

# Autotuning with Cloud Computing

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## Abstract

This research project presents a proposal for a conference paper. The objective is to extend the OpenTuner autotuning framework to leverage the cloud computing resources from Google Compute Engine. An overview of the autotuning research area is presented, supporting the novelty and contribution potential of this proposal. The objectives and current work are discussed in detail, and a research schedule is presented.

## 1 Introduction

The program autotuning problem fits in the framework of the Algorithm Selection Problem, introduced by Rice in 1976 [16]. The objective of an autotuner is to select the best algorithm, or algorithm configuration, for each instance of a problem. Algorithms or configurations are selected according to performance metrics such as the time to solve the problem instance, the accuracy of the solution and the energy consumed. The set of all possible algorithms and configurations that solve a problem define a *search space*. Guided by the performance metrics, various optimization techniques search this space for the algorithm or configuration that best solves the problem.

Autotuners can specialize in domains such as matrix multiplication [3], dense [19] or sparse [18] matrix linear algebra, and parallel programming [13]. Other autotuning frameworks provide more general tools for the representation and search of program configurations, enabling the implementation of autotuners for different problem domains [2, 12].

Figure 1 shows the Algorithm Selection Problem framework. Bougeret *et al.* [5] proved that the Algorithm Selection Problem is NP-complete when calculating

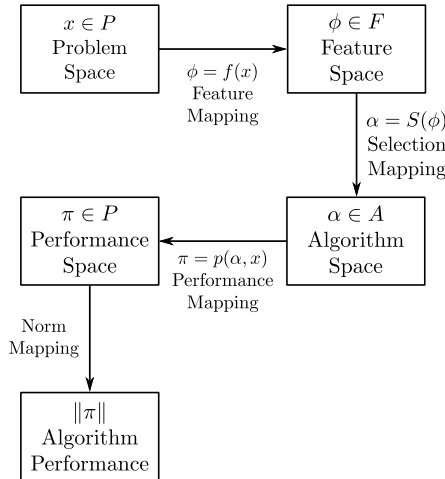


Figure 1: Rice’s Algorithm Selection Framework [16].

static distributions of algorithms in parallel machines. Guo [8] proved the problem is undecidable in the general case.

This research proposal consists in the implementation of an extension to the OpenTuner framework [2] that will enable it to leverage cloud computing resources. The remaining of this document is organized as follows. Section 2 discusses related work and the OpenTuner framework. Section 3 presents a detailed discussion of the objectives and reports the current state of the research. Section 4 discusses the methods and benchmarks that will be used to test and validate the implementations. Section 5 presents a preliminary schedule. Section 6 concludes the proposal.

## 2 Related Work

Rice’s conceptual framework [16] formed the foundation of autotuners in various problem domains. In 1997, the PHiPAC system [3] used code generators and search scripts to automatically generate high performance code for matrix multiplication. Since then, systems tackled different domains with a diversity of strategies. Whalley *et al.* [19] introduced the ATLAS project, that optimizes dense matrix multiply routines. The OSKI [18] library provides automatically tuned kernels for sparse matrices. The FFTW [7] library provides tuned C subroutines for computing the

Discrete Fourier Transform. In an effort to provide a common representation of multiple parallel programming models, the INSIEME compiler project [13] implements abstractions for OpenMP, MPI and OpenCL, and generates optimized parallel code for heterogeneous multi-core architectures.

Some autotuning systems provide generic tools that enable the implementation of autotuners in various domains. PetaBricks [1] is a language, compiler and autotuner that introduces abstractions, such as the `either...or` construct, that enable programmers to define multiple algorithms for the same problem. The ParamILS framework [12] applies stochastic local search methods for algorithm configuration and parameter tuning. The OpenTuner framework [2] provides ensembles of techniques that search spaces of program configurations. Bosboom *et al.* and Eliahu use OpenTuner to implement a domain specific language for data-flow programming [4] and a framework for recursive parallel algorithm optimization [6].

In a progression of papers [9, 10, 11], Gupta *et al.* provide experimental evaluations of the application of cloud computing to high performance computing, describing which kind of applications has the greatest potential to benefit from cloud computing. Their work highlights small and medium scale projects as the main beneficiaries of cloud computing resources.

## 2.1 OpenTuner

OpenTuner search spaces are defined by *Configurations*, that are composed of *Parameter* of various types. Each type has restricted bounds and manipulation functions that enable the exploration of the search space. OpenTuner implements ensembles of optimization techniques that perform well in different problem domains. The framework uses *meta-techniques* to coordinate the distribution of resources between techniques. Results found during search are shared between techniques through a database. An OpenTuner application can implement its own search techniques and meta-techniques, making the ensemble more robust.

Figure 2 shows a high-level view OpenTuner’s architecture. Measurement and searching are done in separate modules, called drivers, that share results through the database. The search driver requests measurements by registering configurations to the database. The measurement driver reads those configurations and

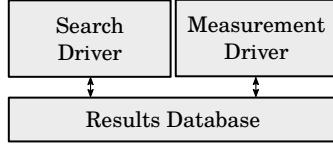


Figure 2: Simplified OpenTuner Architecture.

writes back the desired results. Currently, the measurements are performed sequentially.

OpenTuner implements optimization techniques such as the Nelder-Mead [15] simplex method and Simulated Annealing [14]. OpenTuner implements a resource sharing mechanism that aims to take advantage of the strengths of each technique. A meta-technique must balance the exploitation of a technique that has produced good results in the past and the exploration of new, and possibly best, techniques.

### 3 Objectives

The objectives of this research project are the following:

- Implement an extension to the OpenTuner measurement driver, the *MeasurementClient*, that requests virtual machines in the Google Compute Engine to produce measurements of configurations;
- Implement a *MeasurementServer* that runs in the virtual machines. The server receives requests for results, computes them, and send them to the client;
- Normalize the results obtained from virtual machines to the local machine;
- Evaluate the performance of the implementation, using the benchmark applications provided with OpenTuner [2].

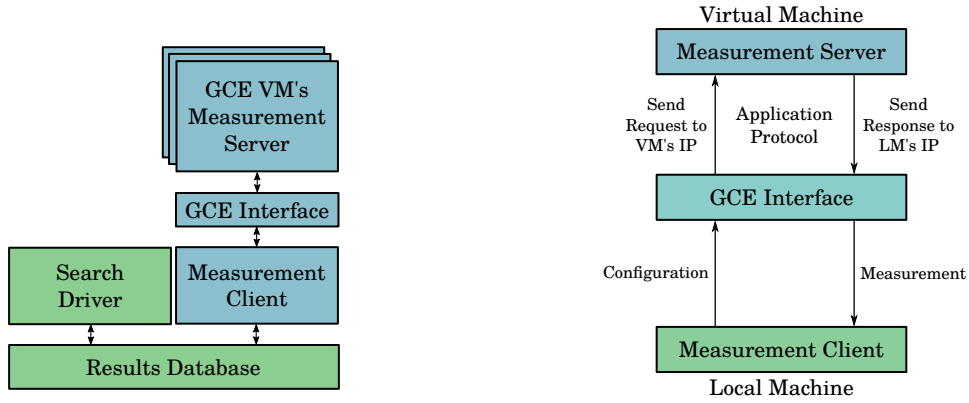
The remaining of this section describes the implementation objectives in detail, and reports the current state of the research. Section 4 describes the performance evaluations and the benchmark.

### 3.1 Measurement Server and Client

The interactions between the local and virtual machines will follow the client-server model. The local machine will run a measurement client, that will request results from various measurement servers running in virtual machines hosted at the Google Compute Engine.

Figure 3a shows the proposed architecture of an OpenTuner application running the measurement client and communicating with the measurement servers. Green boxes in the figure represent OpenTuner modules that will not be modified, and blue boxes represent new or modified modules.

Figure 3b shows, on a lower level of abstraction, the interactions between the measurement client and servers. A simple application protocol will be devised to mediate the requests and responses. The configurations will be sent to the server, that will run the correspondent program and respond with the measurement.



(a) A high-level view of the proposed architecture. Green boxes represent unmodified modules, blue boxes represent new or modified modules.

(b) A lower-level view of the proposed architecture, illustrating the communication between server and client, mediated by the Google Compute Engine API.

Figure 3: Proposed OpenTuner Architecture, using the Google Compute Engine (GCE) API.

OpenTuner controls the execution flow of an application with the `main` function of the `TuningRunMain` class. This function calls the `main` function of the search driver, which runs the main loop of an OpenTuner application. The search driver generates configurations to be tested and saves them to the database. It then calls

the `process_all` function of the measurement driver and blocks until the function returns.

The measurement driver is able to compile programs in parallel, but the measurements are done sequentially. Listing 1 shows the functions of the measurement driver that will have to be modified for the `MeasurementClient` to be able to process results with the Google Compute Engine.

During its initialization, the measurement client will initialize and configure the virtual machines, storing each measurement server's IP in the GCE interface. When the search driver requests for results, the `process_all` function will route the requests to the servers via the GCE interface. The interface will call the appropriate GCE Python API functions to send requests to the servers, and will wait for their responses.

The OpenTuner source code is available<sup>1</sup> under the MIT License.

```
class MeasurementClient(MeasurementDriver):
    """
    Reads DesiredResults and requests VMs
    in the cloud to compute Results.
    """
    def __init__(self,
                  measurement_interface,
                  input_manager,
                  **kwargs):
        super(MeasurementDriver, self).__init__(**kwargs)
        """
        Instantiate and configure the VM Measurement
        Servers using the GCE interface.
        """

    def process_all(self):
        """
        Process all results in the
        database, by sending requests to
        VMs in the cloud and waiting
        for responses.
        """
```

Listing 1: Proposed modifications to `MeasurementDriver`.

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<sup>1</sup>The code is hosted at GitHub: [github.com/jansel/opentuner](https://github.com/jansel/opentuner)

## 3.2 Normalizing the Results

The autotuner will optimize programs for a machine that will typically have an architectural specification different from the machines in the cloud. A normalization technique must be devised that enables the results found in the virtual machines to be valid for the local machine. Four preliminary approaches to this problem are discussed in the following.

### Use OpenTuner to Model Performance

Another autotuner could be used to optimize parameters of a simple performance model, that would associate a configuration's measurement and the virtual machine that produced it with a conversion function. This function should map the performance result to the target architecture, producing a valid result.

### Compose Ensembles of Virtual Machines

The cloud application could be composed of virtual machines with different architectures. The final performance measurement for a configuration would then be built from the results obtained in these different virtual machines.

### Simulate the Target Architecture

The target machine could be modeled by an architecture simulator such as *zsim* [17], a simulator for multi-core architectures available<sup>2</sup> under the GNU General Public License. Using a simulator would solve the normalization problem but introduce other problems, such as the simulator's accuracy and performance.

### Run the Autotuner in the Cloud

Finally, the normalization problem could be sidestepped, at least in initial research, by running the servers and clients in the cloud using the same kind of virtual machine.

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<sup>2</sup>Hosted at GitHub: <https://github.com/s5z/zsim>

### 3.3 Using the Google Compute Engine

Simple experiments with GCE have been performed. A project was started and utility functions were implemented. The utilities include adding and removing virtual machines, configuring firewall access rules, configuring virtual machines with a startup script and obtaining a virtual machine’s IP.

Each virtual machine is setup and starts running a simple Python TCP echo server at the **8080** port. Figure 2 shows the code for the server.

The utility functions and the measurement server’s and client’s code are available<sup>3</sup> under the GNU General Public License.

```
#!/usr/bin/env python

import socket

TCP_IP = ''
TCP_PORT = 8080
BUFFER_SIZE = 1024

s = socket.socket(socket.AF_INET, socket.SOCK_STREAM)
s.bind((TCP_IP, TCP_PORT))
s.listen(1)

conn, addr = s.accept()

while 1:
    data = conn.recv(BUFFER_SIZE)
    if not data: break
    conn.send(data)
```

Listing 2: A simple echo server in Python.

## 4 Experiments

A benchmark of applications will be composed to compare the performance of the OpenTuner framework with and without the proposed modifications. An ideal benchmark would comprise the applications used to validate OpenTuner [2]. The normalization techniques devised for the results from virtual machines will be compared using the same benchmark.

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<sup>3</sup>All code is hosted at GitHub:  
[github.com/phrb/measurement-server](https://github.com/phrb/measurement-server)  
[github.com/phrb/autotuning-gce](https://github.com/phrb/autotuning-gce)



We expect that the experiments provide insight into the situations when using cloud computing resources for autotuning is beneficial, and into the application and efficiency of the result normalization techniques.

## 5 Research Schedule

Table 1 presents a first version of the research schedule following the assignment’s delivery dates. The schedule spreads the tasks so that portions of the work predicted to be harder are assigned to longer time frames.

<b>AP2 &amp; PR 25/09</b>	<b>AR1 16/10</b>	<b>AP3 &amp; AR2 13/11</b>	<b>AR3 25/11</b>
Paper proposal.	First version of the paper.	Second version of the paper.	
10-minute presentation.	Measurement Client implementation.	20-minute presentation.	Final version of the paper.
Preliminary experiments at GCE.	Result normalization techniques.	Measurement Server implementation.	Experiments, results and analysis.
High and low-level views of the implementation.	GCE Interface implementation.	Application protocol specification.	

Table 1: Task scheduling for the project.

## 6 Conclusion

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