

# 3308 Maxwell's Theory of Electrodynamics Notes

Based on the 2011 spring lectures by Prof Y  
Kurylev

OBSOLETE

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# 3308 MAXWELL'S THEORY OF ELECTROMAGNETISM

Prof. Yaroslav Kurylev

KLB204

y.kurylev@math.ucl.ac.uk

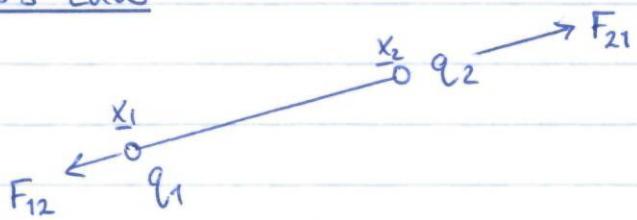
"It's Physics. The name of the course is physics".

Short-ish book: [http://www.phys.ufl.edu/~o7Edorsey/  
phy6346-00/lectures](http://www.phys.ufl.edu/~o7Edorsey/phy6346-00/lectures)



## ELECTROSTATICS

### Coulomb's Law



If we have two charged particles of charges  $q_1, q_2$  at points  $x_1, x_2 \in \mathbb{R}^3$ , then

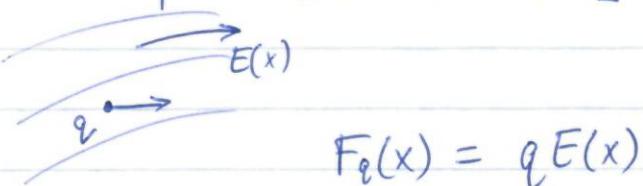
$$F_{12} = F_{1 \leftarrow 2} = k q_1 q_2 \frac{x_{12}}{|x_{12}|^3}$$

*"it will heal you or kill you"*

K is a constant to do with units

How do they exert a force on each other? They used to think there was ether which gave a transfer material to go through. This was later rubbish, of course. Turns out when you place a charged particle, it propagates a magnetic field. Now we're looking for Higgs bosons!

If we have an electric field  $E(x) [E^1, E^2, E^3]$



$$F_q(x) = q E(x)$$

So by looking at Coulomb's law, we can see the field created by  $q_2$  if we place  $q_1$ :

$$F_q(x) = k q q_2 \frac{x - x_2}{|x - x_2|^3}$$

$$\Rightarrow E(x) = k q_2 \frac{x - x_2}{|x - x_2|^3}$$

*sometimes seen as*  $\frac{\widehat{x - x_2}}{|x - x_2|^2}$

*sometimes seen as*  $k = \frac{1}{2\pi\epsilon_0}$

Electric fields add linearly.

if you have electric field  $E$   
and potential  $\Phi$ , (scalar electric potential)  
physicists use

$$E(x) = -\nabla \Phi(x)$$

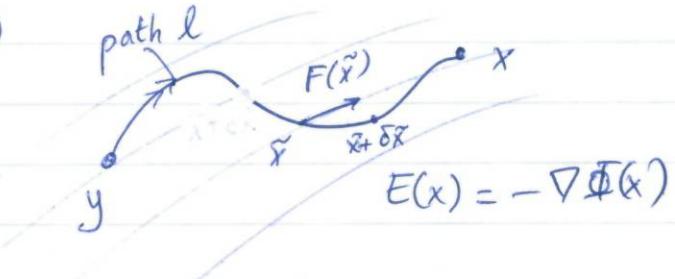
(Note that  $\text{curl } E = 0$  }  $\rightarrow$  it has a potential  $\Phi$  by 1402  
(and domain simply connected) and since domain is simply connected)

Obviously  $\Phi$  is defined up to a constant. So  $\Phi$  has no real physical meaning, but the difference of potentials does, of course.

Say we have  $\Phi(x) - \Phi(y)$

$$F(\tilde{x}) = q E(\tilde{x})$$

Work done getting from  $\tilde{x}$  to  $\tilde{x} + \delta\tilde{x}$ :  $dA = F(\tilde{x}) \cdot d\tilde{x}$



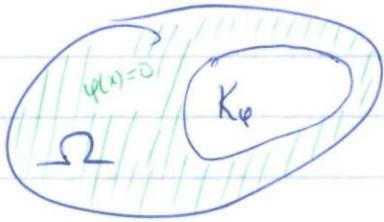
$$\text{Work} = A = \int_l F(\tilde{x}) \cdot d\tilde{x} = q \int_l E(\tilde{x}) \cdot d\tilde{x}$$

$$= q \int_l \nabla \Phi(\tilde{x}) d\tilde{x} = -q [\Phi(x) - \Phi(y)] \\ = q [\Phi(y) - \Phi(x)]$$

The convention is that  $\Phi = 0$  at infinity.

## THEORY OF DISTRIBUTIONS

DuBois - Raymond lemma: Say we have a domain  $\Omega$  and a  $f^n$   $f \in C_c(\Omega)$



Take a  $f^n$   $\varphi \in C_0^\infty(\Omega)$ , i.e.,  
 $\varphi$  can be differentiated arbitrarily many times.

There is a compact region  $K_\varphi \subset \Omega$  s.t.  
 $\varphi(x) = 0$ ,  $x \notin K_\varphi$ .

Lemma 1.1: Let  $f \in C_c(\Omega)$  and for all  $\varphi \in C_0^\infty(\Omega)$ ,

$$\int_{\Omega} f(x)\varphi(x) dx = 0. \quad \text{Then } f \equiv 0.$$

Corollary: If  $f_1, f_2 \in C_c(\Omega)$ ,  $\forall \varphi \in C_0^\infty(\Omega)$ ,

$$\int_{\Omega} f_1(x)\varphi(x) dx = \int_{\Omega} f_2(x)\varphi(x) dx. \quad \text{Then } f_1 = f_2$$

Proof of corollary: Subtract, then use lemma.

↑ This is useful.  $\varphi$  is called "test function" because we can see if  $f_1 = f_2$  by using their integrals. Cool.

$C_0^\infty$  is called the space of test functions, and is often denoted by  $D(\Omega)$ .

Propn 1.2  $K_1 \subset K_2$  i.e.  $K_1 \subset K_2^{\text{int}}$



For any two compacts,

there exists  $\varphi \geq 0$ ,  $\varphi \in C_0^\infty(K_2)$ , i.e.  $\varphi = 0$  outside  $K_2$ .  
 s.t.  $\varphi = 1$  in  $K_1$ .

Proof of Lemma 1.1 Say we have  $x_0 \in \Omega$  s.t.  $f(x_0) > 0$ .

$f \in C(\Omega) \Rightarrow \exists$  a bowl of radius  $\delta$

$B_\delta(x_0)$  s.t.  $f(x) > \frac{1}{2}f(x_0)$

$x \in B_\delta(x_0)$

$$\forall \varepsilon > 0 \exists \delta \text{ s.t. } |f(x) - f(x_0)| < \varepsilon \Rightarrow |x - x_0| < \delta$$

$$\text{Let } \varepsilon = \frac{1}{2}f(x_0)$$

Choose  $\varphi$  from  $C_0^\infty$  s.t. (a)  $\varphi \geq 0$

(b)  $\varphi = 1, x \in B_{\delta/2}(x_0)$  ( $= K_1$ )

(c)  $\varphi = 0, x \notin B_\delta(x_0)$  ( $= K_2$ )

Look at  $\int_{\Omega} f(x)\varphi(x) dx = \int_{B_\delta(x_0)} f(x)\varphi(x) dx$   $\because \varphi \text{ is zero outside this bowl.}$

$\begin{matrix} \nearrow \\ \text{all these terms} \\ \searrow \end{matrix}$

are positive

$$\geq \int_{B_{\delta/2}(x_0)} f(x)\varphi(x) dx \geq \frac{1}{2}f(x_0) \cdot \text{Vol}(B_{\delta/2}(x_0)) > 0$$

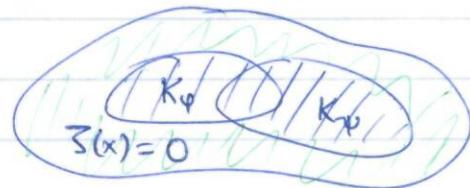
$\rightarrow f$  is zero everywhere.

□

$\mathcal{D}(\Omega)$  is a topological vector space. What does that mean?

- (1) it's a vector space — you can {add vectors  
if we have  $\varphi, \psi \in C_0^\infty(\Omega)$ ,  $\lambda, \mu \in \mathbb{R}$   
then  $\tilde{\varphi}(x) = \lambda\varphi(x) + \mu\psi(x) \in C_0^\infty(\Omega)$ .  
 $\Rightarrow \tilde{\varphi}(x) = 0$  for  $x \notin K_\varphi \cup K_\psi$

DBR lemma



- (2) topological  $\Leftrightarrow$  there is a notion of convergence,  
ie. there is a meaning to  $\varphi_k \xrightarrow{k \rightarrow \infty} \varphi$ .

Two conditions to convergence:

- (a) For any  $n$ -dimensional vector  $\underline{\alpha} = (\alpha_1, \dots, \alpha_n)$ ,  $\underline{\alpha} \in \mathbb{N}_0^n$ ,

$$\mathbb{N}_0^+ = \mathbb{N}_0$$

$$\partial^\alpha \varphi_k(x) \rightarrow \partial^\alpha \varphi(x), \quad x \in \Omega$$

all derivatives  
cvng

$$\frac{\partial^{\alpha_1 + \alpha_2 + \dots + \alpha_n} \varphi_k}{\partial x_1^{\alpha_1} \dots \partial x_n^{\alpha_n}}(x)$$

whatever derivative  
at whatever point  
you choose.  
+ will tend to the  
derivative at that pt

Notation:

$$|\underline{\alpha}| = \alpha_1 + \dots + \alpha_n$$

$$\underline{\alpha}! = \alpha_1! \dots \alpha_n!$$

- (b)  $\exists K \subset \Omega$  s.t.  $\varphi_k(x) = 0 \quad \left. \begin{array}{l} \\ \end{array} \right\} x \notin K$   
 $\varphi(x) = 0 \quad \left. \begin{array}{l} \\ \end{array} \right\} x \in K$

region where  
both satisfy  
DBR.

Defn 1.4  $\varphi_k \rightarrow \varphi$  in  $\mathcal{D}(\Omega)$  if (a) and (b) are satisfied.

Examples of vector space:  $\mathbb{R}^2 = (x, y) = x$  with norm  $\sqrt{x^2 + y^2}$   
 $\|x\|_\infty = \max(|x_1|, |y_1|)$   
 $\|x\|_p = (|x_1|^p + |y_1|^p)^{\frac{1}{p}}$   $p \geq 1$

Def<sup>n</sup>: a  $f^n$   $f: V \rightarrow \mathbb{R}$  mapping onto the reals is a functional

Def<sup>n</sup>: a functional  $f$  is linear if  $f(\lambda v + \mu w) = \lambda f(v) + \mu f(w)$   
for  $v, w \in V$

Def<sup>n</sup>: The space of all linear continuous  $f^n$ 's form a linear vector space called a dual vector space.

$$f, g \in V^* \quad \leftarrow \text{prime means dual space}$$
$$(\lambda f + \mu g)(v) = \lambda f(v) + \mu g(v)$$

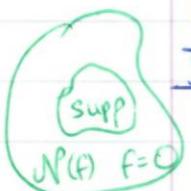
A functional is continuous if when  $x_n \rightarrow x$ ,  $f(x_n) \rightarrow f(x)$ .

What are the  $f^n$ 's in  $\mathbb{R}^2$ ?  $f = (f_1, f_2)$   
 $f(x) = f_1 x + f_2 y$ .

They all have this form; it gives you nothing new.  
The dual space of  $\mathbb{R}^2$  is  $\mathbb{R}^2$  itself.

L2

Recall  $D(\Omega) = C_0^\infty(\Omega)$ .

  
Def<sup>n</sup>:  $N(f) \in C(\Omega)$  is the largest open set where  $f=0$ .

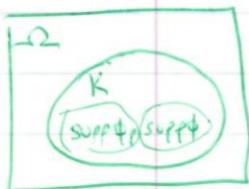
Def<sup>n</sup>: The support  $\text{supp}(f) = \Omega \setminus N(f)$  and it is closed.  
 $\text{supp}(f) = \text{cl} \{x : f(x) \neq 0\}$

Def<sup>n</sup>  
of  
convergence  
(again)

Def<sup>n</sup> 1.4  $\varphi_p \rightarrow \varphi$  in  $D(\Omega)$  iff

(a)  $\partial^\alpha \varphi_p(x) \rightarrow \partial^\alpha \varphi(x)$ ,  $x \in \Omega$ , where  $\alpha$  is any multi-index  
 $\alpha = (\alpha_1, \alpha_2, \dots, \alpha_n)$

(b) there is a compact set  $K \subset \Omega$   
s.t.  $\text{supp}(\varphi_p), \text{supp}(\varphi) \subset K$ .  
↑ and ↑ d. bounded



Problem: if we have sequences  $\varphi_1^p, \varphi_2^p \in \mathcal{D}(\Omega)$ ,  
 $\lambda_1^p, \lambda_2^p \in \mathbb{R}$

and  $\varphi_i^p \xrightarrow{\text{def}} \varphi_i$ ,  $\lambda_i^p \xrightarrow{\text{def}} \lambda_i$   $i=1,2$

$$(1) \quad \lambda_1^p \varphi_1^p + \lambda_2^p \varphi_2^p \xrightarrow{\text{def}} \lambda_1 \varphi_1 + \lambda_2 \varphi_2 \text{ in } \mathcal{D}(\Omega) \quad \dots (1)$$

recall  
topological means  
notion of convergence

Since  $\mathcal{D}(\Omega)$  is a vector space which has the notion  
of convergence which satisfies (1),  $\mathcal{D}(\Omega)$  is a  
topological vector space

If  $V$  is a topological vector space

$V'$  is a dual space, i.e. the space of all linear continuous  
 ↴ the <sup>↑</sup>  
 corresponding functionals on  $V$

Recall a functional is a map  $F: V \rightarrow \mathbb{R}$

Defn  
1.7

it is linear:  $F(\lambda_1 v_1 + \lambda_2 v_2) = \lambda_1 F(v_1) + \lambda_2 F(v_2)$

it has continuity:  $F(v_p) \rightarrow F(v)$  if  $v_p \rightarrow v$ .

These  $F$  form a topological vector space called dual to  $V$ .

If  $F_1, F_2 \in V'$ ,  $\lambda_1, \lambda_2 \in \mathbb{R}$ :

$$(\lambda_1 F_1 + \lambda_2 F_2)(v) = \lambda_1 F_1(v) + \lambda_2 F_2(v)$$

Need to check that this object is linear and continuous.

$$\begin{aligned} (1) \text{ Linearity: } & (\lambda_1 F_1 + \lambda_2 F_2)(\mu_1 v_1 + \mu_2 v_2) \\ &= \lambda_1 F_1(\mu_1 v_1 + \mu_2 v_2) \\ &\quad + \lambda_2 F_2(\mu_1 v_1 + \mu_2 v_2) \end{aligned}$$

each  $F_1, F_2$  are linear  $f^{n \times n} \Rightarrow$

DUAL  
= LINEAR  
CTS  
FNL'S

$$= \lambda_1 (\mu_1 F_1(v_1) + \mu_2 F_1(v_2)) \\ + \lambda_2 (\mu_1 F_2(v_1) + \mu_2 F_2(v_2))$$

$$= \mu_1 [\lambda_1 F_1(v_1) + \lambda_2 F_2(v_1)] \\ + \mu_2 [\lambda_1 F_1(v_2) + \lambda_2 F_2(v_2)]$$

$$= \mu_1 (\lambda_1 F_1 + \lambda_2 F_2)(v_1) \\ + \mu_2 (\lambda_1 F_1 + \lambda_2 F_2)(v_2)$$

(2) Cont. : want  
 $(\lambda_1 F_1 + \lambda_2 F_2)(v_p) \rightarrow (\lambda_1 F_1 + \lambda_2 F_2)(v)$  if  $v_p \rightarrow v$   
 // by defn.

$$\begin{matrix} \lambda_1 F_1(v_p) + \lambda_2 F_2(v_p) \\ \downarrow \qquad \downarrow \\ \lambda_1 F_1(v) + \lambda_2 F_2(v) \end{matrix}$$

$$\lambda_1 F_1(v) + \lambda_2 F_2(v) = (\lambda_1 F_1 + \lambda_2 F_2)(v). \quad \square$$

Say

$$(1) F_1, F_2 \in V', \lambda_1, \lambda_2 \in \mathbb{R}, (\lambda_1 F_1 + \lambda_2 F_2)(v) \\ = \lambda_1 F_1(v) + \lambda_2 F_2(v)$$

$$(2) F_p \rightarrow F \text{ in } V' \text{ if } \forall v \in V, F_p(v) \rightarrow F(v).$$

If  $\begin{cases} \lambda_1^p \rightarrow \lambda_1 \\ \lambda_2^p \rightarrow \lambda_2 \\ F_1^p \rightarrow F_1 \\ F_2^p \rightarrow F_2 \end{cases}$  then  $\lambda_1^p F_1^p + \lambda_2^p F_2^p \rightarrow \lambda_1 F_1 + \lambda_2 F_2$

$\Updownarrow$

$\forall v \in V \quad (\lambda_1^p F_1^p + \lambda_2^p F_2^p)(v) \rightarrow (\lambda_1 F_1 + \lambda_2 F_2)(v)$

H/W  
prove  
this

Def<sup>n</sup> 1.11 : The space of distributions is the topological vector space dual to  $\mathcal{D}(\Omega)$ , i.e. the space of linear continuous fns on  $\mathcal{D}(\Omega)$ .

Prob 1.5 :  $\forall \varphi \in C_0^\infty(\Omega)$ ,  $\forall \beta$  multiindex  
then  $\psi = \partial^\beta \varphi \in C_0^\infty(\Omega)$ .

Proof :  $\xrightarrow[\text{more zero areas after diff!}]{}$   $N(\psi) \supset N(\varphi) \Rightarrow \text{supp}(\partial^\beta \varphi) \subset \text{supp}(\varphi)$ .  
 $N(\partial^\beta \varphi)$

If  $\beta \in C^\infty(\Omega)$ ,  $\forall \varphi \in \mathcal{D}(\Omega)$   $\psi = \beta \varphi \in \mathcal{D}(\Omega)$   
 $\downarrow$   
 $\text{supp}(\psi) \subset \text{supp}(\varphi) \subset \Omega$

end of def<sup>n</sup>s. Now coming onto essential stuff.

If  $f(x) \in C(\Omega)$ , we can look at integrals

$$\int_{\Omega} f(x) \varphi(x) dx \quad \varphi \in \mathcal{D}(\Omega) \quad \begin{matrix} \text{space of test} \\ \text{fns, remember!} \end{matrix}$$

Prop<sup>n</sup>: For any  $f \in C(\Omega)$  (and even  $f \in L^1_{\text{loc}}(\Omega)$ ), the integrals  $\int_{\Omega} f(x) \varphi(x) dx$  form a linear cont. fn in  $\mathcal{D}(\Omega)$ .

Prof: Linearity :  $\int_{\Omega} f(x) [\lambda_1 \varphi_1(x) + \lambda_2 \varphi_2(x)] dx$   
 $= \lambda_1 \int_{\Omega} f(x) \varphi_1(x) dx + \lambda_2 \int_{\Omega} f(x) \varphi_2(x) dx$

cont : let  $\varphi_f \rightarrow \varphi$  in  $\mathcal{D}(\Omega)$ .

Then for any multi-index  $\alpha$ ,  $\partial^\alpha \varphi_p(x) \rightarrow \partial^\alpha \varphi(x)$ ,  $x \in \Omega$ .  
 Take  $\underline{\alpha} = (0, 0, \dots, 0)$ .

Then  $\partial^0 \varphi = \varphi$  by def<sup>n</sup>, so,  $\varphi_p(x) \rightarrow \varphi(x)$   $\forall x \in \Omega$ .

Then  $f(x)\varphi_p(x) \rightarrow f(x)\varphi(x)$   $\forall x \in \Omega$ .

But we can't say  $\int \dots \rightarrow \int \dots$  because  
 this is not true!! Why?

counter example

$$\left\{ \begin{array}{l} \text{Take interval } (0, 1) \\ \varphi_p(x) = \begin{cases} p & \text{on } (0, \frac{1}{p}) \\ 0 & \text{on } [\frac{1}{p}, 1] \end{cases} \\ \forall x \in (0, 1), \varphi_p(x) \rightarrow 0. \\ \int_0^1 \varphi_p(x) dx = 1 \end{array} \right.$$

What extra condition do we need to make the integrals converge?

$$\text{If } \int_{-\Omega} X_p(x) dx \rightarrow \int_{-\Omega} X(x) dx$$

then  $X_p \rightarrow X$  uniformly

$$\forall \varepsilon > 0 \exists p(\varepsilon) \text{ s.t. } p > p(\varepsilon) \quad |X_p(x) - X(x)| < \varepsilon \\ \forall x \in \Omega.$$

There was a part of def<sup>n</sup> of convergence:

that  $\text{supp } \varphi_p$  lie in the same compact.

Reminder: If  $X_p \in C(\Omega)$  and  $X_p(x) \rightarrow X(x)$  at any  $x \in \Omega$ . Then for any compact  $K \subset \Omega$ ,  $X_p \rightarrow X$  uniformly in  $K$ .

By (b) there is compact  $K \subset \Omega$  s.t.

$$\text{supp}(\varphi_p), \text{supp}(\varphi) \subset K,$$

$$\text{i.e. } \varphi_p(x) = \varphi(x) = 0, \quad x \notin K.$$

$$\text{So } \int_{\Omega} f(x) \varphi_p(x) dx = \int_K f(x) \varphi_p(x) dx \rightarrow \int_K f(x) \varphi(x) dx$$

□

by the reminder,  
the integrands converge  
uniformly, so the  
integrals converge.

Summarise: every  $f \in C(\Omega)$  defines a distribution  
in  $\mathcal{D}'(\Omega)$  which we denote  $F_f \in \mathcal{D}'(\Omega)$ .  
(dash means dual)

$$C(\Omega) \subset \mathcal{D}(\Omega)$$

embedding

$$F_f(\varphi) = \int_{\Omega} f(x) \varphi(x) dx$$

This embedding is continuous  
la la la la

Prob 1.12.

We say that  $f_p \rightarrow f$  pointwise if  
 $f_p(x) \rightarrow f(x) \quad \forall x \in \Omega$ .

Then if  $f_p, f \in C(\Omega)$  and  $f_p \rightarrow f$  ptwise  
then

$$F_{f_p} \rightarrow F_f \text{ in } \mathcal{D}'(\Omega).$$

Proof:  $F_{f_p} \rightarrow F_f$  in  $\mathcal{D}'(\Omega)$  means  $\forall \varphi \in \mathcal{D}'(\Omega)$ ,  $F_{f_p}(\varphi) \rightarrow F_f(\varphi)$

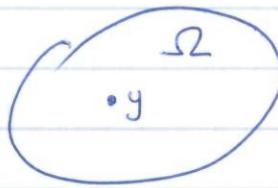
$$\Leftrightarrow \int_{\Omega} f_p(x) \varphi(x) dx \rightarrow \int_{\Omega} f(x) \varphi(x) dx.$$

$$K = \text{supp}(\varphi) \quad \int\limits_K^{\Omega} f_p(x)\varphi(x) dx \quad \int\limits_K^{\Omega} f(x)\varphi(x) dx$$

Since  $f_p \varphi \rightarrow f \varphi$  pointwise and  $f_p \varphi$  and  $f \varphi$  are continuous, then  $f_p \varphi \rightarrow f \varphi$  uniformly in  $K$ .  $\square$

For every  $f$ : there is one distribution.

Example 1.13:



dual space = linear cts fcts on  $\Omega$

Let  $\delta_y \in \mathcal{D}'(\Omega)$  be the following distribution:

$$\delta_y(\varphi) := \varphi(y)$$

linearity: trivial (in printout)

cont'd: if  $\varphi_p \rightarrow \varphi$  in  $\mathcal{D}(\Omega)$ , then for any  $\alpha$ , in particular  $\alpha = (0, \dots, 0)$ , and any  $x \in \Omega$ , in particular  $x=y$ , we have  $\partial^\alpha \varphi_p(x) \rightarrow \partial^\alpha \varphi(x)$ .

For  $\alpha = (0, \dots, 0)$ ,  $x=y$ , we get  $\varphi_p(y) \rightarrow \varphi(y)$ .

$$\delta_y(\varphi_p) \rightarrow \delta_y(\varphi).$$

Prob 1.14 : There are no  $f \in C(\Omega)$  or  $f \in L^1_{\text{loc}}(\Omega)$  s.t.

$$F_f = \delta_y.$$

Ex. 1.15 :  $\Omega = \mathbb{R}^3$ . Consider the plane, say  $x_3=a$ .

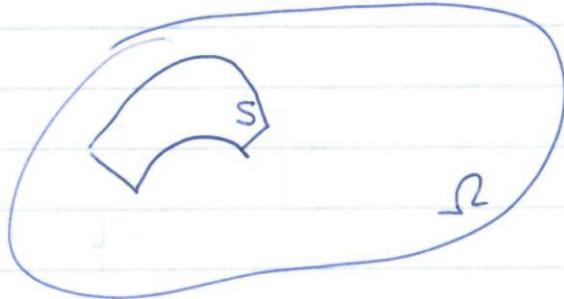
Let  $h(x_1, x_2)$  be a cts fct on  $\mathbb{R}^2$ , with comp  $\in C(\mathbb{R}^2)$

$$F_{a,h}(\varphi) = \int_{\mathbb{R}^2} h(x_1, x_2) \varphi(x_1, x_2, a) dx_1 dx_2$$

$$= \int_{\text{plane } x_3=a} h(x) \varphi|_{\mathbb{R}} dA$$

$\in \text{plane } \mathbb{R}^3$

plane  $x_3=a$

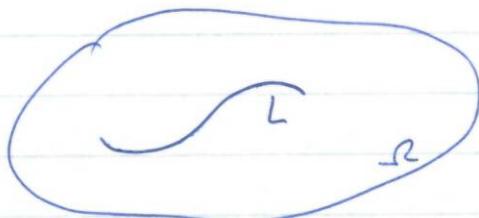


surface  
 $\curvearrowleft$   
 $S \subset \Omega$

$h$  cts on  $S$ .

$$F_{h,S}(\varphi) = \int_S h \varphi|_S dA$$

↑ surface integral from 1402.



$L$  line in  $\Omega \subset \mathbb{R}^2 \text{ or } \mathbb{R}^3$

$h$  cts on  $L$

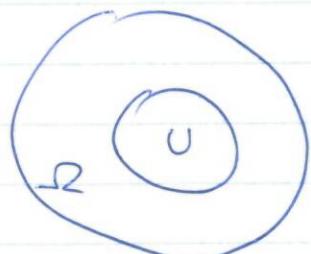
$$F_{h,L}(\varphi) = \int_L h \varphi|_L dl$$

↑ length element.

## 1.2 SUPPORT OF A DISTRIBUTION

If  $f \in C(\Omega)$  then  $N(f)$  is the largest open set where  $f \equiv 0$ .  
(by def!)

Say we have open  $U \subset \Omega$ . Is it possible to check that  $f \equiv 0$  in  $U$  without evaluating  $f(x)$  pointwise?



$$\int_{\Omega} f(x) \varphi(x) dx = 0 \text{ if } \text{supp}(\varphi) \subset U$$

By DuBois-Raymond, also  $f|_U = 0$  if  $\int_U f(x) \varphi(x) dx = 0$   
 for  $\forall \varphi \in C_0^\infty(U)$ .



$$C_0^\infty(U) = \{\varphi \in C_0^\infty(\Omega) : \text{supp}(\varphi) \subset U\}$$

Thus  $f|_U = 0$  if  $\int_{\Omega} f(x) \varphi(x) dx = 0 \quad \forall \varphi \in \mathcal{D}(\Omega),$   
 $\text{supp}(\varphi) \subset U$ .

$$f|_U = 0 \Leftrightarrow F_f(\varphi) = 0 \text{ if } \text{supp}(\varphi) \subset U.$$

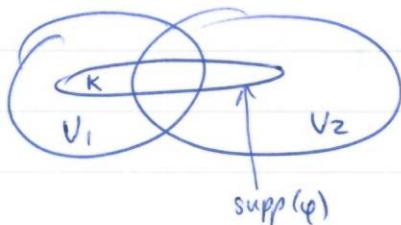
Defn: We say  $F|_U = 0$ , where  $F \in \mathcal{D}'(\Omega)$   
 if  $F(\varphi) = 0$  for  $\varphi \in \mathcal{D}(\Omega), \text{supp}(\varphi) \subset U$ .

Defn: If  $F \in \mathcal{D}'(\Omega)$  then  $N(F)$  is the largest open set in  $\Omega$  where  $F = 0$ .

$$\boxed{F=0 \Leftrightarrow F(\varphi)=0 \quad \forall \varphi \in \mathcal{D}(\Omega), \text{supp}(\varphi) \subset U}$$

If we have  $F(\varphi)=0$  if  $\text{supp}(\varphi) \subset U_1$   
 $F(\varphi)=0$  if  $\text{supp}(\varphi) \subset U_2$   
 $\Downarrow$   
 $F(\varphi)=0$  if  $\text{supp}(\varphi) \subset U_1 \cup U_2$  (not trivial but TRUE).

Why? Suppose we have  $X \in C^\infty$   
 s.t.  $0 \leq X \leq 1, X=1 \text{ in } K_1$   
 $X=0 \text{ in } K_2$ .



we can write  $\varphi = \varphi_1 + \varphi_2$   $\text{supp}(\varphi_1) \subset U_1$   
 $\text{supp}(\varphi_2) \subset U_2$

$$F(\varphi) = F(\varphi_1) + F(\varphi_2)$$

$\overset{\text{def}}{=} \quad \overset{\text{def}}{=}$

Not a proof but  
a feeling.

def? continued...

$$\text{supp}(F) = \Omega \setminus N(F)$$

Example 1.18  $\text{supp}(\delta_y) = \{y\}$ . Recall  $\delta_y(\varphi) = \varphi(y)$

$$\Omega \setminus \{y\} \subset N(\delta_y).$$

We need to show that if  $\text{supp}(\varphi) \subset \Omega \setminus \{y\} \Rightarrow \delta_y(\varphi) = 0$

$$\delta_y(\varphi) = 0$$

$$\text{and } \text{supp}(\varphi) \cap \{y\} = \emptyset \Rightarrow \varphi(y) = 0.$$

Assume that  $y \in N(\delta_y)$ . Then  $N(\delta_y) = \Omega$

$$\delta_y(\varphi) = 0 \quad \forall \varphi \in \mathcal{D}(\Omega)$$

However, by Prop 1.2 there exist

$$\varphi \in C_0^\infty(\Omega) \text{ s.t. } \varphi(y) = 1.$$

But then  $\delta_y(\varphi) = \varphi(y) = 1 \quad \#$

$\Rightarrow y \notin N(\delta_y)$ .  $\square$

Def<sup>n</sup>:  $F \in \mathcal{E}'(\Omega)$  [distributions with compact support]  
 if  $\text{supp}(F) = \Omega \setminus N(F)$  is compact in  $\Omega$ .

Then we can define  $F(\psi)$ ,  $\forall \psi \in C_c^\infty(\Omega) = \mathcal{E}(\Omega)$   
 $\psi_n \rightarrow \psi$  in  $C_c^\infty(\Omega)$  if  $\forall \alpha$ ,  $\forall x \in \Omega$ ,  $\partial^\alpha \psi_n(x) \rightarrow \partial^\alpha \psi(x)$

By Prop 1.2,  $\exists \chi \in C_0^\infty(\Omega) = \mathcal{D}(\Omega)$  s.t.  $\chi = 1$  on  $K$

By def<sup>n</sup>,  $F(\psi) := F(\overset{\in \mathcal{D}(\Omega)}{\chi \psi})$ . [Pick some  $\chi$  with this property]

Note that if  $\hat{\chi} \in C_0^\infty$  and  $\hat{\chi} = 1$  on  $K$ , then  $F(\hat{\chi}\psi) = F(\chi\psi)$

Showing true for any  $\chi$  (indeed  $F(\chi) - F(\hat{\chi}) = F((\chi - \hat{\chi})\psi)$ ).  
 but  $\chi(x) = \hat{\chi}(x) = 1$  on  $x \in \text{supp}(F) \cap \text{supp}(\hat{\chi})$   
 $\Rightarrow \text{supp}(\chi - \hat{\chi}) \cap \text{supp } F = \emptyset$  by def<sup>n</sup> of  $\text{supp } F$   
 $\Rightarrow F((\chi - \hat{\chi})\psi) = 0$

## Differentiation of Distributions

Take  $f \in C_c^\infty(\Omega)$ , then  $\forall \beta$ ,  $\partial^\beta f = \frac{\partial^\beta f}{\partial x_1^{\beta_1} \dots \partial x_n^{\beta_n}} := g$ .

Obviously  $g \in C_c^\infty(\Omega)$  as well.

$$\text{So } F_g(\psi) = \int_{\Omega} g(x) \psi(x) dx.$$

$$\begin{aligned}
 &= \int_{\Omega} \partial^\beta f(x) \psi(x) dx = \int_{\Omega} f(x) \underbrace{\partial^\beta \psi}_{\in \mathcal{D}(\Omega)}(x) dx \quad (\text{no int. } f, \psi = 0 \text{ at boundaries which is where first term goes}) \\
 &\text{int. by parts} \quad = (-1)^{|\beta|} \int_{\Omega} f \underbrace{\partial^\beta \psi}_{\in \mathcal{D}(\Omega)}(x) dx
 \end{aligned}$$

$$= (-1)^{|\beta|} F_f(\partial^\beta \varphi)$$

$$\Rightarrow F_{\partial^\beta f}(\varphi) = (-1)^{|\beta|} F_f(\partial^\beta \varphi)$$

Def'n 1.21 Let  $F \in \mathcal{D}'$ ,  $\beta$  multiindex.

Then  $\partial^\beta F \in \mathcal{D}'$  is the distribution of the form

$$\partial^\beta F(\varphi) = (-1)^{|\beta|} F(\partial^\beta \varphi).$$

Example:  $H(x) = \begin{cases} 1 & x > 0 \\ 0 & x < 0 \\ \text{gazillion} & x = 0 \end{cases}$



val. at 0 plays no role when integrate!

What is  $H'$ ?

$$H'(\varphi) = (-1) H(\varphi') = - \int_0^\infty \varphi'(x) dx = \varphi(0).$$

$(\varphi(\infty) = 0 \text{ because of compact!!})$   
 $= \delta(\varphi)$

$$\Rightarrow H' = \delta.$$

Check that  $\partial^\beta F(\varphi) \in \mathcal{D}(\mathbb{R})$ , i.e. it's cts and linear.

(i) Linearity:  $\partial^\beta F(\lambda \varphi + \mu \psi) = (-1)^{|\beta|} F[\partial^\beta (\lambda \varphi + \mu \psi)]$

$$\lambda \partial^\beta \varphi + \mu \partial^\beta \psi$$

$$= (-1)^{|\beta|} [\lambda F(\partial^\beta \varphi) + \mu F(\partial^\beta \psi)] \quad \because F \in \mathcal{D}'$$

$$= \lambda \partial^\beta F(\varphi) + \mu \partial^\beta F(\psi).$$

(ii) Cont: Let  $\varphi_n \rightarrow \varphi$  in  $\mathcal{D}(\Omega)$ .

We need  $\partial^\beta F(\varphi_n) \rightarrow \partial^\beta F(\varphi)$ .

$$\text{i.e. } (-1)^{|\beta|} F(\partial^\beta \varphi_n) \rightarrow (-1)^{|\beta|} F(\partial^\beta \varphi).$$

By Prob 1.5(i), we know that  $\partial^\beta \varphi_n \rightarrow \partial^\beta \varphi$  in  $\mathcal{D}'(\Omega)$

$$\Rightarrow F(\partial^\beta \varphi_n) \rightarrow F(\partial^\beta \varphi) \quad \because F \text{ is a distribution and distr's have continuity.}$$

as required.

□

If  $f$  is a distribution,  $f \in \mathcal{D}'(\Omega)$  and  $\varphi \in C_c^\infty(\Omega)$

$$\text{then } (\varphi f)(\varphi) = F(\varphi \varphi), \quad \varphi \in \mathcal{D}(\Omega).$$

$\mathcal{D}(\Omega)$

coeffs depend  
on  $x$   $\downarrow$  differentials

$$\underline{\text{Notation}}: P(x, \partial) u = \sum_{|\beta| \leq M} \psi_\beta(x) \overset{\uparrow}{\underset{\mathcal{D}(\Omega)}{\partial^\beta u}} \in \mathcal{D}'(\Omega).$$

If  $u \in \mathcal{D}'(\Omega)$  solves  $A$  then  $u$  is called the Green f. for PDE  $P(x, \partial)$  and denoted  $G(x, \partial)$

## Convolution

Let  $\Omega = \mathbb{R}^n$ .  $f \in C_0(\mathbb{R}^n)$  — i.e. cont. with compact support.  
 $g \in C(\mathbb{R}^n)$ .

$$h(x) = (f * g)(x) = \int_{\mathbb{R}^n} f(x-y) g(y) dy$$

$$= \int_{\mathbb{R}^n} f(y) g(x-y) dy = (g * f)(x).$$

$f$  has compact support so we aren't integrating over whole  $\mathbb{R}^n$  just the  $f$  is nonzero bit.

$$F_h(\varphi) = \int_{\mathbb{R}^n} h(x)\varphi(x) dx$$

$$= \int_{\mathbb{R}^n} \left[ \int_{\mathbb{R}^n} f(x-y) g(y) dy \right] \varphi(x) dx$$

$$= \int_{\mathbb{R}^n} \left[ \int_{\mathbb{R}^n} f(x-y) \varphi(x) dx \right] g(y) dy \quad \text{let } z=x-y.$$

$$= \int_{\mathbb{R}^n} \left[ \int_{\mathbb{R}^n} f(z) \varphi(z+y) dz \right] g(y) dy \quad \text{let } x=z$$

$$= \int_{\mathbb{R}^n} \left[ \int_{\mathbb{R}^n} f(x) \varphi(x+y) dx \right] g(y) dy$$

||  
 $\varphi^y(x)$

$$= \int_{\mathbb{R}^n} \left[ \int_{\mathbb{R}^n} f(x) \varphi^y(x) dx \right] g(y) dy$$

$$= \int_{\mathbb{R}^n} F_f(\varphi^y) g(y) dy$$

$\underbrace{\Phi(y)}$

$$= F_g(\Phi) = F_g(F_f(\varphi^y))$$

Defn: let  $F \in \mathcal{E}'(\mathbb{R}^n)$ ,  $G \in \mathcal{D}'(\Omega)$ .

Then the convolution  $H = F * G \in \mathcal{D}'(\Omega)$

$$(F * G)(\varphi) = G(F(\varphi^y))$$

Questions: Is it well-defined?

Is it linear?

Is it cts?

Question: Does  $F(\varphi^y) \in \mathcal{D}(\mathbb{R}^n)$

(1) Support: since  $F \in \mathcal{E}'(\mathbb{R}^n)$

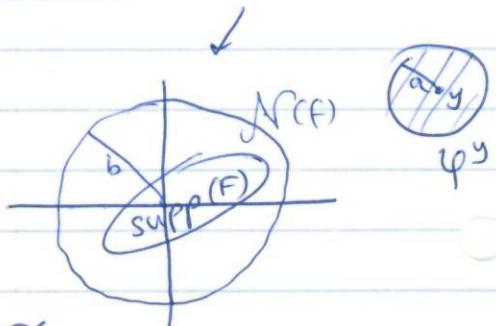
$\Rightarrow \text{supp}(F) \subset \mathbb{R}^n$ , ie.  $\exists b > 0$  s.t.

$\mathbb{R}^n \setminus \text{bowl of radius } b \text{ centred at } 0 \subset N(F).$

$\varphi \in \mathcal{D}(\Omega)$

$\Leftrightarrow \exists a > 0$  s.t.  $\text{supp } \varphi \subset B_a$

$\Leftrightarrow \text{supp } \varphi^y \subset B_a(y)$



Thus if  $|y| > b+a$ ,

$\text{supp } F \cap \text{supp } \varphi^y = \emptyset$ .

$\Rightarrow F(\varphi^y) = 0$

Denote  $\Phi(y) = F(\varphi^y)$ . Then  $\text{supp } \Phi \subset B_{b+a}(0)$ .

(2) Does  $\Phi(y) \in C^\infty(\mathbb{R}^n)$ ?

Use induction.

Assume that  $\Phi \in C^m(\mathbb{R}^n)$ , ie.  $\exists \partial^\alpha \Phi$ ,  $(|\alpha| \leq m)$ .

Want  $\Phi \in C^{m+1}(\mathbb{R}^n)$

Look for  $\partial^\beta \Phi$ ,  $|\beta| = m+1$

$\hookrightarrow$   $i^{\text{th}}$  place

where  $\beta = \underline{\alpha} + \underline{e}_i$  where  $e_i = (0, 0, \dots, 1, \dots, 0)$

$\Rightarrow \partial^\beta \Phi = \partial_i \partial^\alpha \Phi$ .

$$= \lim_{s \rightarrow 0} \frac{\partial^\alpha \Phi(x + se_i) - \partial^\alpha \Phi(x)}{s}$$

ignore

We shall prove that  $\partial^\alpha \Phi = F(\partial^\alpha \varphi^y)$ .

We use induction. Assume  $\partial^\alpha \Phi = F(\partial^\alpha \varphi^y)$ ,  $|\alpha| \leq m$ .

Let us show that  $\partial^\beta \Phi = F(\partial^\beta \varphi^y)$  if  $|\beta| = m+1$

Let  $\beta = \underline{\alpha} + e_i$ ,  
 $\uparrow e_i = (0, \dots, \overset{i\text{th place}}{1}, \dots, 0)$

$$\partial_i \partial^\alpha \Phi \xrightarrow[\text{inductive hypothesis}]{} \partial_i F(\partial^\alpha \varphi^y)$$

↑  
need to prove this exists.

$$\begin{aligned}\partial_i F(\partial^\alpha \varphi^y) &= \lim_{s \rightarrow 0} \frac{F(\partial^\alpha \varphi^{y+se_i}) - F(\partial^\alpha \varphi^y)}{s} \\ &= \lim F\left(\frac{\partial^\alpha \varphi^{y+se_i} - \partial^\alpha \varphi^y}{s}\right) \quad \text{by linearity.}\end{aligned}$$

Claim  $\frac{\partial^\alpha \varphi^{y+se_i} - \partial^\alpha \varphi^y}{s} \xrightarrow{s \rightarrow 0} \partial^\beta \varphi^y$  in  $\mathcal{D}(\mathbb{R}^n)$

$$\frac{\partial^\alpha \varphi(x+y+se_i) - \partial^\alpha \varphi(x+y)}{s} \xrightarrow{s \rightarrow 0} \partial^\beta \varphi^{y+se_i}(x+y)$$

Let  $\underline{\gamma}$  be an arbitrary multiindex

Want to show  $\partial^\gamma \left[ \frac{\partial^\alpha \varphi(x+y+se_i) - \partial^\alpha \varphi(x+y)}{s} \right] \xrightarrow{s \rightarrow 0} \partial^{\gamma+\beta} \varphi(x+y)$ .

Let, for ease of notation,  $f(x) = \partial^{\gamma+\alpha} \varphi(x+y) \in C_0^\infty(\mathbb{R}^n)$

Then

$$\begin{aligned}\frac{f(x+se_i) - f(x)}{s} &= \partial_i f(x) \\ &= \partial_i \partial^{\gamma+\alpha} \varphi(x+y) \\ &= \partial^{\gamma+\alpha+e_i} \varphi(x+y)\end{aligned}$$

$$= \partial^{\alpha+\beta} \varphi(x+y) \quad \square.$$

Due to claim,

$$F\left(\frac{\partial^\alpha \varphi^{y+se_i} - \partial^\alpha \varphi^y}{s}\right) \xrightarrow{s \rightarrow 0} F(\partial^{\alpha+e_i} \varphi^y) \quad \text{for all } y$$

||

$$\frac{1}{s} \left[ F(\partial^\alpha \varphi^{y+se_i}) - \underbrace{F(\partial^\alpha \varphi^y)}_{\Phi(y)} \right]$$

||

$$\frac{\Phi(y+se_i) - \Phi(y)}{s}$$

Thus  $\Phi(y)$  is differentiable and  $\partial_i \Phi(y) = F(\partial^{\alpha+e_i} \varphi^y)$ .

$$\partial_i \partial^\alpha F(\varphi^y) \underset{\substack{\text{induct.} \\ \text{hypoth.}}}{=} \partial_i F(\partial^\alpha \varphi^y) = F(\partial^{\alpha+e_i} \varphi^y)$$

||

$$\partial^{\alpha+e_i} F(\varphi^y) \quad \text{and so} \quad \partial^\alpha F(\varphi^y) = F(\partial^\alpha \varphi^y) \quad |\alpha| \leq m$$

$\Rightarrow F(\varphi^y) \in \mathcal{D}(\Omega)$ . Thus  $G(F(\varphi^y))$  is well defined.

Is it linear? Trivial.

continuous? Also a pain, but same type of pain.

Let  $\varphi_k \rightarrow \varphi$  in  $\mathcal{D}$ . We need

$$(F * G)(\varphi_n) \rightarrow (F * G)\varphi_k \xrightarrow{(F * G)(\varphi)}$$

$$\text{i.e. } G(F(\varphi_k^y)) \xrightarrow{k \rightarrow \infty} G(F(\varphi^y)).$$

It is enough to show that  $\Phi_k(y) (-F(\varphi_k^y)) \rightarrow \Phi(y)$  in  $\mathcal{D}$  ( $= F(\varphi^y)$ )

Check support: let us show that  $\text{supp}(\Phi_k), \text{supp}(\Phi)$  lie in the same bowl.

As  $\varphi_k \rightarrow \varphi$  in  $\mathcal{D}$ ,  $\exists a > 0$  s.t.  $\begin{cases} \text{supp}(\varphi_k), \\ \text{supp}(\varphi) \end{cases} \subset B_a$

Then  $\text{supp}(\Phi_k), \text{supp}(\Phi) \subset B_{b+a}$   
 $(\text{supp } F \subset B_b)$

$$\frac{\partial^\alpha \Phi_k(y) \rightarrow \partial^\alpha \Phi(y)}{\parallel \qquad \parallel} \\ F(\partial^\alpha \varphi_k^y) \qquad F(\partial^\alpha \varphi^y) . \quad \text{By Prop I, since}$$

Since  $\varphi_k \rightarrow \varphi$  in  $\mathcal{D}(\mathbb{R}^n) \Rightarrow \varphi_k^y \rightarrow \varphi^y$  in  $\mathcal{D}(\mathbb{R}^n)$

$\xrightarrow{\text{Prop 1.2}} \partial^\alpha \varphi_k^y \rightarrow \partial^\alpha \varphi^y$  in  $\mathcal{D}(\mathbb{R}) \quad \forall \underline{x}$ .

$$\Rightarrow F(\partial^\alpha \varphi_k^y) \xrightarrow{k \rightarrow \infty} F(\partial^\alpha \varphi^y)$$

Prop 1.25 Suppose  $F_p \rightarrow F$  in  $\mathcal{E}'(\mathbb{R}^n)$   
 $G_p \rightarrow G$  in  $\mathcal{D}'(\mathbb{R}^n)$ .

Then  $F_p * G_p \rightarrow F * G$  in  $\mathcal{D}'(\mathbb{R}^n)$

Not proved  $\therefore$  difficult

Problem Extra\* If  $F_p \rightarrow F$  in  $\mathcal{E}'(\mathbb{R}^n)$ ,  
show  $F_p * G \rightarrow F * G$

$$(F * G)(\psi) = \int_{\mathbb{R}^n} F(y) G(\psi(y)) \, dy$$

↑ has compact support

Lemma:  $G * F = F * G$

(Observe:  $F = F_f$      $G = F_g$  .    Obvious for from the  $f$ 's:

$$G * F = F_h \quad h(x) = \int g(x-y) f(y) \, dy$$

$$F * G = F_h \quad h(x) = \int f(x-y) g(y) \, dy$$

)) equal )

Problem 1.27 Show that  $(\partial^\alpha \delta) * G = \partial^\alpha G$

Note you can split derivatives.

$$\partial^\alpha (G * F) = \partial^\beta G * \partial^\gamma F \quad \forall \beta, \gamma \quad \beta + \gamma = \alpha$$

Since  $\delta$  is smooth

$$G = F_g \in C^\infty$$

$$F = F_f \in C^\infty$$

$$G * F = F_h$$

$$h(x) = \int g(x-y) f(y) \, dy$$

$$\partial^\alpha (G * F) \in \mathcal{E}'_h$$

$$\partial^\alpha (G * F) = F_{\partial^\alpha h}$$

(1)

$$\begin{aligned} \partial^\alpha h(x) &= \int \partial_x^\alpha g(x-y) f(y) \, dy & [\alpha = \beta + \gamma] \\ &= \int \partial_x^\beta (-1)^{\beta \gamma} \partial_y^\gamma g(x-y) f(y) \, dy & [\text{int. by parts}] \\ &= \int \partial_x^\beta g(x-y) \partial_y^\gamma f(y) \, dy \\ \Rightarrow F_{\partial^\alpha h} &= F_{\partial^\beta g} * F_{\partial^\gamma f} \end{aligned}$$

$$\text{Prop}^n 1.28 \quad \partial^\alpha(F * G) = F * \partial^\alpha G = \partial^\alpha F * G.$$

$$\begin{aligned} \partial^\alpha(F * G)(\varphi) &= (-1)^{|\alpha|}(F * G)(\partial^\alpha \varphi) \quad \text{by differentiation} \\ &= (-1)^{|\alpha|} G(F(\partial^\alpha \varphi)) \quad \text{by def}^n \text{ of } * \end{aligned}$$

$$\begin{aligned} F(\partial^\alpha \varphi) &= F(\partial_x^\alpha \varphi(x+y)) \\ &= F(\partial_y^\alpha \varphi(x+y)) \\ &= \partial_y^\alpha(F(\varphi)) \end{aligned}$$

like last lecture  
when we proved  $\partial^\alpha F(\varphi) = F(\partial^\alpha \varphi)$

$$\begin{aligned} \Rightarrow \partial^\alpha(F * G)(\varphi) &= (-1)^{|\alpha|} G(\partial^\alpha(F(\varphi))) \\ &= (-1)^{|\alpha|} \partial^\alpha G(F(\varphi)) \\ &= (F * \partial^\alpha G) \quad \square \end{aligned}$$

And since  $F * G = G * F$ , swapping  $F$  and  $G$  holds.

(f) Also  $\partial^{\beta+\gamma}(F * G) = \partial^\beta F * \partial^\gamma G$ . as a corollary.

Recall Prop 1.25:  $F_p \rightarrow F, G_p \rightarrow G \Rightarrow F_p * G_p \rightarrow F * G$

We know smaller version,  $F_f * G \cdot F_g = F_{f \cdot g} = F_g * f = F_g * F_f$ .  
if the distrib come from functions

The proposition is v. difficult to prove.

Thm 1.29 (Density) If we have  $\Omega \subset \mathbb{R}^n$   
 $F \in \mathcal{D}'(\Omega)$ ,  
 $\exists$  a sequence  $f_p \in C_0^\infty(\Omega)$   
s.t.  
 $F_{f_p} \xrightarrow{p \rightarrow \infty} F$  in  $\mathcal{D}'(\Omega)$

$F * G = \lim_{p \rightarrow \infty} F_{f_p} * F_{g_p}$  by approximating  $G$  by  $F_{g_p}$   
(a thm tells us we can always find  
a seq.  $F_{g_p} \rightarrow G$   $\forall \epsilon$ )

$$= \lim_{\substack{\downarrow \\ G}} (F_{g_p} * F_{f_p}) = \lim_{\substack{\downarrow \\ F}} G * F.$$

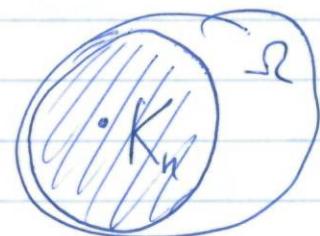
Corollary: If  $F \in \mathcal{E}'(\Omega)$ , then  $F_{f_p} \rightarrow F$  in  $\mathcal{E}'(\Omega)$ .

Sketch of proof: (1) From  $\mathcal{D}'(\Omega)$  to  $\mathcal{E}'(\Omega)$

Let  $K_n = \{x \in \Omega : |x| \leq n, d(x, \partial\Omega) \geq \frac{1}{n}\}$

$$\Omega = \bigcup_{n=1}^{\infty} K_n$$

Also  $K_n \subset K_{n+1}^{\text{int}}$



by Prop^n 1, 2,  $X_n \in C_0^\infty(\Omega)$   $0 \leq X_n$  s.t.

$$X_n = 1 \text{ in } K_n$$

$$X_n = 0 \text{ outside } K_{n+1}$$

Let  $F \in \mathcal{D}'(\Omega)$ ,  $F_n = X_n F$ .

$$\text{Supp}(F_n) \subset K_{n+1}.$$

Indeed, if  $\varphi \in \mathcal{D}(\Omega)$  and  $\text{supp}(\varphi) \cap K_{n+1} = \emptyset$   
 then  $F_n(\varphi) = (X_n F)(\varphi) = F(X_n \varphi) = 0$ .

Also  $F_p \rightarrow F$ . To prove this:  $\forall \varphi \in \mathcal{D}(\Omega)$ ,  
 $F_p(\varphi) \rightarrow F(\varphi)$ .

$$\overline{F(X_p \varphi)}$$

Indeed, for large  $p$ ,  $K \subset K_p$ .

Proof:  $d(K, \delta \Omega) = d > 0$  as  $K \subset \Omega$ .

As  $R$ -compact  $K \subset B_R$ , for some  $R > 0$ . Thus, for  $p > \max(R, \frac{1}{d})$ ,  $K \subset K_p$ .

Any distribution can be approximated by distributions with compact support.

(2)  $\forall F \in \mathcal{E}'(\Omega)$ , there are  $f_p \in C_0^\infty(\Omega)$  s.t.

$$f_p \xrightarrow{\text{dists. with compact support}} F \text{ in } \mathcal{E}'(\Omega)$$

$$X(x) \in C_0^\infty(\mathbb{R}^n), \quad X = X((x)) \quad \text{radial}$$

$$\int X(x) dx = 1 \quad X = 0 \text{ for } |x| > 1$$

$$X^\varepsilon(x) = \varepsilon^{-n} X\left(\frac{x}{\varepsilon}\right) \leftarrow \text{has support in } B_\varepsilon(0).$$

$$\int X^\varepsilon(x) dx = 1.$$

[Problem\*: Prove  $X^\varepsilon \xrightarrow[\varepsilon \rightarrow 0]{} \delta$ .]

$$F^{*\varepsilon} = X^\varepsilon * F \in \mathcal{E}'(\Omega) \quad \varphi \in \mathcal{D}(\Omega).$$

$$(X^\varepsilon * F)(\varphi) = F(X^\varepsilon(\varphi^y)) \quad \text{by defn of } *.$$

$$F_{X^\varepsilon}(\varphi^y) := \int_{\Omega \cap R^n} X^\varepsilon(x) \varphi(x+y) dx$$

$$\in C_0^\infty(R^n)$$

$$F^\varepsilon(\varphi) = (X^\varepsilon * F)(\varphi) = F(X^\varepsilon \varphi^y) = \int X^\varepsilon(x) \varphi(x+y) dx$$

$$= X^\varepsilon(\varphi^y) \rightarrow \varphi(y).$$

Moreover, we can prove that  $(X^\varepsilon \varphi^y) \rightarrow \varphi$  in  $C^0(\Omega)$ .

Call  $X^\varepsilon(\varphi^y) = \psi^\varepsilon(y)$ . Then

$$\psi^\varepsilon(y) = \int_{|x| \leq \varepsilon} X^\varepsilon(x) \varphi(x+y) dx = \int_{|x| \leq \varepsilon} X^\varepsilon(x) \varphi(y) dx = \varphi(y).$$

$$= \varphi(y) + \int_{|x| \leq \varepsilon} X^\varepsilon(x) [\varphi(x+y) - \varphi(y)] dx$$

$$\text{Observe } \sup_{|x| \leq \varepsilon} |\varphi(x+y) - \varphi(y)| \xrightarrow[\varepsilon \rightarrow 0]{} 0$$

$\Rightarrow [\varphi(x+y) - \varphi(y)]$  in integral  $\rightarrow 0$   
uniformly for  $y \in K \subset \Omega$ .

$$+ b(x)^3 x$$



$$\parallel X^\varepsilon(\varphi^y)$$

Therefore  $\psi^\varepsilon(y) \rightarrow \varphi(y) \quad \forall y \in \Omega$  (and uniformly on any compact).

Same for derivative, if we replace  $\psi^\varepsilon(y)$  by  $\partial^\alpha \psi^\varepsilon(y)$ , we do the same trick,  
so  $\partial^\alpha \psi^\varepsilon(y) \rightarrow \partial^\alpha \varphi(y) \quad \forall y \in \Omega$  and  $\alpha$ .

This means  $\psi^\varepsilon \rightarrow \varphi$  in  $\mathcal{E}'(\Omega) = C^\infty(\Omega)$

$F(\psi^\varepsilon) \xrightarrow{\varepsilon \rightarrow 0} F(\varphi)$  since  $F \in \mathcal{E}'(\Omega)$ .

$$F(X^\varepsilon(\varphi^y)) = (X^\varepsilon * F)(\varphi) \Rightarrow X^\varepsilon * F \rightarrow F \text{ in } \mathcal{D}'(\Omega).$$

Note  $\text{supp} \left( \int X^\varepsilon(x) \varphi(x+y) dx \right) \subset \varepsilon\text{-vicinity of } \text{supp}(F)$

$$F^\varepsilon(\varphi) = (X^\varepsilon * F)(\varphi) = F(X^\varepsilon(\varphi))$$

Claim  $\text{supp}(X^\varepsilon * F) \subset \varepsilon\text{-vicinity of } \text{supp}(F)$

$$= \{x : d(x, \text{supp } F) \leq \varepsilon\} = \text{supp}(F)^\varepsilon$$

$$\text{Let } \text{supp}(\varphi) \cap (\text{supp } F)^\varepsilon = \emptyset$$

$$\Leftrightarrow d(\text{supp}(\varphi), \text{supp}(F)) > \varepsilon$$

$$\Rightarrow [\varepsilon\text{-vicinity of } \text{supp}(\varphi)] \cap \text{supp } F = \emptyset.$$

$$\text{Thus } \text{supp}(\psi^\varepsilon) \cap \text{supp}(F) = \emptyset.$$

$$\Rightarrow F(\psi^\varepsilon) = (X^\varepsilon * F)(\varphi) = 0. \quad \square$$

[This proves that  $\text{supp}(X^\varepsilon(\varphi^y))$  is compact  
i.e.  $X^\varepsilon(\varphi^y) \in \mathcal{E}' \Rightarrow X^\varepsilon * F \rightarrow F$  in  $\mathcal{D}'(\Omega)$ ]

Therefore,  $\text{supp}(X^\varepsilon * F) \subset \varepsilon_0\text{-vicinity of } \text{supp}(F)$   
if  $\varepsilon < \varepsilon_0$ .

Thus  $X^\varepsilon * F \rightarrow F$  in  $\mathcal{E}'(\Omega)$  if  $\varepsilon \leq \varepsilon_0$

$$= \frac{1}{2} d[\text{supp}(F), \partial\Omega]$$

Claim:  $X^\varepsilon * F \in C_0^\infty(\Omega)$  [when  $\varepsilon < \frac{1}{2} d[\text{supp}(F), \partial\Omega]$ ]

i.e.  $\exists a f^n h^\varepsilon \in C_0^\infty(\Omega)$  s.t.  $X^\varepsilon * F = F_{h^\varepsilon}$

$$\begin{aligned} \text{Sketch of proof: Let } F &= F_f. \text{ Then } (X^\varepsilon * F_f)(\varphi) \\ &= F(X^\varepsilon(\varphi)) \end{aligned}$$

$$= \int f(y) \left[ \int X^\varepsilon(x) \varphi(x+y) dx \right] dy$$

$$\begin{aligned} \text{let } z &= x+y \\ \Rightarrow x &= z-y \end{aligned} \quad = \int \varphi(z) \left[ \int f(y) X^\varepsilon(z-y) dy \right] dz$$

$$= F_{h^\varepsilon}(\varphi), \text{ where}$$

$$h^\varepsilon(z) = \int f(y) X^\varepsilon(z-y) dy.$$

because we take abs. value

$$= \int f(y) X^\varepsilon(y-z) dy$$

$$= F_f(X^{\varepsilon-z})$$

$$\varphi^y = \varphi(x+y)$$

$$\varphi^{-z} = \varphi(x-z).$$

$$(X^\varepsilon * F)(\varphi) = F_{h^\varepsilon}(\varphi)$$

"

$$R^\varepsilon(z) = F(X^{\varepsilon-z}) .$$

$$\because F(\varphi^y) \underset{\partial \Omega}{\in} C^\infty(\mathbb{R}^n) \Rightarrow F(\varphi^{-y}) \in C^\infty(\mathbb{R}^n)$$

$$\text{Thus } F(X^{\varepsilon-z}) \in C_0^\infty(\mathbb{R}^n) .$$

$$\psi^\varepsilon(y) = \int K X^\varepsilon(x) \varphi(x+y) dx = \int_K X^\varepsilon(z-y) \varphi(z) dz \underset{\mathbb{R}}{\in} C^\infty(\Omega) .$$

$$= \lim_{\delta \rightarrow 0} \sum_i X^\varepsilon(z^i - y) \varphi(z^i) \delta^n \quad \text{in } C^\infty(\Omega) .$$

$$\partial^\alpha \psi^\varepsilon(y) = \int_K (-1)^{|\alpha|} \partial^\alpha X^\varepsilon(z-y) \varphi(z) dz$$

$$= (-1)^{|\alpha|} \lim_{\delta \rightarrow 0} \sum \partial^\alpha X^\varepsilon(z^i - y) \varphi(z^i) \delta^n$$

$$\text{Thus } \psi^\varepsilon = \lim_{\delta \rightarrow 0} R_\delta^\varepsilon \quad \text{in } C^\infty(\Omega)$$

$$\Rightarrow F(\psi^\varepsilon) = \lim F(R_\delta^\varepsilon)$$

$$= \lim_{\delta \rightarrow 0} F\left( \sum X^\varepsilon(z^i - y) \varphi(z^i) \delta^n \right)$$

$$= \lim_{\delta \rightarrow 0} \sum \left( F(X^{\varepsilon-z^i}) \right) \varphi(z^i) \delta^n$$

$$= \int F(X^{\varepsilon-z}) \varphi(z) dz$$

$$(X^\varepsilon * F)(\varphi) = F_{h^\varepsilon}(\varphi), \quad h^\varepsilon(z) = \int F(X^{\varepsilon-z}) dz .$$

$$\Rightarrow C_0^\infty(\Omega) .$$

*(We can take all these guys out)*

Self  
Study

## Integration of distnbs wrt $\tau$

Let  $F_\tau$ ,  $\tau \in A \subset \mathbb{R}^d$  is a distribution depending continuously on parameter  $\tau$ ,  $F_\tau \in \mathcal{D}'(\Omega)$  and  $\tau = (\tau_1, \dots, \tau_d)$

If  $\tau \rightarrow \tau_0$ , then  $F_\tau \xrightarrow{\mathcal{D}} F_{\tau_0}$ .

let  $g \in C_0(A)$  [recall means cont<sup>n</sup>:  $f^n$  with compact support]

Then let  $G_g = \int_A g(\tau) F_\tau d\tau \in \mathcal{D}'(\Omega)$

$$\text{then } G_g(\varphi) = \int_A g(\tau) F_\tau(\varphi) d\tau$$

We can check that if  $F_\tau = F_{f(\tau)}$  where  $f(\tau) = f(x, \tau) \in C(\Omega \times A)$

then  $G_g = F_h$ ,  $h(x) = \int_A g(\tau) f(x, \tau) d\tau$

let's consider  $\Omega = \mathbb{R}^n$  and  $A = \mathbb{R}^n$ .

Def<sup>n</sup>: For  $F \in \mathcal{D}'(\mathbb{R}^n)$ ,  $y \in \mathbb{R}^n$ , we define the translation of  $F$  by  $y$  (notated  $T_y F$ )

If  $F = F_f$ , then  $T_y F = F_{T_y F}$   $(T_y F)(x) = f(x-y)$

$$\begin{aligned} \text{Observe that } F_{T_y F}(\varphi) &= \int \varphi(x) f(x-y) dx \\ &= \int f(x) \varphi(x+y) dx \end{aligned}$$

$$= F_f(\varphi^y)$$

$$\underbrace{(T_y F)(\varphi)}_{\sim} = F_f(\varphi^y) \leftarrow \text{Definition of translation}$$

Example:  $T_y \delta = \delta_y$  :

$$(T_y \delta)(\varphi) = \delta(\varphi^y) = \varphi^y(0) = \varphi(y) = \delta_y(\varphi)$$

Notation:  $T_y F = F(\cdot - y)$

Observe that  $T_y F := F_y$  is a distribution in  $\mathcal{D}'(\mathbb{R}^n)$ , which depends continuously on  $y$ .

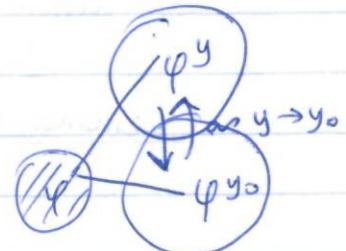
$$T_y F \rightarrow T_{y_0} F \text{ as } y \rightarrow y_0 \\ (T_y F)(\varphi) = F_y(\varphi^y) \xrightarrow{?} (T_{y_0} F)(\varphi) = F(\varphi^{y_0})$$

This is true :-  $\varphi^y \rightarrow \varphi^{y_0}$  in  $\mathcal{D}(\mathbb{R}^n)$  if  $y \rightarrow y_0$

$$\varphi(x+y) \xrightarrow{\mathcal{D}(\mathbb{R}^n)} \varphi(x+y_0)$$

*need to do  
this to show it  
goes in  $\mathcal{D}(\mathbb{R}^n)$*   
Clearly  $\partial^\alpha \varphi(x+y) \rightarrow \partial^\alpha \varphi(x+y_0) \quad \forall \alpha \quad \forall x \in \mathbb{R}^n$   
when  $y \rightarrow y_0$

The supports lie in the same compact



~~Let~~ Let  $g \in C_0(\mathbb{R}^n)$ . Then we can

$$G_g = \int_{\mathbb{R}^n} g(y) (T_y F) dy$$

Problem :  $G_g = F_g * F$

## Laplace operator and Green's function

$$DF = \sum_{|\alpha| \leq m} \psi_\alpha(x) \partial^\alpha F \quad \begin{aligned} \psi_\alpha &\in C^\infty(\Omega) \\ F &\in \mathcal{D}'(\Omega) \end{aligned}$$

Can we solve the eqn?  $DF = \delta_y$ ?

If we can we have a distribution  $G_y \in \mathcal{D}'(\Omega)$   
called Green's function

Typically  $G_y$  depends continuously on  $y$

Recall the Laplacian in  $\mathbb{R}^n$  (or  $\Omega \subset \mathbb{R}^n$ )

$$\Delta = -\sum_{i=1}^n \partial_i^2$$

Green's f<sup>n</sup> for the Laplacian is also called the fundamental solution and denoted  $\Phi_y(x) = G_y$

Lemma 1.38  $\Phi_y(x) = \frac{1}{4\pi|x-y|}$  is the fundamental

sol<sup>n</sup> for  $\Omega = \mathbb{R}^3$ .

i.e. need to prove  $\Delta \Phi = \delta_y$ .

$$\text{Proof: } (\Delta \Phi_y)(\varphi) = -\Phi_y(\Delta \varphi)$$

$$= \frac{1}{4\pi} \int_{\mathbb{R}^3} \frac{\Delta \varphi(x)}{|x-y|} dx$$

$$= \frac{1}{4\pi} \lim_{\epsilon \rightarrow 0} \int_{\mathbb{R}^3 \setminus B^\epsilon(y)} \frac{\Delta \varphi(x)}{|x-y|} dx$$

Since  $\frac{1}{4\pi|x-y|}$  is smooth in  $\mathbb{R}^3 \setminus B_\varepsilon(y)$  we can integrate by parts in the above integral.

Recall Green's second identity from 1402:

$$\int_V \Delta f g = \int_V f \Delta g + \int_S \left( \frac{\partial f}{\partial n} g - f \frac{\partial g}{\partial n} \right) dS$$

Using this we get

$$\lim_{\varepsilon \rightarrow 0} \left[ \frac{1}{4\pi} \int_{\mathbb{R}^3 \setminus B_\varepsilon} \varphi(x) \underbrace{\Delta_x \left( \frac{1}{|x-y|} \right)}_0 dx \right]$$

$$f = \varphi \\ g = \frac{1}{|x-y|}$$

$$\text{new} \rightarrow \left. -\frac{1}{4\pi} \int_{S_\varepsilon} \left( \frac{\partial \varphi}{\partial n} \cdot \frac{1}{|x-y|} - \varphi \frac{\partial}{\partial n} \left( \frac{1}{|x-y|} \right) \right) dS_x \right]_{y \text{ is fixed}}$$

$$\text{Let } x \rightarrow z = x - y$$

$$z \rightarrow (\rho, \theta, \varphi) \text{ spherical coords}$$

$$\text{Observe } \frac{\partial}{\partial n} = -\frac{\partial}{\partial \rho}.$$

$$\Rightarrow = \frac{1}{4\pi} \lim_{\varepsilon \rightarrow 0} \int_{S_\varepsilon} \left[ +\frac{\partial \varphi}{\partial \rho} (y + \rho \omega) \frac{1}{\varepsilon} - \varphi \frac{\partial}{\partial \rho} \left( \frac{1}{\rho} \right) \Big|_{\rho=\varepsilon} \right] dS_\varepsilon$$

$$-\frac{1}{\varepsilon^2}$$

where  $\omega$  is a unit vector made of  $\partial_1 \varphi$   
 $\omega = (\sin \theta \cos \varphi, \sin \theta \sin \varphi, \cos \theta)$

$$\text{So } (\Delta \Phi_y)(\varphi) = \frac{1}{4\pi} \lim_{\varepsilon \rightarrow 0} \int_{S_\varepsilon} \left( +\frac{\partial \varphi}{\partial \rho} \cdot \frac{1}{\varepsilon} + \frac{1}{\varepsilon^2} \varphi (y + \rho \omega) \right) \cdot \varepsilon^2 \sin \theta d\theta d\varphi dS_\varepsilon$$

$$\iint_{\substack{0 \leq \theta \leq \pi \\ 0 \leq \varphi \leq 2\pi}}$$

$$\text{Now note (1)} \quad \iint \frac{\partial \varphi}{\partial \rho} \frac{1}{\varepsilon} \varepsilon^2 \sin \theta d\theta d\rho \xrightarrow[\varepsilon \rightarrow 0]{} 0$$

↑ bounded

$$\text{and (2)} \quad \frac{1}{4\pi} \iint_{\Omega, \varphi} \varphi(y + \varepsilon \omega) \sin \theta d\theta d\rho$$

↓  
 $\varphi(y)$

$\xrightarrow[\varepsilon \rightarrow 0]$

$(f = \varepsilon \text{ on the sphere})$

$$\frac{1}{4\pi} \varphi(y) \iint_{\Omega, \varphi} \sin \theta d\theta d\rho$$

$\brace{ \quad }$

$$= \text{vol. of sphere of radius 1} = 4\pi$$

□

$$\text{So we have shown } -\Delta \left( \frac{1}{4\pi(x-y)} \right) = \delta_y$$

$$\text{Want to let } y=0: \quad -\Delta \left( \frac{1}{4\pi|x|} \right) = \delta \quad ?$$

$$-\Delta \left( T_y \left( \frac{1}{4\pi|x|} \right) \right) = T_y \delta$$

$$\text{Noting } T_y \circ \delta^\alpha = \delta^\alpha \circ T_y$$

$$T_y \left( -\Delta \frac{1}{4\pi|x|} \right) = T_y \delta = \delta_y$$

So it's sufficient to prove  $-\Delta \left( \frac{1}{4\pi|x|} \right) = \delta$  and use commutativity to solve  $-\Delta \left( \frac{1}{4\pi|x-y|} \right) = \delta_y$ .

Why is knowledge of Green's<sup>n</sup> such a useful thing?

Say we want to solve  ~~$\Delta F = g$~~   
an operator with constant coeffs

$$D = \sum_{|\alpha| \leq m} c_\alpha \partial^\alpha$$

Assume we know  $G$  s.t.  $DG = \delta$  (Green's<sup>n</sup>)

$$DF = H \in \mathcal{E}'(\mathbb{R}^n) \quad \text{so } F = G * H$$

Recall if  $DF = \sum c^\alpha \partial^\alpha (G * H)$

$$= \underbrace{\left( \sum c^\alpha \partial^\alpha G \right) * H}_{\delta} = \delta * H = H$$

So if you ever want to solve  $-\Delta \cdot F = g$  in  $\mathbb{R}^3$   
 $\omega \subset \mathbb{R}^3$

$$\text{Then } F = \frac{1}{4\pi|x|} * g$$

Observe that if  $g \in C_0(\mathbb{R}^3)$

$$F(x) = \frac{1}{4\pi} \int_{\mathbb{R}^3} \frac{g(y)}{|x-y|} dy$$



If we have an electrostatic potential  
 $(q_i, y_i) \quad i=1, \dots, p$

$$\Phi^t(x) = \sum_{i=1}^p \frac{q_i}{4\pi\epsilon_0(x-y_i)}$$

$$E^t(x) = -\nabla \Phi^t$$

$$g = \sum_{i=1}^p \frac{q_i}{\epsilon_0} \delta_{y_i}$$

$$\Phi * \frac{g}{\epsilon_0} = \frac{1}{4\pi|x|} * \frac{1}{\epsilon_0} \sum_{i=1}^p q_i \delta_{y_i} = \frac{1}{\epsilon_0} \sum_{i=1}^p \underbrace{\frac{1}{4\pi|x|} * q_i}_{\text{since } \varphi^y(z) = \varphi^z(y)} \delta_{y_i}$$

$$\text{Recall } \delta_z * H = H$$

$$(\delta_z * H)(y)$$

$$\text{since } \varphi^y(z) = \varphi^z(y)$$

$$H(\delta_z \varphi^y) = H(\varphi^y(z)) = H(\varphi^z) = (T_z H)(y)$$

$$\text{So we get } \delta_z * H = T_z H$$

$$\frac{q_i}{4\pi|x-y_i|}$$

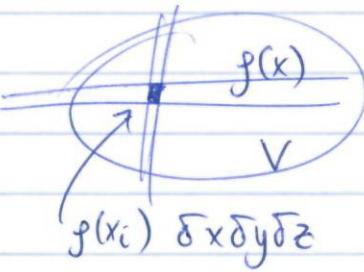
$$\text{So } \Phi^t(x) = \Phi * \frac{1}{\epsilon_0} \left( \sum_{i=1}^p q_i \delta_{y_i} \right)$$

What is the electrostatic potential due to a distribution  
 $\rho \in \mathcal{E}'(\mathbb{R}^3)$  of charges

$$\Phi^s = \Phi * \frac{\rho}{\epsilon_0}$$

Remember triple integrals

cubes:



← inside this point there's approx. this charge

$$\frac{g(x_i) \delta x \delta y \delta z}{4\pi \epsilon_0 |x - x_i|}$$

$$\text{Take } \lim_{\substack{\delta x \\ \delta y \\ \delta z \rightarrow 0}} \sum_i \frac{g(x_i) \delta x \delta y \delta z}{4\pi \epsilon_0 |x - x_i|}$$

$$= \frac{1}{4\pi \epsilon_0} \int_V \frac{g(y)}{|x - y|} dy = \frac{1}{4\pi|x|} * \frac{g}{\epsilon_0}$$

$$= \Phi * \frac{g}{\epsilon_0} = \Phi^g$$

$$-\nabla^2 \Phi^g = \nabla^2 \Phi * \frac{g}{\epsilon_0} = \delta * \frac{g}{\epsilon_0} = \frac{g}{\epsilon_0}$$

And  $-\nabla^2 \Phi^g = \frac{g}{\epsilon_0}$  Poisson eq<sup>n</sup>.

$$E^g = -\nabla \Phi^g$$

electric field due to particle distribution  $g$

Gauss' law

$$\left. \begin{aligned} \nabla \cdot E^g &= \frac{g}{\epsilon_0} \\ \nabla \times E^g &= 0 \end{aligned} \right\} \text{Fundamental eq}^n \text{s of electrostatics !}$$

NFE

$$f \in \mathcal{E}', \quad f_p \in C_0(\mathbb{R}^3)$$

$$f_p \rightarrow f \text{ in } \mathcal{E}'(\Omega)$$

$$\underline{\Phi}^{f_p} = \underline{\Phi} * \frac{f_p}{\epsilon_0} \longrightarrow \underline{\Phi} * \frac{f}{\epsilon_0}$$

Green's

$$-\nabla^2 \underline{\Phi} = \delta, \quad \underline{\Phi} = \frac{1}{4\pi|x|}, \quad \mathbb{R}^3$$

If  $f \in C_0(\mathbb{R}^3)$  - cont. charge densities with compact support.

$\underline{\Phi} * \frac{f}{\epsilon_0} = \underline{\Phi}^f$  - electrostatic potential of the charge density  $f$ .

$$\underline{\Phi}^f(x) = \frac{1}{4\pi\epsilon_0} \int_{\mathbb{R}^3} \frac{f(y)}{|x-y|} dy$$

$$-\nabla^2 \underline{\Phi}^f = \frac{f}{\epsilon_0}$$

$$\text{If } f \in \mathcal{E}'(\mathbb{R}^3), \quad \underline{\Phi}^f = \frac{1}{\epsilon_0} \underline{\Phi} * f$$

$$\underline{\Phi}_y^a = \frac{a}{4\pi\epsilon_0|x-y|}$$

$$\underline{E}^f = -\nabla \underline{\Phi}^f = -\nabla \underline{\Phi} + \frac{f}{\epsilon_0}$$

$$-\nabla \underline{\Phi} = \frac{x}{4\pi|x|^3}$$

$$\underline{E}^f(x) = \frac{1}{4\pi\epsilon_0} \int \frac{f(y)(x-y)}{4\pi|x-y|^3} dy$$

3D vector

If  $f$  is ct  
this integral  
is cvgt.

Problem:  $F \in \mathcal{D}'(\Omega)$        $\Omega \subset \mathbb{R}^3$   
 $\left( \frac{\partial F}{\partial x}, \frac{\partial F}{\partial y}, \frac{\partial F}{\partial z} \right) = \nabla F \in \mathcal{D}'(\Omega)^3$       3D vector distribution  
 $\nabla \times \nabla F \stackrel{?}{=} 0$   
 $\nabla \cdot (\nabla F) = \nabla^2 F$

$$\begin{aligned}
 \nabla \cdot E^S &= -(\nabla \cdot \nabla \Phi^S) \quad \text{by defn of } E^S \\
 &= -\nabla^2 \Phi^S \\
 &= \frac{g}{\epsilon_0}
 \end{aligned}
 \tag{Gauss' law in differential form}$$

$$\begin{aligned}
 \nabla \times E^S &= -\nabla \times (\nabla \Phi^S) \\
 &= -\nabla \times (\nabla \Phi \times \frac{g}{\epsilon_0}) \\
 &= \underbrace{(-\nabla \times \nabla \Phi)}_0 + \frac{g}{\epsilon_0} \\
 &= 0. \quad \text{i.e. each component is zero.}
 \end{aligned}$$

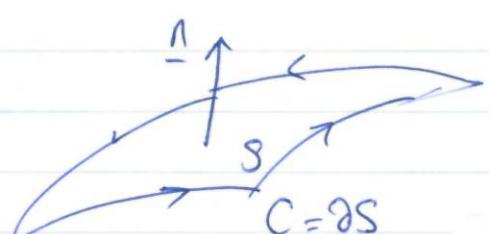
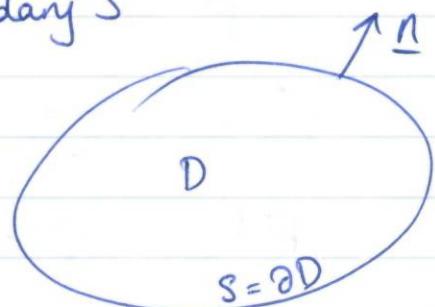
basic laws of electrostatics

Now, if we have a domain  $D$  with boundary  $S$

Write down divergence thm:

$$\begin{aligned}
 \int_S E^S \cdot \underline{n} dS &= \int_D \underbrace{\nabla \cdot E^S}_{\parallel} dV \\
 &= \frac{1}{\epsilon_0} \int_D g dV \quad \frac{g}{\epsilon_0} \\
 \text{total charge in } D \rightarrow \frac{Q(D)}{\epsilon_0}
 \end{aligned}$$

(Gauss' law in integral form)



P.C.

Problem Pct  $\rho = \rho(r)$ . Find  $E^{\phi}$  then  $\Phi^{\phi}$ .

Because of spherical symmetry,

$$E = E(r) = \epsilon(r) \underline{e}_r \quad \text{unit vec. in radial dir?}.$$

By Gauss law in integral form, we have

$$\begin{aligned} \iint_{S_r} E \cdot \underline{n} dS &= \frac{1}{\epsilon_0} Q(B_r) \\ &= \frac{1}{\epsilon_0} \int_{B_r} \rho dV \\ &= \frac{1}{\epsilon_0} \int_0^r g(r') (r')^2 dr' \underbrace{\int d\omega}_{\frac{4\pi}{3}} = \frac{4\pi}{3\epsilon_0} R(r) \end{aligned}$$

But  $\iint_{S_r} E \cdot \underline{n} dS = \iint_{S_r} E \cdot \underline{r} dS = \epsilon_r \iint dS = 4\pi r^2 \epsilon(r)$

$$\rightarrow \epsilon(r) = \frac{R(r)}{\epsilon_0 r^2} \xrightarrow[r \rightarrow 0]{} 0 \quad \text{as } R(r) \sim r^3$$

Now to find  $\Phi^{\phi}$ .

$$-\nabla \Phi(r) = E.$$

$$\rightarrow \Phi(r) = \int_r^{\infty} \epsilon(r) dr \quad \text{because normally } - \int_{\infty}^r \epsilon(r) dr$$

l set potential to be 0 at infinity

$$\Phi(r) \xrightarrow[r \rightarrow \infty]{} 0 \quad \nabla \int_r^{\infty} \frac{R(r')}{(r')^2} dr'$$

We can use integration by parts on  $\int_r^\infty \frac{R(r')}{r'^2} dr'$

$\therefore R$  is itself an integral.

$$\begin{aligned}\text{sec} \\ \text{first} \\ \text{sec} = R(r) \\ \text{first} \\ \frac{d}{dr} \text{sec} = \frac{1}{r^2}\end{aligned}$$

$$= \left[ R(r) \left( -\frac{1}{r} \right) \right]_r^\infty + \int_r^\infty R'(r) \frac{1}{r} dr$$

$$= \frac{R(r)}{r} + \int_r^\infty g(r') r' dr'$$

$$R' = \cancel{\frac{g(r)}{r^2}}$$

P.C.

1.71 Q:  $f \in C(\mathbb{R}^n)$  satisfies

$$\int_{\mathbb{R}^n} f(x) dx = 1$$

$$\int_{\mathbb{R}^n} |f(x)| dx < \infty.$$

let  $f_p(x) = p^n f(px)$   $p=1, 2, \dots$

Show  $f_p \rightarrow \delta$  as  $p \rightarrow \infty$  in  $\mathcal{D}'(\mathbb{R}^n)$ .

Ans:  $F_{f_p}(\varphi) = p^n \int_{\mathbb{R}^n} f(px) \varphi(x) dx$

$y = px \Rightarrow$   $= \int_{\mathbb{R}^n} f(y) \varphi\left(\frac{y}{p}\right) dy$   $\because x \text{ is } n\text{-dim vector}$

$= \underbrace{\int_{\mathbb{R}^n} f(y) \varphi(0) dy}_{= \varphi(0)} + \underbrace{\int_{\mathbb{R}^n} f(y) [\varphi\left(\frac{y}{p}\right) - \varphi(0)] dy}_{\xrightarrow{\text{pointwise}} 0}$

$= \varphi(0)$  since  $\int f(y) dy = 1$

Pointwise is OK but we really need uniformly.

Want to show

$$\forall \varepsilon \exists p(\varepsilon) \text{ s.t. } p > p(\varepsilon), \left| \underbrace{\int_{\mathbb{R}^n} f(y) [\varphi\left(\frac{y}{p}\right) - \varphi(0)] dy}_{= \int_{B_A} + \int_{\mathbb{R}^n \setminus B_A}} \right| < \varepsilon$$

$$= \int_{B_A} + \int_{\mathbb{R}^n \setminus B_A}.$$

But  $\int_{\mathbb{R}^n} |f(x)| dx = C < \infty \Rightarrow \forall \delta \exists A(\delta) \text{ s.t. } \int_{\mathbb{R}^n \setminus B_A} |f(x)| dx < \delta$

Let  $M = \max\{|\varphi(y)|\}$

$$\text{let } \delta = \frac{\varepsilon}{4M}$$

$$\begin{aligned} A(\delta) &= \int_{\mathbb{R}^n \setminus B_A} |f(y)| [\varphi\left(\frac{y}{p}\right) - \varphi(0)] dy \\ &\leq 2M \int_{\mathbb{R}^n \setminus B_A} |f(y)| dy \leq \frac{\varepsilon}{2} \end{aligned}$$

Look  
for

$$\int_{B_A} |f(y)| |\varphi\left(\frac{y}{p}\right) - \varphi(0)| dy$$

$\left| \frac{y}{p} \right| \leq \frac{A}{p} \xrightarrow[p \rightarrow \infty]{} 0$

$$S_0 \left| \varphi\left(\frac{y}{p}\right) - \varphi(0) \right| \leq \frac{\varepsilon}{2C} \text{ if } p \geq p(\varepsilon)$$

$$S_0 \leq \frac{\varepsilon}{2C} \int_{\mathbb{R}^n} |f(y)| dy = \frac{\varepsilon}{2}.$$

$$0 = \oint_S (\nabla \times E^S) \cdot d\mathbf{S} = \oint_C E^S \cdot d\mathbf{r}$$

$\mathbb{R}$  [Stokes' law]

recall only valid for  
simply connected domains

$\times$  Problem:  $\rho = \rho(r)$   $r^2 = x^2 + y^2 + z^2 = |\mathbf{r}|^2$

ie assume charge distribution is  $f$  of  $r$  alone

Find  $\Phi^S(\mathbf{r})$  in terms of  $\rho(r)$ . and  $E^S$ . to get it

So  $\Phi^S = \Phi^S(r)$  by symmetry since  $\rho = \rho(r)$ .

(PET) Problem\*:  $\rho = \rho(d)$  in cylindrical coords.  $(d, \varphi, z)$   
 $d = \sqrt{x^2 + y^2}$

Find  $E^S$  (use Gauss' law)

### Dipoles

If we have charge distribution  $p \cdot \nabla \delta_y$ , ( $p = p\mathbf{u}$   $\leftarrow$  unit vector)

$$p \cdot \nabla \delta_y = p \left( \frac{\partial \delta_y}{\partial x} u_1 + \frac{\partial \delta_y}{\partial y} u_2 + \frac{\partial \delta_y}{\partial z} u_3 \right)$$

$$= p \frac{\partial \delta_y}{\partial \mathbf{u}} \quad \text{directional derivative}$$

$p \cdot \nabla \delta_y$  is called the dipole of size  $p$  in  
the direction  $\mathbf{u}$  at the point  $y$ .

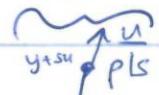
(What is the directional derivative of an arbitrary  $f$ ?  $f'$ )

$$\frac{\partial}{\partial \mathbf{u}} f(\mathbf{x}) = \lim_{s \rightarrow 0} \frac{f(\mathbf{x} + s\mathbf{u}) - f(\mathbf{x})}{s}$$

$$\text{So } p \frac{\partial \delta_y}{\partial \mathbf{u}} = \lim_{s \rightarrow 0} \frac{p \delta_{y+s\mathbf{u}} - p \delta_y}{s}$$

$$= \lim_{s \rightarrow 0} \left( \frac{P}{s} \delta_{y+su} - \frac{P}{s} \delta_y \right)$$

overall charge 0



If at the point  $y+su$  we put charge  $P/s$   
and at the point  $y$  we put charge  $-P/s$ ,  $y = -P/s$   
this is dipole.

then  $\Phi^s$  due to  $\left( \frac{P}{s} \delta_{y+su} - \frac{P}{s} \delta_y \right)$  is the two  $p^+$  charges

$$\Phi_{p,y}^s = \frac{P}{\epsilon_0 s} \left[ \frac{1}{4\pi|x-(y+su)|} - \frac{1}{4\pi|x-y|} \right]$$

$$\lim_{s \rightarrow 0} \Phi_{p,y}^s(x) = -\frac{P}{\epsilon_0} \frac{\partial}{\partial u_x} \Phi_y(x)$$

$$= -\frac{P}{\epsilon_0} \frac{\partial}{\partial u_x} \Phi_y(x)$$

But we know that  $\Phi_{p,y}^d = -\frac{1}{\epsilon_0} \underline{\Phi} \times (\underline{p} \cdot \nabla \delta_y)$  Electrostatic potential

dipole, size  $P$  sitting on the point  $y$ .  
dir?  $\underline{u}$

$$= \frac{1}{\epsilon_0} \underline{p} \cdot \nabla (\underline{\Phi} \cdot \delta_y)$$

$$= \underbrace{\frac{1}{\epsilon_0} (\underline{p} \cdot \nabla \underline{\Phi})}_{\uparrow p \frac{\partial \underline{\Phi}}{\partial u}} \cdot \delta_y$$

↑ convolution  
with  $\delta$  fn mean  
take at a point

Problem: Evaluate  $\Phi_{p,y}^d$  and  $E_{p,y}^d$

OK. Recall  $F_{h,s}(\varphi) = \int_S h(x) \varphi(x) dS_x$   $h \in C_0(S)$



$h$ -surface charge distribution

$$\Phi_{h,s} \quad E_{h,s}$$

Want to prove  $\Phi_{h,s}(x) = \frac{1}{\epsilon_0} \Phi * F_{h,s} = \frac{1}{4\pi\epsilon_0} \int_S \frac{h(y)}{|x-y|} dS_y$ . ... (\*)

$\downarrow \frac{1}{4\pi\epsilon_0|x|}$

$\Rightarrow$

and

$\Rightarrow$

What are  
we  
showing  
here?

$\varphi(y))$   
 $dS_x \leftarrow y \text{ is fixed}$

$$\left[ \int_S h(x) \varphi(x+y) dS_x \right] dy$$

$$\left[ \int_{\mathbb{R}^3} \frac{\varphi(x+y)}{|y|} dy \right] dS_x$$

$$= \frac{1}{4\pi\epsilon_0} \int_S h(x) \left[ \int_{\mathbb{R}^3} \frac{\varphi(z)}{|x-z|} dz \right] dS_x$$

$$= \int_{\mathbb{R}^3} \varphi(z) \underbrace{\left[ \frac{1}{4\pi\epsilon_0} \int_{\mathbb{R}^3} \frac{h(x)}{|x-z|} dS_x \right]}_F dz$$

$$= F_f(\varphi).$$

$$\Phi_{h,s}(x)$$

in (\*) above !!

D

HT  
Answers

↙ how??

Note that  $\Phi_{h,s}$  is continuous across  $S$ .

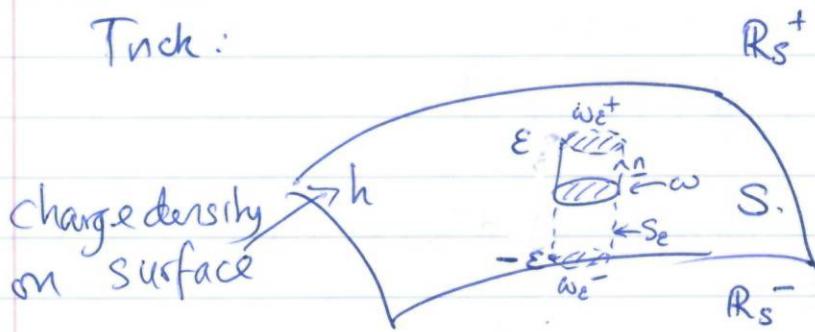
However,  $E_{h,s}$  has a jump discontinuity across  $S$ .

To find  $E$  we need to take  $\nabla$  of  $\Phi$ , and

$\frac{h(y)}{|x-y|}$  becomes like  $\sim \frac{1}{r^2} r dr$  and we

have problems. Hopefully explained now.

Trick:



Consider  $C_w^e = \omega \times (-\epsilon, \epsilon) \underline{n}$

Write Gauss law in integral form for this cylinder.

$$\int_{\partial C_w^e} [E_{h,s}; \underline{v}] dS = \frac{Q(C_w^e)}{\epsilon_0}$$

↑  
normal to  $\partial C_w^e$

$$= \frac{1}{\epsilon_0} \int_{\omega} h dS$$

because only  
charge is in  
the disc

Now let's take a look at LHS:

$w_e^\pm = \{w \pm \epsilon \underline{n}\}$ , the top and bottom of cylinder

$S_\epsilon = \{\partial \omega \times (-\epsilon, \epsilon) \underline{n}\}$ , the surface of the cylinder

$$\rightarrow \int_{\partial C_w^e} = \int_{w_e^+} + \int_{w_e^-} + \int_{S_\epsilon}$$

Take  $\varepsilon \rightarrow 0$ .

$$\int_{S_\varepsilon} E \cdot \underline{v} \, dS \rightarrow 0 \quad \text{since Area}(S_\varepsilon) \rightarrow 0.$$

$$\int_{\omega_\varepsilon^+} E \cdot \underline{v} \, dS = \int_{\omega} [E(x + \varepsilon \underline{n}) \cdot \underline{n}] \, dS_x$$

$$\xrightarrow{\varepsilon \rightarrow 0^+} \int_{\omega} \lim_{\varepsilon \rightarrow 0} E(x + \varepsilon \underline{n}) \cdot \underline{n} \, dS_x$$

$$= \int_{\omega} E^+(x) \cdot \underline{n} \, dS_x$$

it looks



$$\int_{\omega_\varepsilon^-} E \cdot \underline{v} \, dS = - \int_{\omega} [E(x - \varepsilon \underline{n}) \cdot (-\underline{n})] \, dS_x$$

$$\rightarrow - \int_{\omega} E^-(x) \cdot \underline{n} \, dS_x$$

$$\Rightarrow \lim_{\varepsilon \rightarrow 0} \int_{\partial C_\omega^\varepsilon} E_{h,S} \cdot \underline{v} \, dS = \int_{\omega} [E^+(x) - E^-(x)] \cdot \underline{n} \, dS$$

$$\stackrel{\text{def}}{=} \frac{1}{\varepsilon_0} \int h(x) \, dS \quad (\text{the RHS of the eq?})$$

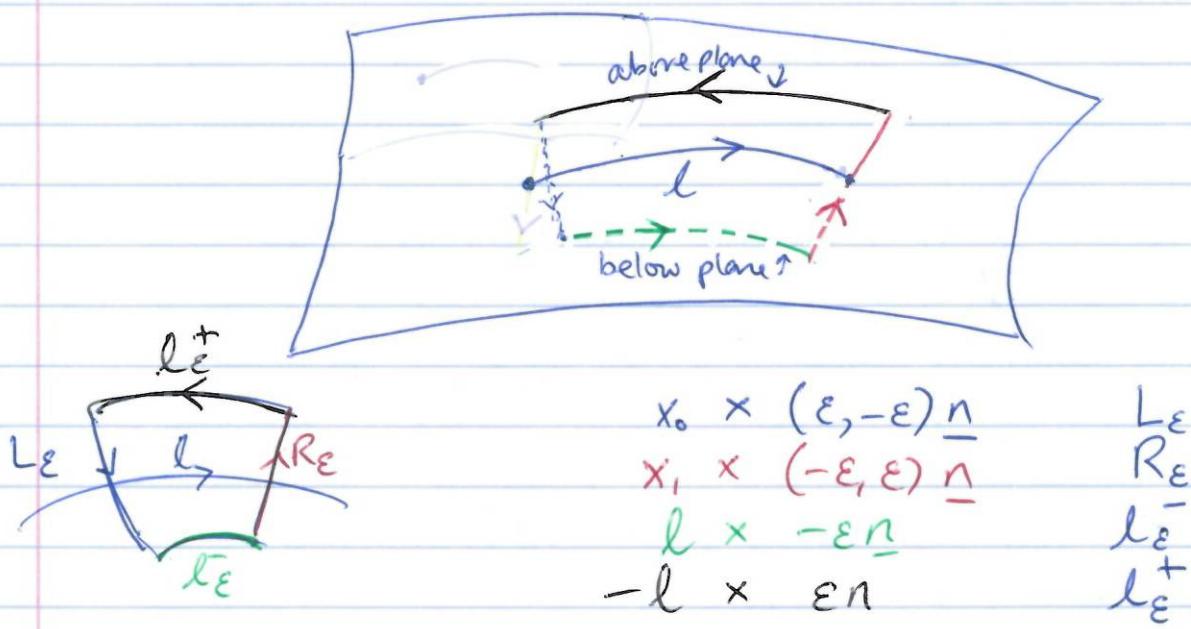
$$\Rightarrow \underbrace{[E^+(x) - E^-(x)] \cdot \underline{n}}_{\text{jump of normal component across } S} = \frac{h(x)}{\varepsilon_0}$$

$\Rightarrow$  the normal component of  $E_{h,S}$  has a jump across  $S$  of size  $\frac{h(x)}{\varepsilon_0}$ .

Theorem

Btw,  
check  
that's it  
ben!

This time take a line instead of a section



$$\begin{aligned} x_0 \times (\epsilon, -\epsilon) \underline{n} \\ x_1 \times (-\epsilon, \epsilon) \underline{n} \\ l \times -\epsilon \underline{n} \\ -l \times \epsilon \underline{n} \end{aligned}$$

$$\begin{aligned} L_E \\ R_E \\ l_E^- \\ l_E^+ \end{aligned}$$

$$\oint_{C_\epsilon} \underline{E} \cdot d\underline{r} = 0$$

$$\oint_{C_\epsilon} = \int_{l_E^-} + \int_{l_E^+} + \int_{L_E} + \int_{R_E}$$

$\rightarrow 0 \because \text{length is } 2\epsilon$

$$\lim_{\epsilon \rightarrow 0} \left[ \int_{l_E^-} + \int_{l_E^+} \right] = \int_l [E^-(x) - E^+(x)] \cdot \underbrace{d\underline{r}}_{\underline{t} dt} = 0$$

$\underline{t}$  - tangential vector to  $S := \underline{t}$

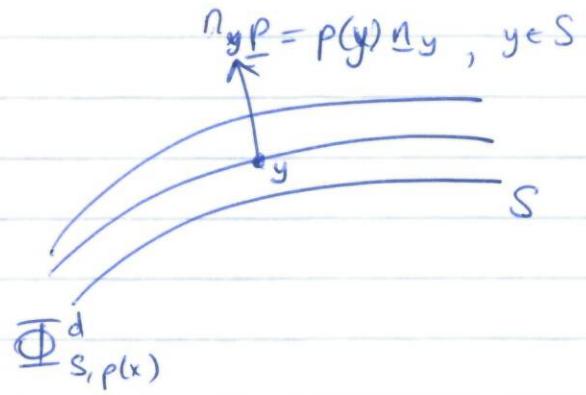
Change  $l$  through any  $x \in S$  (ie. rotate  $l$ ) to have all possible tangential dir's

Then (+) means that  $[E^+(x) - E^-(x)] \cdot \underline{t} = 0$  for any tangential  $\underline{t}$

tang  
part of  
Elect. Field  
 $\Rightarrow$  is cts !!

$\underline{p} \delta_y$  - dipole at  $y$

$$\underline{\Phi}_{p,y}(x) = \int_S \frac{(\underline{p}, \underline{x}-\underline{y})}{|\underline{x}-\underline{y}|^3}$$

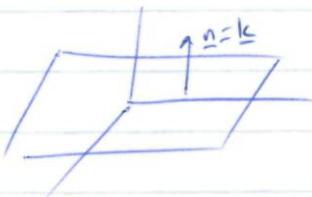


$$\underline{\Phi}_{S,p(x)}^d(x) = \int_S \frac{\underline{p}(y) \cdot (\underline{x}-\underline{y})}{|\underline{x}-\underline{y}|^3} d\underline{S}_y$$

Problem \* :  $S = \{z=0\}$ , the  $xy$  plane.

Assume the magnitude of the dipole is constant

$$p = p_0$$

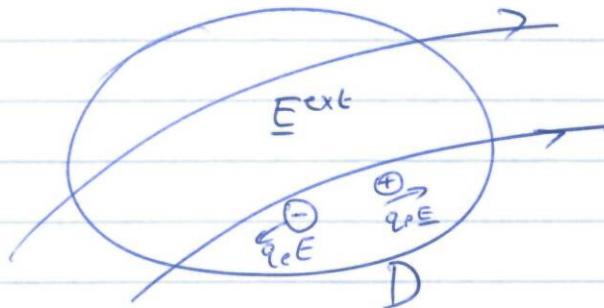


- Find  $\underline{\Phi}(x)$ , the corresponding electrostatic potential of this surface
- Find the jump of  $\underline{\Phi}(x)$  across  $z=0$ .



# CONDUCTORS

A conductor is a very good metal.  
Assume we have a conductor in a domain  $D$ , put into an electrostatic field  $\underline{E}^{\text{ext}}$

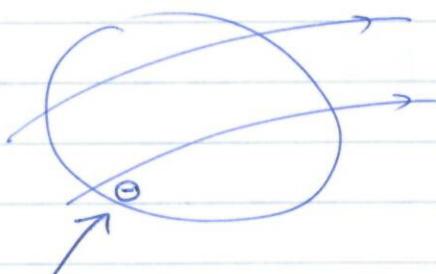


hand waving

→ very charged particles move along  $\underline{E}^{\text{ext}}$   
→ very - - - - -  $-\underline{E}^{\text{ext}}$ ,  
under the action of the electric field.

too heavy  
don't move.

Eventually inside this conductor, the electric field is 0 for statics.



- very charged particles at the boundary, somehow competing with  $\underline{E}^{\text{ext}}$  creating  $\underline{E}=0$ .

So electrons move to the boundary on one side

In conductors, elementary charges can move freely.

As a result, there will be a redistribution of these elementary charges inside  $D$  and the total electric field becomes 0 in  $D$ .

$$\text{As } \underline{\underline{E}}^t = \underline{\underline{E}}^{\text{ext}} + \underline{\underline{E}}$$

As  $\underline{\underline{E}}^t = \underline{\underline{E}}^{\text{total}} = 0$  in  $D \Rightarrow \Phi = \text{const inside } D$ .

By Poisson eqn,  $-\nabla^2 \Phi = \frac{\rho}{\epsilon_0}$ .

$\Rightarrow \rho = 0$  inside  $D$ .

Therefore the charges are concentrated on  $S = \partial D$ .



i.e. we have surface charge  $F_{s,o}$

where  $\sigma$  is the charge distribution over the surface

( $\underline{\underline{E}}^t = \underline{\underline{E}}$ ) notation

Recall [for jumps of electric field across charged surface,]  $[E^+(y) - E^-(y)] \cdot \underline{n}_y = \frac{\sigma(y)}{\epsilon_0}$

$[E^+(y) - E^-(y)] \cdot \underline{t} = 0$  for any tangential vector  $\underline{t}$

But  $E^- = 0$  since  $\underline{\underline{E}} = 0$  inside  $D$

$$\Rightarrow E^+(y) = \frac{1}{\epsilon_0} \sigma(y) \underline{n}_y$$

$\Phi^+(y) = \Phi^-(y)$  because  $\underline{\underline{E}}$  is continuous across the boundary for  $y$  on the surface

and since  $\Phi$  is const on the surface

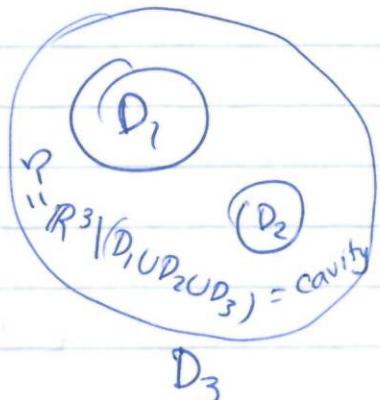
$$\Phi^+(y) = \Phi^-(y)|_{\text{yes}} = \text{const.}$$

Suppose we have 2 conductors that are insulated from each other

$$\text{val of } \Phi \text{ on boundary of } D_1 : \cancel{\Phi|_{D_1} = C_1}$$

$$\cancel{\Phi|_{D_2} = C_2}$$

$$\cancel{\Phi|_{D_3} = C_3}$$



$$\text{for } x \in \overset{\text{cavity}}{\Omega}, \quad \Phi|_{S_1=\partial D_1} = C_1$$

$$\Phi|_{S_2=\partial D_2} = C_2$$

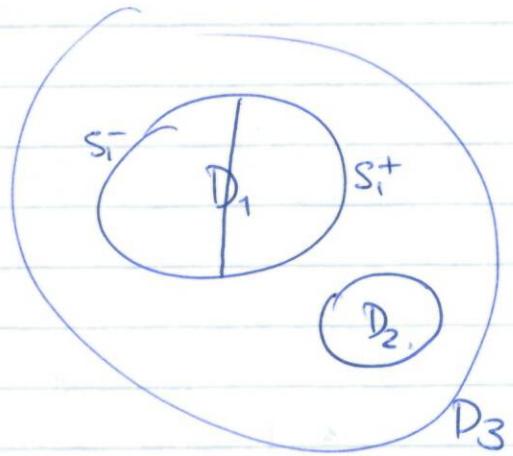
$$\Phi|_{S_3=\partial D_3} = C_3$$

Now divide  $D_1$  by an insulator

Electrostatic potential in two halves can be different.

$$\Phi|_{S_1^+} = C_1^+$$

$$\Phi|_{S_1^-} = C_1^-$$



Keep on dividing  $D_1$  into smaller and smaller portions, each giving a different value of  $\Phi$ .

"By dividing conductors by insulating layers into infinitesimally small pieces, we can obtain

$$\Phi|_{\partial\Omega} = \varphi \text{ arbitrary continuous function}$$

where  $\varphi$  tells you the charge at a point.

Therefore, when considering  $\Phi(x)$ ,  $x \in \Omega$ , we can often assume that when we know

$$\Phi|_{\partial\Omega} = \varphi \text{ given } f! . \quad \begin{matrix} \text{(Dirichlet} \\ \text{bdy condition)} \end{matrix} \quad (1)$$

(e.g. when conductor is grounded,  $\Phi_{\text{conductor}} = 0$ )

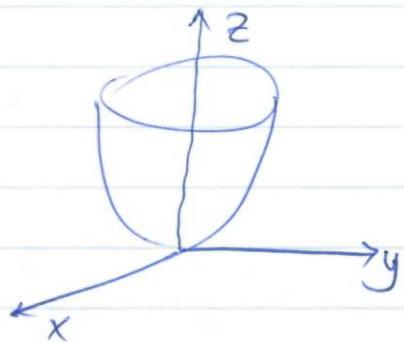
but we know also that  $\Phi$  in  $\Omega$  satisfies Poisson's eq!:

$$-\nabla^2 \Phi = \frac{\rho}{\epsilon_0} \quad \dots \dots \dots \dots \dots \dots \dots \quad (2)$$

(1)+(2) is called in mathematics 'the Dirichlet boundary value problem for Poisson's eq!'

Problem 16:  $\Phi(x) = \begin{cases} \sin x & z \geq x^2 + y^2 \\ \sin x + e^z(z - x^2 - y^2) & z < x^2 + y^2 \end{cases}$

- Find corresponding  $\rho$ , the charge density outside the paraboloid
- Find  $\sigma$ , the surface charge density on ~~the paraboloid~~ the paraboloid  $.z - (x^2 + y^2) = 0.$



Recall that if your surface is given by the eq!:

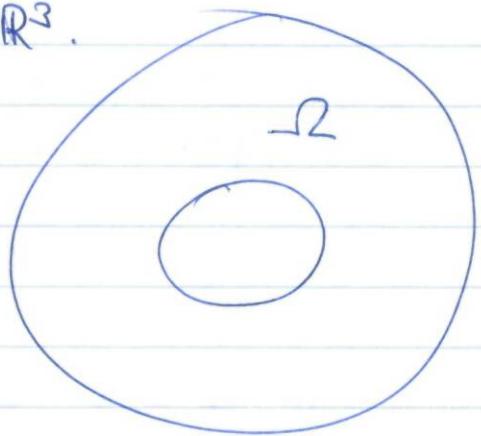
$$S = \{f(x, y, z) = 0\}, \text{ then } n = \frac{\nabla f}{|\nabla f|}$$

# BOUNDARY VALUE PROBLEMS OF ELECTROSTATICS

Say we have domain (cavity)  $\Omega \subset \mathbb{R}^3$ .

We have the following conditions

$$(0) \quad \left\{ \begin{array}{l} \bullet -\nabla^2 \bar{\Phi} = \frac{\rho}{\epsilon_0} \text{ in } \Omega \\ \bullet \bar{\Phi}|_{\partial\Omega} = \varphi, \text{ given} \\ \bullet \bar{\Phi}(x) \rightarrow 0 \text{ if } |x| \rightarrow \infty \quad (\text{not necessary in } \uparrow \text{ this case}) \\ \qquad \qquad \qquad (\text{have it with a bit of salt}) \end{array} \right.$$



Our problem is linear in the following case:

$\bar{\Phi}_1, \bar{\Phi}_2$  solve problems (A) and (B):

$$(A) : \left\{ \begin{array}{l} -\nabla^2 \bar{\Phi}_1 = \rho/\epsilon_0 \\ \bar{\Phi}_1|_{\partial\Omega} = 0 \\ \bar{\Phi}_1 \rightarrow 0 \text{ at } \infty \end{array} \right.$$

$$(B) : \left\{ \begin{array}{l} -\nabla^2 \bar{\Phi}_2 = 0 \quad (\rho=0) \quad (\text{Laplace's eq!}) \\ \bar{\Phi}_2|_{\partial\Omega} = \varphi \\ \bar{\Phi}_2 \rightarrow 0 \text{ at } \infty. \end{array} \right.$$

Then  $\bar{\Phi} = \bar{\Phi}_1 + \bar{\Phi}_2$  solves (0). (Nice, huh!)

Note that (B).1 is Laplace's eq!  $\Rightarrow \bar{\Phi}_2$  is a harmonic f!.

When

$\rho$  is  
delta  
 $f^1$

Now let's look for Green's f<sup>-1</sup> corresponding to the problem (A).  
It is a distribution (actually a discontinuous f<sup>n</sup>) in  $D'(\Omega)$ :  
 $G(x,y)$ ,  $y \in \Omega$  is a fixed parameter  
s.t.

$$(A_p) \left\{ \begin{array}{l} -\nabla_x^2 G(x,y) = \delta(x-y) = \delta_y(x) (\delta f^n \text{ at a pt } y) \\ G(x,y)|_{x \in \partial \Omega} = 0 \quad \text{we can speak about value on the bdy : the} \\ G(x,y) \xrightarrow{x \rightarrow \infty} 0 \quad \text{distribution is from a fn.} \end{array} \right.$$

If  $\Omega = \mathbb{R}^3$  then  $G_0 = \frac{1}{4\pi|x-y|}$   $G_0 \xrightarrow{\Omega \text{ means free space, i.e. } \mathbb{R}^3}$

$$\text{let } \Psi_y(x) = G(x,y) - G_0(x,y).$$

$$\text{Then } -\nabla^2 \Psi_y = -\nabla_x^2 G - (-\nabla_x^2 G_0) \quad (y \text{ is const.})$$

$$= \delta_y(x) - \delta_y(x) = 0.$$

$$\text{So } -\nabla^2 \Psi_y = 0 \text{ in } \Omega.$$

$$\Psi_y|_{x \in \partial \Omega} = \underbrace{G|_{x \in \partial \Omega}}_{\text{but } G \text{ on the bdy is } 0.} - G_0|_{x \in \partial \Omega} = -\frac{1}{4\pi|x-y|} \Big|_{x \in \partial \Omega}$$

$$\Rightarrow \Psi_y(x) \rightarrow 0$$

$$\text{i.e. this is } (B_p) \left\{ \begin{array}{l} -\nabla^2 \Psi_y = 0 \text{ in } \Omega \\ \Psi_y(x)|_{x \in \partial \Omega} = -\frac{1}{4\pi|x-y|} \Big|_{x \in \partial \Omega} \\ \Psi_y(x) \rightarrow 0 \quad x \rightarrow \infty \end{array} \right.$$

Tue pm 7:06  
come for fun

So we have reduced the problem  $(A_p)$  to type  $(B_p)$

Now what about solving  $\Phi$  for  $g \in C_0(\Omega)$ .

$$\begin{aligned}\Phi &= \frac{1}{\varepsilon_0} \int G(x,y) g(y) dy \\ -\nabla_x^2 \Phi &= \frac{1}{\varepsilon_0} \int \underbrace{-\nabla_x^2 G(x,y)}_{J(x-y)} g(y) dy \\ &= \frac{1}{\varepsilon_0} \int \delta(x-y) g(y) dy = \frac{1}{\varepsilon_0} g(x)\end{aligned}$$

but  $\frac{1}{\varepsilon_0} \int G(x,y) g(y) dy = \cancel{\frac{1}{\varepsilon_0} G(g)}$

Lemma : Let  $G(x,y)$  be known,  $x, y \in \Omega$ .  
Then for any  $g \in C_0(\Omega)$ ,

$$\Phi^g(x) = \frac{1}{\varepsilon_0} \int \Omega G(x,y) g(y) dy$$

solves  $\left\{ \begin{array}{l} -\nabla^2 \Phi^g = \frac{1}{\varepsilon_0} g \\ \Phi^g|_{\partial\Omega} = 0 \end{array} \right.$

Proof precedes the lemma.

let's summarise:

We had

$$\left\{ \begin{array}{l} -\nabla^2 \Phi = \frac{g}{\epsilon_0} \\ \Phi|_{\partial\Omega} = 0 \\ \Phi \rightarrow 0 \text{ at } \infty \end{array} \right. \quad \text{Poisson eq:}$$

Reduced to finding the Green's f?

$$\left\{ \begin{array}{l} -\nabla_x^2 G = \delta_y \quad y \in \Omega \\ G|_{\partial\Omega} = 0 \\ G(x, y) \rightarrow 0 \text{ as } x \rightarrow \infty \end{array} \right.$$

and then since  $G(x, y) = G_0(x, y) + \Psi_y(x)$ , reduces to  
find  $\Psi$  s.t.

Special  
Dirichlet  
boundary value  
problems for  
Laplace's eq:

$$\left\{ \begin{array}{l} -\nabla_x^2 \Psi_y(x) = 0 \quad y \in \Omega \\ \Psi_y(x)|_{x \in \partial\Omega} = -\frac{1}{4\pi|x-y|} \\ \Psi_y(x) \rightarrow 0 \text{ as } x \rightarrow \infty. \end{array} \right.$$

## Dirichlet boundary value problem for Laplace's eq?

$$\left\{ \begin{array}{l} \nabla^2 u = 0 \text{ in } \Omega \\ u|_{\partial\Omega} = \varphi \in C(\partial\Omega) \\ u(x) \rightarrow 0 \text{ as } |x| \rightarrow \infty \end{array} \right.$$

$u$  instead of  $\Phi$  so as not to imply  $\mathbb{R}^3$ : this result holds true for any domain  $\Omega \subset \mathbb{R}^n$ .

$\nabla^2 u = 0$  in  $\Omega \Leftrightarrow u(x)$  is a harmonic f<sup>n</sup> in  $\Omega$ .

Problem\*: Assume  $u \in C^2(\bar{\Omega})$ , is  $u$  harmonic.

Show That  $\int_{\partial\Omega} \underbrace{\frac{\partial u}{\partial n}}_{\text{normal distribution}} dS = 0$ .

(hint: use Green's formula)

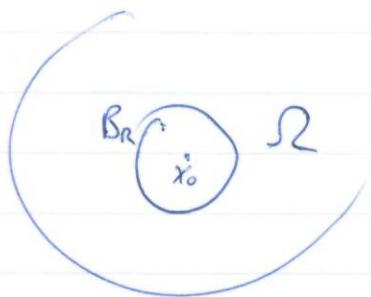
## Thm: (Mean Value Theorem)

Let  $u$  be harmonic in  $\Omega \subset \mathbb{R}^3$  (ie  $\nabla^2 u = 0$ ) and  $B_R(x_0) \subset \Omega$ .

Then  $u(x_0) = \frac{1}{4\pi R^2} \int_{\partial B_R(x_0)} u(x) dS_x$

s. area of sphere  $\partial B_R(x_0) \quad S_R(x_0)$

"mean value"



$$u(x_0) = \frac{1}{2\pi R} \int_{\partial B_R(x_0)} u(x) dS_x$$

$G(x) = \frac{1}{4\pi R^3} \int_{B_R(x_0)} u(x') dx'$

Proof of 3D case:

$$0 = \int_{B_R(x_0)} \nabla^2 u \left( \frac{-1}{4\pi|x-x_0|} \right) dx$$

$$\begin{aligned} \text{by Green's formula} &= \int_{B_R(x_0)} u \underbrace{\nabla^2 \left( \frac{-1}{4\pi|x-x_0|} \right)}_{\delta(x-x_0)} dx + \int_{S_R(x_0)} \frac{\partial u}{\partial n} \left( \frac{-1}{4\pi|x-x_0|} \right) dS \\ &\quad + \int_{S_R(x_0)} u \underbrace{\frac{\partial}{\partial n} \left( \frac{1}{4\pi|x-x_0|} \right)}_{u(x_0)} dS \end{aligned}$$

$$= u(x_0) - \frac{1}{4\pi R} \int_{S_R(x_0)} \frac{\partial u}{\partial n} dS + \int_{S_R(x_0)} u \frac{\partial}{\partial n} \left( \frac{1}{4\pi|x-x_0|} \right) dS$$

$$0 = u(x_0) + \frac{1}{4\pi} \int_{S_R(x_0)} u(x) \underbrace{\frac{\partial}{\partial n} \left( \frac{1}{|x-x_0|} \right)}_{\frac{\partial}{\partial \sigma} \left( \frac{1}{r} \right) \Big|_{r=|x-x_0|}} dS$$

$$\underbrace{- \frac{1}{r^2}}$$

$$\Rightarrow u(x_0) = \frac{1}{4\pi} \int_{S_R(x_0)} u(x) \underbrace{\frac{1}{|x-x_0|^2}}_{R^2} dS$$

$$= \frac{1}{4\pi R^2} \int u(x) dS \quad \square$$

Problem\* Prove for 2D case.

$$\begin{aligned}
 \int_{B_r(x_0)} u(x) dx &= \int_{r=0}^r \left( \int_{S_r(x_0)} u(x) dS \right) dr \\
 &= \int_{r=0}^r 4\pi r^2 u(x_0) dr \\
 &= 4\pi u(x_0) \frac{r^3}{3}
 \end{aligned}$$

$$u(x_0) = \frac{1}{\frac{4\pi}{3} r^3} \int_{B_r(x_0)} u(x) dx$$



'Chalk'

Problem: Show MVT in this case:

$$u(\underline{x}_0) = \frac{1}{\frac{4\pi}{3}r^3} \int_{B_R(\underline{x}_0)} u(\underline{x}) dV \quad (\text{Corollary apparently.})$$

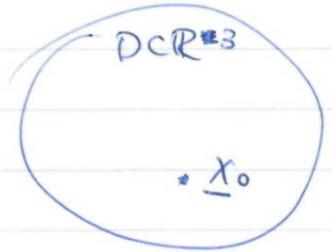
Thm: Maximum Principle

Bounded domain  $D \subset \mathbb{R}^3$ ,

Let  $u$  b.s.t.  $\nabla^2 u = 0$

$\rightarrow u \in C^2(D^{\text{int}}) \cap C(D)$

i.e.  $u$  harmonic and  $D$ -bounded.



$$\text{Let } M = \max_{\underline{x} \in \partial D} u(\underline{x})$$

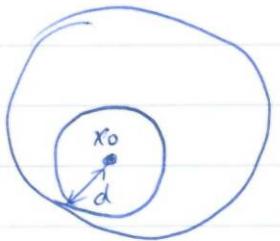
Then  $u(\underline{x}) \leq M, \forall \underline{x} \in D$ .

~~Moreover~~ if  $D$  is connected

Moreover,  $\exists \underline{x}_0 \in D^{\text{int}}$  s.t.  $u(\underline{x}_0) = M$ ,  
then  $u(\underline{x}) \equiv M, \underline{x} \in D$

Proof: Assume that  $\exists \underline{x}_0 \in D^{\text{int}}$   
s.t.  $u(\underline{x}_0) = A = \max_{\underline{x} \in D} u(\underline{x})$ .

Let  $d = \text{dist}(\underline{x}_0, \partial D) > 0$ .



Consider  $B_d(\underline{x}_0) \subset D$ .

By Problem 'Chalk'

$$A = u(\underline{x}_0) = \frac{1}{\frac{4\pi}{3}d^3} \int_{B_d} u(\underline{x}) dV$$

We have  $u(\underline{x}) \leq A$  in  $B_d$ .

$$\text{Therefore } \frac{1}{\frac{4\pi}{3}d^3} \int_{B_d} u(\underline{x}) d\underline{x} \leq A \cdot \underbrace{\frac{1}{\frac{4\pi}{3}d^3} \int dV}_{1 \left( \frac{\text{vol}}{\text{vol}} \right)!!} = A$$

If  $u(\underline{x}) < A$  in some  $\underline{y} \in B_d$  (and  $\therefore$  nearby),

$$\text{then } \frac{1}{\frac{4\pi}{3}d^3} \int_{B_d} u(\underline{x}) d\underline{x} < A$$

Therefore, assuming that  $\exists \underline{y} \in B_d$  s.t.  $u(\underline{y}) < A$ , we get

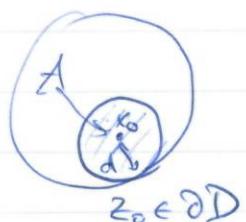
$$A = u(\underline{x}_0) = \frac{1}{\frac{4\pi}{3}d^3} \int_{B_d} u(\underline{x}) d\underline{x} < A. \quad \#$$

$\Rightarrow u(\underline{x}) \equiv A$  inside  $B_d$ .

(Proof of descent)

As  $d = \text{dist}(\underline{x}_0, \partial D) \rightarrow S_d \cap \partial D \neq \emptyset$

$$\Rightarrow \exists \underline{z}_0 \in \partial D \text{ s.t. } u(\underline{z}_0) = A = \max_{\underline{x} \in D} u(\underline{x})$$



$$\text{Thus } \max_{\underline{z} \in \partial D} u(\underline{z}) = \max_{\underline{x} \in D} u(\underline{x}) \\ \text{''} M = \text{''} A.$$

1st part  $\square$ .

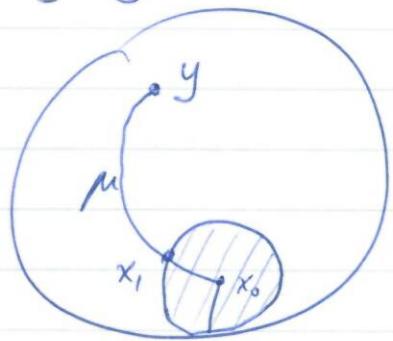
$$\text{Now, } u(\underline{x}_0) = A = \max_{x \in D} u(x).$$

Take any  $y \in D$  and connect  $\underline{x}_0$  and  $y$  by a curve  $\mu$  lying in  $D^{\text{int}}$ .

$$\text{Then } \text{dist}(\mu, \partial D) = g > 0$$

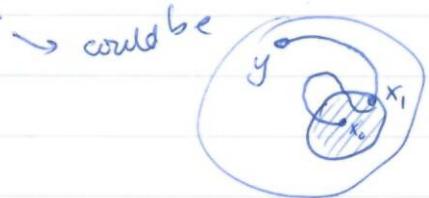
~~Let  $\underline{x}_0 \in D$~~

Assume  $y$  is not in the ball, since  
if  $y \in B_d \rightarrow u(y) = A$ .



Take  $\underline{x}_1 = \text{the last point on } \mu \text{ in } B_d$ .

$$\text{Then } u(\underline{x}_1) = A = \max_{x \in D} u(x).$$



So then take a ball of radius  $g$  ( $\because$  it doesn't touch the bdy).

Consider  $B_g(\underline{x}_1)$ . The same arguments show that  
 $u(x) = A$  in  $B_g(\underline{x}_1)$ .

We continue the process until ~~unless~~  $y \in B_g(\underline{x}_n)$ .  
We need only a finite no. of steps as  $\mu$  has finite length.

'Coke'

Problem: Prove, as a corollary, the minimum principle thm,

$$\min_{z \in \partial D} (u(z)) = \min_{x \in D} u(x).$$

[Can rewrite or  
say  $\tilde{u}(x) = -u(x)$ ]

Def<sup>n</sup>:  $x_0$  is a local <sup>maximum</sup> <sup>minimum</sup> of  $u(x)$  if  
 $\exists B_\epsilon(x_0)$  s.t.

$$u(x_0) = \sup_{x \in B_\epsilon(x_0)} u(x)$$

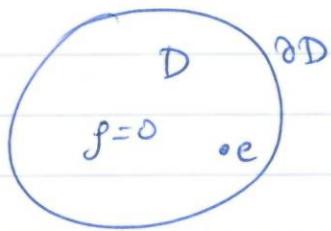
Strong version of the theorem: If  $D$  is connected and  
 $u(x) \neq \text{const}$  and  $\nabla^2 u = 0$  then  $u$  has no local  
maxima and minima inside  $D^{\text{int}}$ . Not proved.

Now, gentlemen, we move to physics.

Let's have a domain  $D$  with no charges inside  
 $\nabla^2 \Phi = 0$  in  $D$ .

Introduce a point charge  $e$ .

Then  $e\Phi$  is <sup>electrostatic</sup> potential energy of  
the charge  $e$ .



Now recall if we have  $\Phi$ , we have  $E$  s.t.  $E = -\nabla \Phi$ .

Then there is a force  $F = eE$ .

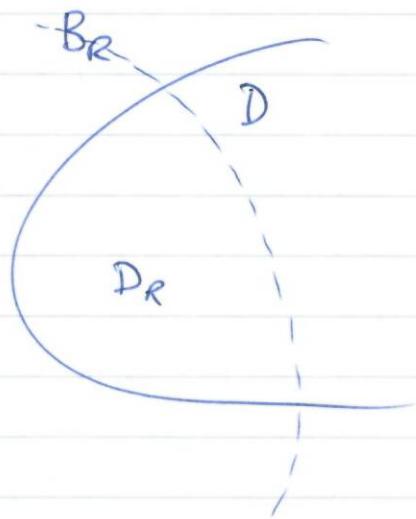
↓  
this electrostatic force tries to decrease  
the electrostatic energy of  $e$ .

Since  $\min e\Phi$  is achieved on  $\partial D$  (by cor. (oke)),  
the charge ends up on the boundary.

If you get  
out of this  
window  
you will  
fall down

## Unbounded domain

Let  $\begin{cases} \nabla^2 u = 0 & \text{in } D \\ u|_{\partial D} = 4 \\ u \rightarrow 0 \text{ as } x \rightarrow \infty \end{cases}$ .



Let  $D_R = D \cap B_R$

$$u(x) \Big|_{x \in D_R} \leq \max_{z \in \partial D_R} u(z) \quad \text{by maximum principle}$$

$$\partial D_R = (\partial D \cap B_R) \cup (S_R \cap D)$$

$$\leq \max \left[ \max_{z \in \partial D \cap B_R} u(z), \max_{x \in S_R \cap D} u(x) \right]$$

↑      ↓  
smaller set  
should be larger set

$$\leq \max \left[ \max_{z \in \partial D} u(z), \max_{x \in S_R \cap D} u(x) \right]$$

↑      ↓  
does not depend on R.      as R \rightarrow \infty

0 since  $u \rightarrow 0$  as  $x \rightarrow \infty$ .

$$\Rightarrow u(x) \Big|_{x \in D} \leq \max \left[ \max_{z \in \partial D} u(z), 0 \right]$$

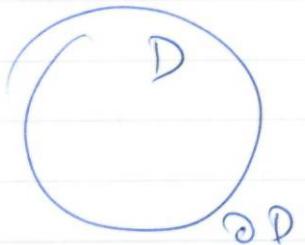
Also use the minimum principle

$$u(x) \Big|_{x \in D} \geq \min \left[ \min_{z \in \partial D} u(z), 0 \right]$$

So if  $D = \mathbb{R}^3$ ,  $\partial D = \emptyset \Rightarrow u(x) \Big|_{x \in \mathbb{R}^3} = 0$ .

Now, let us have a bounded domain

$$\begin{array}{l} \text{Dirichlet} \\ \text{b.c.} \\ ??(\text{check})?? \end{array} \quad \left\{ \begin{array}{l} \nabla^2 u = 0 \text{ in } D \\ u|_{\partial D} = \varphi \in C(\partial D) \end{array} \right.$$



Claim: For any bounded  $D$  and any  $\varphi \in C(\partial D)$ ,  
 $\exists$  a unique  $u^\varphi$  which solves the Dirichlet b.c.s.

Proof: not given, but proven using potential theory for  
 Dirichlet problems for Laplace's eqn.

Note:  $u^\varphi \in C^2(D^{\text{int}}) \cap C(D)$ .

But we can prove uniqueness.

Proof of uniqueness: Assume we have  $u_1^\varphi, u_2^\varphi$  which solve  
 the Dirichlet b.c.s.

$$\text{Let } u = u_1^\varphi - u_2^\varphi \Rightarrow \begin{cases} \nabla^2 u = 0 \\ u|_{\partial D} = 0 \end{cases}$$

By maximum principle,  $u(x) \leq 0 \quad x \in D$

By minimum principle,  $u(x) \geq 0 \quad x \in D$

$$\Rightarrow u \equiv 0 \text{ and } u_1^\varphi = u_2^\varphi \quad \square.$$

What happened to distributions?

let's look at  $\mathcal{D}'_\varphi(D) \subset \mathcal{D}'(D)$ , ie. those which have a 'meaningful' restriction on  $\partial D$  which is equal to  $\varphi$ . ~~If~~

If  $u \in \mathcal{D}'_\varphi(D)$  is harmonic,  $\nabla^2 u = 0$   
 $\Rightarrow u \in C^\infty(D^{\text{int}})$ .



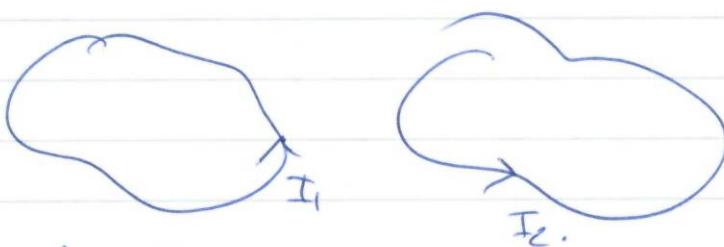
# MAGNETOSTATICS

→ 1980, German

guy Orsted found  
that electric field  
current, it effects  
magnetic dipole, ie  
 $\exists$  a force which acts  
on magnets.

## Biot-Savart Law

1820 - Biot-Savart



two electric circuits.

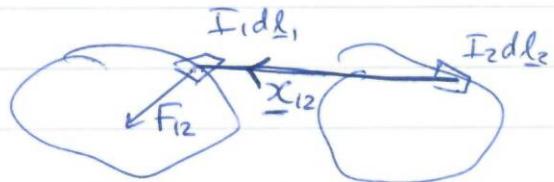
Turn on  $I_1$

[8]

Turn on  $I_2$ . Then  $\exists$  a force applied to the first circuit.

Take small part of each circuit

$$I_1 d\underline{l}_1 \quad I_2 d\underline{l}_2$$



They found the relation

$$F_{12} = \frac{\mu_0}{4\pi} \frac{(I_1 d\underline{l}_1) \times (I_2 d\underline{l}_2 \times \underline{x}_{12})}{|x_{12}|^3} = \text{force by 2 on 1}$$

## Biot-Savart Law

$$\underline{B}(x) = \frac{\mu_0}{4\pi} \frac{I_2 d\underline{l}_2 \times (x - x_2)}{|x - x_2|^3}$$

"magnetic field"

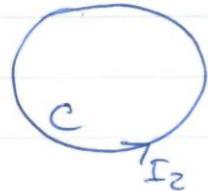
in Russian "magnetic flux density"  
and  $H$  is the magnetic field

Suppose we have a flow of charges  $\underline{J}(y)$

$$\text{Then } \underline{B}(\underline{x}) = \frac{\mu_0}{4\pi} \int_{R^3} \frac{\underline{J}(y) \times (\underline{x} - \underline{y})}{|\underline{x} - \underline{y}|^3} dV_y \quad \dots \dots \dots \quad (*)$$

$$\underline{J}(y) = \dot{y}(s) \delta_{I_2, C} \quad \begin{matrix} \leftarrow \text{like } \delta_{h, z} \\ \leftarrow I_2 \text{ is constant} \end{matrix} \quad \leftarrow \text{Prob. 146}$$

$\uparrow$  tangent to curve



$$C = \{y = y(s)\}$$

$$\dot{y}(s) ds = d\underline{l} \quad \text{convolution of cross products}$$

$$\text{then } \underline{B}(\underline{x}) = \frac{\mu_0}{4\pi} \int_{R^3} \underline{J} * \nabla \underline{\Phi}$$

(vector valid convolution  
valid for each component of  $\underline{J}_i$ )

Let us have an electric field  $\underline{E}(\underline{x})$ . If we have a charge  $q$ , in electrostatics

$$\underline{F}(\underline{x}) = q \underline{E}(\underline{x}).$$

If  $g(\underline{x})$  is an electric charge distribution (ie. we don't have pt charges but continuous instead).

$$\text{Then } \underline{F}^{\text{total}} = \int_D g(\underline{x}) \underline{E}(\underline{x}) dV$$

$\nwarrow$  not  $J(x)$  which caused  $B$  initially.

Now suppose we have a body with some  $\widetilde{\underline{J}}(\underline{x})$  inside.

$$\text{Then } \underline{F}_{\text{mag}}^{\text{total}} = \int_D \widetilde{\underline{J}}(\underline{x}) \times \underline{B}(\underline{x}) dV$$

"absorbed?"

$\nwarrow$  Amper's law of magnetic forces

Ampère was a big boy; he had lots of laws.

Ampère's law, analogous to Gauss' law

~~Let  $\underline{J}(\underline{y}) \in \mathcal{D}(\mathbb{R}^3)$~~

Look at (\*).

Prob: Show that

$$\nabla \times (\underline{a} f(\underline{x})) = -\underline{a} \times \nabla f$$

Note  $-\frac{(\underline{x}-\underline{y})}{|\underline{x}-\underline{y}|^3} = \nabla \frac{1}{|\underline{x}-\underline{y}|}$

$\underline{J}(\underline{y})$  is constant w.r.t.  $\underline{x}$ . Let  $\underline{J}(\underline{y}) \in \mathcal{D}(\mathbb{R}^3)$

~~These (x) because~~ ~~so look at~~ Then (\*) becomes

$$\underline{B}(\underline{x}) = \cancel{\text{B.G.}} \frac{\mu_0}{4\pi} \nabla \times \int_{\mathbb{R}^3} \frac{\underline{J}(\underline{y})}{|\underline{x}-\underline{y}|} dV_y$$

so  $\underline{B}$  is the curl of some magnetic field  
and remember  $\underline{E}$  was the gradient of  $-\Phi \Rightarrow \nabla \times \underline{E} = 0$ .

$$\underline{B} = \nabla \times \left( \frac{\mu_0}{4\pi} \int_{\mathbb{R}^3} \frac{\underline{J}(\underline{y})}{|\underline{x}-\underline{y}|} dy \right)$$

$$\Rightarrow \nabla \cdot \underline{B} = 0 \quad \text{since } \operatorname{div}(\operatorname{curl}(\cdot)) = 0.$$

What is  $\nabla \times \underline{B}$ ?

Problem: show that  $\nabla \times \nabla \times \underline{F} = \nabla(\nabla \cdot \underline{F}) - \nabla^2 \underline{F}$   
vector field

$$\begin{aligned}
 S_0 \cdot \nabla \times \underline{B} &= \frac{\mu_0}{4\pi} \int \left[ \nabla_x \times \nabla_x \left( \frac{\underline{J}(y)}{|x-y|} \right) \right] dV_y \\
 &= \frac{\mu_0}{4\pi} \underbrace{\int \left[ \nabla_x \left( \nabla_x \cdot \frac{\underline{J}(y)}{|x-y|} \right) \right] dV_y}_B \\
 &\quad - \underbrace{\frac{\mu_0}{4\pi} \int \left[ \nabla_x^2 \left( \frac{\underline{J}(y)}{|x-y|} \right) \right] dV_y}_A \\
 A &= - \frac{\mu_0}{4\pi} \int_{\mathbb{R}^3} \left[ \underline{J}(y) \nabla_x^2 \left( \frac{1}{|x-y|} \right) \right] dV_y \\
 &= \mu_0 \int_{\mathbb{R}^3} \underline{J}(y) \delta(x-y) dV_y \\
 &= \mu_0 \underline{J}(x)
 \end{aligned}$$

Let's prove:

$$\begin{aligned}
 B &= \int \left[ \nabla_x \left( \nabla_x \cdot \frac{\underline{J}(y)}{|x-y|} \right) \right] dV_y \\
 &= \nabla_x \left[ \int \nabla_x \cdot \frac{\underline{J}(y)}{|x-y|} dV_y \right]
 \end{aligned}$$

[Problem: show  $\nabla \cdot (\underline{a} f(x)) = \underline{a} \cdot \nabla f$ ]

$$\begin{aligned}
 &= \nabla_x \int \underline{J}(y) \cdot \nabla_x \left( \frac{1}{|x-y|} \right) dV_y \\
 &= - \nabla_x \int \underline{J}(y) \cdot \nabla_y \left( \frac{1}{|x-y|} \right) dV_y
 \end{aligned}$$

[Problem: show  $\int F \cdot \nabla F dV = - \int (\nabla \cdot F) F dV$ ]

hint: use div. thm.  $\rightarrow \nabla \cdot (FF) = F \cdot \nabla F + (\nabla \cdot F)F$

$$= +\nabla_x \cdot \left[ \int (\nabla \cdot \underline{J})(y) \cdot \frac{1}{|x-y|} dV_y \right] \dots \dots \dots \text{(*)}$$

[ Claim: in magnetostatics,  $\nabla \cdot \underline{J} = 0$ . ]

because of  
philosophy  
of life.  
Nothing  
comes  
from  
nothing.

$$= 0$$

$$\rightarrow \nabla \cdot \underline{B} = 0 \quad \square$$

"Ampere's law of electro  
magneto  
statics"

$$\rightarrow \nabla \times \underline{B} = \mu_0 \underline{J}(x)$$

Proving the claim

Not  
dust  
ex  
machina.  
Else we  
should  
shut  
our doors  
and go  
to  
church.

Take a region  $V$  and look for total charge in the region

$$Q^{\text{total}}(t) = \int_V q(x,t) dV_x$$

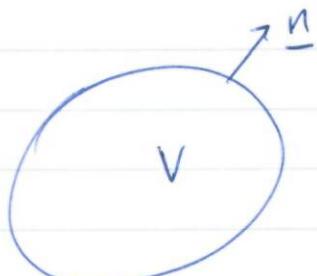
We believe charge doesn't appear from nothing. If it changes, charge comes in and out.

If  $Q$  as a f" of time changes, there should be an inflow/outflow of charge in the region.

If  $\frac{\partial Q}{\partial t} \neq 0$ , there should be current flux through  $S = \partial V$

But this current flux is

$$\int_S \underline{J}(x,t) \cdot \underline{n} dS$$



Thus the continuity law is

$$\int_V \frac{\partial \rho}{\partial t} (x, t) dV = - \int_S \underline{J}(t) \cdot \underline{n} dS$$

↑ (minus sign if  $\rho$  increases,  
 $\underline{J}$  points inwards)

by div. thm,  $= - \int_V \nabla \cdot \underline{J}(t) dV$

Since  $V$  is arbitrary,

$$\frac{\partial \rho}{\partial t} = - \nabla \cdot \underline{J}(x, t)$$

ie.  $\underbrace{\frac{\partial \rho}{\partial t} + \nabla \cdot \underline{J}}_0 = 0$  continuity eq<sup>n</sup>.

We are talking about stationary, so  $\frac{\partial \rho}{\partial t} = 0$   
↑ time!!

$\nabla \cdot \underline{J} = 0.$

Ampère's law

So we have the 4 laws of electromagnetostatics:

$$\left. \begin{array}{l} \text{diff. form} \\ \nabla \cdot \underline{E} = \frac{g}{\epsilon_0} \text{ (Gauss)} \\ \nabla \times \underline{E} = 0 \\ \nabla \times \underline{B} = \mu_0 \underline{J} \text{ (Ampère)} \\ \nabla \cdot \underline{B} = 0 \end{array} \right\}$$

$$\left. \begin{array}{l} \text{int. form} \\ \int_{S=\partial V} \underline{E} \cdot \underline{n} dS = \frac{1}{\epsilon_0} \int_V g dV \\ \oint_C \underline{E} \cdot d\underline{r} = 0 \\ \oint_S \underline{B} \cdot \underline{n} dS = 0 \end{array} \right\}$$

### Dynamical case

$$\nabla \cdot \underline{J} \neq 0, \text{ instead } \nabla \cdot \underline{J} = - \frac{\partial \phi}{\partial t}.$$

$$\nabla \times \underline{B} = - \frac{\mu_0}{4\pi} \nabla_x \frac{\partial}{\partial t} \underbrace{\int \frac{g(\underline{y}, t)}{|\underline{x} - \underline{y}|} dV_y}_{\text{depends on } \underline{x}, t.} + \mu_0 \underline{J}(x) \quad \begin{matrix} \text{from} \\ (*) \end{matrix} \quad \begin{matrix} \cdots \cdots \cdots \\ (+) \end{matrix}$$

$$\text{But what is } \frac{1}{4\pi\epsilon_0} \int \frac{g(\underline{y}, t)}{|\underline{x} - \underline{y}|} dV_y ?$$

what is that  
what is that?

$$= \underline{\Phi}^s(x, t) !!$$

$$(+) = \epsilon_0 \mu_0 \frac{\partial}{\partial t} (-\nabla_x \underline{\Phi}^s) + \mu_0 \underline{J}(x)$$

$$= \epsilon_0 \mu_0 \frac{\partial}{\partial t} \underline{E}(x, t) + \mu_0 \underline{J}(x).$$

$$\Rightarrow \nabla \times (\mu_0^{-1} \underline{B}) = \frac{\partial}{\partial t} (\epsilon_0 \underline{E}) + \underline{J}$$

Maxwell  
Ampère  
eq.  
in vacuum

What are  $\mu_0, \epsilon_0$ ? In vacuum they are just some constants (but specific to vacuum)

If we go to the brick,  $\epsilon_0, \mu_0$  will change.



$\epsilon_0, \mu_0$  are matrices, actually different for each material. They depend on  $x, t$ .

Sometimes it goes to 10,000.

Sometimes  $\underline{H} := \mu_0^{-1} \underline{B}$

↑  
"magnetic field" or "mag. flux density"

field strength

$\underline{D} := \epsilon_0 \underline{E}$

↑  
"electric displacement in vacuum"

and the equation is even easier.

Why call  $\underline{H}$  magnetic field instead of  $\underline{B}$ ?

Recall  $\nabla \cdot \underline{E} = \frac{\rho}{\epsilon_0}$  but this is bad since  $E$  is a matrix

$\nabla \cdot \underline{D} = \rho$  better.

and recall  $\nabla \cdot \underline{B} = 0$ .

Recall  $\nabla \times \underline{E} = 0$ . for statics. We need to change this  
for dynamics.

Max-Amp says  $\nabla \times \underline{H} = \frac{\partial}{\partial t} \underline{D} + \underline{J}$

Max-Amp.  
eq?  
(not nec. in  
vacuum!!)

where  $\underline{D} = \epsilon \underline{E}$  } constitutive  
 $\underline{B} = \mu \underline{H}$  } relation

How does  $\nabla \times \underline{E} = 0$  change in dynamics, ~~giving~~  
we call the new version

In 1830s, Faraday made the carried out his famous  
expt. He takes a closed piece of wire



and he produced mag. flux through it by placing  
another wire with current next to it. (by Bio-Sav. law)



If you change  $\underline{B}$ , there appears a current in the wire  
We change flux through  $\underline{B}$  which creates a force through  
it  $\propto$  to the force. What produces forces? E. fields!

So he concluded when you change through time an  
electric field you change a mag. field.

After all these fantastic experiments, he found

$$\nabla \times \underline{E} = - \frac{\partial \underline{B}}{\partial t} \quad \xrightarrow{\text{Max. Faraday}} \text{Max. Faraday}, \text{ eq?}$$

So we have

- "Adam: Where are horses?"
- "Stables!"

$$\nabla \cdot \underline{D} = \rho$$

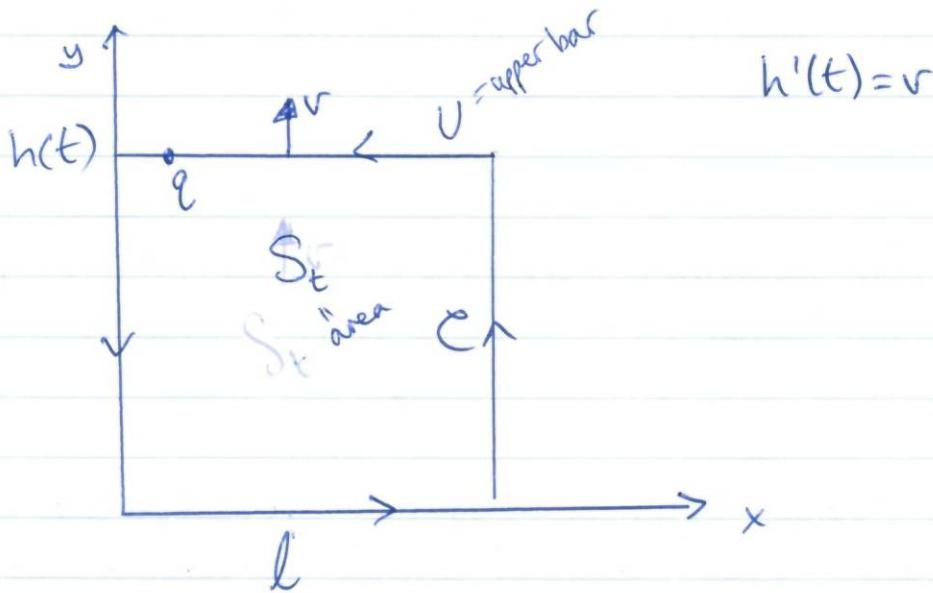
$$\nabla \cdot \underline{B} = 0$$

$$\nabla \times \underline{E} = -\frac{\partial \underline{B}}{\partial t}$$

$$\nabla \times \underline{H} = \frac{\partial}{\partial t} \underline{D} + \underline{J}$$

And now, gentlemen and ladies, we will derive from Ampère, Max-Far. law.

Let us have a circuit



Let  $\underline{B} = B_0 \hat{k}$ ,  $B_0$  is magnetic field of the Earth.

Take a charge  $q$  along the bar at height  $h(t)$ .

$$\underline{J} = q \underline{v} = q v \hat{j}$$

Then by Ampère's law of forces,

$$\underline{F} = q \underline{v} \times \underline{B}$$

(usually integrate but  
this is deltaf^n: one point)

$$= q v B_0 \hat{l}$$

but we know

$$\underline{F} = q \underline{E}$$

$$\Rightarrow \underline{E} = v B_0 \hat{\underline{i}}$$

$$= \underline{v} \times \underline{B}$$

Let us look at  $\oint_{C(t)} \underline{E} \cdot d\underline{s}$ .

$$\oint_{C(t)} \underline{E} \cdot d\underline{s} = \int_U v B_0 \hat{\underline{i}} \cdot d\underline{s}$$

$$= -v B_0 l$$

- - - - - (1)

$$\int_{S_t} \underline{B} \cdot \underline{n} dS = \int_{S_t} \underline{B} \cdot \hat{\underline{k}} dS$$

$$= \int_{S_t} B_0 \hat{\underline{k}} \cdot \hat{\underline{k}} dS$$

$$= B_0 \int_{S_t} dS = B_0 \text{Area}(S_t)$$

$$= B_0 l h(t)$$

$$\rightarrow \frac{\partial}{\partial t} \int_{S_t} \underline{B} \cdot \underline{n} dS = \frac{d}{dt} B_0 l h(t)$$

$$= B_0 l v$$

- - - - - (2)

$$\rightarrow - \oint_{C(t)} \underline{E} \cdot d\underline{s} = \frac{\partial}{\partial t} \int_{S_t} \underline{B} \cdot \underline{n} dS \quad \text{by } (1) = (2)$$

$$\text{or } - \oint_{C(t)} \underline{E}(\underline{t}) \cdot d\underline{s} = \frac{\partial}{\partial t} \int_{S_t} \underline{B}(\underline{t}) \cdot \underline{n} dS$$

Now we say this charge is not  $\therefore$  changing area, it's  $\therefore$  changing flux  
 Thus,

$$-\oint_{\mathcal{C}} \underline{E}(\underline{x}, t) \cdot d\underline{r} = \frac{\partial}{\partial t} \int_S \underline{B}(t) \cdot \underline{n} dS$$

$\parallel$  Stokes

$\parallel \because S$  not dep on  $t$

$$-\oint_S \underline{B} \cdot (-\nabla \times \underline{E}) \cdot \underline{n} dS = \int_S \frac{\partial \underline{B}}{\partial t} \cdot \underline{n} dS$$

$$\text{arbitrary } \Rightarrow \nabla \times \underline{E} = -\frac{\partial \underline{B}}{\partial t}$$

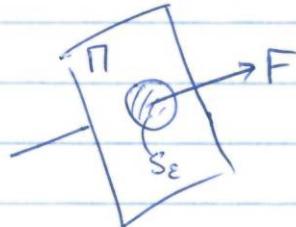
why is this step valid? It's a version of DuBois-Reymond:

$$\int (\nabla \times \underline{E} + \frac{\partial \underline{B}}{\partial t}) \cdot \underline{n} dS = 0$$

$$\Leftrightarrow \underbrace{\nabla \times \underline{E} + \frac{\partial \underline{B}}{\partial t}}_F = 0.$$

Why? Assume it is not zero at some point.  
 ie  $\exists \underline{x}_0$  s.t.  $F(\underline{x}_0) \neq 0$ .

Take a plane  $\Gamma$  to  $F$  through  $\underline{x}_0$ .



$S_\epsilon$  disc of radius  
 $\epsilon$  in  $\Pi$

$$\text{Then I need } \int_{S_\epsilon} \underline{E} \cdot \underline{n} dS = 0$$

but  $\underline{n} = \frac{F(\underline{x}_0)}{|F(\underline{x}_0)|}$  by clever choice of plane

$$\Rightarrow \underline{E} \cdot \underline{n} \Big|_{\underline{x}=\underline{x}_0} = |F(\underline{x}_0)| > 0.$$

but  $\underline{F}$  is cts on  $\Pi$ .

$$\rightarrow \underline{E} \cdot \underline{n} > \frac{1}{2} |\underline{F}(x_0)| \text{ if } \epsilon \text{ is sufficiently small.}$$

Thus  $\int_{S_\epsilon} \underline{E} \cdot \underline{n} dS > \frac{1}{2} |\underline{F}(x_0)| \text{ Area}(S_\epsilon) > 0 \quad \times$

$$\rightarrow \underline{F}(x) \equiv 0 \quad \times$$

So we get Maxwell-Faraday.

So we have Maxwell's eqns: (in any material)

$$\left\{ \begin{array}{l} \nabla \cdot \underline{D} = \rho \\ \nabla \times \underline{E} = - \frac{\partial \underline{B}}{\partial t} \\ \nabla \cdot \underline{B} = 0 \\ \nabla \times \underline{H} = \frac{\partial \underline{D}}{\partial t} + \underline{J} \end{array} \right. \quad \text{where } \left\{ \begin{array}{l} \underline{D} = \epsilon \underline{E} \\ \underline{B} = \mu \underline{H} \end{array} \right.$$

In integral form:

$$\left\{ \begin{array}{l} \int_S \underline{D} \cdot \underline{n} dS = \int_V \rho dV \\ \int_S \underline{B} \cdot \underline{n} dS = 0 \\ \int_C \underline{E} \cdot d\underline{r} = - \int_S \frac{\partial \underline{B}}{\partial t} dS \\ \int_C \underline{H} \cdot d\underline{r} = \int_S \frac{\partial \underline{D}}{\partial t} + \underline{J} dS \end{array} \right.$$

Etude on differential forms

$$\int_C \underline{E} \cdot d\underline{r} = \int_C E_1 dx^1 + E_2 dx^2 + E_3 dx^3 \quad \dots \quad (L)$$

$$\text{Let } x^1 = x^1(t), \quad x^2 = x^2(t), \quad x^3 = x^3(t)$$

$$= \int_a^b \left[ E_1(\underline{x}(t)) \dot{x}^1(t) + \dots + E_3(\underline{x}(t)) \dot{x}^3(t) \right] dt$$

Let  $x^i = x^i(y^k)$   $k, i = 1, 2, 3$ .  
 i.e. our  $x$  coords are in terms of  $y$  coords  
 e.g.  $\infty$  polars in cartesian

$$\text{Then } dx^1 = \frac{\partial x^1}{\partial y^1} dy^1 + \frac{\partial x^1}{\partial y^2} dy^2 + \frac{\partial x^1}{\partial y^3} dy^3$$

$$\begin{aligned} (L) &= \cancel{\int} \left[ E_1 \frac{\partial x^1}{\partial y^1} + E_2 \frac{\partial x^2}{\partial y^1} + E_3 \frac{\partial x^3}{\partial y^1} \right] dy^1 \\ &\quad + \left[ E_1 \frac{\partial x^1}{\partial y^2} + E_2 \frac{\partial x^2}{\partial y^2} + E_3 \frac{\partial x^3}{\partial y^2} \right] dy^2 \\ &\quad + \left[ E_1 \frac{\partial x^1}{\partial y^3} + E_2 \frac{\partial x^2}{\partial y^3} + E_3 \frac{\partial x^3}{\partial y^3} \right] dy^3 \\ &= \int_C \hat{\underline{E}} \cdot d\underline{y} \quad \hat{\underline{E}} = \underline{E} \text{ in } y\text{-coordinates} \end{aligned}$$

$$\hat{E}_1 = \sum_{i=1}^3 \frac{\partial x^i}{\partial y^1} \cdot E_i = \sum_{i=1}^3 \frac{\partial x^i}{\partial y^1} E_i$$

$$j=1,2,3 \quad \hat{E}_j = \sum_{i=1}^3 \frac{\partial x^i}{\partial y^j} E_i$$

$$\text{so} \quad \sum_{i=1}^3 E_i(x) dx^i \leftrightarrow \sum_{j=1}^3 \hat{E}_j(y) dy^j$$

differential form  
of first order

Vectors and covectors: velocity is a real vector

$\vec{v}$

$$\vec{v}^i = \frac{dx^i}{dt} = \frac{d(x^i(y))}{dt}$$

$$\hat{v}^j = \frac{dy^j}{dt}$$

$$v^i = \frac{dx^i}{dt} = \frac{d(x^i(y))}{dt} = \sum_{j=1}^3 \frac{\partial x^i}{\partial y^j} \frac{\partial y^j}{\partial t} = \sum_{j=1}^3 \frac{\partial x^i}{\partial y^j} \hat{v}^j$$

Sum over  $j$ , in contrast  
to  $\hat{E}$ , where we sum  
over  $i$ .

$$\rightarrow \hat{v}^j = \left( \frac{\partial x}{\partial y} \right)^{-1} v$$

$$\hat{E} = \left( \frac{\partial x}{\partial y} \right)^T E$$

$v$  is a vector      } when you look at a point  
 $E$  is a covector      }

At any point in  $E$  you have a covector.

$$\text{Ohm's law: } \underline{\mathbf{J}} = \underline{\mathbf{J}}^{\text{ext}} + \sigma \underline{\mathbf{E}}$$

$\sigma$  conductivity  
 $\sigma$  matrix  
 $\uparrow$   
 $\begin{matrix} \text{pos/nr} \\ \text{definite} \end{matrix}$   
 $\uparrow$   
 $\sigma \geq 0$  of  $x, t$

## Electromagnetic Energy

( $\epsilon, \mu$  are time indpt;  $\sigma=0$ )  $\Rightarrow$  the system has losses

$\therefore$  From now on,  $\epsilon = \epsilon(x)$ ,  $\mu = \mu(x)$ ,  $\sigma = 0$ .

So what is the energy of an EM field.

EM wave is a solution to Maxwell's eq's when  $\sigma=0$ ,  $\mathbf{J}^{\text{ext}}=0$ .

Energy density  $\mathcal{E}(x, t)$  of an EM is

$$\mathcal{E}(x, t) = \frac{1}{2} [\underline{\mathbf{D}} \cdot \underline{\mathbf{E}} + \underline{\mathbf{B}} \cdot \underline{\mathbf{H}}]$$

$$= \frac{1}{2} [(\epsilon \underline{\mathbf{E}}) \cdot \underline{\mathbf{E}} + (\mu \underline{\mathbf{H}}) \cdot \underline{\mathbf{H}}]$$

Now we look on how  $\mathcal{E}$  changes with time in some volume  $V$ .

$$E_V(t) = \int_V \mathcal{E}(x, t) dV_x$$

$$\Rightarrow \frac{\partial E_V(t)}{\partial t} = \int_V \frac{\partial}{\partial t} \mathcal{E}(x, t) dV_x$$

Do you like  
Medieval  
paintings?

$$= \int_V \left[ \left( \frac{\partial}{\partial t} (\epsilon \underline{E}) \cdot \underline{E} \right) + \left( \frac{\partial}{\partial t} (\mu \underline{H}) \cdot \underline{H} \right) \right] dV$$

since  $\frac{\partial}{\partial t} [(\epsilon \underline{E}) \cdot \underline{E}] = 2 \frac{\partial}{\partial t} (\epsilon \underline{E}) \cdot \underline{E}$

$$= \int_V \left[ \frac{\partial \underline{D}}{\partial t} \cdot \underline{E} + \frac{\partial \underline{B}}{\partial t} \cdot \underline{H} \right] dV$$

Recall my Maxwell's eq's that  $\frac{\partial \underline{D}}{\partial t} = \nabla \times \underline{H} \quad (J=0)$

$$-\frac{\partial \underline{B}}{\partial t} = \nabla \times \underline{E} \quad \text{⊗.}$$

$$= \int_V \left[ (\nabla \times \underline{H}) \cdot \underline{E} - \underline{H} \cdot (\nabla \times \underline{E}) \right] dV$$

[Prob. A1\*: Show  $\nabla \cdot (\underline{a} \times \underline{b}) = (\nabla \times (\underline{a} \cdot \underline{b})) - \underline{a} \cdot (\nabla \times \underline{b})$ ]

$$= - \int_V \nabla \cdot (\underline{E} \times \underline{H}) dV \quad . . . . . (1)$$

Call  $\underline{S} = \underline{E} \times \underline{H}$  pointing vector

[Prob A2\*: Show  $\frac{\partial \underline{E}}{\partial t}(x,t) + \nabla \cdot \underline{S}(x,t) = 0$

$$\text{and } \frac{\partial \underline{E}_r(t)}{\partial t} = - \int_{\partial V} \underline{S} \cdot \underline{n} dA$$

Now, let  $\epsilon, \mu$  be scalars and constants  $> 0$ .

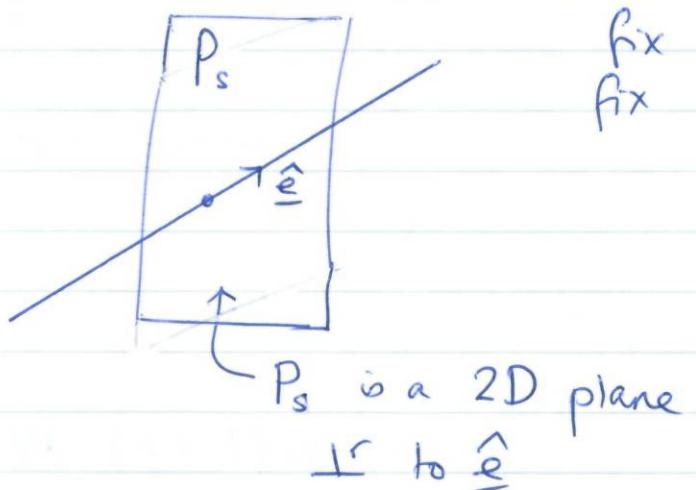
$$\left. \begin{array}{l} p=0 \\ f=0 \end{array} \right\} \text{still} .$$

(isotropic homogeneous medium w/o dissipation)

EM wave is called a "plane wave" if it depends there is a direction  $\hat{\underline{e}}$  (unit vector) s.t. ~~so that~~

$$\underline{E} = \underline{E}(\underline{x}, t)$$

$$\underline{H} = \underline{H}(\underline{x}, t)$$



Then  $\underline{E}, \underline{H}$  do not vary along  $P_s$ .

Since we are in isotropic material,  
take  $\hat{\underline{e}} = \hat{\underline{z}}$ .

$$\Rightarrow \underline{E} = \underline{E}(x^1, t)$$
$$\underline{H} = \underline{H}(x^1, t).$$

[Prob 3.4 is now star]

[Prob B2\*: Show that  $\nabla \cdot \underline{E} = \nabla \cdot \underline{H} = 0$  for isotropic, homogeneous medium]

Let us differentiate one of Maxwell's eq's.

$$\frac{\partial}{\partial t} (\nabla \times \underline{H}) = \frac{\partial}{\partial t} \left( \frac{\partial \underline{E}}{\partial t} \right) \quad (\text{Maxwell-Ampere})$$

$$\nabla \times \frac{\partial \underline{H}}{\partial t} = \frac{\partial^2}{\partial t^2} (\epsilon \underline{E})$$

// Max-Far.

$$-\frac{1}{\mu} (\nabla \times \nabla \times \underline{E})$$

// Prob 3.4 and B2\* (i.e.  $\nabla \cdot \underline{E} = 0$ )

$$\frac{1}{\mu} \nabla^2 \underline{E}$$

$$\hookrightarrow \frac{\partial^2 \underline{E}}{\partial t^2} = \frac{1}{\epsilon \mu} \nabla^2 \underline{E}$$

ie.  $\frac{\partial^2 E_j}{\partial t^2} = \frac{1}{\epsilon \mu} \nabla^2 E_j$

componentwise

[Prob B3\*] Derive  $\frac{\partial^2 \underline{H}}{\partial t^2} = \frac{1}{\epsilon \mu} \nabla^2 \underline{H}$

These are the wave eq's with speed  $c = \frac{1}{\sqrt{\epsilon \mu}}$

$$\therefore \frac{\partial^2 f}{\partial t^2} = c^2 \nabla^2 f \quad \text{is usual wave eq.}$$

Note: when deriving wave eq's we don't require that  $\underline{E}, \underline{H}$  are plane waves.

[Prob B4\*]: Show that if  $\underline{E} = \underline{E}(x^1, t)$   
 $\underline{H} = \underline{H}(x^1, t)$ ,

then

$$E_n(x, t) = E_n^+(x^1 + ct) + E_n^-(x^1 - ct)$$

$$H_n(x, t) = H_n^+(x^1 + ct) + H_n^-(x^1 - ct) \quad n=1, 2, 3$$

for some  $f$ 's  $E_n^\pm(s)$ ,  $H_n^\pm(s)$ .  $(s=x^1)$

Note: just look at wave eqn:  $\frac{\partial^2 f}{\partial t^2} = c^2 \nabla^2 f$

assuming that  $f=f(x^1, t)$ . Use substitution

$$\xi = x^1 - ct, \eta = x^1 + ct$$

to show that  $\frac{\partial^2 f}{\partial \xi \partial \eta} = 0$ .

*Adam  
Bix  
Cheese  
like Pepper  
it's good*

Then for  $F = \frac{\partial f}{\partial \xi}$  we get  $\frac{\partial F}{\partial \eta} = 0$

i.e.  $F(\xi, \eta)$  is an arbitrary f.  $F(\xi)$

i.e.  $\frac{\partial F(\xi, \eta)}{\partial \xi}$  is an arbitrary f. of  $\xi$

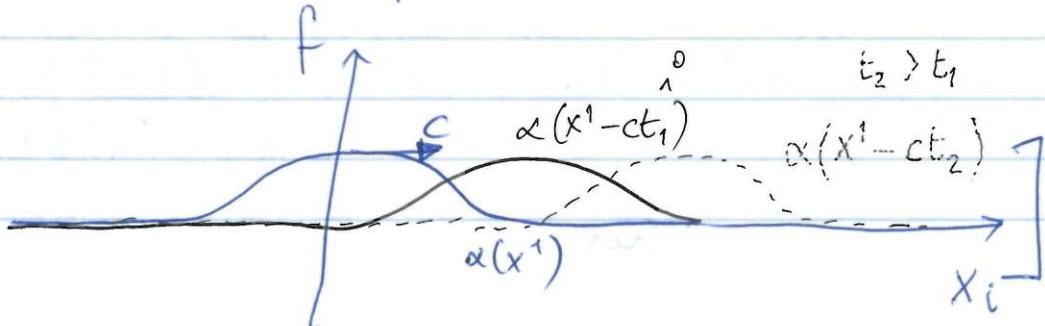
$$\therefore \frac{\partial F}{\partial \xi}(\xi, \eta) = F(\xi)$$

Show that these imply  $f(\xi, \eta)$

$$= \alpha(\xi) + \beta(\eta)$$

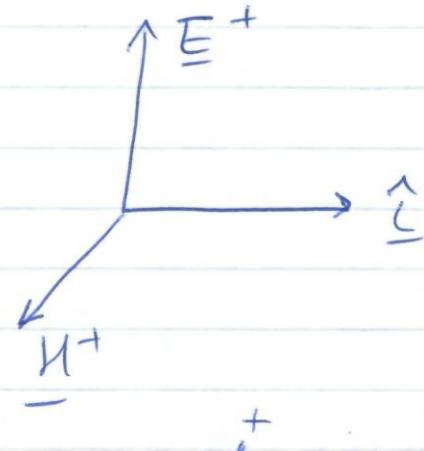
where  $\alpha, \beta$  arbitrary f.'s

$$f(x^1, t) = \alpha(x^1 - ct) + \beta(x^1 + ct)$$



So we get  $\underline{E}, \underline{H}$  are superposition of two waves, one going to right and one going to left.

Suppose  $E_1, H_1 = 0$ , i.e.  $\underline{E}, \underline{H} \perp \underline{\zeta}$   
and  $\underline{E} \perp \underline{H}$



Look at pointing vector  $\underline{S}^+$  (pointing to right)

$$\underline{S}^+ = \underline{E}^+ \times \underline{H}^+ = |\underline{S}^+| \underline{\zeta}$$

EM wave is harmonic if it's periodic in  $t$  and its dependence on  $t$  is of the form  $e^{\pm i\omega t}$  ( $\omega$  = freq.)

Harmonic plane wave is then of the form

$$\underline{E} = \underline{E}^+ e^{i(kx_e - \omega t)} + \underline{E}^- e^{i(kx_e + \omega t)} + \text{comp. conj.}$$

$\underline{E}^+, \underline{E}^-$  constant complex vectors

$$x_e = \underline{x} \cdot \underline{e}$$

$$\text{Plane waves} \Rightarrow e^{i k(x_e - \frac{\omega}{k} t)}$$

$$k = \frac{\omega}{c}$$

depend on  $x \cdot \underline{e}$



so  $\underline{E} = \sum$  four terms. All should satisfy Max Eq's  $\therefore$  they're indep.

We need that each term  $E \pm e^{i(kx^1 - ct)}$  satisfies Max Eq's.

$$H(x, t) = H^+ e^{ik(x^1 - ct)} + H^- e^{ik(x^1 + ct)} + \text{c.c.}$$

We are studying EM waves of form

$$\underline{E}_0 e^{ik(x^1 - ct)}, \underline{H}_0 e^{ik(x^1 - ct)} \quad \begin{cases} \underline{E}_0 \\ \underline{H}_0 \end{cases} \} \text{constant complex vectors}$$

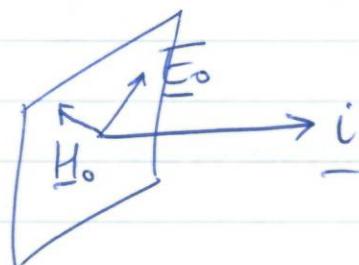
let's apply divergence to this formula.  
(recall  $\nabla \cdot \underline{E} = \nabla \cdot \underline{B} = 0$ )

$$\nabla \cdot (\underline{E}_0 e^{ik(x^1 - ct)}) = E_0' i k e^{ik(x^1 - ct)} = 0$$

$$\Rightarrow E_0' = 0$$

$$\Rightarrow (\underline{E}_0 \cdot \hat{i}) = 0$$

$$\text{and similarly } (\underline{H}_0 \cdot \hat{i}) = 0.$$



$$\text{Now recall } \nabla \times \underline{E} = -\frac{\partial \underline{B}}{\partial t} = -\mu \frac{\partial \underline{H}}{\partial t}$$

$\mathcal{R} \alpha \beta$   $\kappa \alpha \beta$



KUEOTLOVS  
 $\kappa \beta \epsilon \sigma \tau \lambda \omega \delta \sigma$   
 S

$$\rightarrow -\mu \frac{\partial \underline{H}}{\partial t} = i \kappa \mu \underline{H}$$

$$\nabla \times \underline{E} = i \kappa (\underline{\hat{z}} \times \underline{E}) \quad - \text{check.}$$

Greek sigma  
 is sat  
 end of word

$$\rightarrow \underline{H} = \frac{1}{c\mu} (\underline{\hat{z}} \times \underline{E})$$

$$= \sqrt{\frac{\epsilon}{\mu}} (\underline{\hat{z}} \times \underline{E}) = \frac{1}{Z} (\underline{\hat{z}} \times \underline{E})$$

$$Z = \sqrt{\frac{\mu}{\epsilon}} \quad \text{electromagnetic impedance}$$

$\underline{\hat{z}}, \underline{E}_0, \underline{H}_0$  form orthogonal basis

~~By shifting~~  
not a wave

$$E_0^{22} e^{ik(x-zt)} = |E_0|^2 e^{i\beta} \quad \text{for some } \beta.$$

$$\underline{E}_0 = K_2 \underline{\hat{j}} + K_3 e^{i\alpha} \underline{\hat{k}} \quad K_1, K_2 > 0 \quad \alpha \text{ phase}$$

$$\underline{H}_0 = \frac{K_2}{Z} \underline{\hat{k}} - \frac{K_3}{Z} e^{i\alpha} \underline{\hat{j}} \quad \leftrightarrow$$

## Polarisation.

Where  $\alpha = 0, \pm \pi$ , we have linearly polarised waves  
 ie  $e^{i\alpha} \in \mathbb{R}$  ( $t$ 's  $\pm 1$ )

$$\underline{E}_0 = (K_2 \underline{\hat{j}} \pm K_3 \underline{\hat{k}}) \quad \text{real vector}$$

$$\underline{H}_0 = \frac{1}{Z} (\underline{\hat{k}} (K_2 \underline{\hat{k}} \pm K_3 \underline{\hat{j}})) \quad \text{real vector}$$

$$\operatorname{Re}[E_0 e^{ik(x^1-ct)}] = E_0 \cos[k(x^1-ct)]$$

and same with  $H_0$ .

Take  $\alpha = \frac{\pi}{2}$ .

(Recall  $E_0$ )

$$\text{Recall } E_0 = K_2 \hat{j} + i K_3 \hat{k}$$

$$\operatorname{Re}(E_0 e^{ik(x^1-ct)}) = K_2 \cos(k(x^1-ct)) \hat{i} \\ - K_3 \sin(k(x^1-ct)) \hat{k}$$

$\uparrow$   
 $\alpha \neq \frac{\pi}{2}, K_3 \neq 0$  gives you an ellipse

[Problem C]: Let  ~~$\alpha = \frac{\pi}{2}$~~ ;  ~~$e^{i\alpha}$~~  is not real.

find the formula of  $E_0$ ]

→ show we get

