Hello, Hello, World!

- Porting GO to ucore.

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- Analysis of the program "Hello world";
- Set up GDB debugging environment;

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• Get to know the basic porting requirements;



 Research on syscalls to be implemented;

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Confirm the maximum working set;

• Set up experiment environment and succeed in cross-compiling. Extract the os-dependent package;



• Tool chain: a python script;

• runtime • exit1: exit the current os thread;

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- Minimize working set;
- Tool chain: a shell script;
- runtime · setldt:fake ldt entries;



- Fix some bug in runtime write: stderr, etc;
- runtime
 rt_sigaction: set
 to a direct return;

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• runtime • write: repeated calls to putc();



runtime · mmapimplementation;

• Disable environment constants and starting-up arguments;

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runtime · mmap implementation: the "with hint" version;



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• "Hello, world!"

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• Read through Go specifications;

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- Advanced hello world: using "fmt" package. "fmt" is os-independent -> "syscall" package;
- Read through Go specifications;
- peter.go: a
 program used for
 thread test;

peter.go

```
package main
import
        "fmt"
        //"time"
var c chan int
func ready(index int) {
        //time.Sleep(5e9)
        fmt.Println(index)
        c < -1
func main() {
        total := 100
        c = make(chan int)
        for i := 0; i < total; i++ {
                go ready(i)
        for i := 0; i < total; i++ {
                <- C
```



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Research on goroutines in Linux;

• Clone: return pid as tid;

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 Attempts on semaphore: cause ucore to "reboot";

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• Updated version of the shell script: originates from the one used for a demo.

demo.sh

- -ng: disables the entire compiling of the Go compiler;
- -nre: disables the part-recompile of our packages (those lie in patch);
- -ntest: disables the compiling of the whole testsuit;
- Recursively compile all test cases;
- Automatically detect Makefile;
- Automatically generate testall.sh under each folder, which will be used in ucore;



• Semaphore again: the nextm problem;

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• Semaphore again: we are pretty sure the semaphore is set correctly, but still not working;

Lock/Unlock in Go

• The user-mode lock/unlock:

```
54 void
55 runtime·lock(Lock *l)
56 {
      if(m->locks < 0)
57
58
           runtime · throw("lock count");
59
       m->locks++;
60
61
       if(runtime \cdot xadd(&l->key, 1) > 1) { // someone else has it; wait
           // Allocate semaphore if needed.
62
63
           if(l->sema == 0)
64
               initsema(&l->sema, 0);
           runtime·sem wait(l->sema, 0);
65
66
```



• Stuck in gcc 4.6 bootblock size;

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- sleep: replace the former one using select;
- A user-leveled simulator: semtest5.c



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- Finally focus on the gs: ucore would not store/restore fs/gs! This would cause an unexpected running stream;
- Add fs/gs swap, problem solved;
- The Println problem: it's not.

The Println problem: it's not.



• Succeed in compiling ucore bootblock with gcc 4.6

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• exit_group: exit all threads attached with the current os thread. Two attempts;



• Testsuit;

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- Testsuit;
- Environment constant: now contains "GOARCH=386", which is used for env.go;

Testsuit categories

- Compiler test: expected compiling error, tested and excluded;
- Linked test: provided for other test cases, normally requires Makefile;
- Generator test: used to generate another go file. Replaced;
- The rest: listed in testall.sh, should be tested in ucore. Panic on error (except for the panic test, see wiki);

To be done

• Signal!

We have looked through the whole runtime package, which is the base of the GO world, and signal is the only one that has not been implemented;

Thanks!