



# The Any% Method: A Lessons Learned on Designing and Executing LeanSat Missions Quickly and Affordably

Bronco Space  
California State Polytechnic University,  
Pomona

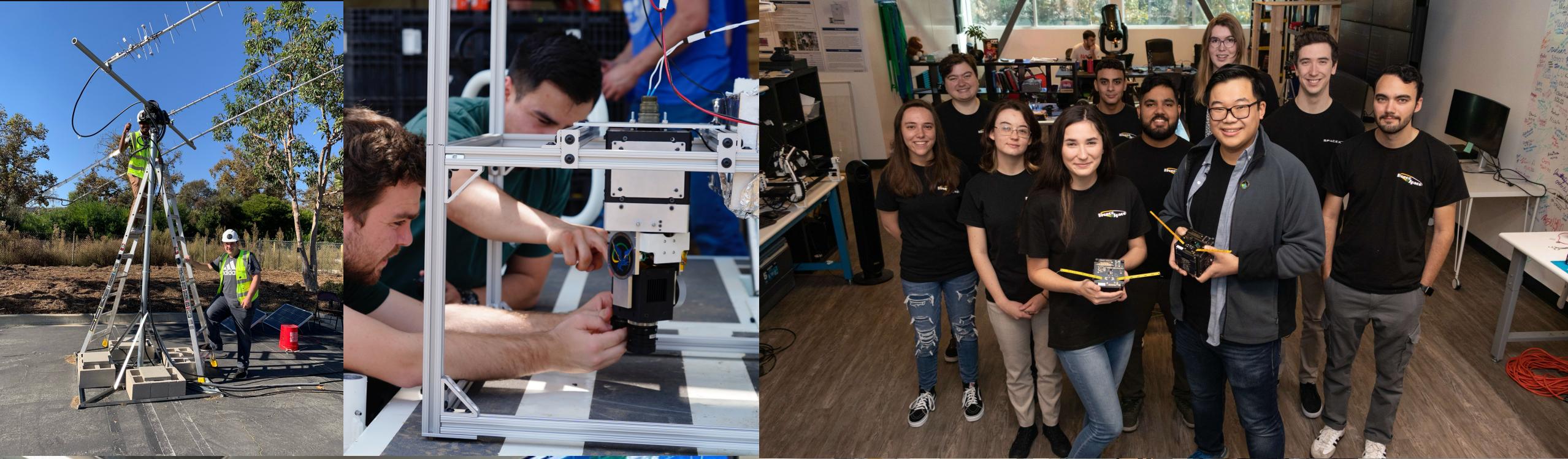
For Public Release



# About Bronco Space



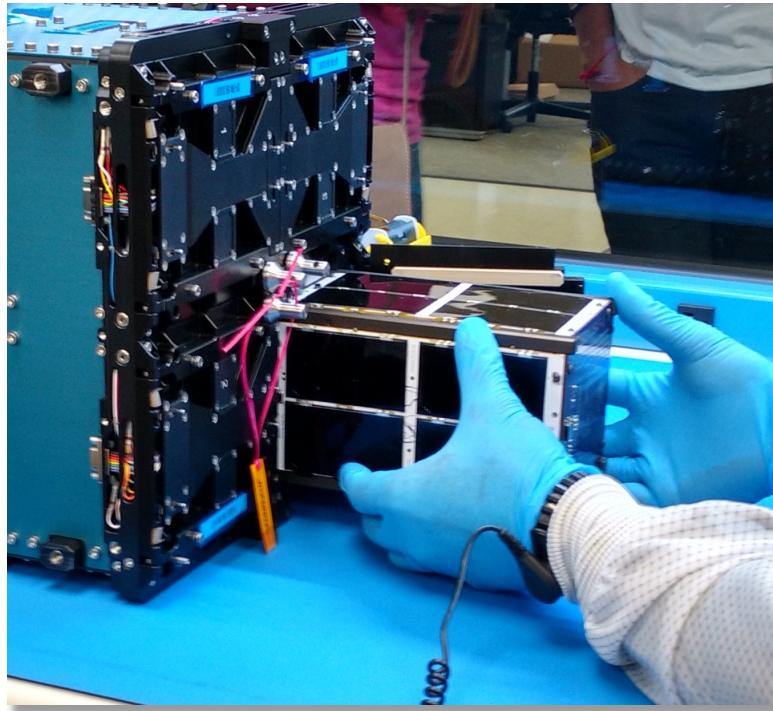
- Bronco Space is a mostly undergraduate student organization at Cal Poly Pomona.
- Founded in 2019, Bronco Space has run the entire gamut from starting at zero to becoming the leading space technology group at Cal Poly Pomona.
- Bronco Space has engaged in multiple NASA funded instrument development projects. Average time for TRL 3 to TRL 6 is 10 months.



# A Bronco Space Lab Walkthrough



# Bronco Space's Satellites



- In the last calendar year our organization has delivered three unique CubeSats for launch to LEO, all on commercial launch services. Our first CubeSat was launched in Summer 2022.
- The satellites have trended to be significantly cheaper and faster with each iteration.
- Our current effort is focused on PROVES (Pleiades Rapid Orbital Verification Experiment System).

# BroncoSat-1 Mission Results

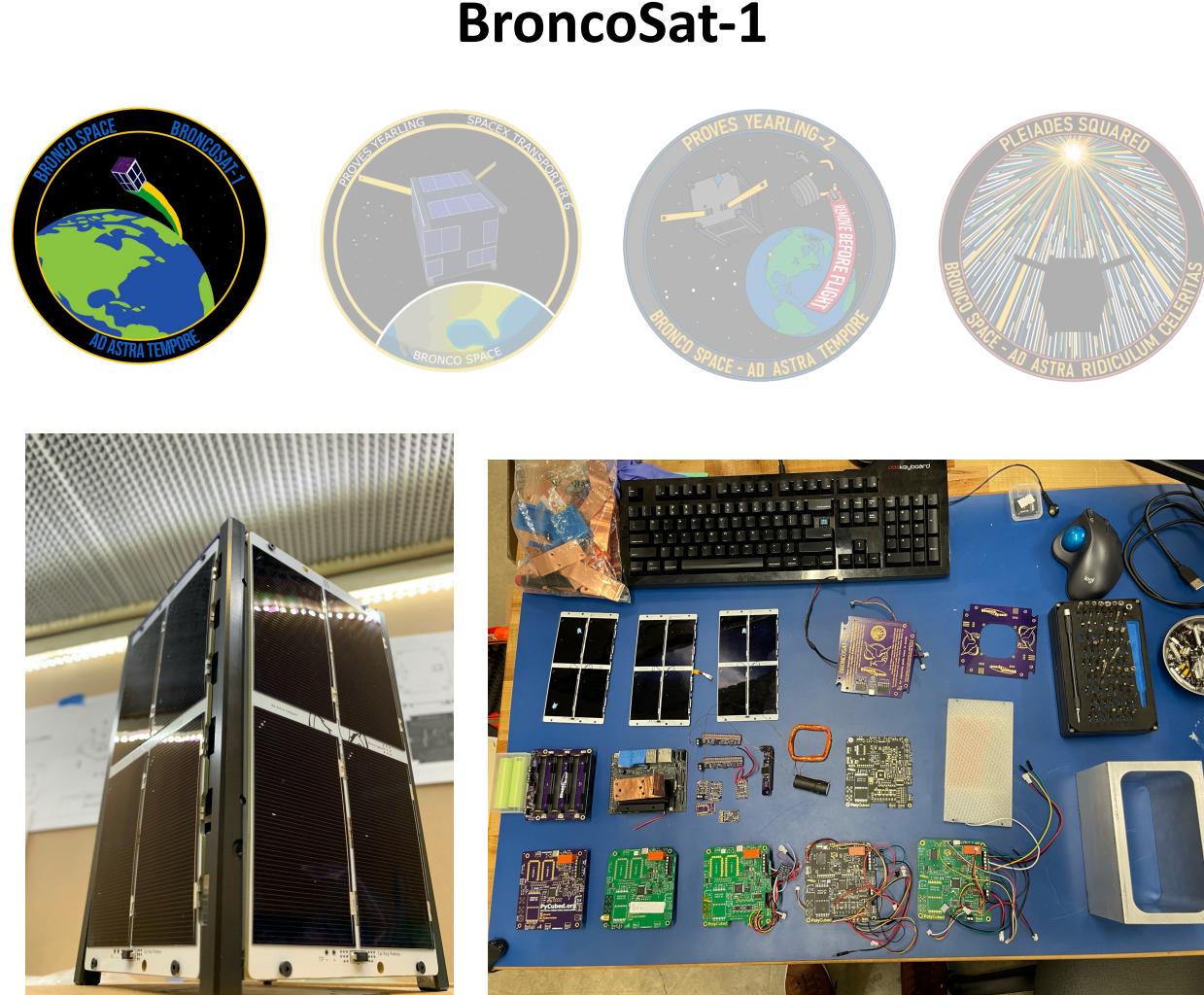


## Mission Metrics

- **Mission Objective:** Artificial Intelligence and Machine Learning Technology Demonstration
- **Initial Planned Launch:** November 2021
- **Actual Launch:** June 2022 (Delay by Launch Provider)
- **Launch Result:** Dead on Arrival
- **Initial Budget:** \$10k USD (Not Including Launch)
- **Actual Cost:** \$120k USD (Not Including Launch)

### Key Lessons Learned

- Do not trust performance claims from COTS vendors without independent validation.
- Closed source and non-transparent designs are not conducive to an academic project.
- It is possible to deliver a CubeSat with very little in person involvement if properly managed.



# The Three US Open Source CubeSat Platforms

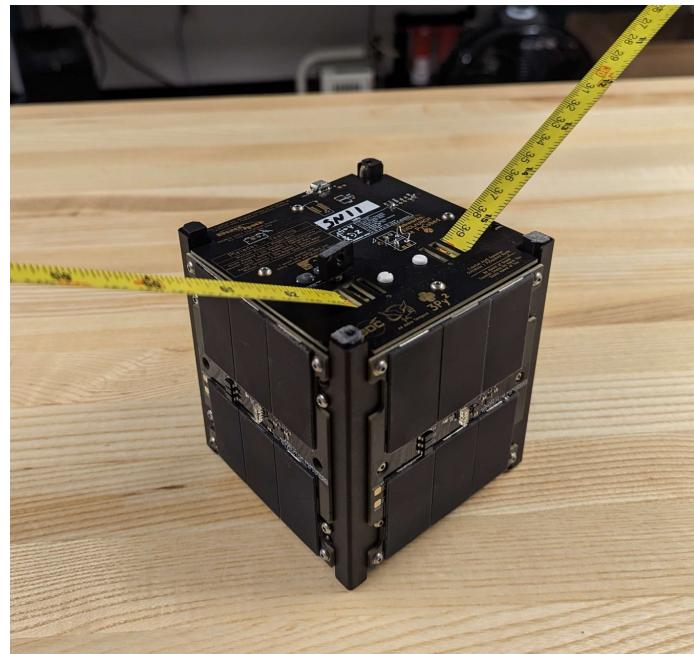


OreSat



- Modular Card Cage System
- OreSat Power Domain and Backplane are unique features
- Resilient but high cost

PyCubed / PROVES



- Single Board Computer architecture
- Minimal overhead is the goal
- Less resilient but very low cost

Artemis CubeSat



- Most traditional CubeSat architecture
- PC104 stackup and Raspberry Pi
- Heavily supported by NASA

# Pleiades – Yearling 1 Mission Results



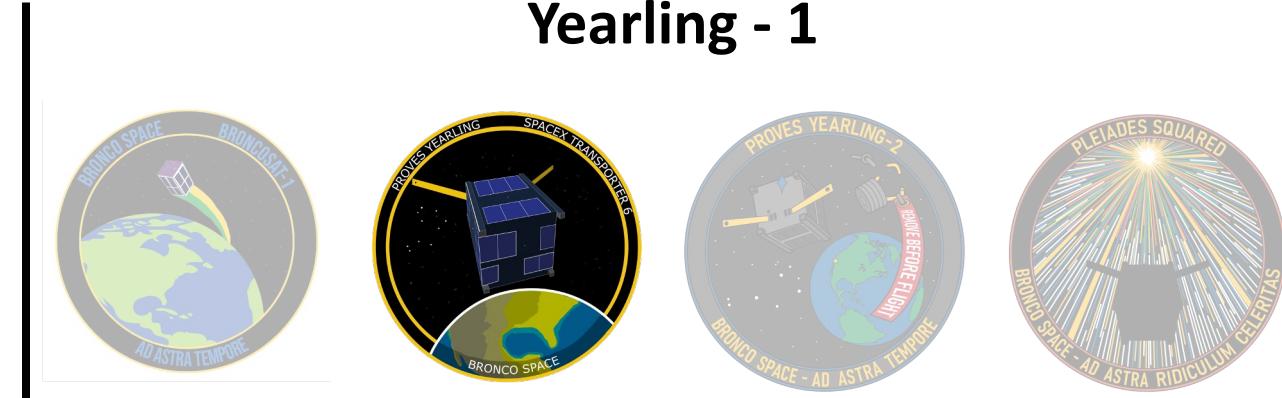
## Mission Metrics

- **Mission Objective:** Flight Validation of PROVES Kit & Intersatellite Link Demonstration
- **Initial Planned Launch:** October 2022
- **Actual Launch:** January 2023 (Delay by SpaceX)
- **Launch Result:** Failure to Deploy (OTV Failure)
- **Initial Budget:** \$35k USD (Including Launch)
- **Actual Cost:** \$48k USD (Including Launch)

### Key Lessons Learned

- Supply chain must be a key consideration during the parts selection process.
- Try to chose readily available parts that also have the smallest learning curve for the team.
- Trust but verify performance of the launch provider, especially if they are a new provider.

## Yearling - 1



# Pleiades – Yearling 2 Mission Results

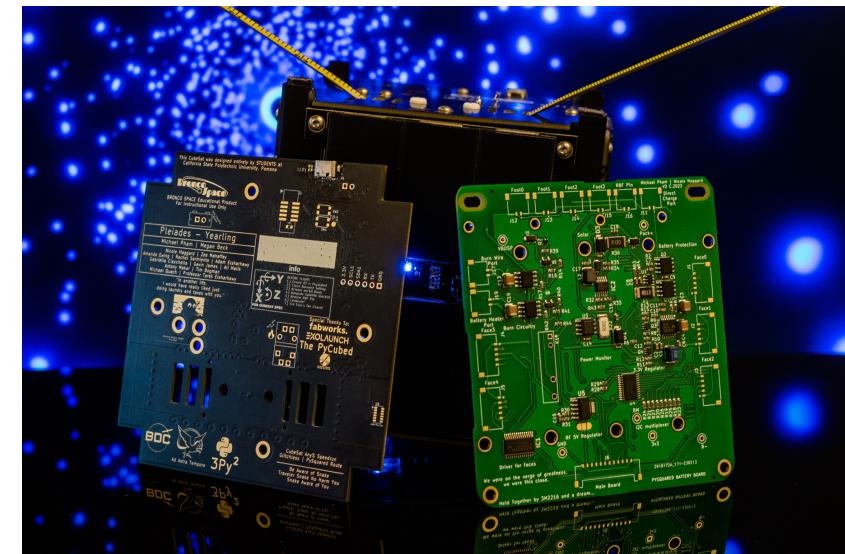
## Mission Metrics

- **Mission Objective:** Flight Validation of PROVES Kit & Intersatellite Link Demonstration
- **Initial Planned Launch:** NET Fall 2023
- **Actual Launch:** April 2023
- **Launch Result:** Initial Telemetry | Early Loss
- **Initial Budget:** \$30k (Including Launch)
- **Actual Cost:** \$32k (Including Launch)

### Key Lessons Learned

- "Think slow, act fast" design philosophy works very well for rapid iteration of designs.
- Parallel workflows are essential to quick design, build, test, fix loops.
- Responsive and fast early mission ops is extremely important. Utilize global community networks whenever possible.

## Yearling - 2



# Design for Mass Manufacturing



- Sheet metal structure for faster manufacturing.
- Enforcing conformity to simpler designs rather than enabling complexity.



- Single sided PCBs that could be quickly SMT assembled and with parts already at the board house.
- Completed sub-assemblies can be binned for quality.



- Multiple iterations to actively fix issues that slowed integration
- Batch manufacturing to maximize experience carry over and parallelism

# Pleiades – Squared Mission Results



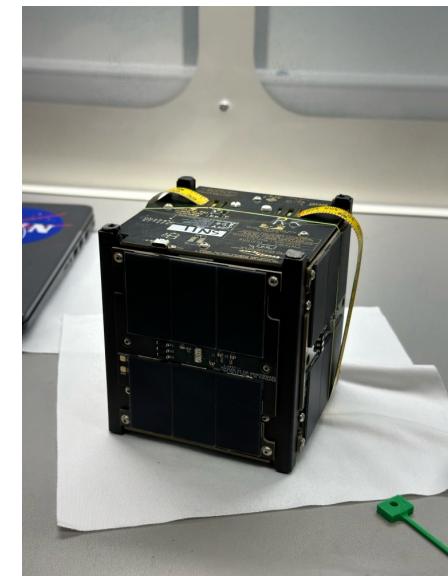
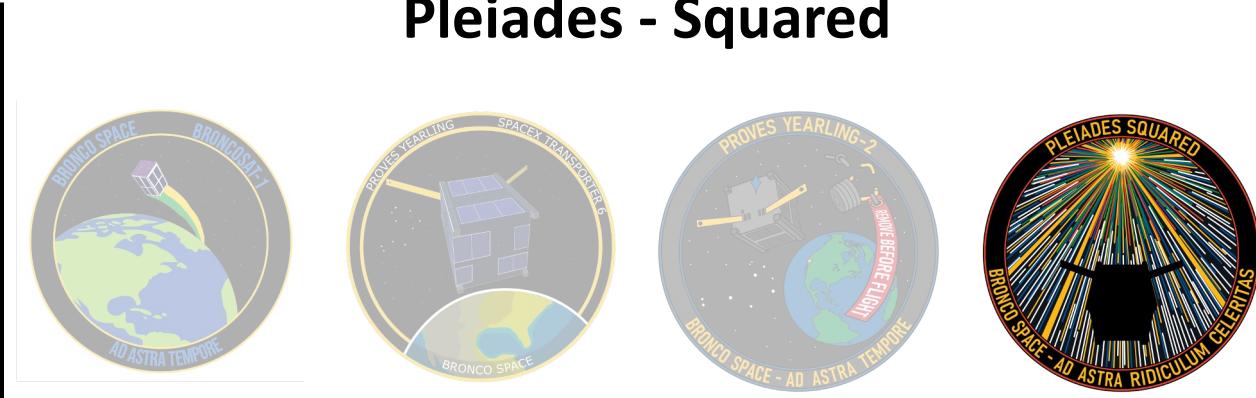
## Mission Metrics

- Mission Objective:** Rapid Response CubeSat Delivery Demonstration
- Initial Planned Launch:** NLT 2024
- Actual Launch:** June 2023
- Launch Result:** Full Mission Data | Early Loss
- Initial Budget:** \$30k (Including Launch)
- Actual Cost:** \$26k (Including Launch)

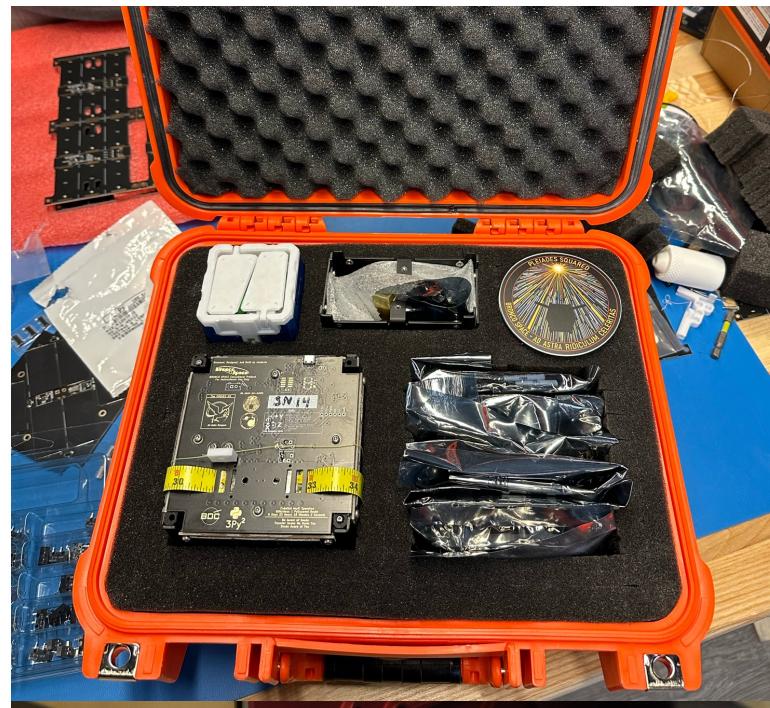
### Key Lessons Learned

- Pre-stocked and binned components allow for can allow for extremely fast delivery.
- Repeated experience with integration and test procedures net very large gains in efficiency.
- Prepare extra operational contingencies during early mission in case of launch provider mishap.

## Pleiades - Squared



# The PROVES Kit



- 21 PROVES Serial Numbers assigned as of February 2024
- Another 5 builds are in progress at various partner organizations.
- Currently there are 8 university users of the PROVES Kit and 2 high school users.

# Radiation Testing

## Key Points For Radiation Testing

- **Objective**
  - To investigate the Polar Low Earth Orbit radiation effects of the electronics of the PROVES Flight Controller (FC) Board
  - Protons and Heavy Ions are the particles of concern in this orbit
  - Recently irradiated the FC board with High Energy Protons to observe single event effects

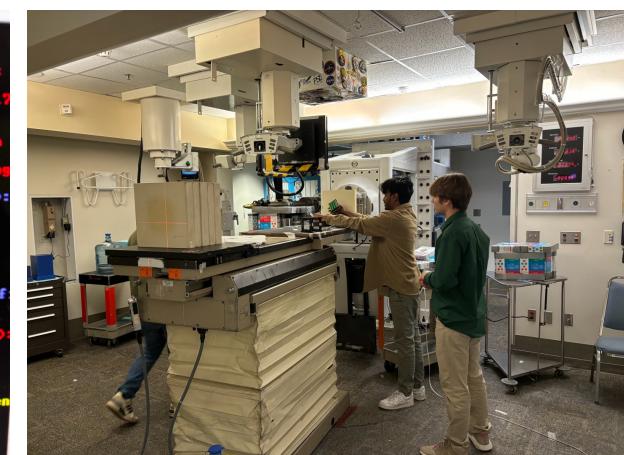
### Key Lessons Learned

- The Flight Controller Board encountered numerous non-destructive single-event effects
- Practice runs of setting up the test setup before the date of testing will help in being efficient with time at the facility
- Provides valuable educational experience for aspiring

## Testing at Loma Linda

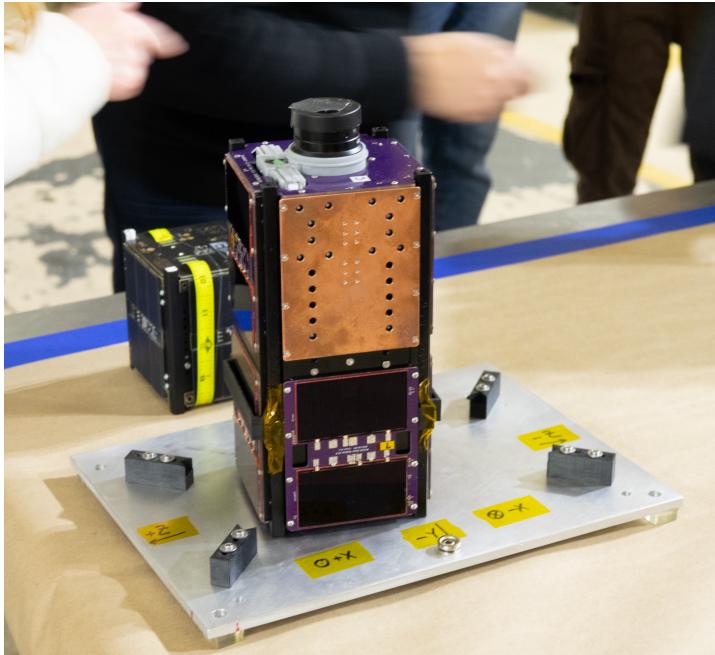


```
[py)squared]Started to manage battery  
[py)squared]MICROCONTROLLER Temp: 24.3296 C  
[py)squared]internal Temperature: 21.75 C  
[py)squared]charge current: -0.31199mA, and charge voltage:  
-22520  
[py)squared]Draw current: 14.557mA, and battery voltage: 7.7  
2529  
[py)squared]system voltage: 7.52374V  
[py)squared]Warning! The Satellite is drawing more power than  
receiving  
[py)squared]CONTENT SHIFT INTO MAXIMUM POWER MODE: Attempting  
to revive all systems...  
[MAIN]Error in Main Loop: Traceback (most recent call last):  
File "main.py", line 264, in <module>  
NameError: name 'DEn->Hh' is not defined  
#t = 0.1 sec  
#J = 10|N?B-YEE-28C=H-1?m J"e@In8GfLkO!9ain!m@  
R = <?>20 ? S@M H =@ !9aG@t J M@Um(=M@G@, is not def  
ined  
[py)squared]ERROR[SD Card]Traceback (most recent call last):  
File "/lib/py)squared.py", line 224, in __init__  
OSError: no SD card  
[Payload]Initializing IMU0055...  
[Payload]ERROR Initializing IMU sensor: Traceback (most recent  
call last):  
File "payload.py", line 67, in __init__  
File "/lib/adafruit_imu0055.py", line 792, in __init__  
File "/lib/adafruit_imu0055.py", line 628
```



# Upcoming Satellite Missions

OreSat-0.5



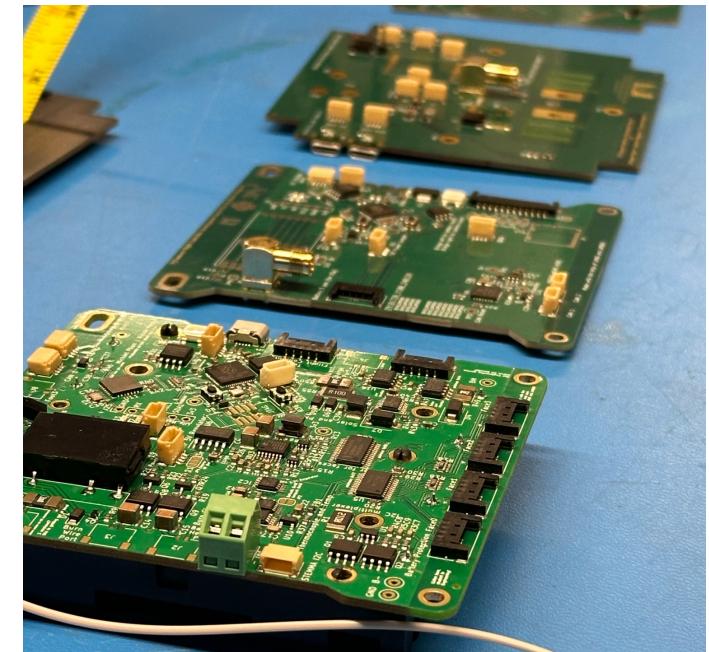
- Fully Open Source ADCS
- DxWiFi High Speed 2.4Ghz Data Link
- Launch on SpaceX TR11

Pleiades - Orpheus



- Additional validation for the PROVES Kit
- Built by High School Students
- Launch on SpaceX TR11

Pleiades - Cerberus



- Testing COPPER
- Common Payload Plate for Expedited Research
- Launch NET Summer 2024

# Any% Speed Running and Lean Satellites



A screenshot of the Speedrun.com website for Super Mario 64 (1996). The page shows a list of players and their times for the full game. The top player is Weegie with a time of 1h 36m 21s. Other players listed include Karin, marlene, Liam, cheese, puncayahun, batora, Persee02, Smau, Kelly, and simply. The platform is N64.

A second screenshot of the Speedrun.com website for Super Mario 64 (1996), showing a different set of results. The top player is Slugi with a time of 1h 36m 48s. Other players listed include KANNO, cijrokokomero, Persee02, Dowsky, Teg009, Poke, Raisin, Akira, Xiah, and wara. The platform is N64.

Source: speedrun.com

- The term Any% is borrowed from the video game speed running community.
- A video game speed run is an activity in which people attempt to complete the game in as little time as possible.
- Common types are 100% or Any%



Source: NASA

- Lean satellites tend to adopt ideas from lean manufacturing techniques.
- Lean manufacturing generally calls for process optimization and removing unneeded steps that slow down the delivery of value.
- Commonly CubeSats or other SmallSats

# A Primer on Video Game Speed Running



Speedrun Clip of Super Mario Brothers – Credit: Sethbling, Source: Youtube

- Clip to the left is a speed run of a Super Mario Brothers level done by a YouTuber known as Sethbling

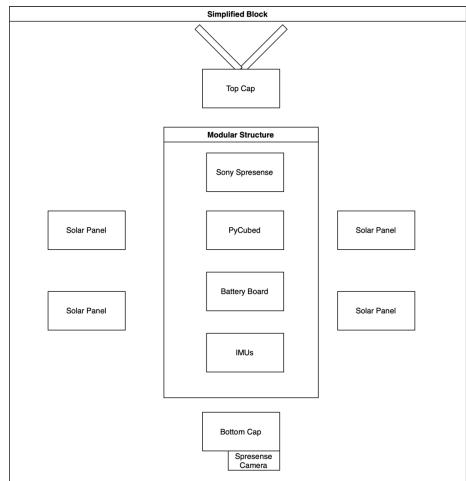


Speedrun Clip of Super Mario Brothers with Splits – Credit: Niftski, Source: Youtube

- Clip to the right is a speed run with "splits" of Super Mario Brothers done by a YouTuber known as Niftski

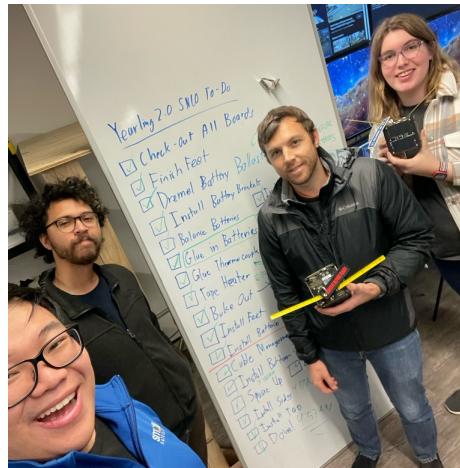
# An Overview of the Any% Method

# Goal Clarity



- Well defined and clearly understood goals
  - Trying to limit to one or two essential objectives and no more

# Benchmarking



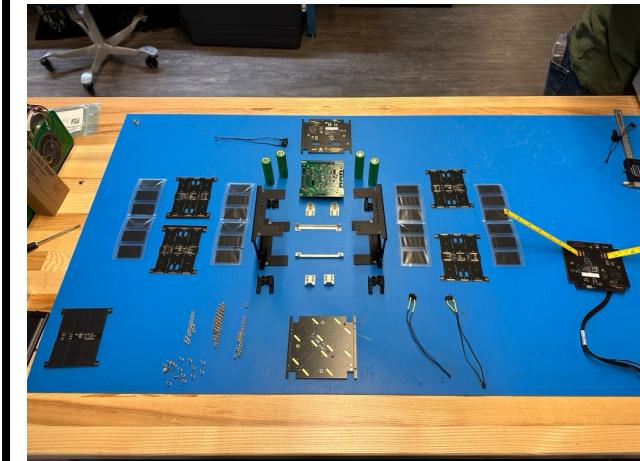
- Measure performance against the expectations of the community
  - Use measured performance to inform needed improvements

## **Repetition & Refinement**



- Improve through repetition.
  - Practice key procedures in the same way one may practice an instrument

# Route Optimization



- Explore alternative arrangements that avoid recurring issues
  - Optimize by choosing the best route, rather than just refining one most traveled

# Goal Clarity

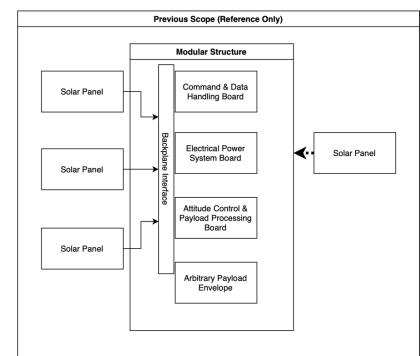
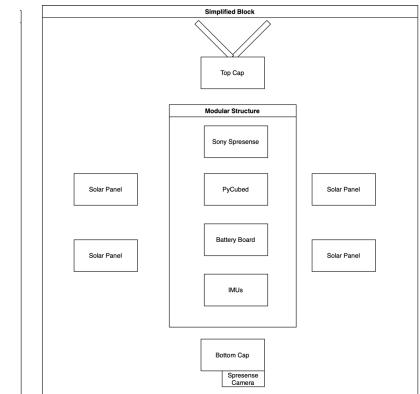
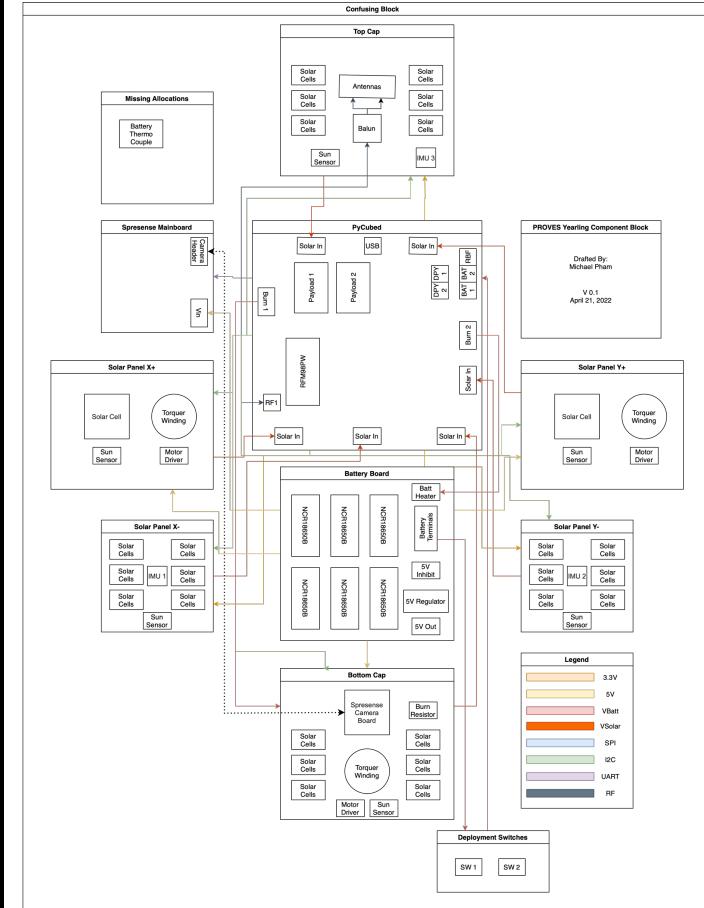
## Key Points

- **Clear Goals:** Every team member should know exactly what the overarching goal of the mission is, and how their personal objectives contribute to that goal.
- **Controlling Scope:** For lean missions, the goals and objectives should focus on the key value proposition of the mission. Additional goals should be disregarded until the key goal is met.

### Key Lessons Learned

- A well understood and clearly defined goal keeps the team on track.
- Minimizing the scope of the goal(s) ensures that the project stays manageable.
- Goals should be changed if the need for them is no longer clear.

## Clear Block Diagrams



# Benchmarking

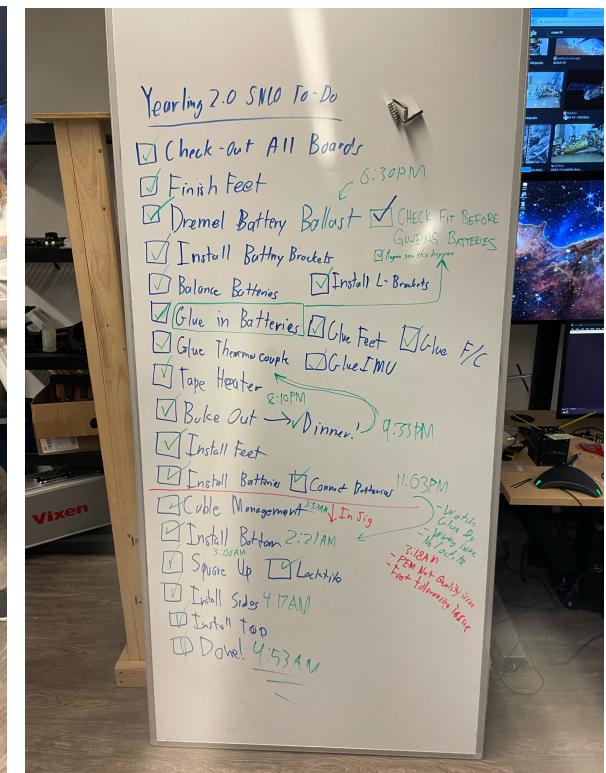
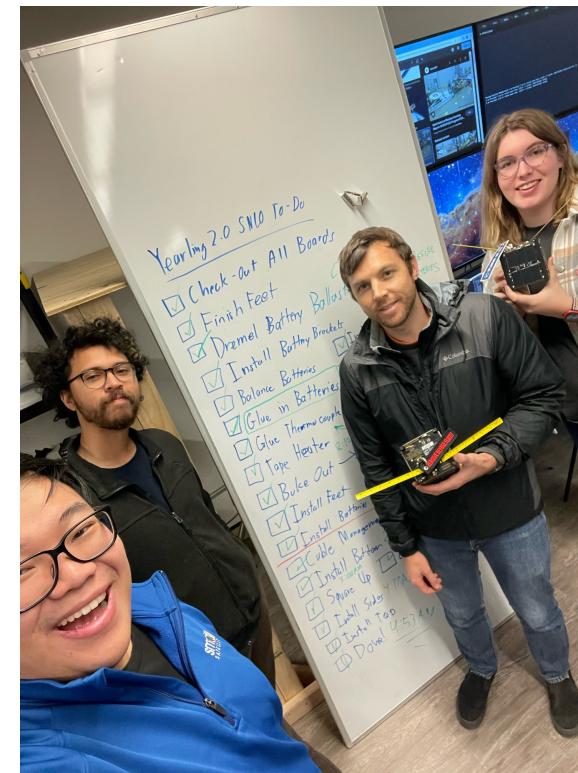
## Key Points

- **Use Data to Understand Your Process:** Just like how an athlete tracks the time it takes for them to run every mile of a marathon, engineers should track how long each step of their process takes.
- **Identify Bottlenecks:** Large improvements can come from focusing on improving the slowest steps rather than trying to generally be faster.

### Key Lessons Learned

- Attempting to rush through the project holistically causes corner cutting and welcomes design flaws.
- Usually focusing on improving one or two critical operations (soldering, staking, testing, etc.) yields great results in optimization.

## Time Trials



# Repetition and Refinement

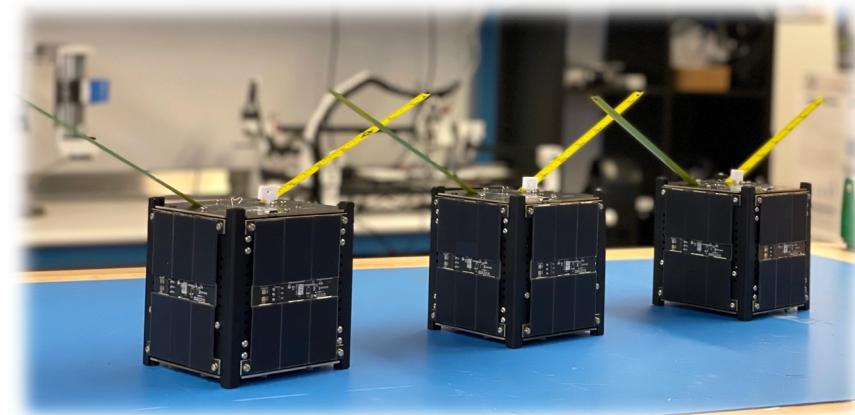
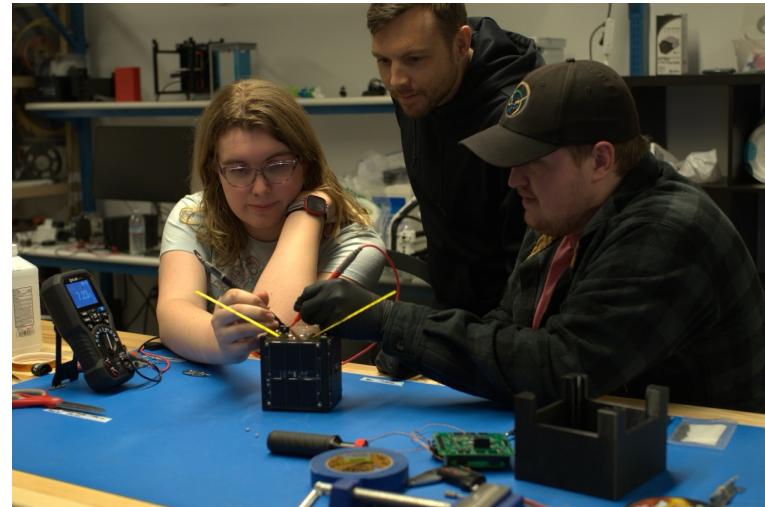
## Key Points

- **Building Skill:** Especially among new and academic programs building institutional knowledge is essential.
- **Treat it Like an Instrument:** Just as it takes multiple sessions in order to begin to build an intuition on how to place a musical instrument, it will also take multiple sessions to build an intuition for satellites.

### Key Lessons Learned

- Every time we do another integration of an engineering unit we get faster.
- As the engineers get experience building few mistakes are made and more design flaws are weeded out.
- Currently a PROVES Kit can be built in 4 hours.

## Practice Makes Perfect



# Route Optimization

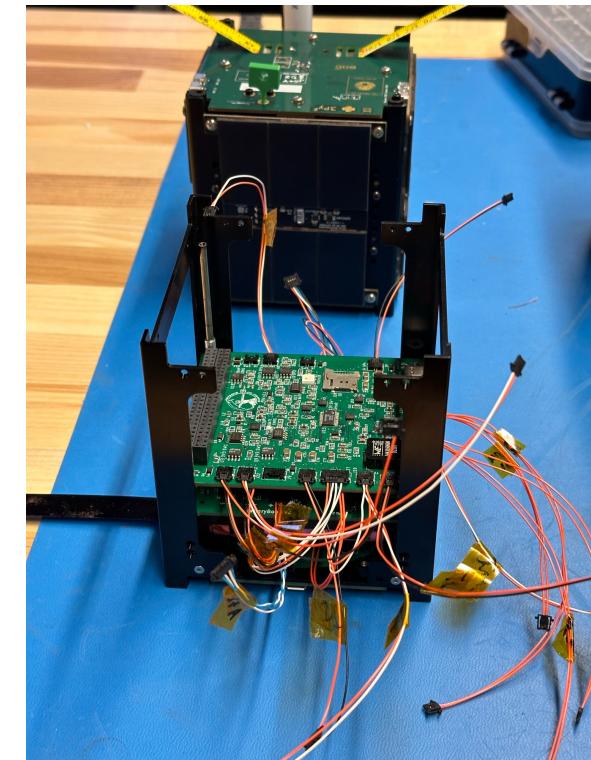
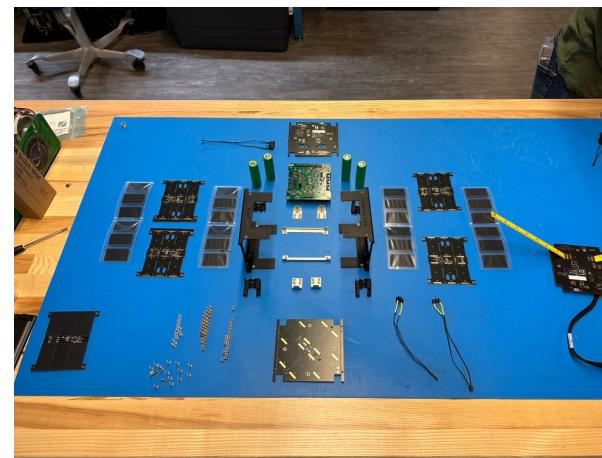
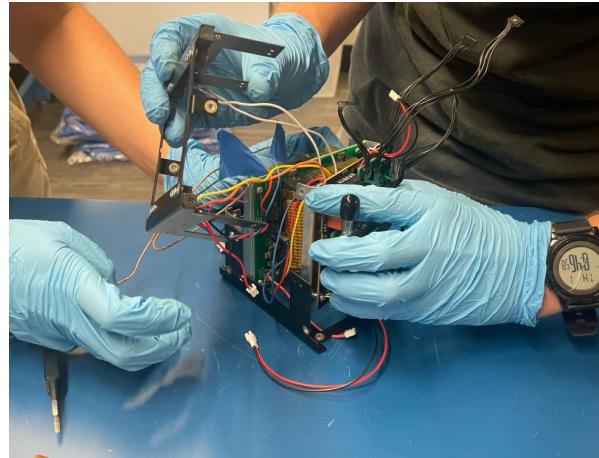
## Key Points

- **Discovering More Efficient Means:** Exploration must be done to find better ways to do things.
- **Engaging with the Community:** Learn from other architectures and what they do to succeed.
- **Avoiding the Critical Path:** Any operations that can stall the entire process should be avoided.
- **Parallelization:** Do as much in parallel as possible.

### Key Lessons Learned

- Selecting a good path is essential to maintaining a high project velocity.
- Velocity is important to minimize mistakes and maintain schedule.
- If major operations can fit inside one working day and one working shift the number of potential mistakes decreases significantly.

## Eliminating Complexity



# The Pleiades Five

- Five unique universities joining Cal Poly Pomona in building and launching a cluster of six 1U CubeSats.
- Looking to study the dynamics of creating sustainable space programs at the participating universities.
- Implementing lessons learned from past university missions:
  - **Unified Architecture:** All universities flying a PROVES Kit at the core, with custom payloads as they wish.
  - **Joint Operations Plan:** Coordinated operations plan improves ground station availability and helps to streamline the licensing process.
  - **Compact Timeline:** Compacting the student experience to 1 year. Aligns with other popular student engineering experiences and minimizes the chance of program disruption and delay.



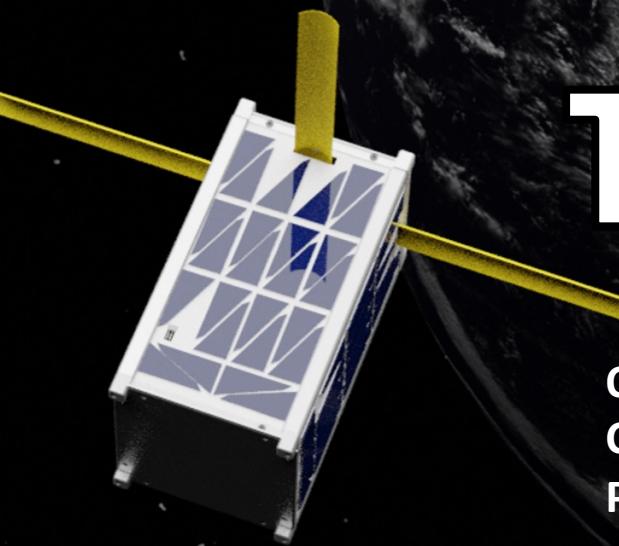
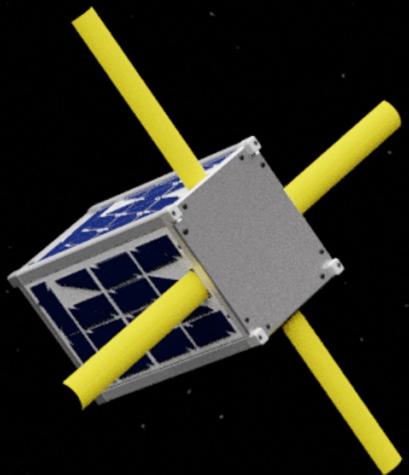
# Recommendations for the CubeSat Community



## Potential Solutions

- Push an understanding of Academic CubeSats as primarily or purely educational tools.
- Discuss cost more openly and drive for CubeSats to become more accessible through significantly lower cost.
- Reduce the timeline of academic CubeSats to align them with other successful student programs.
- Promote and participate in collaborative channels and share data and designs openly.
  - **Support open CubeSat architectures!**
  - Like the 1U PROVES Kit





# Thank You!

Questions?

Contact: [mlpham@cpp.edu](mailto:mlpham@cpp.edu)

PROVES Kit Open Source: [github.com/proveskit](https://github.com/proveskit)