

CN LAB

1BM/8CS077

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```
#include
```

```
using namespace std;
```

```
#define V 5
```

```
int minDistance(int dist[], bool sptSet[])  
{
```

```
    int min = 9999, min_index;
```

```
    for (int v = 0; v < V; v++)
```

```
        if (sptSet[v] == false && dist[v] <= min)
```

```
            min = dist[v], min_index = v;
```

```
    return min_index;
```

```
}
```

```
void printPath(int parent[], int j)
```

```
{
```

```
    if (parent[j] == -1)
```

```
        return;
```

```
    printPath(parent, parent[j]);
```

```
cout<<}
```

```
void printSolution(int dist[], int n, int parent[])  
{  
    int src = 0;  
    cout<<"Vertex\tDistance\tPath"< for (int i = 1; i <  
        V; i++)  
    {  
        cout<<"\n"< < printPath(parent, i);  
    }  
}
```

```
void dijkstra(int graph[V][V], int src)  
{
```

```
    int dist[V];
```

```
    bool sptSet[V];
```

```
    int parent[V];
```

```
    for (int i = 0; i < V; i++)  
    {  
        parent[i] = -1;
```

```
dist[i] = 9999;  
sptSet[i] = false;  
}
```

```
dist[src] = 0;
```

```
for (int count = 0; count < V - 1; count++)  
{
```

```
    int u = minDistance(dist, sptSet);
```

```
    sptSet[u] = true;
```

```
    for (int v = 0; v < V; v++)
```

```
        if (!sptSet[v] && graph[u][v] &&  
            dist[u] + graph[u][v] < dist[v])  
        {
```

```
            parent[v] = u;
```

```
            dist[v] = dist[u] + graph[u][v];  
        }
```

```
    }
```

```
printSolution(dist, V, parent);  
}
```

```
int main()
{
    int graph[V][V];
    cout<<"Enter the graph (Enter 99 for infinity): "<
    for(int i = 0; i<
    for(int j = 0; j< cin>>graph[i][j];
    }
    cout<<"Enter the source: "< int src;
    cin>>src;

    dijkstra(graph, src);
    cout<<"return 0;
}
```