

1 SLAM Research

The resources [2] and [1] might be helpful.

References

- [1] M. G. Dissanayake, P. Newman, S. Clark, H. F. Durrant-Whyte, and M. Csorba. A solution to the simultaneous localization and map building (slam) problem. *IEEE Transactions on robotics and automation*, 17(3):229–241, 2001.
- [2] H. Durrant-Whyte and T. Bailey. Simultaneous localization and mapping: part i. *IEEE robotics & automation magazine*, 13(2):99–110, 2006.