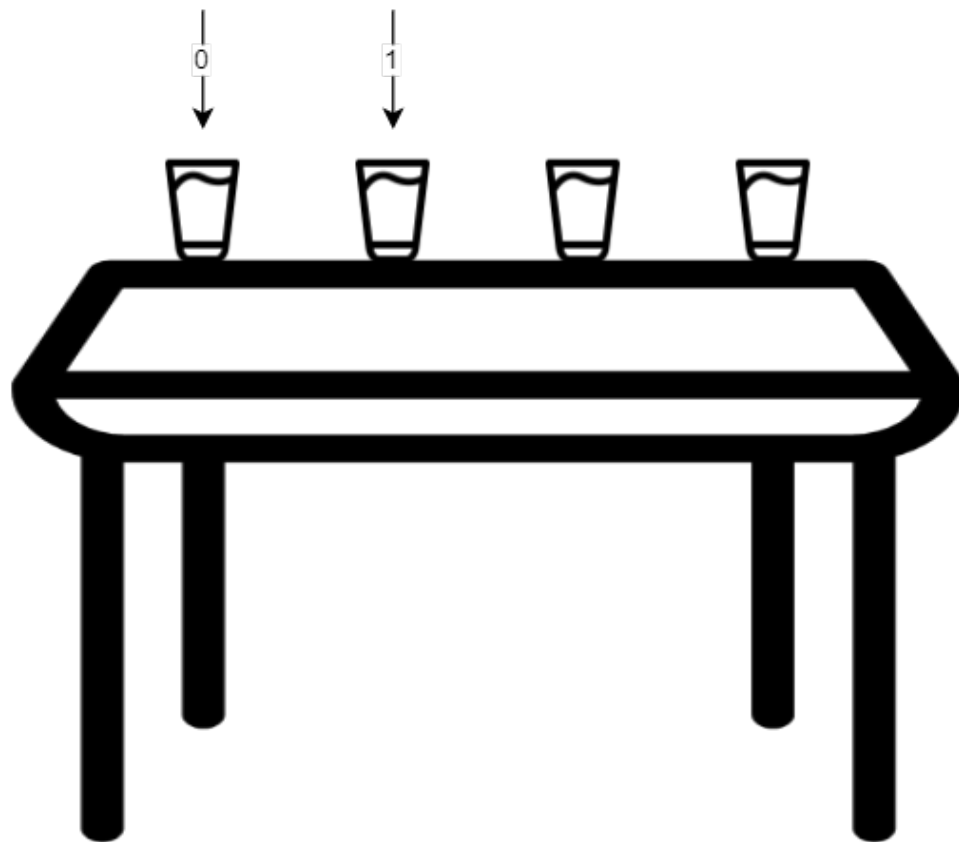


Robot arm control menu

Alternate item

Toggle grasp





Inputs to pick up second glass


1: MI left (alternate item)

2: MI right (grasp item)

Required MI labels

 MI left-hand squeeze: alternate item to grasp

 MI right-hand squeeze: grasp or release item

 MI idle state: do nothing