

Assignment Project Exam Help

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L10_1 Finite-State- Machines_Implementation

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Learning Objectives

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- Be able to identify the components and trade-offs relevant to a finite state machine.
- Identify the course-granularity operation of the implementation for an FSM.

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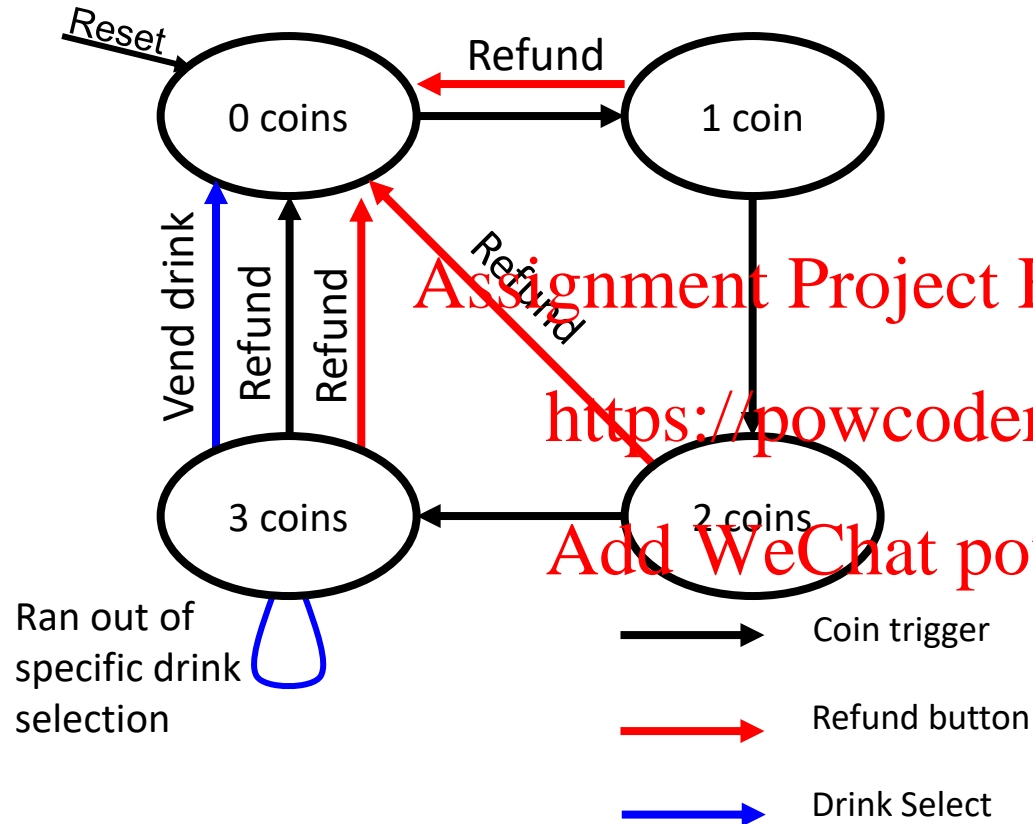
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FSM for Vending Machine

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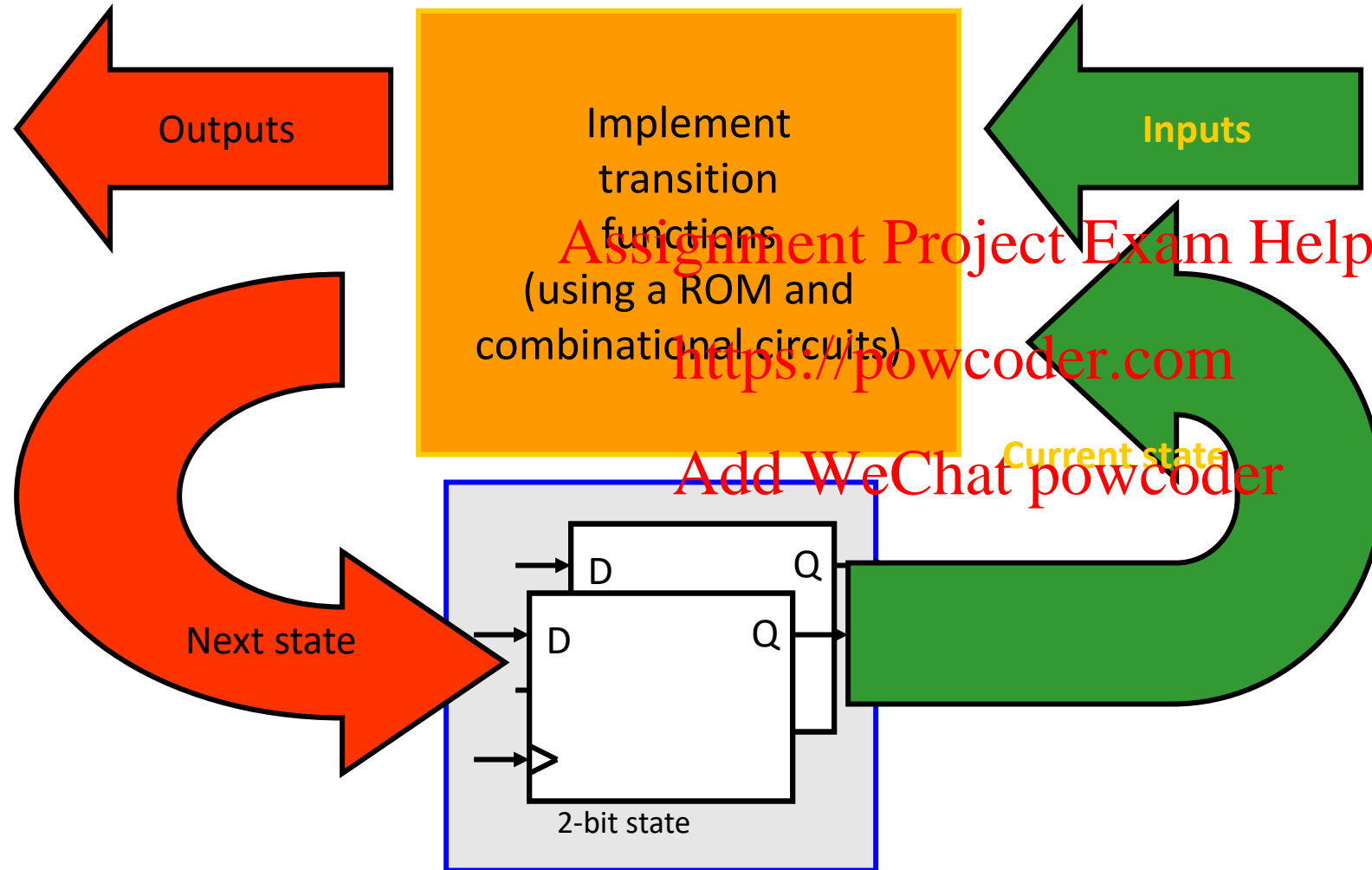


Is this a Mealy or Moore Machine?
 Mealy ~ output is based on current state
 AND input



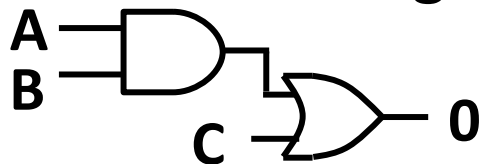
Implementing a FSM

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Implementing Combinational Logic (1)

- If I have a truth table:
- I can either implement this using combinational logic:

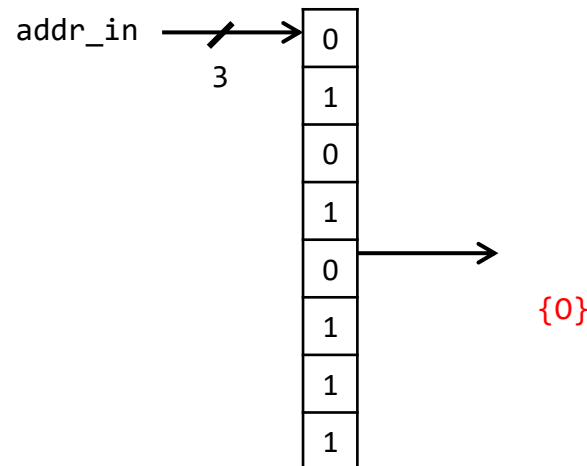


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- ...or I could literally just store the entire truth table in a memory and just "address" it using the input!

| A | B | C | O |
|---|---|---|---|
| 0 | 0 | 0 | 0 |
| 0 | 0 | 1 | 1 |
| 0 | 1 | 0 | 0 |
| 0 | 1 | 1 | 1 |
| 1 | 0 | 0 | 0 |
| 1 | 0 | 1 | 1 |
| 1 | 1 | 0 | 1 |
| 1 | 1 | 1 | 1 |



Implementing Combinational Logic (2)

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- Custom logic

- Pros:

- Can optimize the number of gates used

- Cons:

- Can be expensive / time consuming to make custom logic circuits

- Lookup table:

- Pros:

- Programmable ROMs (Read-Only Memories) are very cheap and can be programmed very quickly

- Cons:

- Size requirement grows exponentially with number of inputs (adding one just more bit doubles the storage requirements!)

| A | B | C | O |
|---|---|---|---|
| 0 | 0 | 0 | 0 |
| 0 | 0 | 1 | 1 |
| 0 | 1 | 0 | 0 |
| 0 | 1 | 1 | 1 |
| 1 | 0 | 0 | 0 |
| 1 | 0 | 1 | 1 |
| 1 | 1 | 0 | 1 |
| 1 | 1 | 1 | 1 |

Add one more input...

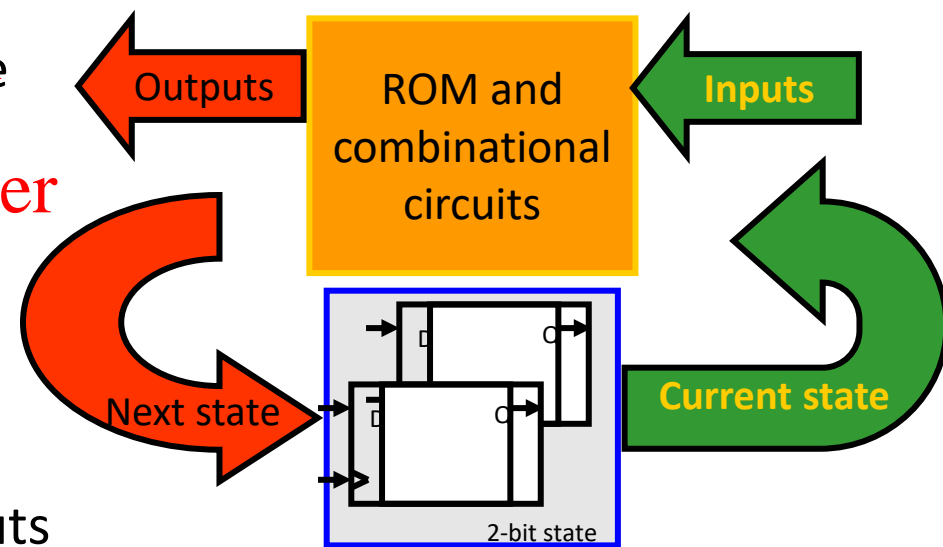
| A | B | C | D | O |
|---|---|---|---|---|
| 0 | 0 | 0 | 0 | 0 |
| 0 | 0 | 0 | 1 | 1 |
| 0 | 0 | 1 | 0 | 0 |
| 0 | 0 | 1 | 1 | 1 |
| 0 | 1 | 0 | 0 | 0 |
| 0 | 1 | 0 | 1 | 1 |
| 0 | 1 | 1 | 0 | 0 |
| 0 | 1 | 1 | 1 | 1 |
| 1 | 0 | 0 | 0 | 0 |
| 1 | 0 | 0 | 1 | 1 |
| 1 | 0 | 1 | 0 | 0 |
| 1 | 0 | 1 | 1 | 1 |
| 1 | 1 | 0 | 0 | 0 |
| 1 | 1 | 0 | 1 | 1 |
| 1 | 1 | 1 | 0 | 1 |
| 1 | 1 | 1 | 1 | 1 |

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ROMs and PROMs

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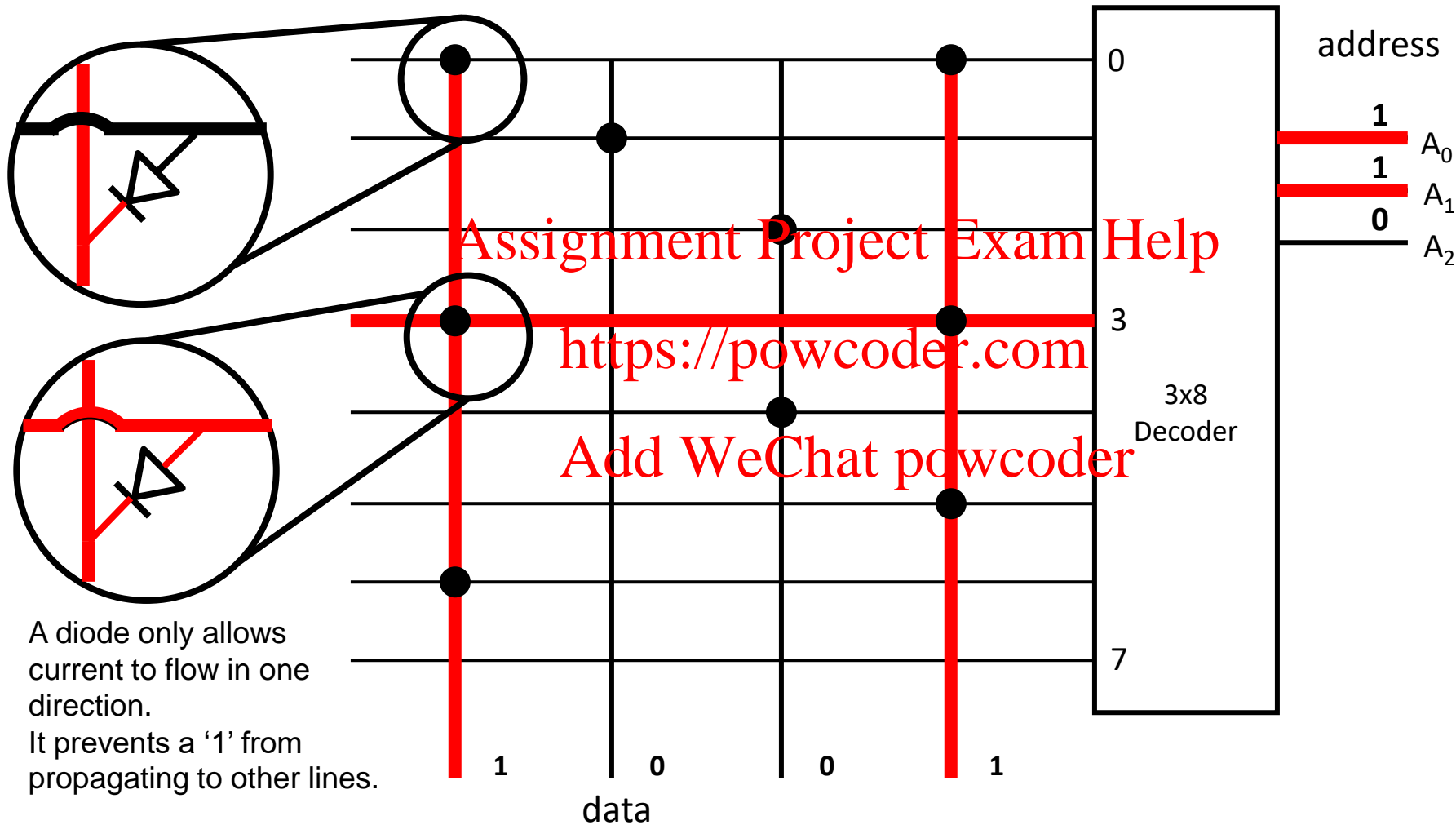
- Read Only Memory
 - Array of memory values that are constant
 - Non-volatile
- Programmable Read Only Memory
 - Array of memory values that can be written exactly once (destructive writes)
- You can use ROMs to implement FSM transition functions
 - ROM inputs (i.e., ROM address): current state, primary inputs
 - ROM outputs (i.e., ROM data): next state, primary outputs



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8-entry 4-bit ROM

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ROM for Vending Machine Controller

- Use current state and inputs as address
 - 2 state bits + 22 inputs = 24 bits (address)
 - Coin, refund, 10 drink selection, 10 sensors
- Read next state and outputs from ROM
 - 2 state bits + 11 outputs = 13 bit (memory)
 - Refund release, 10 drink latches
- We need 2^{24} entry, 13 bit ROM memories
 - 218,103,808 bits of ROM seems excessive for our cheap controller

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Reducing the ROM Needed

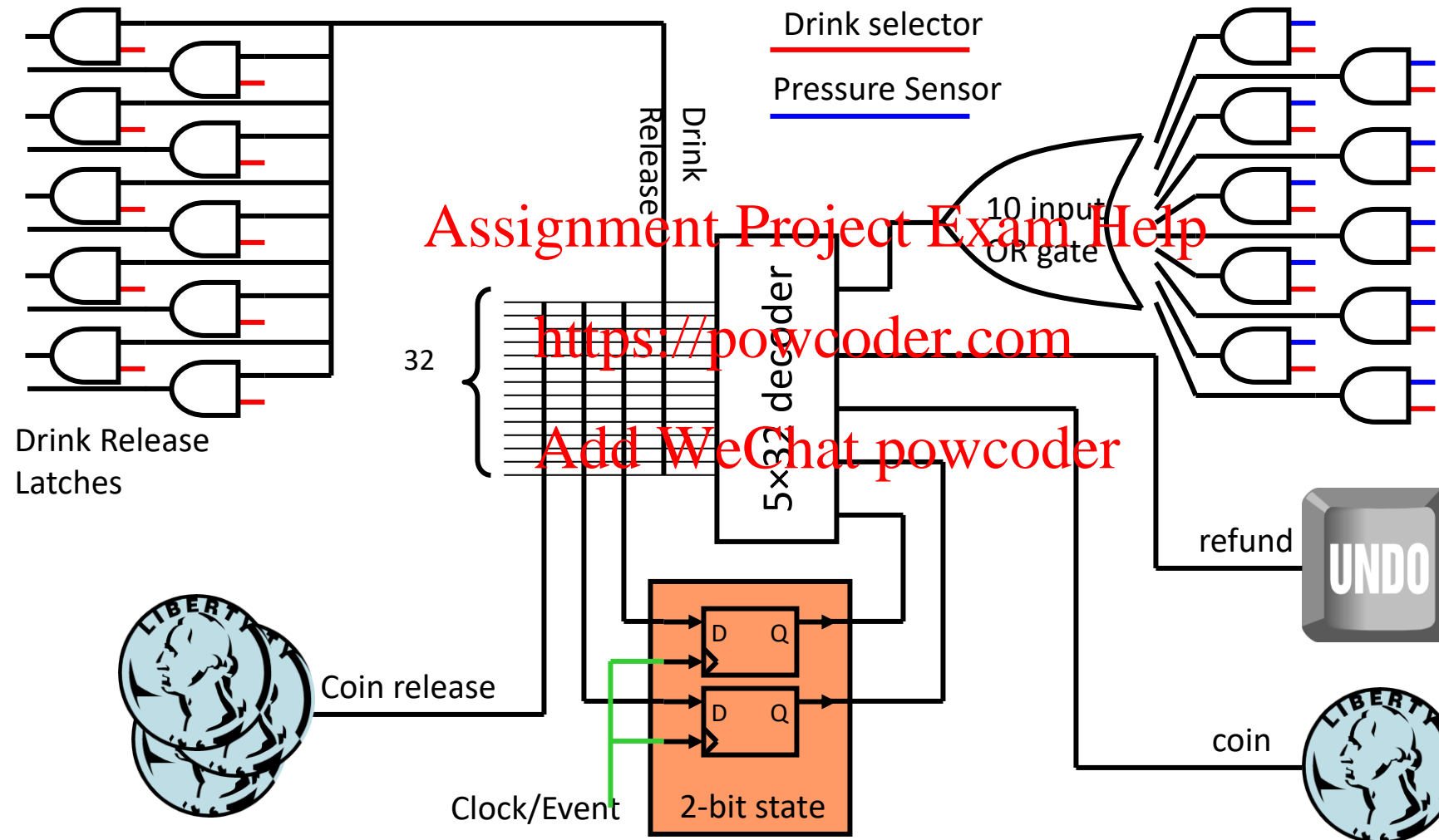
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- Idea: let's do a hybrid between combinational logic and a lookup table
 - Use basic hardware (AND / OR) gates where we can, and a ROM for everything more complicated
- Replace 10 selector inputs and 10 pressure inputs with a single bit input (drink selected)
 - Use drink selection input to specify which drink release latch to activate
 - Only allow trigger if pressure sensor indicates that there is a bottle in that selection. (10 2-bit ANDs)
- Now:
 - 2 current state bits + 3 input bits (5 bit ROM address)
 - 2 next state bits + 2 control trigger bits (4 bit memory)
 - $32 \times 4 = 128$ bit ROM (good!)

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Putting It All Together

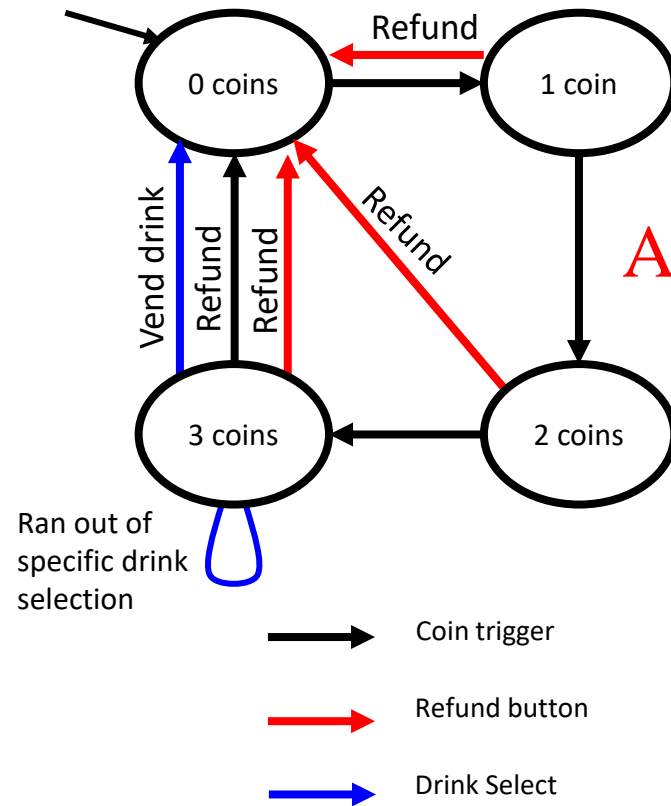
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Some of the ROM Contents

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| Current state | Coin trigger | Drink select | Refund button | Next state | Coin release | Drink release |
|---------------------|--------------|--------------|---------------|---------------------|--------------|---------------|
| 0 0 | 0 | 0 | 0 | 0 0 | 0 | 0 |
| 0 0 | 0 | 0 | 1 | 0 0 | 0 | 0 |
| 0 0 | 0 | 1 | 0 | 0 0 | 0 | 0 |
| 0 0 | 1 | 0 | 0 | 0 1 | 0 | 0 |
| 0 1 | 1 | 0 | 0 | 1 0 | 0 | 0 |
| 1 0 | 1 | 0 | 0 | 1 1 | 0 | 0 |
| 1 1 | 0 | 1 | 0 | 0 0 | 0 | 1 |
| 1 1 | 1 | 0 | 0 | 0 0 | 1 | 0 |
| ... 24 more entries | | | | ... 24 more entries | | |

ROM address (current state, inputs)

ROM contents (next state, outputs)

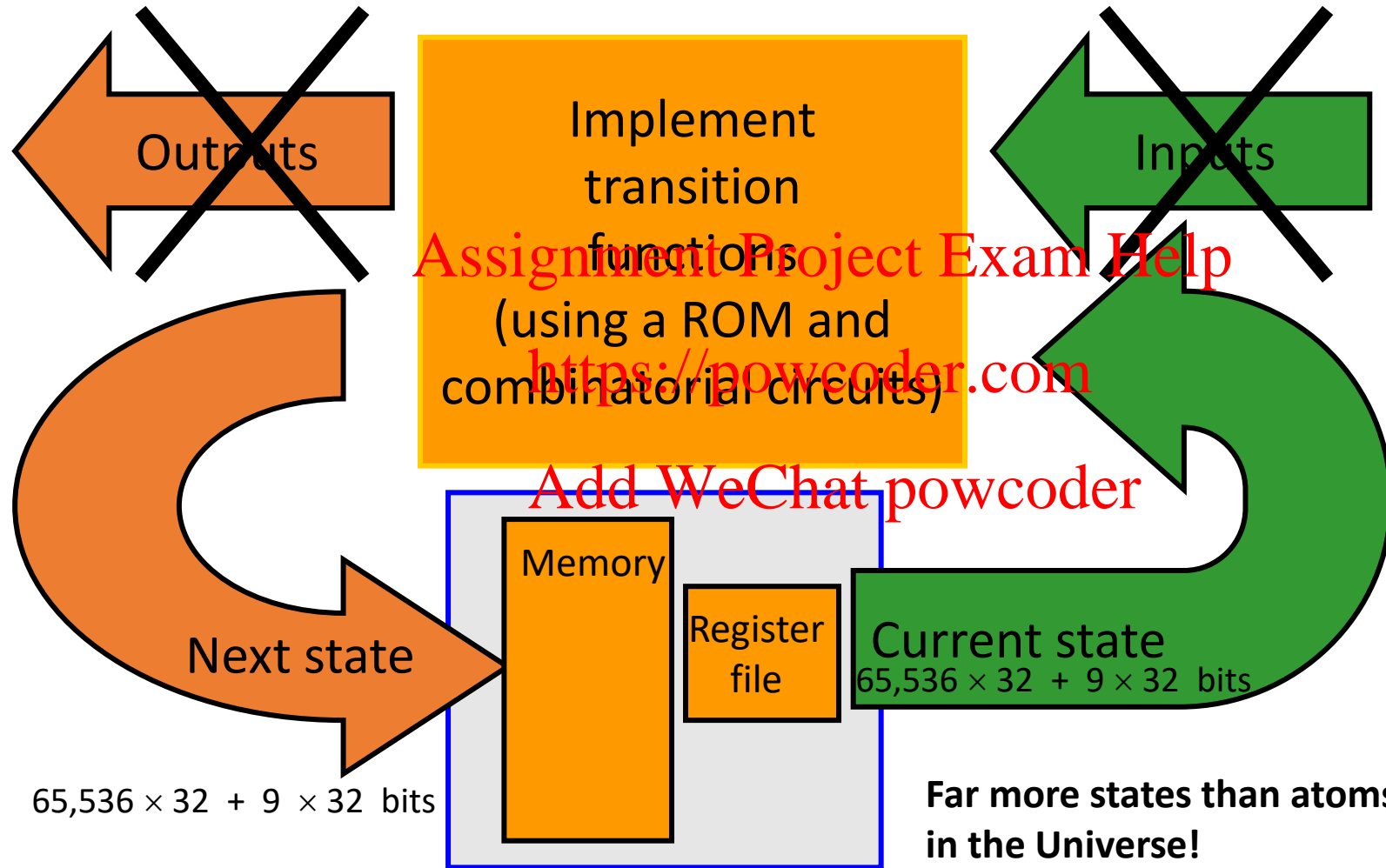
Limitations of the Controller

- What happens if we make the price \$1.00?, or what if we want to accept nickels, dimes and quarters?
 - Must redesign the controller (more state, different transitions)
 - A programmable processor only needs a software upgrade.
 - If you had written software anticipating a variable price, perhaps no change is even needed
- Next Topic - Our first processor!

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LC2Kx Processor as FSM

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Logistics

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- There are 3 videos for lecture 10
 - L10_1 – Finite-State-Machines_Implementation
 - L10_2 – Single-Cycle Processor
 - L10_3 – LC2K_Datapath
- There is one worksheet for lecture 10
 1. Finite state machine – you can do this now

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L10_2 Single-Cycle-Processor

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Learning Objectives

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- To identify the components used to implement a processor for LC-2K and understand the mapping from these components to LC-2K instructions.

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Single-Cycle Processor Design

Single-Cycle

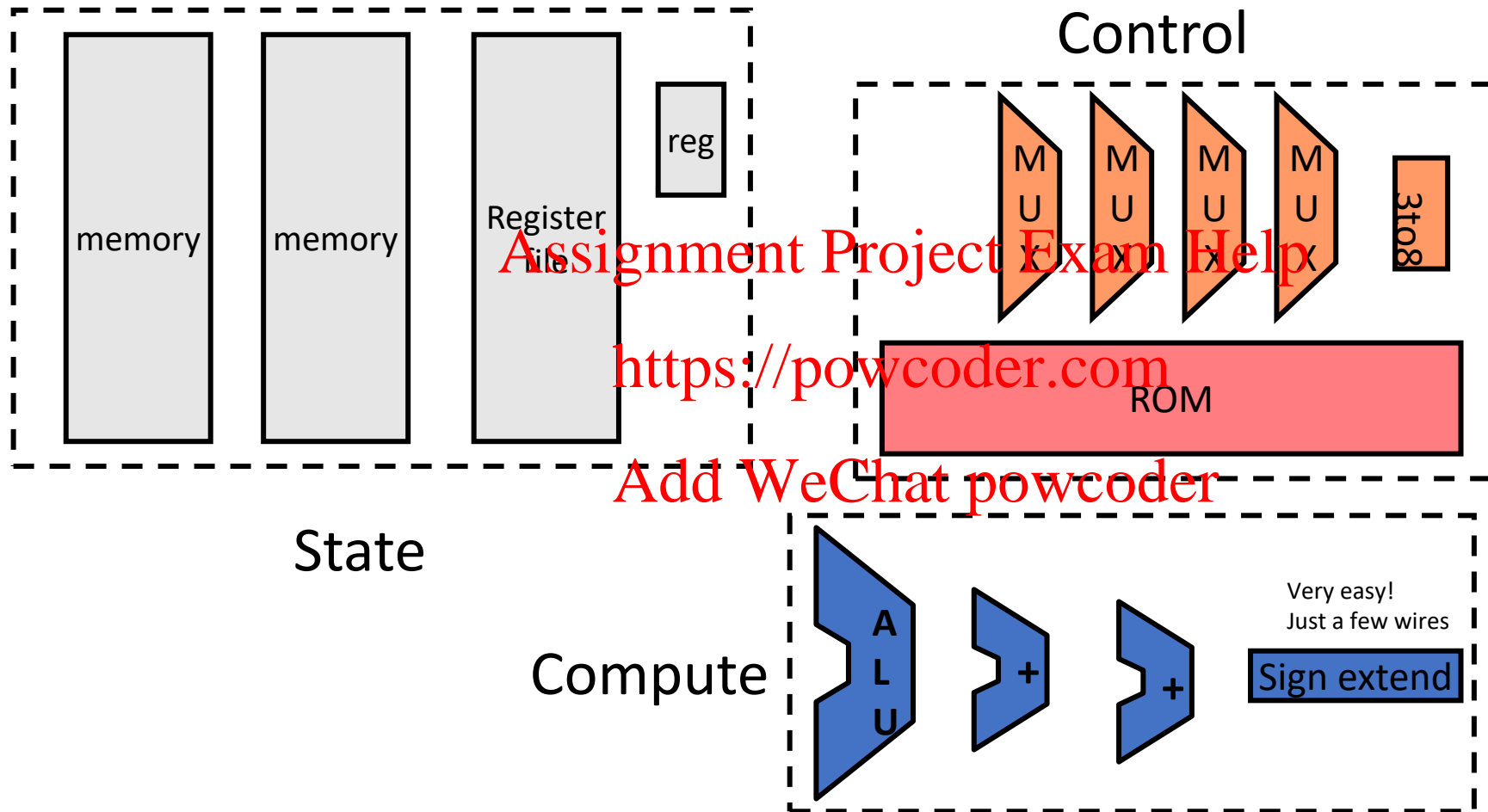
General-Purpose Processor Design

- Fetch Instructions
- Decode Instructions
 - Instructions are input to control ROM
- ROM data controls movement of data
 - Incrementing PC, reading registers, ALU control
- Clock drives it all
- Single-cycle datapath: Each instruction completes in one clock cycle

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Building Blocks for the LC2K

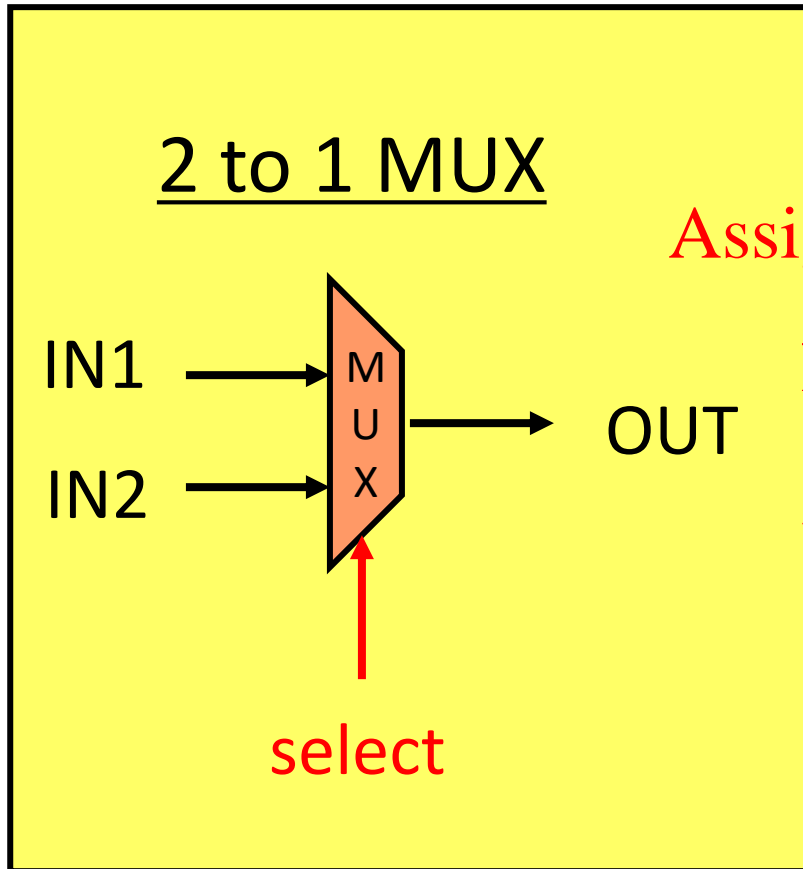
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Here are the pieces, go build yourself a processor!

Control Building Blocks (1)

Single-Cycle



Connect one of the inputs to OUT based on the value of select

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If (! select)

OUT = IN1

Else

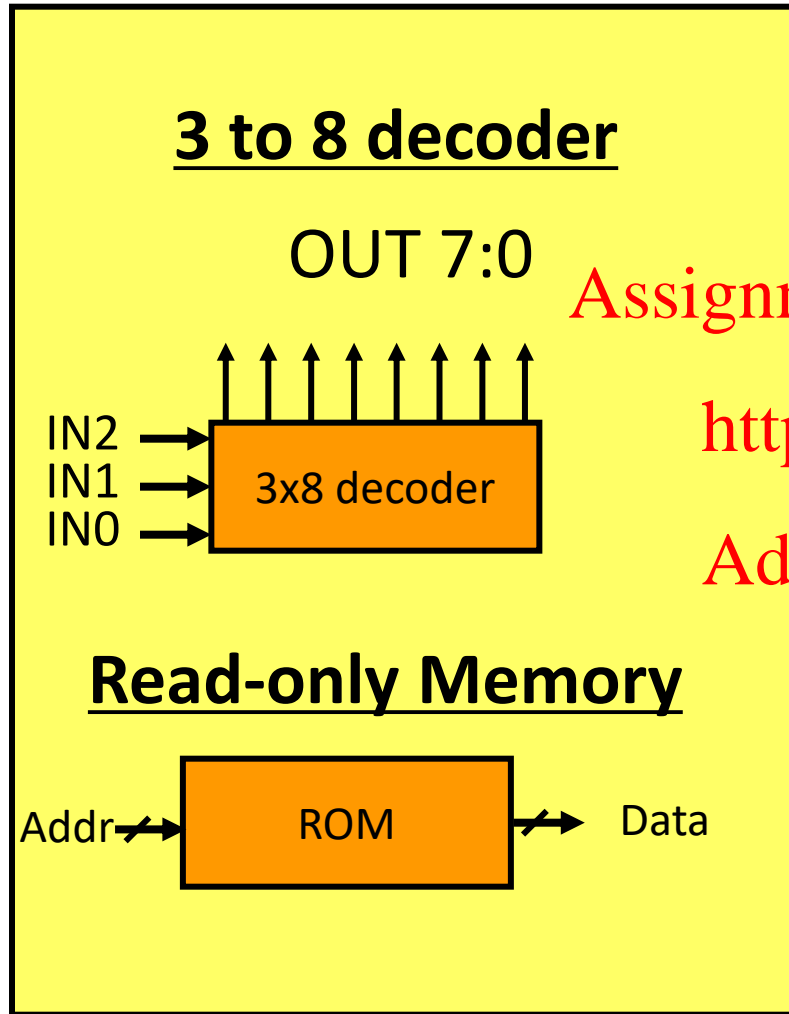
OUT = IN2

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Control Building Blocks (2)

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Single-Cycle



Decoder activates one of the output lines based on the input

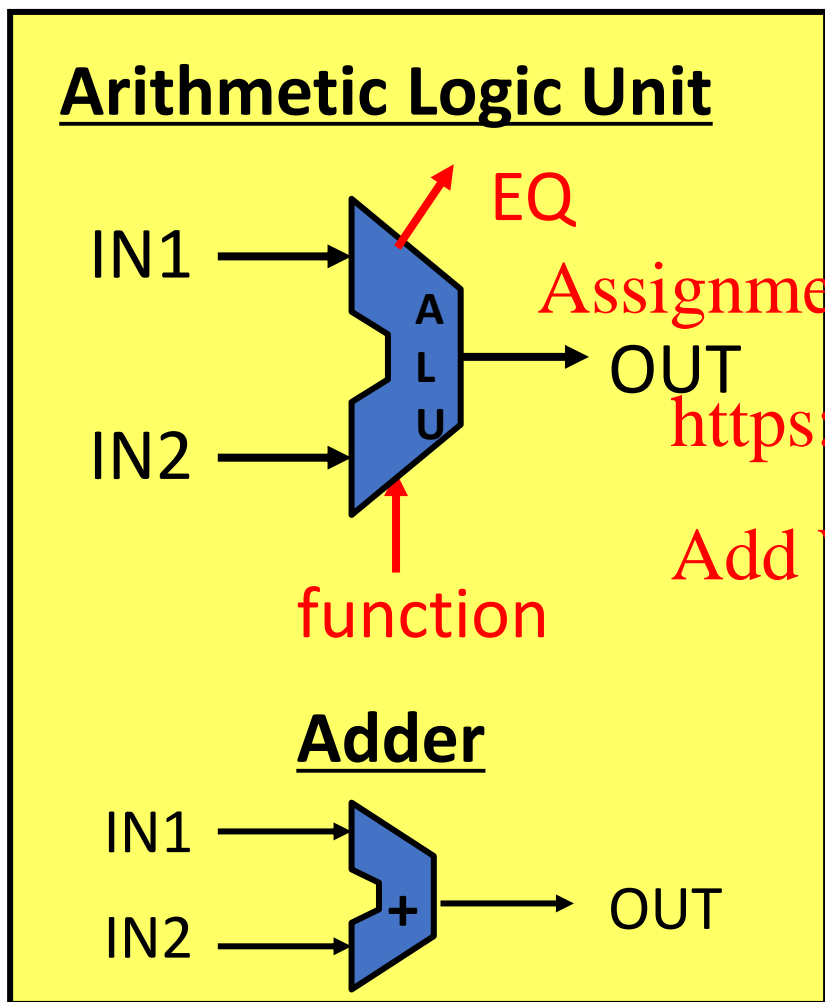
| IN | OUT |
|------|----------|
| 000 | 00000001 |
| 001 | 00000010 |
| 010 | 00000100 |
| 011 | 00001000 |
| etc. | |

ROM stores preset data in each location.
Give address to access data.

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Compute Building Blocks (1)

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Perform basic arithmetic functions

$$OUT = f(IN1, IN2)$$

$$EQ = (IN1 == IN2)$$

For LC2K:

f=0 is add

f=1 is nor

For other processors, there are many more functions.

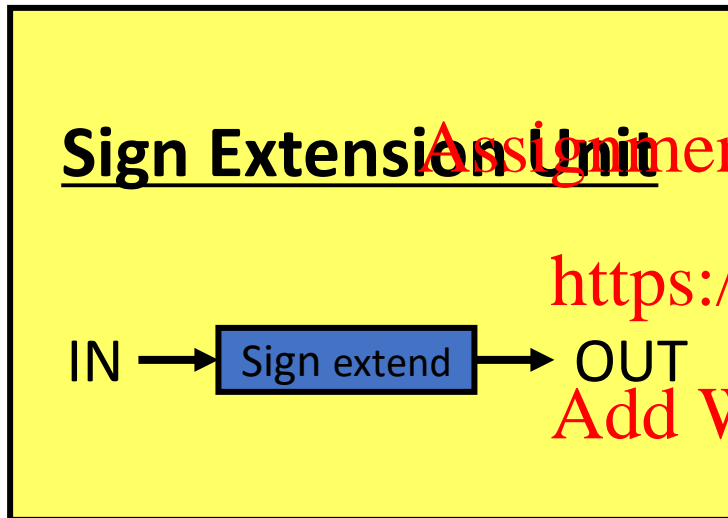
Just adds

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Compute Building Blocks (2)

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Single-Cycle



Sign extend input by replicating the MSB to

width of output

$$\text{OUT}(31:0) = \text{SE}(\text{IN}(15:0))$$

$$\text{OUT}(31:16) = \text{IN}(15)$$

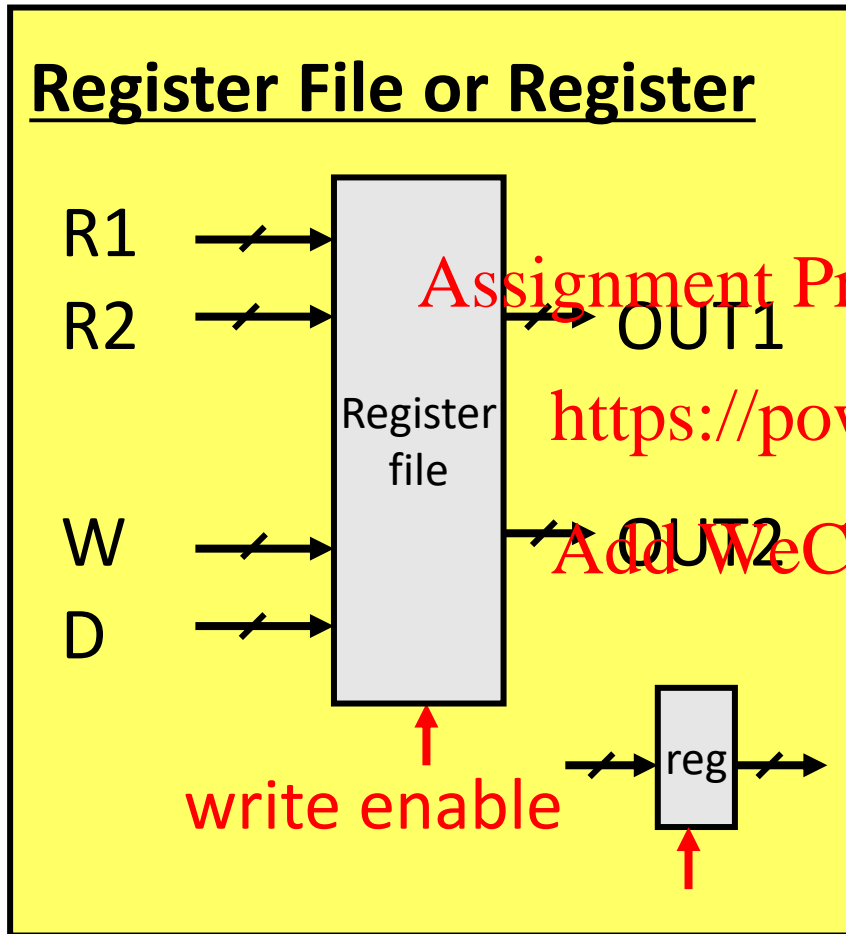
$$\text{OUT}(15:0) = \text{IN}(15:0)$$

Useful when compute unit is wider than data

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State Building Blocks (1)

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Small/fast memory to store temporary values

n entries (LC2 = 8)

r read ports (LC2 = 2)

w write ports (LC2 = 1)

* R_i specifies register number to read

* W specifies register number to write

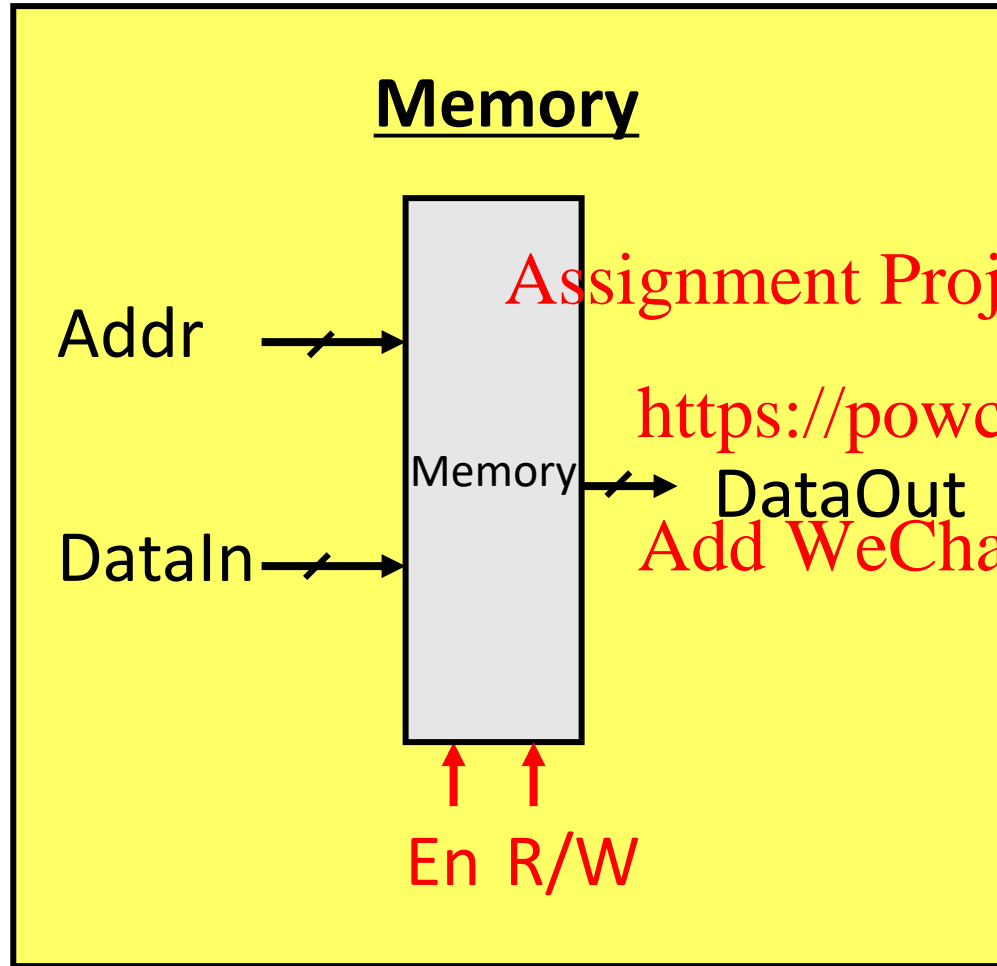
* D specifies data to write

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State Building Blocks (2)

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Single-Cycle



Slower storage structure to hold large amounts of stuff.

Use 2 memories for LC2

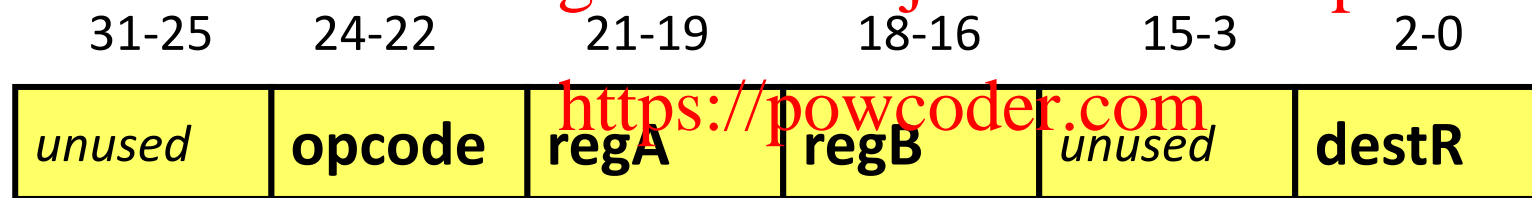
- * Instructions
- * Data
- * 65,536 total words

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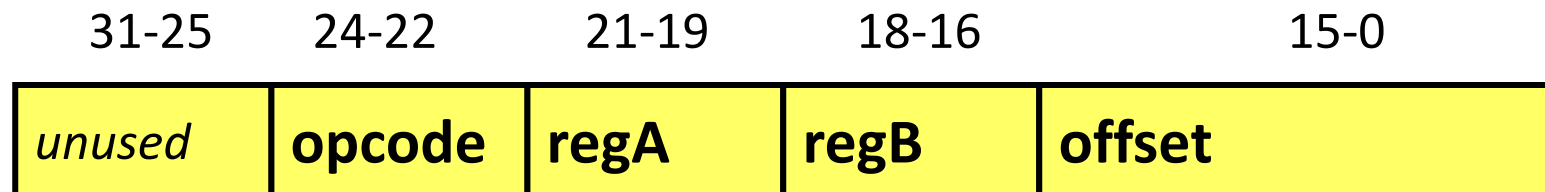
Review: LC2K Instruction Formats

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- Tells you which bit positions mean what
- R-type instructions (opcodes add 000, nor 001)



- I-type instructions (opcodes lw 010, sw 011, beq 100)



Logistics

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 - L10_3 – LC2K-Datapath
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L10_3 LC2K-Datapath

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Learning Objectives

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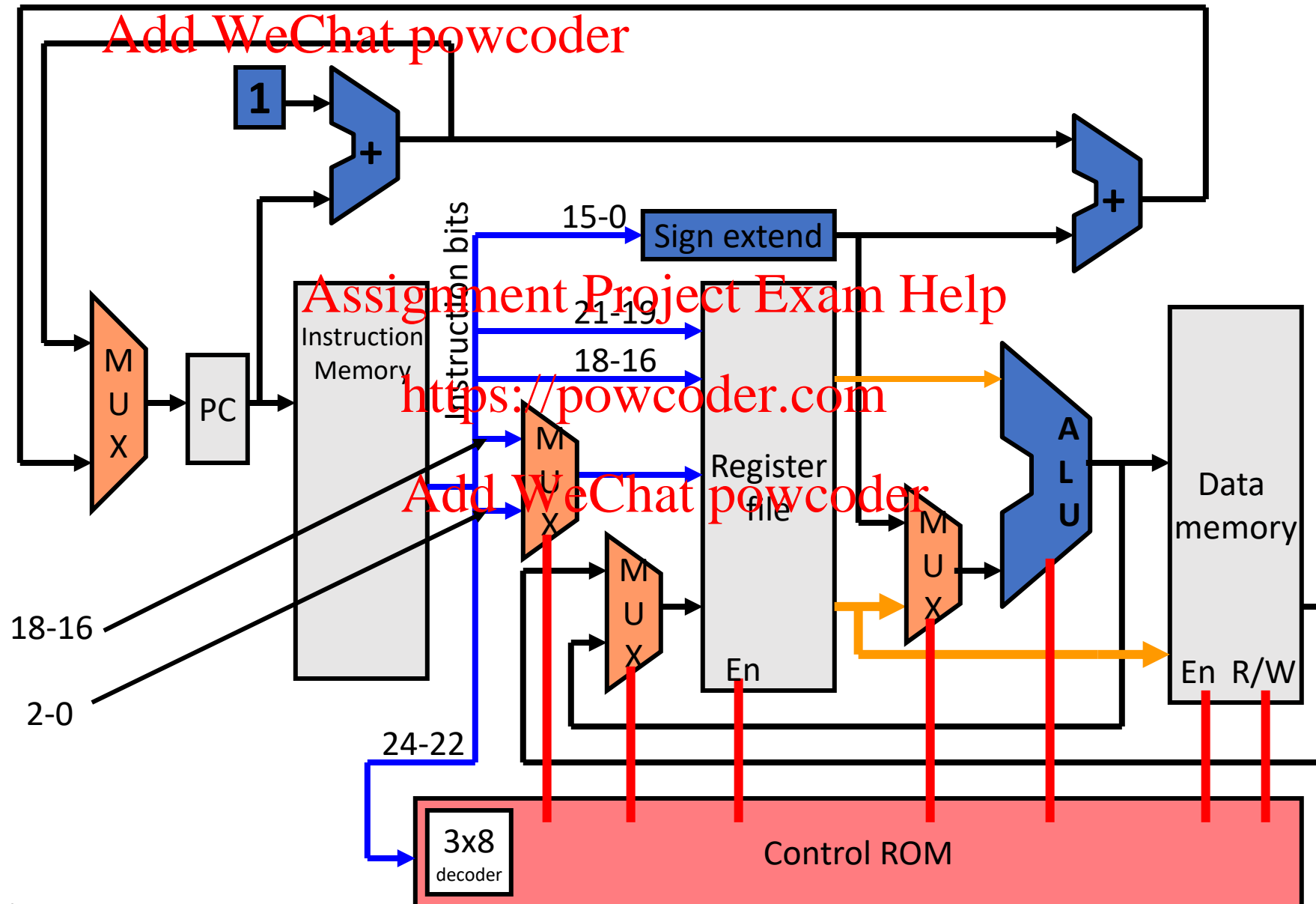
- Ability to trace and explain the flow of data in a single-cycle processor diagram, using the blocks from the previous lecture.
- Identify the timing and operation of control circuit for a single-cycle processor.

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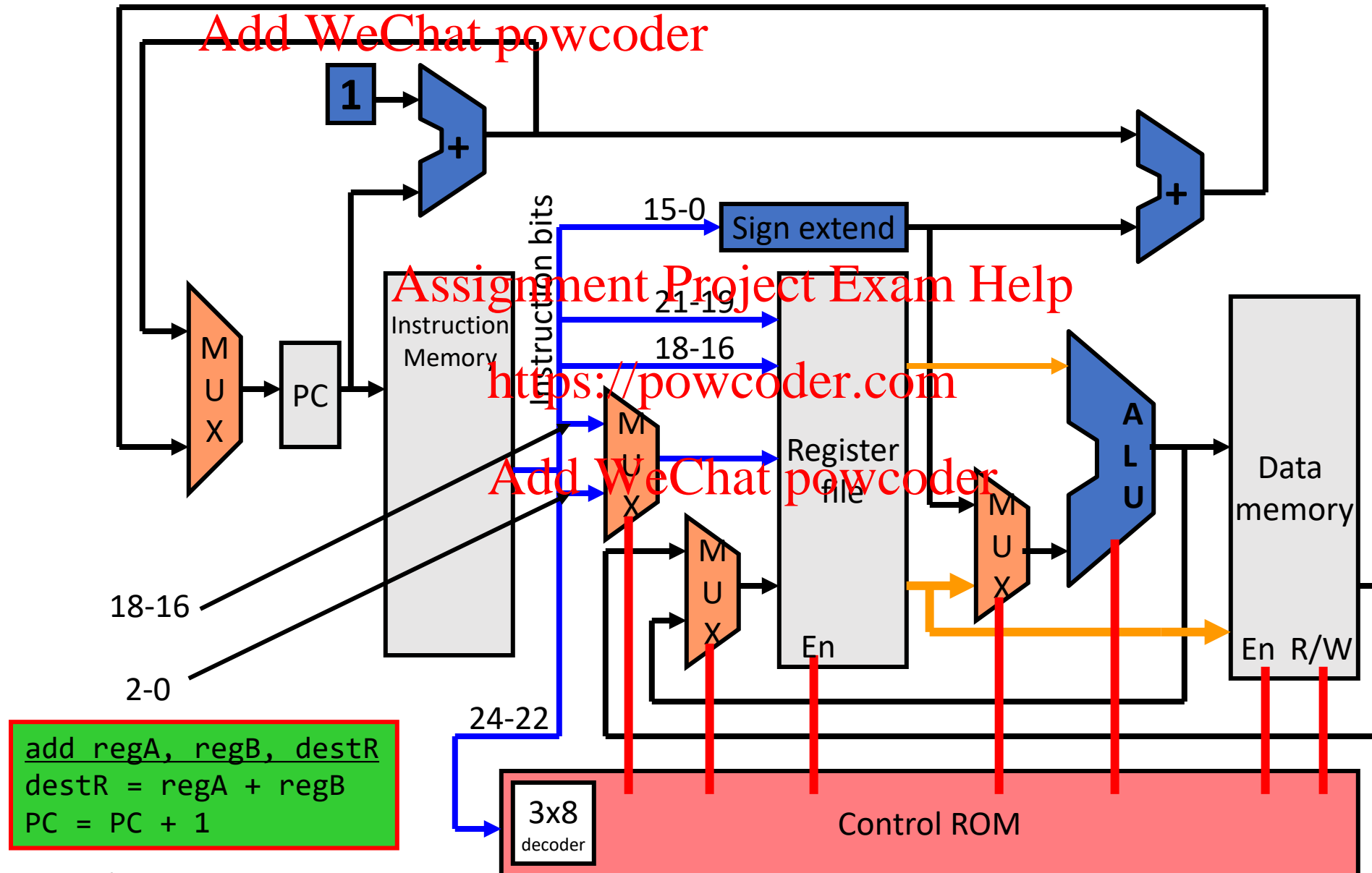
LC2Kx Datapath Implementation

Single-Cycle



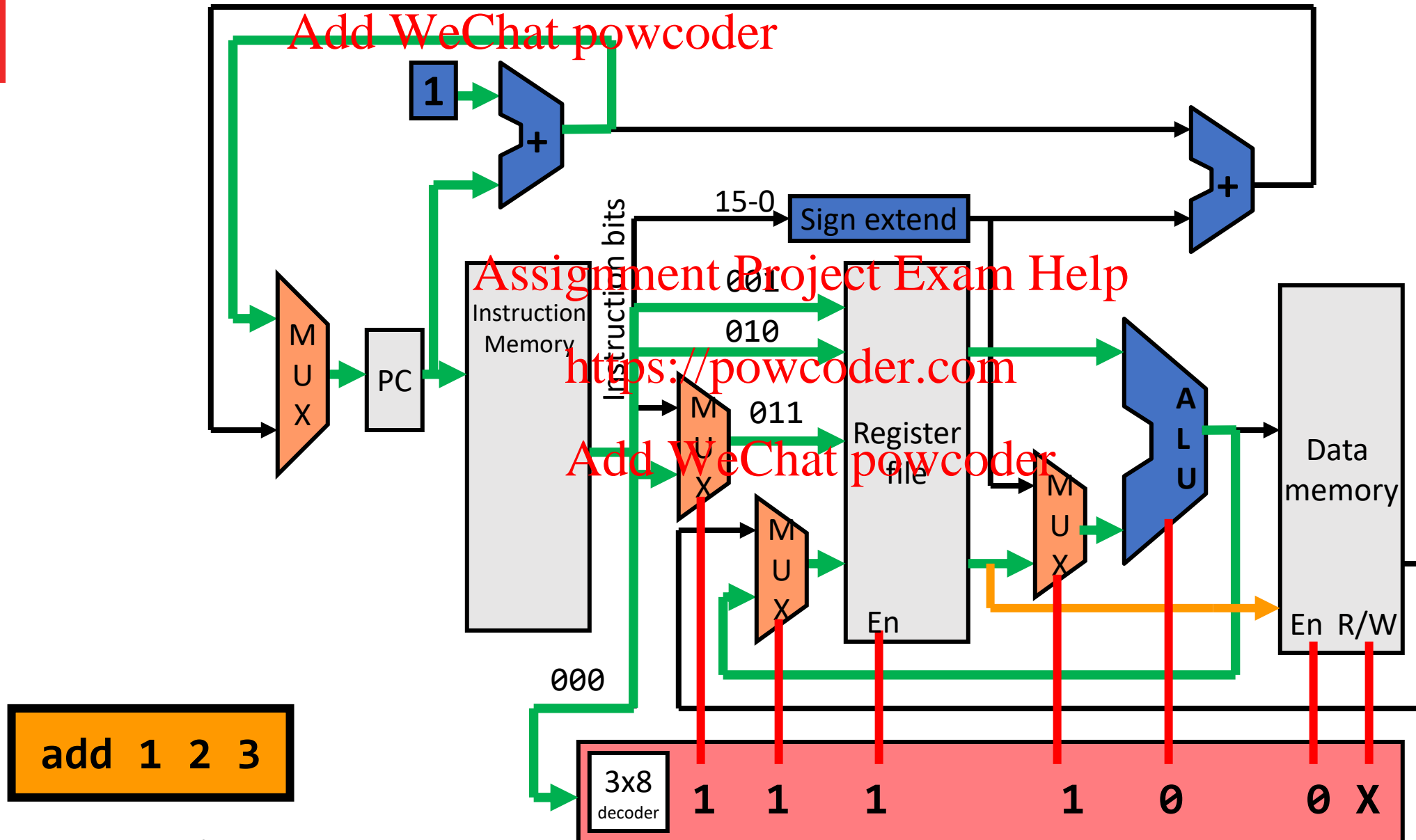
Executing an ADD Instruction

Single-Cycle



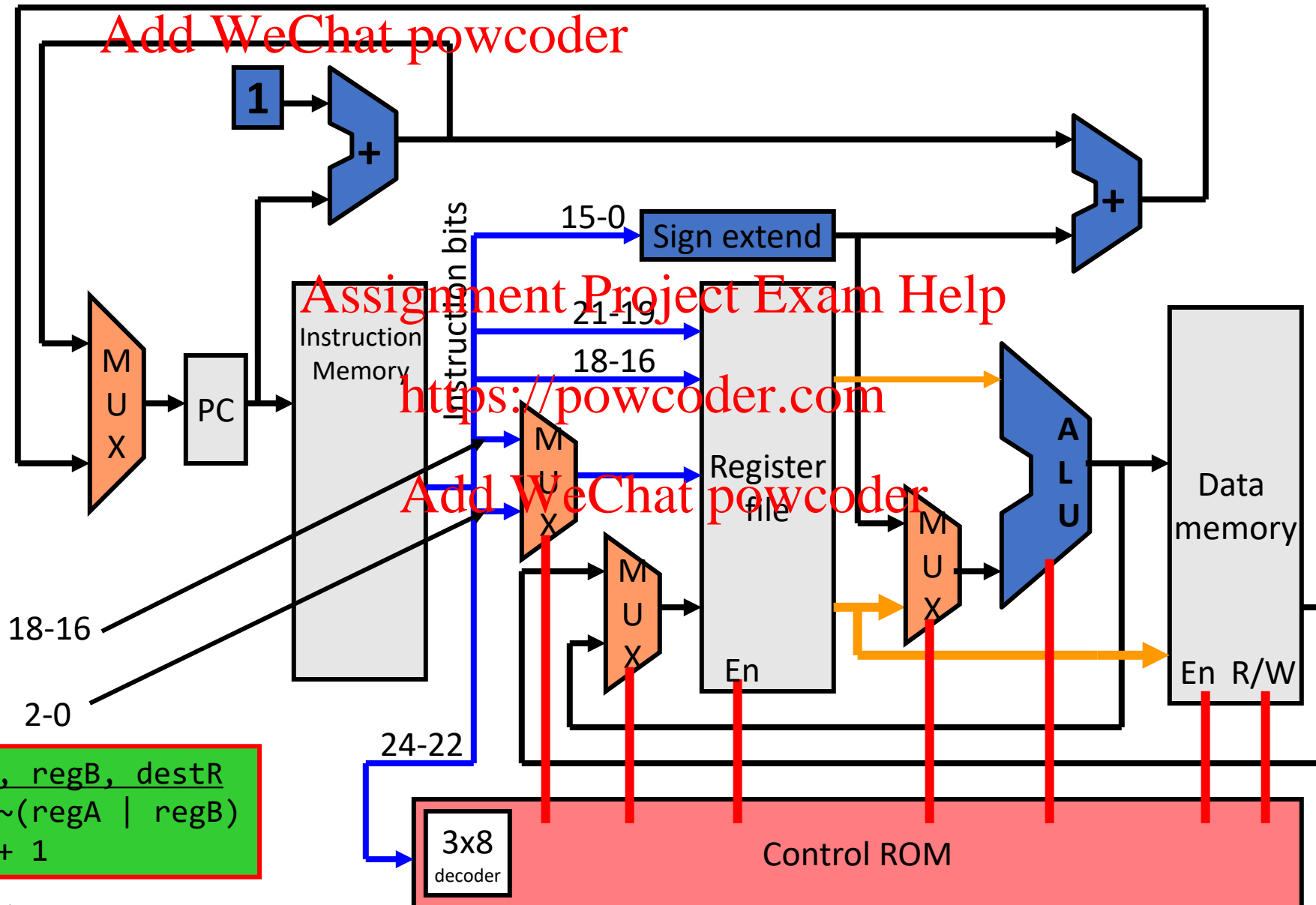
Executing an ADD Instruction

Single-Cycle



Executing a NOR Instruction

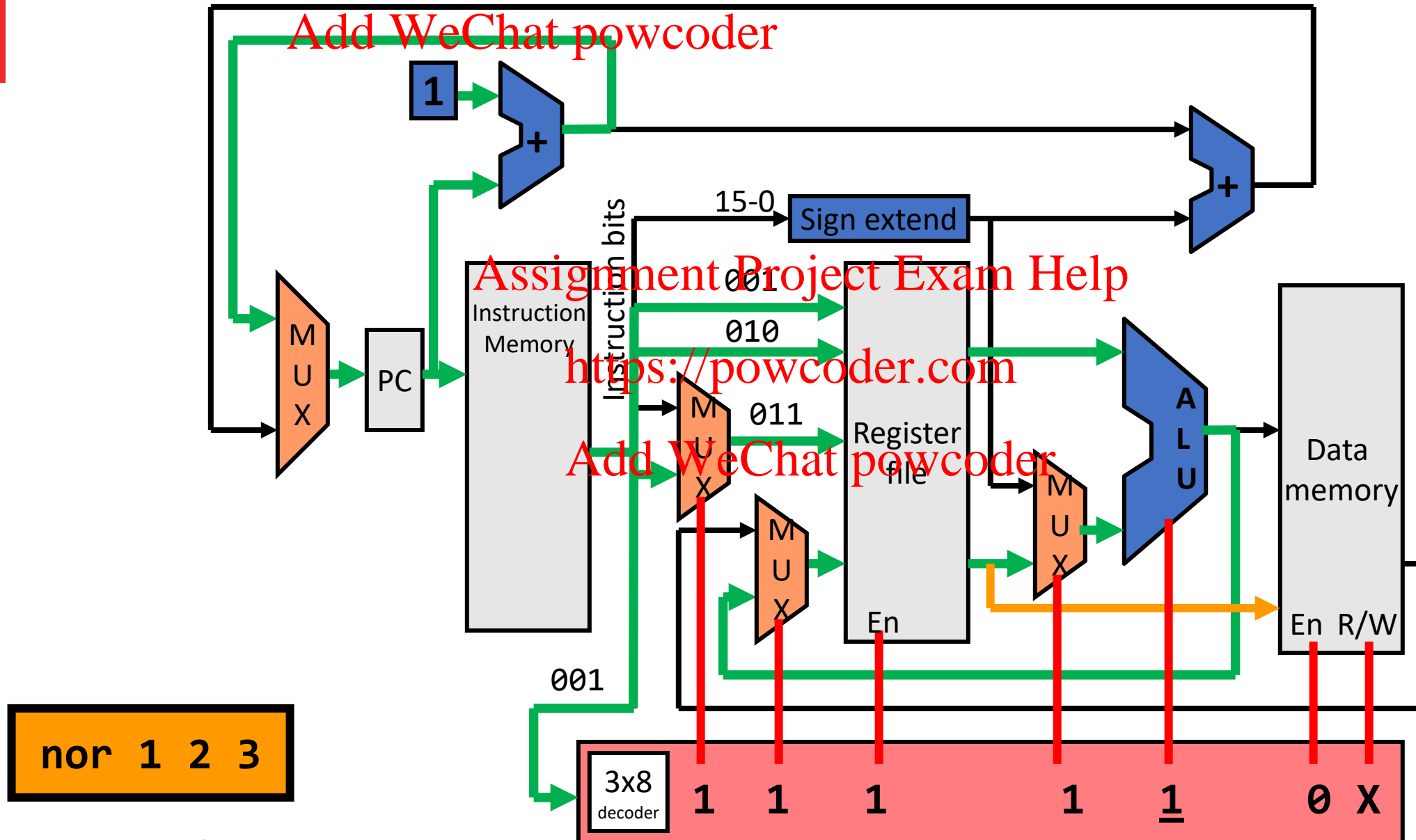
Single-Cycle



```
nor regA, regB, destR  
destR = ~(regA | regB)  
PC = PC + 1
```

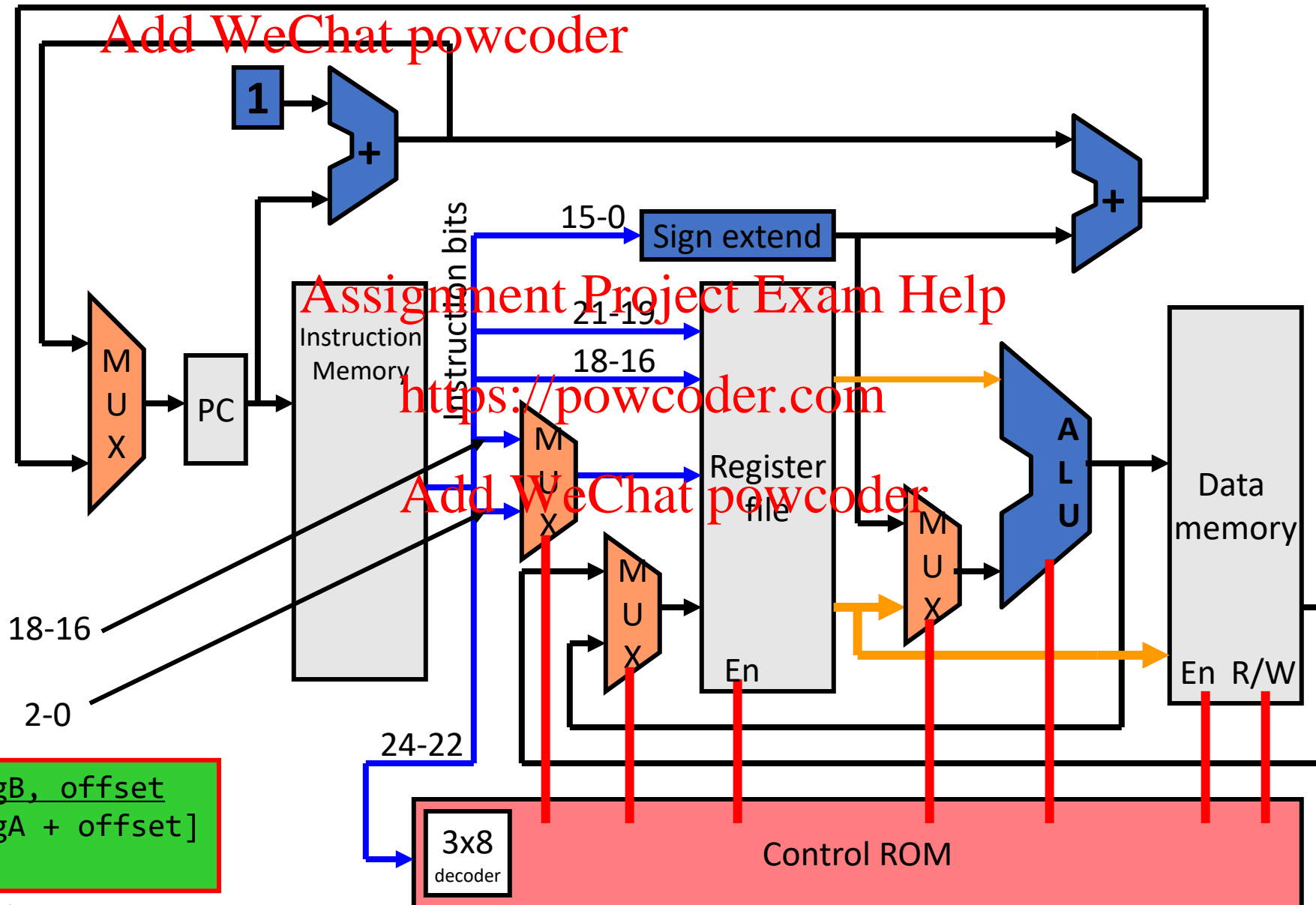
Executing a NOR Instruction

Single-Cycle



Executing an **LW** Instruction

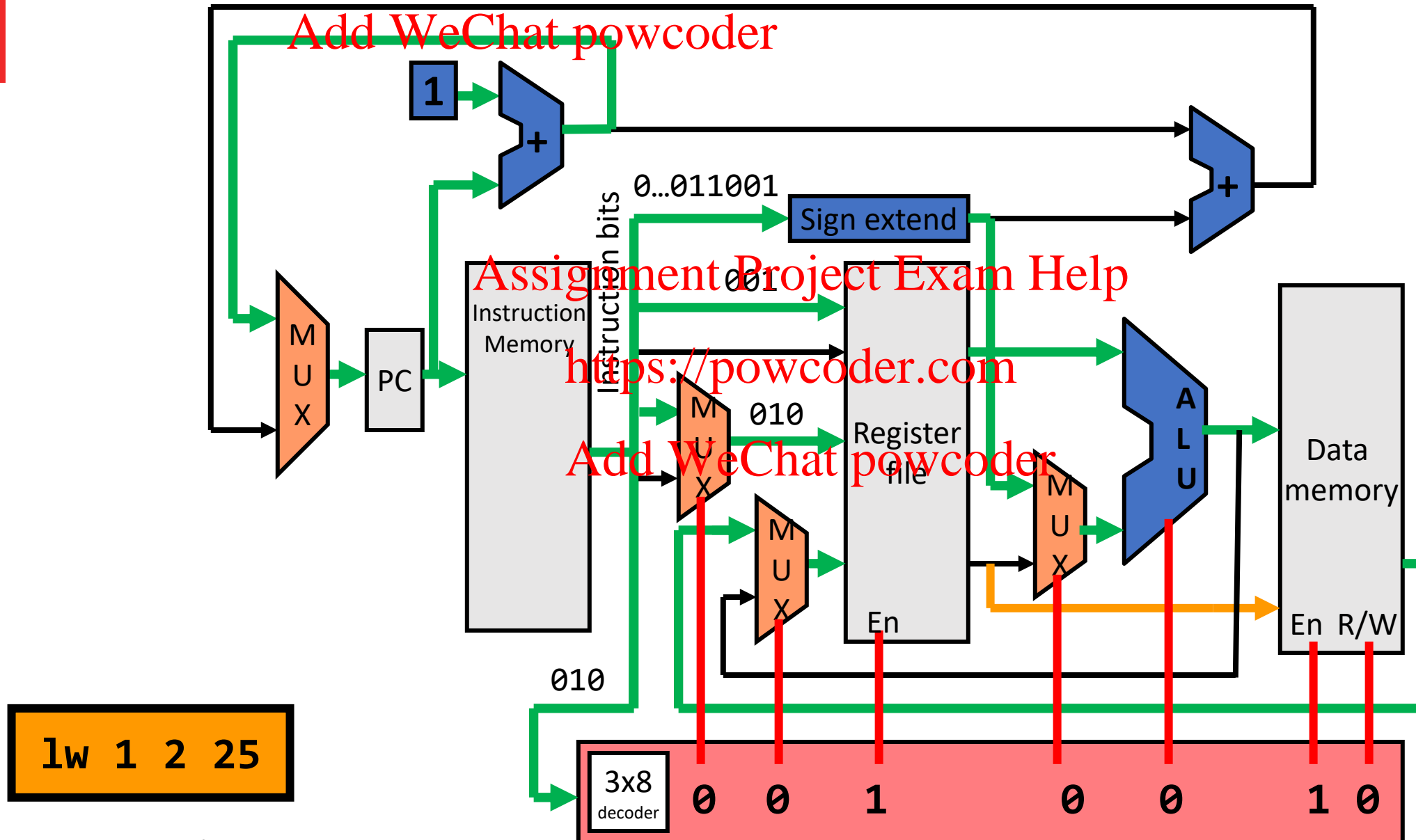
Single-Cycle



`lw regA, regB, offset`
 $\text{regB} = \text{M}[\text{regA} + \text{offset}]$
 $\text{PC} = \text{PC} + 1$

Executing an **LW** Instruction

Single-Cycle



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More instructions to come...

Next lecture!

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