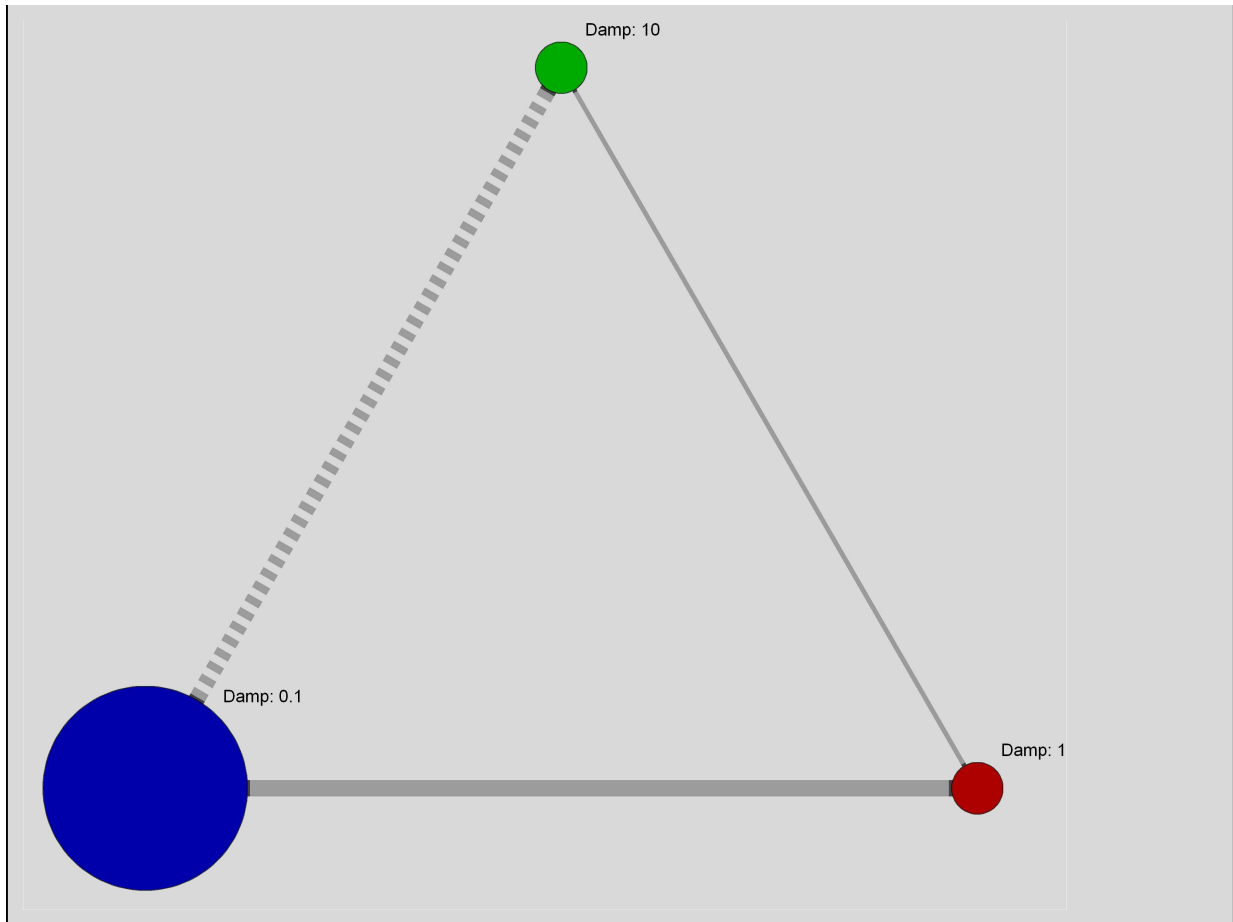


Synthetic Test Case Overview

In[1]:=

```
versca1 = 0.01;
versca2 = 0.05;
edgsca1 = 0.007;
edgsca2 = 0.02;
Graph[{Style[1, Darker@Blue], Style[2, Darker@Red], Style[3, Darker@Green]},
      {Style[1 ↔ 2, Thickness[ $\frac{40}{17}$  edgsca1], Gray], Style[2 ↔ 3, Thickness[ $\frac{4}{17}$  edgsca2], Gray],
      Style[3 ↔ 1, Thickness[ $\frac{40}{17}$  edgsca1], Dashed, Gray]}, VertexShapeFunction → "Circle",
      VertexSize → {1 ->  $\frac{417}{17}$  versca1, 2 ->  $\frac{21}{17}$  versca2, 3 ->  $\frac{21}{17}$  versca2},
      VertexLabels → {1 → "Damp: 0.1", 2 → "Damp: 1", 3 → "Damp: 10"}
```

Out[1]=



In[2]:=

$$H = \begin{pmatrix} 0 & 0 & 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 0 & -1 \\ \frac{417}{17} & -\frac{40}{17} & \frac{40}{17} & \frac{1}{10} & 0 & 0 \\ -\frac{40}{17} & \frac{21}{17} & -\frac{4}{17} & 0 & 1 & 0 \\ \frac{40}{17} & -\frac{4}{17} & \frac{21}{17} & 0 & 0 & 10 \end{pmatrix};$$

In[3]:=

$$\text{eqnham} = \text{Flatten}\left[\text{FullSimplify}\left[\begin{pmatrix} x_1'[t] \\ x_2'[t] \\ x_3'[t] \\ p_1'[t] \\ p_2'[t] \\ p_3'[t] \end{pmatrix} + H \cdot \begin{pmatrix} x_1[t] \\ x_2[t] \\ x_3[t] \\ p_1[t] \\ p_2[t] \\ p_3[t] \end{pmatrix}\right]\right];$$

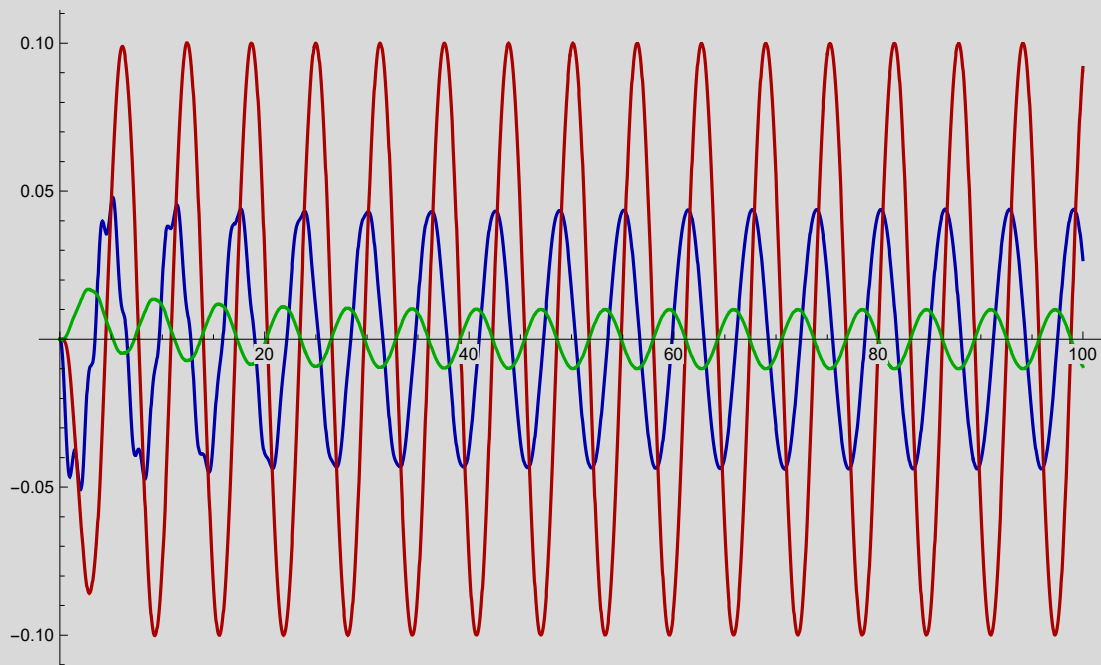
In[5]:=

```
solham = NDSolve [
  {eqnham[[1]] == 0, eqnham[[2]] == 0, eqnham[[3]] == 0, eqnham[[4]] == Cos[t + 1.7], eqnham[[5]] == 0,
  eqnham[[6]] == 0, x1[0] == 0, x2[0] == 0, x3[0] == 0, p1[0] == 0, p2[0] == 0, p3[0] == 0},
  {x1, x2, x3, p1, p2, p3}, {t, 0, 100}, Method -> "ImplicitRungeKutta"];
```

In[6]:=

```
Plot[{x1[t] /. solham, x2[t] /. solham, x3[t] /. solham}, {t, 0, 100}, PlotRange -> All,
PlotStyle -> {Darker@Blue, Darker@Red, Darker@Green}, ImageSize -> 570]
```

Out[6]=



Stochastic ODE & Data Generation

In[32]:=

```
proc = ItoProcess[{{a[t], b[t], c[t], - $\frac{a[t]}{10} - \frac{417 x[t]}{17} + \frac{40 y[t]}{17} - \frac{40 z[t]}{17} + \text{Cos}[t + 1.7]$ ,  

  -b[t] +  $\frac{40 x[t]}{17} - \frac{21 y[t]}{17} + \frac{4 z[t]}{17}$ , -10 c[t] -  $\frac{40 x[t]}{17} + \frac{4 y[t]}{17} - \frac{21 z[t]}{17}$ },  

  {{0}, {0}, {0}, {1/3}, {1/3}, {1/3}}, {x[t], y[t], z[t], a[t], b[t], c[t]},  

  {{x, y, z, a, b, c}, {0, 0, 0, 0, 0, 0}}, {t, 0}];  

time = 50;  

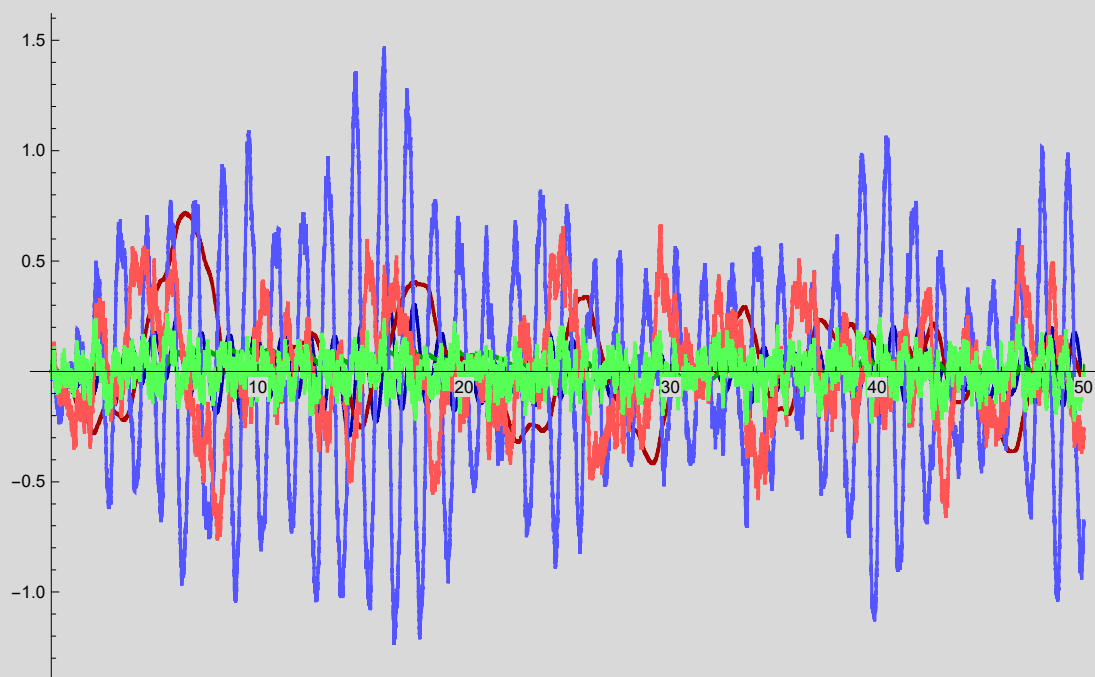
resolution = 10-3;  

path = RandomFunction[proc, {0., time, resolution}, Method → "StochasticRungeKutta";  

ListLinePlot[path, PlotStyle → {Darker@Blue, Darker@Red, Darker@Green,  

  Lighter@Blue, Lighter@Red, Lighter@Green}, PlotRange → All, ImageSize → 570]
```

Out[32]=



Discrete Frequencies

In[8]:=

```
time  
N@ $\frac{time}{2\pi}$  {1, 5}
```

Out[8]=

```
{7.95775, 39.7887}
```

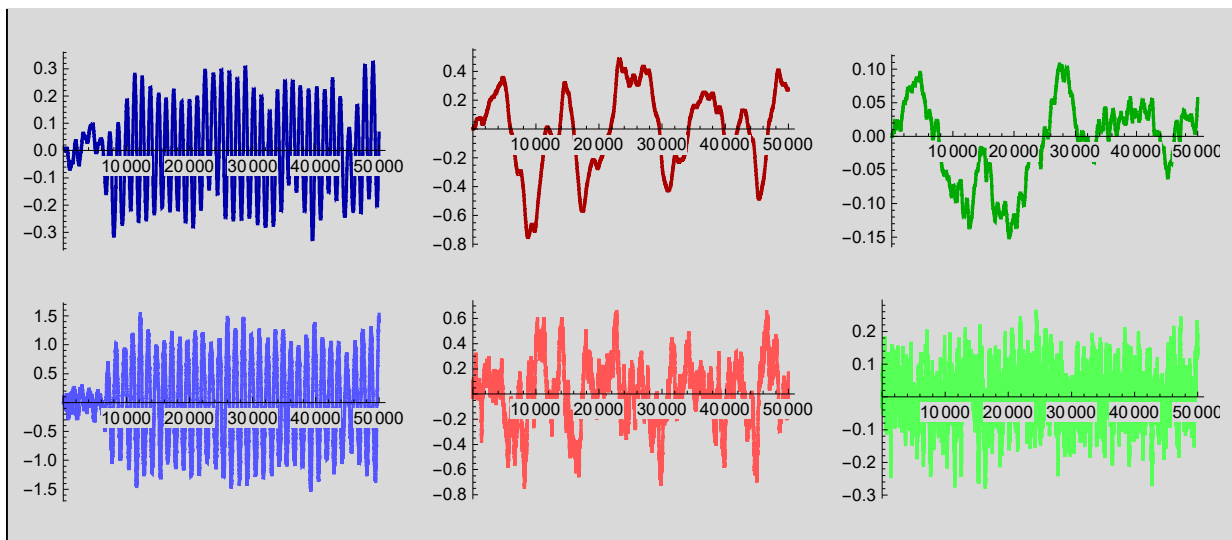
In[40]:=

```

tsfulldata = Flatten[Normal@
  |aplatis |forme normale
  RandomFunction[proc, {0., time, resolution}, Method → "StochasticRungeKutta"], 1];
  |fonction aléatoire |méthode
samples = Length[tsfulldata] - 1;
  |longueur
tssignal = Table[tsfulldata[[k, 2, i]], {i, 1, 6}, {k, 1, samples}];
  |table
tsderivative =
  Table[
    |table
    
$$\frac{\text{tsfulldata}[[k + 1, 2, i]] - \text{tsfulldata}[[k, 2, i]]}{\text{tsfulldata}[[k + 1, 1]] - \text{tsfulldata}[[k, 1]]}, \{i, 1, 6\}, \{k, 1, \text{samples}\}];
matrixsignal = Sum[{tssignal[[;;, k]]}^T.{tssignal[[;;, k]]}, {k, 1, samples}] / samples;
  |somme
matrixderivativesignal =
  Sum[{tssignal[[;;, k]]}^T.{tsderivative[[4;;6, k]]}, {k, 1, samples}] / samples;
  |somme
colorlist = {Darker@Blue, Darker@Red, Darker@Green,
  |plus fo... |bleu |plus fo... |ro... |plus fo... |vert
  Lighter@Blue, Lighter@Red, Lighter@Green};
  |plus clair |bleu |plus clair |ro... |plus clair |vert
fouriersignal = Table[Fourier[tssignal[[i]], {i, 1, 6}];
  |table |transformée de Fourier discrète
fourierderivative = Table[Fourier[tsderivative[[i]], {i, 1, 6}];
  |table |transformée de Fourier discrète
fouriermatrixsignal = Table[
  |table
  Re[Conjugate[{fouriersignal[[;;, k]]}^T].{fouriersignal[[;;, k]]}], {k, 1, samples}];
  |conjugué
fouriervectorderivativesignal = Table[Re[Conjugate[fourierderivative[[i, k]]
  |table |p... |conjugué
  fouriersignal[[;;, k]]], {i, 1, 6}, {k, 1, samples}];
fourierdynamic = Table[Abs[fourierderivative[[i + 3, k]] +
  |table |valeur absolue
  H[[4;;6, ;;]] [[i, ;;]].fouriersignal[[;;, k]], {i, 1, 3}, {k, 1, samples}];
GraphicsGrid[Partition[Table[ListPlot[tssignal[[i]], PlotRange → {{0, All}, All},
  |partitionne |table |tracé de liste |zone de tracé |tout |tout
  Joined → True, PlotStyle → colorlist[[i]], ImageSize → 190], {i, 1, 6}], 3]]
  |vrai |style de tracé |taille d'image$$

```

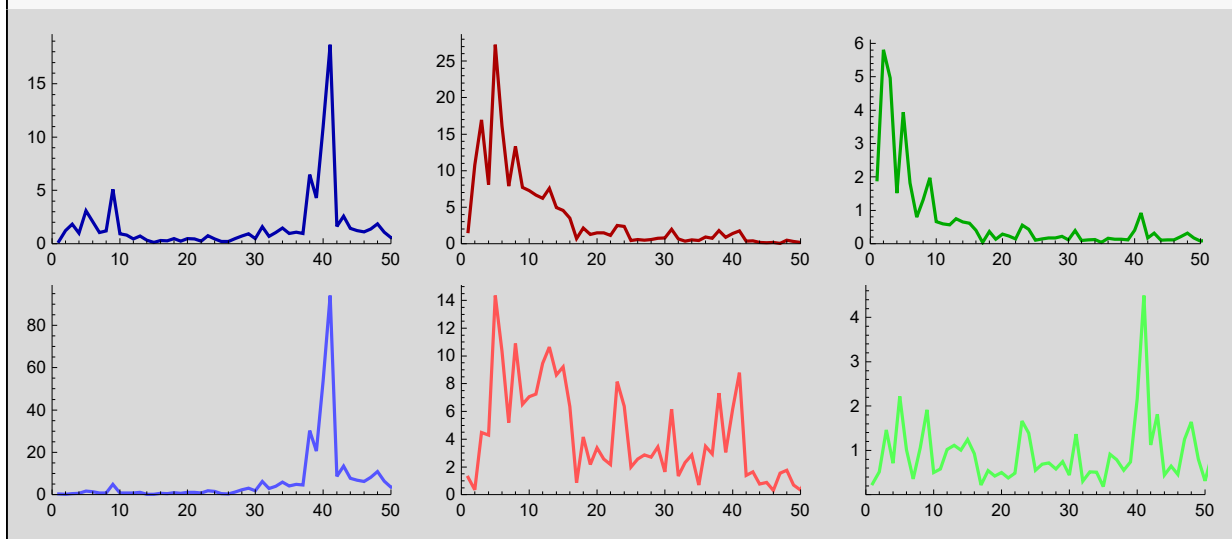
Out[40]=



In[41]:=

```
GraphicsGrid[
  grille de graphiques
  Partition[Table[ListPlot[Abs[fouriersignal[i]], PlotRange -> {{0, 50}, {0, All}},
    partitionne table tracé de liste valeur absolue zone de tracé tout
    Joined -> True, PlotStyle -> colorlist[i], ImageSize -> 190], {i, 1, 6}], 3]
    vrai style de tracé taille d'image
```

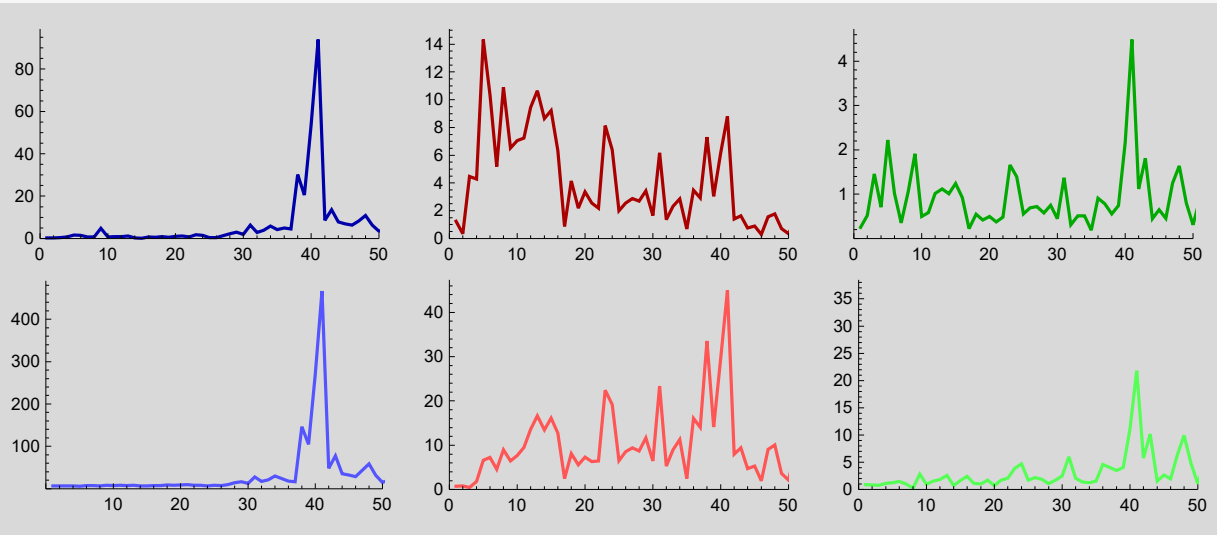
Out[41]=



In[42]:=

```
GraphicsGrid[Partition[
  grille de graphi... | partitionne
  Table[ListPlot[{Abs[fourierderivative[[i]]]}, PlotRange -> {{0, 50}, {0, All}},
    tracé de liste | valeur absolue | zone de tracé | tout
    Joined -> True, PlotStyle -> colorlist[[i]], ImageSize -> 190], {i, 1, 6}], 3]]
  vrai | style de tracé | taille d'image
```

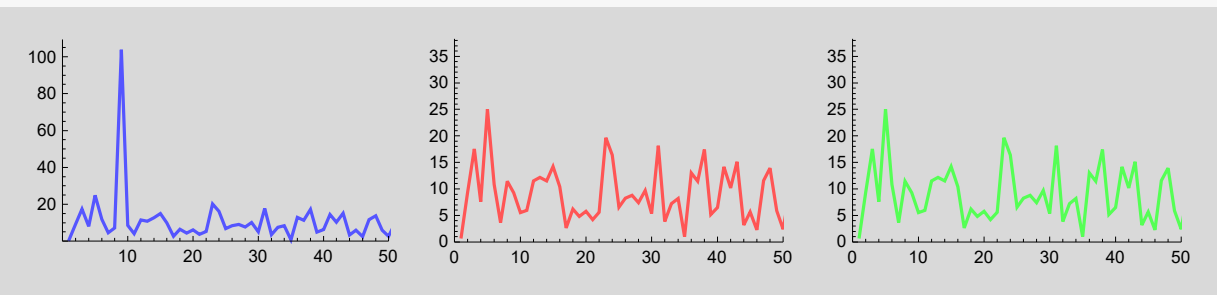
Out[42]=



In[43]:=

```
GraphicsGrid[
  grille de graphiques
  {Table[ListPlot[{Abs[fourierdynamic[[i]]]}, PlotRange -> {{0, 50}, {0, All}},
    table | tracé de liste | valeur absolue | zone de tracé | tout
    Joined -> True, PlotStyle -> colorlist[[i + 3]], ImageSize -> 190], {i, 1, 3}]}
  joint | vrai | style de tracé | taille d'image
```

Out[43]=



Log-Likelihood Regression

In[44]:=

```

localizationreg = Table[varmat =  $\begin{pmatrix} a_1 & b_1 & b_2 & c_1 & 0 & 0 \\ b_1 & a_2 & b_3 & 0 & c_2 & 0 \\ b_2 & b_3 & a_3 & 0 & 0 & c_3 \end{pmatrix}$ ;

NMinimize[ $\left\{ \text{Tr}[\text{varmat}^T \cdot \text{varmat} \cdot \text{matrixsignal}] + 2 \text{Tr}[\text{varmat} \cdot \text{matrixderivativesignal}] + \frac{1}{2} \gamma^2 - \frac{2 \gamma}{\sqrt{\text{samples}}} (\text{Tr}[\{\text{varmat}[[1, ;;]]^T \cdot \{\text{varmat}[[1, ;;]] \cdot \text{fouriermatrixsignal}[[k + 1]] + 2 \text{fouriervectorderivativesignal}[[3 + 1, k + 1]] \cdot \text{varmat}[[1, ;;]] + \text{Abs}[\text{fourierderivative}[[3 + 1, k + 1]]^2]^{1/2}, \gamma \geq 0 \&\& c_1 \geq 0 \&\& c_2 \geq 0 \&\& c_3 \geq 0 \&\& a_1 \geq 0 \&\& a_2 \geq 0 \&\& a_3 \geq 0 \right\}$ , {a1, a2, a3, b1, b2, b3, c1, c2, c3, γ}], {1, 1, 3}, {k, 0, 50}];

freqreg = Table[{k, localizationreg[[1, k + 1, 1]]}, {1, 1, 3}, {k, 0, 50}];

```

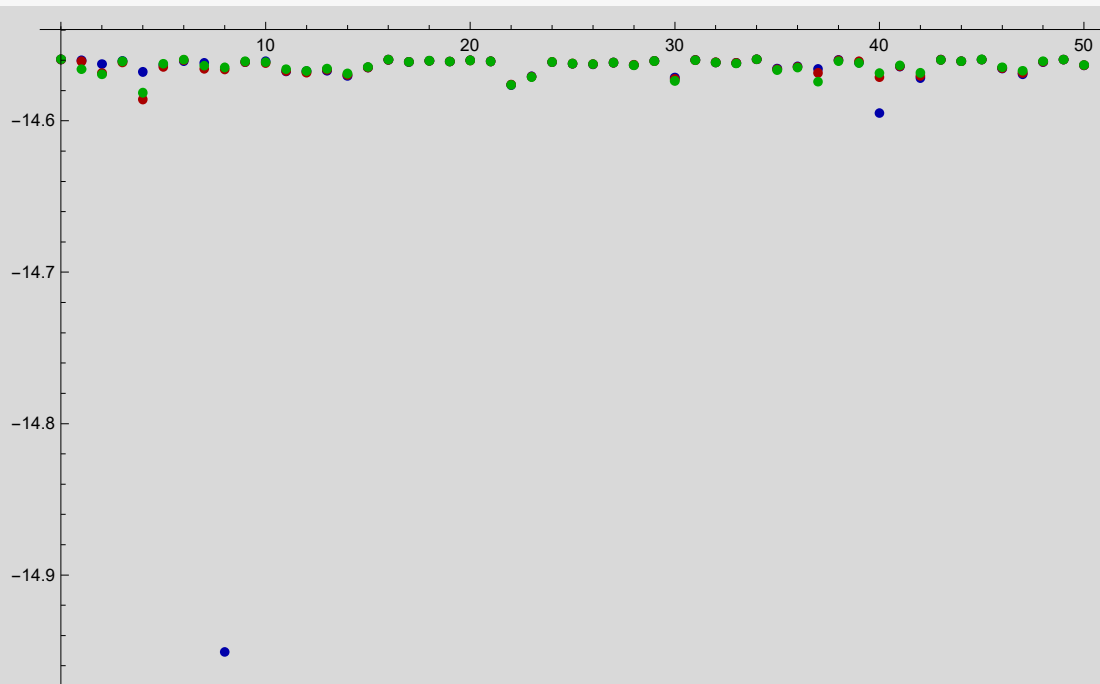
In[45]:=

```

ListPlot[freqreg, PlotRange → All, PlotStyle → colorlist[[1 ;; 3]], ImageSize → 570]

```

Out[45]=



Estimated Matrix & Amplitude

In[46]:=

```

siteest = 1;
frequest = 8;
Grid[{{MatrixForm[varmat /. localizationreg[siteest, frequest + 1, 2]],
  [grille] [apparence matricielle]
  "γ = " ~~ ToString[γ /. localizationreg[siteest, frequest + 1, 2]]}]]
  [convertis en chaîne de caractères]

```

Out[46]=

$$\begin{pmatrix} 24.4667 & -2.58193 & 2.43902 & 0.0289876 & 0 & 0 \\ -2.58193 & 1.05439 & -0.526089 & 0 & 1.147 & 0 \\ 2.43902 & -0.526089 & 1.98908 & 0 & 0 & 9.98179 \end{pmatrix} \gamma = 0.910979$$

Ground Truth

In[47]:=

```

Grid[{{MatrixForm[N@H[4 ;; 6, ;;]], "γ = 1"}}]
  [grille] [apparence m...] [valeur numérique]

```

Out[47]=

$$\begin{pmatrix} 24.5294 & -2.35294 & 2.35294 & 0.1 & 0. & 0. \\ -2.35294 & 1.23529 & -0.235294 & 0. & 1. & 0. \\ 2.35294 & -0.235294 & 1.23529 & 0. & 0. & 10. \end{pmatrix} \gamma = 1$$

Log-Likelihood Spatial Relaxation

In[48]:=

```

relocalizationreg = Table[varmat = 
$$\begin{pmatrix} a_1 & b_1 & b_2 & c_1 & 0 & 0 \\ b_1 & a_2 & b_3 & 0 & c_2 & 0 \\ b_2 & b_3 & a_3 & 0 & 0 & c_3 \end{pmatrix}$$
;

NMinimize[{Tr[varmatT.varmat.matrixsignal] + 2 Tr[varmat.matrixderivativesignal] +

$$\frac{1}{2} (\gamma_1^2 + \gamma_2^2 + \gamma_3^2) - \left( \frac{2 \gamma_1}{\sqrt{\text{samples}}} (\text{Tr}[\{\text{varmat}[[1, ;;]]^T \cdot \{\text{varmat}[[1, ;;]] \cdot \right.$$

fouriermatrixsignal[[k + 1]] + 2 fourivectorderivativesignal[[3 +
1, k + 1]].varmat[[1, ;;]] + Abs[fourierderivative[[3 + 1, k + 1]]2)1/2 +

$$\frac{2 \gamma_2}{\sqrt{\text{samples}}} (\text{Tr}[\{\text{varmat}[[2, ;;]]^T \cdot \{\text{varmat}[[2, ;;]] \cdot \text{fouriermatrixsignal}[[k + 1]] +$$

2 fourivectorderivativesignal[[3 + 2, k + 1]].varmat[[2, ;;]] +
Abs[fourierderivative[[3 + 2, k + 1]]2)1/2 + 
$$\frac{2 \gamma_3}{\sqrt{\text{samples}}}$$


$$(\text{Tr}[\{\text{varmat}[[3, ;;]]^T \cdot \{\text{varmat}[[3, ;;]] \cdot \text{fouriermatrixsignal}[[k + 1]] +$$

2 fourivectorderivativesignal[[3 + 3, k + 1]].varmat[[3, ;;]] +
Abs[fourierderivative[[3 + 3, k + 1]]2)1/2},

$$\gamma_1 \geq 0 \ \&\& \ \gamma_2 \geq 0 \ \&\& \ \gamma_3 \geq 0 \ \&\& \ c_1 \geq 0 \ \&\& \ c_2 \geq 0 \ \&\& \ c_3 \geq 0 \ \&\& \ a_1 \geq 0 \ \&\& \ a_2 \geq 0 \ \&\& \ a_3 \geq 0 \},$$

{a1, a2, a3, b1, b2, b3, c1, c2, c3, γ1, γ2, γ3}, {k, 0, 50}];
refreqreg = Table[{k, relocalizationreg[[k + 1, 1]]}, {k, 0, 50}];

```

In[49]:=

```
ListPlot[refreqreg, PlotRange → All, PlotStyle → Black, ImageSize → 570]
```

[tracé de liste

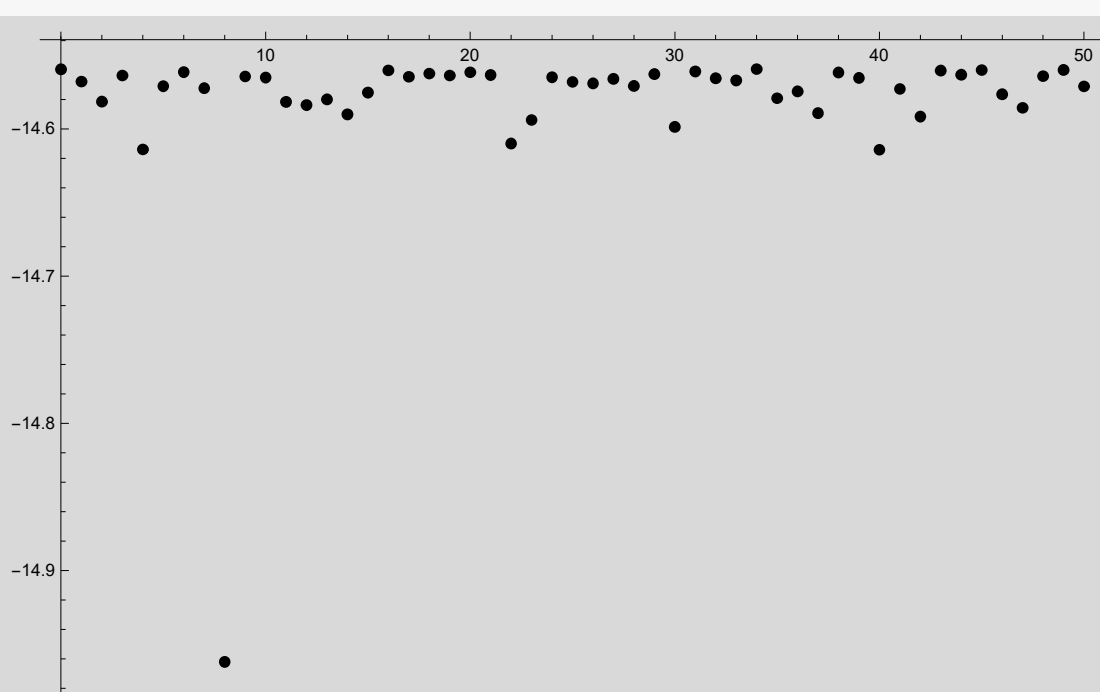
[zone de tracé

[tout

[style de tracé

[noir

[taille d'image



Out[49]=

Estimated Matrix & Amplitude

In[50]:=

```
frequest = 8;
```

```
Grid[{{MatrixForm[varmat /. relocalizationreg[[frequest + 1, 2]]],
```

[grille

[apparence matricielle

```
"(γ1, γ2, γ3) = " ~~ ToString[{γ1, γ2, γ3} /. relocalizationreg[[frequest + 1, 2]]]}}
```

[convertis en chaîne de caractères

Out[50]=

```
(
  24.473   -2.59643   2.3902   0.0290794   0   0
  -2.59643   1.01942  -0.585697   0   1.16075   0
   2.3902   -0.585697   2.23086   0   0   10.1016
)
```

(γ₁, γ₂, γ₃) =

{0.909947, 0.108548}

Ground Truth

In[51]:=

```
Grid[{{MatrixForm[N@H[4 ;; 6, ;;]], "γ = 1"}}]
```

[grille

[apparence m...

[valeur numérique

Out[51]=

```
(
  24.5294   -2.35294   2.35294   0.1   0.   0.
  -2.35294   1.23529  -0.235294   0.   1.   0.
   2.35294  -0.235294   1.23529   0.   0.  10.
)
```

γ = 1