- Use primary (x,y=0 at z=0) tracks as "reference":
    - For them the extrapolation is a expansion in $\frac{q}{p}$ (4th order)
    - Using coefficients that are tabulated as a function of x, y
- Perform a expansion in the deviation from these tracks (δ_{t_x} and δ_{t_y}) for the correction of the coefficients of the $\frac{q}{p}$ expansion