Topological data analysis Lecture 5

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Persistent homology: practical algorithm

- Previously we had D_1, D_2, \ldots matrices of simplicial differentials $\partial_i \colon C_i(K) \to C_{i-1}(K)$
- D_i is the incidence matrix between *i*-dim simplices and (i-1)-dim simplices at least over \mathbb{Z}_2 .
- Now we combine them all in a huge matrix D of size $N \times N$,
- ullet where N is the total number of simplices in a filtration.
- The order of rows and columns as in the array Simplices.

Gauss elimination on columns

- Reduce D by elementary operations on columns.
- It is allowed to any column, to add another column multiplied by a scalar.
- We move from left to right checking all $1 \le i \le N$.
- Let low(j) denote the index of the lowest nonzero element in j-th column.
- For each j we loop through r < j, and look for r such that low(r) = low(j).
- When we meet such r, we reduce j-th column by r-th column.
- We loop until low: [N] → [N] becomes injective. This is called the reduced form of a matrix.
- Permutations are not allowed.

You have the Matrix...

	1	2	4	23	34	12	24	234	13	14	123	124	134	1234
2						(1)								
3				(1)					(1)					
4					(1)		(1)			(1)				
23														
34														
12								0						
24								(1)						
234											0			
13											1	0		
14												(1)	(1)	
123														
124														
134														(1)
1234		0	0	0		0			0	0				

After Gauss elimination in columns

	1	2	4	23	34	12	24	234	13	14	123	124	134	1234
						1								
2						(1)								
3				(1)										
4					(1)									
23														
34														
12														
24								(1)						
234														
13											(1)			
14												(1)		
123														
124														
134														(1)
1234														

After Gauss

Look at the reduced matrix M.

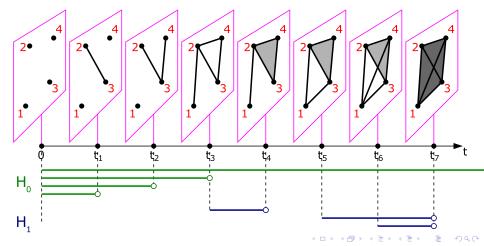
Theorem

- Let $j = low(s) \neq 0$ in M. Then **Simplices[j]** gives birth to homology of rank dim Simplices[j] and **Simplices[s]** kills this homology. Each such pair (j, s) gives rise to the interval module $I_{[BirthTimes[j],BirthTimes[s])}$.
- If the whole r-th column vanish and moreover $r \notin low([N])$, then Simplices[r] gives birth to homology of rank dim Simplices[r] which never dies. It gives the interval module $I_{[BirthTimes[r],+\infty)}$.

Persistent homology of the filtration is the direct sum of all the listed interval modules.

Example

Simplices = [1, 2, 3, 4, 23, 34, 12, 24, 234, 13, 14, 123, 124, 134, 1234] BirthTimes = [0, 0, 0, 0, t1, t2, t3, t3, t4, t5, t6, t7, t7, t7]



Our reduced matrix

	1	2	3	4	23	34	12	24	234	13	14	123	124	134	1234
1							1								
2					1		1								
3					1	1									
4						(1)									
23						$\overline{}$			1						
34									1						
12												1	1		
24									(1)				1		
234									\circ			_			1
13												(1)			
14													(1)		
123													\circ		1
124															1
134															(1)
1234															

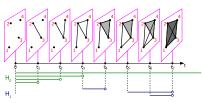
Circled elements have indices: [3,23], [4,34], [2,12], [24,234], [13,123], [14,124], [134,1234].

Reading births and deaths



Norns determine the fate of homology

Simplices = [1, 2, 3, 4, 23, 34, 12, 24, 234, 13, 14, 123, 124, 134, 1234] BirthTimes = [0, 0, 0, 0, 11, t2, t3, t3, t4, t5, t6, t7, t7, t7, t7]



- We see pairs: [3,23], [4,34], [2,12], [24,234], [13,123], [14,124], [134,1234].
- For example, vertex 3 gives rise to homology which dies when 23 appears.
- 3 appears at time 0, and 23 at time t_1 .
- Hence we have interval module $I_{[0;t_1)}$ in 0-th homology.
- etc...

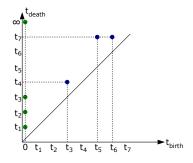
We have decomposition: $I_{[0;t_1)} \oplus I_{[0;t_2)} \oplus I_{[0;t_3)} \oplus I_{[t_3;t_4)} \oplus I_{[t_6;t_7)} \oplus I_{[t_6;t_7]} \oplus I_{[t_6;t_7$

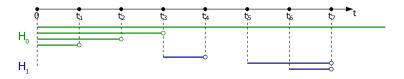
Real times

- Let K_t , $t \in \mathbb{R}$ be a collection of simplicial complexes on vertex set [m],
- such that $t_1 < t_2$ implies $K_{t_1} \subseteq K_{t_2}$.
- This is called a filtration with real time.
- Changes may occur only at discrete time moments.
- Therefore, the only difference is that BirthTimes stores real values.
- The algorithm above outputs the interval decomposition.

How to encode persistent homology?

Persistence diagram instead of barcode.





Philosophy

- If some homology lives long, then it is a meaningful homology.
- The lifetime = death time birth time.
- Lifetime is long, if the point of persistence diagram is far from the diagonal y = x.
- Points close to the diagonal are considered noise.
- Long-live-homology are important topological features of a filtration.

Filtrations: Čech

Demonstration: press to play in browser

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- Let $X = \{x_1, \dots, x_m\} \subset \mathbb{R}^d$ be a point-cloud.
- Let $X_t = \bigcup B_{t/2}(x_i)$.
- X_t is a filtration, but not of simplicial complexes.

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- Let $X_t = \bigcup B_{t/2}(x_i)$.
- X_t is a filtration, but not of simplicial complexes.
- Replace X_t by its **nerve**!

Nerve complex

Let $K_t^{\mathcal{C}}$ be a simplicial complex on [m], such that $\{i_1,\ldots,i_s\}\in K_t^{\mathcal{C}}$ iff

$$B_{t/2}(x_{i_1}) \cap \cdots \cap B_{t/2}(x_{i_s}) \neq \emptyset$$

Let $K_t^{\check{C}}$ be a simplicial complex on [m], such that $\{i_1,\ldots,i_s\}\in K_t^{\check{C}}$ iff $B_{t/2}(x_{i_1})\cap\cdots\cap B_{t/2}(x_{i_s})\neq\varnothing$.

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- ullet Therefore X_t and $K_t^{reve{\mathcal{C}}}$ have the same homology for each t.
- Hence they have the same persistent homology.
- \bullet We can work with simplicial filtration $\{\mathcal{K}_t^{\check{C}}\}$ called $\bar{\textbf{Cech}}$ filtration.

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- Simplex I is born at the time = minimal t for which balls of radii t/2 around x_i , $i \in I$, intersect.
- It may be difficult to find this number in practice.

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- $I \in K_t^{VR}$ iff all pairwise distances between x_i and x_j , for $i \neq j$, $i, j \in I$, are less than t.
- Simplex I is born at time moment $\max_{i \neq j \in I} \operatorname{dist}(x_i, x_j)$.

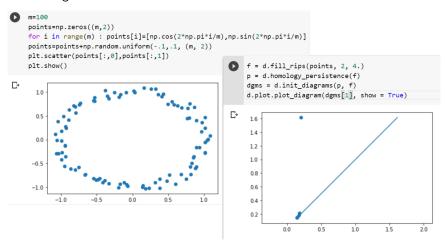
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- Very easy to compute birth times!
- Can be adapted to any finite metric space, e.g. metric graph.

Some experiments with Dionysus2

Link to Google Colab



- We have two filtrations $\{K_t\}$ and $\{L_t\}$ on the same set [m].
- Set $\operatorname{dist}(\{K_t\}, \{L_t\}) = \max_{I \subset [m]} |\operatorname{BirthTime}_K[I] \operatorname{BirthTime}_L[I]|$.

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- If $X = \{x_1, \dots, x_m\}$ and $Y = \{y_1, \dots, y_m\}$ are two data clouds and
- $dist(X, Y) = max_i dist(x_i, y_i)$, and
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- \bullet K_t^{VR} and L_t^{VR} are their Vietoris–Rips filtrations, then
- Exercise: $\operatorname{dist}(\{K_t^{\mathit{VR}}\},\{L_t^{\mathit{VR}}\})\leqslant 2\operatorname{dist}(X,Y).$
- What about their persistent diagrams?

Metric on diagrams

Bottleneck distance (or Wasserstein, or Kantorovich metric)

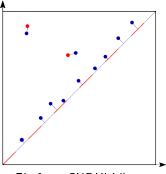


Fig.from GUDHI Library

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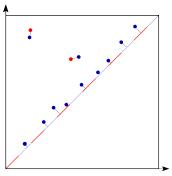


Fig.from GUDHI Library

Stability theorem

 $\mathsf{dist}(\mathsf{PD}(\{K_t\}), \mathsf{PD}(\{L_t\})) \leqslant \mathsf{dist}(\{K_t\}, \{L_t\}).$

Generalizations of persistent modules

We can hardly see this slide. However if we do, then it is time to switch to whiteboard

Sources



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Technical slide

Colab

Unity