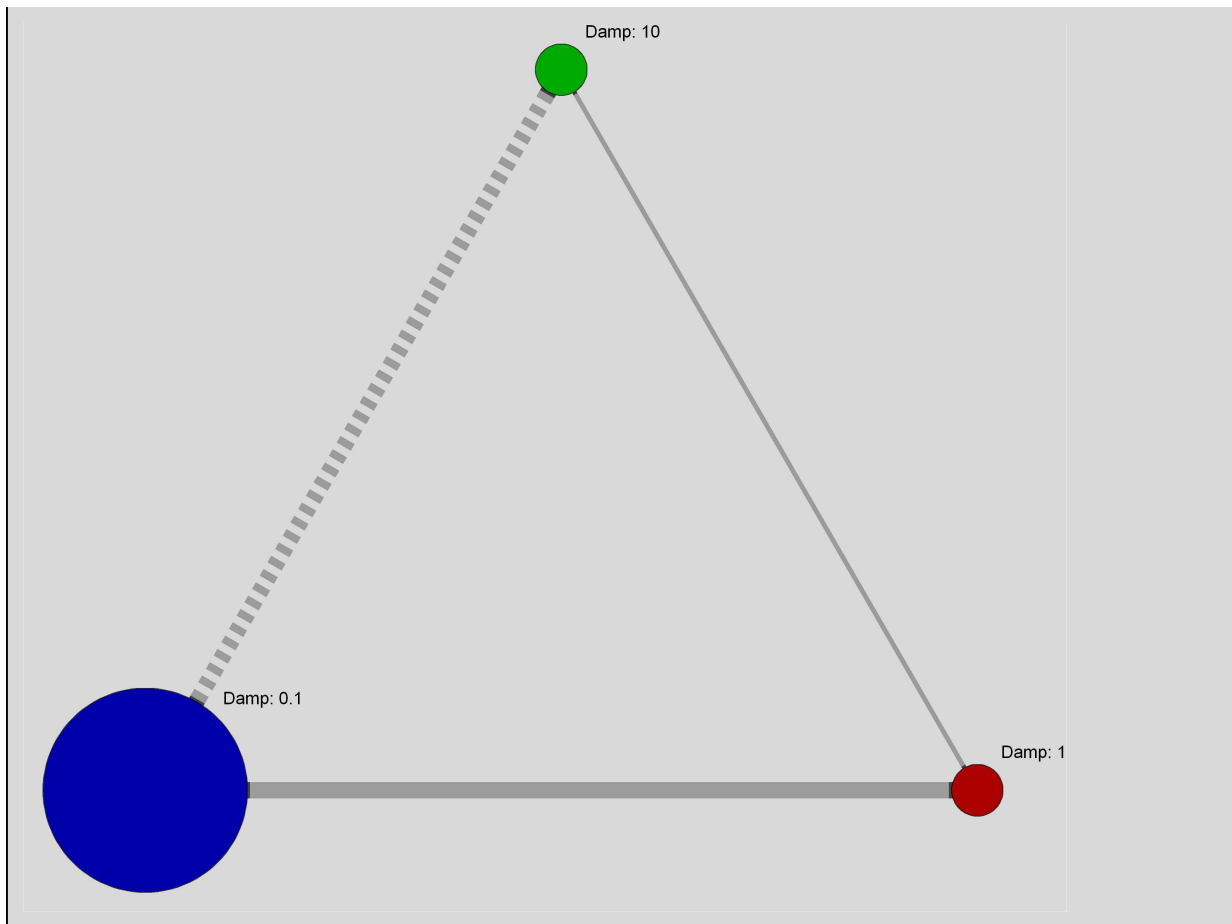


Synthetic Test Case Overview

In[1]:=

```
versca1 = 0.01;
versca2 = 0.05;
edgsca1 = 0.007;
edgsca2 = 0.02;
Graph[{Style[1, Darker@Blue], Style[2, Darker@Red], Style[3, Darker@Green]},
      {Style[1 ↔ 2, Thickness[ $\frac{40}{17}$  edgsca1], Gray], Style[2 ↔ 3, Thickness[ $\frac{4}{17}$  edgsca2], Gray],
      Style[3 ↔ 1, Thickness[ $\frac{40}{17}$  edgsca1], Dashed, Gray]}, VertexShapeFunction → "Circle",
      VertexSize → {1 ->  $\frac{417}{17}$  versca1, 2 ->  $\frac{21}{17}$  versca2, 3 ->  $\frac{21}{17}$  versca2},
      VertexLabels → {1 → "Damp: 0.1", 2 → "Damp: 1", 3 → "Damp: 10"}
```

Out[1]=



In[2]:=

$$H = \begin{pmatrix} 0 & 0 & 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 0 & -1 \\ \frac{417}{17} & -\frac{40}{17} & \frac{40}{17} & \frac{1}{10} & 0 & 0 \\ -\frac{40}{17} & \frac{21}{17} & -\frac{4}{17} & 0 & 1 & 0 \\ \frac{40}{17} & -\frac{4}{17} & \frac{21}{17} & 0 & 0 & 10 \end{pmatrix};$$

In[3]:=

$$\text{eqnham} = \text{Flatten}\left[\text{FullSimplify}\left[\begin{pmatrix} x_1'[t] \\ x_2'[t] \\ x_3'[t] \\ p_1'[t] \\ p_2'[t] \\ p_3'[t] \end{pmatrix} + H \cdot \begin{pmatrix} x_1[t] \\ x_2[t] \\ x_3[t] \\ p_1[t] \\ p_2[t] \\ p_3[t] \end{pmatrix}\right]\right];$$

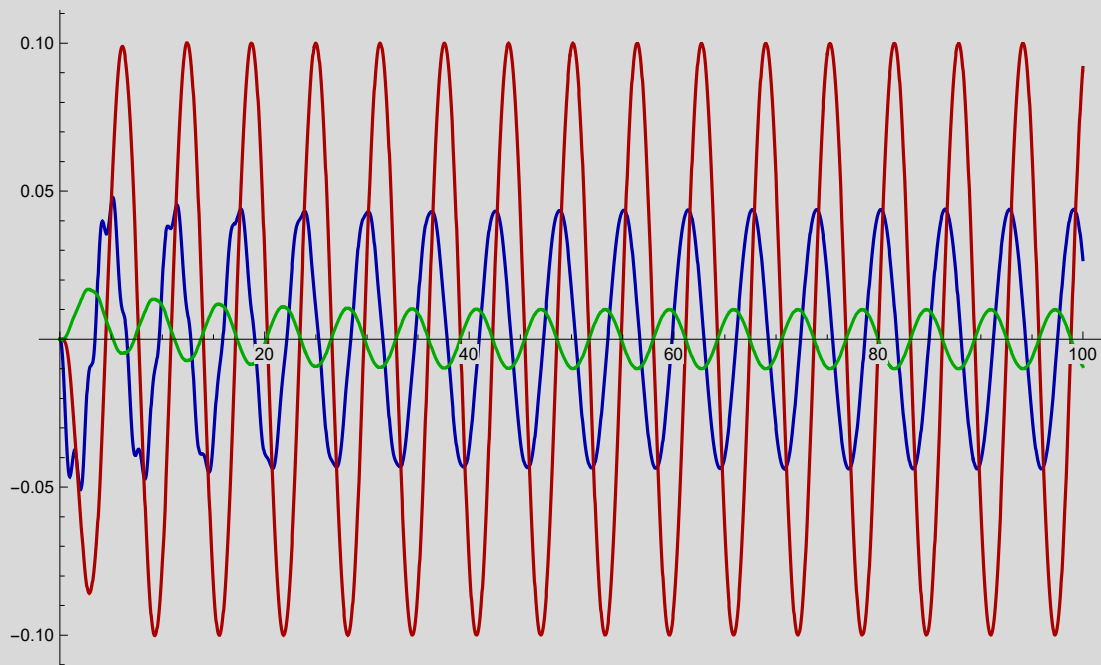
In[5]:=

```
solham = NDSolve [
  {eqnham[[1]] == 0, eqnham[[2]] == 0, eqnham[[3]] == 0, eqnham[[4]] == Cos[t + 1.7], eqnham[[5]] == 0,
  eqnham[[6]] == 0, x1[0] == 0, x2[0] == 0, x3[0] == 0, p1[0] == 0, p2[0] == 0, p3[0] == 0},
  {x1, x2, x3, p1, p2, p3}, {t, 0, 100}, Method -> "ImplicitRungeKutta"];
```

In[6]:=

```
Plot[{x1[t] /. solham, x2[t] /. solham, x3[t] /. solham}, {t, 0, 100}, PlotRange -> All,
PlotStyle -> {Darker@Blue, Darker@Red, Darker@Green}, ImageSize -> 570]
```

Out[6]=



Stochastic ODE & Data Generation

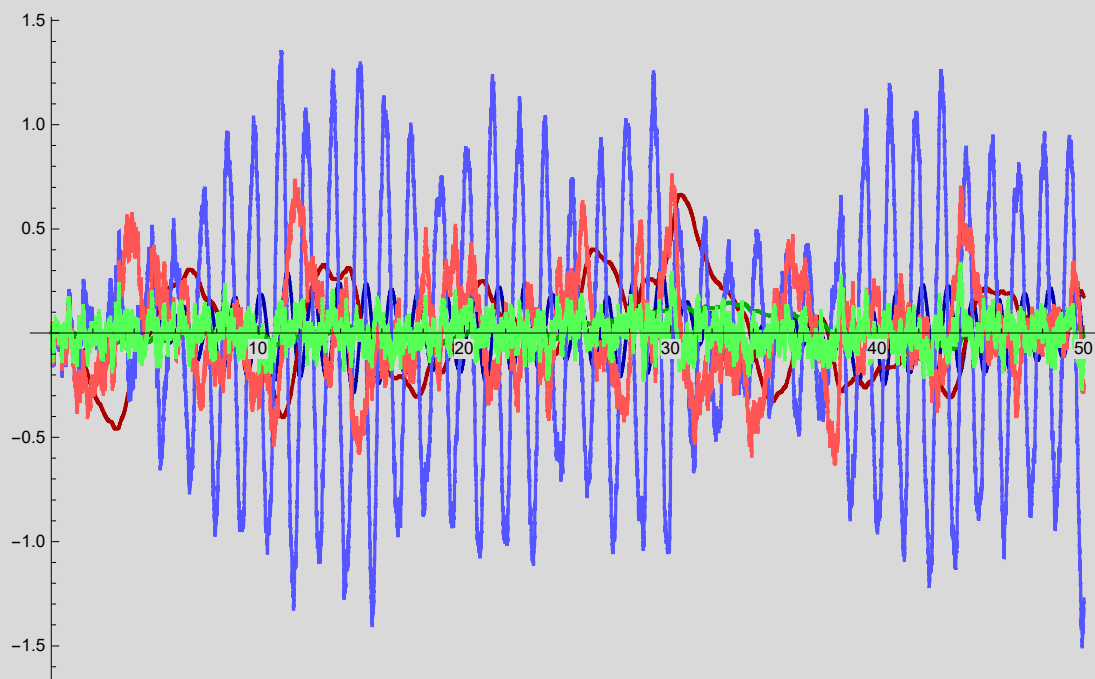
In[65]:=

```

proc = ItoProcess[{{a[t], b[t], c[t], - $\frac{a[t]}{10} - \frac{417 x[t]}{17} + \frac{40 y[t]}{17} - \frac{40 z[t]}{17} + \text{Cos}[t + 1.7]$ ,
  -b[t] +  $\frac{40 x[t]}{17} - \frac{21 y[t]}{17} + \frac{4 z[t]}{17}$ , -10 c[t] -  $\frac{40 x[t]}{17} + \frac{4 y[t]}{17} - \frac{21 z[t]}{17}$ },
  {{0}, {0}, {0}, {1/3}, {1/3}, {1/3}}, {x[t], y[t], z[t], a[t], b[t], c[t]},
  {{x, y, z, a, b, c}, {0, 0, 0, 0, 0, 0}}, {t, 0}];
time = 50;
resolution = 10-3;
path = RandomFunction[proc, {0., time, resolution}, Method → "StochasticRungeKutta"];
ListLinePlot[path, PlotStyle → {Darker@Blue, Darker@Red, Darker@Green,
  Lighter@Blue, Lighter@Red, Lighter@Green}, PlotRange → All, ImageSize → 570]

```

Out[65]=



Discrete Frequencies

In[8]:=

```

time
N@ $\frac{time}{2 \pi}$  {1, 5}

```

Out[8]=

```
{7.95775, 39.7887}
```

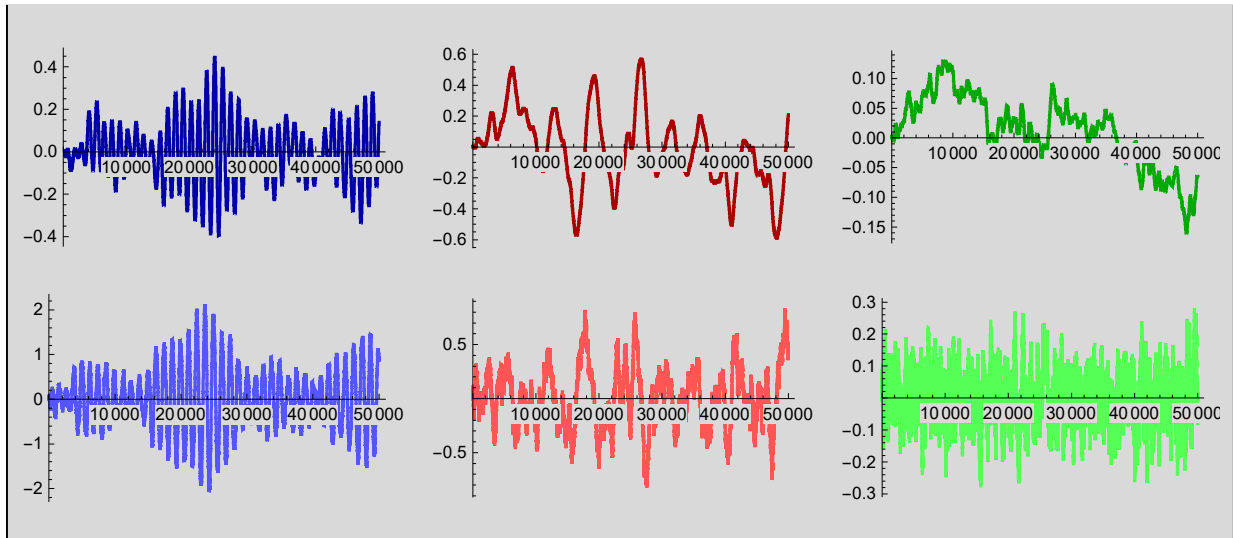
In[81]:=

```

tsfulldata = Flatten[Normal@
  RandomFunction[proc, {0., time, resolution}, Method → "StochasticRungeKutta"], 1];
samples = Length[tsfulldata] - 1;
tssignal = Table[tsfulldata[[k, 2, i]], {i, 1, 6}, {k, 1, samples}];
tsderivative =
  Table[
    (tsfulldata[[k + 1, 2, i]] - tsfulldata[[k, 2, i]] /
     tsfulldata[[k + 1, 1]] - tsfulldata[[k, 1]]), {i, 1, 6}, {k, 1, samples}];
matrixsignal = Sum[{tssignal[[;;, k]]^T.{tssignal[[;;, k]]}, {k, 1, samples}] / samples;
matrixderivativesignal =
  Sum[{tssignal[[;;, k]]^T.{tsderivative[[4;;6, k]]}, {k, 1, samples}] / samples;
colorlist = {Darker@Blue, Darker@Red, Darker@Green,
  Lighter@Blue, Lighter@Red, Lighter@Green};
fouriersignal = Table[Fourier[tssignal[[i]], {i, 1, 6}];
fourierderivative = Table[Fourier[tsderivative[[i]], {i, 1, 6}];
fouriermatrixsignal = Table[
  Re[Conjugate[{fouriersignal[[;;, k]]^T}.{fouriersignal[[;;, k]]}], {k, 1, samples}];
fouriervectorderivativesignal = Table[Re[Conjugate[fourierderivative[[i, k]]
  fouriersignal[[;;, k]]], {i, 1, 6}, {k, 1, samples}];
fourierdynamic = Table[Abs[fourierderivative[[i + 3, k]] +
  H[4;;6, ;;][[i, ;;].fouriersignal[[;;, k]]], {i, 1, 3}, {k, 1, samples}];
GraphicsGrid[Partition[Table[ListPlot[tssignal[[i]], PlotRange → {{0, All}, All},
  Joined → True, PlotStyle → colorlist[[i]], ImageSize → 190], {i, 1, 6}], 3]]

```

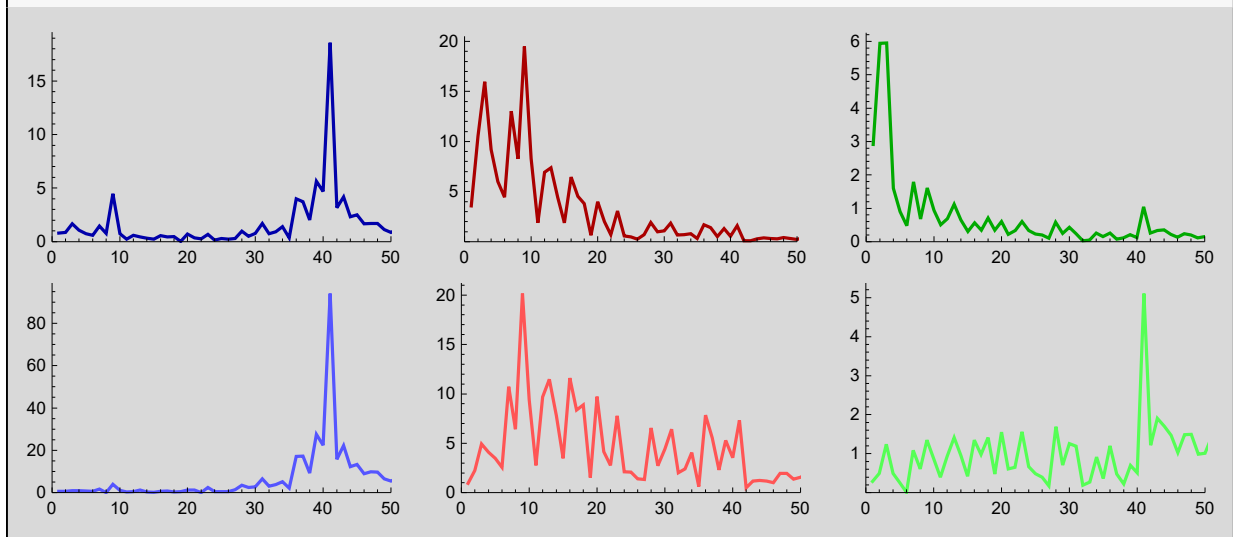
Out[81]=



In[82]:=

```
GraphicsGrid[
  grille de graphiques
  Partition[Table[ListPlot[{Abs[fouriersignal[i]]}], PlotRange -> {{0, 50}, {0, All}},
    partitionne table tracé de liste valeur absolue zone de tracé tout
    Joined -> True, PlotStyle -> colorlist[i], ImageSize -> 190], {i, 1, 6}], 3]
    vrai style de tracé taille d'image
```

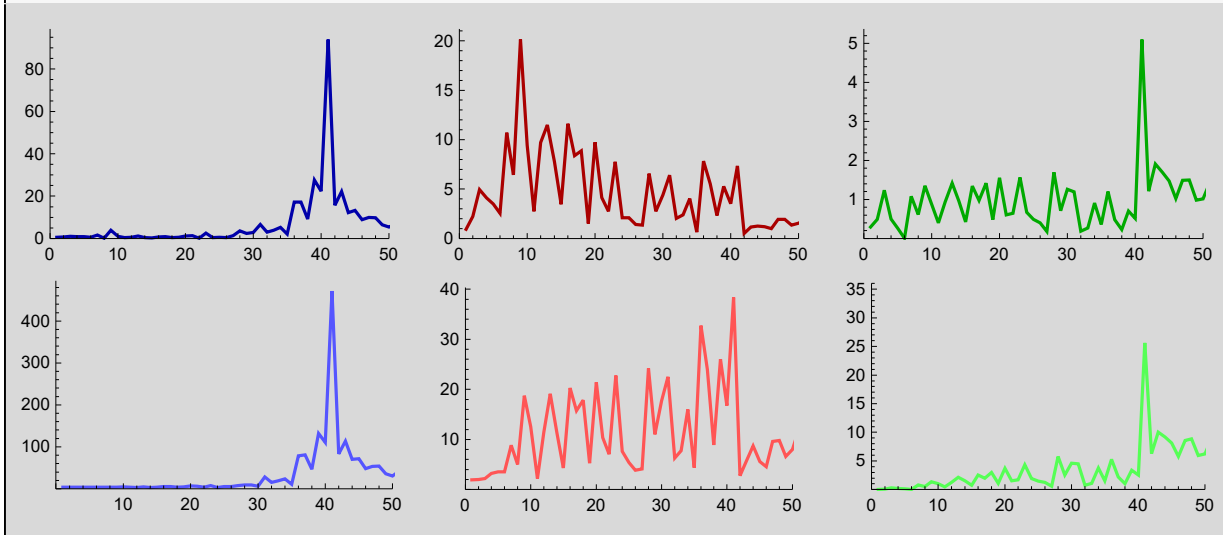
Out[82]=



In[83]:=

```
GraphicsGrid[Partition[
  grille de graphi... | partitionne
  Table[ListPlot[{Abs[fourierderivative[i]]], PlotRange -> {{0, 50}, {0, All}},
    | tracé de liste | valeur absolue | zone de tracé | tout
    Joined -> True, PlotStyle -> colorlist[i], ImageSize -> 190], {i, 1, 6}], 3]]
    | vrai | style de tracé | taille d'image
```

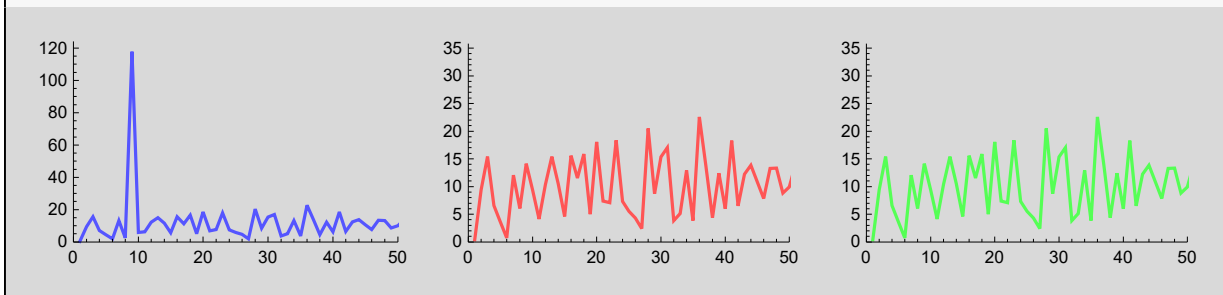
Out[83]=



In[84]:=

```
GraphicsGrid[
  grille de graphiques
  {Table[ListPlot[{Abs[fourierdynamic[i]]], PlotRange -> {{0, 50}, {0, All}},
    | table | tracé de liste | valeur absolue | zone de tracé | tout
    Joined -> True, PlotStyle -> colorlist[i + 3], ImageSize -> 190], {i, 1, 3}]}
    | joint | vrai | style de tracé | taille d'image
```

Out[84]=



Log-Likelihood Regression

In[88]:=

```

localizationreg = Table[varmat =  $\begin{pmatrix} a_1 & b_1 & b_2 & c_1 & 0 & 0 \\ b_1 & a_2 & b_3 & 0 & c_2 & 0 \\ b_2 & b_3 & a_3 & 0 & 0 & c_3 \end{pmatrix}$ ;

NMinimize[ $\left\{ \text{Tr}[\text{varmat}^T \cdot \text{varmat} \cdot \text{matrixsignal}] + 2 \text{Tr}[\text{varmat} \cdot \text{matrixderivativesignal}] + \frac{1}{2} \gamma^2 - \frac{2 \gamma}{\sqrt{\text{samples}}} (\text{Tr}[\{\text{varmat}[[1, ;;]]^T \cdot \{\text{varmat}[[1, ;;]] \cdot \text{fouriermatrixsignal}[[k + 1]] + 2 \text{fouriervectorderivativesignal}[[3 + 1, k + 1]] \cdot \text{varmat}[[1, ;;]] + \text{Abs}[\text{fourierderivative}[[3 + 1, k + 1]]^2]^{1/2}, \gamma \geq 0 \&\& c_1 \geq 0 \&\& c_2 \geq 0 \&\& c_3 \geq 0 \&\& a_1 \geq 0 \&\& a_2 \geq 0 \&\& a_3 \geq 0 \right\}$ , {a1, a2, a3, b1, b2, b3, c1, c2, c3, γ}], {1, 1, 3}, {k, 0, 50}];

freqreg = Table[{k, localizationreg[[1, k + 1, 1]]}, {1, 1, 3}, {k, 0, 50}];

```

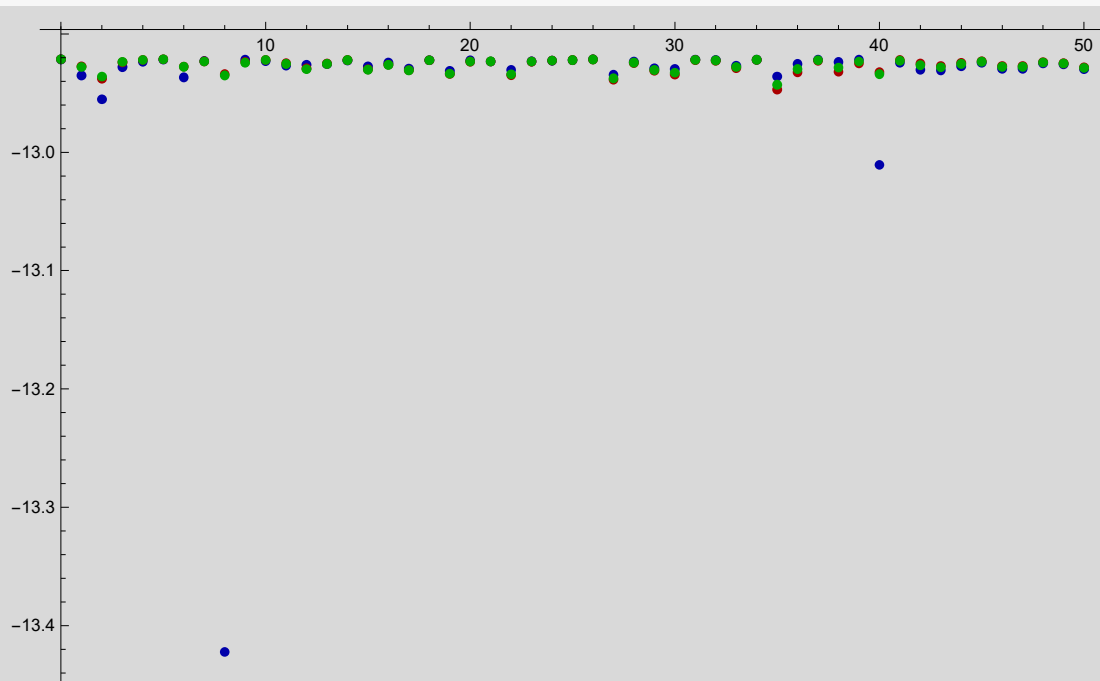
In[89]:=

```

ListPlot[freqreg, PlotRange → All, PlotStyle → colorlist[[1 ;; 3]], ImageSize → 570]

```

Out[89]=



Estimated Matrix & Amplitude

In[90]:=

```

siteest = 1;
frequest = 8;
Grid[{{MatrixForm[varmat /. localizationreg[siteest, frequest + 1, 2]],
  [grille] [apparence matricielle]
  "γ = " ~~ ToString[γ /. localizationreg[siteest, frequest + 1, 2]]}]]
  [convertis en chaîne de caractères]

```

Out[90]=

$$\begin{pmatrix} 24.7743 & -2.07591 & 2.3514 & 0.0698741 & 0 & 0 \\ -2.07591 & 1.35923 & -0.101915 & 0 & 0.925181 & 0 \\ 2.3514 & -0.101915 & 1.25028 & 0 & 0 & 9.59457 \end{pmatrix} \quad \gamma = 1.04081$$

Ground Truth

In[91]:=

```

Grid[{{MatrixForm[N@H[4 ;; 6, ;;]], "γ = 1"}}]
  [grille] [apparence m...] [valeur numérique]

```

Out[91]=

$$\begin{pmatrix} 24.5294 & -2.35294 & 2.35294 & 0.1 & 0. & 0. \\ -2.35294 & 1.23529 & -0.235294 & 0. & 1. & 0. \\ 2.35294 & -0.235294 & 1.23529 & 0. & 0. & 10. \end{pmatrix} \quad \gamma = 1$$

Log-Likelihood Spatial Relaxation

In[92]:=

```

relocalizationreg = Table[varmat = 
$$\begin{pmatrix} a_1 & b_1 & b_2 & c_1 & 0 & 0 \\ b_1 & a_2 & b_3 & 0 & c_2 & 0 \\ b_2 & b_3 & a_3 & 0 & 0 & c_3 \end{pmatrix}$$
;

NMinimize[{Tr[varmatT.varmat.matrixsignal] + 2 Tr[varmat.matrixderivativesignal] +

$$\frac{1}{2} (\gamma_1^2 + \gamma_2^2 + \gamma_3^2) - \left( \frac{2 \gamma_1}{\sqrt{\text{samples}}} (\text{Tr}[\{\text{varmat}[[1, ;;]]^T \cdot \{\text{varmat}[[1, ;;]] \cdot \right.$$

fouriermatrixsignal[[k + 1]] + 2 fourivectorderivativesignal[[3 +
1, k + 1]].varmat[[1, ;;]] + Abs[fourierderivative[[3 + 1, k + 1]]2)1/2 +

$$\frac{2 \gamma_2}{\sqrt{\text{samples}}} (\text{Tr}[\{\text{varmat}[[2, ;;]]^T \cdot \{\text{varmat}[[2, ;;]] \cdot \text{fouriermatrixsignal}[[k + 1]] +$$

2 fourivectorderivativesignal[[3 + 2, k + 1]].varmat[[2, ;;]] +
Abs[fourierderivative[[3 + 2, k + 1]]2)1/2 + 
$$\frac{2 \gamma_3}{\sqrt{\text{samples}}}$$


$$(\text{Tr}[\{\text{varmat}[[3, ;;]]^T \cdot \{\text{varmat}[[3, ;;]] \cdot \text{fouriermatrixsignal}[[k + 1]] +$$

2 fourivectorderivativesignal[[3 + 3, k + 1]].varmat[[3, ;;]] +
Abs[fourierderivative[[3 + 3, k + 1]]2)1/2

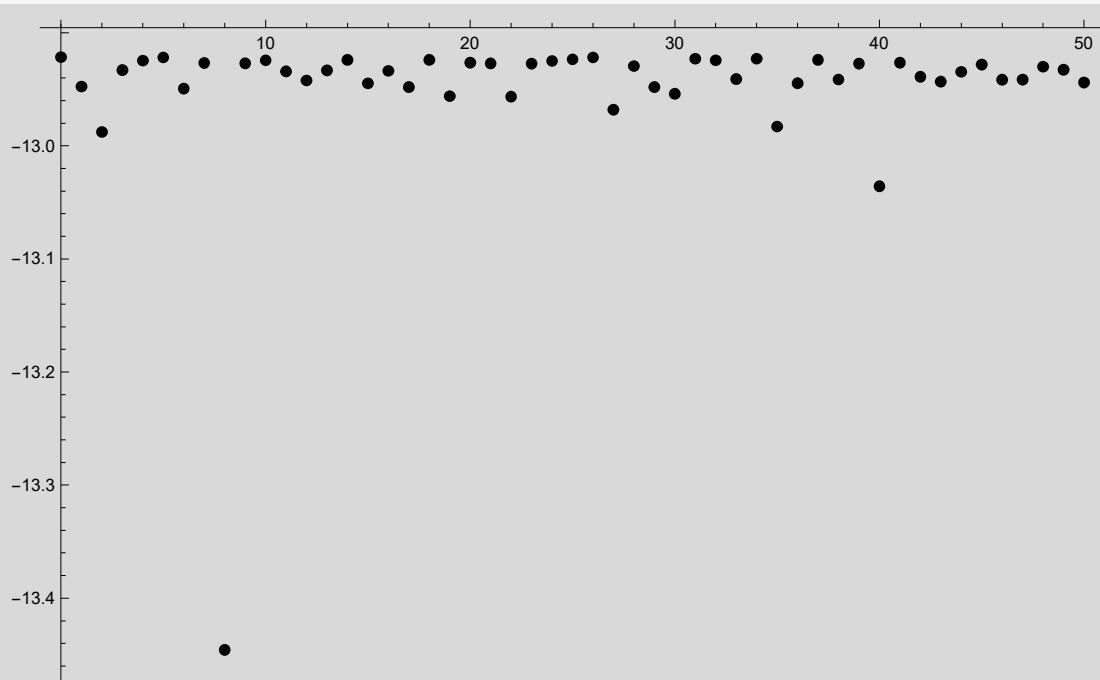
$$\gamma_1 \geq 0 \&\& \gamma_2 \geq 0 \&\& \gamma_3 \geq 0 \&\& c_1 \geq 0 \&\& c_2 \geq 0 \&\& c_3 \geq 0 \&\& a_1 \geq 0 \&\& a_2 \geq 0 \&\& a_3 \geq 0 \}$$
,
{a1, a2, a3, b1, b2, b3, c1, c2, c3, γ1, γ2, γ3}], {k, 0, 50}];
refreqreg = Table[{k, relocalizationreg[[k + 1, 1]]}, {k, 0, 50}];

```

In[93]:=

```
ListPlot[refreqreg, PlotRange → All, PlotStyle → Black, ImageSize → 570]
```

[tracé de liste] [zone de tracé] [tout] [style de tracé] [noir] [taille d'image]



Out[93]=

Estimated Matrix & Amplitude

In[94]:=

```
frequest = 8;
```

```
Grid[{{MatrixForm[varmat /. relocalizationreg[frequest + 1, 2]],
```

[grille] [apparence matricielle]

```
"(γ1, γ2, γ3) = " ~~ ToString[{γ1, γ2, γ3} /. relocalizationreg[frequest + 1, 2]]}}
```

[convertis en chaîne de caractères]

Out[94]=

$$\begin{pmatrix} 24.7661 & -2.08956 & 2.49514 & 0.0687766 & 0 & 0 \\ -2.08956 & 1.48441 & 0.169378 & 0 & 1.07486 & 0 \\ 2.49514 & 0.169378 & 0.413976 & 0 & 0 & 9.81136 \end{pmatrix} (\gamma_1, \gamma_2, \gamma_3) = \{1.03953, 0.167$$

Ground Truth

In[95]:=

```
Grid[{{MatrixForm[N@H[4 ;; 6, ;;]], "γ = 1"}}]
```

[grille] [apparence m...] [valeur numérique]

Out[95]=

$$\begin{pmatrix} 24.5294 & -2.35294 & 2.35294 & 0.1 & 0. & 0. \\ -2.35294 & 1.23529 & -0.235294 & 0. & 1. & 0. \\ 2.35294 & -0.235294 & 1.23529 & 0. & 0. & 10. \end{pmatrix} \gamma = 1$$