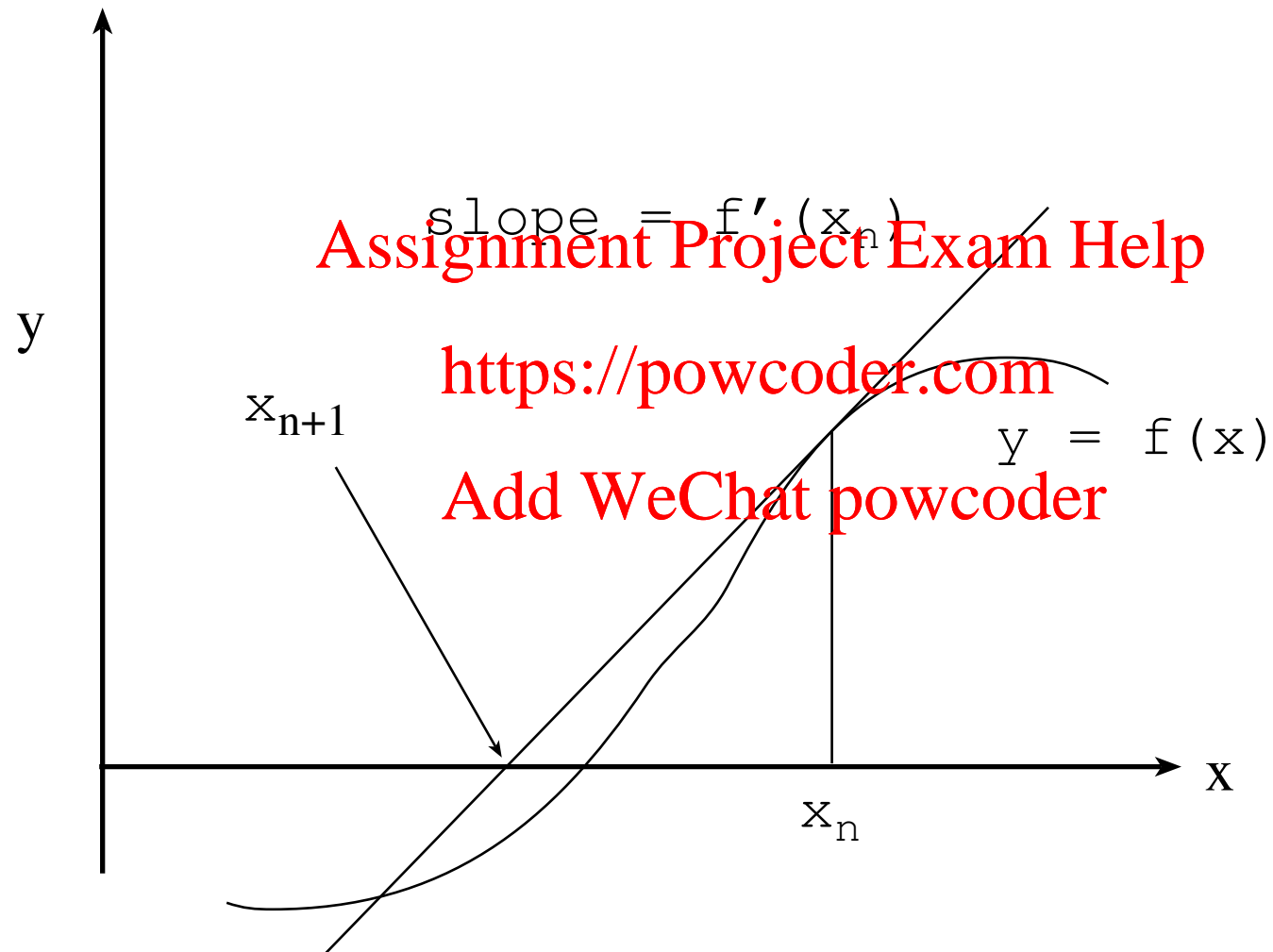


Newton's method



based on **slope** of function

Derivation

Taylor series around x_n :

$$f(x_{n+1}) \approx f(x_n) + f'(x_n)(x_{n+1} - x_n) = 0$$

which gives

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Newton-Raphson iteration:

$$x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}.$$

Again, a first order recurrence relation.

\implies we expect problems if $f'(x_n) = 0$

Simple roots

Definition

f has a **simple root** at x^* if $f(x^*) = 0, f'(x^*) \neq 0$.

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Definition

f has a **double root** at x^* if $f(x^*) = 0, f'(x^*) = 0, f''(x^*) \neq 0$.

\implies Newton's method has trouble at a double root

Example

Convergence rates

At a simple root:

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 $e_{n+1} \sim Ce_n^2$

quadratic convergence

At a double root:

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 $e_{n+1} \sim Ce_n$

linear convergence

Definition

Order of convergence If $e_{n+1} \sim Ce_n^p \implies$ order of convergence = p

Explanation by Taylor series ...

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Can derive this more rigorously.

Linear convergence

Write $e_n = 10^{-b_n}$

b_n = number of correct decimal digits

Linear Convergence \Rightarrow

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 $e_{n+1} \approx C e_n \quad C < 1$

$$\Rightarrow b_{n+1} \approx b_n - \log_{10} C$$

\rightarrow number of correct digits increases by a constant

Quadratic Convergence



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$e_{n+1} \approx C e_n^2$
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$\log_{10} C \approx 2/n$
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→ number of correct digits doubles each iteration!!

⇒ Quadratic Convergence **very desirable**

Problems with Newton's method

- $f'(x)$ may be hard to calculate
- it may not converge :-(

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Theorem

If $f''(x)$ is C^1 then $\exists \delta > 0$ such that $\forall x \in [x^* - \delta, x^* + \delta]$, Newton's method converges to the root x^*

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\implies converges provided we start close enough

BUT

- don't know x^*
- don't know δ

\implies get close with a globally convergent method, then switch to a fast method

\rightarrow **hybrid method**

Convex functions

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Note: for some functions, Newton's method is guaranteed to converge

Example

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Secant method

What if the derivative is really nasty? \Rightarrow try the secant method instead, which **doesn't need the derivative function**.

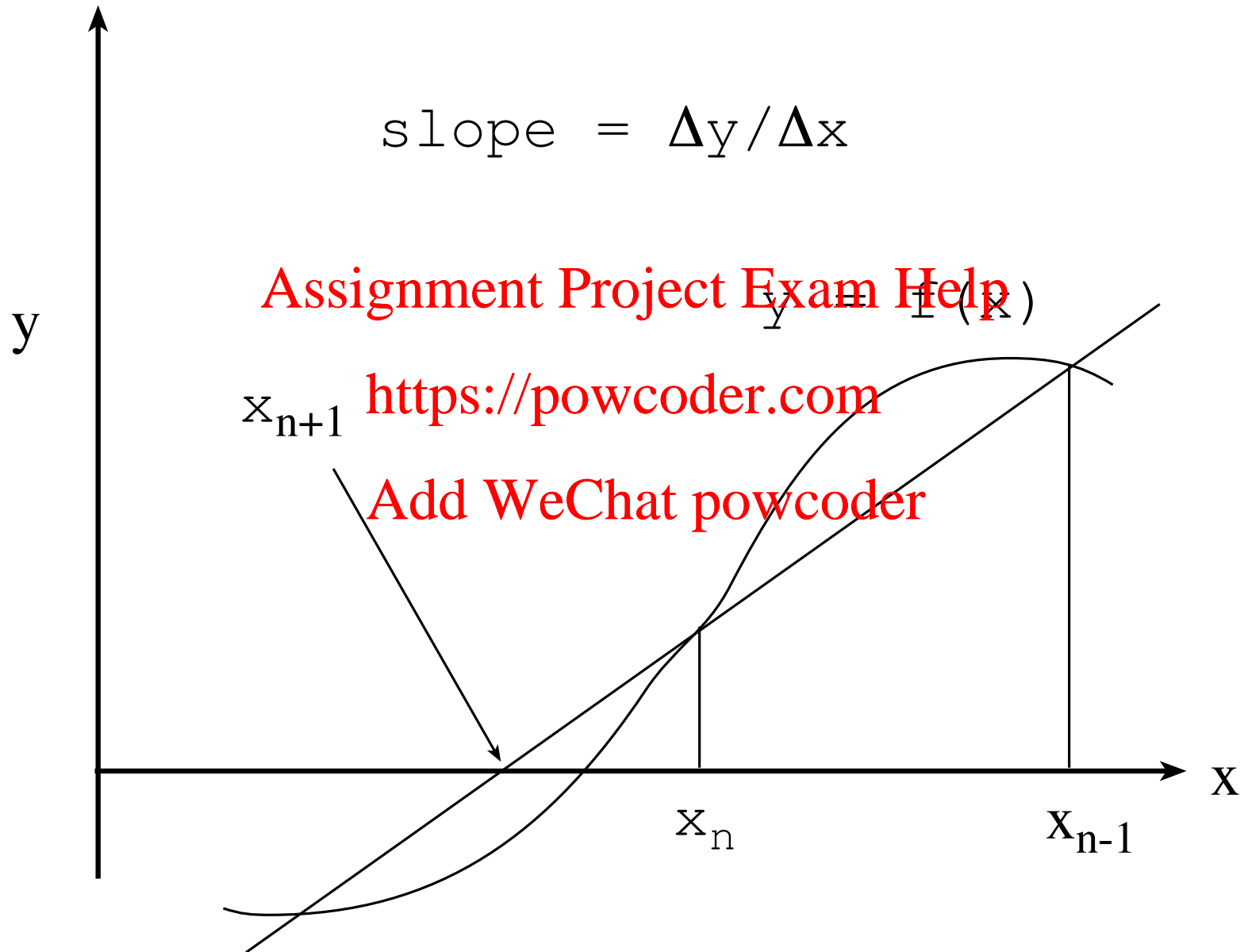
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The secant method.

For this method, use **two current "guesses"** at a root of $f(x) = 0$.

Want to replace the pair x_0, x_1 by the pair x_1, x_2 where x_2 is a new guess.

Use the straight line L from $(x_0, f(x_0))$ to $(x_1, f(x_1))$ (a **secant** of the curve $y = f(x)$) to give the slope.



Secant method algorithm

Just replace $f'(x_n)$ from NR method by

$$\frac{f(x_n) - f(x_{n-1})}{x_n - x_{n-1}}$$

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which gives

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Secant method:

$$x_{n+1} = x_n - f(x_n) \frac{x_n - x_{n-1}}{f(x_n) - f(x_{n-1})}.$$

Since each new guess depends on the previous two guesses \implies a second order recurrence relation.

Properties

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The secant method:

- quite efficient: converges quickly towards a root :-)
- must start with two guesses :- (
- don't need derivative :-)

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Order of convergence

Using Taylor series, \rightarrow (at simple root)

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$$e_{n+1} \sim C e_n e_{n-1}$$

$$\Rightarrow e_{n+1} \sim C e_n^p \text{ where } p = \frac{1+\sqrt{5}}{2} \approx 1.618$$

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\Rightarrow secant is **superlinearly convergent but not quadratically convergent**

(but only need 1 function evaluation/iteration; Newton needs 2)

Summary

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| | | |
|-------------|-------------------------------|---------------------|
| fixed point | $e_{n+1} \sim Ce_n$ | may diverge |
| bisection | $e_{n+1} \sim \frac{1}{2}e_n$ | globally convergent |
| Newton | $e_{n+1} \sim Ce_n^2$ | simple root |
| Newton | $e_{n+1} \sim \frac{1}{2}e_n$ | double root |
| secant | $e_{n+1} \sim Ce_n^{1.618}$ | simple root |

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Hybrid methods

Attractive to combine **global convergence** of bisection with **speed** of another method e.g. Newton or secant
→ hybrid methods that switch between basic methods such that interval is always bracketing

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Example

MATLAB's `fzero`

- switches between bisection, secant and Inverse Quadratic Interpolation (faster than secant)
- needs no derivative

What about systems of nonlinear equations?

Try Newton's Method for system of 2 equations in 2 variables.

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$$f(x, y) = 0 \quad g(x, y) = 0$$

Expand in Taylor series about current iterate to get tangent plane approximation:

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$$f(x_{n+1}, y_{n+1}) \approx f(x_n, y_n) + \frac{\partial f}{\partial x} \Big|_n (x_{n+1} - x_n) + \frac{\partial f}{\partial y} \Big|_n (y_{n+1} - y_n) = 0$$

$$g(x_{n+1}, y_{n+1}) \approx g(x_n, y_n) + \frac{\partial g}{\partial x} \Big|_n (x_{n+1} - x_n) + \frac{\partial g}{\partial y} \Big|_n (y_{n+1} - y_n) = 0$$

or in matrix notation

$$\begin{bmatrix} f(x_n, y_n) \\ g(x_n, y_n) \end{bmatrix} + \begin{bmatrix} \frac{\partial f}{\partial x} \Big|_n & \frac{\partial f}{\partial y} \Big|_n \\ \frac{\partial g}{\partial x} \Big|_n & \frac{\partial g}{\partial y} \Big|_n \end{bmatrix} \begin{bmatrix} x_{n+1} - x_n \\ y_{n+1} - y_n \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

where partial derivs are evaluated at (x_n, y_n)

\Rightarrow at each iteration, must solve a **linear system** of the form

$$J \Big|_n (x_{n+1} - x_n) = -f \Big|_n$$

\Rightarrow must learn how to solve linear systems first!

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End of Lecture 10

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