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100	Unsupervised Machine le	
	Goal: To discover pal	
-		och as grouping similar
	low dimensional	representations.
	Example: Clustering, Dim Anomaly detection	
	Hnomoly derec	La deminate to
	Clustering:	similar dala mints
	· Making group of s	er the underlying
	structure of the do	
		ch as pattern recogni-
	The state of the s	The state of the s

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Application:	
a) For customer segment	ation:
-> You can cluste	er your customer based
on their purcha	.92
useful for	recommender system
The State of the S	Like Strandard Comment
b) For data analysis	: Annual Control of the Control of t
-> Perform an	alysis on each cluster.
anthol anthol	the Camara
a) Anomoly Detecti	00
	e which has a low
affinity to all	cluster is likely to be
anamaly deta	ection
well be har slok	ade In arutante
d) Dimensionality Re	Start Bit herst
e) for search engin	10 900m 100 m
f) to segment an i	mage

THE REPORT

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3	Approaches for Clustering
	a) Agglomerative:
	First considers all paints as individual
	clusters and then finds out the similarity bet
	two points, puts them into a cluster.
=	Then, It goes on finding similar points &
	clusters until there is only one cluster left te
	'all points belong to big cluster' -> bottom up
	Toplante of deciding and a second to talks
	b) Bivisive
-	· It is aposite of Agglomerative approach
=	first consider all points as a cluster
-	lin subsequent steps
3	Find out the points/cluster which are least similar to each other.
3	clusteras
-	biggercluster Continuetill many as

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variation among the point should be minimum. The with-in-cluster variance is denoted by W(CK). Hence, according to the statement above, we need to minimize this vovience for all the cluders.

Mathematically,

Williamise & K M(CK)

5) The next step is to define the criterion for measing the within cluster varience. Generally, the criterion is Euclidean Distances between the datapoints.

-> It calculates the mean of variance in each cluster.

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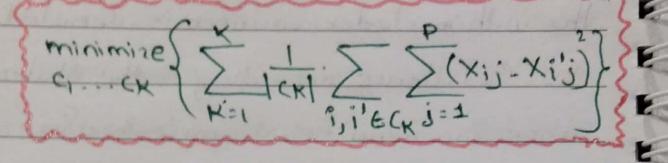
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So, ultimately, our goal is to minimize:



Algorithm:

- 1. Randomly assign K centres-
- 2. Calculate the distance of all the points from all the K centres and allocates the points to cluster based on the shortest distance. The model's inertia is the mean squared distance bet each instance & it's closest centroid. The goal is to have low mer-
- 3. Once all points are assigned to cluster, recompute the centroids.

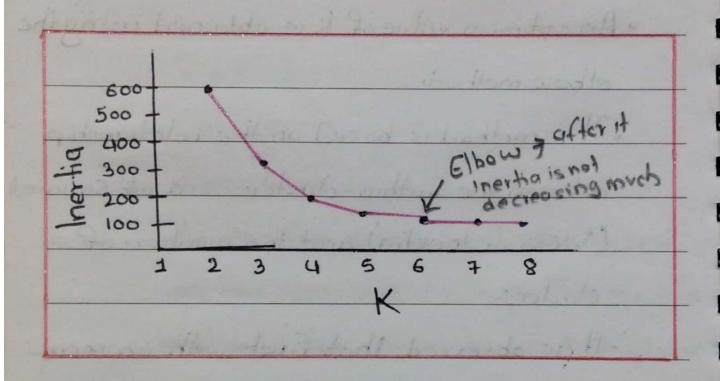
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3	4. Repeat the steps 2 and 3 until the location
3	of centroids stop changing and the cluste
7	- allocation of the points become constant.
	The state of the s
7	Elbow Method:
3	· An optimum value of K is obtained using the
3	elbow method.
3	. This method is based on the relationship
-	between the within cluster sum of square
	(WCSS or Inertia) and the number of
	clusters.
3	- It is observed that first with an incre-
3	ase in the numberied of clusters WCSS
3	decreases steeply and then after a
1	certain number of clusters, the drop in
1	wess is not that prominent.
2	The point after which the graph beth
9	

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was and the number of clusters become comparatively become smother is termed as the elbow.

· The number of cluster at the elbow point is optimum.



Challenges in K-Means:

DK-means do not behave well when cluster
have varying shape, size, different densities
or nonspherical shape

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	number of cluster before hand.
Improvement:	
K-Means ++	Many B. T. League B. C.
· Modified ver	sion of K-Heans
Steps:	of Belleville of Roll
1> Choose the f	first centroid randomly
2> For each data	point, calculate the distance
from the selection	cted centroid.
3> Assign the	probability to each data point
proportional to	the square of its distance
from the sel	ected centroid.
y choose the	next centroid randomly,
lidadora a him	ity that the selecting points
	ay from the existing centroid.
	til all k centroids have
been selected	

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PAssign data point to the closest centroid.

PRecalculate the centroids as the mean of the data points in each cluster

PRepeat 7-8 until rentroid no longer move or maximum number of iteration is reached.

The final K-cluster, along with their centroids form the O/p.

## Minibatch-Krleans

Instead of using full dataset at each iteration,
the algorithm is cable of using minibatches
moving centroid just slightly at each iteration.

This speedup the algorithm by 3-4 times

From skleam duster import MiniBatch KHeans

minibath\_kmeans = MiniBathKMeans (n\_dus=5)

minibatch\_ Kmeans fit (x)