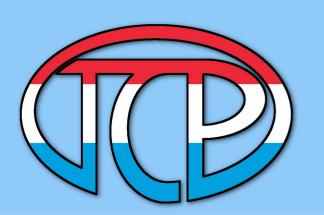
A jumpstart into machine-learning

Dahvyd Wing

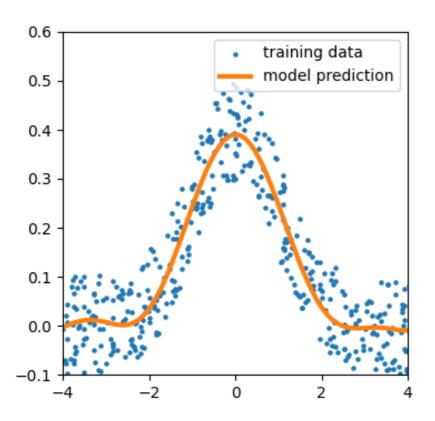




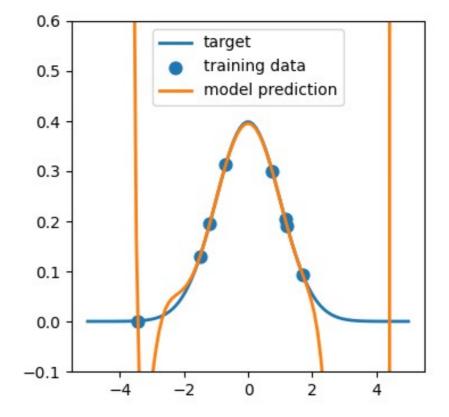


Regression for computational chemistry

Most applications: lots of noisy data



Our case: few data points with almost no noise



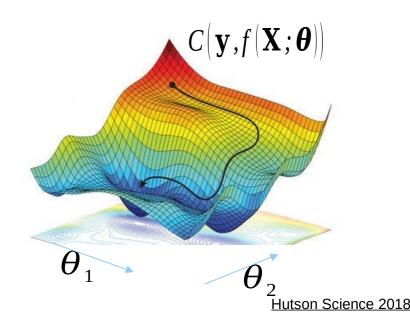
1. Data:

2. Model:

are trainable parameters

3. Cost function: mean squared error (MSE)

4. Find using gradient descent



Pytorch example lj_1_overfit.py

- 1. Open anaconda prompt
- 2. conda activate ml_tutorial
- 3. Go to ml_tutorial folder
- 4. spyder &
- 5. In spyder open lj_1_overfit.py

1. Data:

- Instance/object of a customized dataset class
- Implement 3 functions: __init__, __len__, and __get_item__
- dataloader pulls random batches of data from the dataset



1. Data:

- 2. Model:
 - Instance/object of a customized nn.module class
 - Implement 2 functions: __init__ and __forward__
 - Descriptor:

One hot encoding:

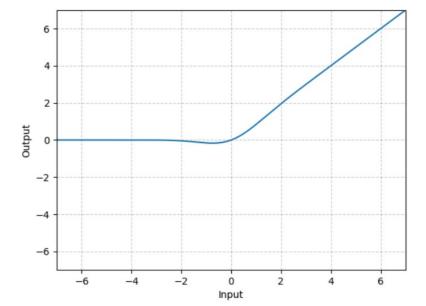
Continuous data: x=3.1 \bigcirc 0.5 0.3 0.01 0 0) $\phi_1(x)$ $\phi_2(x)$ $\phi_3(x)$ $\phi_3(x)$

1. Data:

2. Model:

- Instance/object of a customized nn.module class
- Implement 2 functions: __init__ and __forward__
- Descriptor
- Neural network:

is the nonlinear activation function: GELU



Use a continuously differentiable activation function

$$y_{pred} = \boldsymbol{w_3} \cdot \boldsymbol{y_3} + b_3$$

- 1. Data:
- 2. Model:
- 3. Cost function:
 - Mean squared error

1. Data:

2. Model:

3. Cost function:

4. Find

Batch 1

, ,

 $\boldsymbol{\theta}' = \boldsymbol{\theta} - \nabla_{\boldsymbol{\theta}} C(\mathbf{y}, f(\mathbf{X}; \boldsymbol{\theta}))$

Batch 2

, ,

$$\boldsymbol{\theta}' = \boldsymbol{\theta} - \nabla_{\boldsymbol{\theta}} C(\mathbf{y}, f(\mathbf{X}; \boldsymbol{\theta}))$$

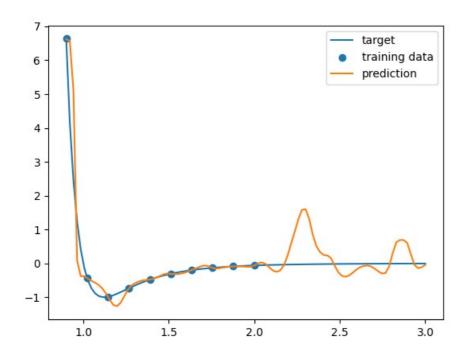
Batch 3

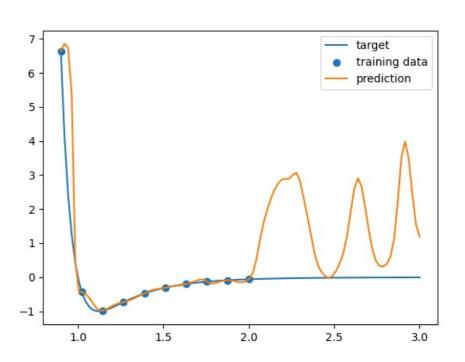
, ,

$$\boldsymbol{\theta}' = \boldsymbol{\theta} - \nabla_{\boldsymbol{\theta}} C(\mathbf{y}, f(\mathbf{X}; \boldsymbol{\theta}))$$
 $\boldsymbol{\theta}' = \boldsymbol{\theta} - \nabla_{\boldsymbol{\theta}} C(\mathbf{y}, f(\mathbf{X}; \boldsymbol{\theta}))$

Overfitting

- NNs often have many more parameters than samples in the training data
- Run lj_1_overfit.py several times
 - 6,601 trainable parameters, 10 data points

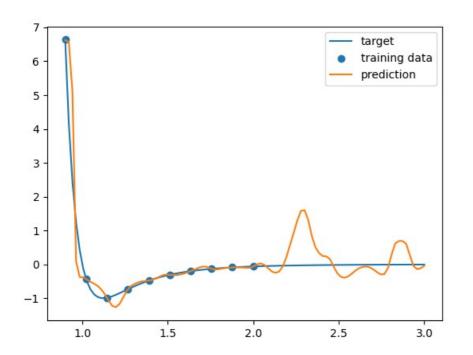


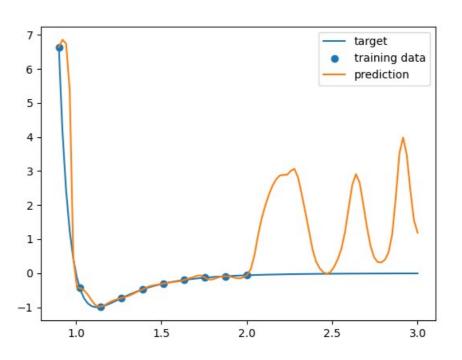


• Each model perfectly fits the training points, but doesn't do a great job in the interpolation region You measure a model by testing on data it has never seen

Overfitting

- NNs often have many more parameters than samples in the training data
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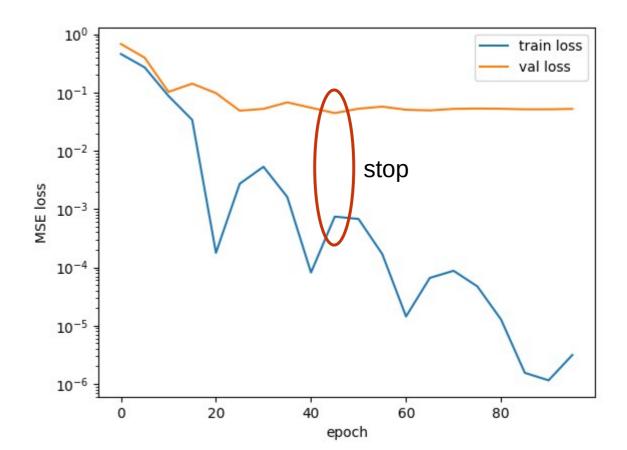
- Each model perfectly fits the training points, but doesn't do a great job in the interpolation region
- The models do terrible in the extrapolation regime

Validation and test sets

- Separate your data into a training set, a validation set, and a test set
- Validation set used to measure overfitting and tune hyperparameters
- Test set is only used for the final model to get a final estimate of how accurate the model really is

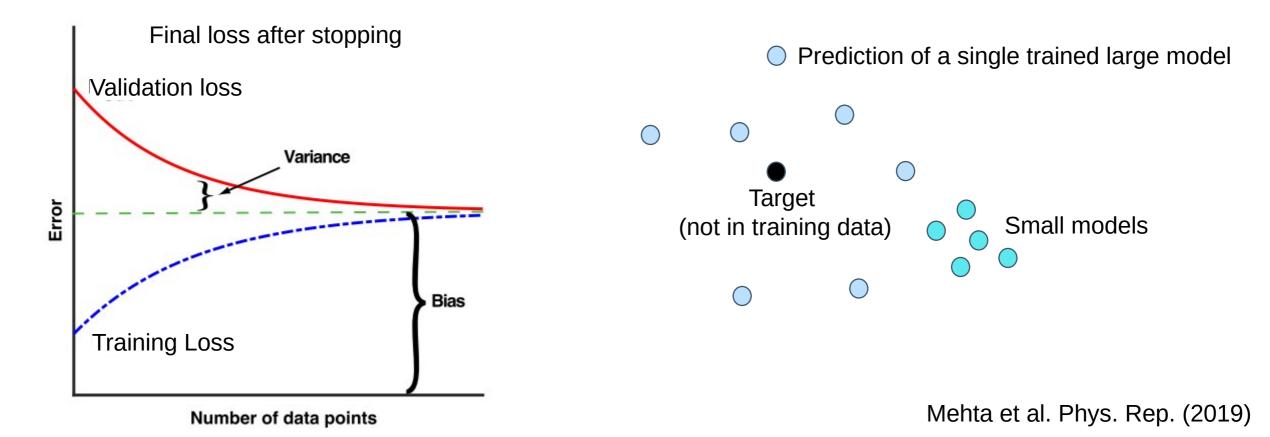
- Run lj_2_overfit_with_validation.py
 - The main change in the code is lines 56-58

 To get the best performance model stop when there is a steady increase in validation loss and decrease in training loss (early stopping)



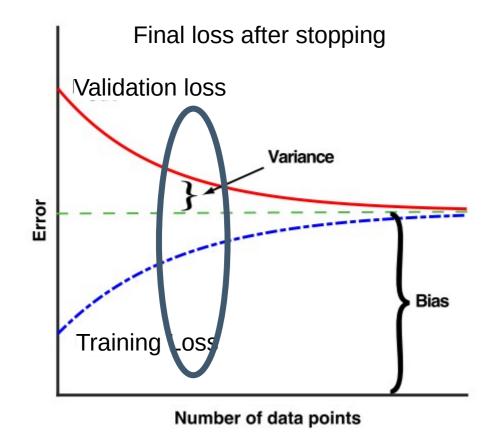
Learning curve

- With enough data the validation loss and training loss should converge
- Variance: a models trained with different, but equal number of points yield different results
 - The more parameters, the more variance in the model
- Large high variance models overfit



Learning curve

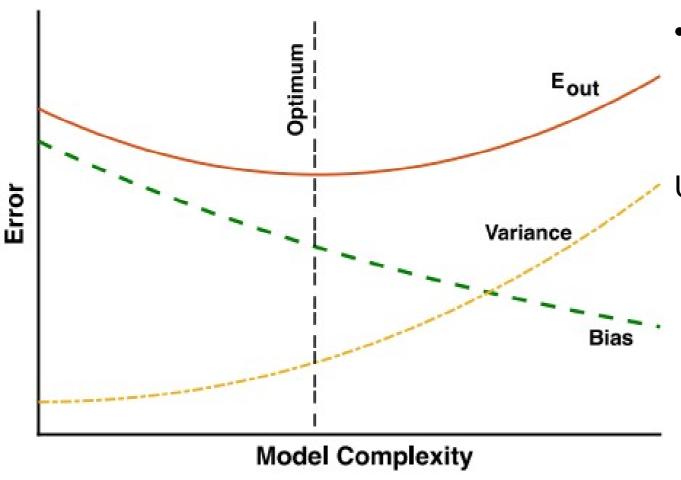
- With enough data the validation loss and training loss should converge
- Variance: a models trained with different, but equal number of points yield different results
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- Enough data removes variance
- We are always working in the low data regime

Bias variance tradeoff

• There is an optimum size of your model for a given amount of data.



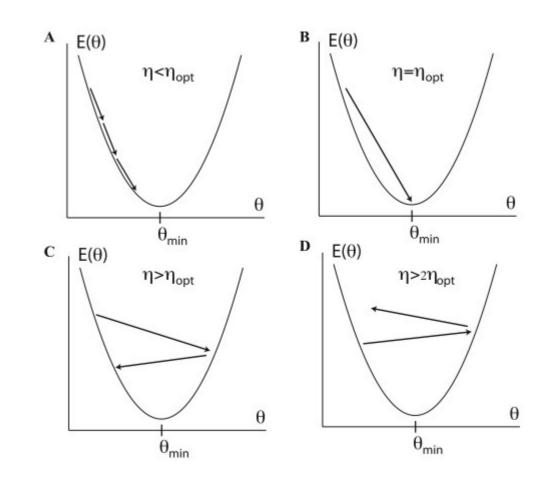
- L2 regularization lowers variance.
 - Prevents overfitting
 - Allows you to use larger models

Use the right amount of regularization

Find: Gradient descent

$$\boldsymbol{\theta}_{t+1} = \boldsymbol{\theta}_t + \boldsymbol{v}_t$$

- Momentum algorithms
 - Build up speed in shallow directions

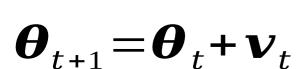


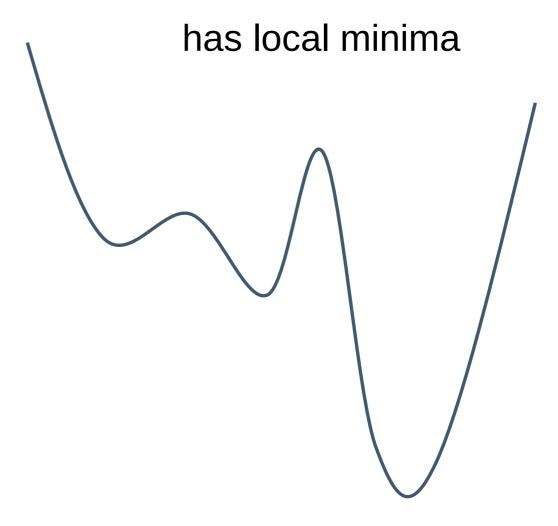
$$\boldsymbol{\theta}_{t+1} = \boldsymbol{\theta}_t + \boldsymbol{v}_t$$

Momentum

$$\boldsymbol{\theta}_{t+1} = \boldsymbol{\theta}_t + \boldsymbol{v}_t$$

- Momentum algorithms
 - Build up speed in shallow directions
 - Can get out of local minima





Mehta et al. Phys. Rep. (2019)

Use stochasticity to get out of local minima

$$\boldsymbol{\theta}_{t+1} = \boldsymbol{\theta}_t + \boldsymbol{v}_t$$

Only compute on a subset of and y

$$\boldsymbol{\theta}_{t+1} = \boldsymbol{\theta}_t + \boldsymbol{v}_t$$



A model to play with

Run lj_3_hyperparameters.py

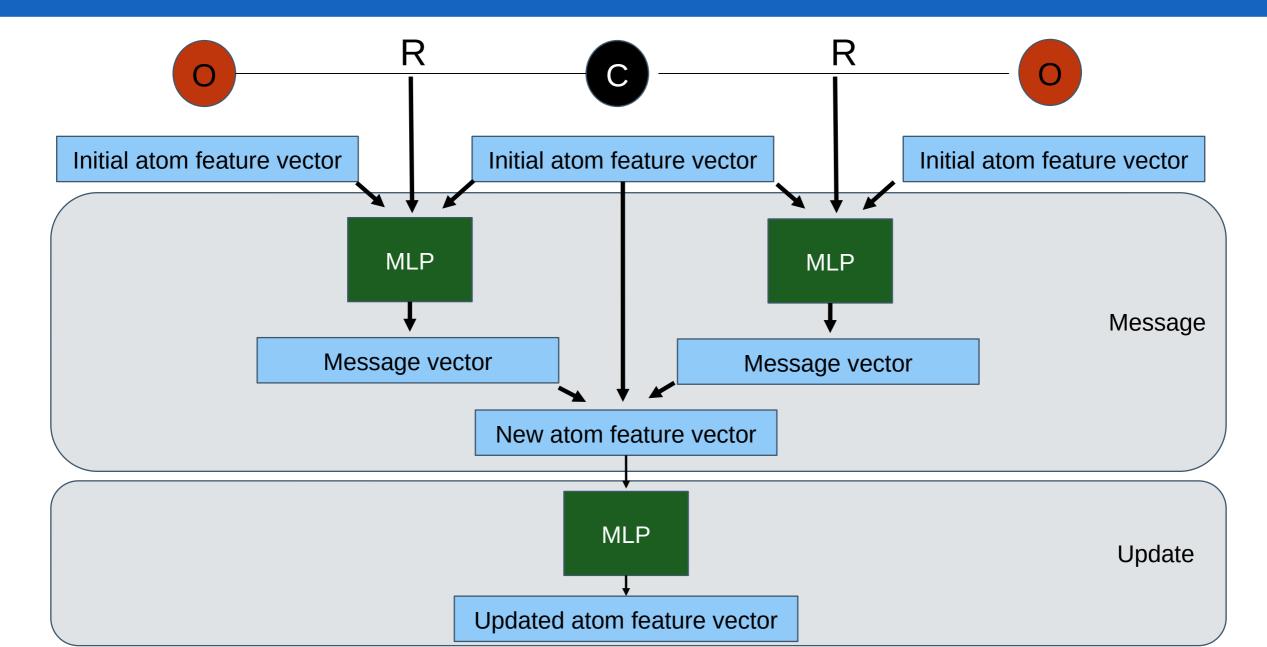
 Change hyperparameters at the top of the script and see how the training progression changes

- Tensorboard to plot training progression
 - In ml_tutorial folder run: tensorboard --logdir=runs --reload_multifile True
 - Go to http://localhost:6006/ in your browser

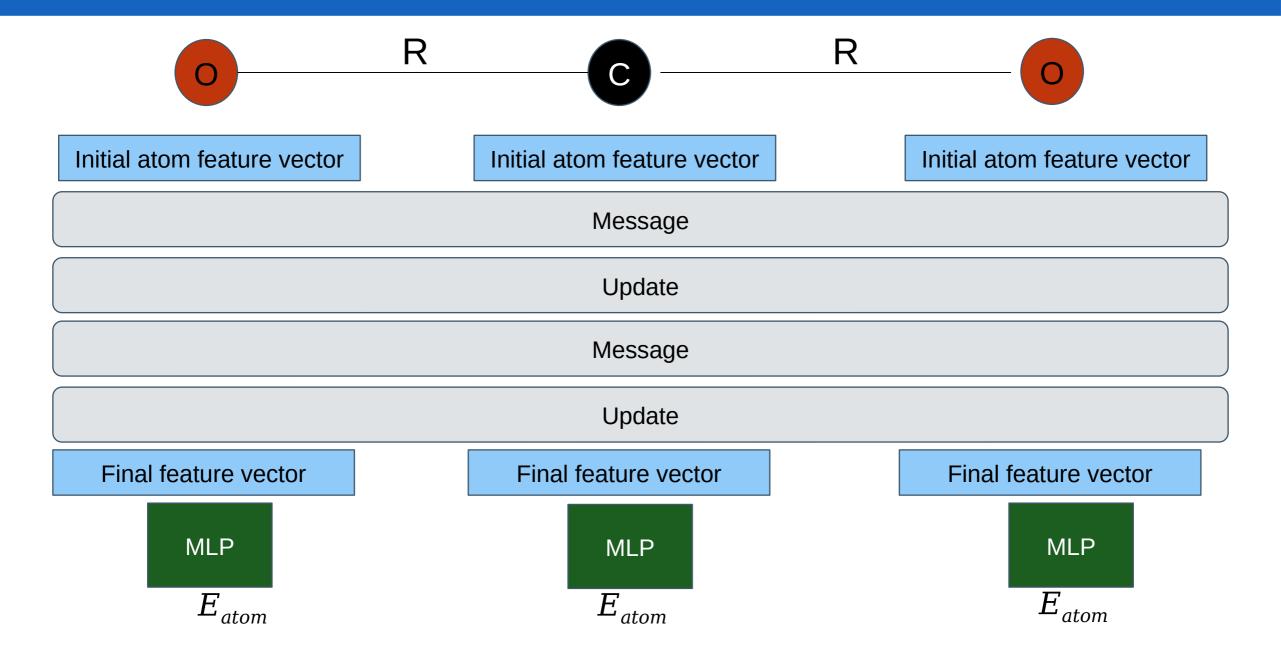
Best practices when developing an NN

- Try to memorize a few data points first
- Try also using fake simple data
- Check your descriptors and targets to make sure you are feeding the NN what you think you are
- Hyperparameter tuning on even just a few epochs to screen out unpromising parameter values
- Use grid search/random search of hyperparameters

Architecture of message passing neural networks



Architecture of message passing neural networks



Getting to molecular dynamics in 1 minute

- In schnet_tutorial folder run script2_train_schnet.py
 - Trains a schnet model on 1000 data points of a ethanol DFT(PBE) MD trajectory for 5 epochs
- run script3_run_md.py
 - Creates an atomic structure environment (ASE) force field calculator using the schnet model. Uses ASE to run an MD trajectory
 - Note: that you can only run this script once, it will throw an error if you run it a second time
- in anaconda prompt run: ase gui
- file -> open -> ase_calcs (in left pane) -> simulation.traj
- tools -> movies -> play
- Note that the state-of-the-art ML-FF's are equivariant (PAINN, NequIP, etc.). Schnet is an invariant model that's cheap to train and run.

Acknowledgements



Prof. Alexandre Tkatechnko



Artem Kokorin







[hank You!