# **Custom macros**

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#### **Bras and kets**

Originally, I was using the braket package for this, but it was honestly easy to just write some macros for this.

$$\texttt{\pra}\{\texttt{\pri}\} \rightarrow \langle \psi |; \texttt{\phi}\} \rightarrow |\phi\rangle$$

# **Expectation value**

 $\arrowvert \arrowvert \arrowver$ 

$$\rightarrow \left\langle \frac{df}{dt} \right\rangle$$

### Commutation

### Commutator

$$\label{eq:comm} {\rm op}\{{\rm x}\}\{{\rm op}\{{\rm p}\}\} \ = \ {\rm i}\{{\rm hbar}\$ \to \left[\hat x,\hat p\right] = i\hbar$$

#### **Anticommutator**

 $s^{\circ}_{c}_{i}}_{\cc}_{j}} = \delta_{\alpha, \beta}$ 

$$\rightarrow \left\{ \hat{c}_{i},\hat{c}_{j}^{\dagger }\right\} =\delta _{\alpha ,\beta }$$

# **Compact derivatives**

\$\$\dlp{f}{t}\$\$

$$\to \partial_t \, f$$