

Eine Woche, ein Beispiel

1.21. complex multilinear algebra

The title comes from
<http://staff.ustc.edu.cn/~wangzuq/Courses/16F-Manifolds/Notes/Lec16.pdf>

We also take the reference from "Introduction to complex geometry", written by Yalong Shi:
http://maths.nju.edu.cn/~yshi/BICMR_ComplexGeometry.pdf

M : cplx mfld, $p \in M$

$M_{\mathbb{R}}$: M viewed as smooth mfld, not base change
 better: M_{sm}

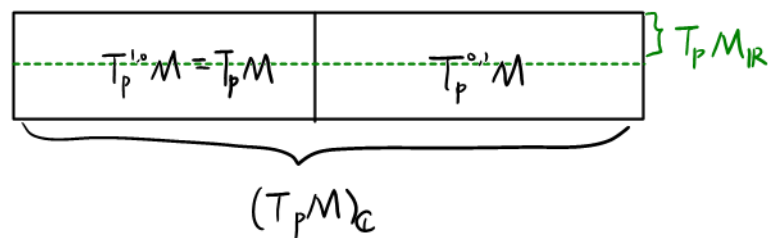
eg. $M = \mathbb{C}^3$ $p = 0$

Notation	base field	dim	basis	name	[YS20]
$T_p M$	\mathbb{C}	3	$\frac{\partial}{\partial z_i}$	holomorphic tangent vector	
$T_p M_{\mathbb{R}}$	\mathbb{R}	6	$\frac{\partial}{\partial x_i}, \frac{\partial}{\partial y_i}$	real tangent vector	$T_p^{\mathbb{R}} M$
$(T_p M)_{\mathbb{C}} = T_p M_{\mathbb{R}} \otimes_{\mathbb{R}} \mathbb{C}$	\mathbb{C}	6	$\frac{\partial}{\partial z_i}, \frac{\partial}{\partial \bar{z}_i}$ or $\frac{\partial}{\partial x_i}, \frac{\partial}{\partial y_i}$	complexified tangent vector	$T_p^{\mathbb{C}} M$
$T_p^{1,0} M = T_p M$	\mathbb{C}	3	$\frac{\partial}{\partial z_i}$	holomorphic tangent vector	
$T_p^{0,1} M$	\mathbb{C}	3	$\frac{\partial}{\partial \bar{z}_i}$	anti-holomorphic tangent vector	
$T_p^* M$	\mathbb{C}	3	dz_i	holomorphic 1-form	Ω_p^1
$T_p^* M_{\mathbb{R}} \hat{=} \Omega_{\mathbb{R}, p}^1$	\mathbb{R}	6	dx_i, dy_i	real 1-form	
$(T_p^* M)_{\mathbb{C}} = T_p^* M_{\mathbb{R}} \otimes_{\mathbb{R}} \mathbb{C}$	\mathbb{C}	6	$dz_i, d\bar{z}_i$ or dx_i, dy_i	complexified 1-form	$T_p^{\mathbb{C}} M = A_p^1$
$T_p^{1,0,*} M \hat{=} \Omega_p^{1,0} = T_p^{*,0} M$	\mathbb{C}	3	dz_i	(1,0)-form	$T_p^{1,0,*} M = A_p^{1,0}$
$T_p^{0,1,*} M \hat{=} \Omega_p^{0,1}$	\mathbb{C}	3	$d\bar{z}_i$	(0,1)-form	$T_p^{0,1,*} M = A_p^{0,1}$

$\Omega^i, \Omega^{i,j}$ sheaves on M

Rmk. We don't have any natural identification between $T_p M$ & $T_p M_{\mathbb{R}}$.
 Notice that $\frac{\partial}{\partial \bar{z}} = \frac{1}{2} \left(\frac{\partial}{\partial x} - i \frac{\partial}{\partial y} \right)$, $-\frac{1}{2}i$ is not real, so $\frac{\partial}{\partial \bar{z}} \notin T_p M_{\mathbb{R}}$.

although our geometrical intuition of $T_p M$ is often $T_p M_{\mathbb{R}}$



Reminder: the (induced) almost complex structure is defined as

$$J: T_p M_{\mathbb{R}} \longrightarrow T_p M_{\mathbb{R}}$$

$$\frac{\partial}{\partial x_i} \longmapsto \frac{\partial}{\partial y_i}$$

$$\frac{\partial}{\partial y_i} \longmapsto -\frac{\partial}{\partial x_i}$$

$$\rightsquigarrow J: T_p M \longrightarrow T_p M$$

$$J \left(\frac{\partial}{\partial x_i}, \frac{\partial}{\partial y_i} \right) = \left(\frac{\partial}{\partial x_i}, \frac{\partial}{\partial y_i} \right) \begin{pmatrix} & -1 \\ 1 & \end{pmatrix}$$

$$J \left(\frac{\partial}{\partial z_i}, \frac{\partial}{\partial \bar{z}_i} \right) = \left(\frac{\partial}{\partial z_i}, \frac{\partial}{\partial \bar{z}_i} \right) \begin{pmatrix} i & \\ & -i \end{pmatrix}$$