

1 SLAM Research

The resources [Durrant-Whyte and Bailey, 2006] and [Dissanayake et al., 2001] might be helpful.

References

- M. G. Dissanayake, P. Newman, S. Clark, H. F. Durrant-Whyte, and M. Csorba. A solution to the simultaneous localization and map building (slam) problem. *IEEE Transactions on robotics and automation*, 17(3):229–241, 2001.
- H. Durrant-Whyte and T. Bailey. Simultaneous localization and mapping: part i. *IEEE robotics & automation magazine*, 13(2):99–110, 2006.