Math508 Final Exam

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1 Problem 1

For Ornstein-Uhlenbeck stationary sequence, $EX_n = 0$, $R(k) = a^{|k|}$. The best linear estimate of X_m given $X_k, X_{k-1}, X_{k-2}, ...$ is

$$\hat{X}_m = k_0 + k_1 * X_k + k_2 * X_{k-1} + k_3 * X_{k-2} + \dots \\ k_0 = EX_m = 0$$
 (1)

The matrices in the normal equation (2) would be infinite although it could be easily be seen that $k_1 = a^{m-k}$ while other k's are all zero. Hence, $\hat{X_m} = a^{m-k}X_k$.

$$\begin{pmatrix} a^0 & a^1 & a^2 & \dots \\ a^1 & a0 & a^1 & \dots \\ \vdots & \vdots & \ddots & \end{pmatrix} \begin{pmatrix} k_1 \\ k_2 \\ \vdots \end{pmatrix} = \begin{pmatrix} a^{m-k} \\ a^{m-k+1} \\ \vdots \end{pmatrix}$$
(2)

Instead guessing, i use the sequential project to prove this result. M_n is a linear subspace generated by $\{1, X_k, X_{k-1}, \dots, Xk - n + 1\}$.

$$\hat{X_{m,n}} = E(X_m | M_n) \tag{3}$$

There's iteration that

$$\hat{X_{m,n}} = \hat{X_{m,n-1}} + \frac{c_{n,n-1}}{u_{n,n-1}} (X_{k-n} - X_{k-n+1})$$

$$\hat{X_{k-n,n-1}} = E(X_{k-n} | M_{n-1})$$

$$c_{n,n-1} = E[(X_m - \hat{X_{m,n-1}})(X_{k-n} - \hat{X_{k-n,n-1}})]$$

Now take $n=2,\,M_2$ is a linear subspace generated by $\{1,X_k,X_{k-1}\}$ and M_1 is a linear subspace generated by $\{1,X_k\}$. We can get following results easily.

$$\hat{X_{m,n-1}} = \hat{X_{m,1}} = a^{m-k} * X_k \tag{4}$$

$$\hat{X_{k-n,n-1}} = \hat{X_{k-1,1}} = aX_k \tag{5}$$

We can prove $c_{n,n-1} = 0$.

$$c_{n,n-1} = c_{2,1} = E[(X_m - a^{m-k} * X_k)(X_{k-1} - aX_k)]$$

$$= E(X_m X_{k-1} - aX_m X_k - a^{m-k} X_k X_{k-1} + a^{m-k+1} X_k X_k)$$

$$= a^{m-k+1} - a * a^{m-k} - a^{m-k} * a + a^{m-k+1} = 0$$
(6)

$$\hat{X_{m,2}} = \hat{X_{m,1}} = a^{m-k} * X_k \tag{7}$$

By induction,

$$\hat{X_m} = a^{m-k} X_k \tag{8}$$

2 Problem 2

2.1 part a

$$P(X_{n+1} \le u, Y_{n+1} \le v | X_n = r, Y_n = s)$$

$$= \int_{-\infty}^{u} P(Y_{n+1} \le v | X_{n+1} = x) f(X_{n+1} = x | X_n = r, Y_n = s) dx$$

$$= \int_{-\infty}^{u} \int_{-\infty}^{v} l(X_{n+1} = x, Y_{n+1} = y) p(X_{n+1} = x | X_n = r) dy dx$$

Differentiate both sides by $\frac{\partial^2}{\partial u \partial v}$ to get the transition kernel

$$q^{r,u}(s,v) = p(r,u)l(u,v)$$
(9)

2.2 part b

Given $X_n = r$, if $W_n \ge -r$, Y_n is distributed as N(r,1). If $W_n < -r$, Y_n is distributed as N(-r,1). Graphically, Y_n 's distribution is a combination of N(r,1) and N(-r,1) with the only positive domain. So,

$$P(Y_n < u | X_n = r) = \int_0^u \rho(y - r) dy + \int_0^u \rho(y + r) dy$$
 (10)

 $\rho(x)$ is the standard normal density function. Differentiate both sides by $\frac{\partial}{\partial u}$ to get

$$l(r, u) = \rho(u - r) + \rho(u + r) \tag{11}$$

3 Problem 3

Professor, in this problem, i found a little problem with hint you gave us. Basically, the filtering procedure (i'll call it procedure 1) is more like a one step prediction. Following dependency structure will help illustrate the problem.

$$X_0[d][r]X_1[d][r]\dots[r]X_n[d][r]X_{n+1}[d]\dots Y_0Y_1Y_2\dots Y_{n+1}Y_{n+2}\dots W_1[u]W_2[u]\dots W_{n+1}[u]W_{n+2}[u]\dots (12)$$

The recursion for **procedure 1** is

$$\gamma_{0}(H_{0}, X_{0}) = 0 (13)$$

$$\gamma_{0}(X_{0}) = \frac{1}{0.1^{2}} \rho(x/0.1) (14)$$

$$\gamma_{n+1}(H_{n+1}, X_{n+1}) = \int_{R} p(X_{n}, X_{n+1}) \lambda^{-1}(Y_{n+1}, X_{n}) [\gamma_{n}(H_{n}, X_{n}) + X_{n} \gamma_{n}(X_{n})] dX_{n} (15)$$

$$\gamma_{n+1}(X_{n+1}) = \int_{R} p(X_{n}, X_{n+1}) \lambda^{-1}(Y_{n+1}, X_{n}) \gamma_{n}(X_{n}) dX_{n} (16)$$

$$E[H_{n}|Y_{[0,n]}] = \frac{\int_{R} \gamma_{n}(H_{n}, X_{n}) dX_{n}}{\int_{R} \gamma_{n}(X_{n}) dX_{n}} (17)$$

$$E[f(X_{n})|Y_{[0,n]}] = \frac{\int_{R} f(X_{n}) \gamma_{n}(X_{n}) dX_{n}}{\int_{R} \gamma_{n}(X_{n}) dX_{n}} (18)$$

Basically, to get the signal of X_{n+1} , we are Y_{n+1} , one step prediction from X_n and all previous information. However, looking at diagram (12), we should incorporate Y_{n+2} to do a full filtering. So after some calculation, i propose **procedure 2**

$$\gamma_{0}(H_{0}, X_{-1}) = 0$$
(19)
$$\gamma_{0}(X_{0}) = \lambda^{-1}(Y_{1}, X_{0}) \frac{1}{0.1^{2}} \rho(x/0.1)$$
(20)
$$\gamma_{n+1}(H_{n+1}, X_{n}) = \lambda^{-1}(Y_{n+1}, X_{n}) \int_{R} p(X_{n-1}, X_{n}) [\gamma_{n}(H_{n}, X_{n-1}) dX_{n-1} + X_{n} \gamma_{n}(X_{n})$$
(21)
$$\gamma_{n+1}(X_{n+1}) = \lambda^{-1}(Y_{n+2}, X_{n+1}) \int_{R} p(X_{n}, X_{n+1}) \gamma_{n}(X_{n}) dX_{n}$$
(22)
$$E[H_{n}|Y_{[0,n]}] = \frac{E[Z_{n}^{-1}H_{n}|Y_{[0,n]}]}{E[Z_{n}^{-1}|Y_{[0,n]}]} = \frac{\int_{R} \gamma_{n}(H_{n}, X_{n-1}) dX_{n-1}}{\int_{R} \gamma_{n-1}(X_{n-1}) dX_{n-1}}$$
(23)
$$E[f(X_{n})|Y_{[0,n+1]}] = \frac{E[f(X_{n})Z_{n+1}^{-1}|Y_{[0,n+1]}]}{E[Z_{n+1}^{-1}|Y_{[0,n+1]}]} = \frac{\int_{R} f(X_{n})\gamma_{n}(X_{n}) dX_{n}}{\int_{R} \gamma_{n}(X_{n}) dX_{n}}$$
(24)

The idea is to get \hat{H}_n , only need information up to Y_n because $H_n = \sum_{k=1}^{k=n} X_{k-1}$ and the last included X is X_{n-1} . Looking at diagram (12), X_{n-1} is depended by Y_n . To get \hat{X}_n , we need information up to Y_{n+1} . It created a little bit hardship in programming as two estimates are not synchronized in terms of sequential computing.

Figure (1, 2, 3, 4) are due to procedure 1. Figure (5, 6, 7, 8) are due to procedure 2. Figure 5 from procedure 2 has smaller MSE than Figure 1 from procedure 1. By checking closely, you can actually see $\hat{X_n}$ in Figure 1 is a little bit lagging behind $\hat{X_n}$ in Figure 5. This lagging phenomenon is due to the one-step-prediction in procedure 1. It's evident in other figures as well.

4 Problem 4

By checking the notes, i realized there're some errors in both the notes and the hints although it won't hurt the result if $\frac{\alpha_{t_{i+1}}}{\alpha_{t_i}}$ is calculated approximately. Most errors are due to the swapping of λ_1 and λ_2 which depends on how to split the Ricotti equation. Ricotti equation is

$$\lambda_1 = \left(a^2 B^4 + b^2 B^2\right)^{1/2} + a B^2 \tag{25}$$

$$\lambda_2 = -(a^2 B^4 + b^2 B^2)^{1/2} + aB^2 \tag{26}$$

$$\frac{dP}{dt} = 2aP_t + b^2 - \frac{P_t^2}{B^2} \tag{27}$$

So assume Ricotti equation is split in the way following

$$\frac{dt}{dP} = \frac{C}{P - \lambda_1} - \frac{C}{P - \lambda_2} = \frac{-B^2}{(P^2 - 2aB^2P - b^2B^2)}$$
 (28)

$$\Rightarrow C = \frac{B^2}{\lambda_2 - \lambda_1} \tag{29}$$

$$\Rightarrow Cln\left|\frac{P-\lambda_1}{P-\lambda_2}\right| = t + const \tag{30}$$

$$\Rightarrow \left| \frac{P - \lambda_1}{P - \lambda_2} \right| = Ke^{t/C} \tag{31}$$

$$\Rightarrow t = 0, K = \left| \frac{P_0 - \lambda_1}{P_0 - \lambda_2} \right| \tag{32}$$

With $P_0 = 0 < \lambda_1$, we'll get

$$K = \frac{\lambda_1}{-\lambda_2} \tag{33}$$

$$\frac{P - \lambda_1}{P - \lambda_2} = -Ke^{t/C} \tag{34}$$

$$\Rightarrow P_t = \frac{\lambda_2 K e^{t/C} + \lambda_1}{K e^{t/C} + 1} = \lambda_2 + \frac{\lambda_1 - \lambda_2}{1 + K e^{t/C}}$$
(35)

$$\alpha_t = exp\{\int_0^t (a - \frac{P_s}{B^2})ds\} = exp\{(a - B^{-2}\lambda_1)t\} \frac{(K+1)e^{t/C}}{Ke^{t/C} + 1}$$
 (36)

One thing about α_t , i'm not sure it should be λ_1 or λ_2 in the formula (i can't work out the complex integral.) So when calculating $\frac{\alpha_{t_{i+1}}}{\alpha_{t_i}}$, i tried both of them, calling them $exactratio_1$ and $exactratio_2$ and compared with the approximated version, which is

$$\frac{\alpha_{t_{i+1}}}{\alpha_{t_i}} \approx exp\{(a - \frac{P_{t_i}}{B^2})\delta t\}$$
 (37)

So in figure 9, the $exactratio_1$ is the correct formula as it's closer to the approximated ratio. So Figure (10, 11, 12, 13) are for different settings. The \hat{X}_n is calculated using both the approximated $\frac{\alpha t_{i+1}}{\alpha t_i}$ and the exact one. Previously, due to the opposite sign of C, \hat{X}_n based on the approximated ratio (red curve) has smaller MSE than \hat{X}_n based on the exact ratio (cyan curve). Now with the correct formula for C (29), \hat{X}_n based on the exact ratio (cyan curve) has smaller MSE, which is within expectation.

5 Figures

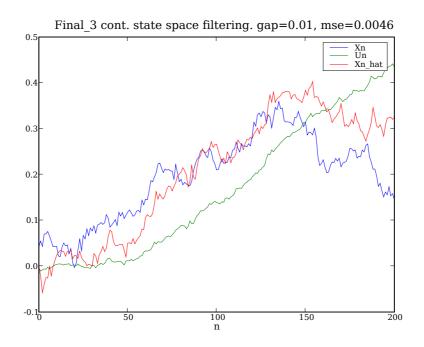


Figure 1:

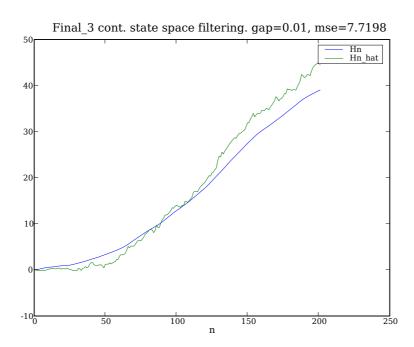


Figure 2:

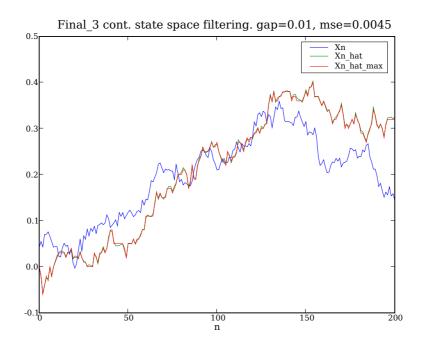


Figure 3:

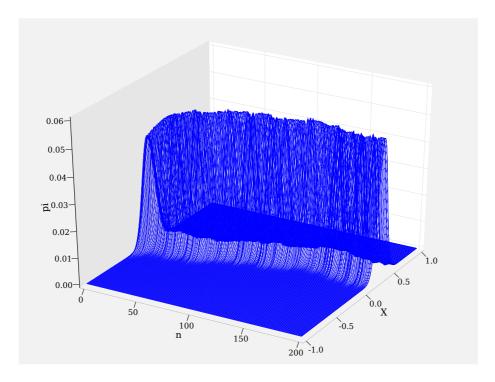


Figure 4:

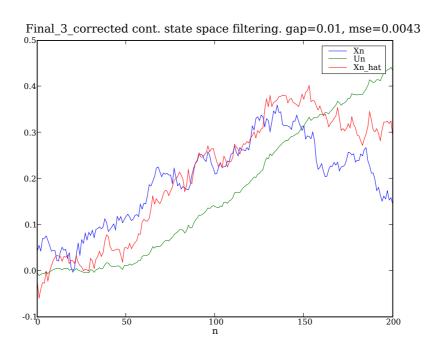


Figure 5:

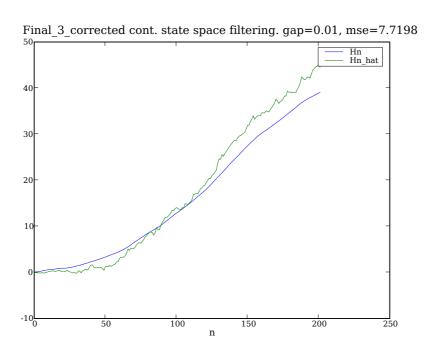


Figure 6:

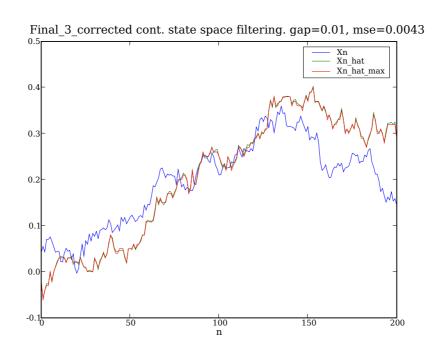


Figure 7:

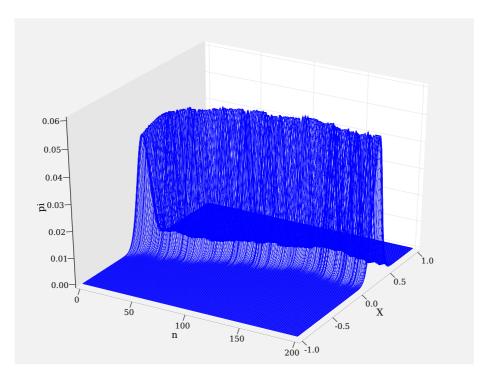
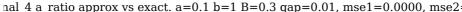


Figure 8:



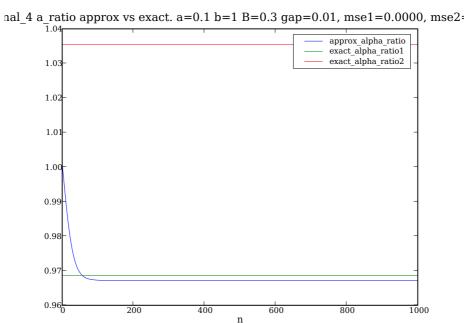


Figure 9:

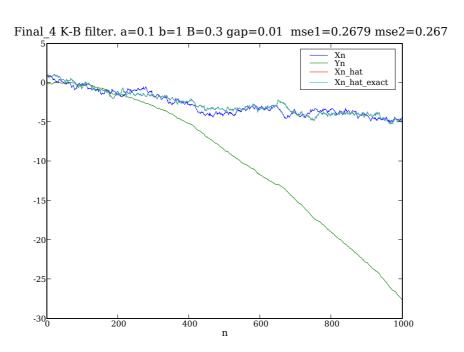


Figure 10:

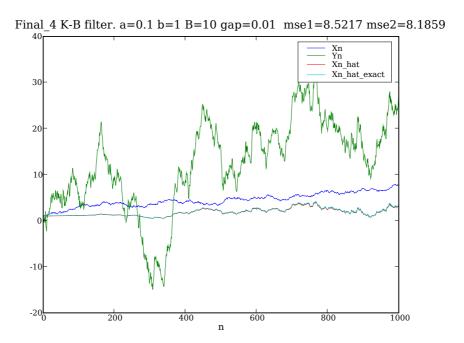


Figure 11:

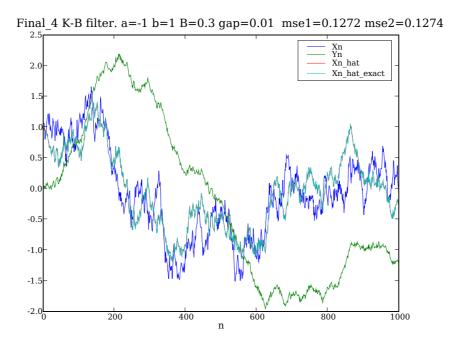


Figure 12:

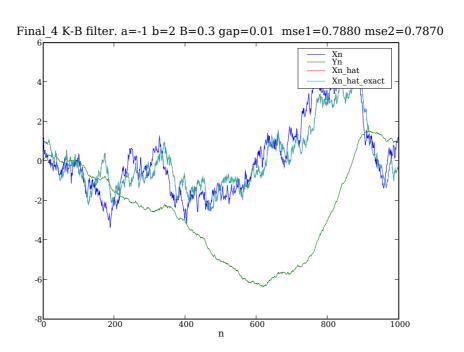


Figure 13: