# AdaFuse: Adaptive Temporal Fusion Network for Efficient Action Recognition

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#### 1. Introduction and Motivation

In video action recognition, both temporal modeling and employing temporal redundancy are crucial. For the purposes, the authors propose AdaFuse, named from an adaptive temporal fusion network, that dynamically selects and fuses the channels of current and past feature maps.

## 2. Method

# 2.1. 2D-CNN for Action Recognition

For action recognition, many methods first extract feature maps from each frame using 2D-CNN  $(\mathcal{F})$  and colligate the feature maps using a consensus operation  $(\mathcal{G})$  used for final prediction. So, the final prediction can be written as follows:

$$P(X_1, ..., X_T) = \mathcal{G}(\mathcal{F}(X_1), ..., \mathcal{F}(X_T))$$

where T is the number of sampled frames, and  $\{X_1,...,X_T\}$  are the sampled frames. The consensus operation can be an average operation or LSTM. AdaFuse is inserted in between layers of  $\mathcal{F}$ .

## 2.2. Adaptive Temporal Fusion

Assume that  $x_t \in \mathbb{R}^{c \times h \times w}$  is a feature map, and  $y_t = \operatorname{conv}(x_t) \in \mathbb{R}^{c' \times h' \times w'}$  is a feature map of the next layer. We define  $v_t = GAP(x_t) \in \mathbb{R}^c$  as a global average pooled feature. AdaFuse adopts an agent g that takes  $v_t$  and  $v_{t-1}$  and outputs  $p_t \in \{0,1,2\}^c$  where  $p_t$  is used to fuse  $y_t$  and  $y_{t-1}$ :

$$\hat{y}_t^i = \mathbf{1}[p_t^i = 0] \cdot y_t^i + \mathbf{1}[p_t^i = 1] \cdot y_{t-1}^i$$

where 1 is the indicator function. We can interpret the equation as follows: if  $p_t^i$  is 0, then we use the i-th channel of  $y_t$ ; else if  $p_t^i$  is 1, we use the i-th channel of  $y_{t-1}$ ; finally, if  $p_t^i$  is 2, we mask the i-th channel as zeros (Figure 1).

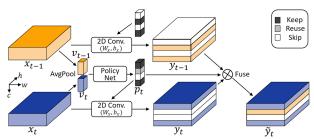


Figure 1. The agent of AdaFuse selects which channels to use dynamically.

#### 2.3. Loss functions

The loss function is the sum of the cross-entropy loss and the FLOPS of AdaFuse layers. The agent learns to minimize the FLOPS while maintaining the accuracy.

#### 3. Results

The authors evaluate the effectiveness of the proposed method on various datasets such as Something-Something V1, Jester, and Mini-Kinetics. AdaFuse consistently improves performance while maintaining the FLOPS of the network, and in some experiments, the method shows better performance while reducing the FLOPS drastically.

## 4. Personal Note

Even though integrating with Reinforce learning seems a little bit complicated, the method seems simple, neat, and efficient.