# ST2334 AY23/24 Sem 2 Finals Cheat Sheet

## Chapter 1: Probability

| Sample Space                  | The sample space, denoted by S, is the set of ALL possible outcomes of a statistical experiment. The sample space depends on the problem of interest. An event is a subset of a sample space.   |  |
|-------------------------------|---|--|
| Notation                      | For a finite set A,  A  denotes the number of elements in A.  |  |
| Equally Likely<br>Probability | If S is a finite sample space in which all outcomes are equally likely and E is an event in S, then the <b>probability</b> of E, denoted $P(E)$ , is $P(E) = \frac{The \ number \ of \ outcomes \ in \ E}{The \ total \ number \ of \ outcomes \ in \ S} = \frac{ E }{ S }$ |  |
| Statistical<br>Experiment     | A Statistical Experiment is any procedure that produces data/<br>observations.  |  |
| Sample Point                  | A sample point is an outcome (element) in the sample space  |  |
| Event                         | An event is a subset of the sample space.   |  |

- The sample space is itself an event, and is called a sure event
- An event that contains NO ELEMENTS is the empty set, denoted by Ø, aka null event

| Event Operation & Relationship Laws |                                |  |  |
|-------------------------------------|--------------------------------|--|--|
| Basic                               |                                | Distributive Law                                 |  |
| $A \cap A' = \emptyset$             | $A \cap \emptyset = \emptyset$ | $A \cup (B \cap C) = (A \cup B) \cap (A \cup C)$ |  |
| $A \cup A' = S$                     | (A')' = A                      | $A \cap (B \cup C) = (A \cap B) \cup (A \cap C)$ |  |
| Set Union Law with Complement       |                                | Absorption Law                                   |  |
| $A \cup B = A \cup (B \cap A')$     |                                | $A = (A \cap B) \cup (A \cup B')$                |  |
| De Morgan's Law                     |                                |  |  |
| $(A_1 \cup A_2 \cup \cup A_N)' =$   |                                | $(A_1 \cap A_2 \cap \cap A_N)' =$                |  |
| $A'_1 \cap A'_2 \cap \cap A'_N$     |                                | $A'_1 \cup A'_2 \cup \cup A'_N$                  |  |
| Note: $(A \cup B)' = A' \cap B$     |                                | Note: $(A \cap B)' = A' \cup B$                  |  |

| D( )     | n! ( 4)( 2) (                            |
|----------|--|
| P(n,r) = | $\frac{n!}{(n-r)!} = n(n-1)(n-2)(n-r+1)$ |
|          |  |

| ,                         | Order Matters | Order Don't Matter |
|---------------------------|---------------|--------------------|
| Repetition is Allowed     | $n^k$         | $\binom{k+n-1}{k}$ |
| Repetition is NOT allowed | P(n,k)        | $\binom{n}{k}$     |

## Probability Axioms

Let S be a sample space. A probability function P from the set of all events in S to the set of real numbers satisfies the following axioms: For all events A and B in S,

- 1.  $0 \le P(A) \le 1$
- P(∅) = 0 and P(S) = 1
- 3. If A and B are disjoint events  $(A \cap B = \emptyset)$ , then (i.e A & B are mutually exclusive events)  $P(A \cup B) = P(A) + P(B)$

### Basic Properties of Probabilities

## Proposition 1:

The probability of the empty set  $\emptyset$  is  $P(\emptyset) = 0$ Proposition 2:

If  $A_1,A_2,\ldots,A_N$  are mutually exclusive events, that is  $A_i\cap A_j=0$  for any  $i\neq j$ , then

| $P(A_1 \cup A_2 \cup \cup A_N) = P(A_1) + P(A_2) + + P(A_N)$ |  |  |
|--|--|--|
| Proposition 3: Complement Rule                               | Proposition 4:                                   |  |
| For any event A, we have:                                    | For any 2 events A & B,                          |  |
| P(A') = 1 - P(A)   | $P(A) = P(A \cap B) + P(A \cap B')$              |  |
| Proposition 5: General Union 2 Events                        | Proposition 6:                                   |  |
| For any events A & B,  | If $A \subset B$ , then $P(A) \leq P(B)$         |  |
| $P(A \cup B) = P(A) + P(B) - P(A \cap B)$                    | $P(A) = P(A B) \cdot P(B) + P(A B') \cdot P(B')$ |  |

| Independence, Mutual Exclusivity                                   |   |  |  |
|--|---|--|--|
| ME   | <ul> <li>2 events CANNOT occur at the same time</li> <li>A, B mutually exclusive ⇔ P(A ∩ B) = Ø</li> </ul>  |  |  |
| Independent Indep $\rightarrow \bot$ dep $\rightarrow \mathcal{X}$ | $P(A) = \frac{P(A \cap B)}{P(B)} \Rightarrow P(A) \times P(B) = P(A \cap B)$ • A, B independent $\Leftrightarrow \frac{P(A \cap B)}{P(B)} = P(A)P(B)$ • If independent $\& P(A) \neq 0 \Rightarrow P(B A) = P(B)$ • If independent $\& P(B) \neq 0 \Rightarrow P(A B) = P(A)$ |  |  |
| Complement   | P(A') = 1 - P(A)  |  |  |
| Expected Value   | $\sum_{k=0}^{n} a_k p_k = a_1 p_1 + a_2 p_2 + a_3 p_3 + \dots + a_n p_n$  |  |  |

## Conditional Probability

$$A) = \frac{P(A \cap B)}{A} - (1)$$

| $P(B A) = \frac{P(A)}{P(A)} - (1)$   |                      |                            |                             |
|--|----------------------|----------------------------|-----------------------------|
| Multiplying both   | sides of (1) by P(A) |                            | es of (2) by P(B A)         |
| $P(A \cap B) = P(B A) \cdot P(A) - (2)$  |                      | $P(A) = \frac{P(A)}{P(B)}$ | $\frac{\cap B}{B A)}$ - (3) |
| Multiplication Rule  |                      |                            | bility Formula              |
| $P(A \cap B) = P(B A) \cdot P(A), if P(A) \neq 0$<br>$P(A \cap B) = P(A B) \cdot P(B), if P(B) \neq 0$ |                      | P(B A) =                   | $\frac{P(A \cap B)}{P(A)}$  |
|  |                      | Then inverse:              |                             |
|  |                      | $P(A B) = \frac{1}{2}$     | $\frac{P(A)P(B A)}{P(B)}$   |
| False Positive   | False Negative       | Sensitivity                | Specificity                 |
| P(+'ve   D')   | P(-'ve   D)          | P(+'ve   D)                | P(-'ve   D <sup>c</sup> )   |



## Partition, Law of Total Probability

$$P(B) = \sum_{i=1}^{N} P(B \cap A_i) = \sum_{i=1}^{N} P(A_i) P(B|A_i)$$

For any events A & B, we have: P(B) = P(A)P(B|A) + P(A')P(B|A')

| Bayes Theorem: |   |  |  |
|----------------|---|--|--|
| K variables    | $\begin{split} P(B_k A) &= \frac{P(A B_k) \cdot P(A_k)}{\sum_{l=1}^n P(B_l) P(A B_l)} \\ P(B_k A) &= \frac{P(A B_1) \cdot P(B_1)}{P(A B_1) \cdot P(B_1)} + \frac{P(A B_k) \cdot P(B_k)}{P(A B_2) \cdot P(B_2) + \dots + P(A B_n) \cdot P(B_n)} \end{split}$ |  |  |
| 2 variables    | $P(B A) = \frac{P(A B) \cdot P(B)}{P(A)} = \frac{P(A B) \cdot P(B)}{P(A B) \cdot P(B) + P(A \overline{B}) \cdot P(\overline{B})} = \frac{P(A \cap B)}{P(A)}$  |  |  |

## Pairwise Independent/ Mutually Independen

| • | Events are mutually independent IFF 4 conditions are satisfied: |   |  |
|---|---|---|--|
|   | $P(A \cap B) = P(A) \cdot P(B)$                                 | $P(A \cap C) = P(A) \cdot P(C)$                   |  |
|   | $P(B \cap C) = P(B) \cdot P(C)$                                 | $P(A \cap B \cap C) = P(A) \cdot P(B) \cdot P(C)$ |  |

- Events can be pairwise independent without satisfying the condition
- $P(A \cap B \cap C) = P(A) \cdot P(B) \cdot P(C)$ Conversely, they can satisfy the condition  $P(A \cap B \cap C) = P(A) \cdot P(B) \cdot$ P(C) without being pairwise independent.

### Mutually Independent:

 $P(A_1 \cap A_2 \cap ... \cap A_n) = P(A_1) \cdot P(A_2) \cdot ... \cdot P(A_n)$ 

|  | $P(A_1 \cap A_2 \cap \cap A_n) = P(A_1) \cdot P(A_2) \cdot \cdot P(A_n)$   |
|--|--|
| Chapter 2: Rand                          | om Variables   |
| Probability<br>Mass<br>Function<br>(PMF) | $f(x) = \begin{cases} P(X = x) & for \ x \in R_x \\ 0 & for \ x \notin R_x \end{cases}$ Properties of PMF: The pmf, $f(x)$ of a discrete random variable MUST satisfy these conditions: $1) \qquad f(x_i) \geq 0 \text{ for all } x_i \in R_x \\ 2) \qquad f(x_i) = 0 \text{ for all } x_i \notin R_x \\ 3) \qquad \sum_{i=1}^m f(x_i) = 1 \text{ OR } \sum_{x_i \in R_x} f(x_i) = 1$ For any set $B \subset \mathbb{R}$ , we have: $\sum_{x_i \in R_x} f(x_i) = \frac{1}{2} \int_{R_x}^{R_x} f(x_i) dx_i =$ |
| Probability                              | $P(X \in B) = \sum_{x_i \in B \cap R_X} f(x_i)$ 1) $f(x) \ge 0 \text{ for all } x \in R_X; f(x) = 0 \text{ for } x \notin R_X$   |
| Density<br>Function<br>(PDF)             | 1) $\int_{R_X} f(x) dx = 1$ 2) $\int_{R_X} f(x) dx = 1$ This is equivalent to: $\int_{-\infty}^{\infty} f(x) dx = 1 \operatorname{Since} f(x) = 0 \operatorname{for} x \notin R_X$ 3) For any $a$ and $b$ such that $a \le b$ :  |
|  | $P(a \le X \le b) = \int_{a}^{b} f(x) \ dx$  |
|  | Note: $P(a < X < b) = P(a < X \le b) = P(a \le X < b) = P(a \le X < b) = P(a \le X \le b) = \int_a^b f(x) \ dx$ . They all represent the area under the graph $f(x)$ between $x = a$ and $x = b$ . To check if pdf:  |
| Cumulative Dist                          | $1. f(x) \ge 0 \text{ for all } x \in R_X; f(x) = 0 \text{ for } x \notin R_X$ $2. \int_{R_X} f(x) dx = 1$ Fibution Function (CDF) $F(x) = P(X \le x)$   |

|                         | $2. \int_{R_X} f(x) dx = 1$   |
|-------------------------|---|
| <b>Cumulative Distr</b> | ibution Function (CDF) $F(x) = P(X \le x)$  |
| Discrete                | $F(x) = \sum_{t \in R_{X} \neq x},  f(t) = \sum_{t \in R_{X} \neq x} P(X = t)$ • The cumulative distribution function of a DRV is a step function. • For any 2 numbers $a < b$ , we have: $P(a \le X \le b) = P(X \le b) - P(X < a) = F(b) - F(a - 1)$ $F(a - 1) = \lim_{t \to a} F(x)$ |
| Continuous              | $F(x) = \int_{-\infty}^{x} f(t) dt , \qquad f(x) = \frac{dF(x)}{dx}$ Further: $P(a \le X \le b) = P(a < X < b) = F(b) - F(a)$   |

- Discrete → Summation; Continuous → Integrate
- The ranges of F(x) and f(x) satisfy the following conditions:
- 1. 0 < F(x) < 1
- 2. For discrete distributions,  $0 \le f(x) < 1$
- 3. For continuous distributions,  $0 \le f(x)$ , but NOT NECESSARILY that  $f(x) \le 1$

| Expectation & Variance **expectation = mean                    |   |  |  |
|--|---|--|--|
| Expectation for DRV  | Expectation for CRV                                 |  |  |
| $\mu x = E(X) = \sum_{x_i \in R_X} x_i f(x_i)$                 | $\mu x = E(X) = \int_{-\infty}^{\infty} x f(x)  dx$ |  |  |
| $= \sum_{x_i \in R_X} x_i P(X = x) = \frac{\sum f(x)}{\sum f}$ | $= \int_{x \in R_X} x f(x)  dx$ rbitrary function   |  |  |
|  |   |  |  |
| $E[g(X)] = \sum_{x \in R_X} g(x)f(x)$                          | $E[g(X)] = \int_{R_X} g(x)f(x) dx$                  |  |  |
| Variance   |   |  |  |
| $\sigma_X^2 = V(X) = E(X - \mu_X)^2 = E(X^2) - [E(X)]^2$       |   |  |  |
| Note:  |   |  |  |

# • $V(X) \ge 0$ for any X.

- Equality holds iff P(X = E(X)) = 1, that is when X is a constant
- The positive root of the variance = standard deviation of X

### $\sigma_X = \sqrt{V(X)}$ Variance for DRV Variance for CRV $V(X) = \sum_{x} (x - \mu_x)^2 f(x)$ $(x - \mu_x)^2 f(x) dx$

## Basic Properties of Expectations & Variance:

| Expectation                             | Variance                                 |
|---|--|
| a) $E(a) = a$                           | a) $V(a) = 0$                            |
| b) $E(aX) = aE(X)$                      | b) $V(aX) = a^2V(X)$                     |
| c) $E(aX \pm b) = aE(X) \pm b$          | c) $V(aX \pm b) = a^2V(X)$               |
| d) $E(aX \pm bY) = aE(X) \pm bE(Y)$     | d) $V(aX \pm bY) = a^2V(X) \pm b^2V(Y)$  |
| e) $E(x_1 + x_2 + \dots + x_n) = nE(X)$ | e) $V(x_1 + x_2 + \cdots + x_n) = nV(X)$ |
| $E(a_1X_1++a_kX_k)$                     |  |
| $= a_1E(X_1)++a_kE(X_k)$                |  |

| Chapter 3. Joint Distributions   |   |  |  |
|--|---|--|--|
|  | 2D Random Vector  |  |  |
| Let E be an ex   | periment and S be a corresponding sample space.                         |  |  |
| Suppose X and  | If Y are two functions each assigning a real number to each $s \in S$ . |  |  |
| We call $(X,Y)$ a <b>2D random vector</b> , or a <b>2D random variable</b> .   |   |  |  |
| 2D Discrete $ (X,Y) \text{ is a discrete 2D random variable if the number of possible values of } (X(s),Y(s)) \text{ are finite/countable.} $ That is, the possible values of $(X(s),Y(s))$ may be represented by: $ (x_{l},y_{l}),  i=1,2,3,; \ j=1,2,3 $ |   |  |  |
| 2D $(X,Y)$ is a <b>continuous 2D random variable</b> if the possible values of $(X(s),Y(s))$ can assume any value in some region of the Euclidean space $\mathbb{R}^2$ .   |   |  |  |

We can view X and Y separately to JUDGE whether (X, Y) is discrete or cont.

If both X and Y are discrete random variables → (X, Y) is discrete.

## • If both X and Y are continuous random variables $\rightarrow (X,Y)$ is continuous

## n-Dimensional Random Vector

Let  $X_1, X_2, \dots, X_n$  be n functions each assigning a real number to all outcome  $s \in S$ . We call  $(X_1, X_2, ..., X_n)$  a n-dimensional random vector, or a n-dimensional random variable.

### Discrete Joint Probability Function

 $f_{x,y}(x,y) = P(X = x, Y = y), for (x,y) \in R_{X,Y}$ 

### Properties of Discrete Joint Probability Function $f_{x,y}(x,y) \ge 0$ for any $(x,y) \in R_{X,Y}$

 $f_{x,y}(x,y) = 0$  for any  $(x,y) \notin R_{X,Y}$ 

$$\sum_{i=1}^{\infty} \sum_{j=1}^{\infty} f_{x,y}(x_i, y_j) = \sum_{i=1}^{\infty} \sum_{j=1}^{\infty} P(X = x_i, Y = y_j) = 1$$

$$\sum_{i=1}^{\infty} \sum_{j=1}^{\infty} f_{x,y}(x_i, y_j) = 1$$

Let A be any subset of  $R_{X,Y}$ , then

$$P((X,Y) \in A) = \sum_{(x,y) \in A} f_{X,Y}(x,y)$$

$$P((X,Y) \in D) = \iint_{(x,y) \in D} f_{x,y}(x,y) \, dy dx$$

For any  $D \subset \mathbb{R}^2$ , more specifically:

$$P(a \le X \le b, c \le Y \le d) = \int_{a}^{b} \int_{c}^{d} f_{x,y}(x, y) \, dy dx$$

## Properties of Continuous Joint Probability Function

 $f_{x,y}(x,y) \ge 0$  for any  $(x,y) \in R_{X,Y}$  $f_{x,y}(x,y) = 0$  for any  $(x,y) \notin R_{X,Y}$ 2.

> $f_{x,y}(x,y)\,dydx=1\qquad ,$  $f_{x,y}(x,y) dydx = 1$

| Y is DRV<br>(Discrete)   | For any $x$ : $f_x(x) = \sum_y f_{x,y}(x,y)$                                |  |
|--------------------------|---|--|
| Y is CRV<br>(Continuous) | For any $x$ : $f_x(x) = \int_{-\infty}^{\infty} f_{x,Y}(x,y)  dy$           |  |
| . Administrated          | table at a la lite a "and la at a " afab a 20 formation for (or a) and at a |  |

- Marginal distribution is like a "projection" of the 2D function  $f_{X,Y}(x,y)$  onto the 1D function.
- The marginal distribution of X is the individual distribution of X ignoring the values of Y.
- $f_X(x)$  is a probability function; so it satisfies all the properties of the probability function

# **Conditional Distribution**

|  | u, cona prob m:  | Given $f_y(y) > 0$ , cond prob in:                    |
|--|--|---|
| $f_{Y X}(y x) = \frac{f_{X,Y}(x,y)}{f_X(x)}$ |  | $f_{X Y}(x y) = \frac{f_{X,Y}(x,y)}{f_{Y}(y)}$        |
| If $f_x(x) > 0$ ,                            | $f_{X,Y}(x,y) = f_X(x)f_{Y X}(y x),$   | If $f_Y(y) > 0$ , $f_{X,Y}(x,y) = f_Y(y)f_{X Y}(x y)$ |
| Discrete                                     | $P(Y = y X = x) = \frac{P(X = x, Y = y)}{P(X = x)} = \frac{f_{X,Y}(x, y)}{f_X(x)}$ |   |
| Continuous                                   | $P(Y \le y   X = x) = \int_{-\infty}^{y} f_{Y X}(y x)  dy$                         |   |
|  | $E(Y X=x) = \int_{-\infty}^{\infty} y f_{Y X}(y x) dy$                             |   |

 $conditional\ distribution = \frac{joint\ density}{marginal\ distribution}$ 

### Independent Random Variables

Random variables X and Y are independent IFF for any x and y:

$$f_{X,Y}(x,y) = f_x(x)f_Y(y)$$

Random variables  $X_1, X_2, ..., X_n$  are independent IFF for any  $x_1, x_2, ..., x_n$ :

 $f_{X_1,X_2,...,X_n}(x_1,x_2,...,x_n) = f_{X_1}(x_1)f_{X_2}(x_2)...f_{X_n}(x_n)$ 

Just check if their joint probability = product of their individual probabilities

If  $R_{X,Y}$  is NOT a product space  $\rightarrow X$  and Y are NOT independent

# Properties of Independent Random Variables

## Suppose X, Y are independent random variables:

1. If A and B are arbitrary subsets of  $\mathbb{R}$ , the events  $X \in A$  and  $Y \in B$  are independent events in S. As such:

$$P(X \in A; Y \in B) = P(X \in A)P(Y \in B)$$
 For any real numbers  $x, y$ :

$$P(X \le x; Y \le y) = P(X \le x)P(Y \le y)$$

- 2. For arbitrary functions  $g_1(\bullet)$  and  $g_2(\bullet)$ ,  $g_1(X)$  and  $g_2(Y)$  are independent. For example
- X<sup>2</sup> and Y are independent.
- sin(X) and cos(Y) are independent.
- $e^X$  and log(Y) are independent.
- 3. Independence is connected with conditional distribution. - If  $f_X(x) > 0$ , then  $f_{Y|X}(y|x) = f_Y(y)$
- If  $f_Y(y) > 0$ , then  $f_{X|Y}(x|y) = f_X(x)$

depending on both x and y.

### CHECKING INDEPENDENCE

We have a handy way to check independence.

X and Y are independent if and only if both of the following hold:

(a)  $R_{XY}$ , the range where the probability function is positive, is a product space. (b) For any  $(x,y) \in R_{X,Y}$ , we have

 $f_{X,Y}(x,y) = C \times g_1(x) \times g_2(y).$ That is,  $f_{X,Y}(x,y)$  can be "factorized" as the product of two functions  $g_1$  and  $g_2$ , where  $g_1$  depends on x only,  $g_2$  depends on y only, and C is a constant not

Note:  $g_1(x)$  and  $g_2(y)$  on their own NEED NOT be probability functions.

| Definition 9: Expectation of 2-Dimensional Random Variables      |  |  |
|--|--|--|
| Consider any 2-variable function $g(x, y)$                       |  |  |
| (Discrete) $ E[g(X,Y)] = \sum_{x} \sum_{y} g(x,y) f_{X,Y}(x,y) $ |  |  |
| If $(x, y)$ is CRV<br>(Continuous)                               | $E[g(X,Y)] = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} g(x,y) f_{X,Y}(x,y)  dy dx$ |  |

 $g(X,Y) = (X - E(X))(Y - E(Y)) = (X - \mu_Y)(Y - \mu_Y)$ 

The expectation E[g(X,Y)] leads to the covariance of X and Y.

# The covariance of X and Y is defined to be:

cov(X,Y) = E[(X - E(X))(Y - E(Y))]If X and Y are  $cov(X,Y) = \sum \sum (x - \mu_x)(y - \mu_y) f_{X,Y}(x,y)$ (Discrete) If X and Y are CRV  $(x - \mu_x)(y - \mu_y)f_{X,Y}(x,y) dydx$ 

### (Continuous) Properties of the Covariance

1. cov(X,Y) = E(XY) - E(X)E(Y)

2. If X and Y are independent, then cov(X, Y) = 0

However, cov(X,Y) = 0 does not imply independence (1 way relation). i.e:

- i)  $X \perp Y \Rightarrow cov(X, Y) = 0$  (X &Y independent  $\rightarrow$  cov = 0)
- ightharpoonup Since  $E(XY) = E(X)E(Y) \rightarrow cov(X,Y) = 0$ ii)  $cov(X,Y) = 0 \Rightarrow X \perp Y$  (cov = 0 does not imply independence)
- 3.  $cov(aX + b, cY + d) = ac \cdot cov(X, Y)$
- i) cov(X, Y) = cov(Y, X)
- cov(X + b, Y) = cov(X, Y)
- iii)  $cov(aX, Y) = a \cdot cov(X, Y)$
- 4.  $V(aX + bY) = a^2V(X) + b^2V(Y) + 2ab \cdot cov(X, Y)$
- $V(aX) = a^2V(X)$
- ii) V(X + Y) = V(X) + V(Y) + 2cov(X, Y)

## **Properties of Variance and Covariance**

Using V(X + Y) = V(X) + V(Y) + 2cov(X, Y), we can derive the following:

1. For random variables X and Y that are independent, we have:

 $V(X \pm Y) = V(X) \pm V(Y)$ 

2. For random variables  $X_1, X_2, \dots, X_n$ , we have: (Not independent)  $V(X_1 + X_2 + ... + X_n) = V(X_1) + V(X_2) + ... + V(X_n) + 2 \sum_{i=1}^{n} cov(X_i, X_i)$ 

3. For random variables  $X_1, X_2, \dots, X_n$  that are independent, we have:

 $V(X_1 \pm X_2 \pm ... \pm X_n) = V(X_1) \pm V(X_2) \pm ... \pm V(X_n)$  $cov(X,Y) = \frac{1}{n-1} \sum_{i=1}^{n} (x_i - E(X))(y_i - E(Y))$  $V(X) = \frac{1}{n-1} \sum_{i=1}^{n} (x_i - E(X))^2$ 



To test if X and Y are independent: -Check  $f_{X,Y}(x,y) = f_X(x) \cdot f_Y(y)$  for all possible combinations





## **Chapter 4: Special Probability Distributions**

| ili a Discrete Offilo | n a Discrete Official Distribution.  |  |  |
|-----------------------|--|--|--|
| Expectation of X      | $\mu_X = E(X) = \sum_{i=1}^{k} x_i f_X(x_i) = \frac{1}{k} \sum_{i=1}^{k} x_i$      |  |  |
| Variance of<br>X      | $\sigma_X^2 = V(X) = E(X^2) - (E(X))^2 = \frac{1}{k} \sum_{i=1}^k x_i^2 - \mu_X^2$ |  |  |

# Note the Probability Equivalence:

- $P(X > a) = 1 P(X \le a)$
- $P(X < a) = P(X \le (a-1))$
- $P(b \le X \le a) = P(X \le a) P(X \le (b-1))$
- $P(b < X < a) = P(X \le (a-1)) P(X \le b)$
- $P(X \ge a) = 1 P(X \le (a-1))$

| <ul> <li>P(X ≤</li> </ul> | $a) = P(X \le a)$  |  |  |     |
|---------------------------|--|--|--|-----|
|                           | bability Distributions:  | V D  | noulli(p)  |     |
| Bern-<br>oulli            | f  | $A \sim Beri$<br>(x) = D(Y = x)  | $y = \begin{cases} p, & x = 1; \\ 1 - p, & x = 0; \end{cases}$                               |     |
|                           | )x'  | $p^{x}(1-p)^{1-x}, f$  | (1-p, x=0)   |     |
|                           | Expectation  |  | $\mu_X = E(X) = p$   | 1   |
|                           | Variance   |  | =V(X)=p(1-p)=pq  | 1   |
| Bino-<br>mial             | (Y = x   | $X \sim Bi$  | n(n,p)<br>$p)^{n-x}$ , for $x = 0,1,2,3,,n$  |     |
| illiai                    | Expectation  | $J = \binom{\chi}{\chi} p (1 - \frac{1}{\chi}) q (1 - \frac{1}{\chi}) $ | E(X) = nv  | 7   |
|                           | Variance   |  | V(X) = np(1-p)   | 1   |
|                           | • $E(X) = E(X_1) + \cdots$   | $+E(X_n)=p+$   | $\cdots + p = np$  |     |
|                           | <ul> <li>V(X) = V(X₁++</li> </ul>                                  | $V(X_1) = V(X_1) + V(X_1)$   | $+V(X_n) = pq++pq = npq$<br>B(k, p)  |     |
| Neg-<br>ative             | $f_X(x) = P(X = x) = ($  | $\binom{x-1}{k-1} p^k (1-1)$   | $p)^{x-k}$ , for $x = k, k + 1, k + 2$ ,   | 3,. |
| Bino-                     | Expectation  |  | $E(X) = \frac{k}{p}$   |     |
| mial                      | Variance   |  | $V(X) = \frac{p}{(1-p)k}$  |     |
| Geom-<br>etric            |  | $X \sim G\epsilon$<br>$f_{x}(x) = P(X = I)$  | com(n)   |     |
| cuit                      | Expectation  |  | $E(X) = \frac{1}{p}$ $E(X) = \frac{1}{p}$  | 1   |
|                           | Variance   |  | $V(X) = \frac{1-p}{p^2}$   | 1   |
| Poi-                      |  | X~Poisson(   | $\lambda$ ), where $\lambda > 0$   |     |
| sson                      |  | $f_X(k) = P(X$   | $=k)=\frac{e^{-\lambda k}}{k!}$  |     |
|                           |  | 0,1,is the #   | occurence of such events   |     |
|                           | Expectation<br>Variance  |  | $E(X) = \lambda$<br>$V(X) = \lambda$   | 4   |
|                           | Note:  | 1  | . (.,)   |     |
|                           |  |  | ion using Poisson Approx   |     |
|                           | <ul> <li>Given n → ∞ a</li> <li>&gt; n &gt; 20 an</li> </ul>       | nd $p \rightarrow 0$ in such<br>d $v < 0.05$ OR $r$  | h a way that $\lambda=np$ remains a const<br>$a\geq 100$ and $np\leq 10$                     | ant |
|                           | Poiss  | son Approximat   | tion (~~ Binomial)   |     |
|                           | 11 _   | $\lim_{0,n\to\infty} P(X=x)$   | $=\frac{e^{-np}(np)^x}{x!}$  |     |
| Cont-                     |  | X ~ U  | U(a,b)   |     |
| Inuous                    | PDF  |  | CDF $ (0, x < a)$  |     |
| Uni-                      | $f_X(x) = \begin{cases} \frac{1}{b-a}, \\ 0, \end{cases}$          | $a \le x \le b$ ;<br>otherwise   | $F_{\chi}(x) = \begin{cases} 0, & x < a \\ \frac{x-a}{b-a}, & a \le x \le b \end{cases}$     | b   |
| form                      |  |  | 1, x > b   |     |
|                           | Expectation  |  | $E(X) = \frac{a+b}{2}$   | 1   |
|                           | Variance   | V(X) =   | $E(X^{2}) - (E(X))^{2} = \frac{(b-a)^{2}}{12}$   | 1   |
|                           | $F_X(x) = 0$ when $x < a$<br>When $a \le x \le b$ :                | and $F_X(x) = 1$   | when $x > b$   |     |
|                           | $F_X(x) = \int_{-\infty}^{x} f_X(t)$                               | $dt = \int_{-\infty}^{a} 0 dt +$   | $-\int_{a}^{x} \frac{1}{b-a} dt = \frac{1}{b-a} [t]_{a}^{x} = \frac{x-a}{b-a}$               |     |
| Expon-                    |  | X∼E  | $xp(\lambda)$  |     |
| ential                    | 1st form   | if r > 0·  | 2 <sup>nd</sup> form   |     |
|                           | $f_X(x) = \begin{cases} \lambda e^{-\lambda x}, \\ 0, \end{cases}$ | $if x \le 0$ , $if x < 0$  | $f_{\chi}(x) = \begin{cases} \frac{1}{\mu} e^{-x/\mu}, & x \ge 0; \\ 0, & x < 0 \end{cases}$ |     |
|                           | E(X) =   | 1 1  | $E(X) = \mu$   |     |
|                           | $V(X) = E(X^2) - (I$   | $E(X))^2 = \frac{1}{\lambda^2}$  | $V(X) = E(X^2) - (E(X))^2 = \mu^2$   | 2   |
|                           | Inverse relationship   | $\mu = \frac{1}{\lambda}$  |  |     |
|                           | +'ve number s and  | t, we have:  | Distribution with $\lambda > 0$ . Then for an  | y 2 |
|                           |  |  | > s) = $P(X > t)emory"/ "memoryless"$  |     |
|                           | Exponential Distribution   |  | , . ,  |     |

Proof Memoryless: Given  $X \sim Exp(\lambda)$ , we check that:  $P(X > s + t | X > s) = \frac{P(\{X > s + t\} \cap \{X > s\})}{P(\{X > s + t\} \cap \{X > s\})}$ 

P(X > s)

 $=e^{-\lambda(t)}=P(X>t)$ 

 $=\frac{e^{-\lambda(s+t)}}{-\lambda(s+t)}$ 

P(X > s + t)

P(X > s)

|     |  | Λ - N (μ, υ )  |  |  |
|-----|--|--|--|--|
|     | $f_{\nu}(x)$   | $= \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu)^2}{2\sigma^2}}, -\infty < x < \infty$                     |  |  |
|     | 7, ()  |  |  |  |
|     | Expectation $E(X) = \mu$   |  |  |  |
|     | Variance   | $V(X) = E(X^2) - (E(X))^2 = \sigma^2$  |  |  |
|     | Properties of Normal I   |  |  |  |
|     | Total area under co  |  |  |  |
|     |  | me V(X), $\sigma^2 \rightarrow$ Same shape, maybe diff points.   |  |  |
|     |  | an, the more the curve shifts right.   |  |  |
|     |  | → curve flattens (Larger range of values)  |  |  |
|     | Standardized Normal I  |  |  |  |
|     |  | $Z \sim N(0,1), Z = \frac{X - \mu}{\sigma}$  |  |  |
|     | <ul> <li>E(Z) = 0 and V(Z</li> </ul>   | ) = 1.   |  |  |
|     | pdf o  | $f Z = \phi(z) = f_Z(z) = \frac{1}{\sqrt{2\pi}}e^{-\frac{z^2}{2}}$   |  |  |
|     |  | $\Phi(z) = \int_{-\infty}^{z} \phi(t) dt = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{z} e^{-\frac{t^2}{2}} dt$ |  |  |
|     | $X < x_2$ )  | 2) and any real numbers $x_1, x_2$ , where $P(x_1 <$   |  |  |
|     | $x_1 < X < x_2 \Leftrightarrow \frac{x_1 - \mu}{\sigma} < \frac{X - \mu}{\sigma} < \frac{x_2 - \mu}{\sigma}$           |  |  |  |
|     | $P(x_1 < X < x_2) = P(z_1 < Z < z_2), where z_1 = \frac{x_1 - \mu}{\sigma}, z_2 = \frac{x_2 - \mu}{\sigma}$            |  |  |  |
|     | $P(x_1 < X < x_2) = \Phi\left(\frac{x_2 - \mu}{\sigma}\right) - \Phi\left(\frac{x_1 - \mu}{\sigma}\right)$             |  |  |  |
|     | Properties of Standard   |  |  |  |
|     | <ol> <li>P(Z ≥ 0) = P(Z ≤</li> </ol>   | $S(0) = \Phi(0) = 0.5$<br>$P(Z \le z) = P(Z \ge -z) = 1 - \Phi(-z)$  |  |  |
|     | - Symmetric pro  |  |  |  |
|     | <ol> <li>If Z~N(0,1), then</li> </ol>  |  |  |  |
|     | 3. If $Z \sim N(0,1)$ , then $-Z \sim N(0,1)$ ;<br>4. If $Z \sim N(0,1)$ , then $\sigma Z + \mu \sim N(\mu, \sigma^2)$ |  |  |  |
|     | Approximation to Binomial  |  |  |  |
|     | Let $X \sim Bin(n, p)$ , so that $E(X) = np$ and $V(X) = np(1 - p)$ . $n \rightarrow \infty$ :                         |  |  |  |
|     | $Z = \frac{X - E(X)}{\sqrt{V(X)}} = \frac{X - np}{\sqrt{np(1 - p)}} is approximately \sim N(0, 1)$                     |  |  |  |
|     |  |  |  |  |
|     | Continuity Correction (IMPT) $P(X = k) \approx P(k - 1/2 < X < k + 1/2)$   |  |  |  |
|     | $P(a \le X \le b) \approx P(a - 1/2 \le X \le b + 1/2)$  |  |  |  |
|     | $P(a < X \le b) \approx P(a + 1/2 < X < b + 1/2)$  |  |  |  |
|     | $P(a \le X \le b) \approx P(a + 1/2 \le X \le b + 1/2)$  |  |  |  |
|     | $P(a < X < b) \approx P(a + 1/2 < X < b - 1/2)$  |  |  |  |
|     |  | $0 \le X \le c$ $\approx P(-1/2 < X < c + 1/2)$  |  |  |
|     |  | $(X \le n) \approx P(c + 1/2 < X < n + 1/2)$   |  |  |
| Cal | nnling & Samnling Distri   | hutions  |  |  |

Chapter 5: Sampling & Sampling Distributions

Denoted by σ<sup>2</sup>

| Sample Mean $\vec{X} = \frac{1}{n} \sum_{i=1}^{n} X_i$ |   | Realization  |
|--|---|--|
|  |   | $\bar{x} = \frac{1}{n} \sum_{i=1}^{n} x_i$           |
|  | Statistic   | Realization  |
| Sample<br>Variance                                     | $S^{2} = \frac{1}{1-1} \sum_{i=1}^{n} (X_{i} - \overline{X})^{2}$ | $s^2 = \frac{1}{n} \sum_{i=1}^{n} (x_i - \bar{x})^2$ |

# Validity of $\overline{X}$ as an estimator for $\mu_X$

- The expectation of  $\bar{X}$  is equal to the population mean  $\mu_X$ . ( $E(\bar{X}) = \mu_X$ )
- In the long run,  $\bar{X}$  does not introduce any systematic bias as an estimator of  $\mu_X$ . - Hence,  $\bar{X}$  can serve as a valid estimator of  $\mu_X$ .
- For an infinite population, when n gets larger and larger,  $\frac{\sigma \tilde{\chi}}{n}$ , the variance of  $\bar{X}$ , becomes smaller and smaller, that is, the accuracy of  $\bar{X}$  as an estimator of  $\mu_X$  keeps improving.  $\mu_{\bar{X}} = E(\bar{X}) = \mu_{\bar{X}} \& \sigma_{\bar{X}}^2 = V(\bar{X}) = \frac{\sigma_{\bar{X}}^2}{n}$

| Error         | <ul> <li>Measures tx<sub>x</sub>.</li> <li>Measures the spread of the sampling distribution (s.d).</li> <li>The standard error of X̄ describes how much X̄ tends to vary from sample to sample of size n.</li> <li>As n increases, <sup>x̄</sup>/<sub>n</sub> decreases → X̄ tends to be closer to μ<sub>X</sub> as n increases.</li> </ul> |  |
|---------------|---|--|
| Law of        | $P( \bar{X} - \mu  > \varepsilon) \to 0 \text{ as } n \to \infty$   |  |
| Large<br>Nums | <ul> <li>As such, X</li></ul>   |  |
|               | <ul> <li>As the sample size increases, the probability that the sample mean<br/>differs from the population mean goes to zero.</li> </ul>   |  |
|               | It is increasingly likely that $\bar{X}$ is close to $\mu_X$ , as $n$ gets larger   |  |
| CLT           | $\frac{\bar{X} - \mu}{\sigma / \sqrt{n}} \to Z \sim N(0,1) \ equivalently \ \bar{X} \to N\left(\mu, \frac{\sigma^2}{n}\right)$  |  |
|               | <ul> <li>Large n → random samples follows the normal distribution.</li> </ul>   |  |
|               | • In the case where $X_1, X_2, \dots, X_n$ are independent and identically  |  |
|               | distributed $N(\mu, \sigma^2)$ , then:  |  |
|               | $\bar{X} \sim N\left(\mu, \frac{\sigma^2}{n}\right),  or  \frac{\bar{X} - \mu}{\sigma/\sqrt{n}} \sim N(0, 1)$   |  |

Exactly, regardless of the sample size n. (For Normal Distribution)

| Chi            | A $\chi^2$ random variable with $n$ degree of freedom(df) as $\chi^2(n)$ .                                  |  |  |
|----------------|---|--|--|
| Square         | Properties of $\chi^2$ Distributions  |  |  |
| $\chi^2$       | <ol> <li>If Y~χ²(n), then E(Y) = n and V(Y) = 2n.</li> </ol>  |  |  |
| Distribu       | <ol> <li>For large n, χ<sup>2</sup>(n) is approximately N(n, 2n).</li> </ol>                                |  |  |
| tion           | 3. If $Y_1$ and $Y_2$ are independent $\chi^2$ random variables with $m$ and $n$                            |  |  |
|                | degrees of freedom respectively, then $Y_1 + Y_2$ is a $\chi^2$ random                                      |  |  |
|                | variable with $m + n$ degrees of freedom.   |  |  |
|                | <ol> <li>The χ<sup>2</sup> distribution is a family of curves, each determined by the</li> </ol>            |  |  |
|                | degrees of freedom, $n$ .   |  |  |
|                | <ul> <li>All the density functions have a LONG RIGHT TAIL.</li> </ul>                                       |  |  |
|                | $1 \sum_{n=1}^{\infty} x_n = x_n$   |  |  |
|                | $S^{2} = \frac{1}{n-1} \sum_{i=1}^{n} (X_{i} - \bar{X})^{2}$  |  |  |
|                | <i>i</i> =1   |  |  |
|                | • $E(S^2) = \sigma^2$   |  |  |
|                | <ul> <li>If S<sup>2</sup> is the VAR of a random sample of size n taken from a normal</li> </ul>            |  |  |
|                | population having the variance $\sigma^2$ , then the random variable:                                       |  |  |
|                | $\frac{(n-1)S^2}{\sigma^2} = \frac{\sum_{i=1}^{n} (X_i - \bar{X})^2}{\sigma^2}$                             |  |  |
|                | ${\sigma^2} = {\sigma^2}$   |  |  |
|                | Has a $\chi^2$ distribution with $n-1$ degrees of freedom. $T = \frac{Z}{\sqrt{\frac{U}{m}}}$               |  |  |
| t-             | $T = \frac{Z}{}$  |  |  |
| distribut      | 1 –   <del>U</del>  |  |  |
| ion            | $\sqrt{\overline{n}}$   |  |  |
|                | Follows the t-distribution with n degrees of freedom.   |  |  |
|                | Properties of t-Distribution  |  |  |
|                | <ol> <li>The t-Distribution approached N(0,1) as n → ∞.</li> </ol>  |  |  |
|                | <ul> <li>When n ≥ 30, we can replace it (approximate) it to be N(0,1).</li> </ul>                           |  |  |
|                | 2. If $T \sim t(n)$ , then $E(T) = 0$ and $V(T) = \frac{n}{(n-2)}$ for $n > 2$ .                            |  |  |
|                | The graph of the t-Distribution is symmetric about the vertical axis  |  |  |
|                | and resembles the graph of the standard normal distribution.  |  |  |
|                | (Graph $t(n)$ similar to graph $N(0,1)$ )   |  |  |
|                | ** t-distribution appears as a result of random sampling  |  |  |
|                | If X. X are independent and identically distributed normal random   |  |  |
|                | variables with mean $\mu$ and variance $\sigma^2$ , then: $\frac{3^2-\mu}{5/\sqrt{m}} \sim t(n)$            |  |  |
|                | variables with mean $\mu$ and variance $\sigma^2$ , then: $\frac{s}{s/\sqrt{n}} \sim t(n)$                  |  |  |
|                | Follows a t-Distribution with $n-1$ degrees of freedom.   |  |  |
| F-             | Follows a t-Distribution with $n-1$ degrees of freedom. $F = \frac{U/m}{V/L}$                               |  |  |
| Distribu       | $F = \frac{7  m}{V  I}$   |  |  |
| tion           | n   |  |  |
|                | Follows the F-distribution with $(m, n)$ degrees of freedom.  Properties of t-Distribution                  |  |  |
|                | 1. The F-distribution with $(m, n)$ df is denoted by: $F(m, n)$ .   |  |  |
|                | <ol> <li>The r-distribution with (m, n) or is denoted by: F (m, n).</li> <li>If X~F(m, n), then:</li> </ol> |  |  |
|                | 2. II X - F (III, II), tileli.  |  |  |
|                | $E(X) = \frac{1}{n-2}$ , for $n > 2$  |  |  |
|                | $E(X) = \frac{n}{n-2}, \text{ for } n > 2$ $V(X) = \frac{2n^2(m+n-2)}{m(n-2)^2(n-4)}, \text{ for } n > 4$   |  |  |
|                |   |  |  |
|                | 3. If $F \sim F(n, m)$ , then $\frac{1}{F} \sim F(m, n)$ .  |  |  |
|                | This follows immediately from the def of the F-Distribution.  |  |  |
|                | <ul> <li>The values of interest are F(m, n; α) such that:</li> </ul>  |  |  |
|                | $P(F > F(m, n; \alpha)) = \alpha$ , where $F \sim F(m, n)$  |  |  |
|                | 4. $F(m, m; 1 - \alpha) = \frac{1}{F}(n, m; \alpha)$  |  |  |
| Chapter 6: Est |   |  |  |
|                |   |  |  |

Let  $X_1, X_2, \dots, X_n$  be a random sample from the same population with mean  $\mu$  and var  $\sigma^2$ . Then  $S^2$  is an unbiased estimator of  $\sigma^2$ , since  $E(S^2) = \sigma^2$ 

$$S^{2} = \frac{1}{n-1} \sum_{i=1}^{n} (X_{i} - \bar{X})^{2}$$

Define  $z_{\alpha}$  to be the number with an upper-tail probability of  $\alpha$  for the standard normal distribution Z. That is  $P(Z > z_{\alpha}) = \alpha$ .

$$P\left(-z_{\alpha/2} \le \frac{\overline{X} - \mu}{\overline{\sigma}/\sqrt{n}} \le z_{\alpha/2}\right) = 1 - a$$

|  | · y n | /  |
|--|-------|--|
| To get Max Error                                 |       | To get min sample size                                     |
| $E = z_{\alpha/2} \cdot \frac{\sigma}{\sqrt{n}}$ |       | $n \ge \left(\frac{z_{\alpha/2} \cdot \sigma}{E}\right)^2$ |

# Point Estimate: Different Cases (Refer to Examplify Formula Sheet)

A confidence interval is a range of values that is likely to contain a population parameter based on a certain degree of confidence.

| Population Proportion:                                | Population Mean   |
|---|---|
| $CI = p^* \pm z^* \times \sqrt{\frac{p^*(1-p^*)}{n}}$ | $CI = \bar{x} \pm t^* \times \frac{s}{\sqrt{n}}$              |
| $z = \frac{x - \mu}{\sigma}$                          | $t = \frac{\bar{x} - \mu_0}{\left(\frac{s}{\sqrt{n}}\right)}$ |

## Independent: (Refer to Examplify Formula Sheet)

## Paired Data:

## Assumptions for Paired Data:

- 1.  $(X_1, Y_1), \dots, (X_n, Y_n)$  are matched pairs, where  $X_1, \dots X_n$  is a random sample from population 1,  $Y_1, \dots, Y_n$  is a random sample from population 2.
- X<sub>i</sub> and Y<sub>i</sub> are dependent.
- (X<sub>i</sub>, Y<sub>i</sub>) and (X<sub>i</sub>, Y<sub>i</sub>) are independent for any i ≠ j.
- 4. For matched pairs, define  $D_i = X_i Y_i$ ,  $\mu_D = \mu_1 \mu_2$ .
- 5. Now we can treat  $D_1, D_2, \dots, D_n$  as a random sample from a SINGLE population with mean  $\mu_D$  and variance  $\sigma_D^2$ .

We can employ all the techniques for single population to Paired Data.

| $T = \frac{\sum_{i=1}^{n} D_i}{\sum_{i=1}^{n} D_i} \sum_{i=1}^{n} (D_i - \overline{D})$ |                   | Where:  | Where:  | $\overline{D} - \mu_D$         |  |
|---|-------------------|---|---|--------------------------------|--|
| $\sqrt{n}$ $D = \frac{1}{n}$ $S_{\tilde{D}} = \frac{1}{n-1}$                            | $\overline{D})^2$ | $S_D^2 = \frac{Z_{i=1}D_i}{n}$ $S_D^2 = \frac{Z_{i=1}(D_i - D)}{n-1}$ | $\overline{D} = \frac{\sum_{i=1}^{n} D_i}{n}$ | $T = \frac{1}{S_D / \sqrt{n}}$ |  |

- If n < 30, and the population is normally distributed, then:  $T \sim t_{n-1}$
- If n ≥ 30 is large, then: T~N(0,1)

For paired data, if n is small & the pop is norm distributed, a  $100(1-\alpha)\%$  CI for  $\mu_n$ :

$$\bar{d} \pm t_{n-1;\alpha/2} \cdot \frac{s_D}{\sqrt{n}}$$

If n is large, a 100(1-lpha)% CI for  $\mu_{\!\scriptscriptstyle D}$   ${ar d} \pm z_{lpha/\!\!\!/}$ 

## Independent Sample vs Paired Data:

- . Independent samples involve measurements from two completely independent groups
- Paired Samples: Paired samples involve measuring the same individuals or units before and after a treatment, intervention, or simply over time.

### **Chapter 7: Hypothesis Testing**

# Step 1: Null Hypothesis vs Alternative Hypothesis

The outcome of hypothesis testing is either to REJECT or NOT REJECT  $H_0$ 

### Step 2: Level of Significance

For any test of hypothesis, there are only 2 possible conclusions:

- Reject Ho and therefore conclude Ho
- DO NOT Reject H<sub>0</sub> and therefore conclude H<sub>0</sub>.

Whatever decision is made, there is always a possibility of making an error:

DO NOT Reject H₀ Reject H<sub>n</sub> Correct Decision Type 1 Error Ho is FALSE Type II Frror Correct Decision

The rejection of H₀ when H₀ is TRUE is called a Type I error.

The probability of making a Type I error is called the **level of significance**,  $\alpha$ .  $\alpha = P(Type\ I\ Error) = P(Reject\ H_0|H_0\ is\ true)$ 

Not rejecting H<sub>0</sub> when H<sub>0</sub> is FALSE is called a Type II error.

The probability of making a Type II error, denoted by  $\beta$ . That is:  $\beta = P(Type\ II\ Error) = P(Do\ not\ reject\ H_0|H_0\ is\ false)$ The power of the test is defined by:

 $1 - \beta = P(Reject H_0|H_0 is false)$ Remarks: Type 1 and Type 2 errors are dependent events.

## Step 3: Test Statistics, Distribution and Rejection Region

As the significance level a is given, a decision rule can be found such that it divides the set of all possible values of the test statistic into two regions, one being the rejection region (or critical region) and the other, the acceptance region.

### Step 4 & 5: Calculation & Conclusion

- We check if the value is within our rejection region.
- YES → sample improbable assuming H<sub>0</sub> is true, hence we reject H<sub>0</sub>.

### - NO → We failed to reject H<sub>0</sub> p-value for Hypothesis Testing

Suppose the computed test statistic was z.

- For a 2-sided test, a "worse" result would be if |Z| > z or Z < −|z|. i.e</li> |Z| > |z|. tail
  - The p-value is given by:
    - p-value = P(|Z| > |z|) = 2P(|Z| > z) = 2P(Z < -|z|)
- For the alternative hypothesis H₁: μ < μ₀, the p-value is P(Z < −|z|), L</li>
- tail For the alternative hypothesis H<sub>1</sub>: μ > μ<sub>0</sub>, the p-value is P(Z > |z|), R

## Hypotest: Known Variance

1-tail test:  $H_0$ :  $\mu = \mu_0$  vs  $H_1$ :  $\mu < \mu_0$  OR  $\mu > \mu_0$ Reject  $H_0$  when  $\bar{X}$  is too large/small compared to  $\mu_0$ 

 $P(z < -z_{\alpha}) = \alpha \ OR \ P(z > z_{\alpha}) = \alpha$  $H_1: u < u_0 \rightarrow z < -z_0$   $H_1: u > u_0 \rightarrow z > z_0$ 2-tail test  $H_0$ :  $\mu = c$  vs  $H_1$ :  $\mu \neq \mu_0$ 

- Reject H<sub>0</sub> when X̄ is too large/small compared to μ<sub>0</sub>.
- $P(|Z| > z_{\alpha/2}) = \alpha$ • Rejection region is defined by:  $|Z|>z_{\alpha/2}$ , which is:
  - $z < -z_{\alpha/2}$  OR  $z > z_{\alpha/2}$

## Hypotest: Unknown Variance

# **1-tail** test: $H_0: \mu = \mu_0 \quad vs \quad H_1: \mu < \mu_0 \quad OR \ \mu > \mu_0$

Reject H<sub>0</sub> when X̄ is too large/small compared to μ<sub>0</sub>.

 $P(t < -t_{n-1;\alpha}) = \alpha \ OR \ P(t > t_{n-1;\alpha}) = \alpha$  $H_1: \mu > \mu_0 \rightarrow t > t_{n-1:\alpha}$ 

 $H_1: \mu < \mu_0 \rightarrow t < -t_{n-1:\alpha}$ **2-tail test:**  $H_0$ :  $\mu = c$  vs  $H_1$ :  $\mu \neq \mu_0$ 

• Reject  $H_0$  when  $\bar{X}$  is too large/small compared to  $\mu_0$ .  $P(|T| > t_{n-1:\alpha/2}) = \alpha$ 

• Rejection region is defined by:  $|Z|>z_{\alpha/2}$  , which is:

 $t < -t_{n-1;\alpha/2}$  OR  $t > t_{n-1;\alpha/2}$ 

Test Comparing Means: Independent Samples (Refer to Examplify Formula Sheet)

2P(Z > |z|) OR 2P(Z < -|z|)

### Independent Samples: Rejection Regions & p-value Rejection Region p-value P(Z > |z|) $\mu_1 - \mu_2 > \delta_0$ $z > z_{\alpha}$ $u_1 - u_2 < \delta_0$ P(Z < -|z|)z < -z

## $\mu_1 - \mu_2 \neq \delta_0$ $z > z_{\alpha/2} \text{ OR } z < -z_{\alpha/2}$ Test Comparing Means: Paired Data

- For paired data, define D<sub>i</sub> = X<sub>i</sub> − Y<sub>i</sub>.
- For paired data, define  $D_l=X_l-r_l$ .
   For the null hypothesis  $H_0$ :  $\mu_D=\mu_{D_0}$ , the test statistics is given by:  $T=\frac{D-\mu_{D_0}}{SD/\sqrt{n}}$
- If n is small (n < 30) and the population if normally distributed, then:  $T \sim t_{n-1}$
- If  $n \ge 30$  is large, then:  $T \sim N(0,1)$
- Equal variance applies when ½ ≤ S1/S2 ≤ 2