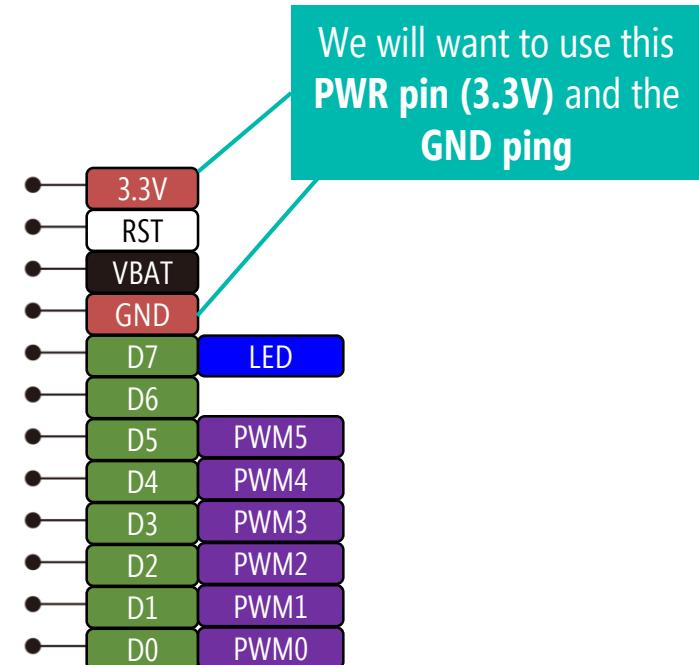
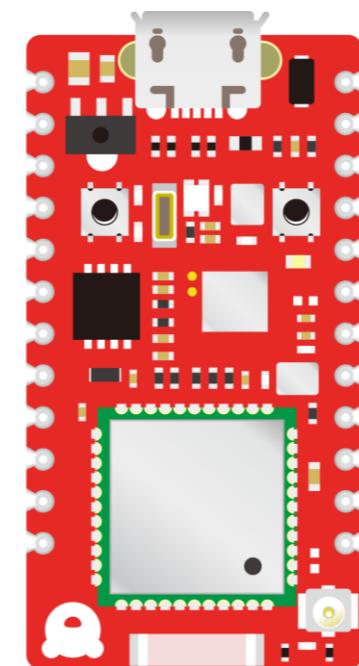
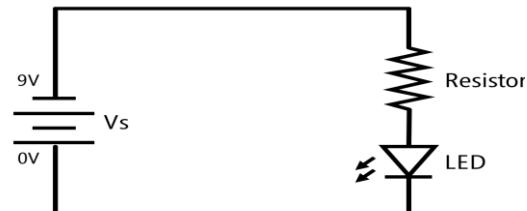
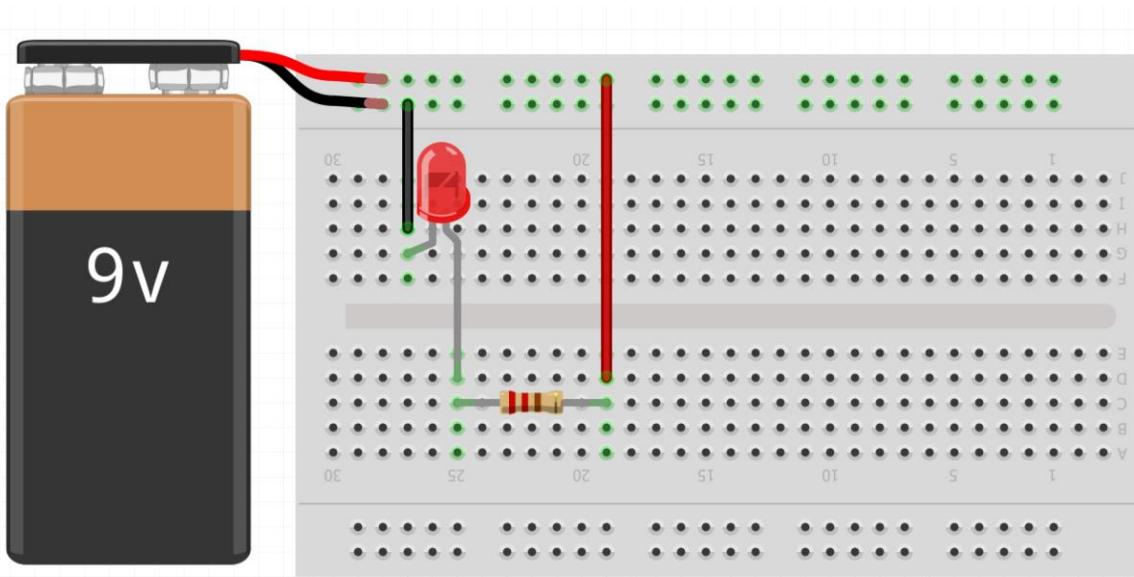
VIN pin: The input voltage from the VIN pin (3.5v ~ 8v) will be regulated to 3.3v by the on-board regulator first and then supply the whole board circuit units.

POWER YOUR CIRCUIT VIA REDBEAR DUO 3.3V OUTPUT

For our first exercise, we are just going to convert the circuit you previously made with the barrel jack + 9V battery to, instead, use the Arduino RedBear Duo 3.3V and GND connections. This is a bit of a toy exercise given that we are not yet taking advantage of the microcontroller platform—we are only using it to power our circuit! ☺

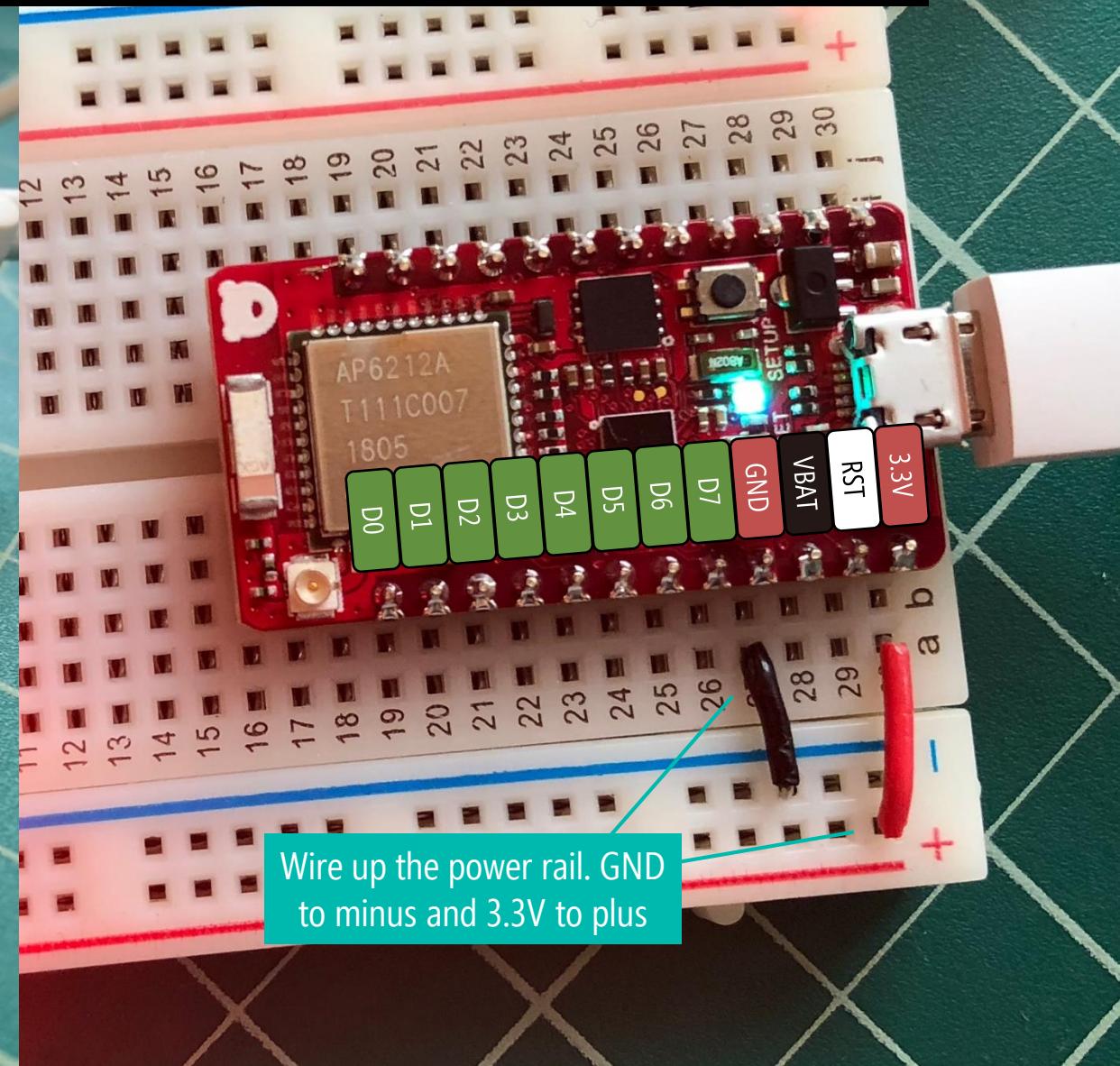
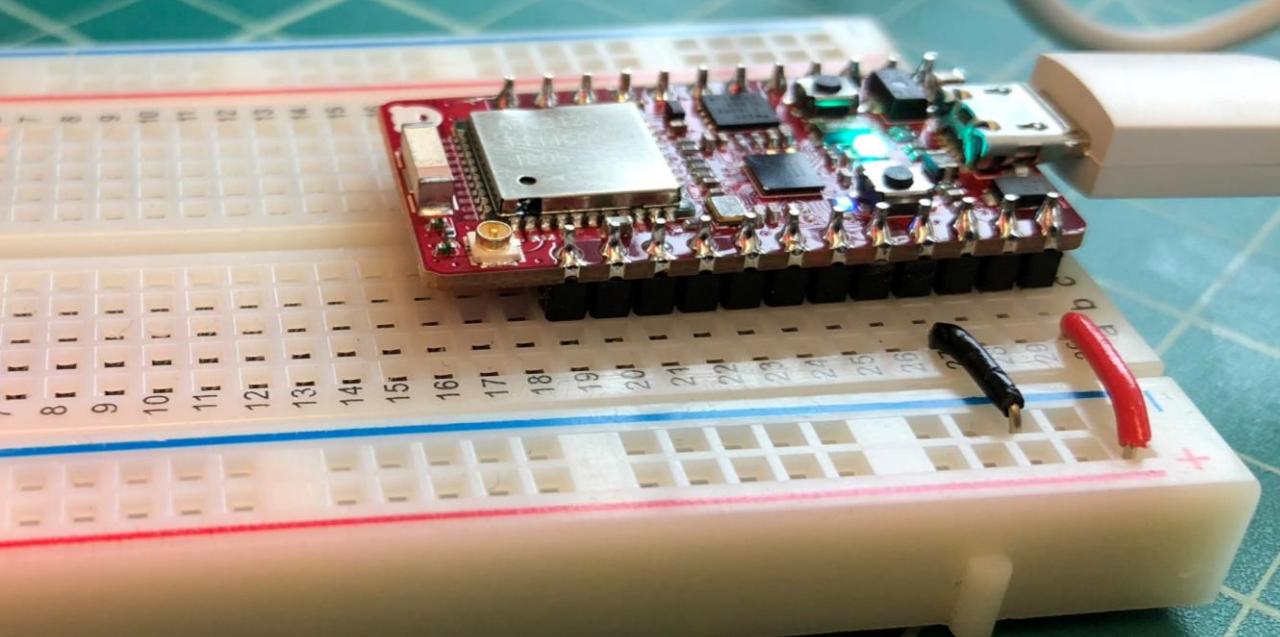
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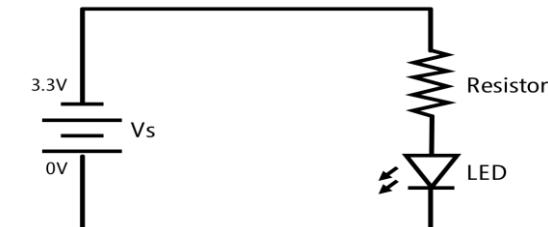
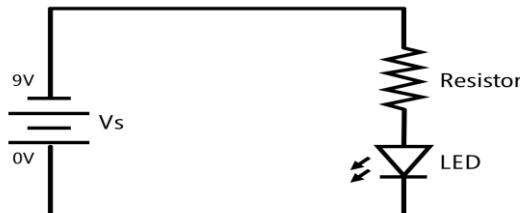
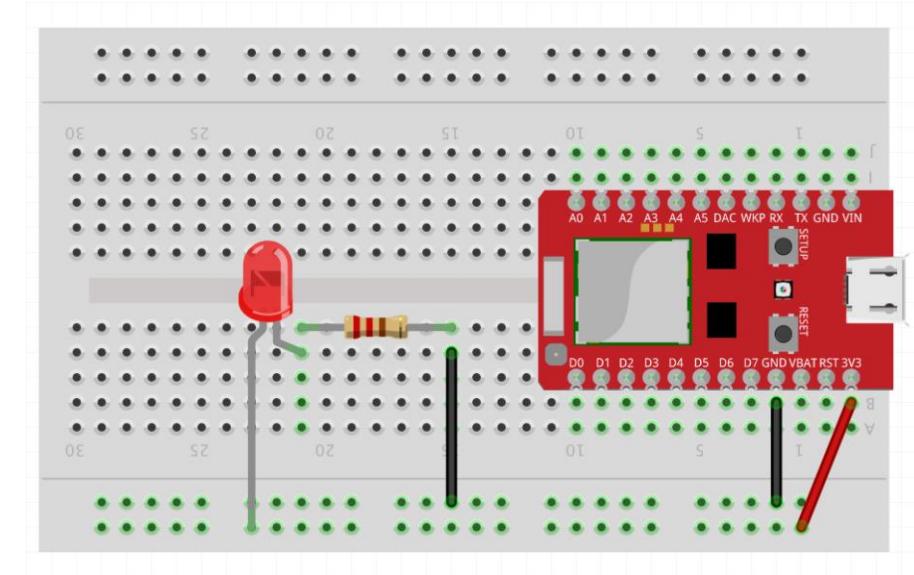
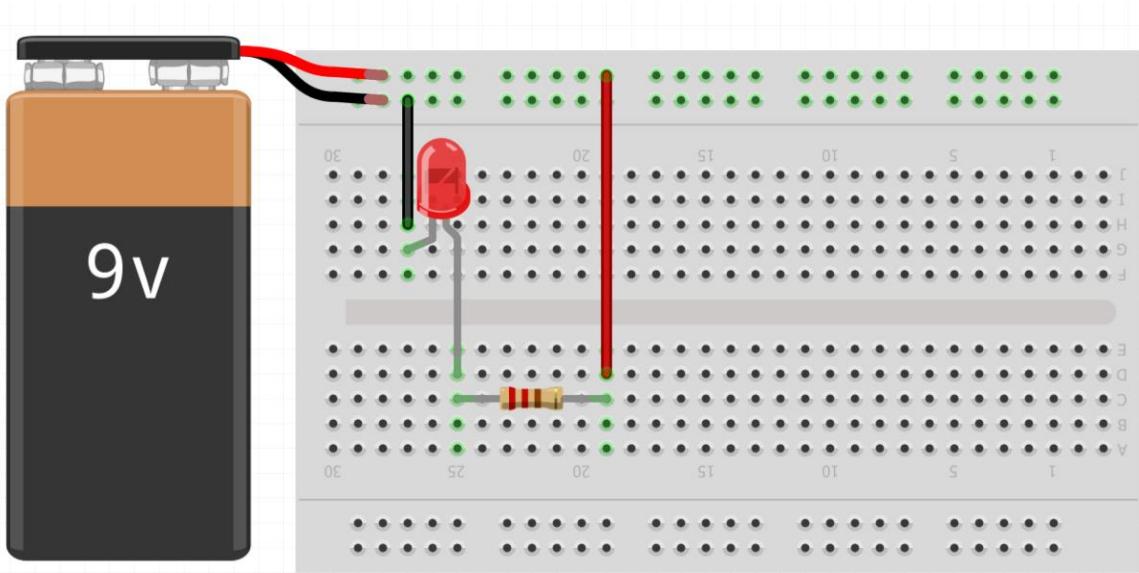
BREADBOARDS

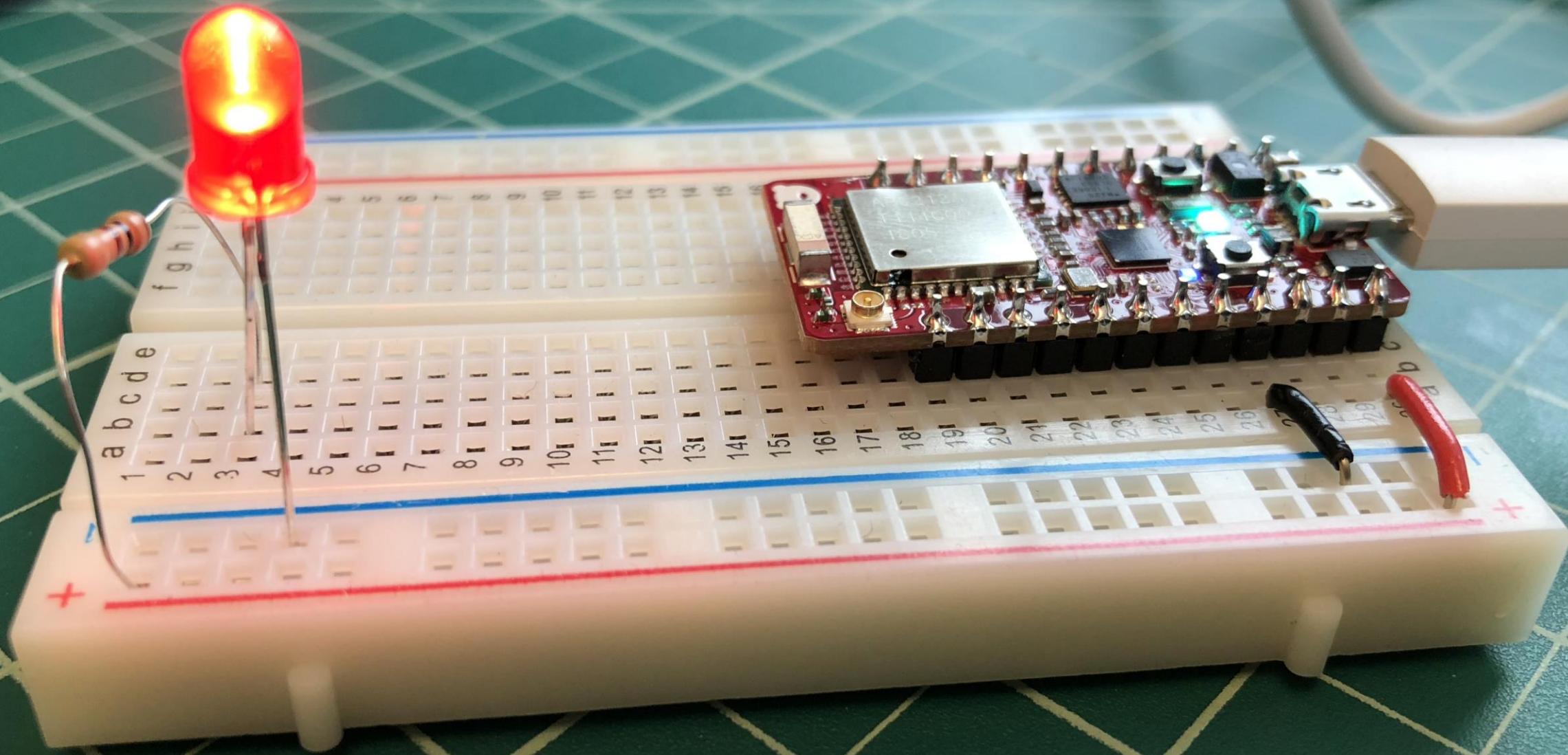
THE REDBEAR DUO IS DESIGNED TO “PLUG” INTO YOUR BREADBOARD



POWER YOUR CIRCUIT VIA REDBEAR DUO 3.3V OUTPUT

For our first exercise, we are just going to convert the circuit you previously made with the barrel jack + 9V battery to, instead, using the Arduino RedBear Duo 3.3V and GND connections. This is a bit of a toy exercise given that we are not yet taking advantage of the microcontroller platform—we are only using it to power our circuit! ☺





OK, now let's do something more fun and interactive! Let's program the Arduino to control the light. To do this, we have to introduce the Arduino programming framework.

ARDUINO FUNCTIONS: I/O

For controlling the Arduino board and performing computations

Digital I/O

`digitalRead()`

`digitalWrite()`

`pinMode()`

Analog I/O

`analogRead()`

`analogReference()`

`analogWrite()`

Advanced I/O

`noTone()`

`pulseIn()`

`pulseInLong()`

`shiftIn()`

`shiftOut()`

`tone()`

External Interrupts

`attachInterrupt()`

`detachInterrupt()`

`Interrupts`

`interrupts()`

`noInterrupts()`

Communication

`Serial`

`stream`

`USB`

`Keyboard`

`Mouse`

ARDUINO VARIABLES: DATA TYPES & CONVERSION

Arduino data types and constants

Data Types		Conversion	Variable Scope & Qualifiers
String	int	byte()	const
String()	long	char()	scope
array	short	float()	static
bool	unsigned char	int()	volatile
boolean	unsigned int	long()	
byte	unsigned long	word()	
char	void		
double			
float	word		

ARDUINO STRUCTURE

The elements of Arduino C/C++ code

Sketch

`loop()`

`setup()`

Control Structure

`break`

`continue`

`do...while`

`else`

`for`

`goto`

`if...else`

`return`

`switch...case`

`while`

Arithmetic Operators

`%` (remainder)

`%` (remainder)

`*` (multiplication)

`+` (addition)

`-` (subtraction)

`/` (division)

`=` (assignment operator)

Comparison Operators

`!=` (not equal to)

`<` (less than)

`<=` (less than or equal to)

`==` (equal to)

`>` (greater than)

`>=` (greater than or equal to)

Pointer Access Operators

`&` (reference operator)

`*` (dereference operator)

Bitwise Operators

`&` (bitwise and)

`<<` (bitshift left)

`>>` (bitshift right)

`^` (bitwise xor)

`|` (bitwise or)

`~` (bitwise not)

Boolean Operators

`!` (logical not)

`&&` (logical and)

`||` (logical or)

Compound Operators

`&=` (compound bitwise and)

`*=` (compound multiplication)

`+=` (increment)

`+=` (compound addition)

`--` (decrement)

`-=` (compound subtraction)

`/=` (compound division)

`^=` (compound bitwise xor)

`|=` (compound bitwise or)

Further Syntax

`#define` (define)

`#include` (include)

`/* */` (block comment)

`//` (single line comment)

`;` (semicolon)

`{}` (curly braces)

ARDUINO PROGRAMMING

ARDUINO CHEAT SHEET

Arduino Programming Cheat Sheet

Structure & Flow

```
Basic Program Structure
void setup() {
  // Runs once when sketch starts
}
void loop() {
  // Runs repeatedly
}

Control Structures
if (x < 5) { ... } else { ... }
while (x < 5) { ... }
for (int i = 0; i < 10; i++) { ... }
break; // Exit a loop immediately
continue; // Go to next iteration
switch (var) {
  case 1:
    ...
    break;
  case 2:
    ...
    break;
  default:
    ...
}
return x; // x must match return type
return; // For void return type

Function Definitions
<ret_type> <name>(<params>)
{
  ...
  e.g. int double(int x) {return x*2;}
}
```

Operators

General Operators

- = assignment
- + add
- * multiply / divide
- % modulo
- == equal to != not equal to
- < less than > greater than
- <> less than or equal to >> greater than or equal to
- && and || or
- ! not

Compound Operators

- ++ increment
- decrement
- + compound addition
- * compound multiplication
- /= compound division
- &= compound bitwise and
- |= compound bitwise or

Bitwise Operators

- & bitwise and | bitwise or
- ^ bitwise xor ~ bitwise not
- << shift left >> shift right

Pointer Access

- & reference: get a pointer
- * dereference: follow a pointer

Variables, Arrays, and Data

Data Types

boolean	true false
char	-128 - 127, 'a'-'\$' etc.
unsigned char	0 - 255
byte	0 - 255
int	-32768 - 32767
unsigned int	0 - 65535
word	0 - 6535
long	-2147483648 - 2147483647
unsigned long	0 - 4294967295
float	-3.4028e+38 - 3.4028e+38
double	currently same as float
void	i.e., no return value

Numeric Constants

123	decimal
0b1111011	binary
0173	octal - base 8
0x7B	hexadecimal - base 16
123U	force unsigned
123L	force long
123UL	force unsigned long
123.0	force floating point
1.23e6	1.23*10 ⁶ = 123000

Qualifiers

static	persists between calls in RAM (nice for ISR)
volatile	read-only in flash
const	
PROGMEM	

Arrays

```
int myPins[] = {2, 4, 8, 3, 6};
int myInts[6]; // Array of 6 ints
myInts[0] = 42; // Assigning first
// index of myInts
myInts[6] = 12; // ERROR! Indexes
// are 0 though 5
```

Built-in Functions

Pin Input/Output

Digital I/O - pins 0-13 A0-A5	pinMode(pin, [INPUT, OUTPUT, INPUT_PULLUP])
analogWrite(pin, [HIGH, LOW])	

Analog In - pins A0-A5

int analogRead(pin)	
analogReference([DEFAULT, INTERNAL, EXTERNAL])	

PWM Out - pins 3 5 6 9 10 11

analogWrite(pin, value)	
-------------------------	--

Advanced I/O

tone(pin, freq_Hz)	
noTone(pin)	
shiftOut(dataPin, clockPin, [MSBFIRST, LSBFIRST], value)	
unsigned long pulseIn(pin, [HIGH, LOW])	

Time

unsigned long millis()	// Overflows at 50 days
unsigned long micros()	// Overflows at 70 minutes
delay(msc)	
delayMicroseconds(usec)	

MATH

min(x, y)	max(x, y)	abs(x)
sin(rad)	cos(rad)	tan(rad)
sqr(x)	pow(base, exponent)	
constrain(x, minval, maxval)		
map(val, fromL, fromH, toL, toH)		

Random Numbers

randomSeed(seed)	// long or int
long random(max) // 0 to max-1	
long random(min, max)	

Primary source: Arduino Language Reference
<http://arduino.cc/en/Reference/>

Libraries

Serial - comm. with PC or via RX/TX

```
begin(long speed) // Up to 115200
end()
int read() // #bytes available
int peek() // Read w/o removing
flush()
print(data) println(data)
write(byte) write(char * string)
write(byte * data, size)
SerialEvent() // Called if data ready
```

SoftwareSerial.h - comm. on any pin

```
SoftwareSerial(rxPin, txPin)
begin(long speed) // Up to 115200
listen() // Only 1 can listen
isListening() // at a time.
read, peek, print, println, write
// Equivalent to Serial library
```

EEPROM.h - access non-volatile memory

```
byte read(addr)
write(addr, byte)
EEPROM[index] // Access as array
```

Servo.h - control servo motors

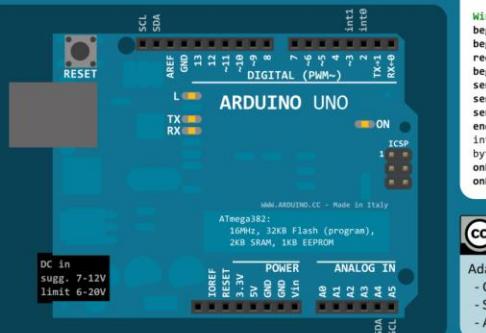
```
attach(pin, [min_us, max_us])
write(angle) // 0 to 180
writeMicroseconds(us) // 1000-2000; 1500 is midpoint
int read() // 0 to 180
bool attached()
detach()
```

Wire.h - I²C communication

```
begin() // Join a master
begin(addr) // Join a slave @ addr
requestFrom(addr, count)
beginTransmission(addr) // Step 1
send(byte) // Step 2
send(char * string)
send(byte * data, size)
endTransmission() // Step 3
int available() // #bytes available
byte receive() // Get next byte
onReceive(handler)
onRequest(handler)
```

Adapted from:

- Original: Gavin Smith
- SVG version: Frederic Dufourg
- Arduino board drawing: Fritzing.org



The Arduino Cheat Sheet handout

we provided in class should be a useful reference to help you get started (until you've internalized the syntax, common functions, etc.).

While this cheat sheet was obviously written for the Arduino Uno—all of the functionality is the same. However, the **pin layout on the Uno is different** from the RedBear Duo and the **Uno runs at 5V**, your **Duo runs at 3.3V!**

ACTIVITY: LEARN DIGITAL OUTPUT

PROGRAM ARDUINO!

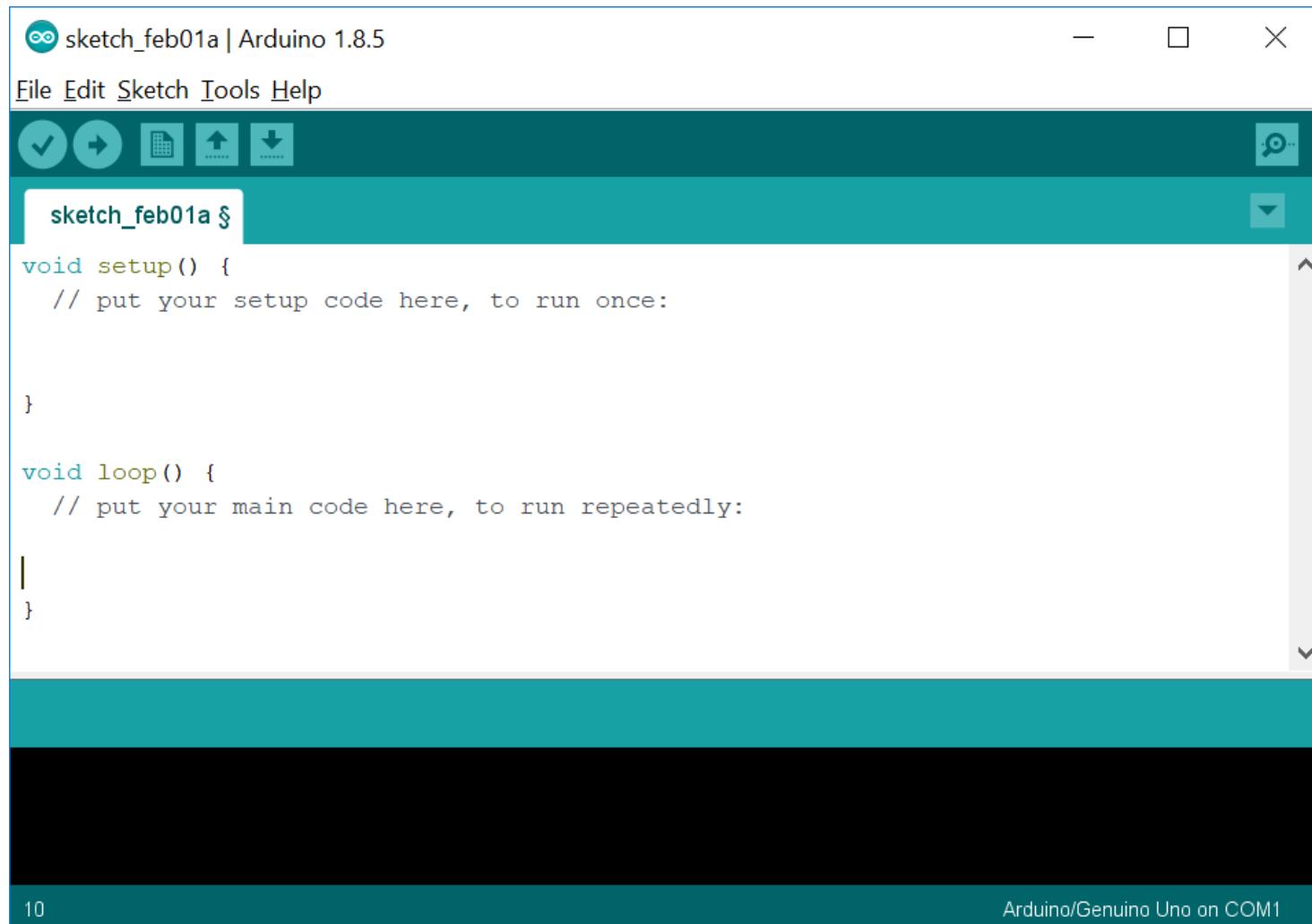
All Arduino programs are comprised of two areas: *setup* and *loop*.

SETUP

Called once at the very beginning of execution. Use this for initialization

LOOP

Called over and over again as fast as possible by the microcontroller. As soon as your code completes here, *loop()* will be called again forever



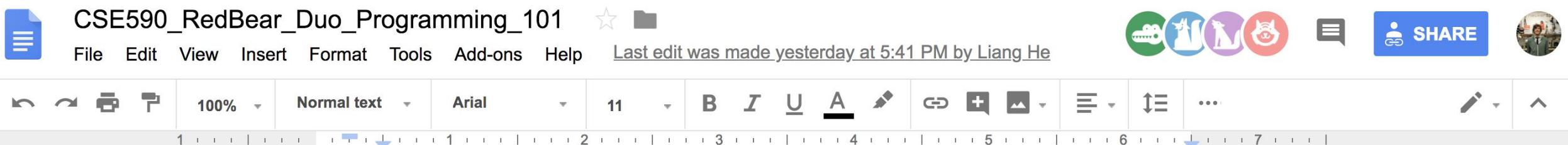
The screenshot shows the Arduino IDE interface with a sketch titled "sketch_feb01a". The code editor displays the following structure:

```
sketch_feb01a | Arduino 1.8.5
File Edit Sketch Tools Help
sketch_feb01a §
void setup() {
  // put your setup code here, to run once:
}

void loop() {
  // put your main code here, to run repeatedly:
}
```

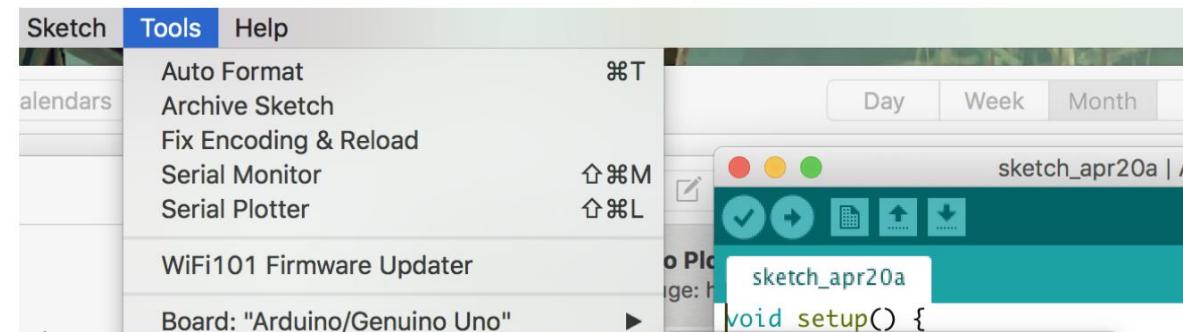
The code editor has a dark teal background with light teal highlights for code blocks. The status bar at the bottom right shows "Arduino/Genuino Uno on COM1".

SETTING UP ARDUINO IDE FOR REDBEAR DUO

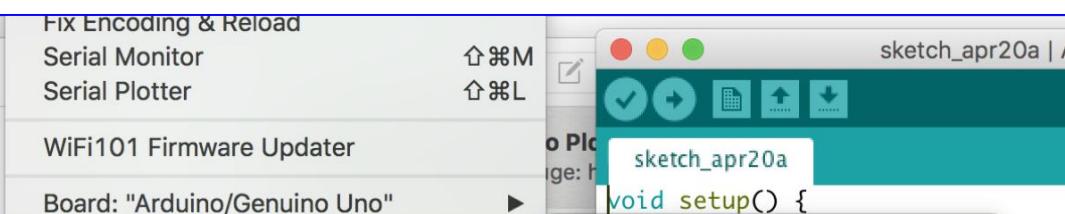
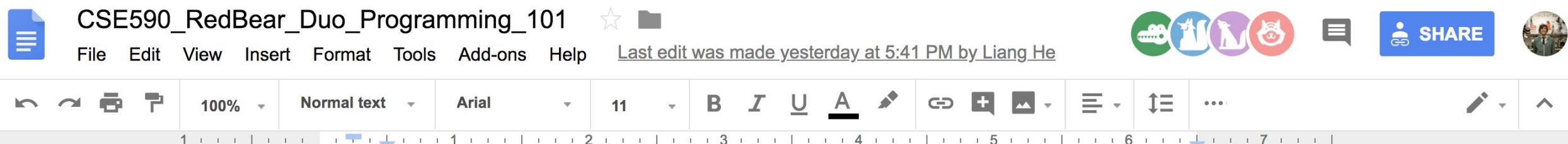


1. Download and install Arduino IDE 1.6.7 or above (latest is 1.8.5):
<https://www.arduino.cc/en/Main/Software>
2. Plug in the RedBear Duo board to your laptop/computer with a micro-USB to USB cable.
Launch Arduino and select the right port under “Tools->Port”, select the port that the RedBear Duo board uses

(On MacOSX) The port looks like the one in the image below (either /dev/tty.usbmodem* or /dev/cu.usbmodem*).



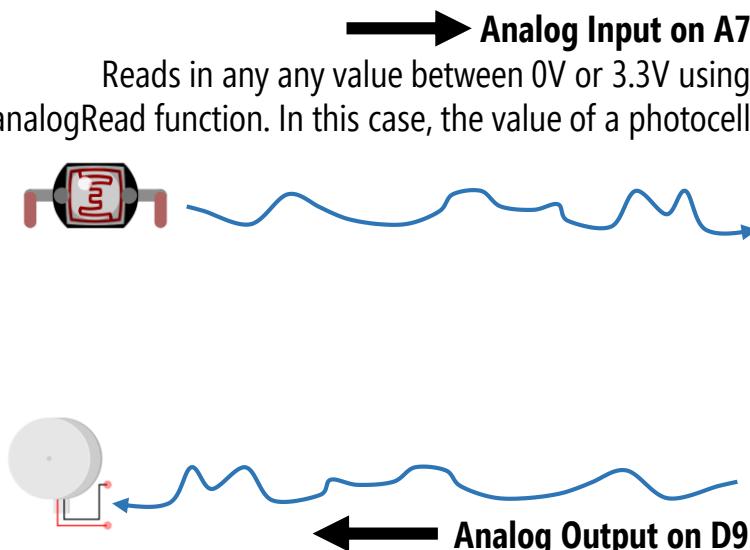
SETTING UP ARDUINO IDE FOR REDBEAR DUO



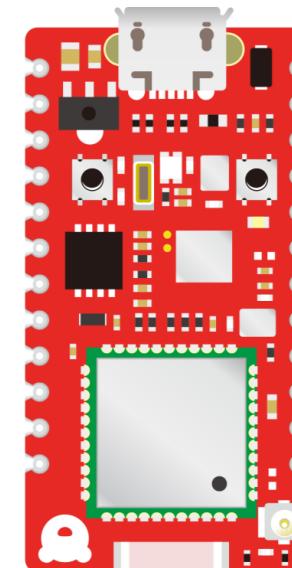
INTRODUCTION TO I/O

INPUT VS. OUTPUT

Input and output is with respect to the microcontroller board. Input is anything that the RedBear Duo reads in (e.g., from a sensor) and output is anything that the RedBear Duo writes out (e.g., to a light or motor)



VIN	
GND	
TX	D17
RX	D16
A7	D15
A6	D14
A5	D13
A4	D12
A3	D11
A2	D10
A1	D9
A0	D8



Digital Input on D7

Reads in a digital input signal (anything below 1.65V converted to LOW, anything above 1.65V converted to HIGH). In this case, the value of switch.

3.3V	
RST	
VBAT	
GND	
D7	
D6	
D5	
D4	
D3	
D2	
D1	
D0	

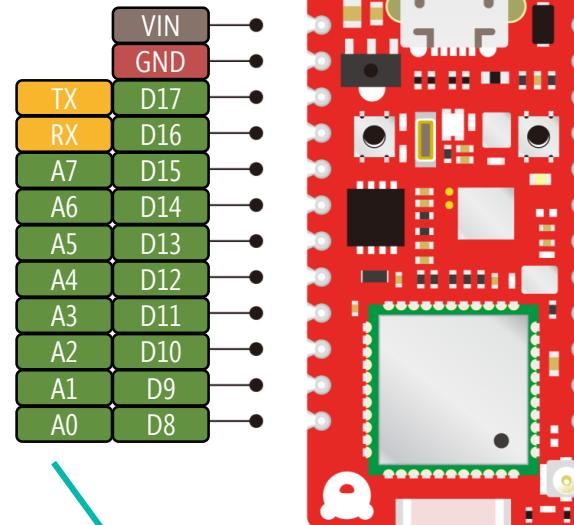
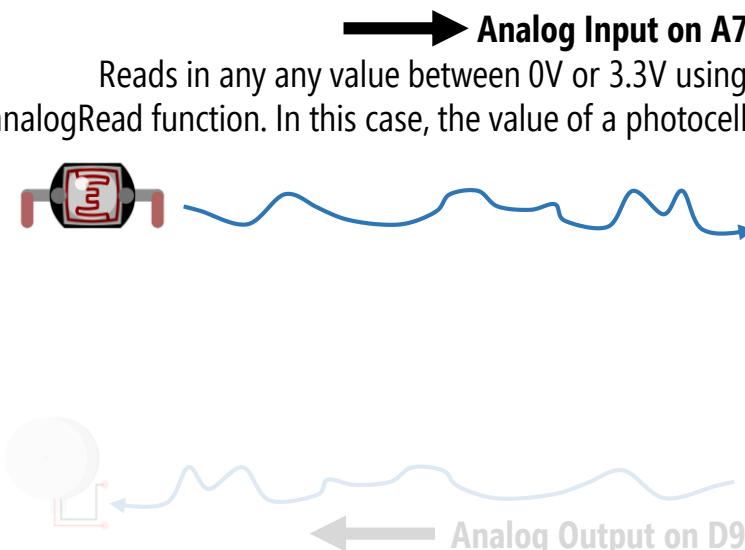
Digital Output on D0

Writes out 0V or 3.3V using digitalWrite function. In this case, turning on and off an LED.

INTRODUCTION TO I/O

INPUT VS. OUTPUT

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We can **only read analog input** on ports labeled A0-A7

Digital Input on D7

Reads in a digital input signal (anything below 1.65V converted to LOW, anything above 1.65V converted to HIGH). In this case, the value of switch.

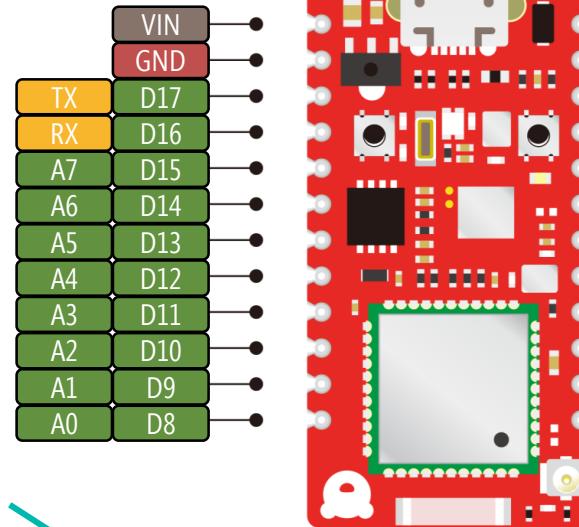
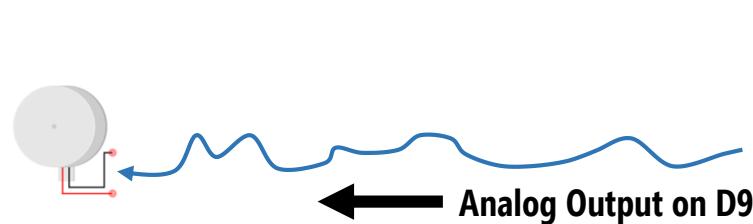
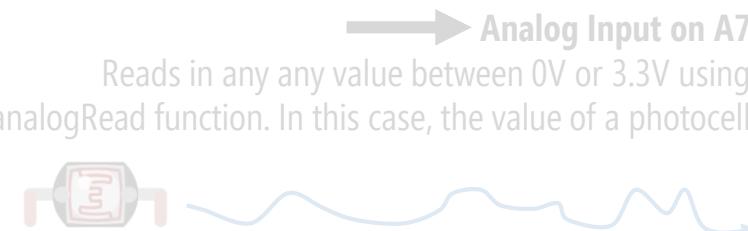
Digital Output on D0

Writes out 0V or 3.3V using digitalWrite function. In this case, turning on and off an LED.

INTRODUCTION TO I/O

INPUT VS. OUTPUT

Input and output is with respect to the microcontroller board. Input is anything that the RedBear Duo reads in (e.g., from a sensor) and output is anything that the RedBear Duo writes out (e.g., to a light or motor)



We can **only write analog output** on ports labeled PWM. Consult prior pin diagram figure.

← **Digital Input on D7**
Reads in a digital input signal (anything below 1.65V converted to LOW, anything above 1.65V converted to HIGH). In this case, the value of switch.



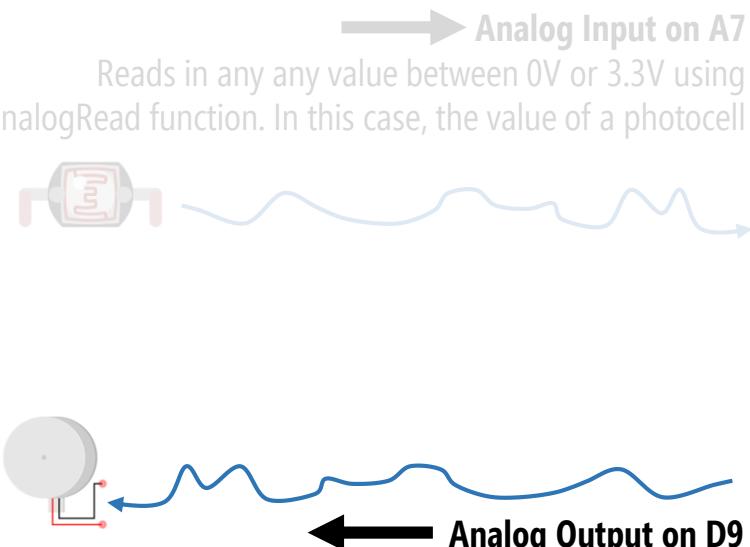
→ **Digital Output on D0**
Writes out 0V or 3.3V using digitalWrite function. In this case, turning on and off an LED.



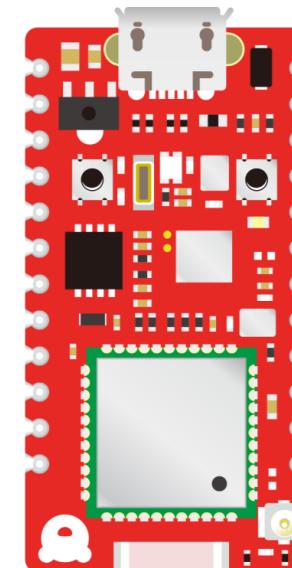
OUTPUT

DIGITAL AND ANALOG OUTPUT

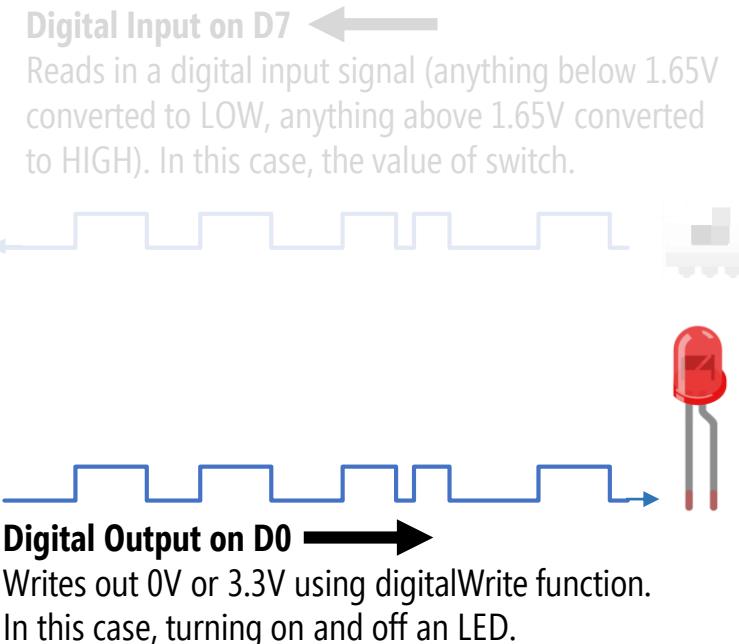
We are going to start with covering digital and analog output



VIN	
GND	
TX	D17
RX	D16
A7	D15
A6	D14
A5	D13
A4	D12
A3	D11
A2	D10
A1	D9
A0	D8



3.3V	
RST	
VBAT	
GND	
D7	
D6	
D5	
D4	
D3	
D2	
D1	
D0	

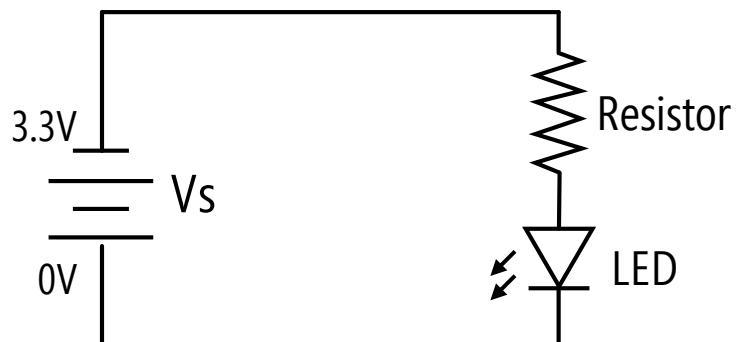
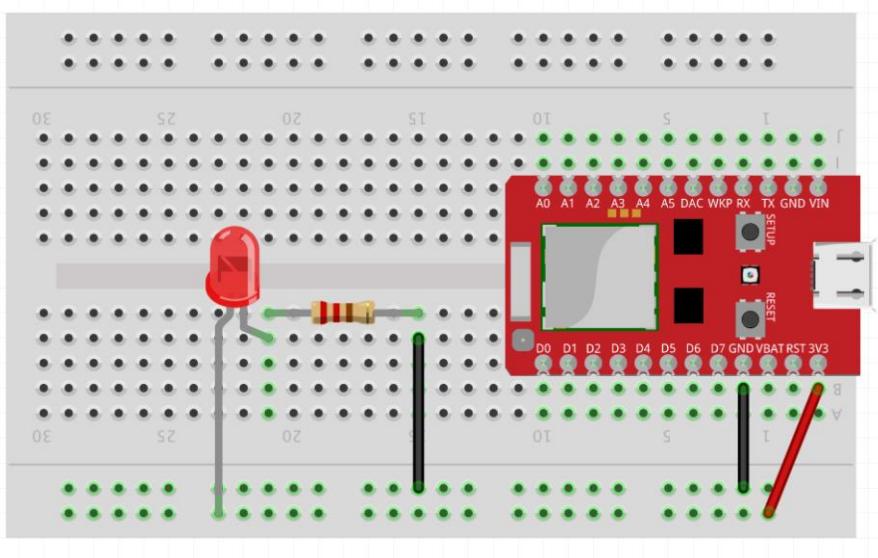


Writing our first Arduino program: **blinking** an LED on and off.
On and *off* implies digital output, so we will use digitalWrite.

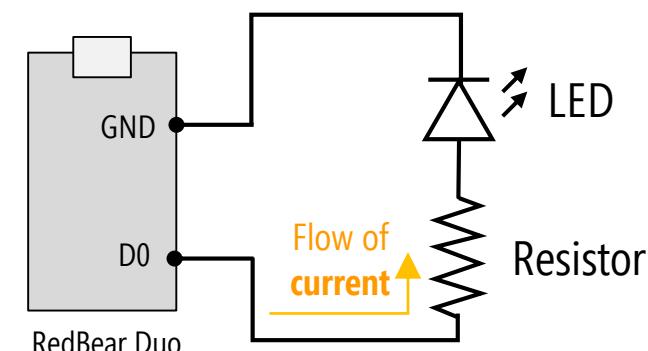
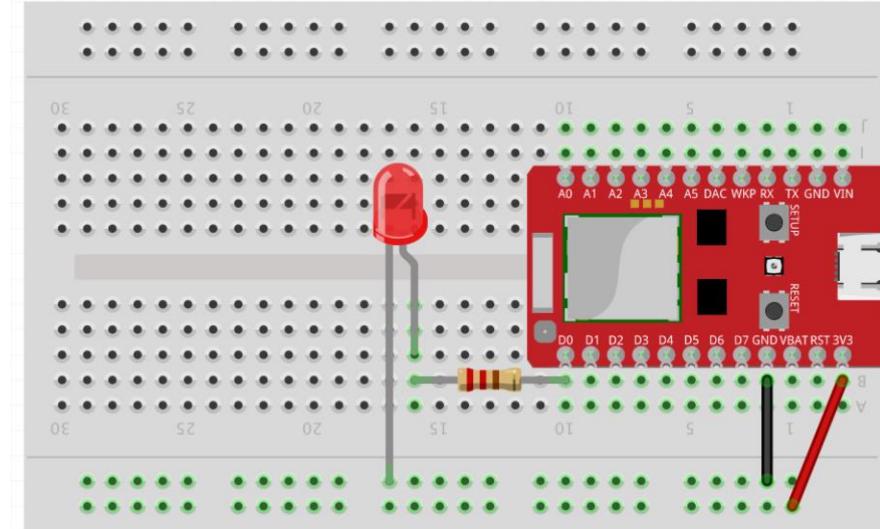
DIGITAL OUTPUT

FLASH LED ON/OFF USING REDBEAR DUO

Previous Circuit: LED Powered via 3.3V pin



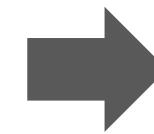
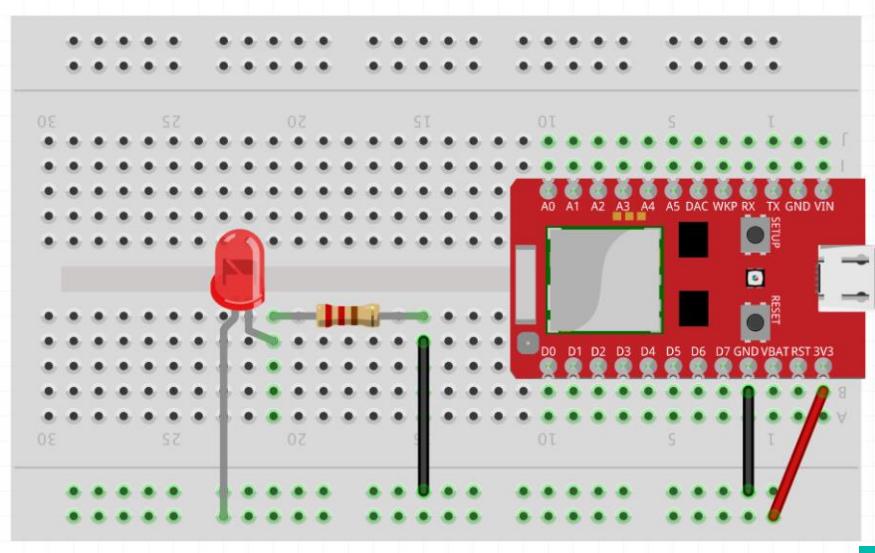
Build Circuit: Flash LED on/off via the D0 pin



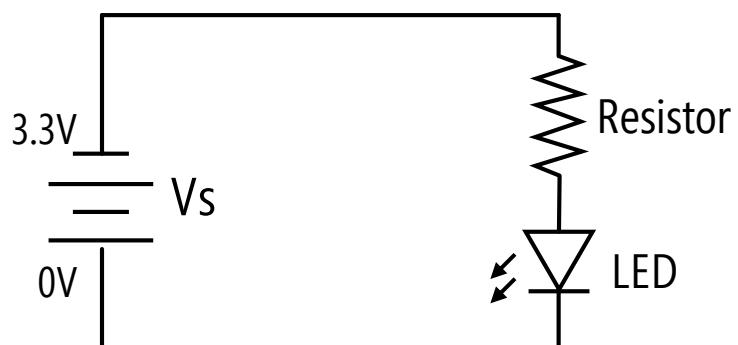
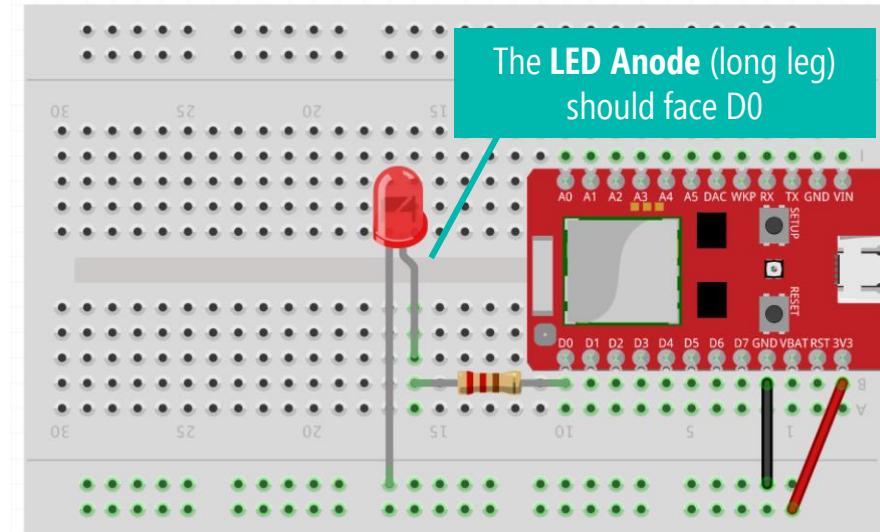
DIGITAL OUTPUT

FLASH LED ON/OFF USING REDBEAR DUO

Previous Circuit: LED Powered via 3.3V pin

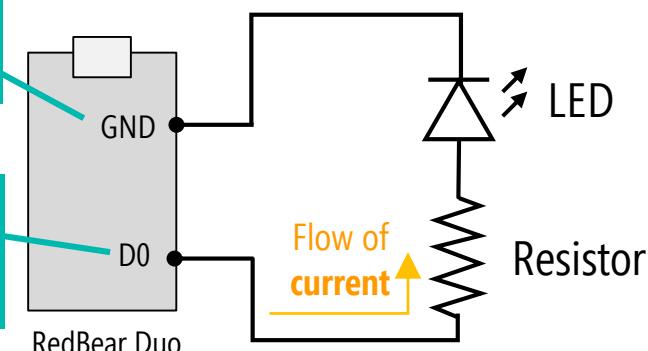


Build Circuit: Flash LED on/off via the D0 pin



GND is always the lowest potential voltage point in our circuit

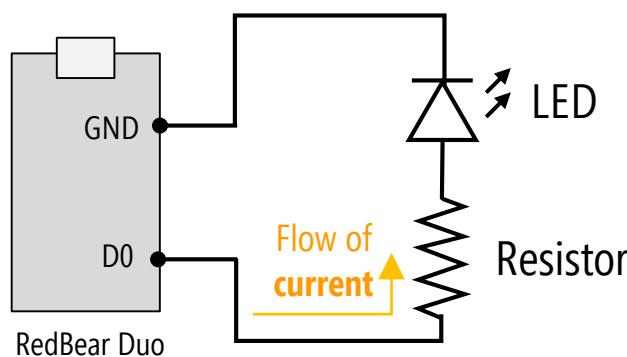
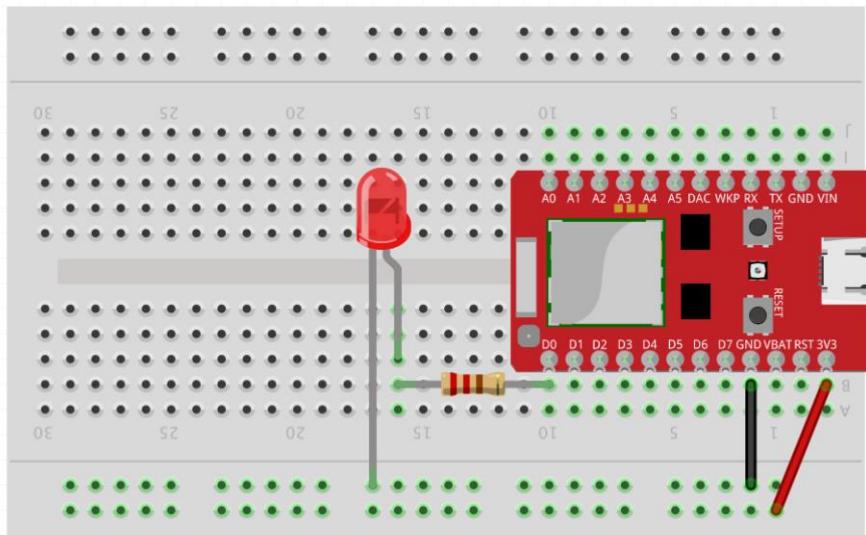
D0 will alternate between 3.3V and 0V. When 3.3V, the LED will turn on.



DIGITAL OUTPUT

FLASH LED ON/OFF USING REDBEAR DUO

Build Circuit: Flash LED on/off via the D0 pin



Write Code: Flash LED on/off via the D0 pin

```
RedBearDuoBlink | Arduino 1.8.5

/*
 * IMPORTANT: When working with the RedBear Duo, you must have this line of
 * code at the top of your program. The default state is SYSTEM_MODE(AUTOMATIC);
 * however, this puts the RedBear Duo in a special cloud-based mode that we
 * are not using. For our purposes, set SYSTEM_MODE(SEMI_AUTOMATIC) or
 * SYSTEM_MODE(MANUAL). See https://docs.particle.io/reference/firmware/photon/#system-modes
 */
SYSTEM_MODE(MANUAL);

const int RED_LED_OUTPUT_PIN = D0;

void setup() {
  pinMode(RED_LED_OUTPUT_PIN, OUTPUT);
}

void loop() {
  // Write out a HIGH value (3.3V in this case as the RedBear Duo is a 3.3V board)
  digitalWrite(RED_LED_OUTPUT_PIN, HIGH);

  // Delay 1000ms (or 1 s)
  delay(1000);

  // Write out a LOW value (0V in this case)
  digitalWrite(RED_LED_OUTPUT_PIN, LOW);

  // Wait another second
  delay(1000);
}

Done Saving.
```

DIGITAL OUTPUT

DIGITAL OUTPUT: PINMODEO

Configures the specified digital I/O pin to behave as either an input or an output. You always do this in **setup()**

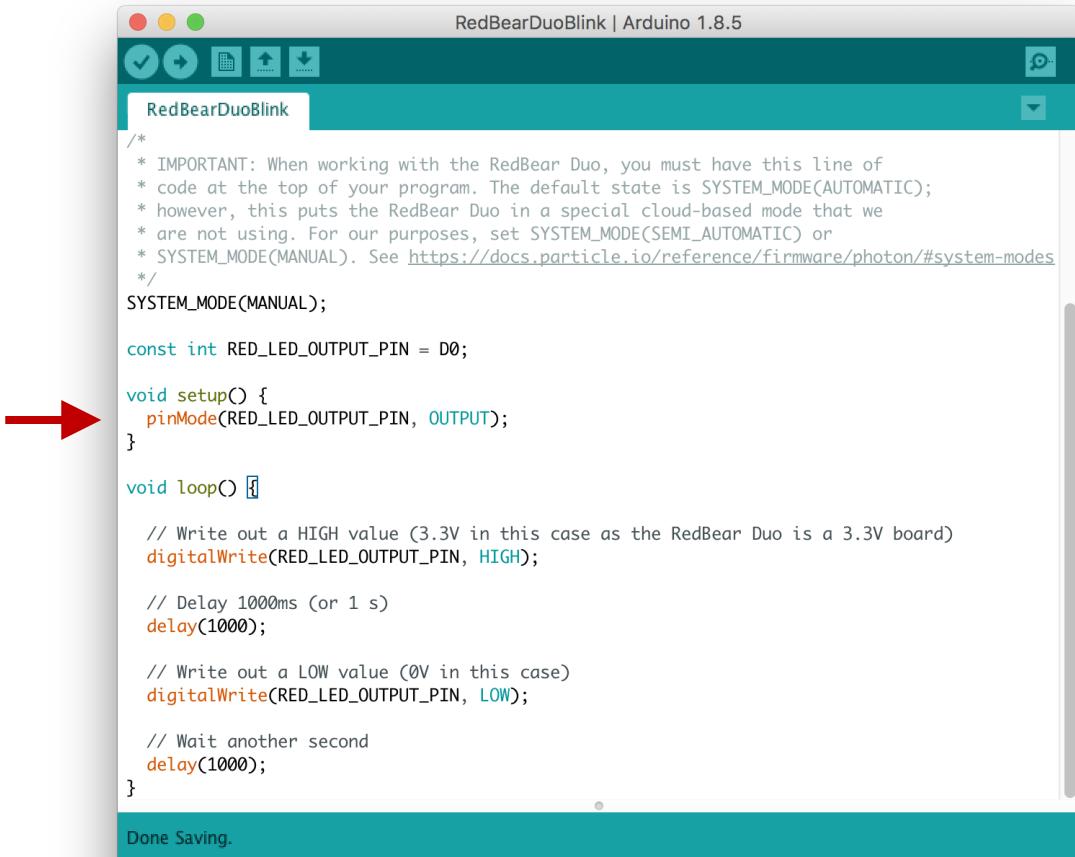
Syntax

`pinMode(pin, mode)`

Parameters

`pin`: the pin number whose mode you wish to set

`value`: INPUT or OUTPUT



```
RedBearDuoBlink | Arduino 1.8.5
RedBearDuoBlink
/*
 * IMPORTANT: When working with the RedBear Duo, you must have this line of
 * code at the top of your program. The default state is SYSTEM_MODE(AUTOMATIC);
 * however, this puts the RedBear Duo in a special cloud-based mode that we
 * are not using. For our purposes, set SYSTEM_MODE(SEMI_AUTOMATIC) or
 * SYSTEM_MODE(MANUAL). See https://docs.particle.io/reference/firmware/photon/#system-modes
 */
SYSTEM_MODE(MANUAL);

const int RED_LED_OUTPUT_PIN = D0;

void setup() {
  pinMode(RED_LED_OUTPUT_PIN, OUTPUT);
}

void loop() {
  // Write out a HIGH value (3.3V in this case as the RedBear Duo is a 3.3V board)
  digitalWrite(RED_LED_OUTPUT_PIN, HIGH);

  // Delay 1000ms (or 1 s)
  delay(1000);

  // Write out a LOW value (0V in this case)
  digitalWrite(RED_LED_OUTPUT_PIN, LOW);

  // Wait another second
  delay(1000);
}

Done Saving.
```

DIGITAL OUTPUT

DIGITAL OUTPUT: digitalWrite()

Writes a HIGH or LOW value to a digital pin

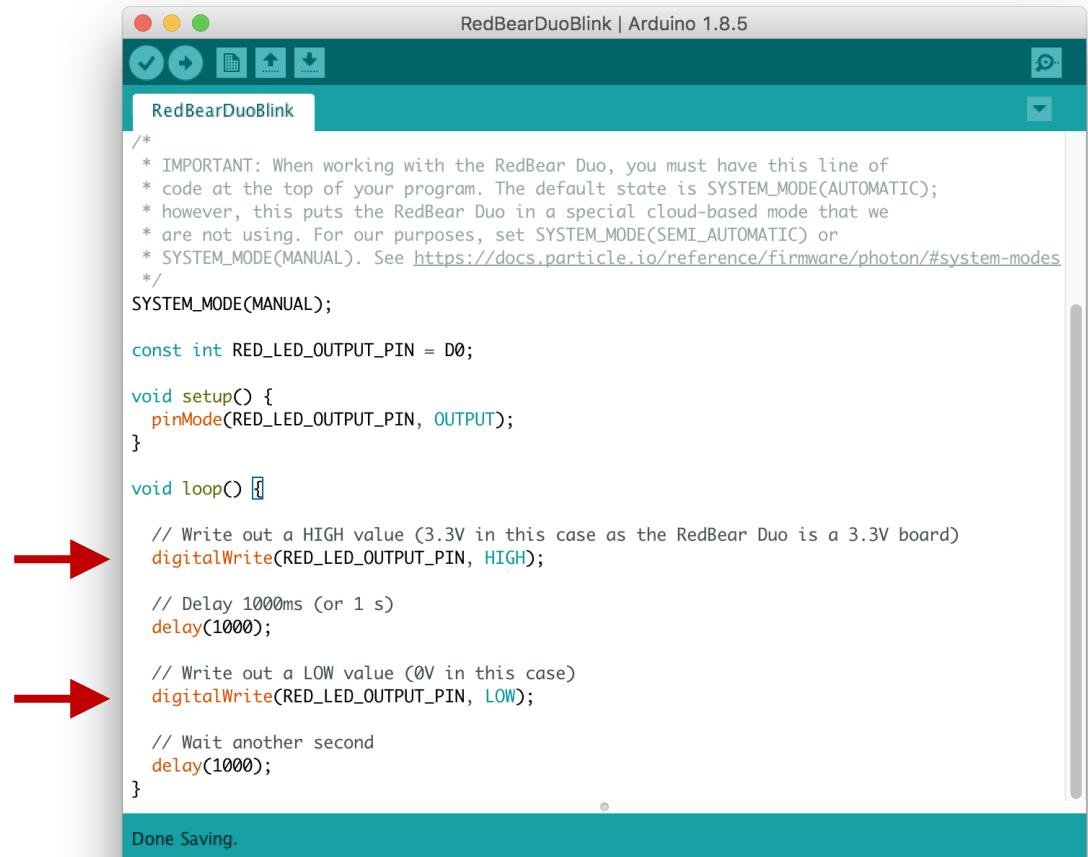
Syntax

`digitalWrite(pin, value)`

Parameters

pin: the pin number

value: HIGH (3.3V) or LOW (0V)



```
RedBearDuoBlink | Arduino 1.8.5
RedBearDuoBlink
/*
 * IMPORTANT: When working with the RedBear Duo, you must have this line of
 * code at the top of your program. The default state is SYSTEM_MODE(AUTOMATIC);
 * however, this puts the RedBear Duo in a special cloud-based mode that we
 * are not using. For our purposes, set SYSTEM_MODE(SEMI_AUTOMATIC) or
 * SYSTEM_MODE(MANUAL). See https://docs.particle.io/reference/firmware/photon/#system-modes
 */
SYSTEM_MODE(MANUAL);

const int RED_LED_OUTPUT_PIN = D0;

void setup() {
  pinMode(RED_LED_OUTPUT_PIN, OUTPUT);
}

void loop() {
  // Write out a HIGH value (3.3V in this case as the RedBear Duo is a 3.3V board)
  digitalWrite(RED_LED_OUTPUT_PIN, HIGH);

  // Delay 1000ms (or 1 s)
  delay(1000);

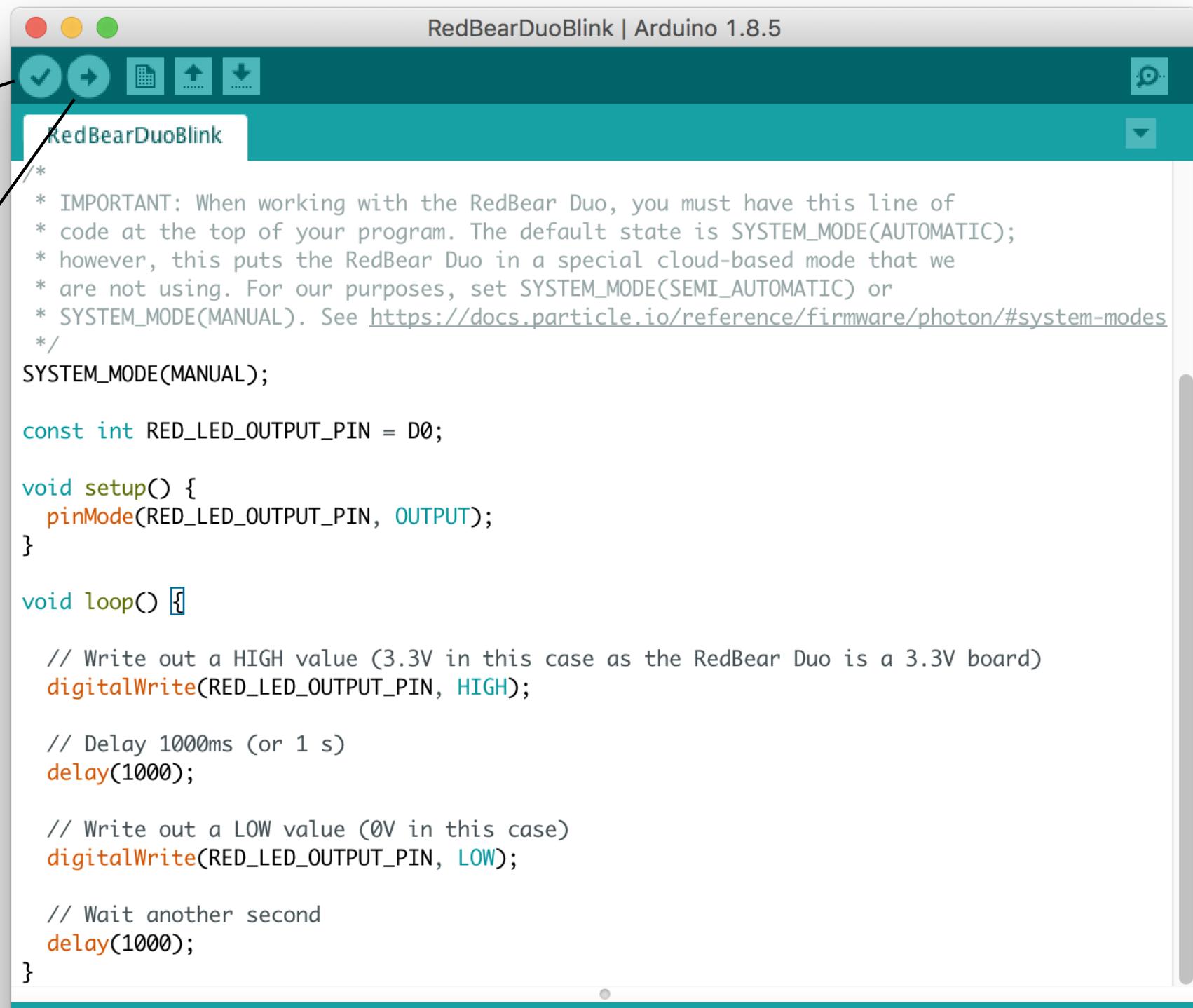
  // Write out a LOW value (0V in this case)
  digitalWrite(RED_LED_OUTPUT_PIN, LOW);

  // Wait another second
  delay(1000);
}

Done Saving.
```

Compile your
program (check for
syntax errors, etc.)

Upload your program
to the Arduino



The screenshot shows the Arduino IDE interface for a project named "RedBearDuoBlink". The title bar reads "RedBearDuoBlink | Arduino 1.8.5". The code editor contains the following sketch:

```
/*
 * IMPORTANT: When working with the RedBear Duo, you must have this line of
 * code at the top of your program. The default state is SYSTEM_MODE(AUTOMATIC);
 * however, this puts the RedBear Duo in a special cloud-based mode that we
 * are not using. For our purposes, set SYSTEM_MODE(SEMI_AUTOMATIC) or
 * SYSTEM_MODE(MANUAL). See https://docs.particle.io/reference/firmware/photon/#system-modes
 */
SYSTEM_MODE(MANUAL);

const int RED_LED_OUTPUT_PIN = D0;

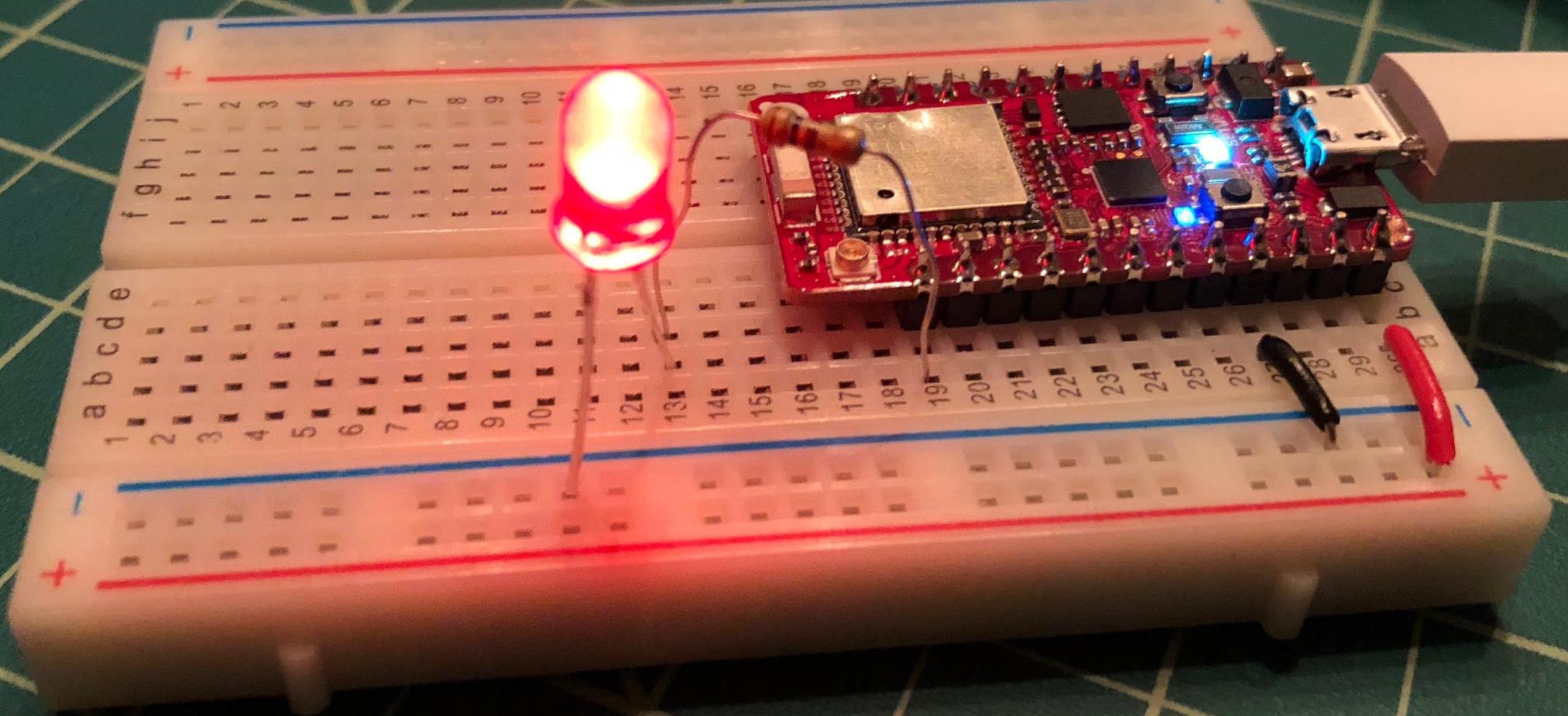
void setup() {
    pinMode(RED_LED_OUTPUT_PIN, OUTPUT);
}

void loop() {
    // Write out a HIGH value (3.3V in this case as the RedBear Duo is a 3.3V board)
    digitalWrite(RED_LED_OUTPUT_PIN, HIGH);

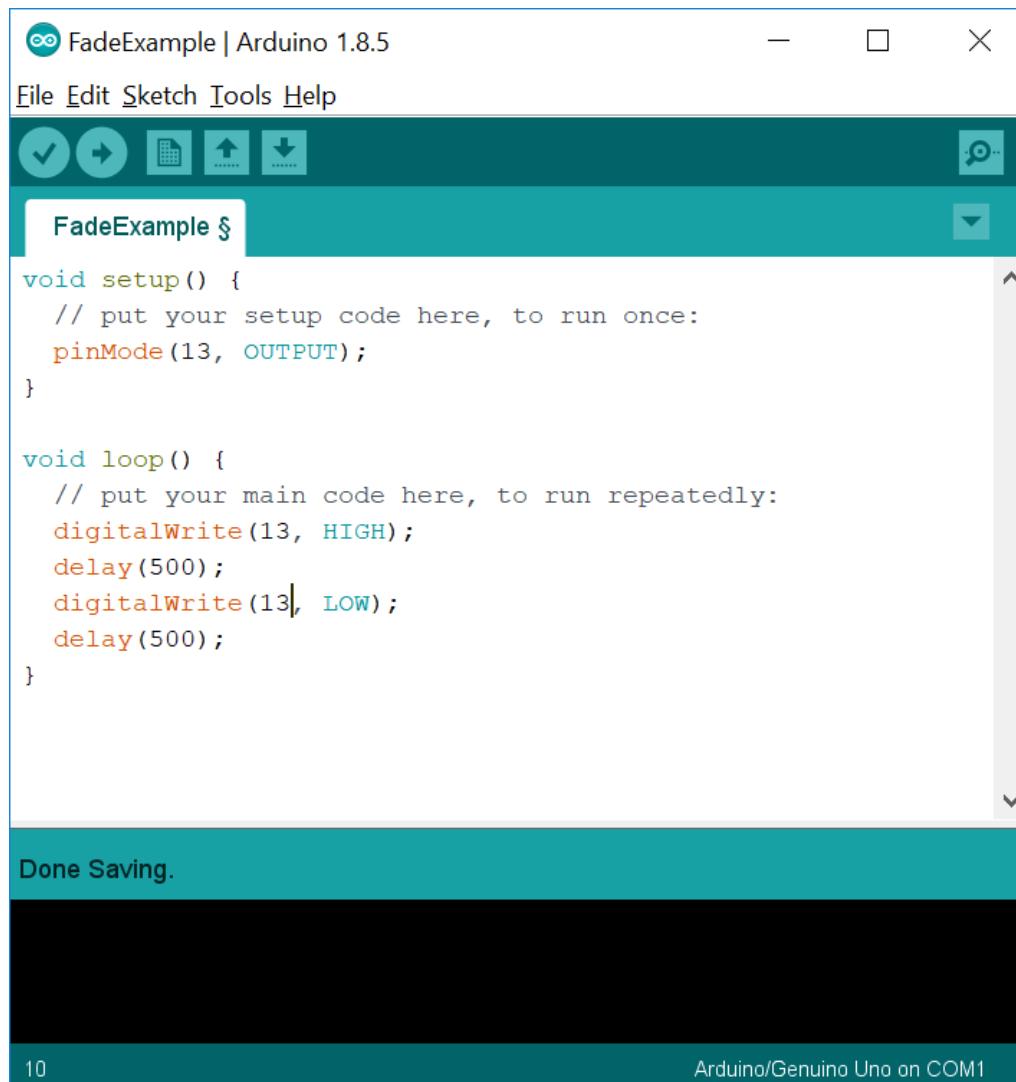
    // Delay 1000ms (or 1 s)
    delay(1000);

    // Write out a LOW value (0V in this case)
    digitalWrite(RED_LED_OUTPUT_PIN, LOW);

    // Wait another second
    delay(1000);
}
```



QUICK TIP: AVOID USING CONSTANTS IN CODE

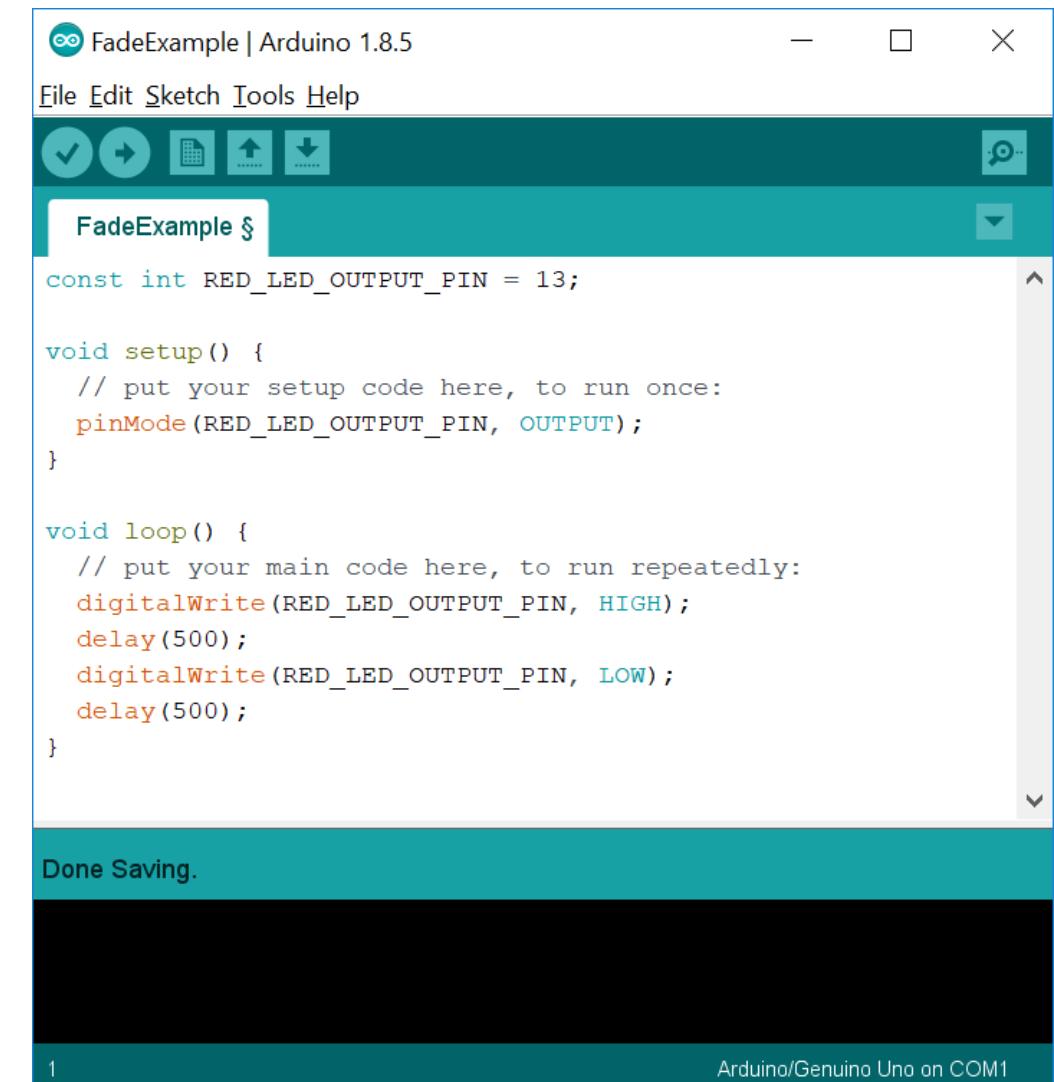
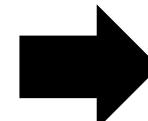


```
void setup() {
  // put your setup code here, to run once:
  pinMode(13, OUTPUT);
}

void loop() {
  // put your main code here, to run repeatedly:
  digitalWrite(13, HIGH);
  delay(500);
  digitalWrite(13, LOW);
  delay(500);
}
```

Done Saving.

Arduino/Genuino Uno on COM1



```
const int RED_LED_OUTPUT_PIN = 13;

void setup() {
  // put your setup code here, to run once:
  pinMode(RED_LED_OUTPUT_PIN, OUTPUT);
}

void loop() {
  // put your main code here, to run repeatedly:
  digitalWrite(RED_LED_OUTPUT_PIN, HIGH);
  delay(500);
  digitalWrite(RED_LED_OUTPUT_PIN, LOW);
  delay(500);
}
```

Done Saving.

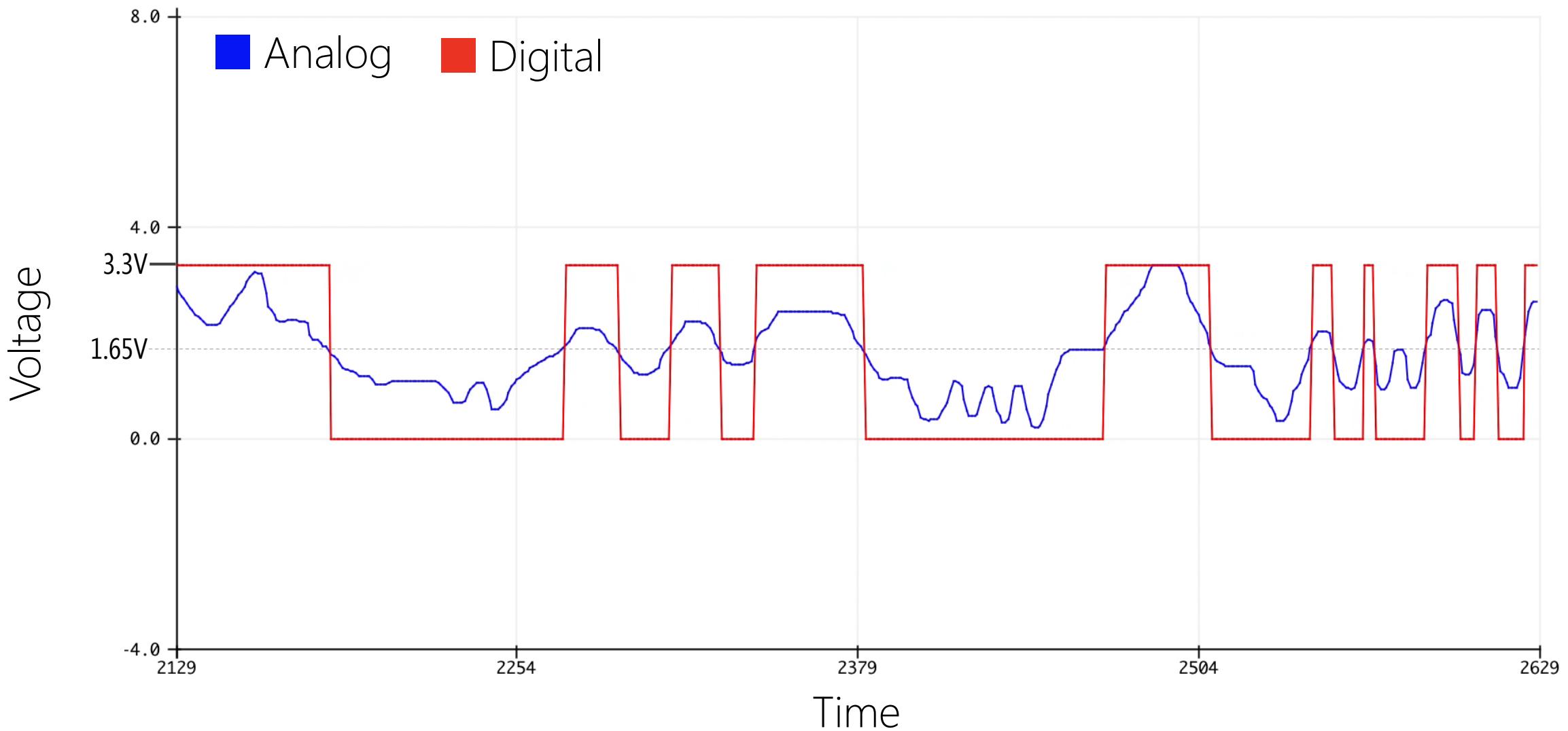
Arduino/Genuino Uno on COM1

Now let's **fade** our LED on and off. To do this, we have to use `analogWrite` rather than `digitalWrite`.

ANALOG VS. DIGITAL

ANALOG VS. DIGITAL

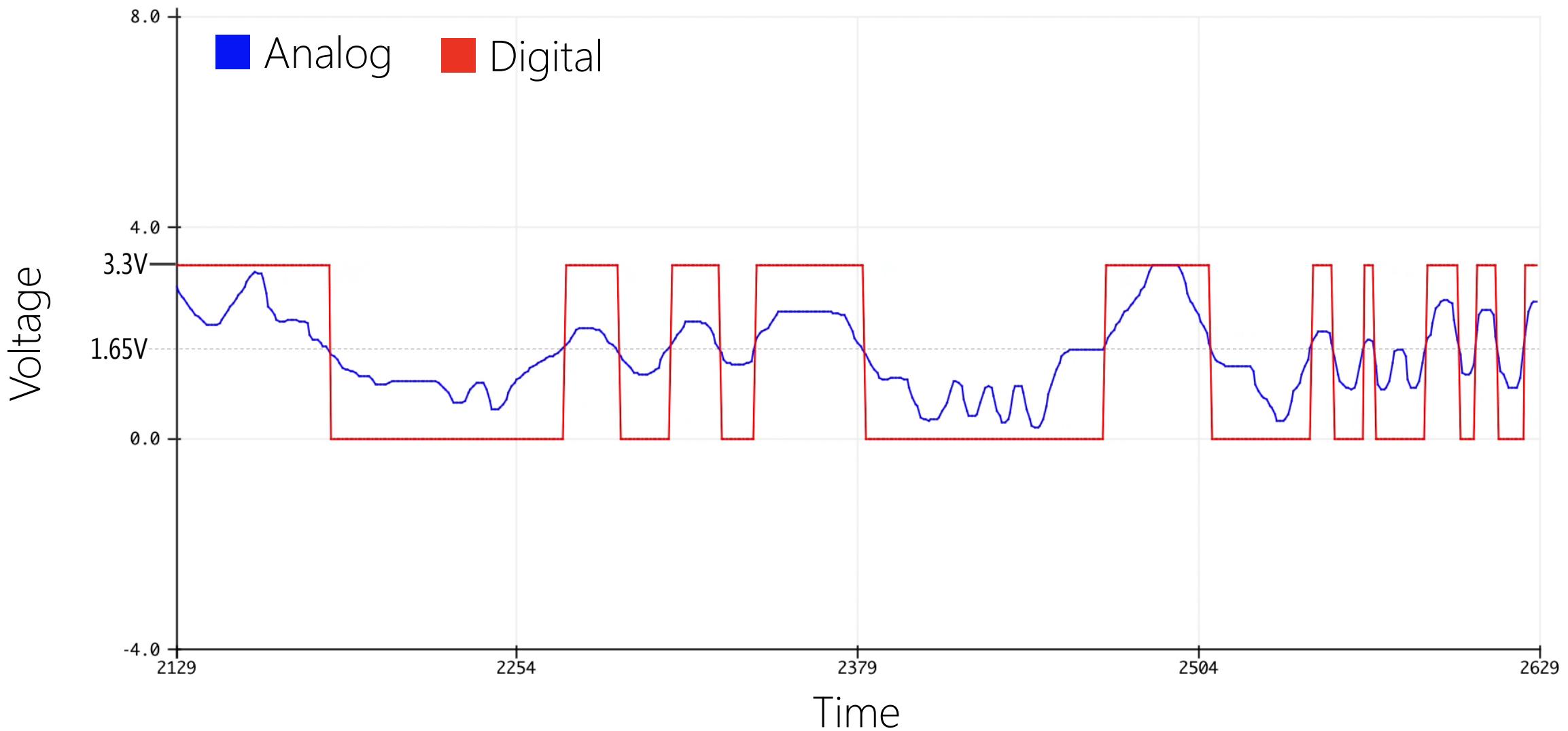
digitalRead and digitalWrite can only be LOW or HIGH corresponding to 0V and 3.3V.



ANALOG VS. DIGITAL

ANALOG VS. DIGITAL

digitalRead and digitalWrite can only be LOW or HIGH corresponding to 0V and 3.3V.

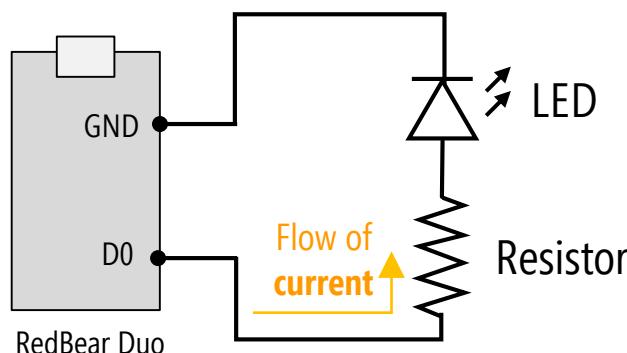
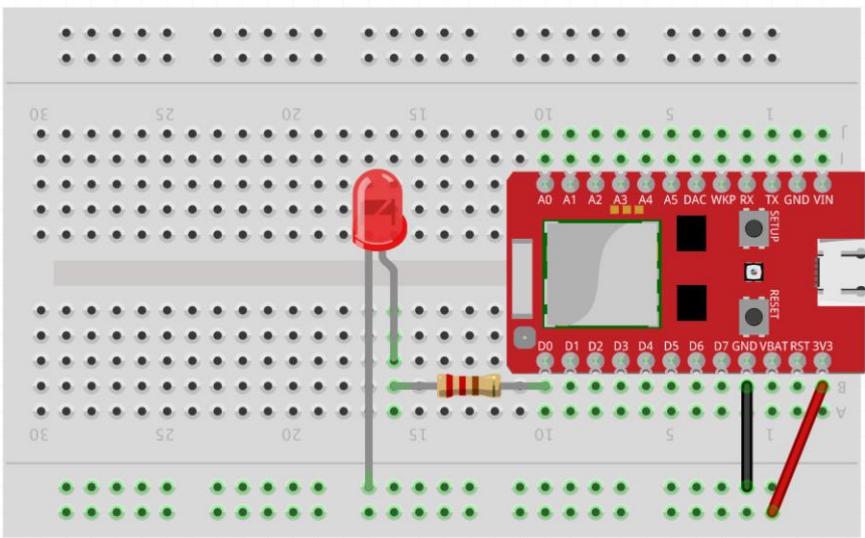


ANALOG OUTPUT

FADE LED ON/OFF USING REDBEAR DUO

The circuit is the same as the last example but the code needs to change.

Circuit: Fade LED on/off via the D0 pin



Write Code: Fade LED on/off via the D0 pin

```
RedBearDuoFade | Arduino 1.8.5

RedBearDuoFade

SYSTEM_MODE(MANUAL);

const int LED_OUTPUT_PIN = D0;

int _brightness = 0;      // how bright the LED is
int _fadeAmount = 5;      // the amount to fade the LED by on each step
int _maxBrightness = 128; // the max allowable analogWrite value is 255

void setup() {
  pinMode(LED_OUTPUT_PIN, OUTPUT);
}

void loop() {

  // set the brightness of pin D0:
  analogWrite(LED_OUTPUT_PIN, _brightness);

  // change the brightness for next time through the loop:
  _brightness = _brightness + _fadeAmount;

  // reverse the direction of the fading at the ends of the fade:
  if (_brightness <= 0 || _brightness >= _maxBrightness) {
    _fadeAmount = -_fadeAmount;
  }

  // wait for 30 milliseconds to see the dimming effect
  delay(30);
}

Done uploading.
```

<https://github.com/jonfroehlich/CSE590Sp2018/tree/master/L05-Arduino/RedBearDuoFade>

ANALOG OUTPUT

ANALOG OUTPUT: analogWrite()

Writes an analog value between 0 and 3.3V to a pin using pulse-width modulation (PWM).

Syntax

```
analogWrite(pin, value)
```

Parameters

pin: the pin to write to.

value: an integer value between 0 & 255 which roughly maps to 0 – 3.3V on the RedBear Duo.



The screenshot shows the Arduino IDE interface with the title bar "RedBearDuoFade | Arduino 1.8.5". The code editor contains the following sketch:

```
RedBearDuoFade
SYSTEM_MODE(MANUAL);

const int LED_OUTPUT_PIN = D0;

int _brightness = 0;    // how bright the LED is
int _fadeAmount = 5;    // the amount to fade the LED by on each step
int _maxBrightness = 128; // the max allowable analogWrite value is 255

void setup() {
  pinMode(LED_OUTPUT_PIN, OUTPUT);
}

void loop() {

  // set the brightness of pin D0:
  analogWrite(LED_OUTPUT_PIN, _brightness);

  // change the brightness for next time through the loop:
  _brightness = _brightness + _fadeAmount;

  // reverse the direction of the fading at the ends of the fade:
  if (_brightness <= 0 || _brightness >= _maxBrightness) {
    _fadeAmount = -_fadeAmount;
  }

  // wait for 30 milliseconds to see the dimming effect
  delay(30);
}

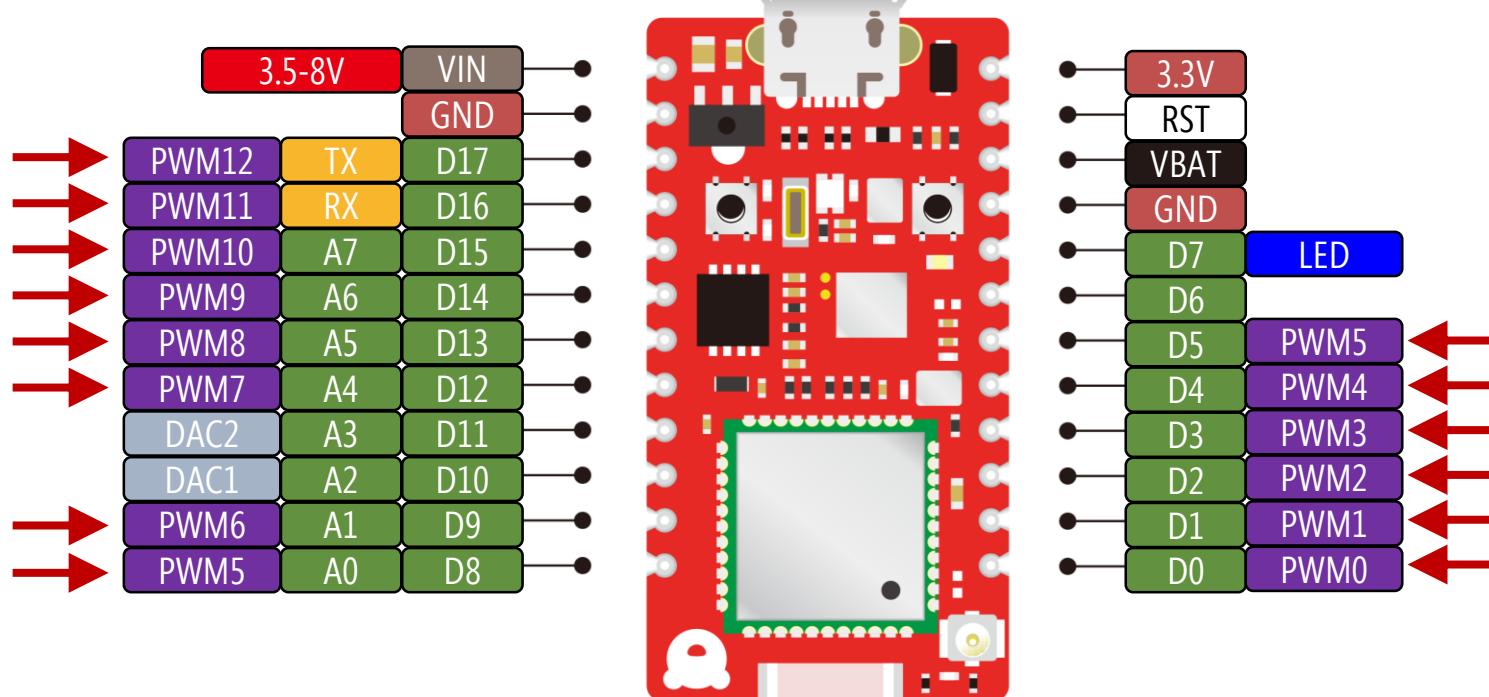
Done uploading.
```

A red arrow points from the word "analogWrite" in the "loop()" section of the code to the corresponding line in the screenshot of the Arduino IDE.

ANALOG OUTPUT

ANALOG OUTPUT: PULSE WIDTH MODULATION

You can only use `analogWrite` on those pins marked with PWM.

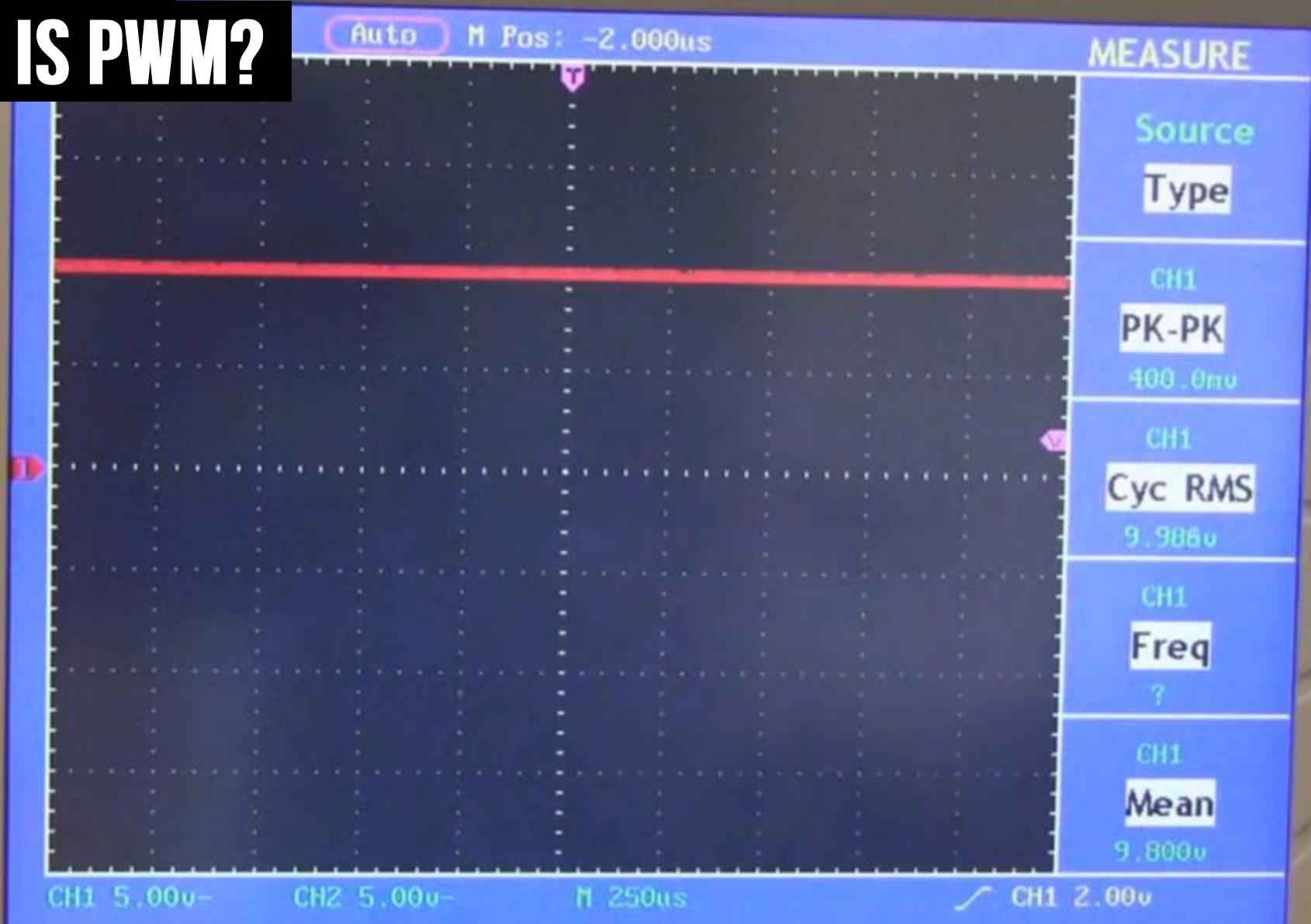


Legend

- AX Analog Input Pin
- DX Digital Input/output Pin
- PWM Supports Analog Out via Pulse Width Modulation

PULSE WIDTH MODULATION

WHAT IS PWM?

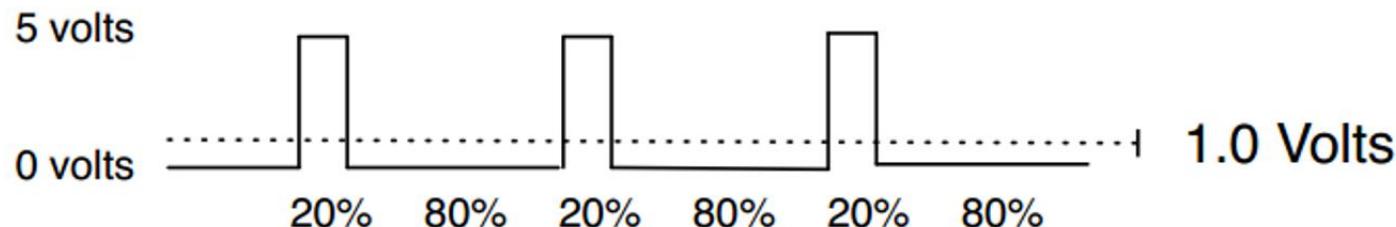
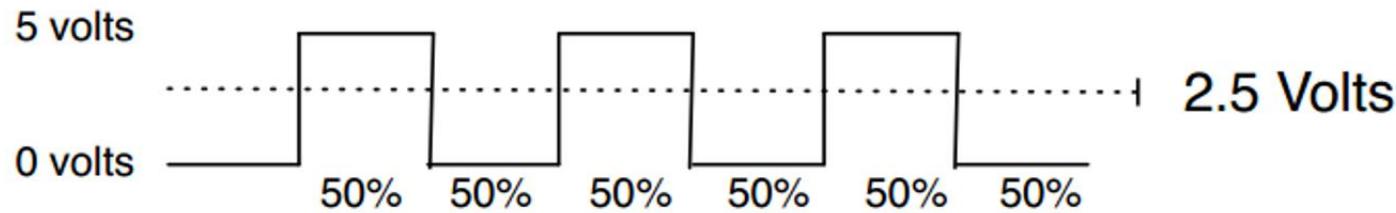
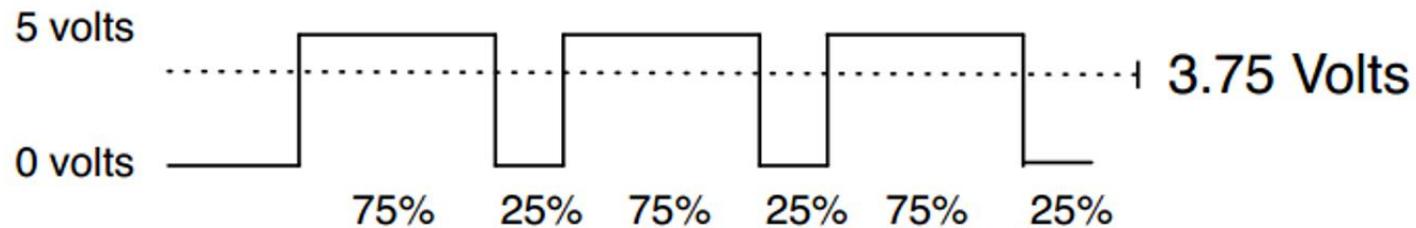


Source: Afrotechmods, <https://youtu.be/YmPziPfaByw>

ANALOG OUTPUT

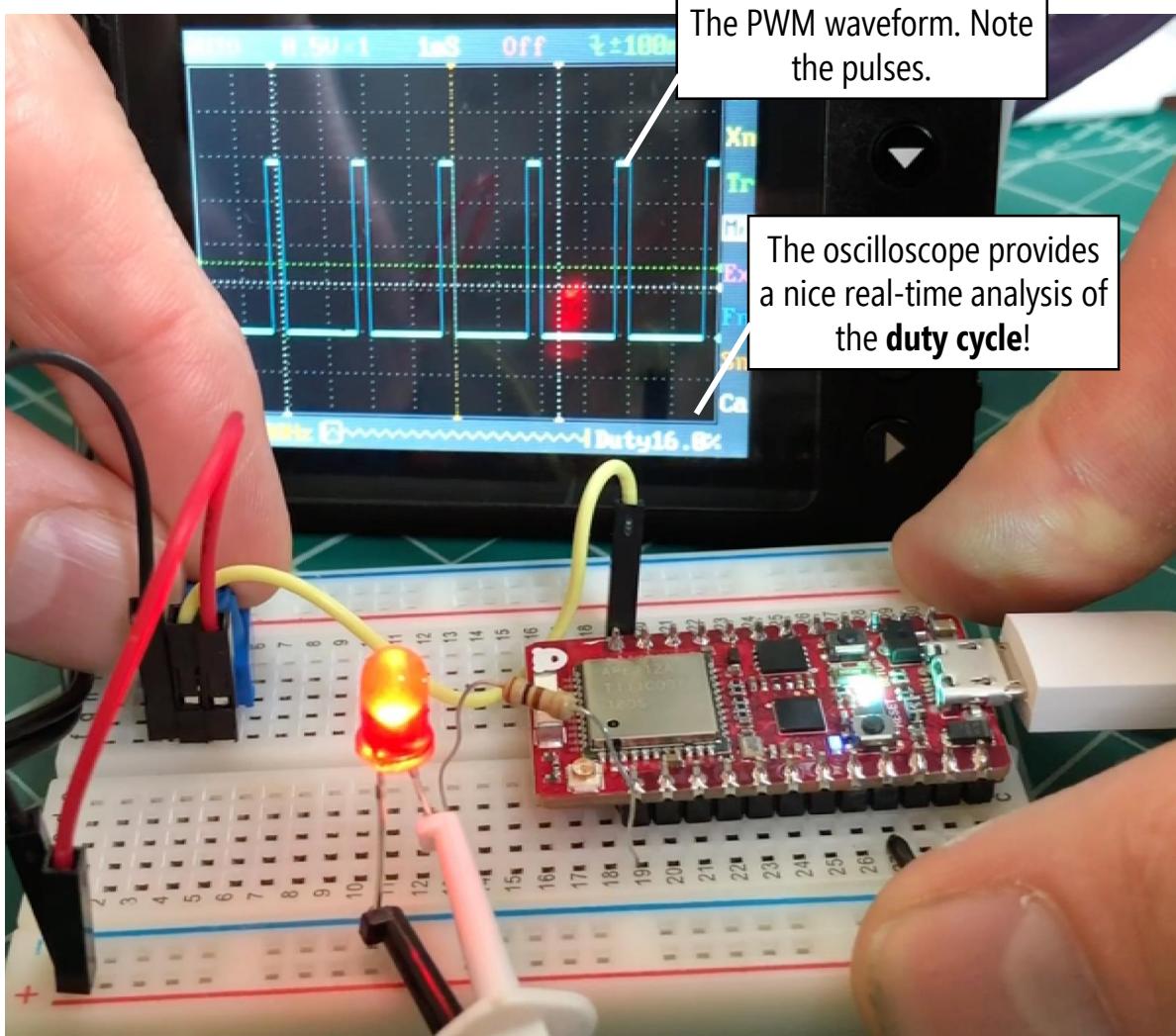
PULSE WIDTH MODULATION

The voltage is max_voltage * duty_cycle_val



ANALOG OUTPUT

VISUALIZING ARDUINO PWM USING AN OSCILLISCOPE



```
RedBearDuoReadPotSetLED | Arduino 1.8.5

RedBearDuoReadPotSetLED

SYSTEM_MODE(MANUAL);

const int LED_OUTPUT_PIN = D0;
const int POT_INPUT_PIN = A0;

void setup() {
  pinMode(LED_OUTPUT_PIN, OUTPUT);
  pinMode(POT_INPUT_PIN, INPUT);
}

void loop() {

  // read the potentiometer value
  int potVal = analogRead(POT_INPUT_PIN);

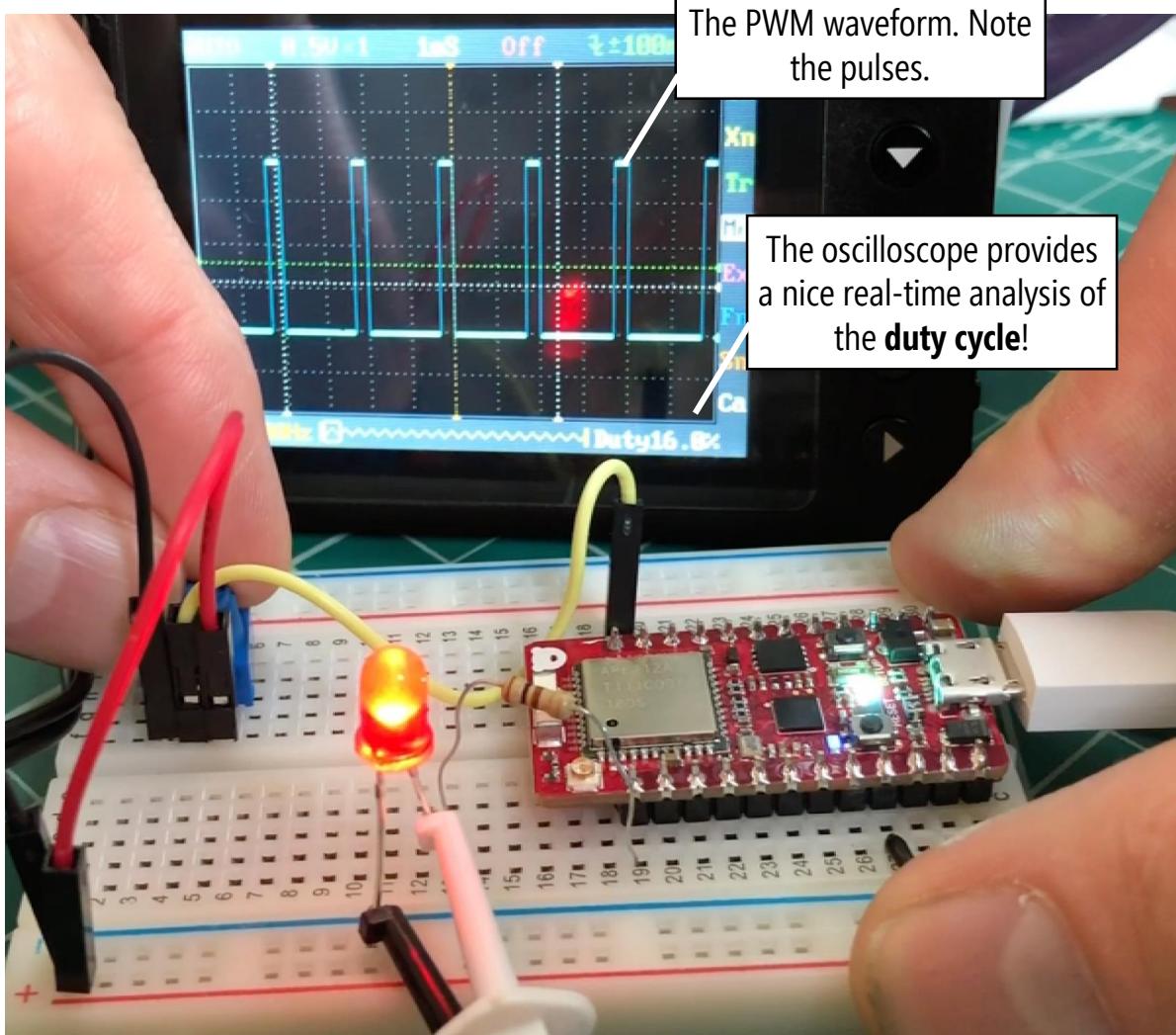
  // the analogRead on the RedBear Duo seems to go from 0 to 4092 (and not 4095
  // as you would expect with a power of two--e.g., 2^12 or 12 bits). On the Arduino
  // Uno, the analogRead ranges from 0 to 1023 (2^10 or 10 bits). Regardless,
  // we need to remap this value linearly from the large range (0-4092) to
  // the smaller range (0-255) since the analogWrite function can only write out
  // 0-255 (a byte--2^8).
  int ledVal = map(potVal, 0, 4092, 0, 255);

  // write out the LED value. This value is translated to voltage by:
  // voltageVal = max_voltage * val/255 or voltageVal = 3.3V * val/255 in
  // the case of the RedBear Duo
  analogWrite(LED_OUTPUT_PIN, ledVal);

  delay(100);
}
```

ANALOG OUTPUT

VISUALIZING ARDUINO PWM USING AN OSCILLISCOPE



```
RedBearDuoReadPotSetLED | Arduino 1.8.5

RedBearDuoReadPotSetLED

SYSTEM_MODE(MANUAL);

const int LED_OUTPUT_PIN = D0;
const int POT_INPUT_PIN = A0;

void setup() {
  pinMode(LED_OUTPUT_PIN, OUTPUT);
  pinMode(POT_INPUT_PIN, INPUT);
}

void loop() {

  // read the potentiometer value
  int potVal = analogRead(POT_INPUT_PIN);

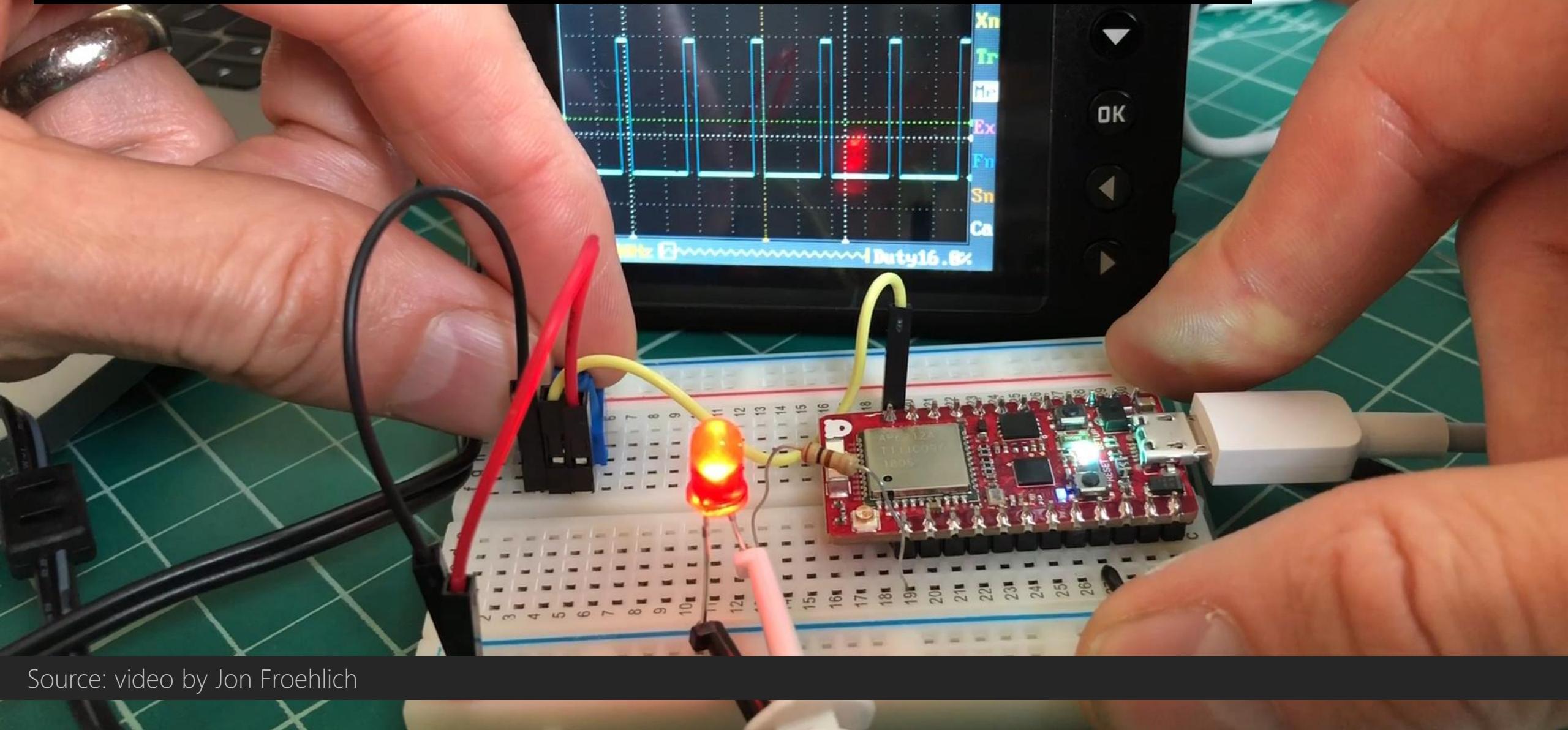
  // the analogRead on the RedBear Duo seems to go from 0 to 4092 (and not 4095
  // as you would expect with a power of two--e.g., 2^12 or 12 bits). On the Arduino
  // Uno, the analogRead ranges from 0 to 1023 (2^10 or 10 bits). Regardless,
  // we need to divide by 256 to get the duty cycle (0 to 4092 to
  // the small 0-255 range)
  int ledVal =
    // write out
    // voltageVal = max_voltage * val/255 or voltageVal = 3.3V * val/255 in
    // the case of the RedBear Duo
    analogWrite(LED_OUTPUT_PIN, ledVal);

  delay(100);
}
```

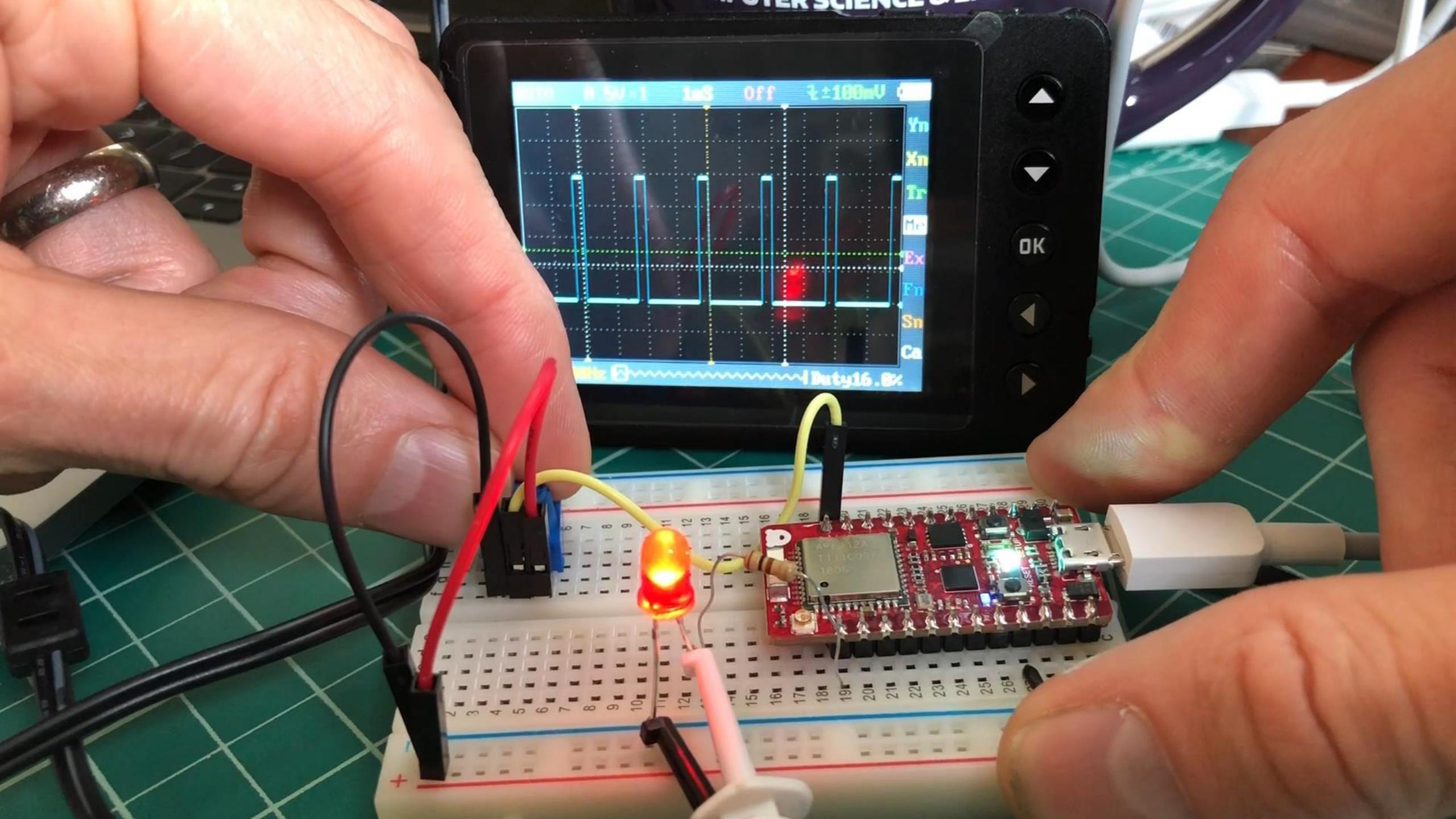
The **analogWrite** call sets the **duty cycle** of the PWM waveform. Note: you cannot set the PWM frequency. See the video on the next slide

PULSE WIDTH MODULATION

VISUALIZING ARDUINO PWM USING AN OSCILLISCOPE



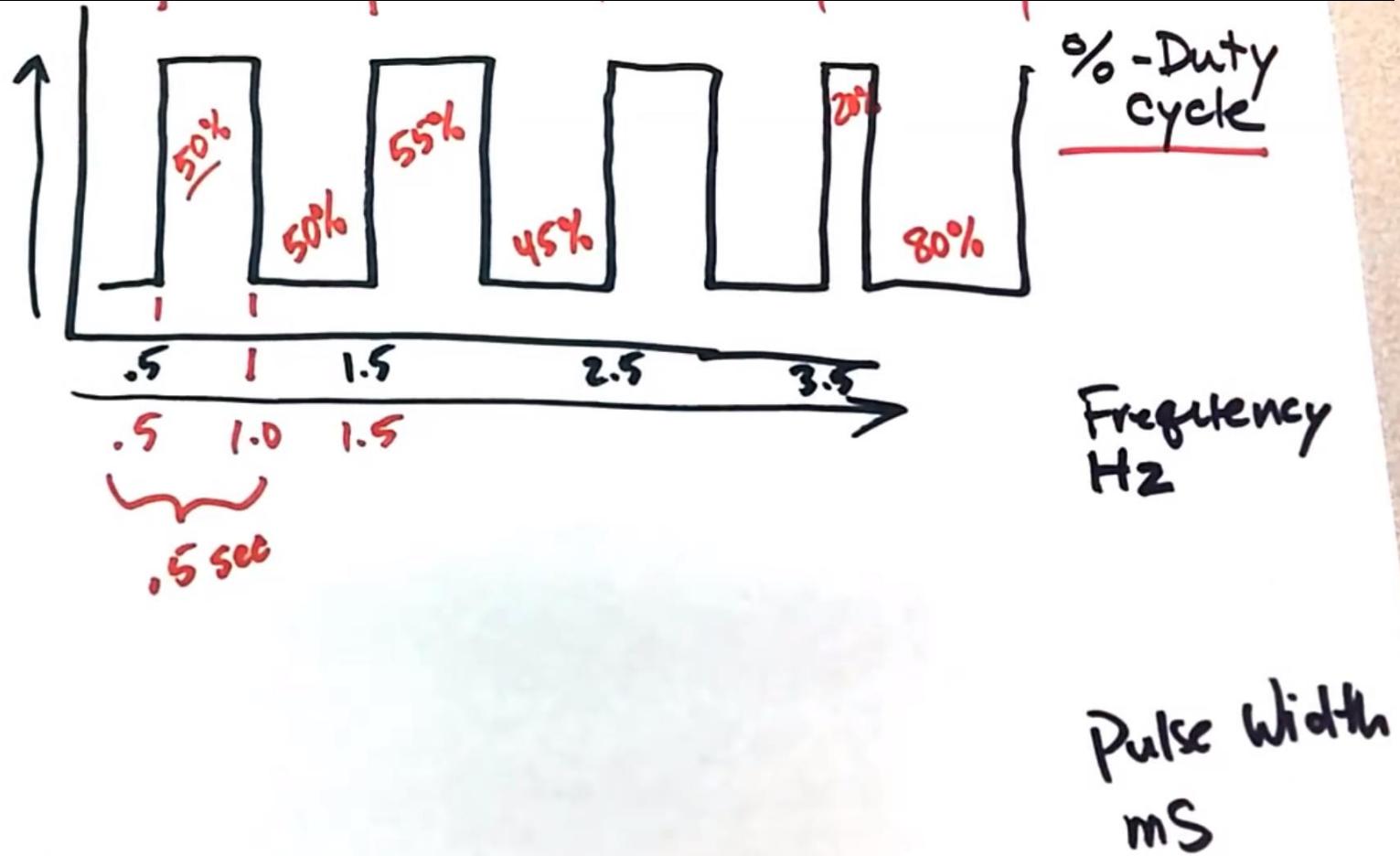
Source: video by Jon Froehlich



Phew, OK, we get it! **Arduino does not actually write out a truly analog signal.** Instead, it "fakes" it by using PWM. When we use analogWrite, we are changing the duty cycle but the waveform frequency is fixed at ~500Hz (see video!). Now that we've got that covered, you don't really need to think about this distinction anymore—at least not for A3.

PULSE WIDTH MODULATION

ANOTHER GREAT VIDEO ON PWM, DUTY CYCLES, & FREQUENCY



Let's switch things up. We've been using a RED LED for all of the examples so far but of course there is a ton of different kinds of output (sound, vibration, motors, etc.). Let's stick with light for now and **play around with an RGB LED.**

ANALOG OUTPUT

USING AN RGB LED

I've already pointed you to the fantastic series of [Adafruit Arduino tutorials](#), including this one on [RGB LEDs](#). But I'm going to show you how to use the particular RGB LED in our kits with the RedBear Duo. Note: as with other material covered in class, please feel free to Google around for tutorials, answers to questions, and please post questions on Canvas! ☺

The screenshot shows the Adafruit website with a black header containing the Adafruit logo, navigation links for SHOP, BLOG, LEARN, FORUMS, VIDEOS, and ADABOX, and a search bar. Below the header, the page title is "Arduino Lesson 3. RGB LEDs". The main content area features a photograph of an Arduino Uno connected to a breadboard with an RGB LED. The breadboard has several resistors and jumper wires. The text "Overview" is followed by "In this lesson, you will learn how to use a RGB (Red Green Blue) LED with an Arduino. You will use the `analogWrite` function of Arduino to control the color of the LED." To the right, there are two product cards: "Adafruit METRO 328 Fully Assembled - Arduino IDE compatible" for \$17.50 and "Premium Male/Male Jumper Wires - 40 x 6" (150mm)" for \$3.95, both with "ADD TO CART" buttons. At the bottom, there's a "Half-size breadboard" image.

Components **LEDS** **ARDUINO COMPATIBLES / LEARN ARDUINO** **LEARN ARDUINO (4 of 18)**

Overview

by Simon Monk

In this lesson, you will learn how to use a RGB (Red Green Blue) LED with an Arduino. You will use the `analogWrite` function of Arduino to control the color of the LED.

Arduino Lesson 3. RGB LEDs

Learn Arduino, Lesson 3. RGB LEDs

[Overview](#)

[Parts](#)

[Breadboard Layout](#)

[Colors](#)

[Arduino Sketch](#)

[Using Internet Colors](#)

[Theory \(PWM\)](#)

[Other Things to Do](#)

Adafruit METRO 328 Fully Assembled - Arduino IDE compatible
\$17.50 [ADD TO CART](#)

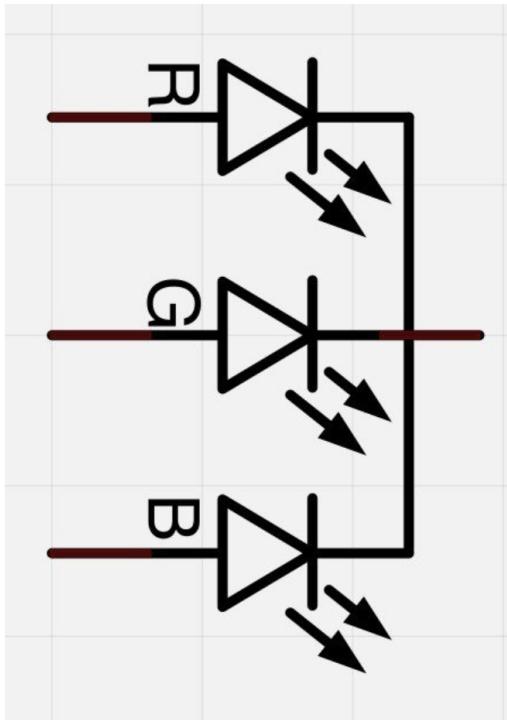
Premium Male/Male Jumper Wires - 40 x 6" (150mm)
\$3.95 [ADD TO CART](#)

Half-size breadboard

USING AN RGB LED: FROM ADAFRUIT TUTORIAL

Breadboard Layout

The RGB LED has four leads. There is one lead going to the positive connection of each of the single LEDs within the package and a single lead that is connected to all three negative sides of the LEDs.

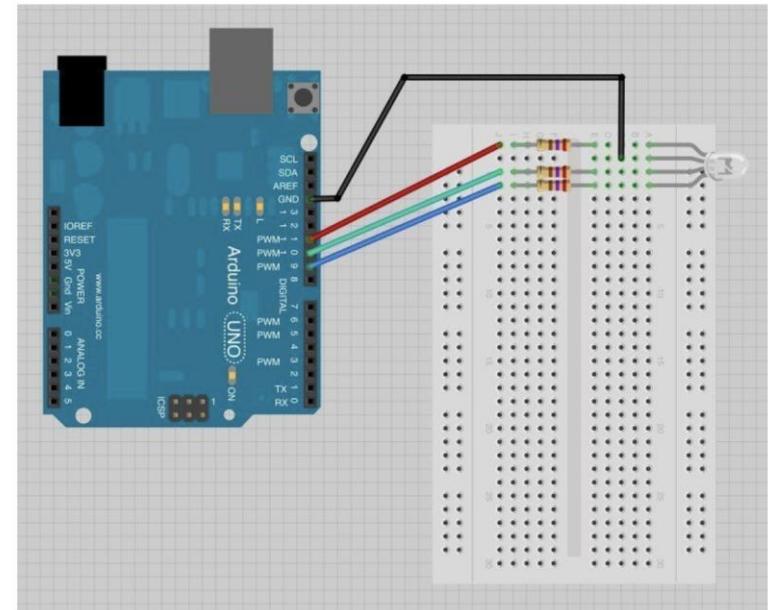


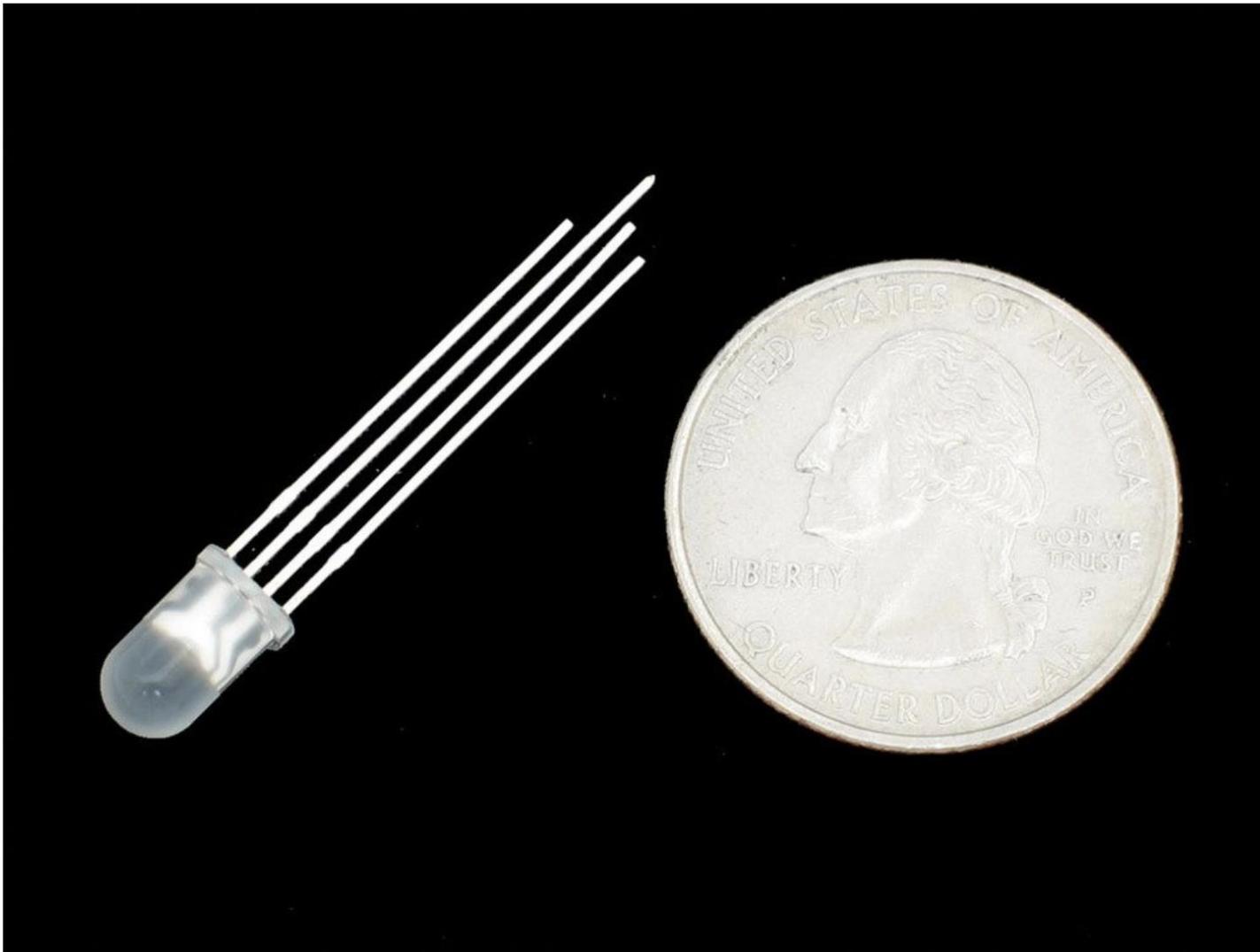
by [Simon Monk](#)

The common negative connection of the LED package is the second pin from the flat side of the LED package. It is also the longest of the four leads. This lead will be connected to ground.

Each LED inside the package requires its own 270Ω resistor to prevent too much current flowing through it. The three positive leads of the LEDs (one red, one green and one blue) are connected to Arduino output pins using these resistors.

! If you are using a common ANODE LED instead of common CATHODE, connect the long pin to +5 instead of ground



[LEDS / BARE LEDS](#) / DIFFUSED RGB (TRI-COLOR) LED

Diffused RGB (tri-color) LED - Common Anode

PRODUCT ID: 159

\$2.00

49 IN STOCK

1

[ADD TO CART](#)

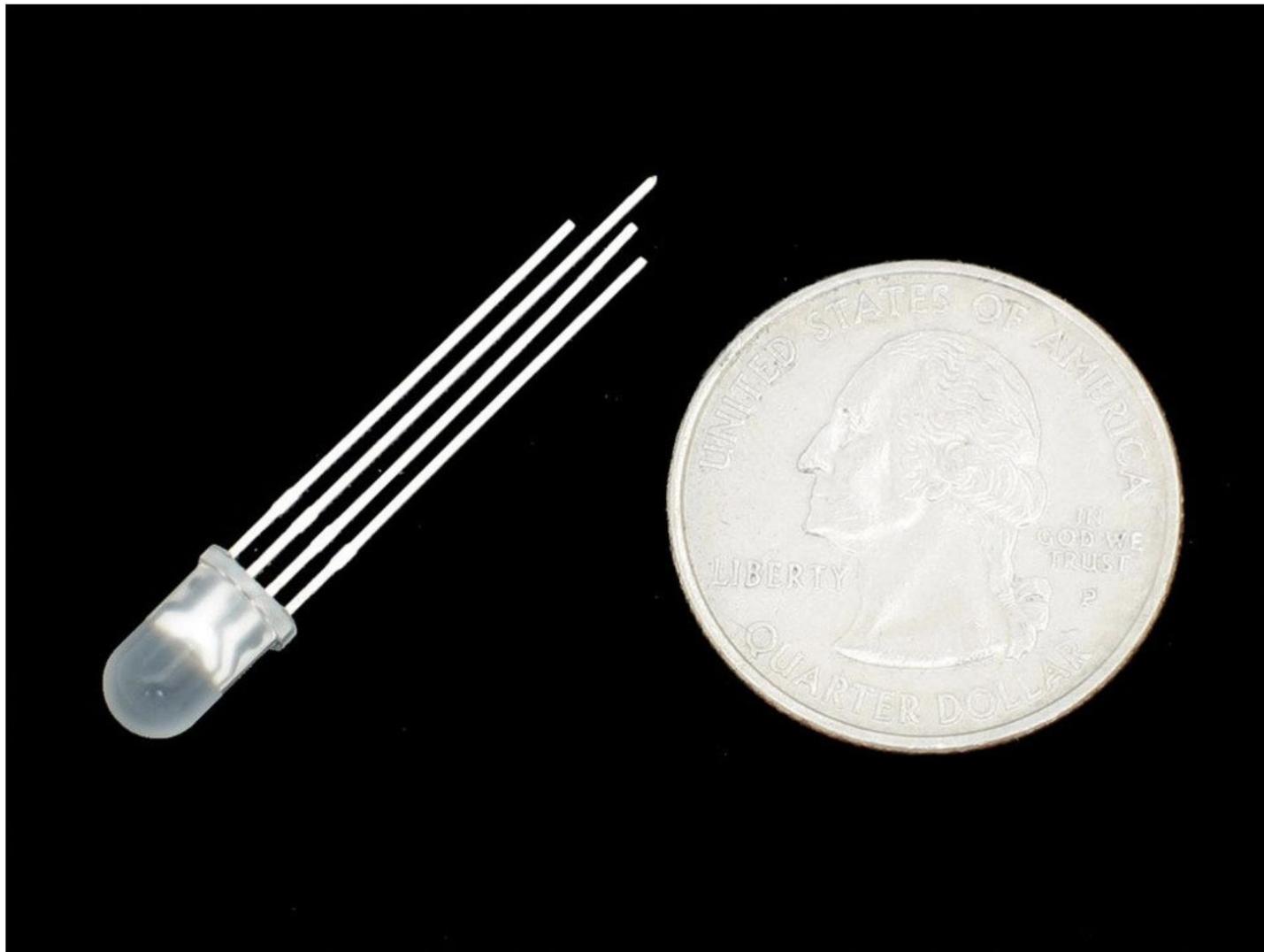
QTY DISCOUNT

1-9 \$2.00

10-49 \$1.75

50+ \$1.50

[ADD TO WISHLIST](#)[DESCRIPTION](#)[TECHNICAL DETAILS](#)[LEARN](#)

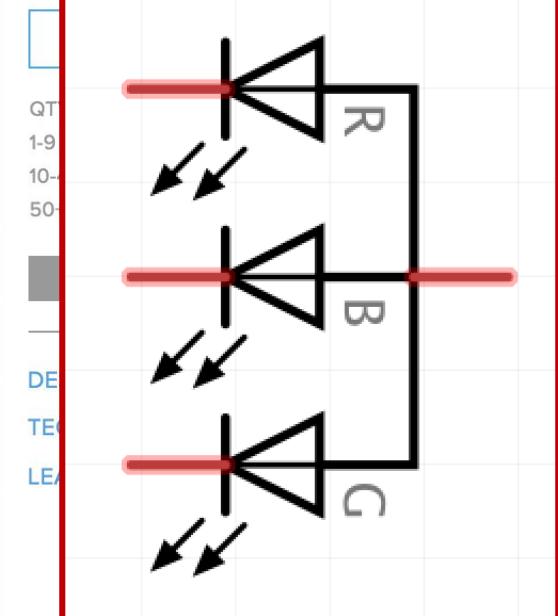
[LEDS / BARE LEDS](#) / DIFFUSED RGB (TRI-COLOR) LED

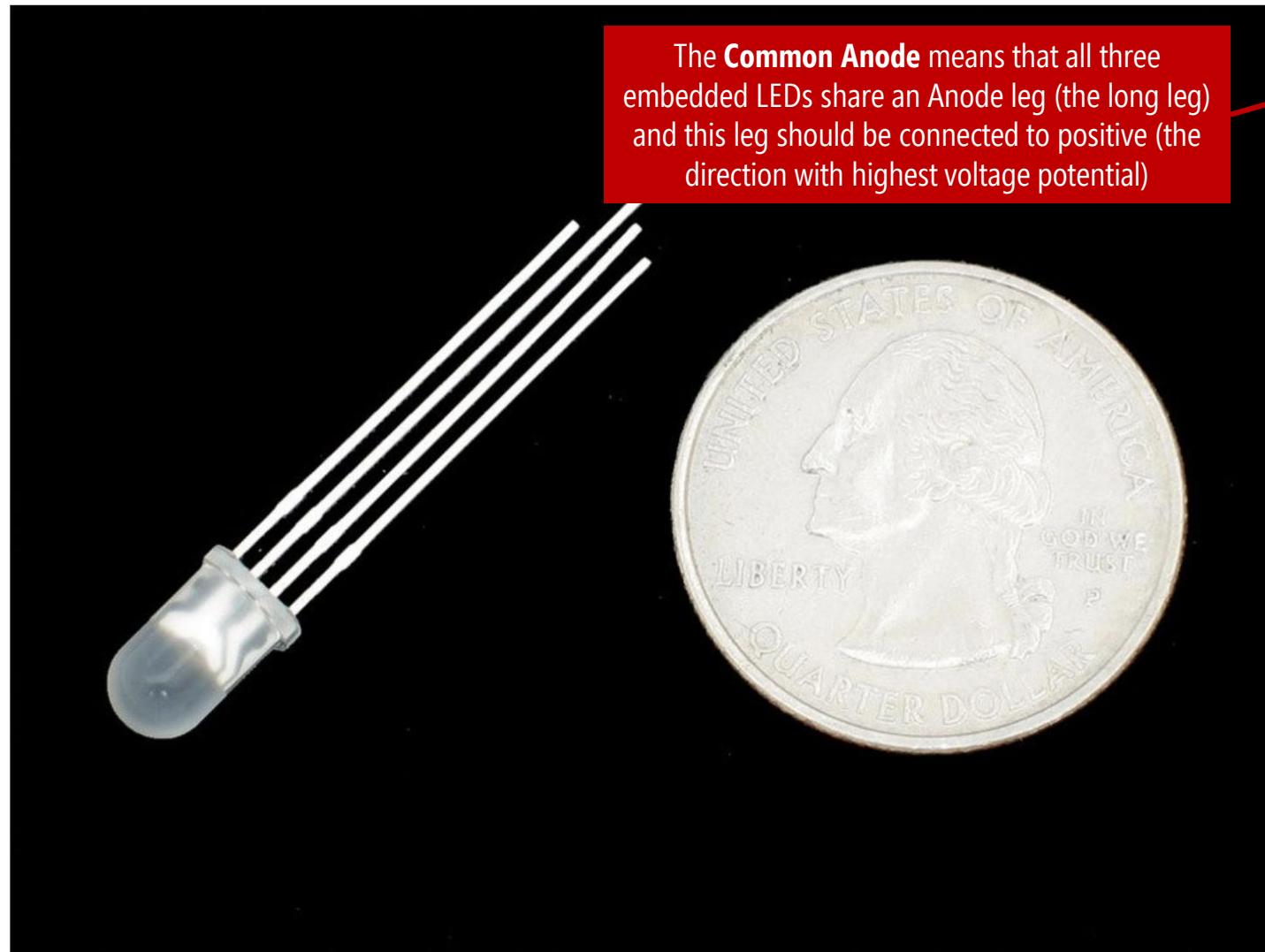
Diffused RGB (tri-color) LED - Common Anode

PRODUCT ID: 159

\$2.00

49 IN STOCK



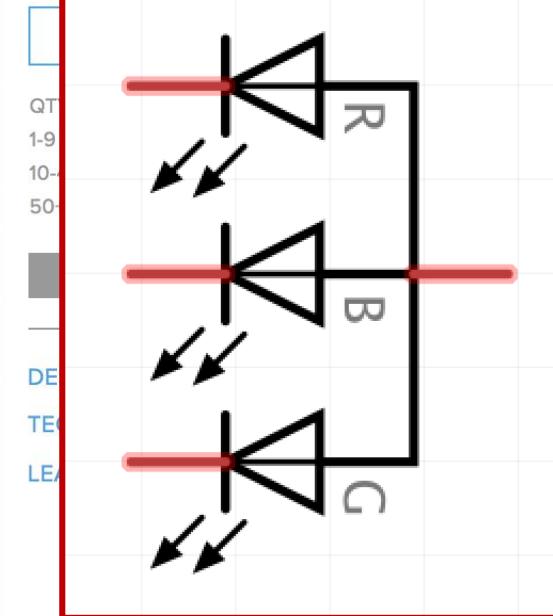


Diffused RGB (tri-color)
LED - Common Anode

PRODUCT ID: 159

\$2.00

49 IN STOCK



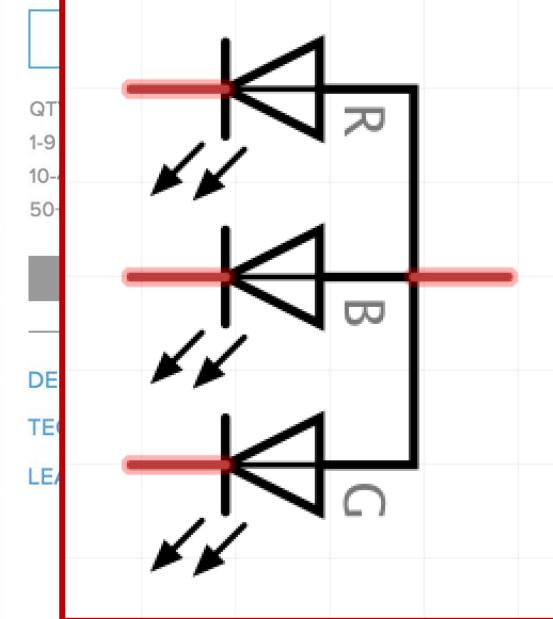


Diffused RGB (tri-color) LED - Common Anode

PRODUCT ID: 159

\$2.00

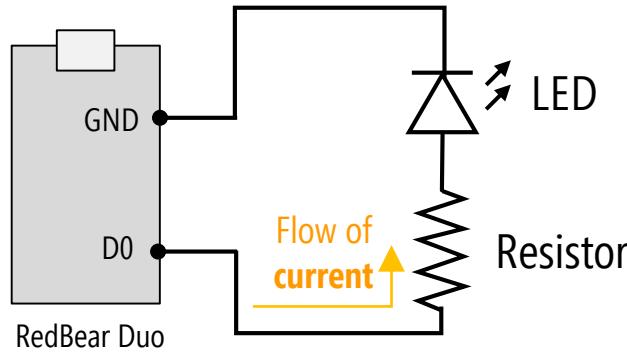
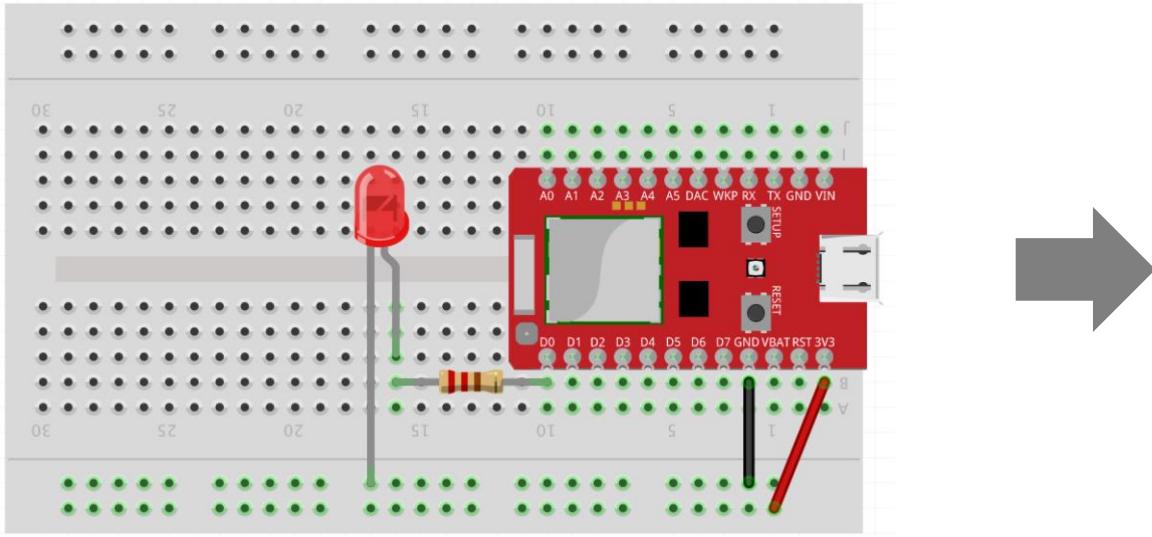
49 IN STOCK



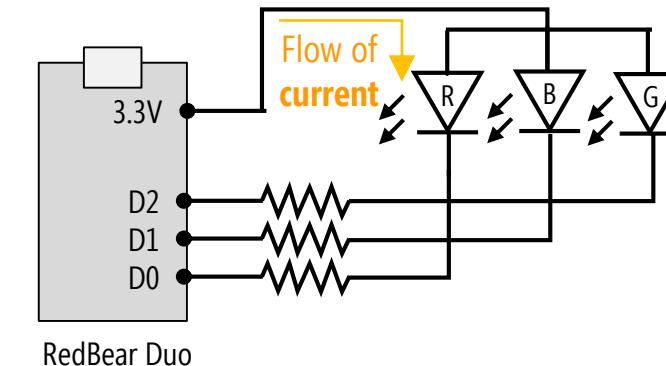
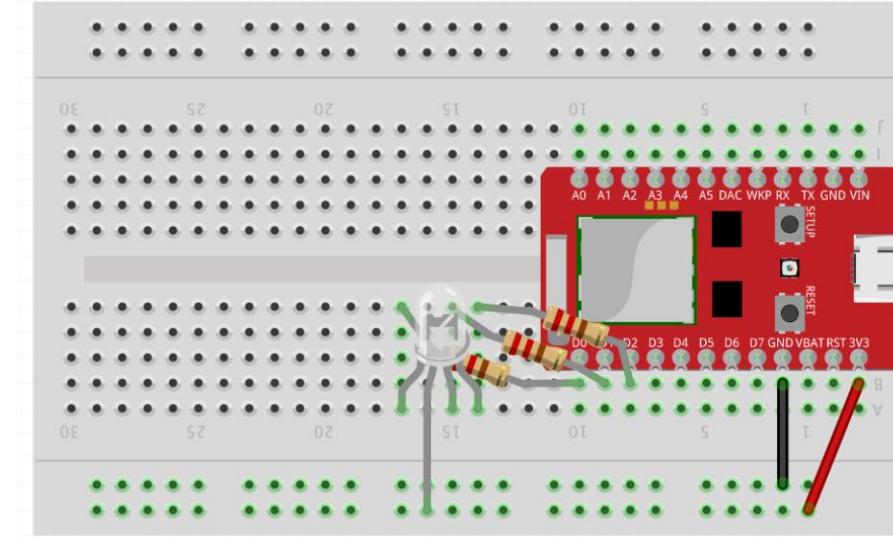
ANALOG OUTPUT

USING AN RGB LED: THE CIRCUIT

Old Circuit: Fade LED on/off via the D0 pin



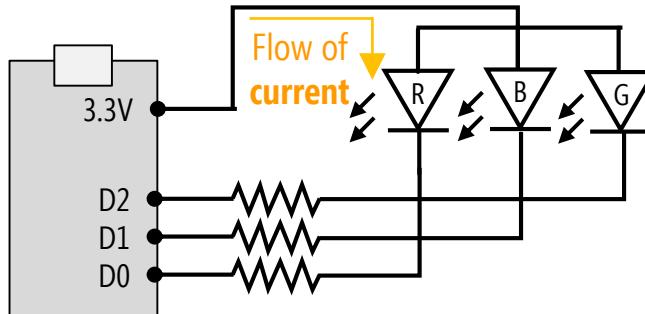
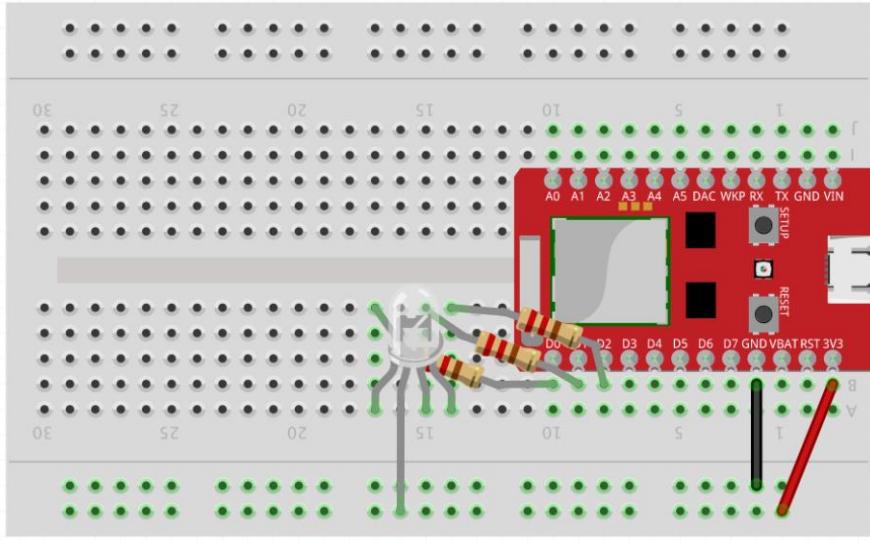
New Circuit: Set R, B, G values via D0, D1, & D2



ANALOG OUTPUT

USING AN RGB LED: THE CODE

Circuit: Set R, B, G values via D0, D1, & D2



RedBear Duo

RedBearDuoRGB §

```
#define COMMON_ANODE 1

const int RGB_RED_PIN = D0;
const int RGB_GREEN_PIN = D1;
const int RGB_BLUE_PIN = D2;
const int DELAY = 1000; // delay between changing colors

void setup() {
    pinMode(RGB_RED_PIN, OUTPUT);
    pinMode(RGB_GREEN_PIN, OUTPUT);
    pinMode(RGB_BLUE_PIN, OUTPUT);

    // Turn on Serial so we can verify expected colors via Serial Monitor
    Serial.begin(9600);
}

void loop() {
    Serial.println("Color=Red");
    setColor(255, 0, 0); // red
    delay(DELAY);

    Serial.println("Color=Green");
    setColor(0, 255, 0); // green
    delay(DELAY);

    Serial.println("Color=Blue");
    setColor(0, 0, 255); // blue
    delay(DELAY);

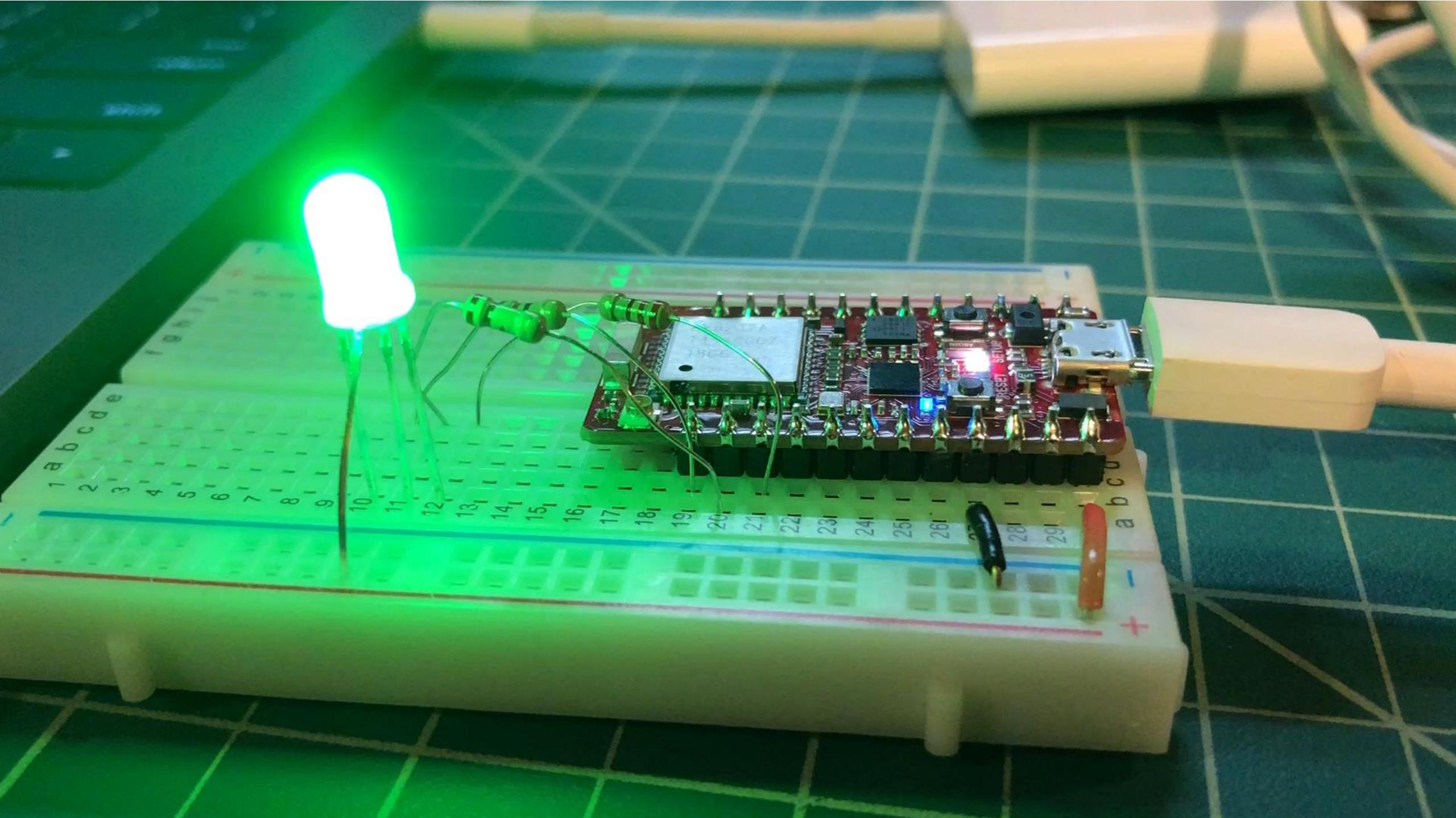
    Serial.println("Color=Yellow");
    setColor(255, 255, 0); // yellow
    delay(DELAY);

    Serial.println("Color=Purple");
    setColor(80, 0, 80); // purple
    delay(DELAY);

    Serial.println("Color=Aqua");
    setColor(0, 255, 255); // aqua
    delay(DELAY);
}

void setColor(int red, int green, int blue)
{
    #ifdef COMMON_ANODE
        red = 255 - red;
        green = 255 - green;
        blue = 255 - blue;
    #endif
    analogWrite(RGB_RED_PIN, red);
    analogWrite(RGB_GREEN_PIN, green);
    analogWrite(RGB_BLUE_PIN, blue);
}
```

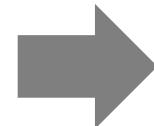
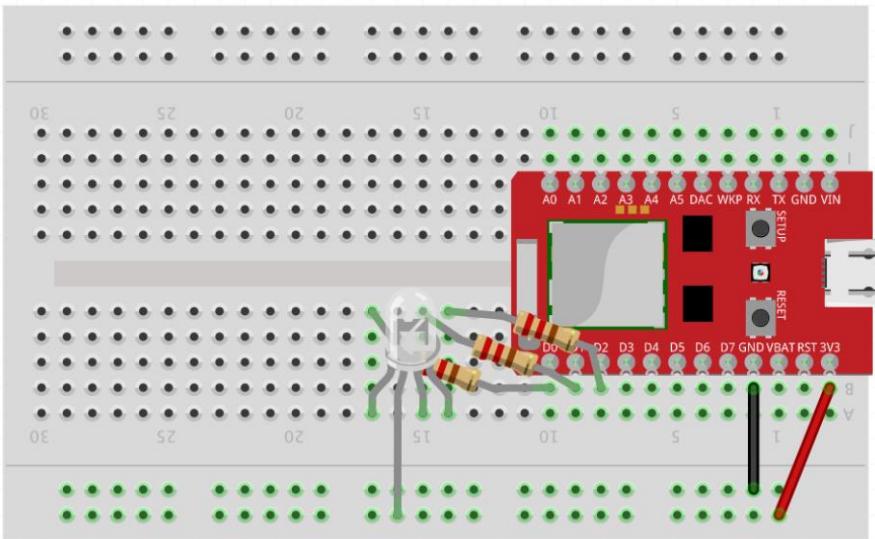
<https://github.com/jonfroehlich/CSE590Sp2018/tree/master/L05-Arduino/RedBearDuoRGB>



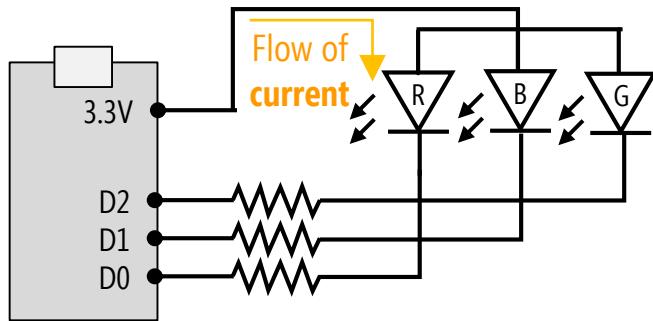
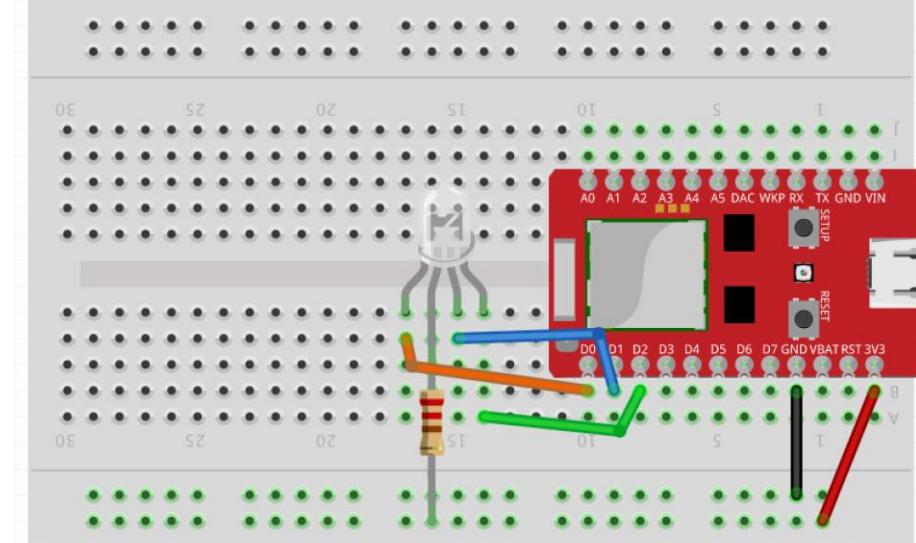
ANALOG OUTPUT

USING AN RGB LED: THE CIRCUIT (AN ALTERNATIVE)

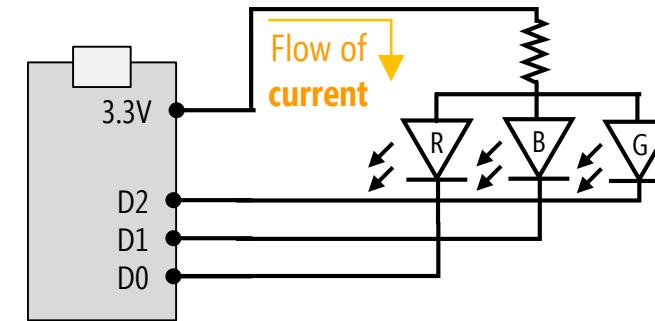
RGB Circuit 1: Set R, B, G values via D0, D1, & D2



RGB Circuit 2: Set R, B, G values via D0, D1, & D2



RedBear Duo



RedBear Duo

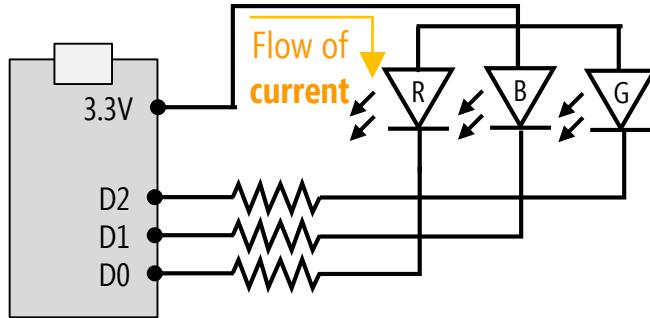
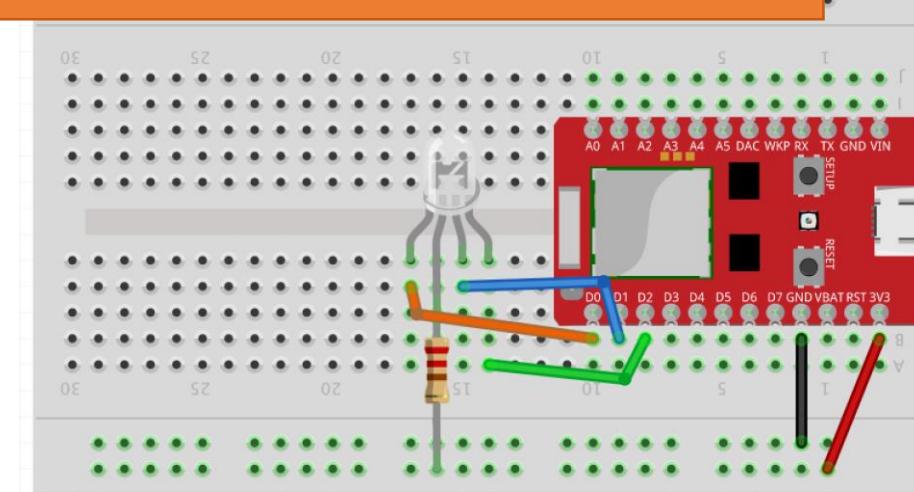
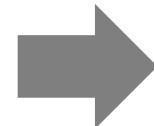
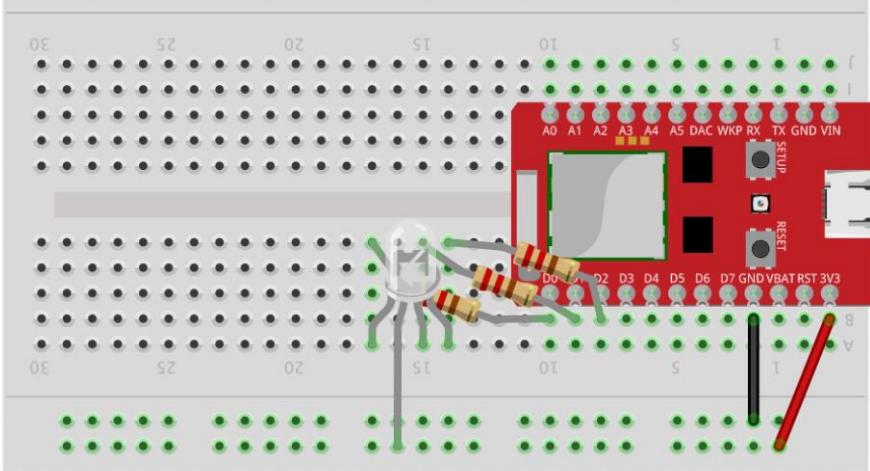
ANALOG OUTPUT

USING AN RGB LED: THE CIRCUIT (AN ALTERNATIVE)

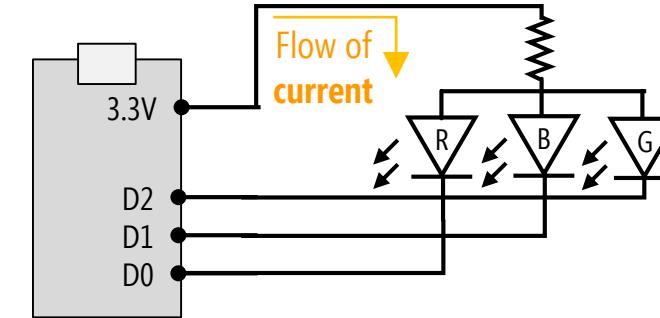
RGE

What are the key differences between the two circuits?

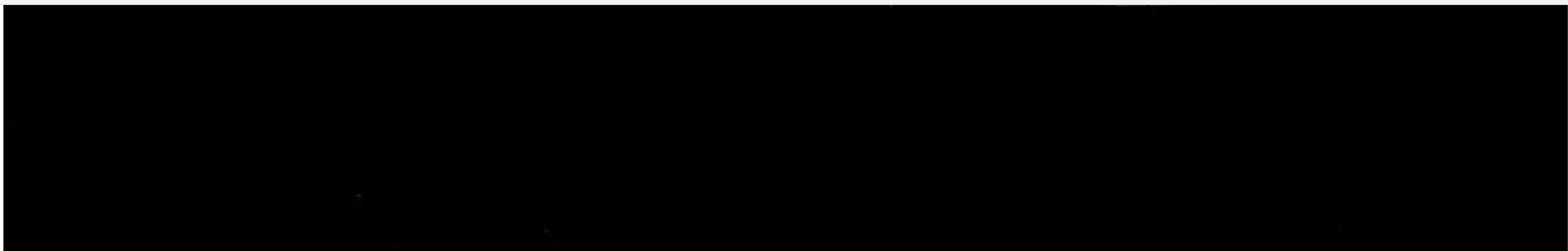
D1, & D2



RedBear Duo



RedBear Duo



Diffused RGB (tri-color) LED - Common Anode

PRODUCT ID: 159

\$2.00

46 IN STOCK

1

ADD TO CART

QTY DISCOUNT

1-9 \$2.00

10-49 \$1.75

50+ \$1.50

ADD TO WISHLIST

DESCRIPTION

Diffused 5mm tri-color LED with separate red, green and blue LED chips inside! Nice indicator, and fun to color-swirl. 60 degree viewing angle. We like diffused RGB LEDs because they color mix inside instead of appearing as 3 distinct LEDs.

These are Common-Anode type which means you connect one pin to 5V or so and then tie the other three legs to ground through a resistor. We carry and use CA more than CC because multi-LED driver chips (such as the TLC5940/TLC5941) are often designed exclusively for CA and can't be used with Common-Cathode.

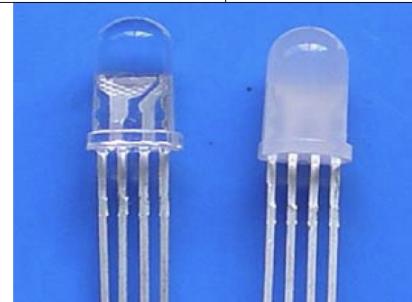
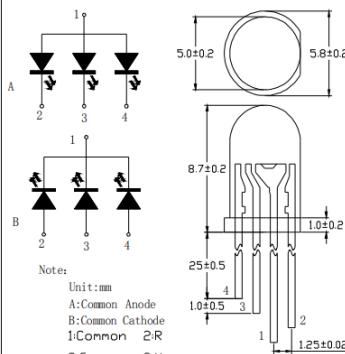
- 5mm diameter
- Red: 630 nm wavelength, Green: 525 nm, Blue: 430 nm
- Red: 2.1-2.5V Forward Voltage, at 20mA current, Green: 3.8-4.5V, Blue: 3.8-4.5V
- Red: 500 mcd typical brightness, Green: 600 mcd, Blue: 300 mcd
- [Datasheet](#)

If you need some help using LEDs, please read our "Introduction to using LEDs" tutorial for any electronics project.

[DESCRIPTION](#)[TECHNICAL DETAILS](#)[LEARN](#)

Features:

- * 5mm Lamp LED
- * Emitting Color Red Green Blue
- * Low Power Consumption
- * Ideal For Backlight Toy Light-Gift Indicator

Circuit and Package Dimension

Absolute Maximum Rating

Item	Symbol	Absolute Maximum Rating		Unit
Forward Current	I _F	20		mA
Peak Forward Current*	I _{FP}	100		mA
Reverse Voltage	V _R	5		V
Reverse Current	I _R	10		uA
Power Dissipation	P _D	150		mW
Electrostatic discharge	E _{SD}	800		V
Operation Temperature	T _{OPR}	-25~+80		°C
Storage Temperature	T _{STG}	-5~+45		°C
Lead Soldering Temperature	T _{SOL}	Max.260°C for 5sec Max(3mm from the base of the epoxy bulb)		

Typical Optical/Electrical Characteristics

Product Type	Lens Color	Emitting Color	Forward Voltage(v)		Prpc Wavelength (nm)		Luminous Intensity(mcd)		50% Power Angle(deg)
			Type	Max.	Type	Max.	Min.	Type	
5TSRGB-A/C	Water Clear	R	1.80	2.40	630	640	3000	4000	18
		G	3.20	3.60	515	525	4000	6000	
		B	3.20	3.60	460	470	900	1000	
5WSRGB-A/C	Diffused	R	1.80	2.40	630	640	2000	3000	45
		G	3.20	3.60	515	525	3000	5000	
		B	3.20	3.60	460	470	700	900	

Absolute Maximum Rating

Item	Symbol	Absolute Maximum Rating		Unit
Forward Current	I _F	20		mA
Peak Forward Current*	I _{FP}	100		mA
Reverse Voltage	V _R	5		V
Reverse Current	I _R	10		uA

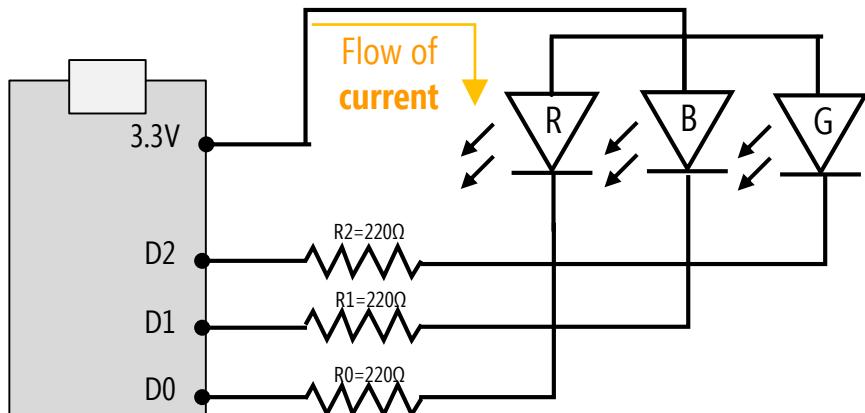
Typical Optical/Electrical Characteristics

Product Type	Lens Color	Emitting Color	Forward Voltage(v)		Prpc Wavelength (nm)	
			Type	Max.	Type	Max.
5TSRGB-A/C	Water Clear	R	1.80	2.40	630	640
		G	3.20	3.60	515	525
		B	3.20	3.60	460	470
5WSRGB-A/C	Diffused	R	1.80	2.40	630	640
		G	3.20	3.60	515	525
		B	3.20	3.60	460	470

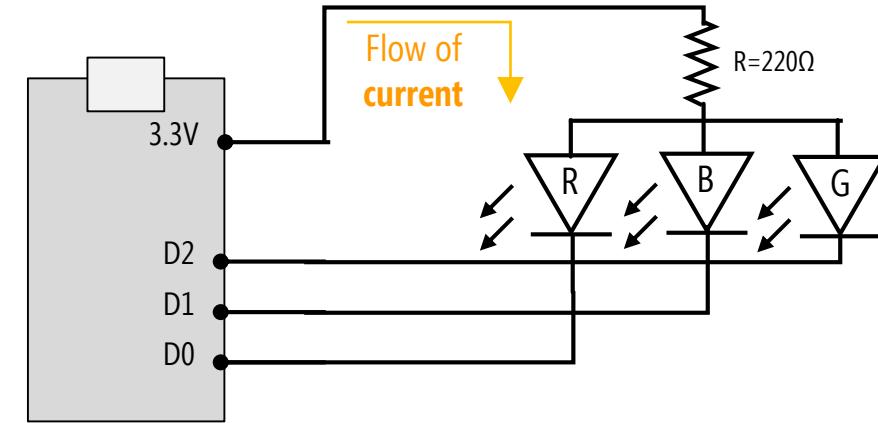
ANALOG OUTPUT

KEY DIFFERENCES BETWEEN RGB CIRCUIT DESIGNS

Assume D2, D1, and D0 are all `analogWrite(0)` so all are 0V (and, consequently, the light is white)



RedBear Duo

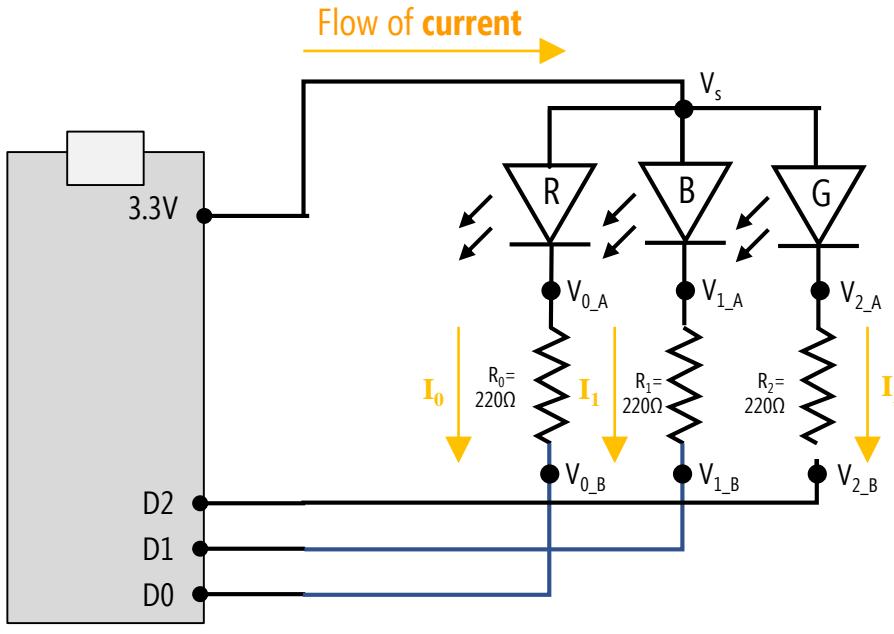


RedBear Duo

ANALOG OUTPUT

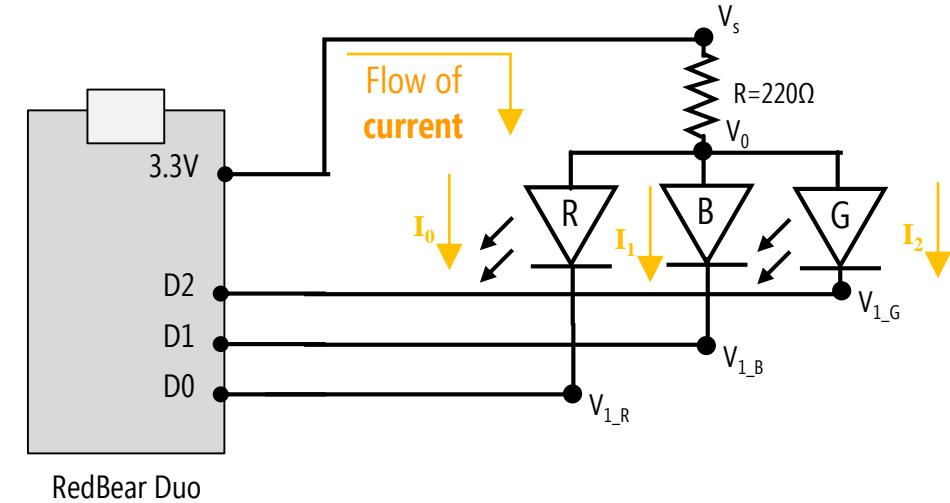
KEY DIFFERENCES BETWEEN RGB CIRCUIT DESIGNS

Assume D2, D1, and D0 are all `analogWrite(0)` so all are 0V (and, consequently, the light is white)



RedBear Duo

- + This circuit provides **more control** over the brightness of each LED
- + This circuit allows you to **account for the different voltage drops** of each LED (*e.g.*, red requires a smaller forward voltage than green)
- This circuit **requires more parts** (but is still, in general, a very simple circuit)



RedBear Duo

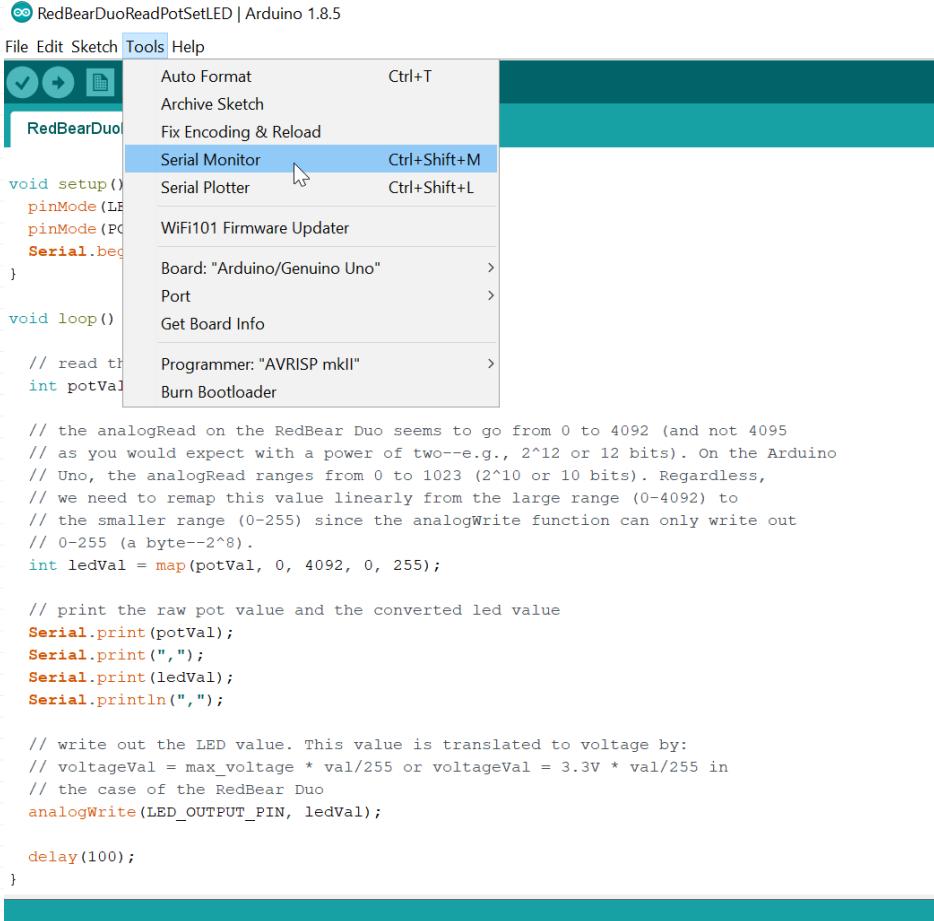
- + This circuit is **simpler** and uses **fewer parts**
- This circuit does **not allow you to individually control** the amount of current (*i.e.*, brightness) of each LED

So, now we've changed the color of the RGB LED. **How would you dynamically change the brightness using Arduino?**

(This is part of your A3 assignment, so I'll leave this up to you).

SERIAL MONITOR

SERIAL MONITOR IS USEFUL FOR DEBUGGING



RedBearDuoReadPotSetLED | Arduino 1.8.5

File Edit Sketch Tools Help

Auto Format Ctrl+T

Archive Sketch

Fix Encoding & Reload

Serial Monitor Ctrl+Shift+M

Serial Plotter Ctrl+Shift+L

WiFi101 Firmware Updater

Board: "Arduino/Genuino Uno" >

Port >

Get Board Info

Programmer: "AVRISP mkII" >

Burn Bootloader

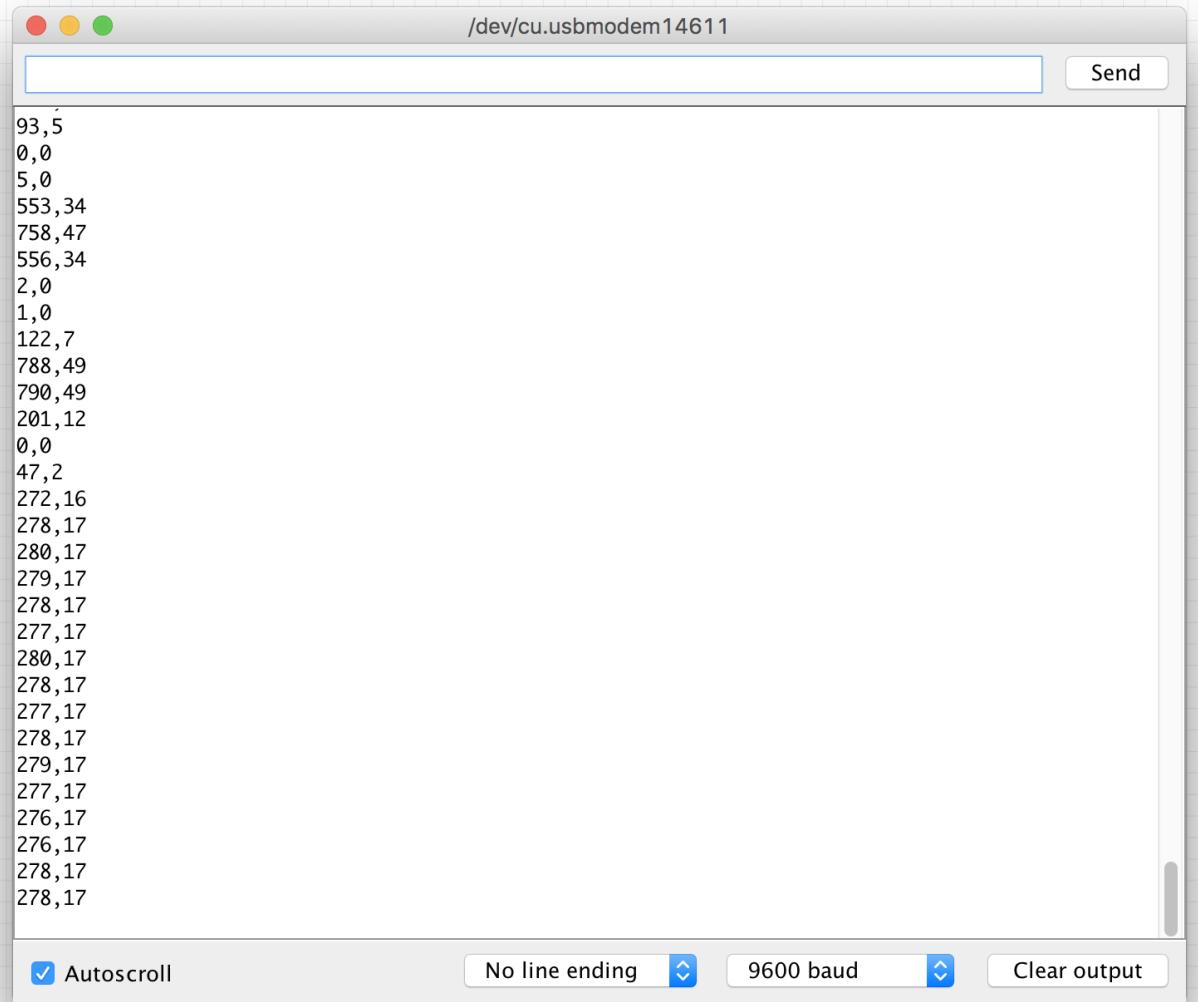
```
void setup() {
  pinMode(LED_BUILTIN, OUTPUT);
  Serial.begin(9600);
}

void loop() {
  int potVal = analogRead(A0);
  // the analogRead on the RedBear Duo seems to go from 0 to 4092 (and not 4095
  // as you would expect with a power of two--e.g., 2^12 or 12 bits). On the Arduino
  // Uno, the analogRead ranges from 0 to 1023 (2^10 or 10 bits). Regardless,
  // we need to remap this value linearly from the large range (0-4092) to
  // the smaller range (0-255) since the analogWrite function can only write out
  // 0-255 (a byte--2^8).
  int ledVal = map(potVal, 0, 4092, 0, 255);

  // print the raw pot value and the converted led value
  Serial.print(potVal);
  Serial.print(",");
  Serial.print(ledVal);
  Serial.println(",");
}

// write out the LED value. This value is translated to voltage by:
// voltageVal = max_voltage * val/255 or voltageVal = 3.3V * val/255 in
// the case of the RedBear Duo
analogWrite(LED_OUTPUT_PIN, ledVal);

delay(100);
}
```



/dev/cu.usbmodem14611

Send

93,5
0,0
5,0
553,34
758,47
556,34
2,0
1,0
122,7
788,49
790,49
201,12
0,0
47,2
272,16
278,17
280,17
279,17
278,17
277,17
280,17
278,17
277,17
278,17
279,17
277,17
276,17
276,17
278,17
278,17

Autoscroll

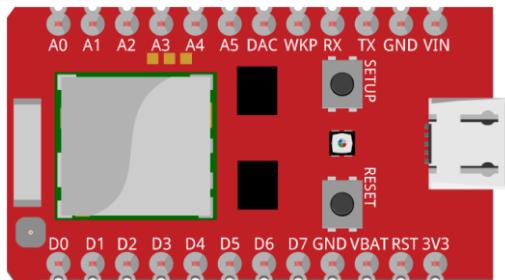
No line ending

9600 baud

Clear output

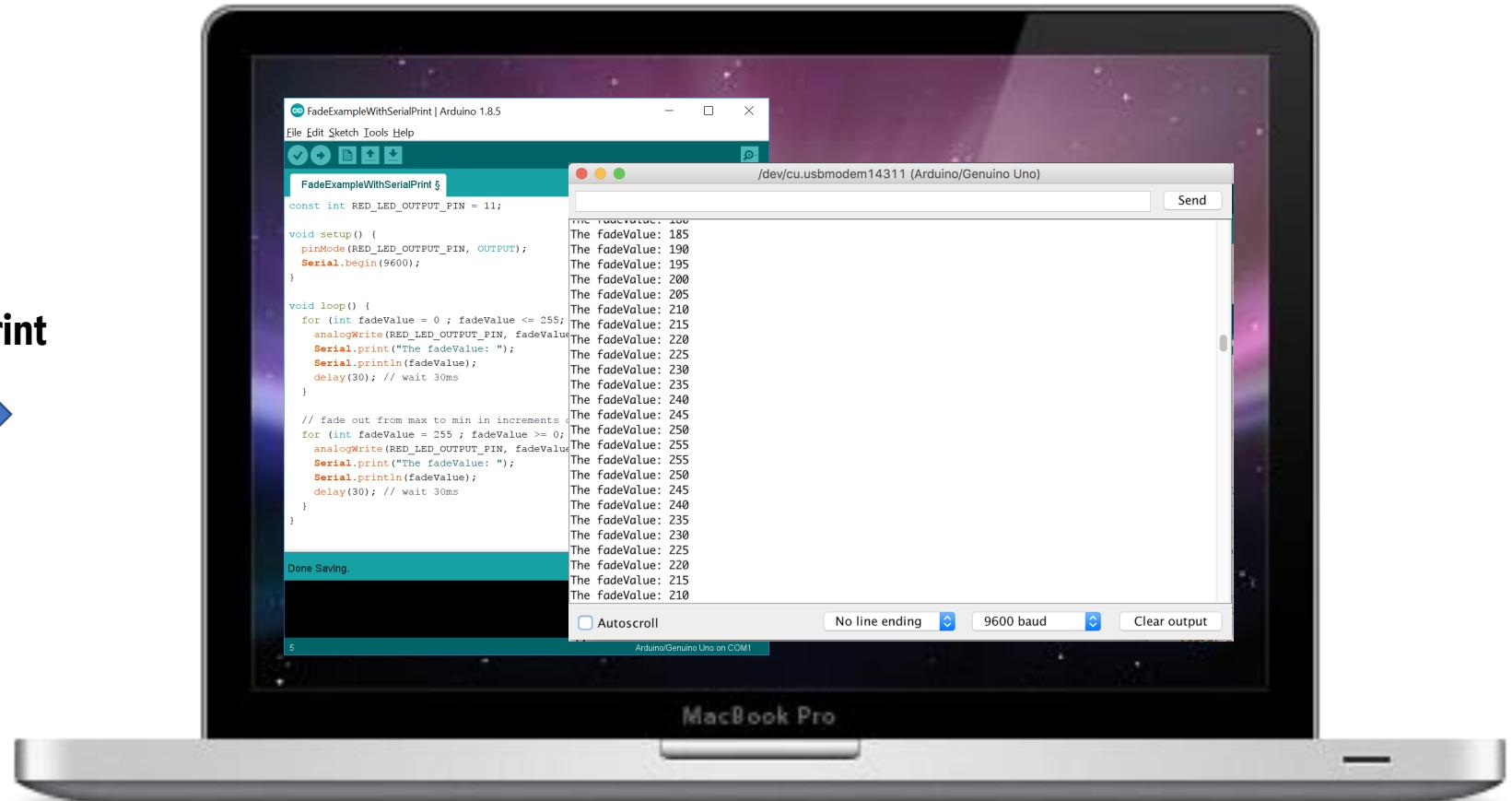
SERIAL MONITOR

CONCEPTUALLY UNDERSTANDING SERIAL.PRINT



Serial.print
→

Serial.print sends data over the USB port (via the Serial protocol), which can be displayed by any terminal program including Arduino's built-in Serial Monitor and Serial Plotter.



PRINTING TO SERIAL MONITOR: PRINT()

Prints data to the serial port.

You must add this line of code to setup() to initialize the serial port

```
Serial.begin(9600);
```

Syntax

```
Serial.print(val)
```

```
Serial.print(val, format)
```

Parameters

val: the value to print

format: specifies formatting, see documentation

SERIAL MONITOR

TRY IT YOURSELF!



The screenshot shows the Arduino IDE interface. The top bar displays "FadeExampleWithSerialPrint | Arduino 1.8.5". The menu bar includes File, Edit, Sketch, Tools, and Help. Below the menu is a toolbar with icons for save, undo, redo, and file operations. The main area shows the code for "FadeExampleWithSerialPrint". The code initializes pin 11 as an output, sets the serial port to 9600 baud, and prints the fade value to the serial monitor in a loop. The code is as follows:

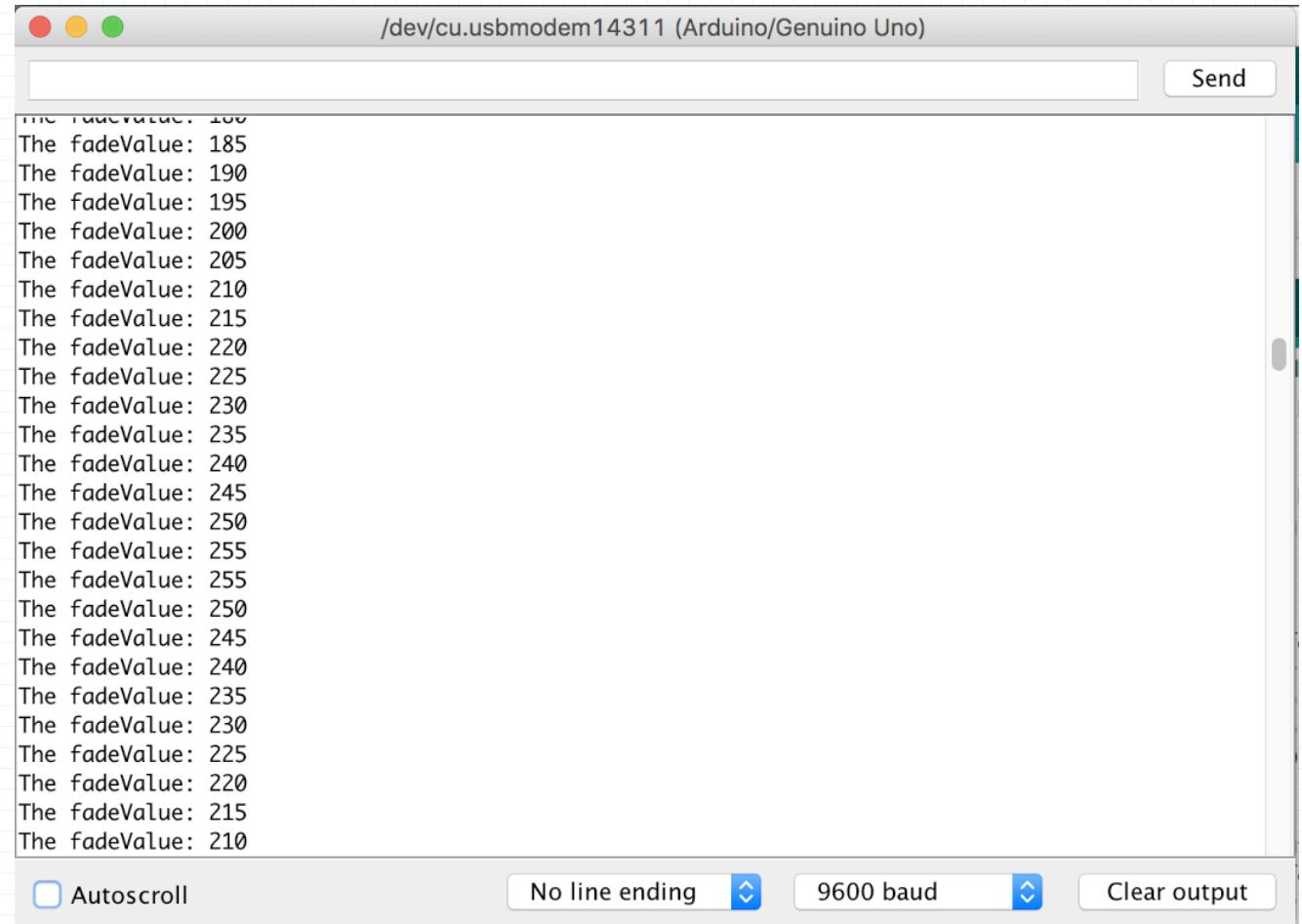
```
const int RED_LED_OUTPUT_PIN = 11;

void setup() {
  pinMode(RED_LED_OUTPUT_PIN, OUTPUT);
  Serial.begin(9600);
}

void loop() {
  for (int fadeValue = 0 ; fadeValue <= 255; fadeValue += 5) {
    analogWrite(RED_LED_OUTPUT_PIN, fadeValue); // set the LED value
    Serial.print("The fadeValue: ");
    Serial.println(fadeValue);
    delay(30); // wait 30ms
  }

  // fade out from max to min in increments of 5 points:
  for (int fadeValue = 255 ; fadeValue >= 0; fadeValue -= 5) {
    analogWrite(RED_LED_OUTPUT_PIN, fadeValue); // set the LED value
    Serial.print("The fadeValue: ");
    Serial.println(fadeValue);
    delay(30); // wait 30ms
  }
}
```

At the bottom, a message says "Done Saving." and the status bar indicates "Arduino/Genuino Uno on COM1".



The screenshot shows the Arduino Serial Monitor window. The title bar reads "/dev/cu.usbmodem14311 (Arduino/Genuino Uno)". The main text area displays the output of the sketch, which is printing "The fadeValue" followed by a series of values from 100 to 210 in increments of 5. The output is as follows:

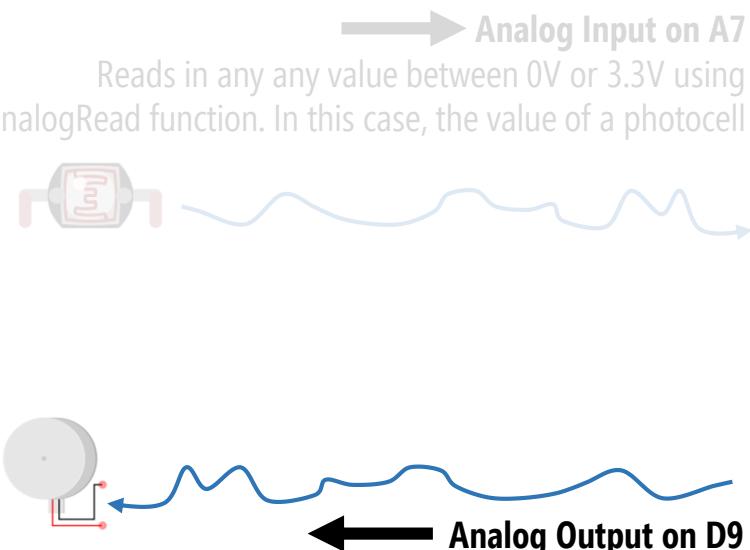
```
The fadeValue: 100
The fadeValue: 105
The fadeValue: 110
The fadeValue: 115
The fadeValue: 120
The fadeValue: 125
The fadeValue: 130
The fadeValue: 135
The fadeValue: 140
The fadeValue: 145
The fadeValue: 150
The fadeValue: 155
The fadeValue: 160
The fadeValue: 165
The fadeValue: 170
The fadeValue: 175
The fadeValue: 180
The fadeValue: 185
The fadeValue: 190
The fadeValue: 195
The fadeValue: 200
The fadeValue: 205
The fadeValue: 210
The fadeValue: 215
The fadeValue: 220
The fadeValue: 225
The fadeValue: 230
The fadeValue: 235
The fadeValue: 240
The fadeValue: 245
The fadeValue: 250
The fadeValue: 255
The fadeValue: 255
The fadeValue: 250
The fadeValue: 245
The fadeValue: 240
The fadeValue: 235
The fadeValue: 230
The fadeValue: 225
The fadeValue: 220
The fadeValue: 215
The fadeValue: 210
```

At the bottom, there are controls for "Autoscroll" (unchecked), "No line ending" (selected), "9600 baud" (selected), and "Clear output".

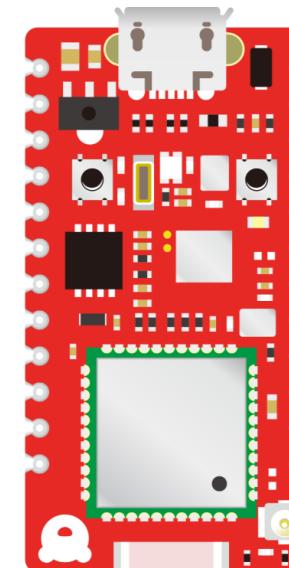
OUTPUT

DIGITAL AND ANALOG OUTPUT

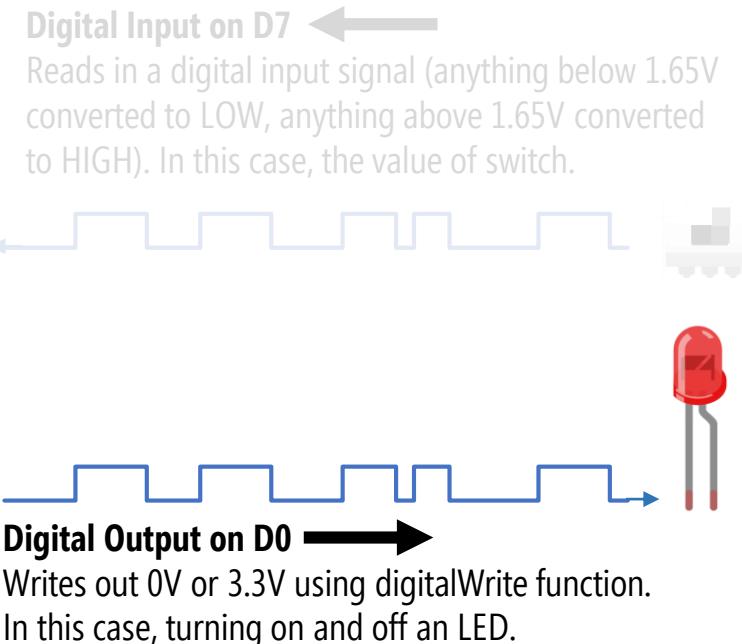
This completes our quick tour of digital and analog output on the Arduino



VIN	
GND	
TX	D17
RX	D16
A7	D15
A6	D14
A5	D13
A4	D12
A3	D11
A2	D10
A1	D9
A0	D8



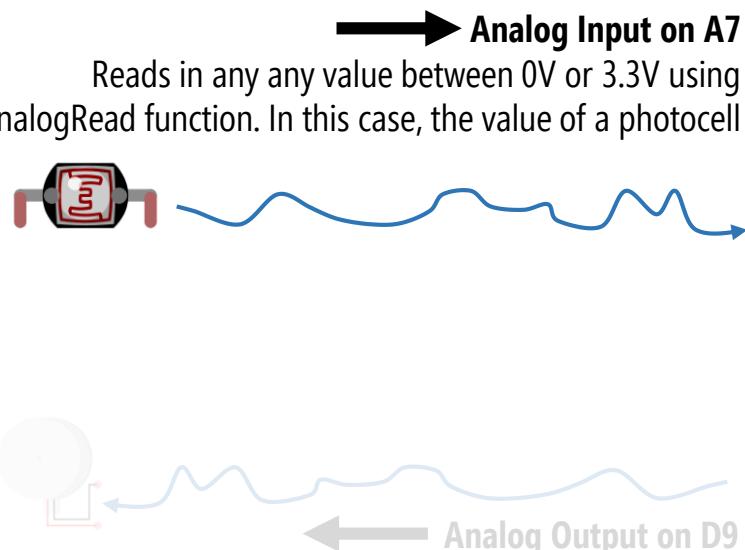
3.3V	
RST	
VBAT	
GND	
D7	
D6	
D5	
D4	
D3	
D2	
D1	
D0	



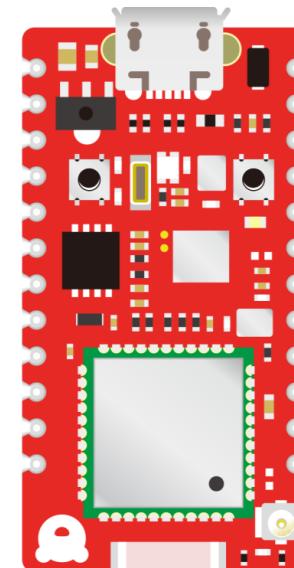
INPUT

DIGITAL AND ANALOG INPUT

Now we are going to switch from talking about output to talking about input



VIN	
GND	
TX	D17
RX	D16
A7	D15
A6	D14
A5	D13
A4	D12
A3	D11
A2	D10
A1	D9
A0	D8



3.3V	
RST	
VBAT	
GND	
D7	
D6	
D5	
D4	
D3	
D2	
D1	
D0	

Digital Input on D7

Reads in a digital input signal (anything below 1.65V converted to LOW, anything above 1.65V converted to HIGH). In this case, the value of switch.

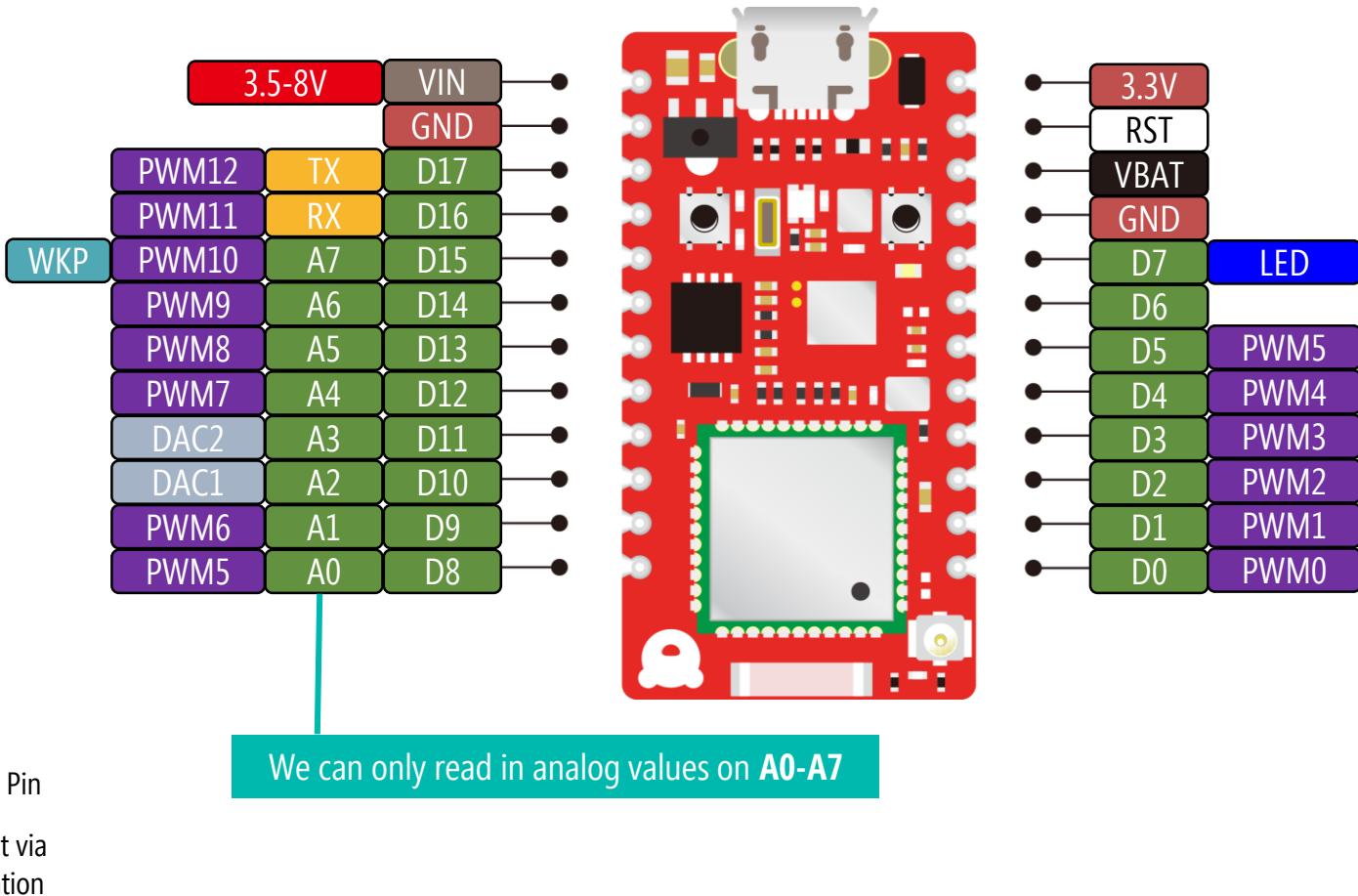
Digital Output on D0

Writes out 0V or 3.3V using `digitalWrite` function. In this case, turning on and off an LED.

Now let's build a circuit and write code to **fade an LED based on the value of a trim potentiometer**. For this, we will use analog input (analogRead) and output (analogWrite)

ANALOG INPUT

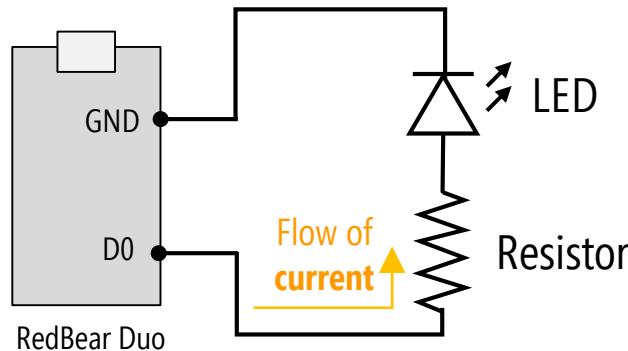
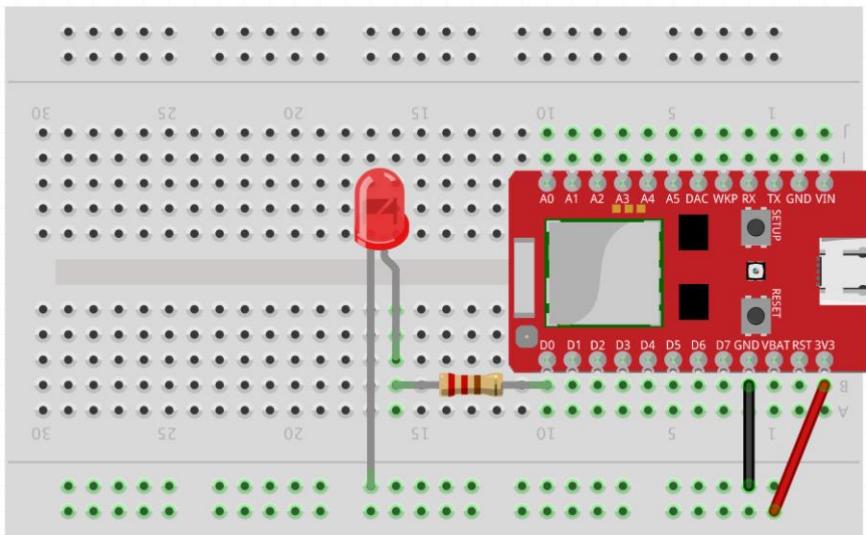
RECALL THAT WE ONLY HAVE EIGHT ANALOG INPUTS



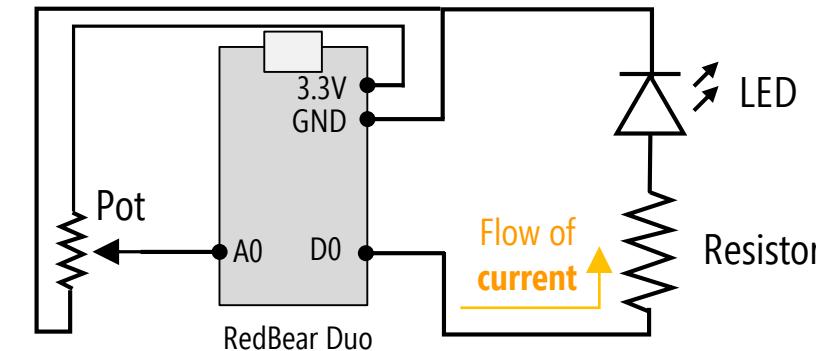
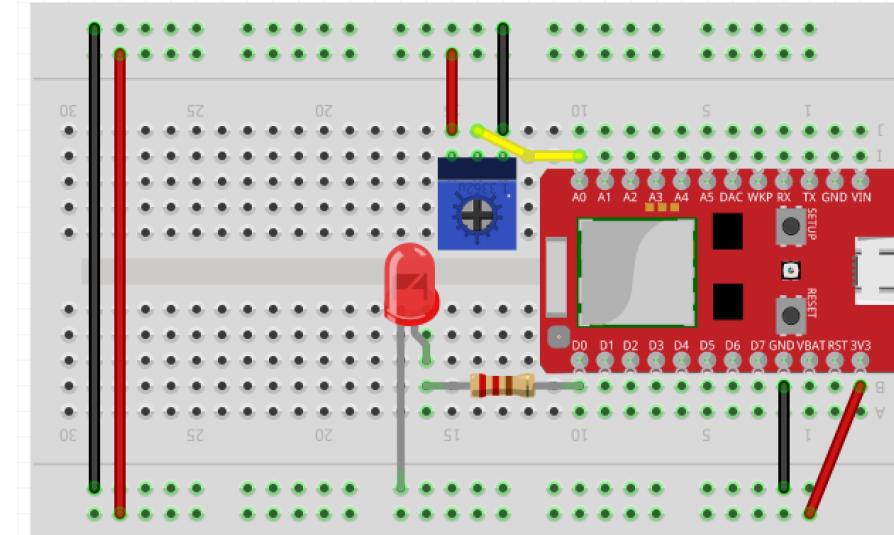
ANALOG INPUT

CONTROL LED BRIGHTNESS WITH POTENTIOMETER

Old Circuit: Fade LED on/off via the D0 pin



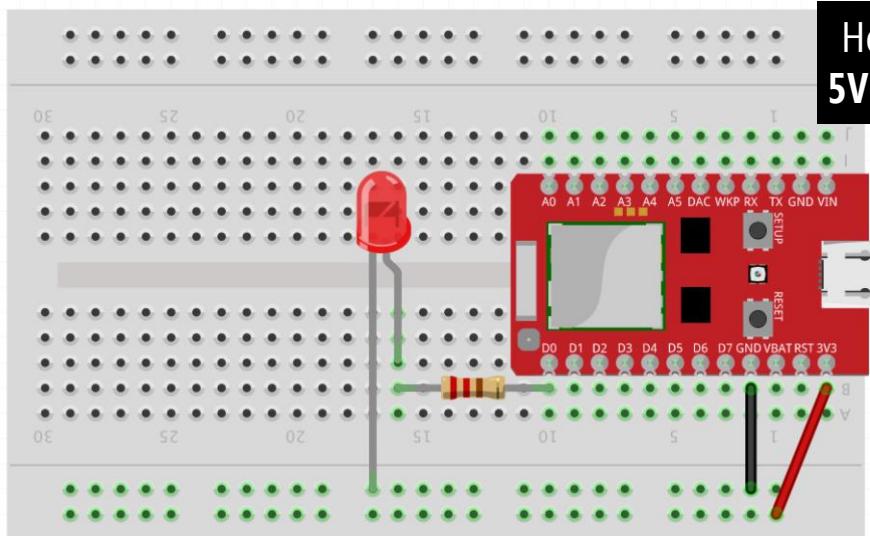
New Circuit: Fade LED on/off via pot value



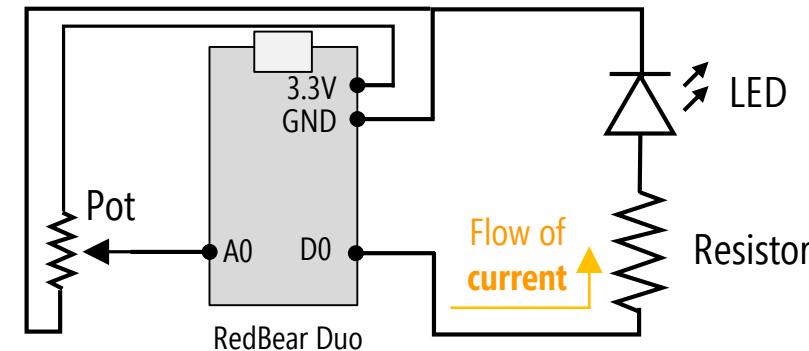
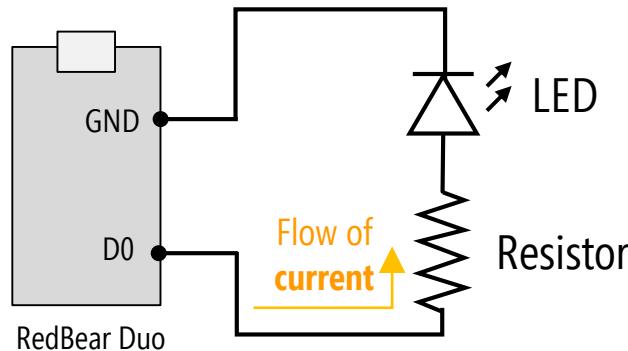
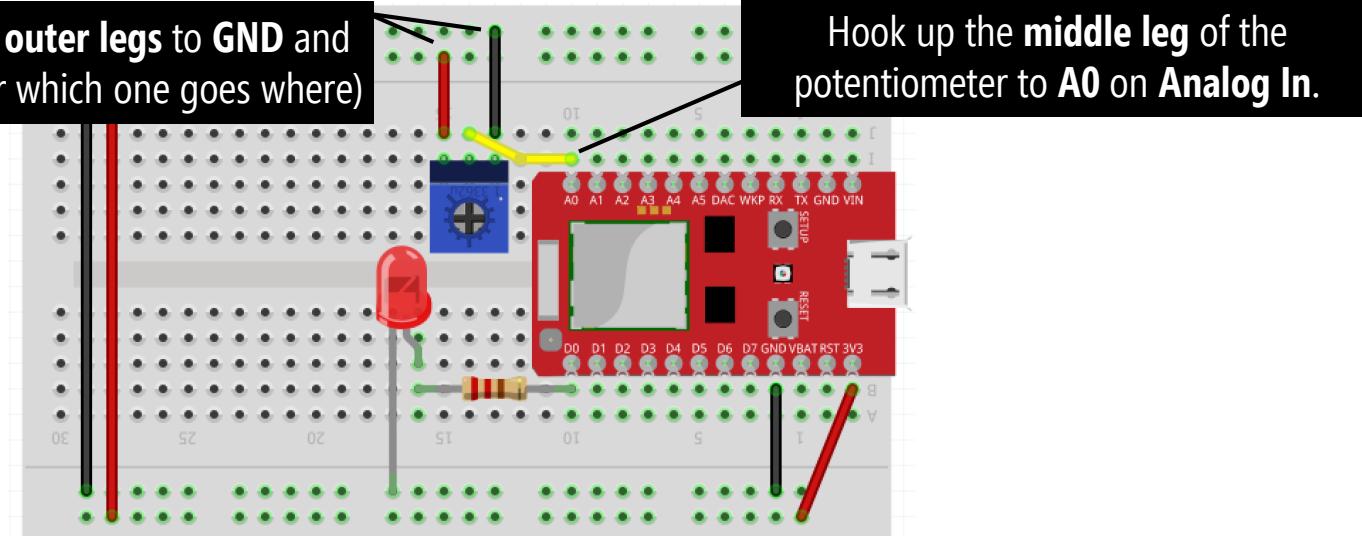
ANALOG INPUT

CONTROL LED BRIGHTNESS WITH POTENTIOMETER

Old Circuit: Fade LED on/off via the D0 pin



New Circuit: Fade LED on/off via pot value



ANALOG INPUT: ANALOGREAD()

Reads the value from the specified analog pin. The input voltage (0-5V) is mapped to 0-1023.

Syntax

`analogRead(pin)`

Parameters

`pin`: the analog pin to read from

Returns

An integer between 0 and 1023 (inclusive). **Note:** on the RedBear Duo, it appears that this is actually more like 0 to 4096 (which is 2^{12} rather than 2^{10} on the Arduino Uno—so, 12 bits reserved for ADC on the Duo). Empirically, I've found that the range is more like 0 to 4092.

ACTIVITY: LEARN ANALOG INPUT

HELPER FUNCTION: MAP()

Remaps a number from one range to another. Warning: it does not constrain values to be within the range.

Syntax

```
map(value, fromLow, fromHigh, toLow, toHigh)
```

Parameters

`value`: the number to map

`fromLow`: the lower bound of the value's current range

`fromHigh`: the upper bound of the value's current range

`toLow`: the lower bound of the value's target range

`toHigh`: the upper bound of the value's target range

Returns

The mapped value

ACTIVITY: LEARN ANALOG INPUT

HELPER FUNCTION: MAP()

Remaps a number from one range to another. Warning: it does not constrain values to be within the range.

Syntax

```
map (value, fromLow, fromHigh, toLow, toHigh)
```

Parameters

value: the number to map

fromLow: the lower bound of the value's current range

fromHigh: the upper bound of the value's current range

toLow: the lower bound of the value's target range

toHigh: the upper bound of the value's target range

Returns

The mapped value

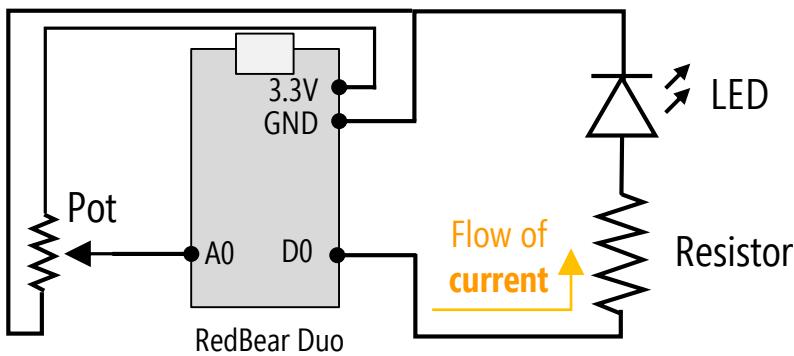
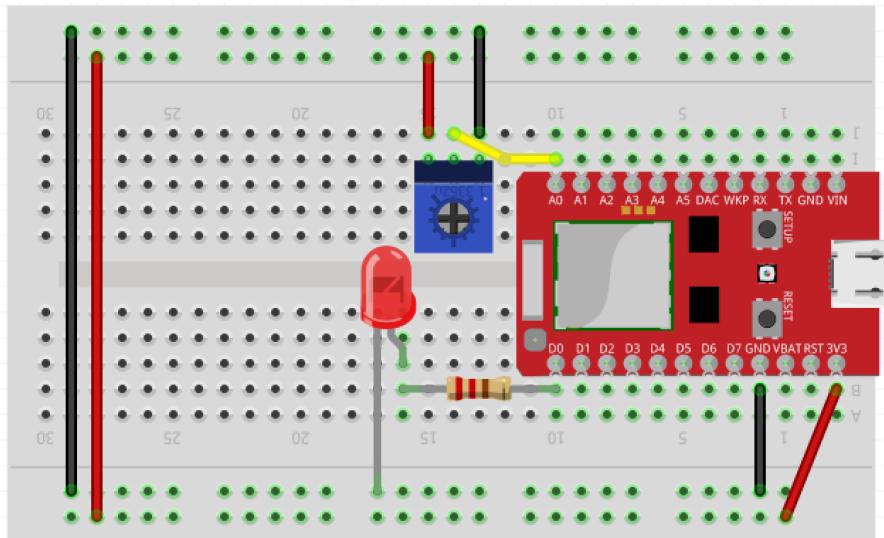
There is no magic here. The full utility function is simply:

```
long map(long val, long fromLow, long fromHigh, long toLow, long toHigh)
{
    float rangeFraction = (toHigh - toLow) / (fromHigh - fromLow);
    return toLow + (x - fromLow) * rangeFraction;
}
```

ANALOG INPUT

CONTROL LED BRIGHTNESS WITH POTENTIOMETER

Circuit: Fade LED on/off via pot value



Write Code: Fade LED on/off via pot value

```
RedBearDuoReadPotSetLED | Arduino 1.8.5
File Edit Sketch Tools Help
RedBearDuoReadPotSetLED
SYSTEM_MODE (MANUAL);

const int LED_OUTPUT_PIN = D0;
const int POT_INPUT_PIN = A0;

void setup() {
  pinMode(LED_OUTPUT_PIN, OUTPUT);
  pinMode(POT_INPUT_PIN, INPUT);
}

void loop() {

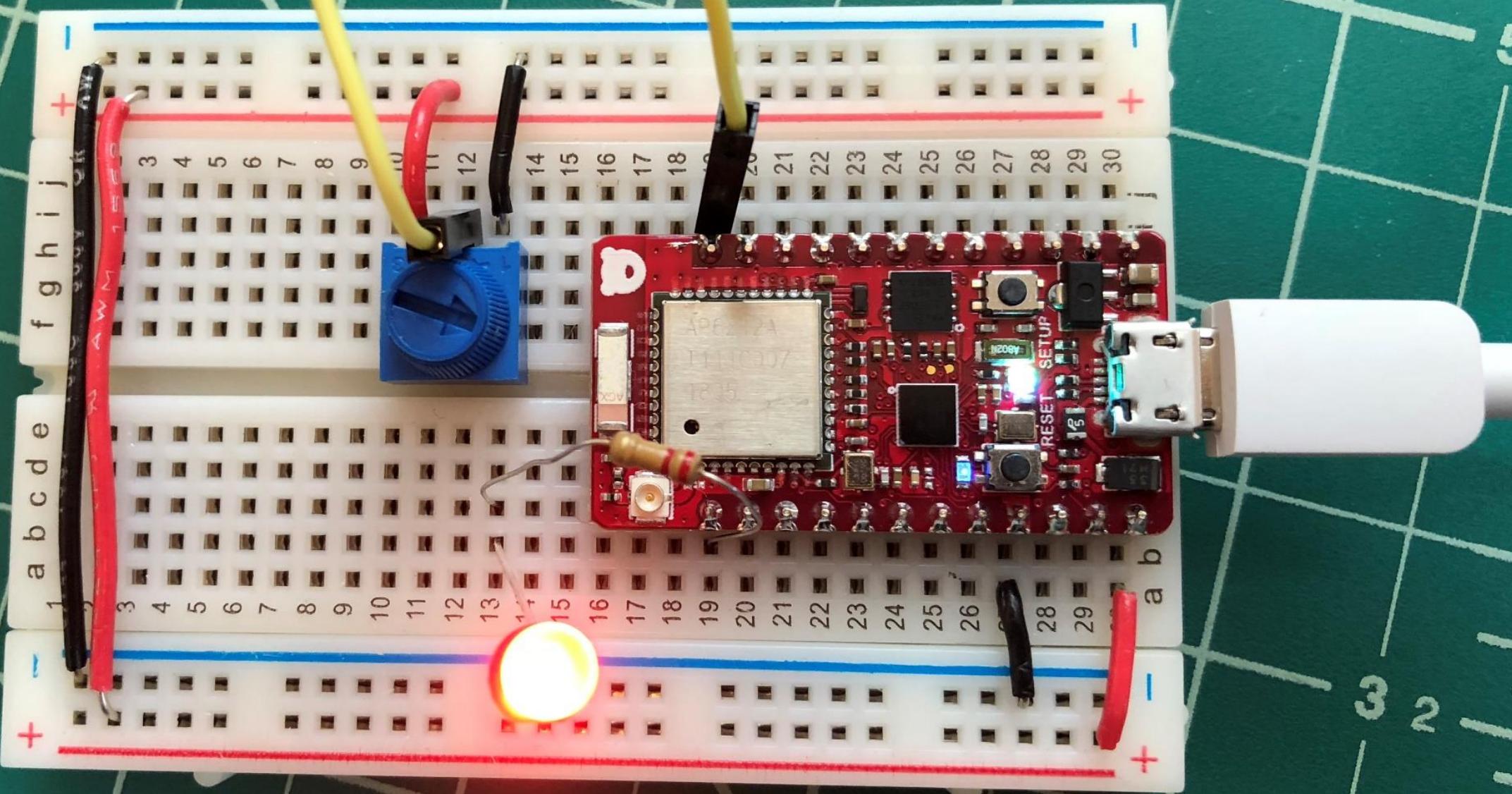
  // read the potentiometer value
  int potVal = analogRead(POT_INPUT_PIN);

  // the analogRead on the RedBear Duo seems to go from 0 to 4092 (and not 4095
  // as you would expect with a power of two--e.g., 2^12 or 12 bits). On the Arduino
  // Uno, the analogRead ranges from 0 to 1023 (2^10 or 10 bits). Regardless,
  // we need to remap this value linearly from the large range (0-4092) to
  // the smaller range (0-255) since the analogWrite function can only write out
  // 0-255 (a byte--2^8).
  int ledVal = map(potVal, 0, 4092, 0, 255);

  // write out the LED value. This value is translated to voltage by:
  // voltageVal = max_voltage * val/255 or voltageVal = 3.3V * val/255 in
  // the case of the RedBear Duo
  analogWrite(LED_OUTPUT_PIN, ledVal);

  delay(100);
}
```

<https://github.com/jonfroehlich/CSE590Sp2018/tree/master/L05-Arduino/RedBearDuoReadPotSetLED>



When I taught Arduino at UMD, one of my first assignments was to make a visualizer for Arduino signals (see [ArduinoGraphTutorials](#)), now the Arduino IDE ships with its own signal visualizer called **Serial Plotter**—a great way to visualize I/O signals. Let's modify our potentiometer code to take advantage of it.

SERIAL PLOTTER

USING THE SERIAL PLOTTER

Serial Plotter automatically visualizes comma separated numerical values coming in off Serial.

Old Code: Fade LED on/off via pot value



The screenshot shows the Arduino IDE interface with the sketch titled "RedBearDuoReadPotSetLED". The code is as follows:

```
RedBearDuoReadPotSetLED | Arduino 1.8.5
File Edit Sketch Tools Help
RedBearDuoReadPotSetLED
SYSTEM_MODE(MANUAL);

const int LED_OUTPUT_PIN = D0;
const int POT_INPUT_PIN = A0;

void setup() {
    pinMode(LED_OUTPUT_PIN, OUTPUT);
    pinMode(POT_INPUT_PIN, INPUT);
}

void loop() {

    // read the potentiometer value
    int potVal = analogRead(POT_INPUT_PIN);

    // the analogRead on the RedBear Duo seems to go from 0 to 4092 (and not 4095
    // as you would expect with a power of two--e.g., 2^12 or 12 bits). On the Arduino
    // Uno, the analogRead ranges from 0 to 1023 (2^10 or 10 bits). Regardless,
    // we need to remap this value linearly from the large range (0-4092) to
    // the smaller range (0-255) since the analogWrite function can only write out
    // 0-255 (a byte--2^8).
    int ledVal = map(potVal, 0, 4092, 0, 255);

    // write out the LED value. This value is translated to voltage by:
    // voltageVal = max_voltage * val/255 or voltageVal = 3.3V * val/255 in
    // the case of the RedBear Duo
    analogWrite(LED_OUTPUT_PIN, ledVal);

    delay(100);
}
```

<https://github.com/jonfroehlich/CSE590Sp2018/tree/master/L05-Arduino/RedBearDuoReadPotSetLED>

Updated Code: Adds in Serial.println of pot value



The screenshot shows the Arduino IDE interface with the sketch titled "RedBearDuoReadPotSetLED". The code has been updated to include `Serial.println` statements for the potentiometer value and the converted LED value. The updated code is as follows:

```
RedBearDuoReadPotSetLED | Arduino 1.8.5
RedBearDuoReadPotSetLED §
SYSTEM_MODE(MANUAL);

const int LED_OUTPUT_PIN = D0;
const int POT_INPUT_PIN = A0;

void setup() {
    pinMode(LED_OUTPUT_PIN, OUTPUT);
    pinMode(POT_INPUT_PIN, INPUT);
    Serial.begin(9600);
}

void loop() {

    // read the potentiometer value
    int potVal = analogRead(POT_INPUT_PIN);

    // the analogRead on the RedBear Duo seems to go from 0 to 4092 (and not 4095
    // as you would expect with a power of two--e.g., 2^12 or 12 bits). On the Arduino
    // Uno, the analogRead ranges from 0 to 1023 (2^10 or 10 bits). Regardless,
    // we need to remap this value linearly from the large range (0-4092) to
    // the smaller range (0-255) since the analogWrite function can only write out
    // 0-255 (a byte--2^8).
    int ledVal = map(potVal, 0, 4092, 0, 255);

    // print the raw pot value and the converted led value
    Serial.print(potVal);
    Serial.print(",");
    Serial.println(ledVal);

    // write out the LED value. This value is translated to voltage by:
    // voltageVal = max_voltage * val/255 or voltageVal = 3.3V * val/255 in
    // the case of the RedBear Duo
    analogWrite(LED_OUTPUT_PIN, ledVal);

    delay(100);
}
```

<https://github.com/jonfroehlich/CSE590Sp2018/tree/master/L05-Arduino/RedBearDuoReadPotSetLED>

SERIAL PLOTTER

USING THE SERIAL PLOTTER

Arduino File Edit Sketch Tools Help

RedBear

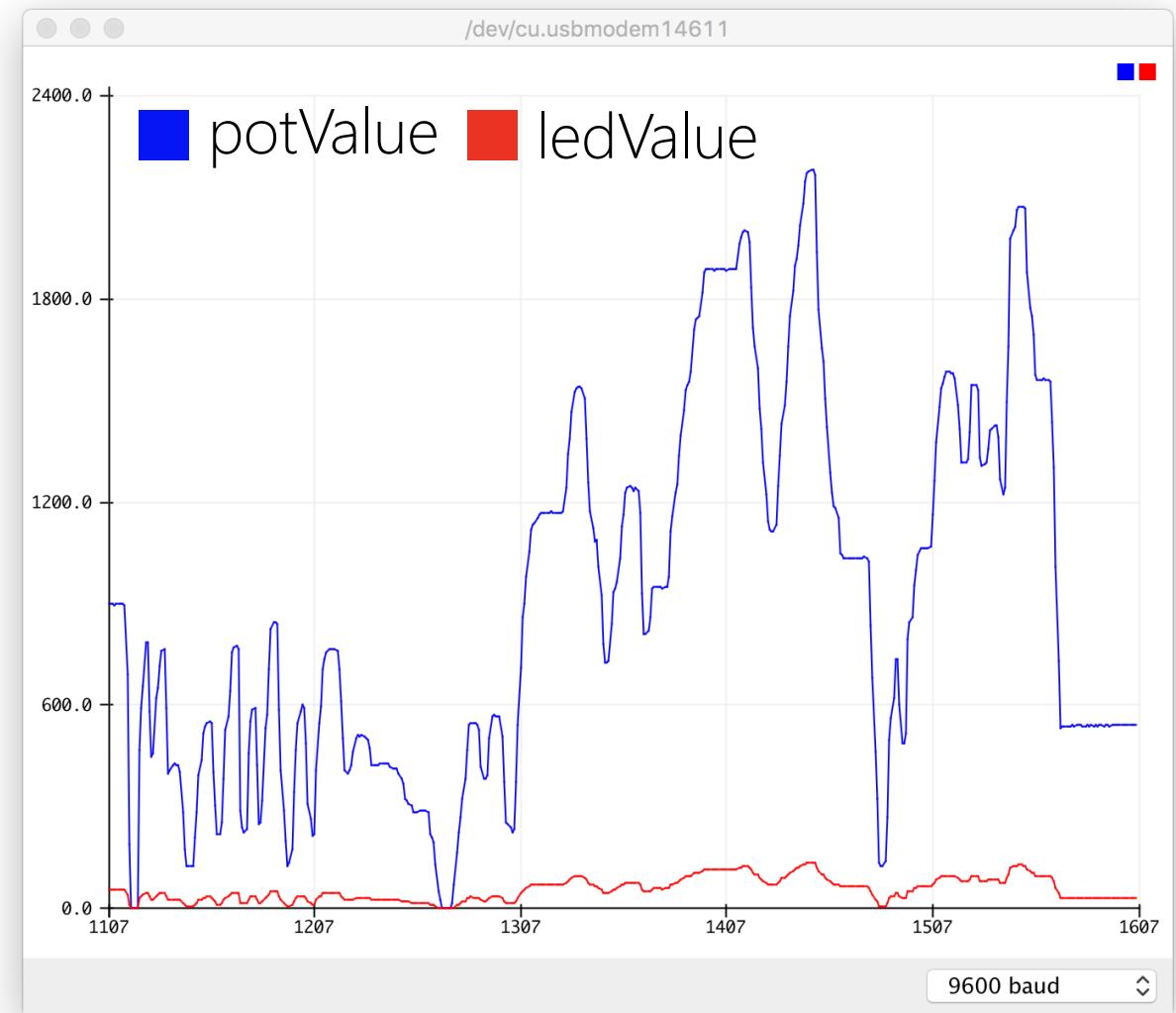
RedBearDuoReadPotSetLED

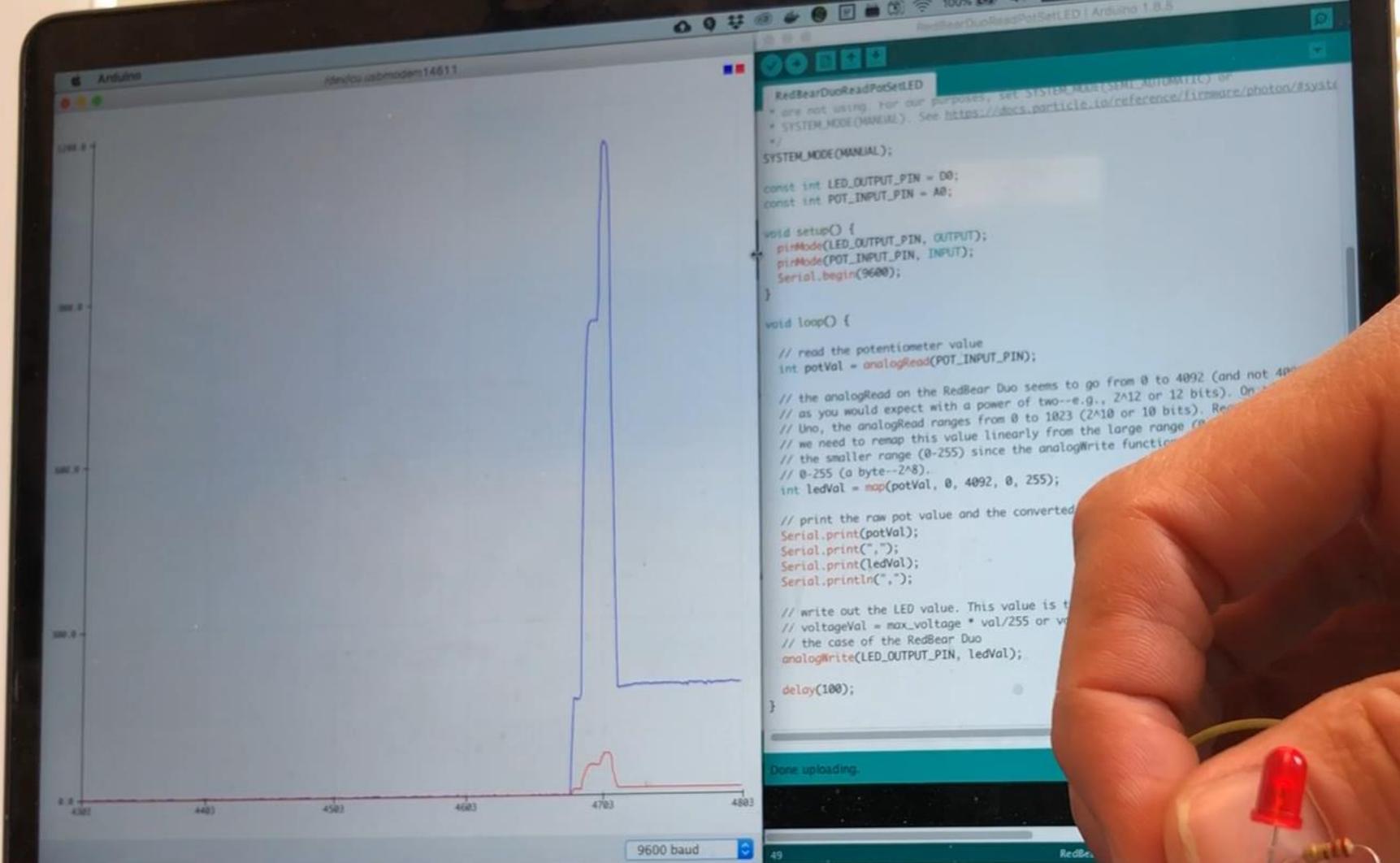
```
/*
 * This example reads in a potentiometer
 * of an LED (hooked up to D0).
 *
 * The analogWrite() function uses PWM
 * using, be sure to use another PWM
 * are identified with a "~" sign, like
 * Duo, please consult the pin layout
 *
 * By Jon Froehlich for CSE590
 * http://makeabilitylab.io
 */

/*
 * IMPORTANT: When working with the RedBear Duo, you must have this line of
 * code at the top of your program. The default state is SYSTEM_MODE(AUTOMATIC);
 * however, this puts the RedBear Duo in a special cloud-based mode that we
 * are not using. For our purposes, set SYSTEM_MODE(SEMI_AUTOMATIC) or
 * SYSTEM_MODE(MANUAL). See https://docs.particle.io/reference/firmware/photon/#system-modes
 */
SYSTEM_MODE(MANUAL);

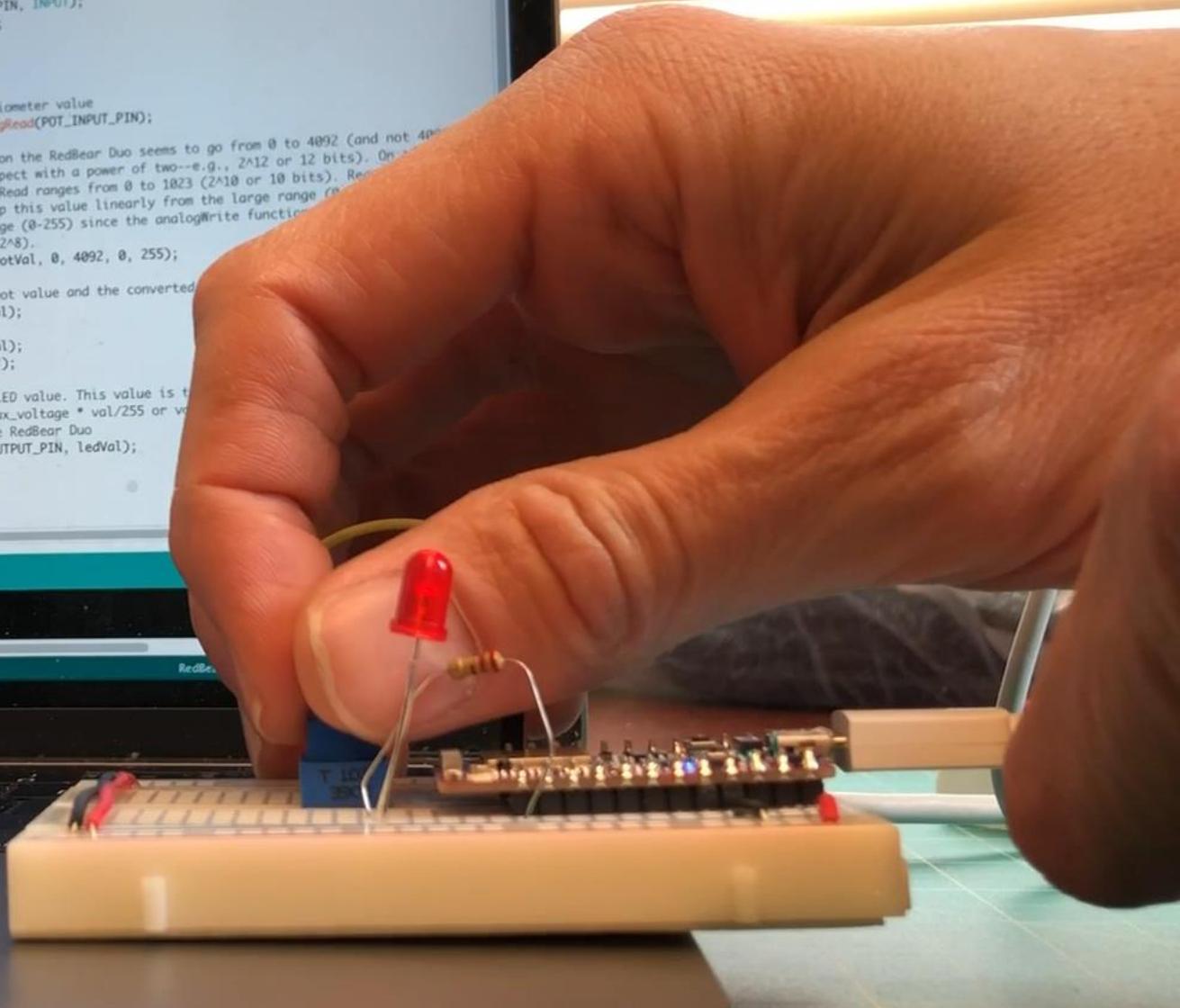
const int LED_OUTPUT_PIN = D0;
const int POT_INPUT_PIN = A0;
```

RedBear Duo (Native USB Port) on /dev/cu.usbmodem14611





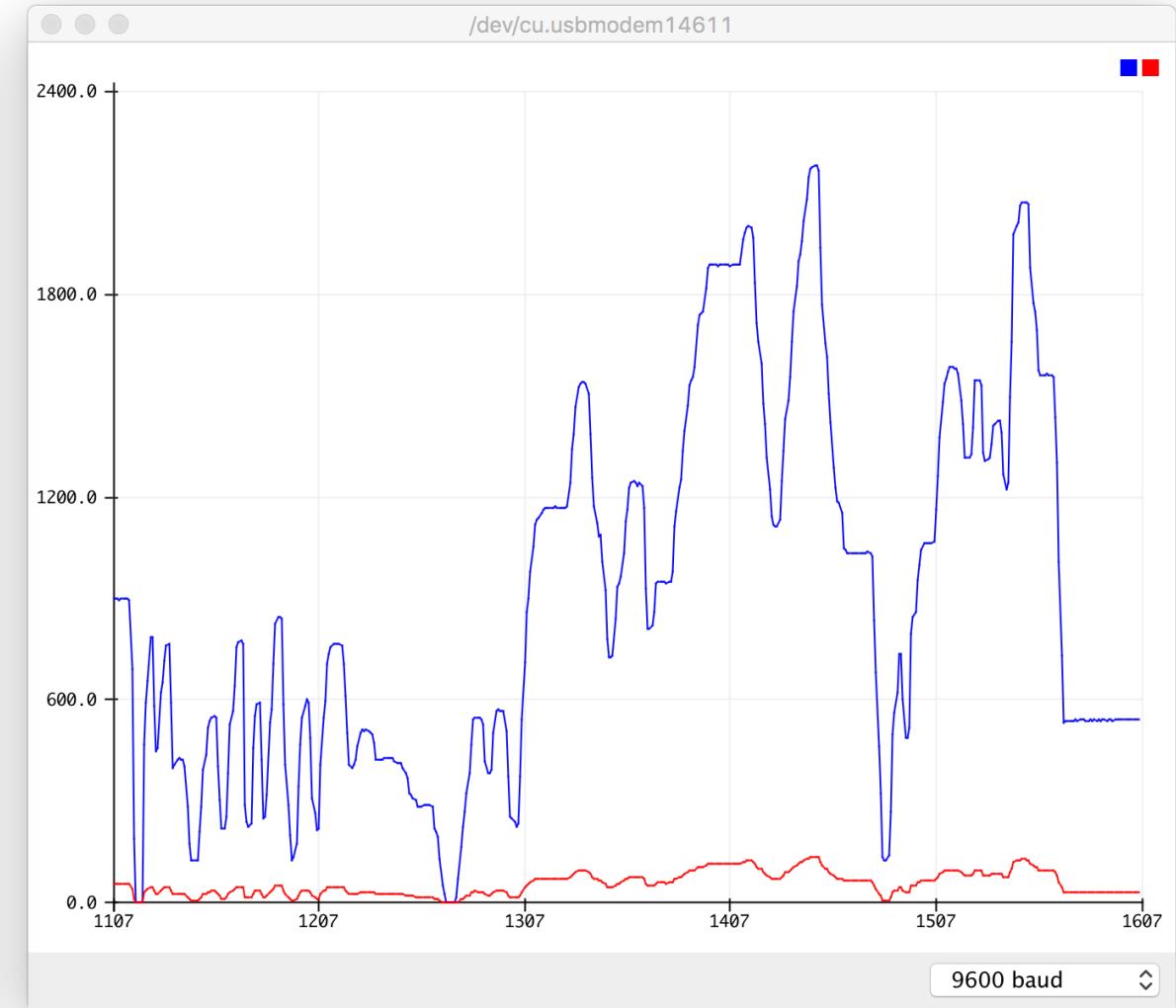
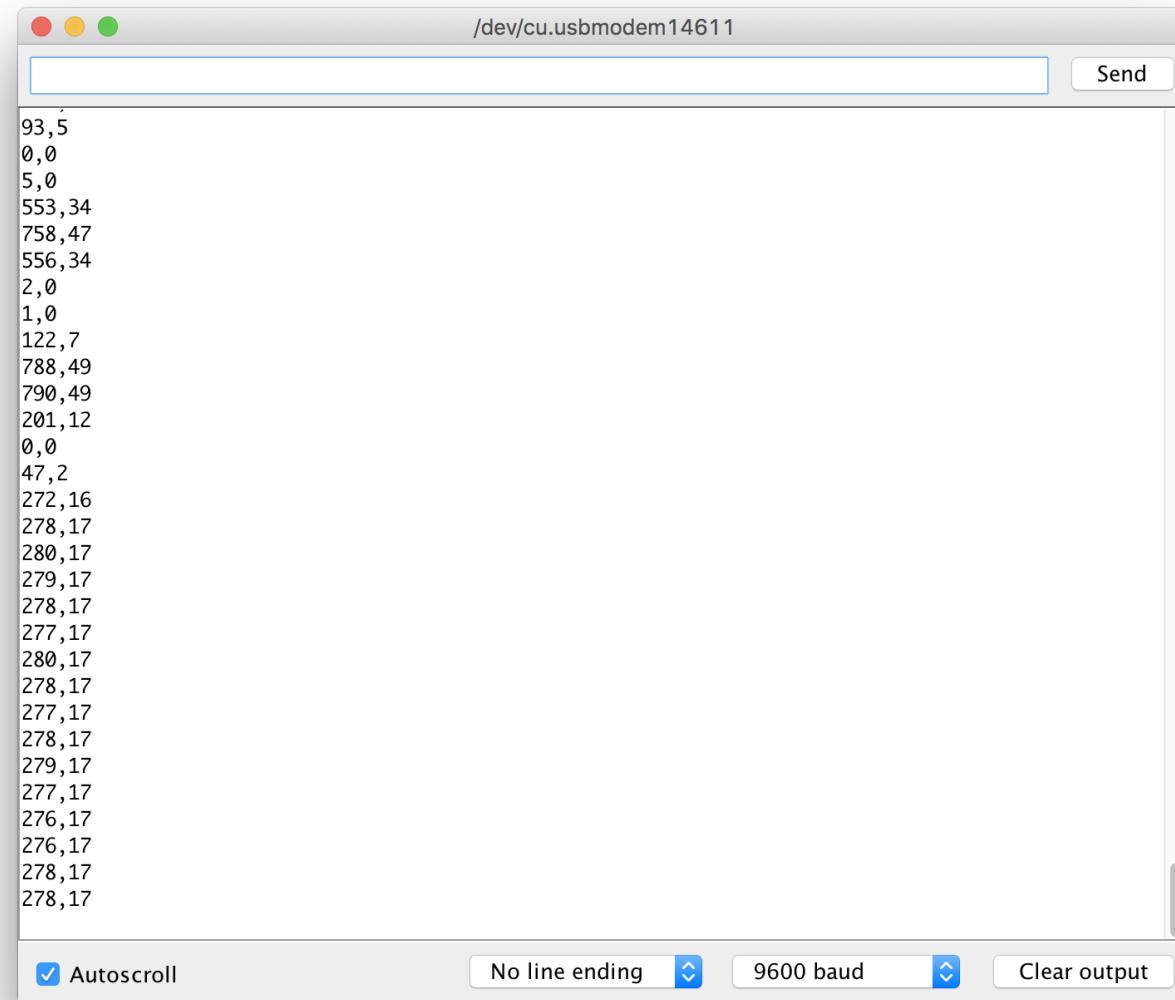
MacBook Pro



SERIAL PLOTTER

SERIAL MONITOR VS. PLOTTER

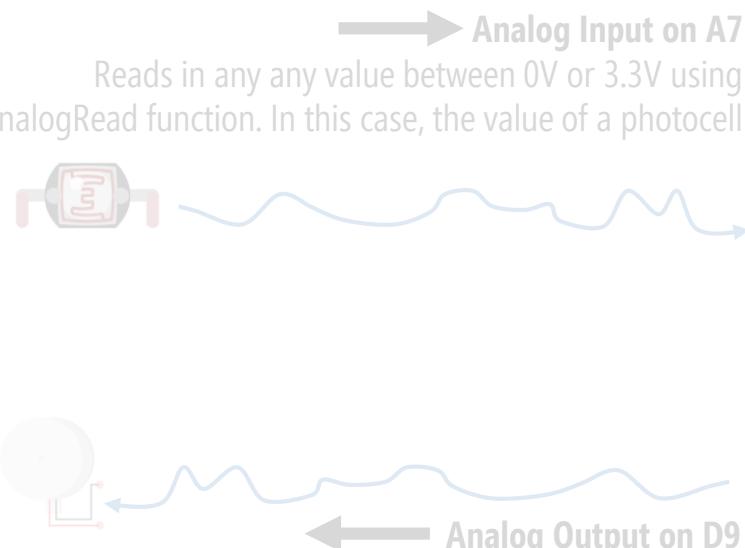
You can only have one of these windows open at once.



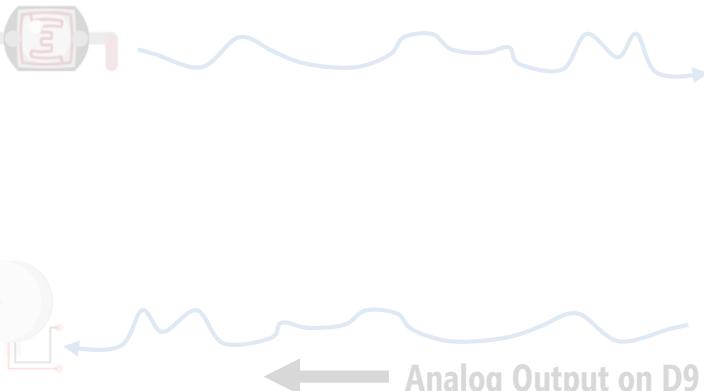
INPUT

DIGITAL INPUT

Finally, the last thing we are going to cover is digital input—which is not as straightforward as you might initially suspect.

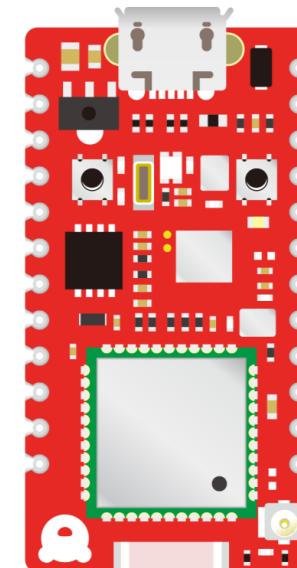


Analog Input on A7
Reads in any value between 0V or 3.3V using
analogRead function. In this case, the value of a photocell



Digital Input on D7
Reads in a digital input signal (anything below 1.65V
converted to LOW, anything above 1.65V converted
to HIGH). In this case, the value of switch.

VIN	
GND	
TX	D17
RX	D16
A7	D15
A6	D14
A5	D13
A4	D12
A3	D11
A2	D10
A1	D9
A0	D8



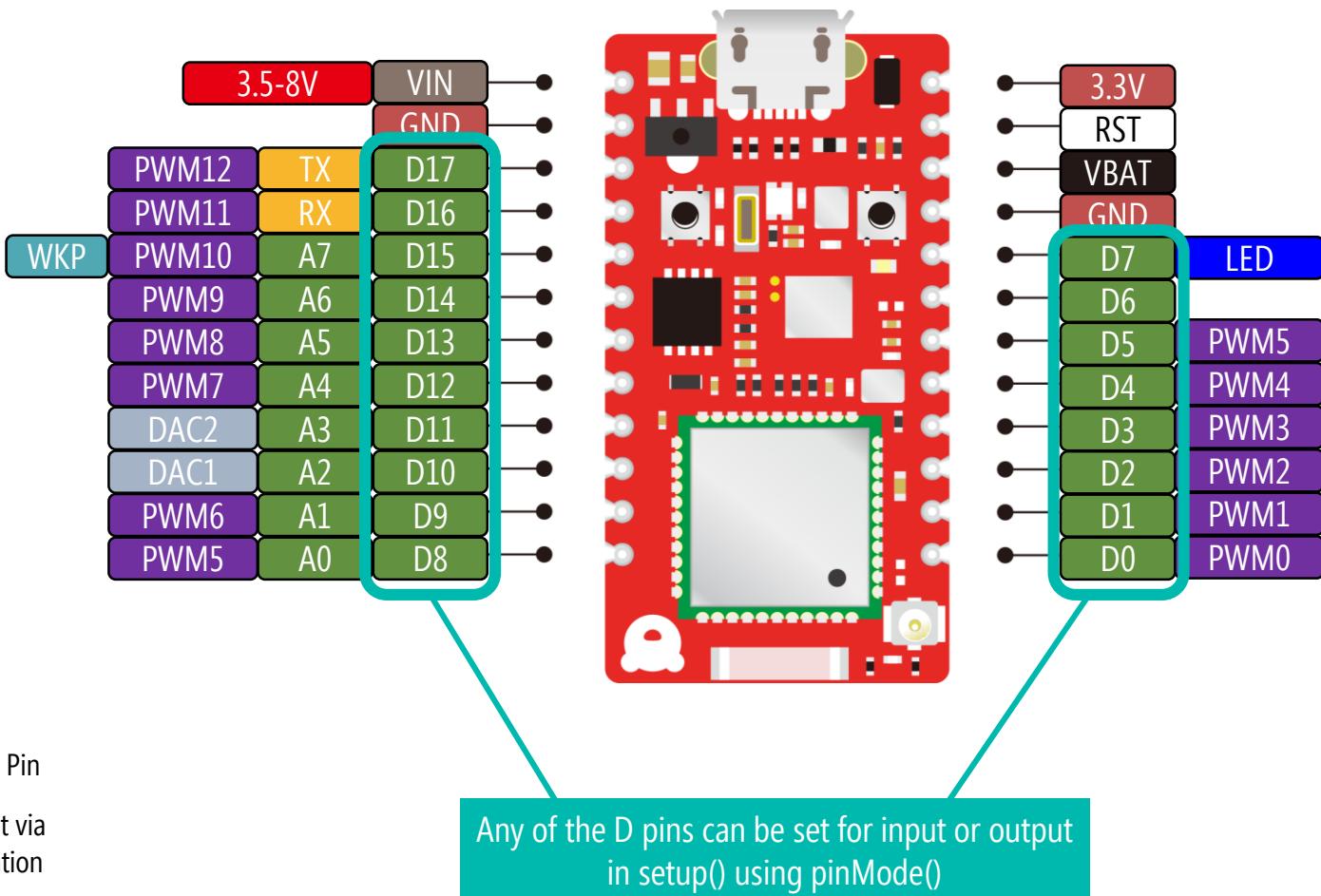
3.3V	
RST	
VBAT	
GND	
D7	
D6	
D5	
D4	
D3	
D2	
D1	
D0	

Digital Input on D7 ←
Reads in a digital input signal (anything below 1.65V
converted to LOW, anything above 1.65V converted
to HIGH). In this case, the value of switch.

Digital Output on D0 →
Writes out 0V or 3.3V using digitalWrite function.
In this case, turning on and off an LED.

DIGITAL INPUT

ANY OF THE D PINS CAN BE SET FOR DIGITAL INPUT OR OUTPUT

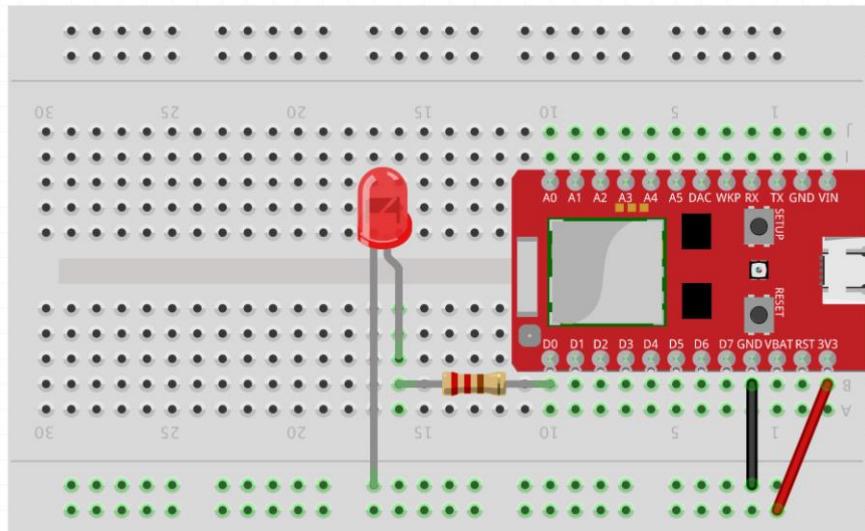


Let's design a circuit & write code to
turn **on** and **off** an **LED** with a **button**.

DIGITAL INPUT

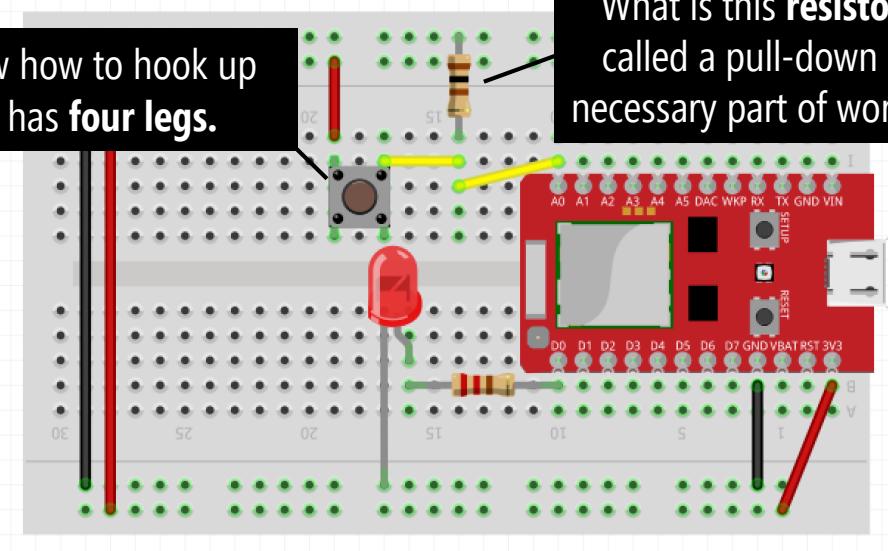
TURN ON/OFF LED WITH A BUTTON

Basic Circuit: Control LED via the D0 pin

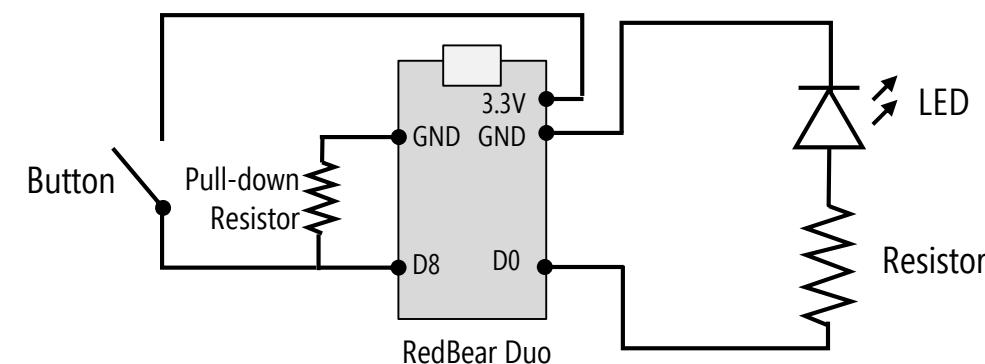
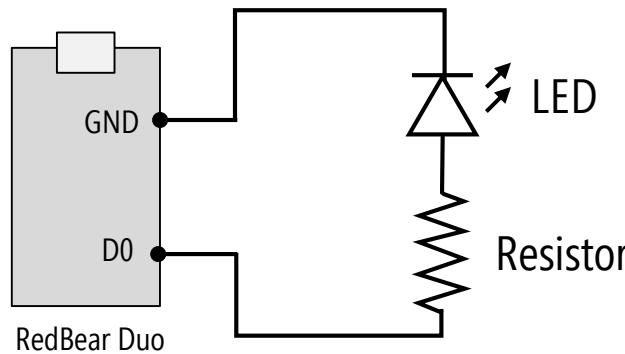


How do we know how to hook up this button? It has **four legs**.

New Circuit: Control LED via a button



What is this **resistor** doing here? It's called a pull-down resistor and it's a necessary part of working with switches.



DIGITAL INPUT

HOOKING UP BUTTON: CONSULT THE DATASHEET

OMRON

**Tactile Switch
B3F**

Miniature, Space-Saving Tactile Switch
Provides Long Service Life and Easy Mounting

Extended mechanical/electrical service life: 10×10^6 operations for 12×12 mm type and 1×10^6 operations for the 6×6 mm type

- Ideal for applications such as audio, office and communications equipment, measuring instruments, TVs, VCRs, etc.
- Taped radial type, vertical type and high force types are available as series versions
- Flux-tight base structure allows automatic soldering of the tactile switches onto a PC board
- Gold plated models available for increased contact reliability, resistance to corrosive gas and insulation fault prevention for ion migration in harsh environments
- RoHS Compliant

Ordering Information

■ B3F-1□□□, B3F-3□□□

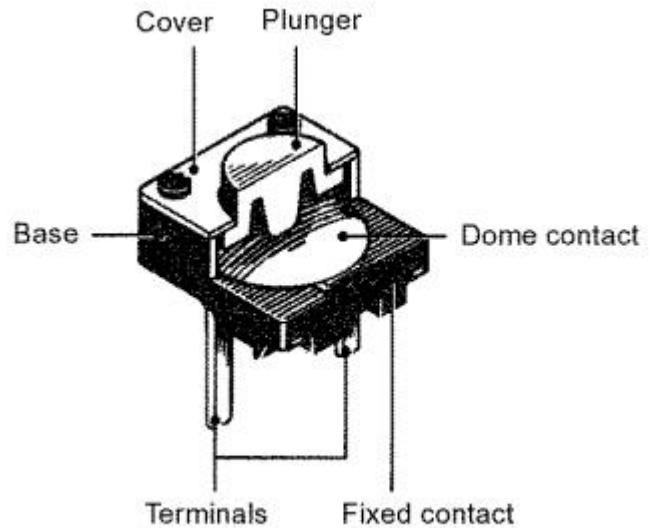
6 x 6 mm type

Type	Plunger	Switch height x pitch	Operating force	Model	
				Without ground terminal With ground terminal	
				Bags Sticks* Bags Sticks*	
Standard	Flat	4.3 x 6.5 mm	General-purpose: 100 g	B3F-1000 B3F-1000S B3F-1100 B3F-1100S	
			High-force: 150 g	B3F-1002 B3F-1002S B3F-1102 B3F-1102S	
		5.0 x 6.5 mm	General-purpose: 100 g	B3F-1005 B3F-1005S B3F-1105 B3F-1105S	
	High-force: 260 g		B3F-1008 B3F-1008S B3F-1108 B3F-1108S		
	Projected	5.0 x 7.5 mm	General-purpose: 100 g	B3F-1020 B3F-1020S B3F-1120 B3F-1120S	
			High-force: 150 g	B3F-1022 B3F-1022S B3F-1122 B3F-1122S	
		7.3 x 6.5 mm	General-purpose: 100 g	B3F-1025 B3F-1025S B3F-1125 B3F-1125S	
	Vertical	Flat	3.15 mm	General-purpose: 100 g	B3F-1050 B3F-1050S B3F-1150 B3F-1150S
				High-force: 150 g	B3F-1052 B3F-1052S B3F-1152 B3F-1152S
Projected		3.85 mm	General-purpose: 100 g	B3F-1055 B3F-1055S B3F-1155 B3F-1155S	
	High-force: 260 g		— — — —		
	6.15 mm	General-purpose: 100 g	B3F-3100 B3F-3102 B3F-3105 —		
	High-force: 150 g	— — — —			
	High-force: 260 g	— — — —			

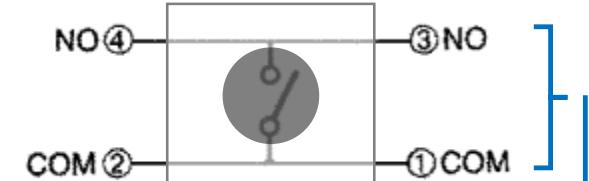
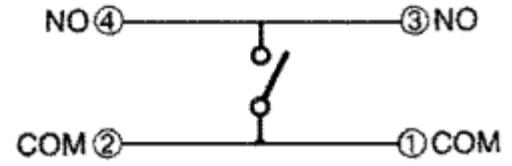
* Number of switches per stick:
Without ground terminal 90/stick
With ground terminal 75/stick

Important Note: Switches cannot be water-washed.

1128 Tactile Switch B3F



These two sides
become connected
when button is
pressed down



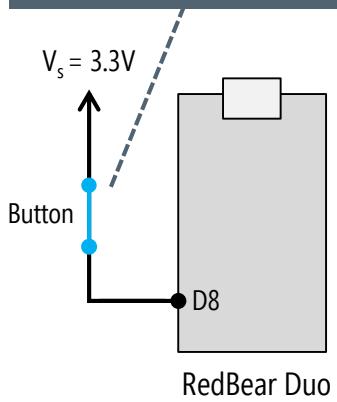
These two sides
become connected
when button is
pressed down



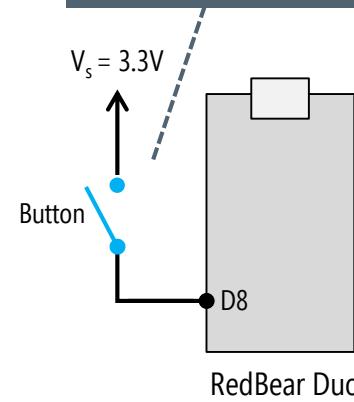
DIGITAL INPUT

HOOKING UP A BUTTON: PULL-DOWN RESISTORS

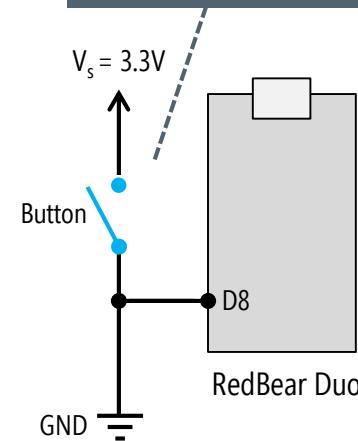
When this button is closed (as it is below), what would the **microcontroller** (MCU) **read** from the **input pin**?



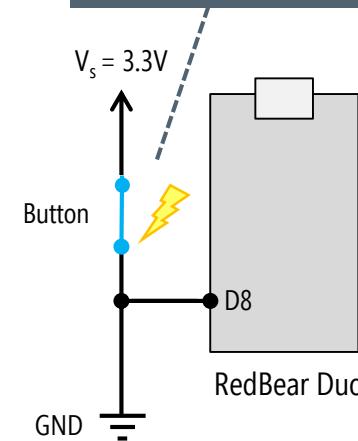
Now, when the **button switches to open**, what would the MCU read?



Well, can't we just solve that by **adding GND** here that "pulls" D8 to 0V when the switch is open?



Now, when the button is closed, we have a **short circuit** (V_s is connected to GND). This could damage our MCU!



Answer: The MCU would read 3.3V (or HIGH)

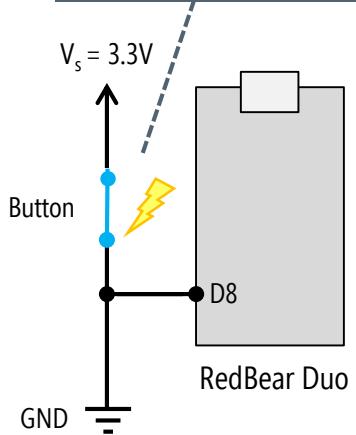
Answer: Uh, oh, the input pin is in an unknown state (commonly called "floating")—this is bad!

Answer: You're on the right track but this will create a short circuit when the button is closed!

Question: So, what do we do? We add what's called a pull-down resistor.

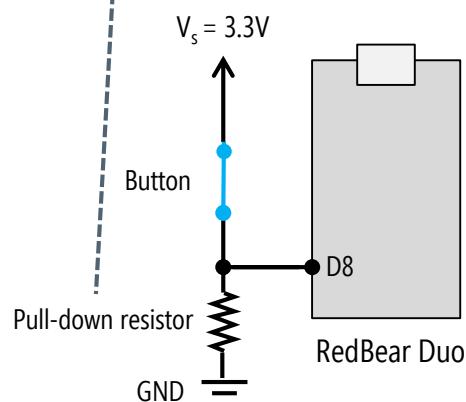
HOOKING UP A BUTTON: PULL-DOWN RESISTORS

Now, when the button is closed, we have a **short circuit** (V_s is connected to GND. This could damage our MCU)!



Question: So, what do we do?
We add what's called a pull-down resistor.

This resistor is called a "**pull-down resistor**" because it biases the input low (to GND) when the switch is open.



Now, when the switch is open,
the MCU is pulled to GND.
When the switch is closed, the
MCU is 3.3V (HIGH).

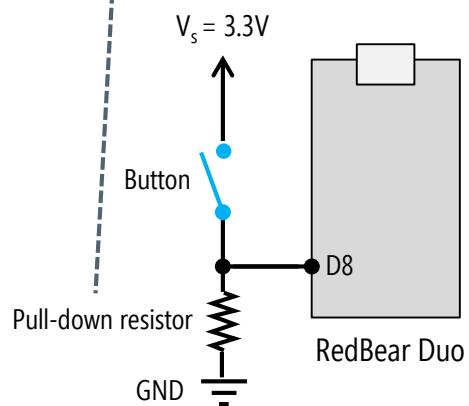
How do you choose the resistor value for the pull-down?

If you choose a low resistor value, more current will be “wasted” by flowing from V_s to GND when the button is closed. In contrast, a high resistor value (e.g., $4M\Omega$) may not work as a pull-down (not enough current will flow).

Arduino recommends using a $10K \Omega$ resistor.

PULL-UP VS. PULL-DOWN RESISTORS

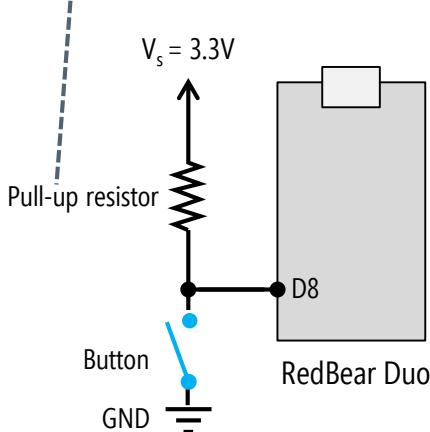
This resistor is called a “**pull-down resistor**” because it biases the input low (to GND) when the switch is open.



Pull-Down Resistor Configuration

When the switch is open, the MCU is pulled to GND. When the switch is closed, the MCU is 3.3V (HIGH) as it becomes directly connected to V_s .

This resistor is called a “**up resistor**” because it biases the input high (to V_s) when the switch is open.



Pull-Up Resistor Configuration

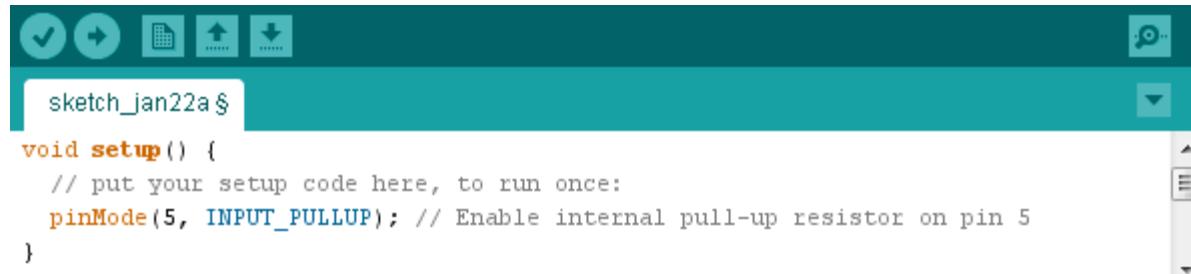
When the switch is open, the MCU is pulled to V_s . When the switch is closed, the MCU is 0V (LOW) as it becomes directly connected to GND.

You can wire up either pull-down resistor configurations or pull-up resistor configurations.

I have a preference towards pull-down resistors because it makes more sense to me that a switch is 0V (LOW) when open and 3.3 (HIGH) when closed.

MANY MCUS HAVE PULL-UP RESISTORS BUILT IN

Pull-up resistors are so commonly needed that many MCUs like the ATmega328 microcontroller have internal pull-up resistors ($20\text{k}\Omega$) that can be enabled or disabled.



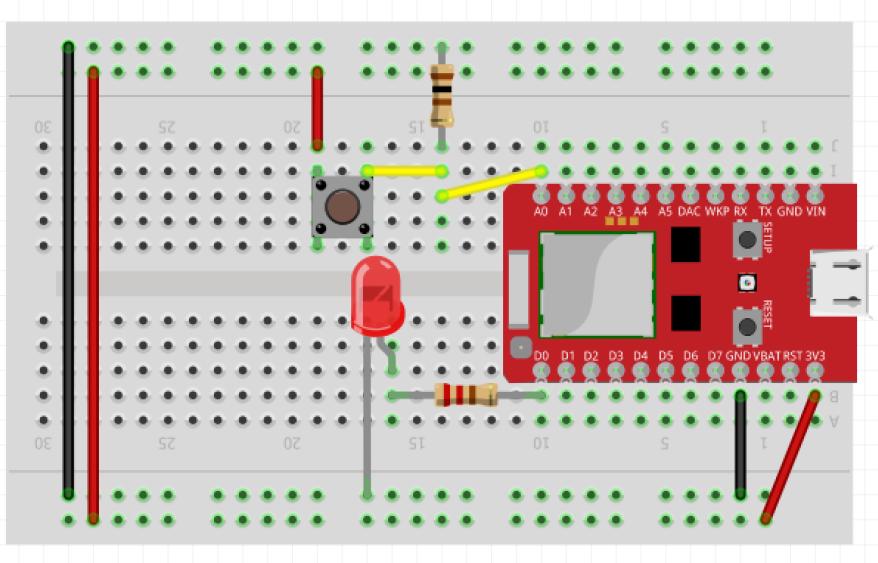
```
sketch_jan22a.ino
void setup() {
    // put your setup code here, to run once:
    pinMode(5, INPUT_PULLUP); // Enable internal pull-up resistor on pin 5
}
```

When connecting a sensor to a pin configured with INPUT_PULLUP, the other end should be connected to ground. In the case of a simple switch, this causes the pin to be read as HIGH when the switch is open and LOW when the switch is pressed (which is somewhat counterintuitive!).

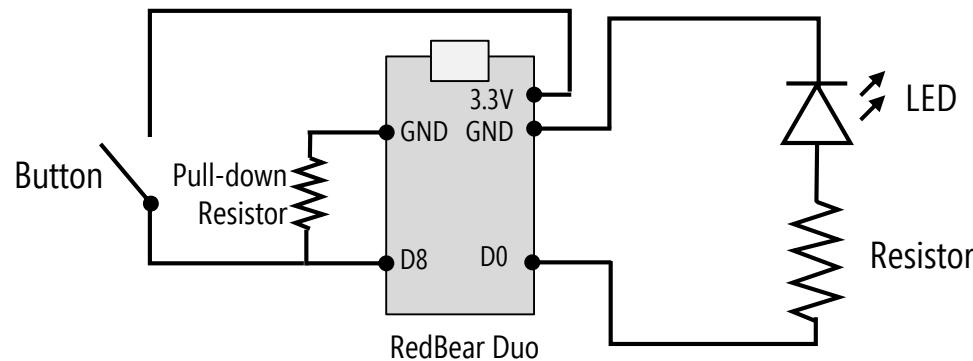
DIGITAL INPUT

TURN ON/OFF LED WITH A BUTTON

Circuit: Control LED via a button



Now we just have to write the Arduino code to take in the button state and turn on/off the LED accordingly.



DIGITAL INPUT: DIGITALREAD()

Reads the value from a specified digital ping and returns either HIGH or LOW

Syntax

```
digitalRead(pin)
```

Parameters

pin: the digital I/O pin you want to read

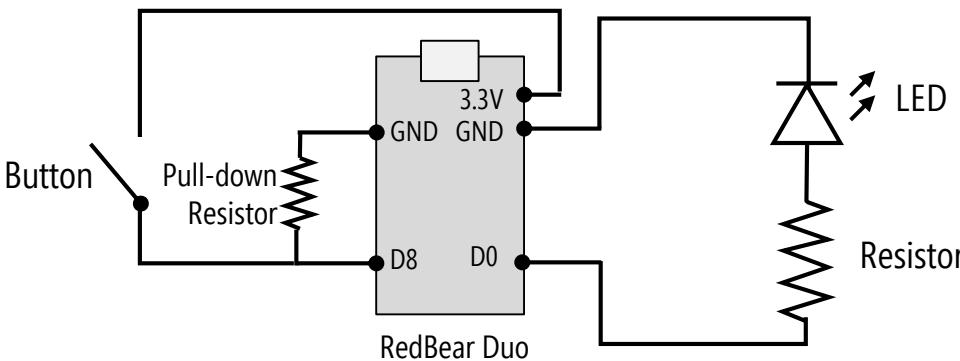
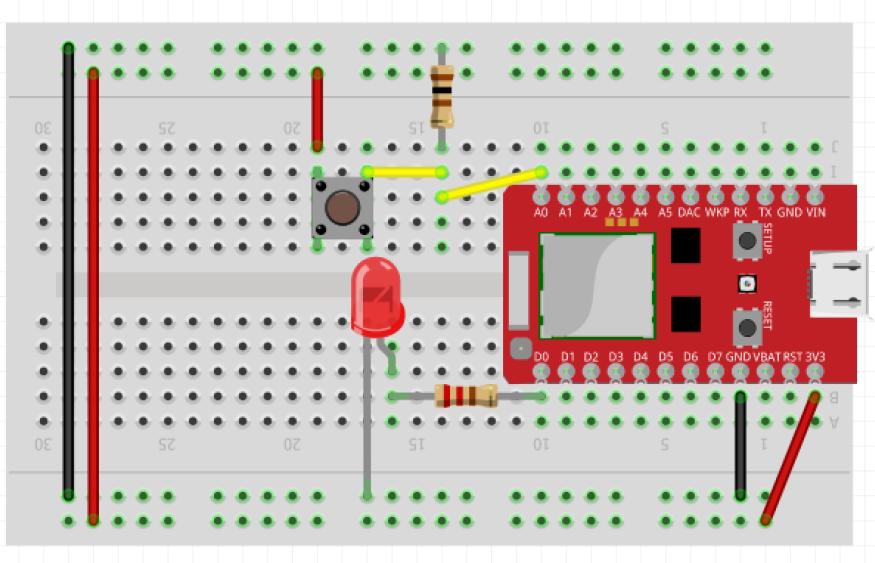
Returns

HIGH or LOW

DIGITAL INPUT

TURN ON/OFF LED WITH A BUTTON

Circuit: Control LED via a button



Code: Read button state and set LED on/off accordingly

```
RedBearDuoReadButtonSetLED | Arduino 1.8.5
File Edit Sketch Tools Help
RedBearDuoReadButtonSetLED §
/*
 * This example reads in a button input on D8 (with a pull-down resistor configuration)
 * and turns on/off an LED on D0 accordingly
 *
 * By Jon Froehlich for CSE590
 * http://makeabilitylab.io
 */
SYSTEM_MODE(MANUAL);

const int LED_OUTPUT_PIN = D0;
const int BUTTON_INPUT_PIN = D8;

void setup() {
  pinMode(LED_OUTPUT_PIN, OUTPUT);
  pinMode(BUTTON_INPUT_PIN, INPUT);
  Serial.begin(9600);
}

void loop() {

  // read the button value. It will be HIGH when pressed and
  // LOW when not pressed
  int buttonVal = digitalRead(BUTTON_INPUT_PIN);

  // Write out HIGH or LOW
  digitalWrite(LED_OUTPUT_PIN, buttonVal);

  // Check for new input every 100ms
  delay(100);
}
```

