

Eine Woche, ein Beispiel

7.18 irreducible representation of semisimple Lie alg

today: $\mathfrak{sl}_2(\mathbb{C})$ & $\mathfrak{sl}_3(\mathbb{C})$

Goal. 1 Get some informations of irr rep

- dim

- weight space + dim

- realization (eg. $\text{Sym}^n V, \wedge^n V, \dots$)

2. Understand why "each irr rep corresponds to each highest weight vector".

1. $sl_2(\mathbb{C})$

Notations:

the split basis $h = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$ $v_+ = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$ $v_- = \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}$

the compact basis of $sl_2(\mathbb{C})$ $\kappa = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$ $x_+ = \frac{1}{2} \begin{bmatrix} 1 & -i \\ -i & -1 \end{bmatrix}$ $x_- = \frac{1}{2} \begin{bmatrix} 1 & i \\ i & -1 \end{bmatrix}$

the Casimir element $\Omega = -\frac{\kappa^2}{4} + \frac{x_+ x_-}{2} + \frac{x_- x_+}{2}$

$$h.v_+ = 2v_+$$

$$h.v_- = -2v_-$$

$$[v_+, v_-] = h$$

$$\text{ad } h = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & -2 \end{bmatrix}$$

$$\text{ad } v_+ = \begin{bmatrix} 0 & 0 & 1 \\ -2 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\text{ad } v_- = \begin{bmatrix} 0 & -1 & 0 \\ 0 & 0 & 0 \\ 2 & 0 & 0 \end{bmatrix}$$

Lie bracket structure on $\Lambda^1 sl_2(\mathbb{C}) = \mathbb{C} \oplus sl_2(\mathbb{C}) \oplus \Lambda^2 sl_2(\mathbb{C}) \oplus \Lambda^3 sl_2(\mathbb{C})$:
of degree -1

$[\downarrow, \rightarrow]$	1	h	e	f	$e \wedge f$	$h \wedge f$	$h \wedge e$	$h \wedge e \wedge f$
1	0	0	0	0	0	0	0	0
h	0	0	$2e$	$2f$	0	$-2h \wedge f$	$2h \wedge e$	0
e	0	$-2e$	0	h	$-h \wedge e$	$-2e \wedge f$	0	0
f	0	$-2f$	h	0	$-h \wedge f$	0	$-2e \wedge f$	0
$e \wedge f$	0	0	$h \wedge e$	$h \wedge f$	0	0	0	0
$h \wedge f$	0	$2h \wedge f$	$2e \wedge f$	0	0	0	$-4h \wedge e \wedge f$	0
$h \wedge e$	0	$-2h \wedge e$	0	$2e \wedge f$	0	$-4h \wedge e \wedge f$	0	0
$h \wedge e \wedge f$	0	0	0	0	0	0	0	0

Representations: $\text{Sym}^n V$

$V \cong \mathbb{C}^2$: standard representation

e.g. $n = 3$

$$h \mapsto \begin{bmatrix} 3 & & & \\ & 1 & & \\ & & -1 & \\ & & & -3 \end{bmatrix} \quad v_+ \mapsto \begin{bmatrix} 0 & 1 & & \\ & 0 & 2 & \\ & & 0 & 3 \\ & & & 0 \end{bmatrix} \quad v_- \mapsto \begin{bmatrix} 0 & & & \\ 3 & 0 & & \\ 0 & 2 & 0 & \\ 0 & & 1 & 0 \end{bmatrix}$$

e.p. the adjoint representation is $\text{Sym}^2 V$

$$2v_- \xrightarrow{1/2} h \xrightarrow{1/2} -2v_+$$

$$y^2 \xrightarrow{1/2} xy \xrightarrow{1/2} x^2$$

2. $sl_3(\mathbb{C})$

Ref: I would recommend the book "Representation Theory -- a First Course" by Fulton. [Lecture 11-13].

Actually, if you just want to find the answer, then the website "https://www.jgibson.id.au/lievis/" can satisfy most of your requirement. And also if you want to draw the rank 2 root diagrams, then "https://ctan.org/pkg/rank-2-roots" may be a good choice.