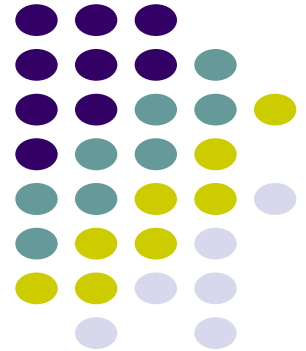


Multi Processes and Scheduling

ECE 469, Feb 15

Aravind Machiry



Recap: Users, Programs, Processes



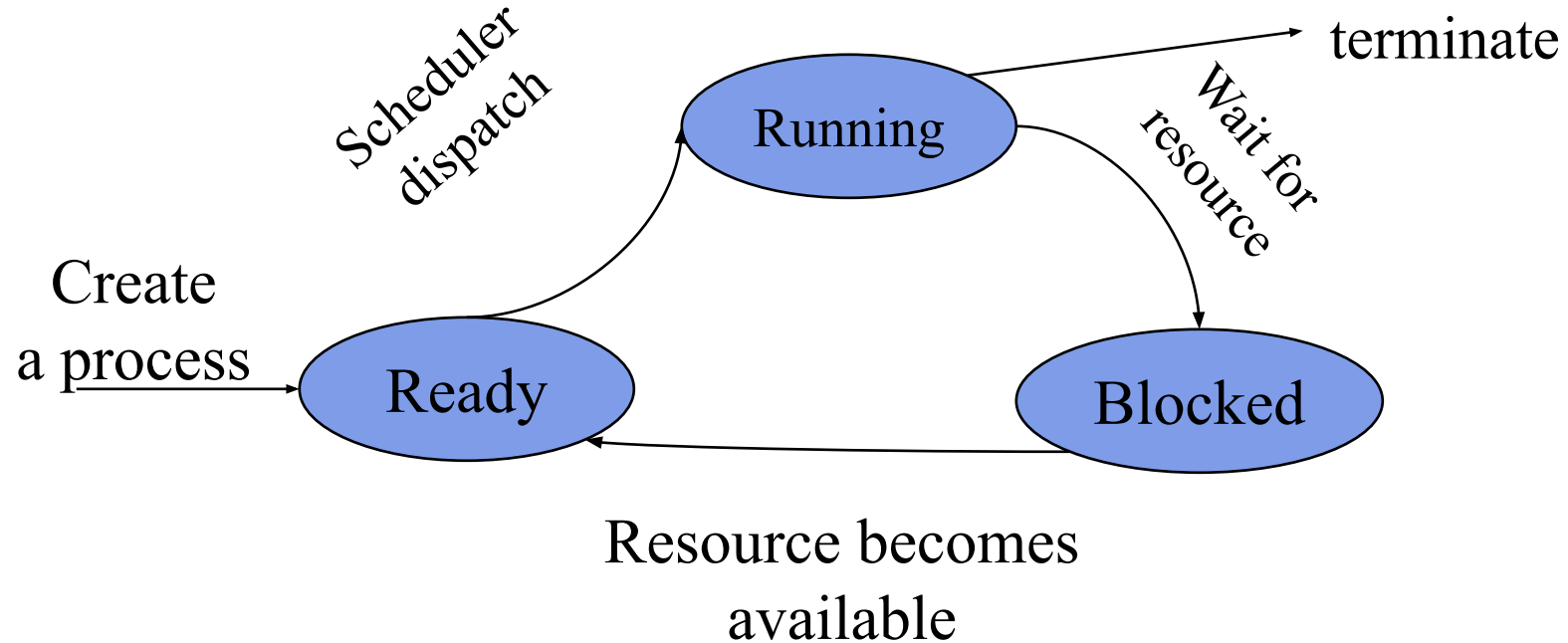
- Users have accounts on the system
- Users launch programs
- There can be multiple programs (i.e., processes), which want to run at the same time

Sequential execution of each process

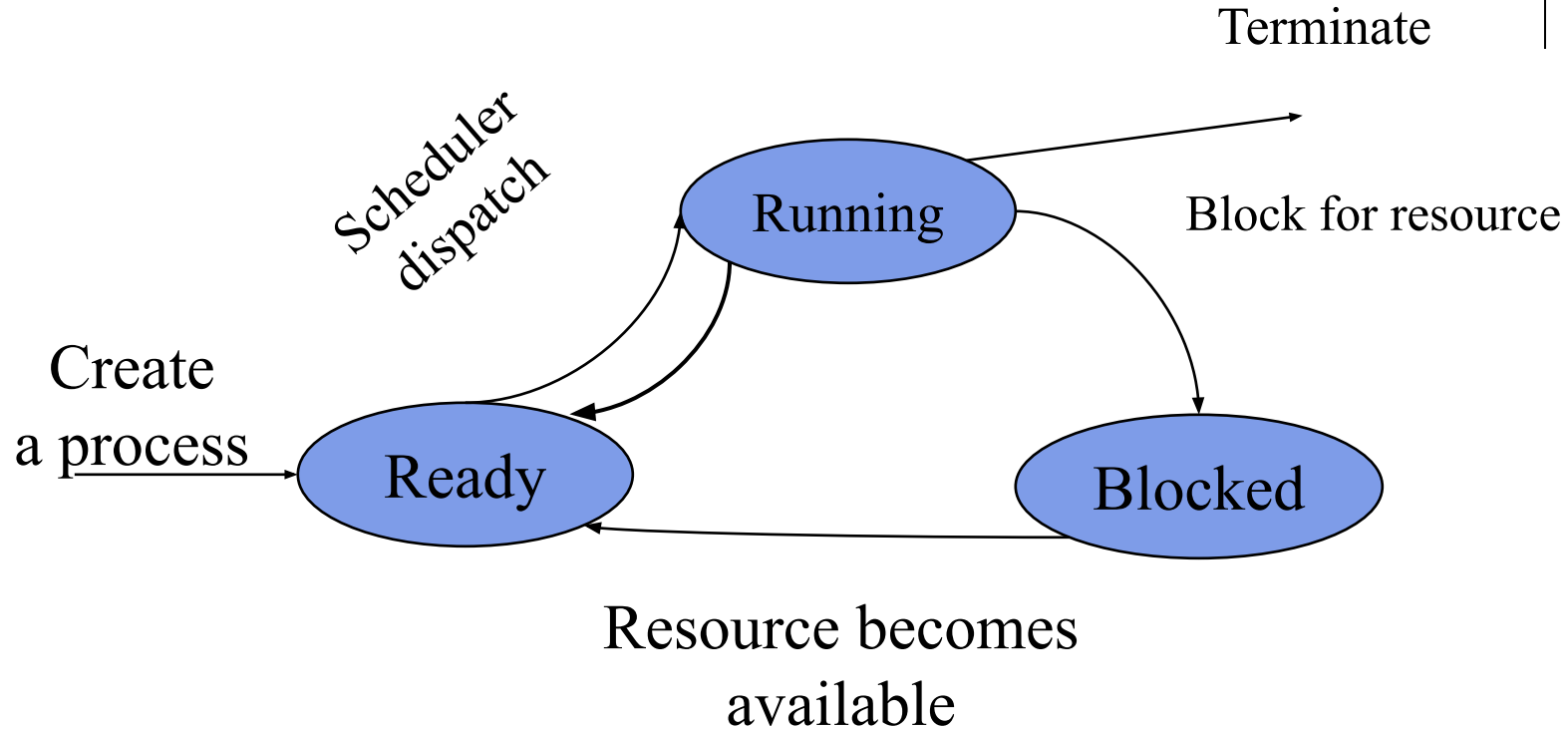


- Assuming single-threaded program
- No concurrency inside a process
- Everything happens sequentially
- Often with interleaved CPU/IO operations

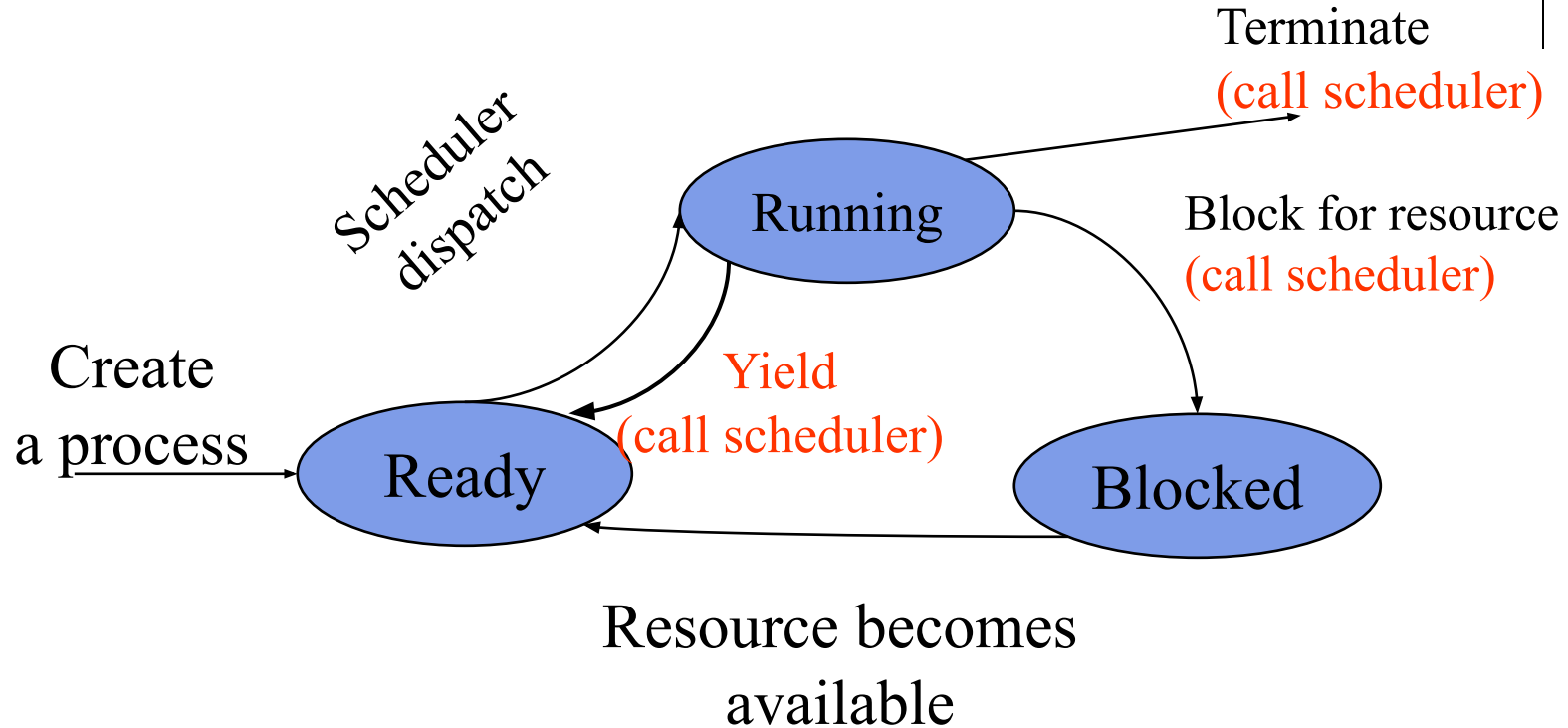
Process Life Cycle



Non-Preemptive Scheduling



Non-Preemptive Scheduling

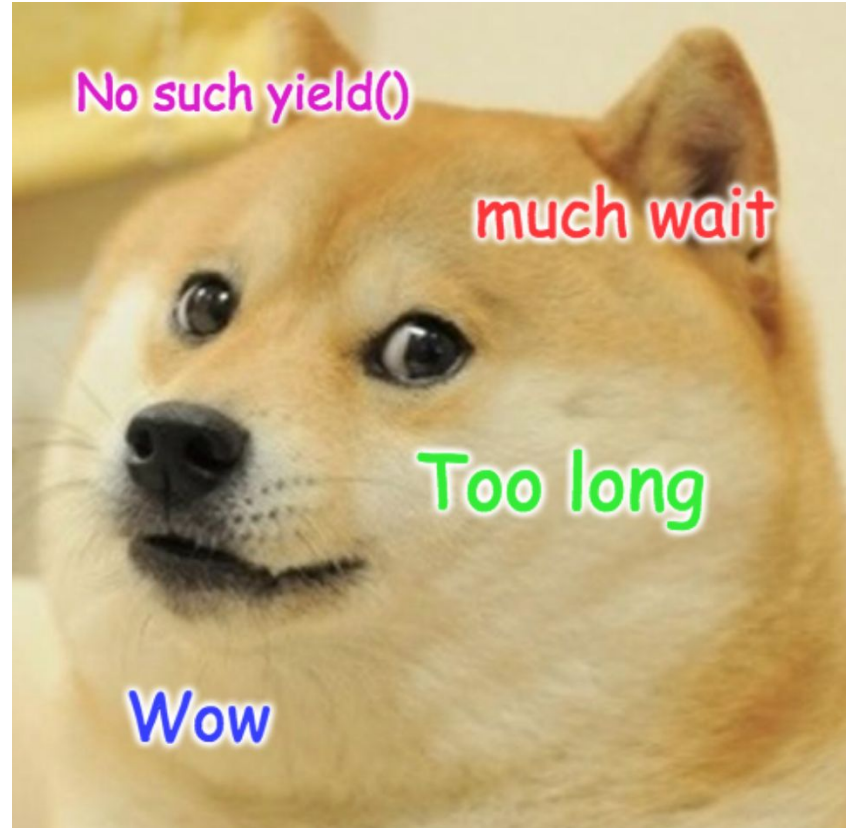


Non-Preemptive Scheduling



- Any issues?
- What if a process runs:

```
int main() {  
    while(1);  
}
```



Concurrent Processes



- Processes in a system can execute concurrently (multitasking)
- Motivations for allowing concurrent execution
 - Physical resource sharing (system utilization)
 - Computational speedup – with several CPUs
 - Modularity (chrome)
 - Convenience (desktop: chrome, google drive, clock, weather)
- Logical resource sharing (eg password files)

Time Sharing Systems



- Timesharing systems support interactive use:
 - each user feels he/she has the entire machine
- How?
 - optimize response time
 - based on time-slicing

Preemptive Scheduling



- Basic idea
 - before moving process to running, OS sets timer
 - if process yields/blocks, clear timer, go to scheduler
 - If timer expires, go to scheduler

Preemptive Scheduling



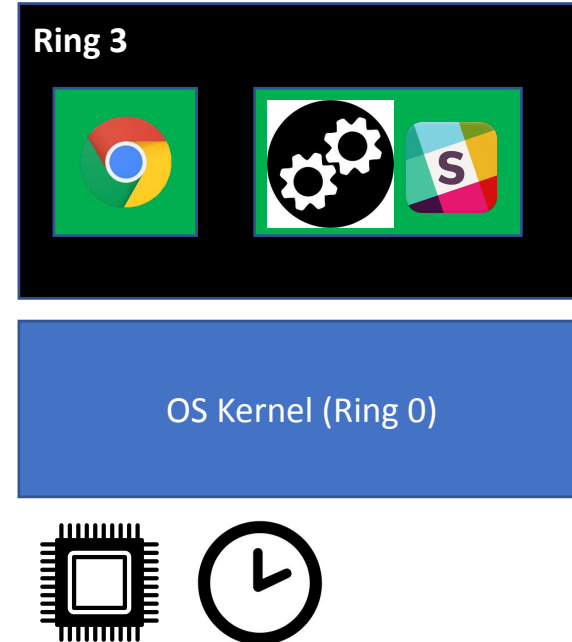
- How does the OS know that the timer expired?

```
int main() {  
    while(1);  
}
```

Preemptive Scheduling



- Preemptive Multitasking (Lab 4)
- CPU generates an interrupt to force execution at kernel after some time quantum
 - E.g., 1000Hz, on each 1ms..

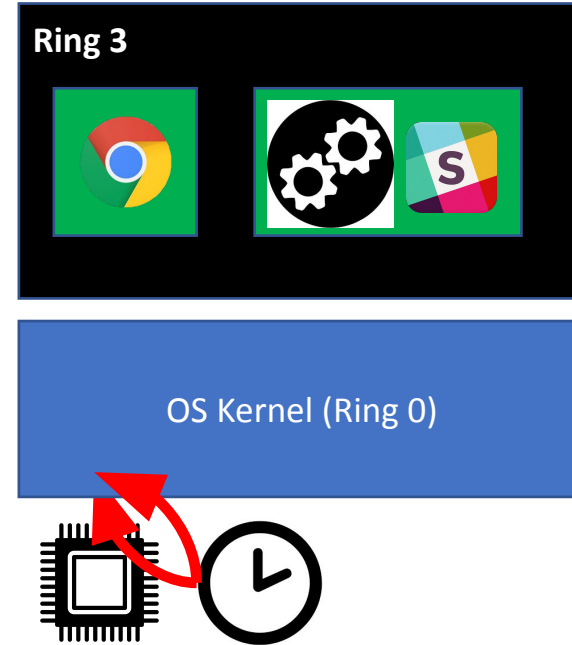


Preemptive Scheduling



- Preemptive Multitasking (Lab 4)
- CPU generates an interrupt to force execution at kernel after some time quantum
 - E.g., 1000Hz, on each 1ms..

After
1ms

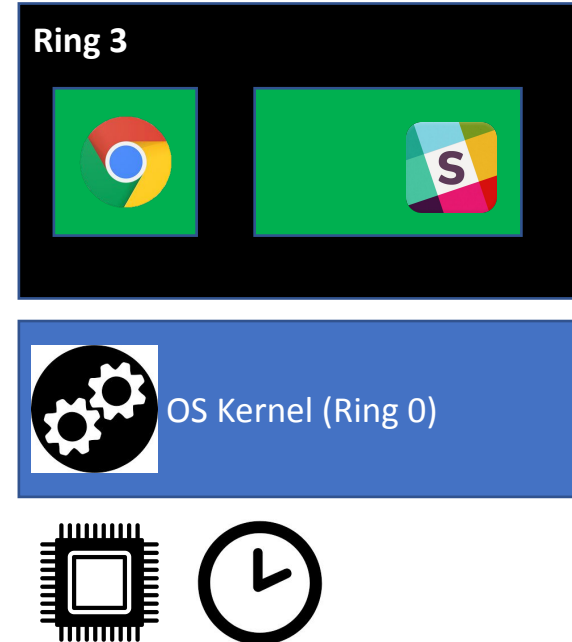


Timer interrupt!

Preemptive Scheduling



- Preemptive Multitasking (Lab 4)
- CPU generates an interrupt to force execution at kernel after some time quantum
 - E.g., 1000Hz, on each 1ms..
- Guaranteed execution in kernel
 - Let kernel mediate resource contention



Preemptive Scheduling



- Preemptive Multitasking (Lab 4)
- CPU generates an interrupt to force execution at kernel after some time quantum
 - E.g., 1000Hz, on each 1ms..
- Guaranteed execution in kernel
 - Let kernel mediate resource contention



Context Switch



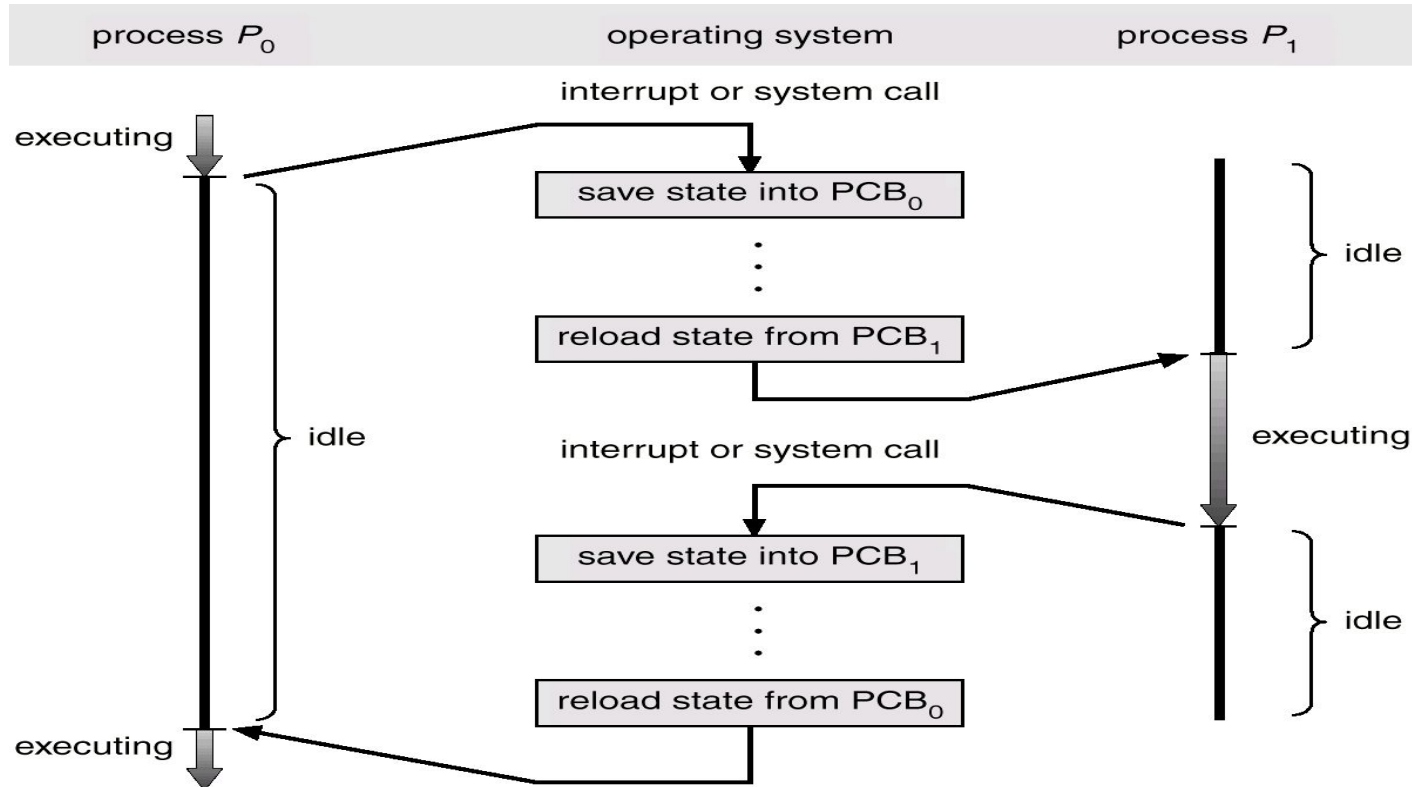
- **Definition:** Switching the CPU to another process, which involves saving the state of the old process and loading the state of the new process
- **What state?**
- **Where to store them?**

Process State: Process Control Block (PCB)

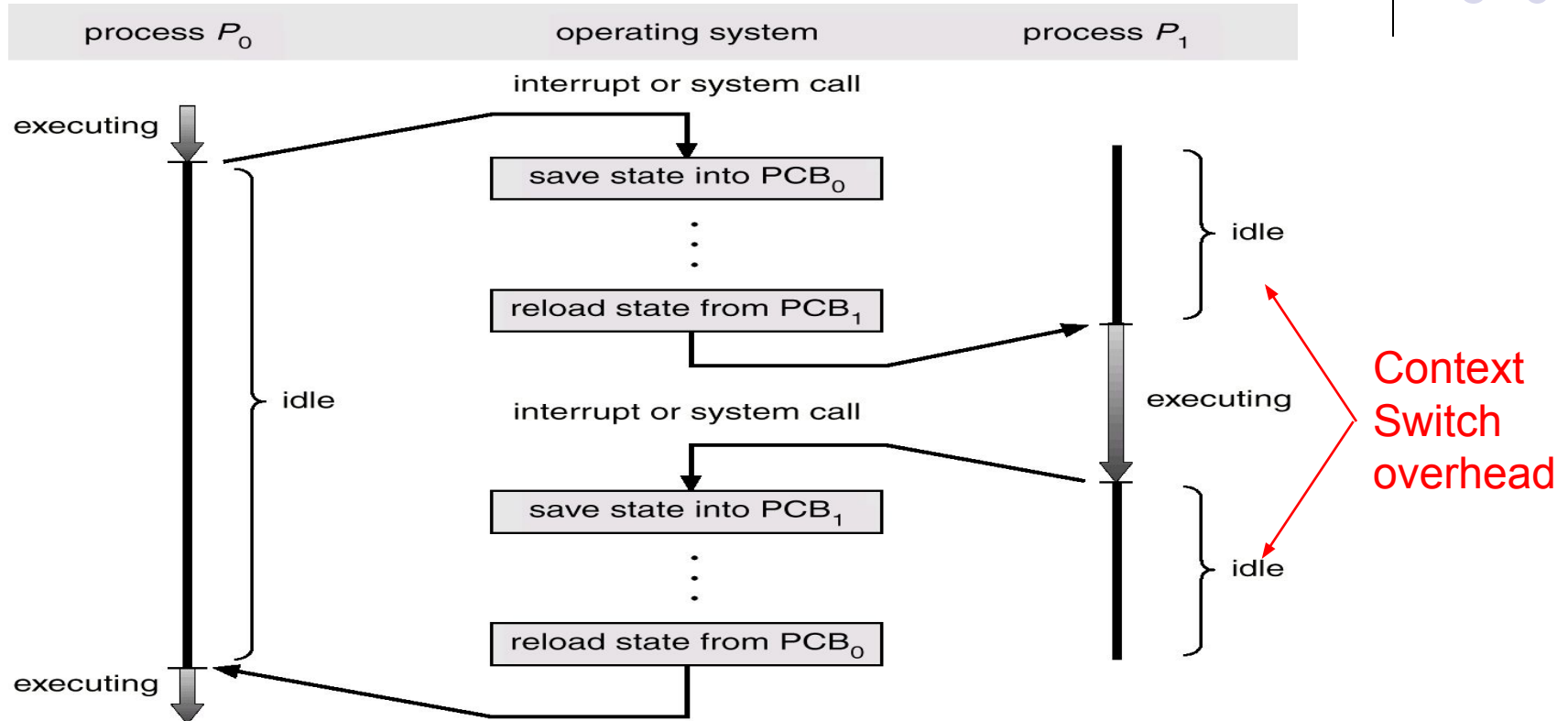


- A.K.A User Environment (JOS)
- Process management info
 - State (ready, running, blocked)
 - PC & Registers, parents, etc
 - CPU scheduling info (priorities, etc.)
- Memory management info
 - Segments, page table, stats, etc
- I/O and file management
 - Communication ports, directories, file descriptors, etc

Context Switch



Context Switch



Preemptive Scheduling Considerations



- Timer granularity
 - **Finer timers = more responsive, high overhead**
 - **Coarser timers = less responsive, more efficient**
- CPU Accounting (CPU running stats)
 - Used by the scheduler
 - Useful for the programmer

Preemptive Scheduling Considerations



- Mechanism + policy
- Mechanisms fairly simple:
 - Save state into a PCB and Restore state from another PCB

Preemptive Scheduling Considerations



- Mechanism + policy
- Mechanisms fairly simple:
 - Save state into a PCB and Restore state from another PCB
- Policy choices harder:
 - When should we switch?

Challenges in Policy



- Flexibility - variability in job types
 - Long vs. short
 - Interactive vs. non-interactive
 - I/O-bound vs. compute-bound
- Issues
 - Short jobs shouldn't suffer
 - (Interactive) Users shouldn't be annoyed

Challenges in Policy (2)



- Fairness
 - All users should get access to CPU
 - Amount of CPU should be roughly even?
- Issue
 - Short-term vs. long-term fairness

Goals



- Goals (Performance metrics)
 - Minimize turnaround time
 - avg time to complete a job
 - $T_{\text{turnaround}} = T_{\text{completion}} - T_{\text{arrival}}$
 - Maximize throughput
 - operations (jobs) per second
 - Minimize overhead of context switches: large quanta
 - Efficient utilization (CPU, memory, disk etc)
 - Short response time
 - $T_{\text{response}} = T_{\text{firstrun}} - T_{\text{arrival}}$
 - type on a keyboard
 - Small quanta
 - Fairness
 - fair, no starvation, no deadlock

Goals

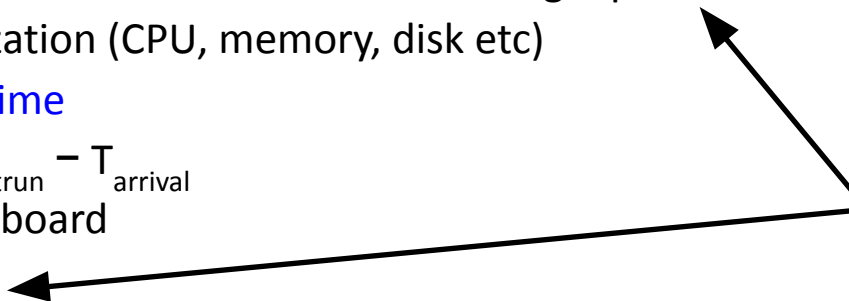


- Goals often conflict
 - Response time vs. throughput
 - fairness vs. avg turnaround time?

Goals and Assumptions



- Goals (Performance metrics)
 - Minimize turnaround time
 - avg time to complete a job
 - $T_{\text{turnaround}} = T_{\text{completion}} - T_{\text{arrival}}$
 - Maximize throughput
 - operations (jobs) per second
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Scheduling Policies



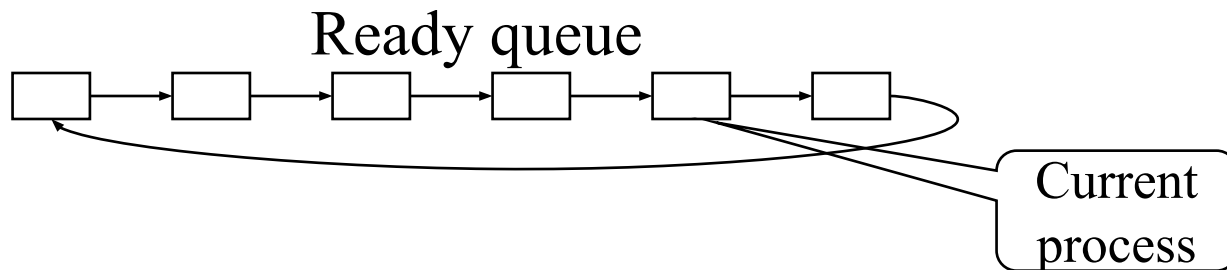
- Is there an optimal scheduling policy?
 - Even if we narrow down to one goal?
- But we don't know about future
 - Offline vs. online

Scheduling Policies

- Round Robin
- SJCF
- SRTCF



Round Robin



- Each runs a time slice or quantum: Fair
- How do you choose time slice?
 - Overhead vs. response time
 - Overhead is typically about 1% or less
 - Quantum typically between 10 ~ 100 millisec

Is Fairness always good?



- Assume 10 jobs waiting to be scheduled, each takes 100 seconds
 - Assume no other overhead
 - Total CPU time? 1000 seconds, always
- Implications?
 - Last job always finishes at 1000 seconds
 - So what's the point of scheduling?

Non-Preemptive Scheduling



- Job 1 – start 0, end 100
 - Job 2 – start 100, end 200
 - ...
 - Job 10 – start 900, end 1000
-
- Average turnaround time = $100 + 200 + \dots / 10 = 550$ sec

Round Robin



- Assume each quantum is 1 second
- Job 0 – 0, 10, 20, 30, 40,..., 990
- Job 1 – 1, 11, 21, 31,..., 991
- Job 2 – 2, 12, 22, 32,..., 992
- ...
- Avg turnaround time = $990 + 991 + \dots / 10 = 995$ sec

Is Fairness always good?



- Unfair policy was faster!
- Job 10 always ended at the same time
- Round-Robin just hurt jobs 1-9 with no gain

Why use Round Robin?



- Imagine 10 jobs
 - Jobs 1-9 are 100 seconds
 - Job 10 is 10 seconds
- Which policy is better now?

Non-preemptive scheduling

- Jobs 1-9 are 100 seconds
- Job 10 is 10 seconds



Non-preemptive scheduling



- Jobs 1-9 are 100 seconds
 - Job 10 is 10 seconds
-
- Job 0 – start 0, end 100
 - Job 1 – start 100, end 200
 - Job 10 – start 900, end 910
-
- Avg turnaround time = $100+200+\dots+910/N = 541$

Round Robin scheduling



- Jobs 1-9 are 100 seconds
 - Job 10 is 10 seconds
-
- Job 0 – 0, 10, 20, ..., 900
 - Job 1 – 1, 11, 21, ..., 901
 - Job 10 – 9, 19, 29, ..., 99
-
- Avg turnaround time = $900 + 901 + 908 + 99 / 10 = 824$

Round Robin scheduling



- Jobs 1-9 are 100 seconds
- Job 10 is 10 seconds

9% work drop

2% avg turnaround drop for
FIFO

- Job 0 – 0, 10, 20, ..., 900
- Job 1 – 1, 11, 21, ..., 901
- Job 10 – 9, 19, 29, ..., 99

17% avg turnaround drop for
RR

- Avg turnaround time = $900 + 901 + 908 + 99 / 10 = 824$

Why use Round Robin?

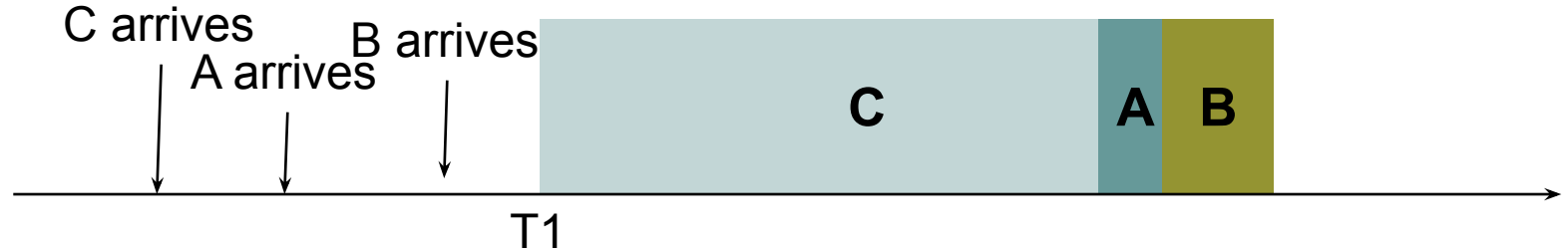


- Imagine 10 jobs
 - Job 1 is 100 seconds
 - Job 2-10 is 10 seconds
- Which policy is better now?
 - FIFO: average turnaround 145
 - RR: average turnaround 105

STCF (SJF) – Shortest Job First



- What shall we do if we care about turn-around time?
 - FIFO can be bad



- STCF/SJF
 - schedule shortest (total completion time) job first



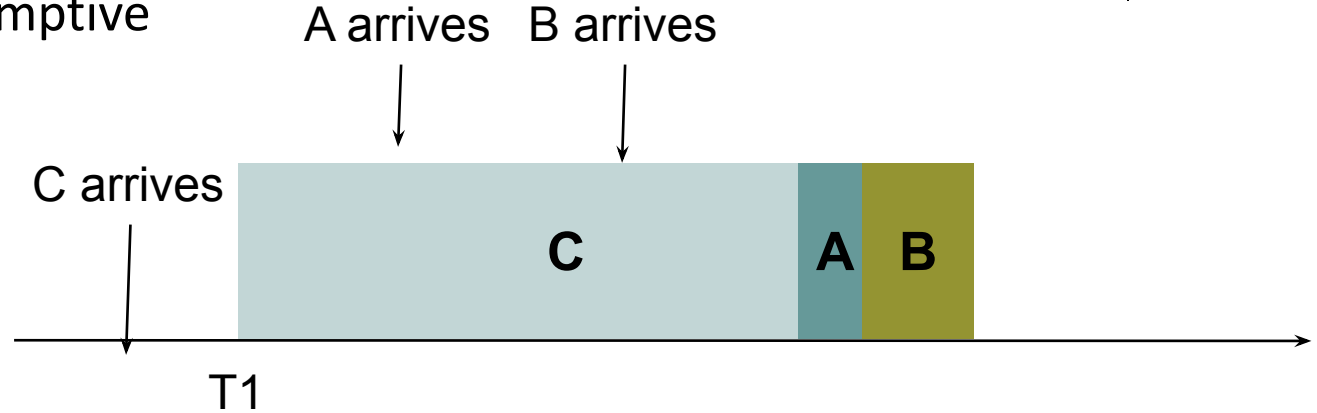
SJF: Pros and Cons



- Can we do better than Shortest Job First in terms of average turnaround time?
 - Assume all jobs arrive at the beginning
- In fact, SJF can be proved to be the optimal scheduling algorithm with the above assumption
 - But we are not going to prove it, since this is not a theory class 😊
- SJF Advantage
 - Minimal average turnaround time
- Disadvantage
 - Difficult to know the future, has to run until finish

STCF

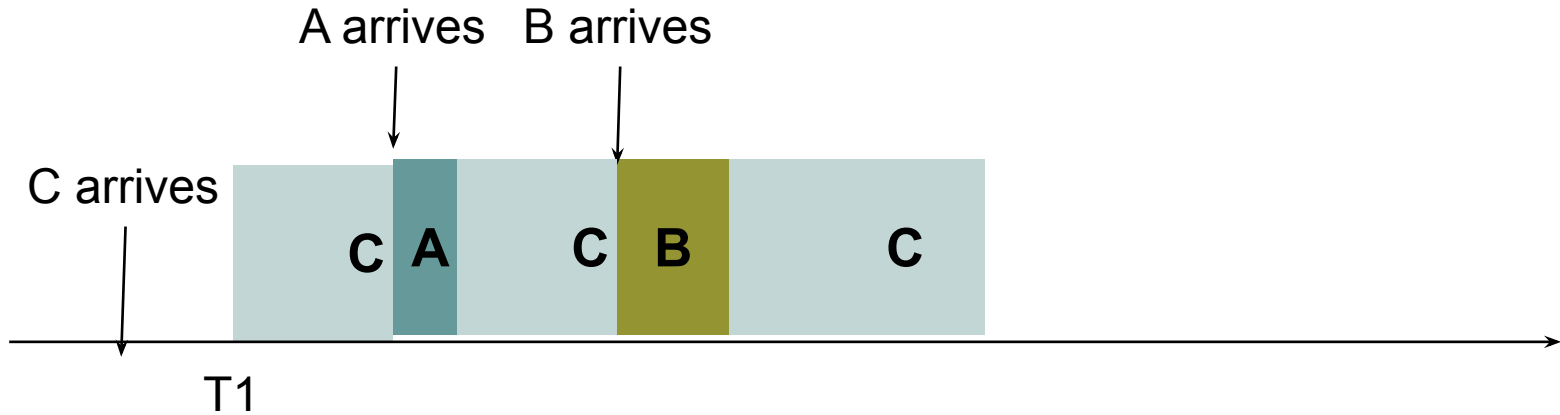
- Shortest time to completion first (shortest job first)
 - Non-preemptive



SRTCF



- Shortest remaining time to completion first
 - Preemptive



Any potential problems?
- Can cause **starvation!**

Policy Decisions



- Need to accommodate interactive jobs
 - Need some kind of RR
- Diversity in jobs – job length, I/O mix
 - RR also appears to help
- SJF also has virtue
 - Reduce avg. turnaround time
- Can we accommodate all?

Scheduling Policies Advantages



FIFO

Response time

RR

Throughput

SJF

Avg. turnaround time

Fairness

Scheduling Policies Advantages



FIFO

Response time

RR

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SJF

Avg. turnaround time

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Scheduling Policies Advantages



FIFO

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Avg. turnaround time

SJF

Fairness

Scheduling Policies Advantages



FIFO

Response time

RR

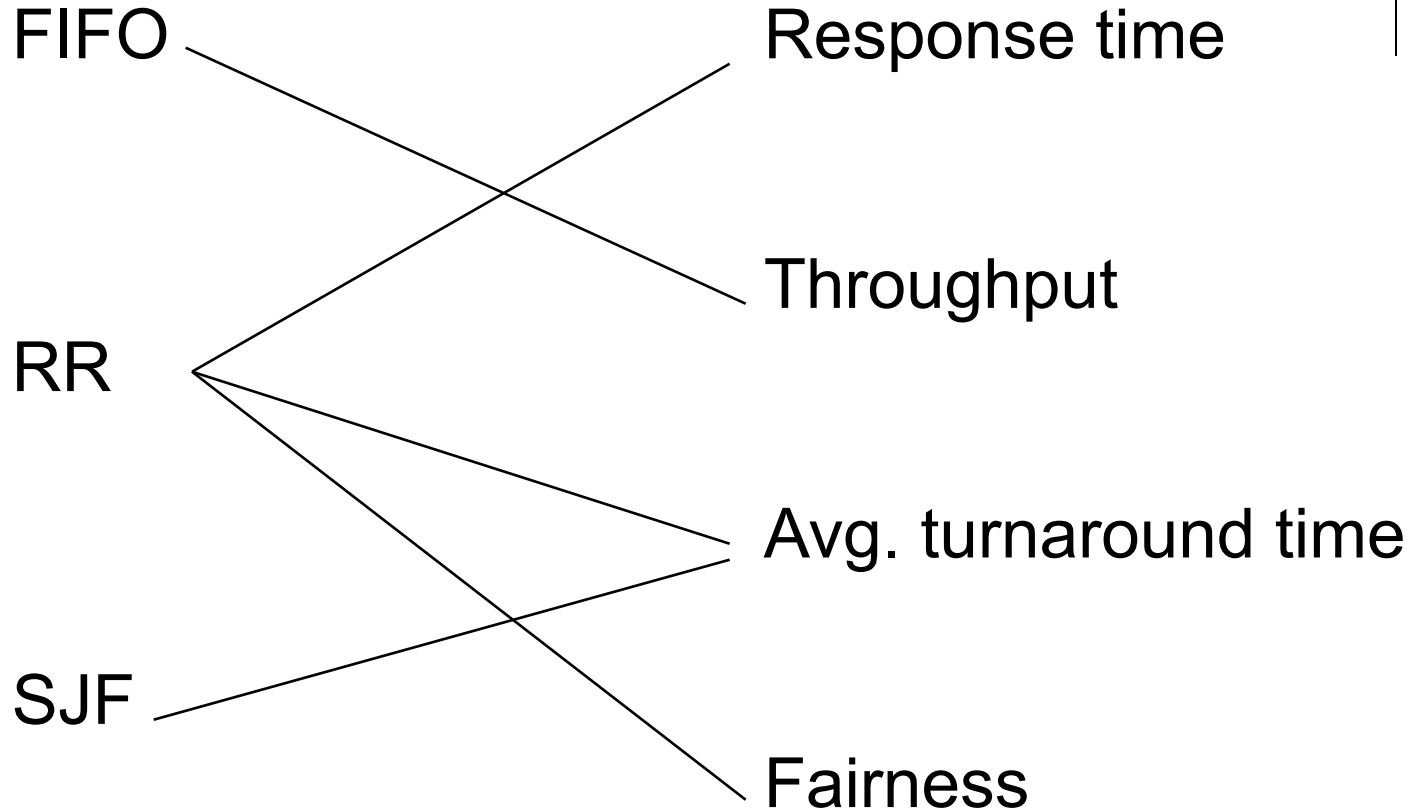
Throughput

SJF

Avg. turnaround time

Fairness

Scheduling Policies Advantages



Scheduling Policy Issues



- Fairness
- Flexibility
- **High utilization (efficiency)**
- Good response time
- Good turnaround time

Scheduling Policy Issues



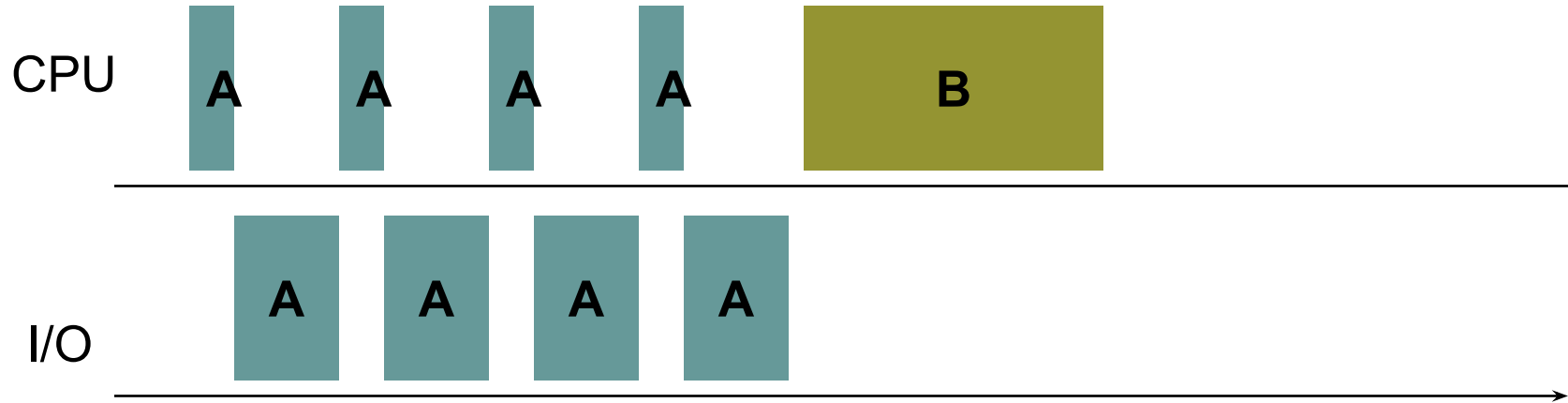
- High utilization (efficiency)
 - Lots of processes (want diff resources)
 - Lots of resources (want full parallelism)
- Issue?
 - How do you get the most useful work out of the system? (job throughput)

Adding I/O into mix



- Resource utilization example
 - A and B each uses 100% CPU
 - C loops forever (1ms CPU and 10ms disk)
 - Time slice 99ms: roughly 30% of disk utilization with Round Robin and roughly 70% of CPU utilization
 - Time slice 1ms: roughly 90% of disk utilization with Round Robin and nearly 100% of CPU utilization
- What do we learn from this example?
 - Small time slice can improve utilization / fairness to I/O jobs

Handling I/Os



Handling I/Os

