





3D TRAINING



- World Matrix
- **☐** View Matrix
- **☐** Projection Matrix
- **□** WVP Matrix

Concepts

Homogeneous coordinate

Add 1 dimension: w

-> Vertex in homogeneous coordinate:

 $(x, y, z, w) \sim (x/w, y/w, z/w, 1.0)$



Concepts

- Transformation: P -> P'
- Transformation matrix:

$$P' = M \times P$$





Spaces transformation

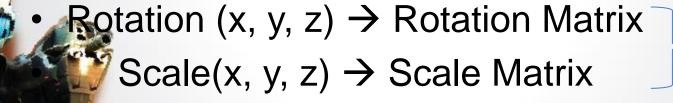
- Local space
 - -> World space
 - -> View space
 - -> Projection space (NDC)

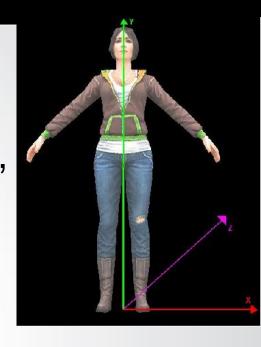


WORLD MATRIX

Local space

- All objects are in the local space, which means they will have the pivot in (0,0,0)
- Position (x, y, z) → Translation
 Matrix





World Matrix



WORLD MATRIX

WorldMatrix = ScaleMatrix *
 RotationMatrix * TranslationMatrix

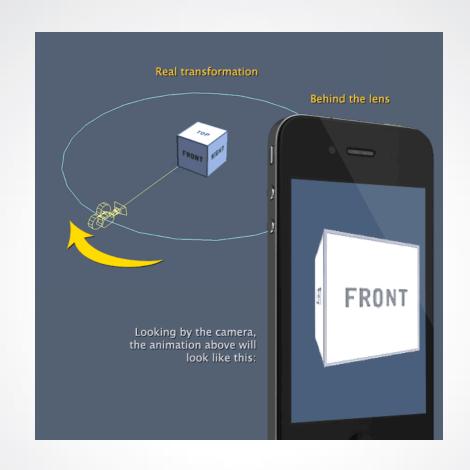
 To bring object from local space to world space: WorldMatrix * Object





VIEW MATRIX

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VIEW MATRIX

- Position $(x, y, z) \rightarrow Translation Matrix$
- Rotation $(x, y, z) \rightarrow Rotation Matrix$

View Matrix

Now is: ViewMatrix * WorldMatrix * Object

Change camera -> need update View Matrix





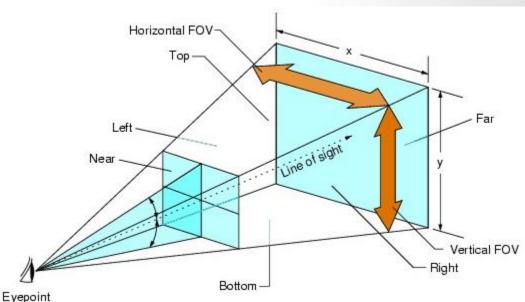
PROJECTION MATRIX

fovy, aspect, near, far

- Ex: FOV $(45, \frac{4}{3}, 1, 10000)$
- \Box Fovy: the camera will open 45 x 2 = 90 degrees
- □ Aspect: All images display with aspect ratio is

SCREEN_WIDTH/SCREEN_HEIGHT of render screen





WVP MATRIX

- ■WVP matrix is World View Projection matrix.
- WVPMatrix = WorldMatrix * ViewMatrix * ProjectionMatrix



Implement WVP matrix to objects

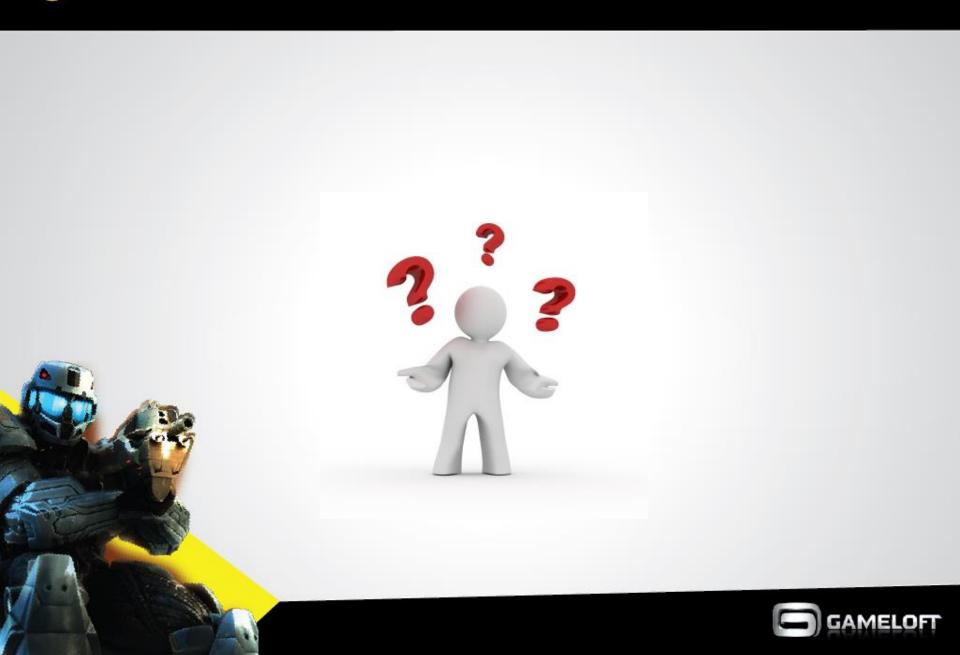
- Press W, S, A, D to move camera
- Pres Left, Right, Up, Down to rotate camera

Hint: Rotate / Translate the View Matrix





QUESTIONS & ANSWERS





Thank you!

