

1 Syntax

The syntax ...

2 MiniSail type system

2.1 Refinement constraint logic

$$\boxed{\llbracket l \rrbracket \sim rv}$$

$$\begin{array}{l} \overline{\llbracket n \rrbracket \sim num} \quad \text{EVAL_LIT_NUM} \\ \overline{\llbracket \mathbf{T} \rrbracket \sim \mathbf{true}} \quad \text{EVAL_LIT_TRUE} \\ \overline{\llbracket \mathbf{F} \rrbracket \sim \mathbf{false}} \quad \text{EVAL_LIT_FALSE} \\ \overline{\llbracket () \rrbracket \sim ()} \quad \text{EVAL_LIT_UNIT} \end{array}$$

$$\boxed{i\llbracket v \rrbracket \sim rv}$$

$$\begin{array}{l} \frac{\llbracket l \rrbracket \sim rv}{i\llbracket l \rrbracket \sim rv} \quad \text{EVAL_V_LIT} \\ \frac{rv = i(x)}{i\llbracket x \rrbracket \sim rv} \quad \text{EVAL_V_VAR} \\ \frac{i\llbracket v_1 \rrbracket \sim rv_1 \quad i\llbracket v_2 \rrbracket \sim rv_2}{i\llbracket (v_1, v_2) \rrbracket \sim (rv_1, rv_2)} \quad \text{EVAL_V_PAIR} \\ \frac{i\llbracket v \rrbracket \sim rv}{i\llbracket C \text{ tid } v \rrbracket \sim C \text{ tid } rv} \quad \text{EVAL_V_CONS} \\ \frac{i\llbracket v \rrbracket \sim rv}{i\llbracket C \text{ tid } [b]v \rrbracket \sim C \text{ tid } b \text{ } rv} \quad \text{EVAL_V_CONSP} \end{array}$$

$$\boxed{i\llbracket ce \rrbracket \sim rv}$$

$$\begin{array}{l} \frac{i\llbracket v \rrbracket \sim rv}{i\llbracket v \rrbracket \sim rv} \quad \text{EVAL_CE_VAL} \\ \frac{i\llbracket v_1 \rrbracket \sim rv_1 \quad i\llbracket v_2 \rrbracket \sim rv_2 \quad rv = rv_1 + rv_2}{i\llbracket v_1 + v_2 \rrbracket \sim rv} \quad \text{EVAL_CE_PLUS} \\ \frac{i\llbracket v_1 \rrbracket \sim rv_1 \quad i\llbracket v_2 \rrbracket \sim rv_2 \quad rv = rv_1 \Leftarrow rv_2}{i\llbracket va1 \leq va2 \rrbracket \sim rv} \quad \text{EVAL_CE_LEQ} \\ \frac{i\llbracket v_1 \rrbracket \sim rv_1}{i\llbracket \mathbf{fst} (v_1, v_2) \rrbracket \sim rv_1} \quad \text{EVAL_CE_FST} \\ \frac{i\llbracket v_2 \rrbracket \sim rv_2}{i\llbracket \mathbf{snd} (v_1, v_2) \rrbracket \sim rv_2} \quad \text{EVAL_CE_SND} \end{array}$$

$$\frac{i\llbracket v_1 \rrbracket \sim rv_1 \quad i\llbracket v_2 \rrbracket \sim rv_2 \quad rv = rv_1 @ rv_2}{i\llbracket v_1 @ v_2 \rrbracket \sim rv} \text{ EVAL_CE_CONCAT}$$

$$\frac{i\llbracket v \rrbracket \sim rv' \quad rv = \mathbf{len} \, rv'}{i\llbracket \mathbf{len} \, v_1 \rrbracket \sim rv} \text{ EVAL_CE_LEN}$$

$$\boxed{i\llbracket \phi \rrbracket \sim rv}$$

$$\frac{i\llbracket ce_1 \rrbracket \sim rv_1 \quad i\llbracket ce_2 \rrbracket \sim rv_2 \quad rv = (rv_1 = rv_2)}{i\llbracket ce_1 = ce_2 \rrbracket \sim rv} \text{ EVAL_C_EQ}$$

$$\frac{i\llbracket \phi_1 \rrbracket \sim rv_1 \quad i\llbracket \phi_2 \rrbracket \sim rv_2 \quad rv = rv_1 \wedge rv_2}{i\llbracket \phi_1 \wedge \phi_2 \rrbracket \sim rv} \text{ EVAL_C_AND}$$

$$\frac{i\llbracket \phi \rrbracket \sim rv' \quad rv = \sim rv'}{i\llbracket \neg \phi \rrbracket \sim rv} \text{ EVAL_C_NOT}$$

$$\frac{i\llbracket \phi_1 \rrbracket \sim rv_1 \quad i\llbracket \phi_2 \rrbracket \sim rv_2 \quad rv = rv_1 \implies rv_2}{i\llbracket \phi_1 \implies \phi_2 \rrbracket \sim rv} \text{ EVAL_C_IMP}$$

$$\boxed{i \models \phi}$$

$$\frac{i\llbracket \phi \rrbracket \sim \mathbf{true}}{i \models \phi} \text{ SATIS_CA_CA}$$

$$\boxed{i \models \Gamma}$$

$$\overline{i \models \cdot} \quad \text{SATIS_G_NIL}$$

$$\frac{i \models \Gamma \quad i \models \phi}{i \models \Gamma, x : b[\phi]} \text{ SATIS_G_CONS}$$

$$\boxed{\Theta \vdash_{wf} rv : b}$$

$$\overline{\Theta \vdash_{wf} \mathit{num} : \mathbf{int}} \quad \text{WF_RCL_V_INT}$$

$$\overline{\Theta \vdash_{wf} \mathbf{true} : \mathbf{bool}} \quad \text{WF_RCL_V_TRUE}$$

$$\overline{\Theta \vdash_{wf} \mathbf{false} : \mathbf{bool}} \quad \text{WF_RCL_V_FALSE}$$

$$\overline{\Theta \vdash_{wf} () : \mathbf{unit}} \quad \text{WF_RCL_V_UNIT}$$

$$\overline{\Theta \vdash_{wf} \mathbf{bitstr} : \mathbf{bvec}} \quad \text{WF_RCL_V_BVEC}$$

$$\begin{array}{c}
\frac{\Theta \vdash_{wf} rv_1 : b_1 \quad \Theta \vdash_{wf} rv_2 : b_2}{\Theta \vdash_{wf} (rv_1, rv_2) : b_1 * b_2} \text{WF_RCL_V_PAIR} \\
\\
\frac{\Theta \vdash_{wf} rv : b \quad \mathbf{union} \text{ } tid = \{ \overline{C_i : \tau_i}^i \} \in \Theta}{\Theta \vdash_{wf} C_j \text{ } tid \text{ } rv : tid} \text{WF_RCL_V_CONS} \\
\\
\frac{\Theta \vdash_{wf} rv : |\tau_j|_b[b_2/\beta] \quad \mathbf{union} \text{ } tid = \forall \beta. \{ \overline{C_i : \tau_i}^i \} \in \Theta}{\Theta \vdash_{wf} C_j \text{ } tid \text{ } b_2 \text{ } rv : \mathbf{bapp} \text{ } tid \text{ } b_2} \text{WF_RCL_V_CONSP} \\
\\
\frac{}{\Theta \vdash_{wf} \mathbf{usort} \text{ } rv : \beta} \text{WF_RCL_V_BOXED}
\end{array}$$

$$\boxed{\Theta; \Gamma \vdash i}$$

$$\begin{array}{c}
\frac{}{\Theta; \cdot \vdash i} \text{WF_VAL_EMPTY} \\
\\
\frac{rv = i(x) \quad \Theta \vdash_{wf} rv : b}{\Theta; \Gamma, x : b[\phi] \vdash i} \text{WF_VAL_CONS}
\end{array}$$

$$\boxed{\Theta; B; \Gamma \models \phi}$$

$$\frac{\Theta; B; \Gamma \vdash_{wf} \phi \quad \forall i. \Theta; \Gamma \vdash i \wedge i \models \Gamma \longrightarrow i \models \phi}{\Theta; B; \Gamma \models \phi} \text{VALID_VALID}$$

2.2 Wellformedness

$$\boxed{\vdash_{wf} \Theta} \quad \text{Wellformedness for type definition context}$$

$$\begin{array}{c}
\frac{}{\vdash_{wf} \cdot} \text{THETA_BEMPTY} \\
\\
\frac{tid \notin \text{dom}(\Theta) \quad \mathbf{distinct} \text{ } C_1 \dots C_n \quad C_1 \dots C_n \notin \Theta}{\vdash_{wf} \Theta, \mathbf{union} \text{ } tid = \{C_1 : \tau_1, \dots, C_n : \tau_n\}} \text{THETA_BUNION}
\end{array}$$

$$\boxed{\Theta; B \vdash_{wf} b} \quad \text{Wellformedness for base-type}$$

$$\begin{array}{c}
\frac{\vdash_{wf} \Theta}{\Theta; B \vdash_{wf} \mathbf{bool}} \text{WF_B_BOOL} \\
\\
\frac{\vdash_{wf} \Theta}{\Theta; B \vdash_{wf} \mathbf{int}} \text{WF_B_INT} \\
\\
\frac{\vdash_{wf} \Theta}{\Theta; B \vdash_{wf} \mathbf{unit}} \text{WF_B_UNIT} \\
\\
\frac{\vdash_{wf} \Theta}{\Theta; B \vdash_{wf} \mathbf{bvec}} \text{WF_B_BVEC}
\end{array}$$

$$\frac{\begin{array}{c} \Theta; B \vdash_{wf} b_1 \\ \Theta; B \vdash_{wf} b_2 \end{array}}{\Theta; B \vdash_{wf} b_1 * b_2} \quad \text{WF_B_PAIR}$$

$$\frac{\begin{array}{c} \vdash_{wf} \Theta \\ \mathbf{union} \text{ } tid = \{C_1 : \tau_1, \dots, C_n : \tau_n\} \in \Theta \end{array}}{\Theta; B \vdash_{wf} tid} \quad \text{WF_B_TID}$$

$$\frac{\beta \in B}{\Theta; B \vdash_{wf} \beta} \quad \text{WF_B_BVR}$$

$\boxed{\Theta \vdash_{wf} \Phi}$ Wellformedness for function definition context

$$\frac{\begin{array}{c} f \notin \text{dom}(\Phi) \\ \Theta; \cdot, \beta \vdash_{wf} b \\ \Theta; \cdot, \beta \vdash_{wf} x : b[\phi] \\ \Theta; \cdot, \beta; x : b[\phi] \vdash_{wf} \tau \end{array}}{\Theta \vdash_{wf} \Phi, \mathbf{val} \forall \beta. f : (x : b[\phi]) \rightarrow \tau} \quad \text{WF_P_VALSPEC_POLY}$$

$$\frac{\begin{array}{c} f \notin \text{dom}(\Phi) \\ \Theta; \cdot \vdash_{wf} b \\ \Theta; \cdot \vdash_{wf} x : b[\phi] \\ \Theta; \cdot; x : b[\phi] \vdash_{wf} \tau \end{array}}{\Theta \vdash_{wf} \Phi, \mathbf{val} f : (x : b[\phi]) \rightarrow \tau} \quad \text{WF_P_VALSPEC}$$

$$\frac{\vdash_{wf} \Theta}{\Theta \vdash_{wf} \cdot} \quad \text{WF_P_EMPTY}$$

$\boxed{\Theta; B \vdash_{wf} \Gamma}$ Wellformedness for immutable variable context

$$\frac{\vdash_{wf} \Theta}{\Theta; B \vdash_{wf} \cdot} \quad \text{WF_G_EMPTY}$$

$$\frac{\begin{array}{c} \Theta; B \vdash_{wf} \Gamma \\ \Theta; B \vdash_{wf} b \\ \Theta; B; \Gamma, x : b[\top] \vdash_{wf} \phi \\ x \notin \text{dom}(\Gamma) \end{array}}{\Theta; B \vdash_{wf} \Gamma, x : b[\phi]} \quad \text{WF_G_CONS}$$

$$\frac{\begin{array}{c} \Theta; B \vdash_{wf} \Gamma \\ \Theta; B \vdash_{wf} b \\ x \notin \text{dom}(\Gamma) \end{array}}{\Theta; B \vdash_{wf} \Gamma, x : b[\top]} \quad \text{WF_G_CONS_TRUE}$$

$$\frac{\begin{array}{c} \Theta; B \vdash_{wf} \Gamma \\ \Theta; B \vdash_{wf} b \\ x \notin \text{dom}(\Gamma) \end{array}}{\Theta; B \vdash_{wf} \Gamma, x : b[\perp]} \quad \text{WF_G_CONS_FALSE}$$

$\boxed{\Theta; B; \Gamma \vdash_{wf} \Delta}$ Wellformedness for mutable variable context

$$\frac{\Theta; B \vdash_{wf} \Gamma}{\Theta; B; \Gamma \vdash_{wf} \cdot} \quad \text{WF_D_EMPTY}$$

$$\frac{\begin{array}{c} \Theta; B; \Gamma \vdash_{wf} \Delta \\ \Theta; B; \Gamma \vdash_{wf} \tau \\ u \notin \text{dom}(\Delta) \end{array}}{\Theta; B; \Gamma \vdash_{wf} \Delta, u : \tau} \text{WF_D_CONS}$$

$\boxed{\Theta; B; \Gamma \vdash_{wf} v : b}$ WF for values

$$\frac{\begin{array}{c} \Theta; B \vdash_{wf} \Gamma \\ x : b[\phi] \in \Gamma \end{array}}{\Theta; B; \Gamma \vdash_{wf} x : b} \text{WF_V_VAR}$$

$$\frac{\Theta; B \vdash_{wf} \Gamma}{\Theta; B; \Gamma \vdash_{wf} n : \mathbf{int}} \text{WF_V_NUM}$$

$$\frac{\Theta; B \vdash_{wf} \Gamma}{\Theta; B; \Gamma \vdash_{wf} \mathbf{T} : \mathbf{bool}} \text{WF_V_TRUE}$$

$$\frac{\Theta; B \vdash_{wf} \Gamma}{\Theta; B; \Gamma \vdash_{wf} \mathbf{F} : \mathbf{bool}} \text{WF_V_FALSE}$$

$$\frac{\Theta; B \vdash_{wf} \Gamma}{\Theta; B; \Gamma \vdash_{wf} () : \mathbf{unit}} \text{WF_V_UNIT}$$

$$\frac{\begin{array}{c} \Theta; B; \Gamma \vdash_{wf} v : |\tau_j|_b \\ \mathbf{union} \text{ } tid = \{ \overline{C_i : \tau_i}^i \} \in \Theta \end{array}}{\Theta; B; \Gamma \vdash_{wf} C_j \text{ } tid \text{ } v : tid} \text{WF_V_CONS}$$

$$\frac{\begin{array}{c} \Theta; B; \Gamma \vdash_{wf} v : |\tau_j|_b[b_2/\beta] \\ \Theta; B \vdash_{wf} b_2 \\ \mathbf{union} \text{ } tid = \forall \beta. \{ \overline{C_i : \tau_i}^i \} \in \Theta \end{array}}{\Theta; B; \Gamma \vdash_{wf} C_j \text{ } tid[b_2]v : \mathbf{bapp} \text{ } tid \text{ } b_2} \text{WF_V_CONSP}$$

$$\frac{\begin{array}{c} \Theta; B; \Gamma \vdash_{wf} v_1 : b_1 \\ \Theta; B; \Gamma \vdash_{wf} v_2 : b_2 \end{array}}{\Theta; B; \Gamma \vdash_{wf} (v_1, v_2) : b_1 * b_2} \text{WF_V_PAIR}$$

$\boxed{\Theta; \Phi; B; \Gamma; \Delta \vdash_{wf} e : b}$ WF for expressions

$$\frac{\begin{array}{c} \Theta; B; \Gamma \vdash_{wf} \Delta \\ \Theta \vdash_{wf} \Phi \\ \Theta; B; \Gamma \vdash_{wf} v : b \\ \mathbf{val} \text{ } f : (x : b[\phi]) \rightarrow \tau \in \Phi \end{array}}{\Theta; \Phi; B; \Gamma; \Delta \vdash_{wf} f \text{ } v : |\tau|_b} \text{WF_E_APP}$$

$$\frac{\begin{array}{c} \Theta; B; \Gamma \vdash_{wf} \Delta \\ \Theta \vdash_{wf} \Phi \\ \Theta; B; \Gamma \vdash_{wf} v : b_1[b_2/\beta] \\ \mathbf{val} \forall \beta. f : (x : b_1[\phi]) \rightarrow \tau \in \Phi \end{array}}{\Theta; \Phi; B; \Gamma; \Delta \vdash_{wf} f[b_2]v : |\tau|_b[b_2/\beta]} \text{WF_E_APP_POLY}$$

$$\frac{\begin{array}{c} \Theta \vdash_{wf} \Phi \\ \Theta; B; \Gamma \vdash_{wf} \Delta \\ \Theta; B; \Gamma \vdash_{wf} v_1 : \mathbf{int} \\ \Theta; B; \Gamma \vdash_{wf} v_2 : \mathbf{int} \end{array}}{\Theta; \Phi; B; \Gamma; \Delta \vdash_{wf} v_1 + v_2 : \mathbf{int}} \text{WF_E_PLUS}$$

$$\frac{\begin{array}{l} \Theta \vdash_{wf} \Phi \\ \Theta; B; \Gamma \vdash_{wf} \Delta \\ \Theta; B; \Gamma \vdash_{wf} v_1 : \mathbf{int} \\ \Theta; B; \Gamma \vdash_{wf} v_2 : \mathbf{int} \end{array}}{\Theta; \Phi; B; \Gamma; \Delta \vdash_{wf} v_1 \leq v_2 : \mathbf{bool}} \quad \text{WF_E_LEQ}$$

$$\frac{\begin{array}{l} \Theta \vdash_{wf} \Phi \\ \Theta; B; \Gamma \vdash_{wf} \Delta \\ \Theta; B; \Gamma \vdash_{wf} v : b_1 * b_2 \end{array}}{\Theta; \Phi; B; \Gamma; \Delta \vdash_{wf} \mathbf{fst} v : b_1} \quad \text{WF_E_FST}$$

$$\frac{\begin{array}{l} \Theta \vdash_{wf} \Phi \\ \Theta; B; \Gamma \vdash_{wf} \Delta \\ \Theta; B; \Gamma \vdash_{wf} v : b_1 * b_2 \end{array}}{\Theta; \Phi; B; \Gamma; \Delta \vdash_{wf} \mathbf{snd} v : b_2} \quad \text{WF_E_SND}$$

$$\frac{\begin{array}{l} \Theta \vdash_{wf} \Phi \\ \Theta; B; \Gamma \vdash_{wf} \Delta \\ \Theta; B; \Gamma \vdash_{wf} v : \mathbf{bvec} \end{array}}{\Theta; \Phi; B; \Gamma; \Delta \vdash_{wf} \mathbf{len} v : \mathbf{int}} \quad \text{WF_E_LEN}$$

$$\frac{\begin{array}{l} \Theta \vdash_{wf} \Phi \\ \Theta; B; \Gamma \vdash_{wf} \Delta \\ \Theta; B; \Gamma \vdash_{wf} v_1 : \mathbf{bvec} \\ \Theta; B; \Gamma \vdash_{wf} v_2 : \mathbf{bvec} \end{array}}{\Theta; \Phi; B; \Gamma; \Delta \vdash_{wf} v_1 @ v_2 : \mathbf{bvec}} \quad \text{WF_E_CONCAT}$$

$$\frac{\begin{array}{l} \Theta \vdash_{wf} \Phi \\ \Theta; B; \Gamma \vdash_{wf} \Delta \\ \Theta; B; \Gamma \vdash_{wf} v_1 : \mathbf{int} \\ \Theta; B; \Gamma \vdash_{wf} v_2 : \mathbf{bvec} \end{array}}{\Theta; \Phi; B; \Gamma; \Delta \vdash_{wf} \mathbf{split} v_1 v_2 : \mathbf{bvec} * \mathbf{bvec}} \quad \text{WF_E_SPLIT}$$

$$\frac{\begin{array}{l} \Theta \vdash_{wf} \Phi \\ \Theta; B; \Gamma \vdash_{wf} \Delta \\ u : \tau \in \Delta \end{array}}{\Theta; \Phi; B; \Gamma; \Delta \vdash_{wf} u : |\tau|_b} \quad \text{WF_E_MVAR}$$

$$\boxed{\Theta; B; \Gamma \vdash_{wf} \phi}$$

WF for constraints

$$\frac{\begin{array}{l} \Theta; B; \Gamma \vdash_{wf} \phi_1 \\ \Theta; B; \Gamma \vdash_{wf} \phi_2 \end{array}}{\Theta; B; \Gamma \vdash_{wf} \phi_1 \wedge \phi_2} \quad \text{WF_C_CONJ}$$

$$\frac{\begin{array}{l} \Theta; B; \Gamma \vdash_{wf} \phi_1 \\ \Theta; B; \Gamma \vdash_{wf} \phi_2 \end{array}}{\Theta; B; \Gamma \vdash_{wf} \phi_1 \implies \phi_2} \quad \text{WF_C_IMP}$$

$$\frac{\begin{array}{l} \Theta; \cdot; B; \Gamma; \cdot \vdash_{wf} e_1 : b \\ \Theta; \cdot; B; \Gamma; \cdot \vdash_{wf} e_2 : b \end{array}}{\Theta; B; \Gamma \vdash_{wf} ce_1 = ce_2} \quad \text{WF_C_EQ}$$

$$\boxed{\Theta; B; \Gamma \vdash_{wf} \tau}$$

WF for types

$$\frac{\Theta; B; \Gamma, z : b[\top] \vdash_{wf} \phi}{\Theta; B; \Gamma \vdash_{wf} \{z : b|\phi\}} \quad \text{WF_T_TAU}$$

$\Theta; \Phi; B; \Gamma; \Delta \vdash_{wf} s : b$

WF for statements

$$\begin{array}{c}
\frac{\Theta \vdash_{wf} \Phi \quad \Theta; B; \Gamma \vdash_{wf} \Delta \quad \Theta; B; \Gamma \vdash_{wf} v : b}{\Theta; \Phi; B; \Gamma; \Delta \vdash_{wf} v : b} \text{WF_S_VAL} \\
\\
\frac{u \notin \text{dom}(\Delta) \quad \Theta; B; \Gamma \vdash_{wf} v : b_1 \quad \Theta; \Phi; B; \Gamma; \Delta, u : \tau \vdash_{wf} s : b_2}{\Theta; \Phi; B; \Gamma; \Delta \vdash_{wf} \mathbf{var} \, u : \tau := v \mathbf{in} \, s : b_2} \text{WF_S_VAR} \\
\\
\frac{\Theta \vdash_{wf} \Phi \quad \Theta; B; \Gamma \vdash_{wf} \Delta \quad u : \{z : b | \phi\} \in \Delta \quad \Theta; B; \Gamma \vdash_{wf} v : b}{\Theta; \Phi; B; \Gamma; \Delta \vdash_{wf} u := v : \mathbf{unit}} \text{WF_S_ASSIGN} \\
\\
\frac{\Theta; B; \Gamma \vdash_{wf} v : \mathbf{bool} \quad \Theta; \Phi; B; \Gamma; \Delta \vdash_{wf} s_1 : b \quad \Theta; \Phi; B; \Gamma; \Delta \vdash_{wf} s_2 : b}{\Theta; \Phi; B; \Gamma; \Delta \vdash_{wf} \mathbf{if} \, v \mathbf{then} \, s_1 \mathbf{else} \, s_2 : b} \text{WF_S_IF} \\
\\
\frac{x \# \Gamma \quad \Theta; \Phi; B; \Gamma; \Delta \vdash_{wf} e : b_1 \quad \Theta; \Phi; B; \Gamma, x : b_1[\phi]; \Delta \vdash_{wf} s : b_2}{\Theta; \Phi; B; \Gamma; \Delta \vdash_{wf} \mathbf{let} \, x = e \mathbf{in} \, s : b_2} \text{WF_S_LET} \\
\\
\frac{x \# \Gamma \quad \Theta; \Phi; B; \Gamma; \Delta \vdash_{wf} s_1 : b_1 \quad \Theta; \Phi; B; \Gamma, x : b_1[\top]; \Delta \vdash_{wf} s_2 : b_2 \quad \Theta; B; \Gamma \vdash_{wf} \{z : b_1 | \phi\}}{\Theta; \Phi; B; \Gamma; \Delta \vdash_{wf} \mathbf{let} \, x : \{z : b_1 | \phi\} = s_1 \mathbf{in} \, s_2 : b_2} \text{WF_S_LET2} \\
\\
\frac{\mathbf{union} \, tid = \{ \overline{C_i : \{z_i : b_i | \phi_i\}^i} \} \in \Theta \quad \Theta; B; \Gamma \vdash_{wf} v : tid \quad \Theta; \Phi; B; \Gamma, x_i : b_i[v = C_i \, tid \, x_i \wedge \phi_i[x_i/z_i]]; \Delta \vdash_{wf} s_i : b^i}{\Theta; \Phi; B; \Gamma; \Delta \vdash_{wf} \mathbf{match} \, v \mathbf{of} \, \overline{C_i \, x_i \Rightarrow s_i^i} : b} \text{WF_S_MATCH} \\
\\
\frac{\Theta; \Phi; B; \Gamma; \Delta \vdash_{wf} s_1 : \mathbf{bool} \quad \Theta; \Phi; B; \Gamma; \Delta \vdash_{wf} s_2 : \mathbf{unit}}{\Theta; \Phi; B; \Gamma; \Delta \vdash_{wf} \mathbf{while} \, (s_1) \mathbf{do} \, \{s_2\} : \mathbf{unit}} \text{WF_S_WHILE} \\
\\
\frac{\Theta; \Phi; B; \Gamma; \Delta \vdash_{wf} s_1 : \mathbf{unit} \quad \Theta; \Phi; B; \Gamma; \Delta \vdash_{wf} s_2 : b}{\Theta; \Phi; B; \Gamma; \Delta \vdash_{wf} s_1; s_2 : b} \text{WF_S_SEQ} \\
\\
\frac{x \# \Gamma \quad \Theta; B; \Gamma \vdash_{wf} \phi \quad \Theta; \Phi; B; \Gamma, x : \mathbf{bool}[\phi]; \Delta \vdash_{wf} s : b}{\Theta; \Phi; B; \Gamma; \Delta \vdash_{wf} \mathbf{assert} \, \phi \mathbf{in} \, s : b} \text{WF_S_ASSERT}
\end{array}$$

$\Theta; B \vdash \Gamma_1 \sqsubseteq \Gamma_2$

Γ_2 is an extension of Γ_1

$$\begin{array}{c}
\frac{\Theta; B \vdash_{wf} \Gamma}{\Theta; B \vdash \Gamma \sqsubseteq \Gamma} \text{EXTEND_G_REFL} \\
\\
\frac{\begin{array}{c} \Theta; B \vdash \Gamma_3 \sqsubseteq \Gamma_1, \Gamma_2 \\ x \notin \text{dom}(\Gamma_1, \Gamma_2) \\ \Theta; B \vdash_{wf} \Gamma, x : b[\phi] \end{array}}{\Theta; B \vdash \Gamma_3 \sqsubseteq \Gamma_1, (\Gamma_2, x : b[\phi])} \text{EXTEND_G_INSERT} \\
\\
\boxed{\Theta; B; \Gamma \vdash \Delta_2 \sqsubseteq \Delta_1} \quad \Delta_1 \text{ is an extension of } \Delta_2 \\
\\
\frac{\Theta; B; \Gamma \vdash_{wf} \Delta}{\Theta; B; \Gamma \vdash \Delta \sqsubseteq \Delta} \text{EXTEND_D_REFL} \\
\\
\frac{\begin{array}{c} \Theta; B; \Gamma \vdash \Delta_3 \sqsubseteq \Delta_1, \Delta_2 \\ u \notin \text{dom}(\Delta_1, \Delta_2) \\ \Theta; B; \Gamma \vdash_{wf} \tau \end{array}}{\Theta; B; \Gamma \vdash \Delta_3 \sqsubseteq \Delta_1, (\Delta_2, u : \tau)} \text{EXTEND_D_INSERT}
\end{array}$$

2.3 Subtyping

$$\boxed{\Theta; B; \Gamma \vdash \tau_1 \lesssim \tau_2} \quad \text{Subtyping}$$

$$\frac{\begin{array}{c} \Theta; B; \Gamma \vdash_{wf} \{z_1 : b|\phi_1\} \\ \Theta; B; \Gamma \vdash_{wf} \{z_2 : b|\phi_2\} \\ \Theta; B; \Gamma, z_3 : b[\phi_1[z_3/z_1]] \models \phi_2[z_3/z_1] \end{array}}{\Theta; B; \Gamma \vdash \{z_1 : b|\phi_1\} \lesssim \{z_2 : b|\phi_2\}} \text{SUBTYPE_ANF_SUBTYPE}$$

2.4 Typing

$$\boxed{\vdash l \Rightarrow \tau} \quad \text{Type synthesis for literals. Infer that type of } l \text{ is } \tau$$

$$\begin{array}{c}
\overline{\vdash () \Rightarrow \{z : \mathbf{unit} | z = ()\}} \quad \text{INFER_L_UNIT} \\
\\
\overline{\vdash \mathbf{T} \Rightarrow \{z : \mathbf{bool} | z = \mathbf{T}\}} \quad \text{INFER_L_TRUE} \\
\\
\overline{\vdash \mathbf{F} \Rightarrow \{z : \mathbf{bool} | z = \mathbf{F}\}} \quad \text{INFER_L_FALSE} \\
\\
\overline{\vdash n \Rightarrow \{z : \mathbf{int} | z = n\}} \quad \text{INFER_L_NUM} \\
\\
\overline{\vdash bin \Rightarrow \{z : \mathbf{bvec} | z = bin\}} \quad \text{INFER_L_BVEC}
\end{array}$$

$$\boxed{\Theta; B; \Gamma \vdash v \Rightarrow \tau} \quad \text{Type synthesis. Infer that type of } v \text{ is } \tau$$

$$\frac{\begin{array}{c} z \# \Gamma \\ \Theta; B \vdash_{wf} \Gamma \\ x : b[\phi] \in \Gamma \end{array}}{\Theta; B; \Gamma \vdash x \Rightarrow \{z : b | z = x\}} \text{INFER_V_ANF_VAR}$$

$$\frac{\begin{array}{c} \vdash l \Rightarrow \tau \\ \Theta; B \vdash_{wf} \Gamma \end{array}}{\Theta; B; \Gamma \vdash l \Rightarrow \tau} \text{INFER_V_ANF_LIT}$$

$$\begin{array}{c}
z\#\Gamma \\
\Theta; B; \Gamma \vdash v_1 \Rightarrow \{z_1 : b_1 | \phi_1\} \\
\Theta; B; \Gamma \vdash v_2 \Rightarrow \{z_2 : b_2 | \phi_2\} \\
\hline
\Theta; B; \Gamma \vdash (v_1, v_2) \Rightarrow \{z : b_1 * b_2 | z = (v_1, v_2)\}
\end{array}
\quad \text{INFER_V_ANF_PAIR}$$

$$\begin{array}{c}
z\#\Gamma \\
\mathbf{union} \, tid = \{ \overline{C_i : \tau_i}^i \} \in \Theta \\
\Theta; B; \Gamma \vdash v \Leftarrow \tau \\
\hline
\Theta; B; \Gamma \vdash C_j \, tid \, v \Rightarrow \{z : tid | z = C_j \, tid \, v\}
\end{array}
\quad \text{INFER_V_ANF_DATA_CONS}$$

$$\begin{array}{c}
z\#\Gamma \\
\mathbf{union} \, tid = \forall \beta. \{ \overline{C_i : \tau_i}^i \} \in \Theta \\
\Theta; B; \Gamma \vdash v \Leftarrow \tau[b/\beta] \\
\hline
\Theta; B; \Gamma \vdash C_j \, tid[b]v \Rightarrow \{z : tid | z = C_j \, tid[b]v\}
\end{array}
\quad \text{INFER_V_ANF_DATA_CONS_POLY}$$

$$\boxed{\Theta; B; \Gamma \vdash v \Leftarrow \tau} \quad \text{Check that type of } v \text{ is } \tau$$

$$\begin{array}{c}
\Theta; B; \Gamma \vdash v \Rightarrow \{z_2 : b | \phi_2\} \\
\Theta; B; \Gamma \vdash \{z_2 : b | \phi_2\} \lesssim \{z_1 : b | \phi_1\} \\
\hline
\Theta; B; \Gamma \vdash v \Leftarrow \{z_1 : b | \phi_1\}
\end{array}
\quad \text{CHECK_V_ANF_VAL}$$

$$\boxed{\Theta; \Phi; B; \Gamma; \Delta \vdash e \Rightarrow \tau} \quad \text{Infer that type of } e \text{ is } \tau$$

$$\begin{array}{c}
z_3\#\Gamma \\
\Theta \vdash_{wf} \Phi \\
\Theta; B; \Gamma \vdash_{wf} \Delta \\
\Theta; B; \Gamma \vdash v_1 \Rightarrow \{z_1 : \mathbf{int} | \phi_1\} \\
\Theta; B; \Gamma \vdash v_2 \Rightarrow \{z_2 : \mathbf{int} | \phi_2\} \\
\hline
\Theta; \Phi; B; \Gamma; \Delta \vdash v_1 + v_2 \Rightarrow \{z_3 : \mathbf{int} | z_3 = v_1 + v_2\}
\end{array}
\quad \text{INFER_E_ANF_PLUS}$$

$$\begin{array}{c}
z_3\#\Gamma \\
\Theta \vdash_{wf} \Phi \\
\Theta; B; \Gamma \vdash_{wf} \Delta \\
\Theta; B; \Gamma \vdash v_1 \Rightarrow \{z_1 : \mathbf{int} | \phi_1\} \\
\Theta; B; \Gamma \vdash v_2 \Rightarrow \{z_2 : \mathbf{int} | \phi_2\} \\
\hline
\Theta; \Phi; B; \Gamma; \Delta \vdash v_1 \leq v_2 \Rightarrow \{z_3 : \mathbf{bool} | z_3 = va1 \leq va2\}
\end{array}
\quad \text{INFER_E_ANF_LEQ}$$

$$\begin{array}{c}
\Theta \vdash_{wf} \Phi \\
\Theta; B; \Gamma \vdash_{wf} \Delta \\
\mathbf{val} \, f : (x : b[\phi]) \rightarrow \tau \in \Phi \\
\Theta; B; \Gamma \vdash v \Leftarrow \{z : b | \phi\} \\
\hline
\Theta; \Phi; B; \Gamma; \Delta \vdash f \, v \Rightarrow \tau[v/x]
\end{array}
\quad \text{INFER_E_ANF_APP}$$

$$\begin{array}{c}
\Theta \vdash_{wf} \Phi \\
\Theta; B; \Gamma \vdash_{wf} \Delta \\
\mathbf{val} \, \forall \beta. f : (x : b[\phi]) \rightarrow \tau \in \Phi \\
\Theta; B; \Gamma \vdash v \Leftarrow \{z : b[b_2/\beta] | \phi\} \\
\hline
\Theta; \Phi; B; \Gamma; \Delta \vdash f[b_2]v \Rightarrow \tau[b_2/\beta][v/x]
\end{array}
\quad \text{INFER_E_ANF_APP_POLY}$$

$$\begin{array}{c}
z\#\Gamma \\
\Theta \vdash_{wf} \Phi \\
\Theta; B; \Gamma \vdash_{wf} \Delta \\
\Theta; B; \Gamma \vdash v \Rightarrow \{z : b_1 * b_2 | \phi\} \\
\hline
\Theta; \Phi; B; \Gamma; \Delta \vdash \mathbf{fst} \, v \Rightarrow \{z : b_1 | z = \mathbf{fst} \, v\}
\end{array}
\quad \text{INFER_E_ANF_FST}$$

$$\begin{array}{c}
z\#\Gamma \\
\Theta \vdash_{wf} \Phi \\
\Theta; B; \Gamma \vdash_{wf} \Delta \\
\Theta; B; \Gamma \vdash v \Rightarrow \{z : b_1 * b_2 | \phi\} \\
\hline
\Theta; \Phi; B; \Gamma; \Delta \vdash \mathbf{snd} v \Rightarrow \{z : b_2 | z = \mathbf{snd} v\} \quad \text{INFER_E_ANF_SND}
\end{array}$$

$$\begin{array}{c}
z\#\Gamma \\
\Theta \vdash_{wf} \Phi \\
\Theta; B; \Gamma \vdash_{wf} \Delta \\
\Theta; B; \Gamma \vdash v_1 \Rightarrow \{z_1 : \mathbf{bvec} | \phi_1\} \\
\Theta; B; \Gamma \vdash v_2 \Rightarrow \{z_2 : \mathbf{bvec} | \phi_2\} \\
\hline
\Theta; \Phi; B; \Gamma; \Delta \vdash v_1 @ v_2 \Rightarrow \{z : \mathbf{bvec} | z = v_1 @ v_2\} \quad \text{INFER_E_ANF_CONCAT}
\end{array}$$

$$\begin{array}{c}
z\#\Gamma \\
\Theta \vdash_{wf} \Phi \\
\Theta; B; \Gamma \vdash_{wf} \Delta \\
\Theta; B; \Gamma \vdash v_1 \Rightarrow \{z_1 : \mathbf{int} | \phi_1\} \\
\Theta; B; \Gamma \vdash v_2 \Rightarrow \{z_2 : \mathbf{bvec} | \phi_2\} \\
\hline
\Theta; \Phi; B; \Gamma; \Delta \vdash \mathbf{split} v_1 v_2 \Rightarrow \{z : \mathbf{bvec} | v_2 = \mathbf{fst} z @ \mathbf{snd} z \wedge v_1 = \mathbf{len}(\mathbf{fst} z)\} \quad \text{INFER_E_ANF_SPLIT}
\end{array}$$

$$\begin{array}{c}
z\#\Gamma \\
\Theta \vdash_{wf} \Phi \\
\Theta; B; \Gamma \vdash_{wf} \Delta \\
\Theta; B; \Gamma \vdash v \Rightarrow \{z : \mathbf{bvec} | \phi\} \\
\hline
\Theta; \Phi; B; \Gamma; \Delta \vdash \mathbf{snd} v \Rightarrow \{z : b_2 | z = \mathbf{len} v\} \quad \text{INFER_E_ANF_LEN}
\end{array}$$

$$\begin{array}{c}
\Theta \vdash_{wf} \Phi \\
\Theta; B; \Gamma \vdash_{wf} \Delta \\
u : \tau \in \Delta \\
\hline
\Theta; \Phi; B; \Gamma; \Delta \vdash u \Rightarrow \tau \quad \text{INFER_E_ANF_MVAR}
\end{array}$$

$\Theta; \Phi; B; \Gamma; \Delta \vdash e \Leftarrow \tau$

Check that type of e is τ

$$\begin{array}{c}
\Theta; \Phi; B; \Gamma; \Delta \vdash e \Rightarrow \{z_2 : b | \phi_2\} \\
\Theta; B; \Gamma \vdash \{z_2 : b | \phi_2\} \lesssim \{z_1 : b | \phi_1\} \\
\hline
\Theta; \Phi; B; \Gamma; \Delta \vdash e \Leftarrow \{z_1 : b | \phi_1\} \quad \text{CHECK_E_ANF_EXPR}
\end{array}$$

$\Theta; \Phi; B; \Gamma; \Delta \vdash s \Leftarrow \tau$

Check that type of s is τ

$$\begin{array}{c}
\Theta \vdash_{wf} \Phi \\
\Theta; B; \Gamma \vdash_{wf} \Delta \\
\Theta; B; \Gamma \vdash v \Leftarrow \tau \\
\hline
\Theta; \Phi; B; \Gamma; \Delta \vdash v \Leftarrow \tau \quad \text{CHECK_S_VAL}
\end{array}$$

$$\begin{array}{c}
u \notin \text{dom}(\Delta) \\
\Theta; B; \Gamma \vdash v \Leftarrow \tau \\
\Theta; \Phi; B; \Gamma; \Delta, u : \tau \vdash s \Leftarrow \tau_2 \\
\hline
\Theta; \Phi; B; \Gamma; \Delta \vdash \mathbf{var} u : \tau := v \mathbf{in} s \Leftarrow \tau_2 \quad \text{CHECK_S_VAR}
\end{array}$$

$$\begin{array}{c}
\Theta \vdash_{wf} \Phi \\
\Theta; B; \Gamma \vdash_{wf} \Delta \\
u : \tau \in \Delta \\
\Theta; B; \Gamma \vdash v \Leftarrow \tau \\
\hline
\Theta; \Phi; B; \Gamma; \Delta \vdash u := v \Leftarrow \{z : \mathbf{unit} | \top\} \quad \text{CHECK_S_ASSIGN}
\end{array}$$

$$\begin{array}{c}
\Theta; B; \Gamma \vdash v \Rightarrow \{z : \mathbf{bool} | \phi_1\} \\
\Theta; \Phi; B; \Gamma; \Delta \vdash s_1 \Leftarrow \{z_1 : b | v = \mathbf{T} \Rightarrow \phi[z_1/z]\} \\
\Theta; \Phi; B; \Gamma; \Delta \vdash s_2 \Leftarrow \{z_2 : b | v = \mathbf{F} \Rightarrow \phi[z_2/z]\} \\
\hline
\Theta; \Phi; B; \Gamma; \Delta \vdash \mathbf{if } v \mathbf{ then } s_1 \mathbf{ else } s_2 \Leftarrow \{z : b | \phi\}
\end{array}
\quad \text{CHECK_S_IF}$$

$$\begin{array}{c}
x \# \Gamma \\
\Theta; \Phi; B; \Gamma; \Delta \vdash e \Rightarrow \{z : b | \phi\} \\
\Theta; \Phi; B; \Gamma; x : b[\phi[x/z]]; \Delta \vdash s \Leftarrow \tau \\
\hline
\Theta; \Phi; B; \Gamma; \Delta \vdash \mathbf{let } x = e \mathbf{ in } s \Leftarrow \tau
\end{array}
\quad \text{CHECK_S_LET}$$

$$\begin{array}{c}
x \# \Gamma \\
\Theta; \Phi; B; \Gamma; x : \mathbf{bool}[\phi]; \Delta \vdash s \Leftarrow \tau \\
\hline
\Theta; \Phi; B; \Gamma; \Delta \vdash \mathbf{assert } \phi \mathbf{ in } s \Leftarrow \tau
\end{array}
\quad \text{CHECK_S_ASSERT}$$

$$\begin{array}{c}
x \# \Gamma \\
\Theta; \Phi; B; \Gamma; \Delta \vdash s_1 \Leftarrow \{z : b | \phi\} \\
\Theta; \Phi; B; \Gamma; x : b[\phi[x/z]]; \Delta \vdash s_2 \Leftarrow \tau \\
\hline
\Theta; \Phi; B; \Gamma; \Delta \vdash \mathbf{let } x : \{z : b | \phi\} = s_1 \mathbf{ in } s_2 \Leftarrow \tau
\end{array}
\quad \text{CHECK_S_LET2}$$

$$\begin{array}{c}
\mathbf{union } tid = \{ \overline{C_i : \{z_i : b_i | \phi_i\}^i} \} \in \Theta \\
\Theta; B; \Gamma \vdash v \Rightarrow \{z : tid | \phi\} \\
\hline
\Theta; \Phi; B; \Gamma; x_i : b_i[v = C_i \text{ tid } x_i \wedge \phi_i[x_i/z_i]]; \Delta \vdash s_i \Leftarrow \tau^i \\
\hline
\Theta; \Phi; B; \Gamma; \Delta \vdash \mathbf{match } v \mathbf{ of } \overline{C_i} x_i \Rightarrow s_i^i \Leftarrow \tau
\end{array}
\quad \text{CHECK_S_MATCH}$$

$$\begin{array}{c}
\Theta; \Phi; B; \Gamma; \Delta \vdash s_1 \Leftarrow \{z : \mathbf{bool} | \top\} \\
\Theta; \Phi; B; \Gamma; \Delta \vdash s_2 \Leftarrow \{z : \mathbf{unit} | \top\} \\
\hline
\Theta; \Phi; B; \Gamma; \Delta \vdash \mathbf{while } (s_1) \mathbf{ do } \{s_2\} \Leftarrow \{z : \mathbf{unit} | \top\}
\end{array}
\quad \text{CHECK_S_WHILE}$$

$$\begin{array}{c}
\Theta; \Phi; B; \Gamma; \Delta \vdash s_1 \Leftarrow \{z : \mathbf{unit} | \top\} \\
\Theta; \Phi; B; \Gamma; \Delta \vdash s_2 \Leftarrow \tau \\
\hline
\Theta; \Phi; B; \Gamma; \Delta \vdash s_1; s_2 \Leftarrow \tau
\end{array}
\quad \text{CHECK_S_SEQ}$$

$$\frac{}{\Theta; \Phi; B; \Gamma; \Delta \vdash \mathbf{abort} \Leftarrow \tau} \quad \text{CHECK_S_ABORT}$$

$$\boxed{\Theta_1; \Phi_1 \vdash def_1 .. def_n \rightsquigarrow \Theta_2; \Phi_2}$$

$$\begin{array}{c}
\mathbf{val } f : (x : b[\phi]) \rightarrow \tau \in \Phi \\
\Theta; \Phi; \cdot; x : b[\phi]; \cdot \vdash s \Leftarrow \tau \\
\hline
\Theta; \Phi \vdash \mathbf{function } f(x) = s \rightsquigarrow \Theta; \Phi, \mathbf{function } f(x) = s
\end{array}
\quad \text{CHECK_DEFS_ANF_FUNDEF}$$

$$\begin{array}{c}
\mathbf{val } \forall \beta. f : (x : b[\phi]) \rightarrow \tau \in \Phi \\
\Theta; \Phi; \cdot; \beta; x : b[\phi]; \cdot \vdash s \Leftarrow \tau \\
\hline
\Theta; \Phi \vdash \mathbf{function } f(x) = s \rightsquigarrow \Theta; \Phi, \mathbf{function } f(x) = s
\end{array}
\quad \text{CHECK_DEFS_ANF_FUNDEF_POLY}$$

$$\begin{array}{c}
\Theta \vdash_{wf} \mathbf{val } f : (x : b[\phi]) \rightarrow \tau \\
\hline
\Theta; \Phi \vdash \mathbf{val } f : (x : b[\phi]) \rightarrow \tau \rightsquigarrow \Theta; \Phi, \mathbf{val } f : (x : b[\phi]) \rightarrow \tau
\end{array}
\quad \text{CHECK_DEFS_ANF_VALSPEC}$$

$$\begin{array}{c}
\Theta \vdash_{wf} \mathbf{val } \forall \beta. f : (x : b[\phi]) \rightarrow \tau \\
\hline
\Theta; \Phi \vdash \mathbf{val } \forall \beta. f : (x : b[\phi]) \rightarrow \tau \rightsquigarrow \Theta; \Phi, \mathbf{val } \forall \beta. f : (x : b[\phi]) \rightarrow \tau
\end{array}
\quad \text{CHECK_DEFS_ANF_VALSPEC_POLY}$$

$$\frac{}{\Theta; \Phi \vdash \mathbf{union } tid = \{ \overline{C_i : \tau_i^i} \} \rightsquigarrow \Theta, \mathbf{union } tid = \{ \overline{C_i : \tau_i^i} \}; \Phi} \quad \text{CHECK_DEFS_ANF_UNIONDEF}$$

$$\begin{array}{c}
\Theta_1; \Phi_1 \vdash def \rightsquigarrow \Theta_2; \Phi_2 \\
\Theta_2; \Phi_2 \vdash def_1 .. def_n \rightsquigarrow \Theta_3; \Phi_3 \\
\hline
\Theta_1; \Phi_1 \vdash def def_1 .. def_n \rightsquigarrow \Theta_3; \Phi_3
\end{array}
\quad \text{CHECK_DEFS_ANF_DEFS}$$

$$\boxed{\vdash p}$$

$$\frac{\begin{array}{l} \cdot; \cdot \vdash def_1 .. def_n \rightsquigarrow \Theta_2; \Phi_2 \\ \Theta_2; \Phi_2; \cdot; \cdot \vdash s \Leftarrow \{z : \mathbf{int} | \top\} \end{array}}{\vdash def_1; ..; def_n; ; s} \quad \text{CHECK_PROGRAM_PROG}$$

$$\boxed{\Theta \vdash \Delta \sim \delta}$$

$$\frac{\begin{array}{l} \delta = u_1 \rightarrow v_1, .., u_n \rightarrow v_n \\ \Delta = u_1 : \tau_1, .., u_n : \tau_n \\ \Theta; \cdot; \cdot \vdash v_1 \Leftarrow \tau_1 \quad .. \quad \Theta; \cdot; \cdot \vdash v_n \Leftarrow \tau_n \end{array}}{\Theta \vdash \Delta \sim \delta} \quad \text{DSIM_DSIM}$$

$$\boxed{\Theta; \Phi; \Delta \vdash (\delta, s) \Leftarrow \tau} \quad \text{Program state typing judgement}$$

$$\frac{\begin{array}{l} \Theta \vdash \Delta \sim \delta \\ \Theta; \Phi; \cdot; \cdot; \Delta \vdash s \Leftarrow \tau \end{array}}{\Theta; \Phi; \Delta \vdash (\delta, s) \Leftarrow \tau} \quad \text{CHECK_REDEX_STMT}$$

2.5 Operational semantics

$$\boxed{\Phi \vdash \langle \delta, s_1 \rangle \rightarrow \langle \delta', s_2 \rangle} \quad \text{One step reduction}$$

$$\frac{}{\Phi \vdash \langle \delta, \mathbf{if} \ \mathbf{T} \ \mathbf{then} \ s_1 \ \mathbf{else} \ s_2 \rangle \rightarrow \langle \delta, s_1 \rangle} \quad \text{REDUCE_IF_TRUE}$$

$$\frac{}{\Phi \vdash \langle \delta, \mathbf{if} \ \mathbf{F} \ \mathbf{then} \ s_1 \ \mathbf{else} \ s_2 \rangle \rightarrow \langle \delta, s_2 \rangle} \quad \text{REDUCE_IF_FALSE}$$

$$\frac{}{\Phi \vdash \langle \delta, \mathbf{let} \ x = v \ \mathbf{in} \ s \rangle \rightarrow \langle \delta, s[v/x] \rangle} \quad \text{REDUCE_LET_VALUE}$$

$$\frac{v_1 + v_2 = v}{\Phi \vdash \langle \delta, \mathbf{let} \ x = v_1 + v_2 \ \mathbf{in} \ s \rangle \rightarrow \langle \delta, \mathbf{let} \ x = v \ \mathbf{in} \ s \rangle} \quad \text{REDUCE_LET_PLUS}$$

$$\frac{v_1 \leq v_2 = v}{\Phi \vdash \langle \delta, \mathbf{let} \ x = v_1 \leq v_2 \ \mathbf{in} \ s \rangle \rightarrow \langle \delta, \mathbf{let} \ x = v \ \mathbf{in} \ s \rangle} \quad \text{REDUCE_LET_LEQ}$$

$$\frac{\begin{array}{l} \mathbf{val} \ f : (x : b[\phi]) \rightarrow \tau \in \Phi \\ \mathbf{function} \ f(x) = s_1 \in \Phi \end{array}}{\Phi \vdash \langle \delta, \mathbf{let} \ y = f \ v \ \mathbf{in} \ s_2 \rangle \rightarrow \langle \delta, \mathbf{let} \ y : \tau[v/x] = s_1[v/x] \ \mathbf{in} \ s_2 \rangle} \quad \text{REDUCE_LET_APP}$$

$$\frac{\begin{array}{l} \mathbf{val} \ \forall \beta. f : (x : b[\phi]) \rightarrow \tau \in \Phi \\ \mathbf{function} \ f(x) = s_1 \in \Phi \end{array}}{\Phi \vdash \langle \delta, \mathbf{let} \ y = f[b_1]v \ \mathbf{in} \ s_2 \rangle \rightarrow \langle \delta, \mathbf{let} \ y : \tau[v/x][b_1/\beta] = s_1[v/x][b_1/\beta] \ \mathbf{in} \ s_2 \rangle} \quad \text{REDUCE_LET_APP_POLY}$$

$$\frac{}{\Phi \vdash \langle \delta, \mathbf{let} \ x = \mathbf{fst} \ (v_1, v_2) \ \mathbf{in} \ s \rangle \rightarrow \langle \delta, \mathbf{let} \ x = v_1 \ \mathbf{in} \ s \rangle} \quad \text{REDUCE_LET_FST}$$

$$\frac{}{\Phi \vdash \langle \delta, \mathbf{let} \ x = \mathbf{snd} \ (v_1, v_2) \ \mathbf{in} \ s \rangle \rightarrow \langle \delta, \mathbf{let} \ x = v_2 \ \mathbf{in} \ s \rangle} \quad \text{REDUCE_LET_SND}$$

$$\frac{v_1 @ v_2 = v_3}{\Phi \vdash \langle \delta, \mathbf{let} \ x = v_1 @ v_2 \ \mathbf{in} \ s \rangle \rightarrow \langle \delta, \mathbf{let} \ x = v_3 \ \mathbf{in} \ s \rangle} \quad \text{REDUCE_LET_CONCAT}$$

$$\frac{v_1 = \mathbf{split} \ v_2 \ v_3}{\Phi \vdash \langle \delta, \mathbf{let} \ x = \mathbf{split} \ v_2 \ v_3 \ \mathbf{in} \ s \rangle \rightarrow \langle \delta, \mathbf{let} \ x = v_1 \ \mathbf{in} \ s \rangle} \quad \text{REDUCE_LET_SPLIT}$$

$$\frac{\mathbf{len} \ v_1 = v_2}{\Phi \vdash \langle \delta, \mathbf{let} \ x = \mathbf{len} \ v_1 \ \mathbf{in} \ s \rangle \rightarrow \langle \delta, \mathbf{let} \ x = v_2 \ \mathbf{in} \ s \rangle} \quad \text{REDUCE_LET_LEN}$$

$$\begin{array}{c}
\frac{v = \delta(u)}{\Phi \vdash \langle \delta, \mathbf{let} \ x = u \ \mathbf{in} \ s \rangle \rightarrow \langle \delta, \mathbf{let} \ x = v \ \mathbf{in} \ s \rangle} \text{REDUCE_LET_MVAR} \\
\frac{u \notin \text{dom}(\delta)}{\Phi \vdash \langle \delta, \mathbf{var} \ u : \tau := v \ \mathbf{in} \ s \rangle \rightarrow \langle \delta[u \mapsto v], s \rangle} \text{REDUCE_MVAR_DECL} \\
\frac{\delta' = \delta[u \mapsto v]}{\Phi \vdash \langle \delta, u := v \rangle \rightarrow \langle \delta', () \rangle} \text{REDUCE_MVAR_ASSIGN} \\
\frac{\Phi \vdash \langle \delta, s_1 \rangle \rightarrow \langle \delta', s_3 \rangle}{\Phi \vdash \langle \delta, s_1; s \rangle \rightarrow \langle \delta', s_3; s \rangle} \text{REDUCE_SEQ1} \\
\frac{}{\Phi \vdash \langle \delta, () ; s \rangle \rightarrow \langle \delta, s \rangle} \text{REDUCE_SEQ2} \\
\frac{}{\Phi \vdash \langle \delta, \mathbf{let} \ x : \tau = v \ \mathbf{in} \ s_2 \rangle \rightarrow \langle \delta, s_2[v/x] \rangle} \text{REDUCE_LET2_VAL} \\
\frac{\Phi \vdash \langle \delta, s_1 \rangle \rightarrow \langle \delta', s_3 \rangle}{\Phi \vdash \langle \delta, \mathbf{let} \ x : \tau = s_1 \ \mathbf{in} \ s_2 \rangle \rightarrow \langle \delta', \mathbf{let} \ x : \tau = s_3 \ \mathbf{in} \ s_2 \rangle} \text{REDUCE_LET2_STMT} \\
\frac{}{\Phi \vdash \langle \delta, \mathbf{match} \ (C_j \ \text{tid} \ v) \ \mathbf{of} \ \overline{C_i} \ x_i \Rightarrow s_i^i \rangle \rightarrow \langle \delta, s_j[v/x_j] \rangle} \text{REDUCE_MATCH} \\
\frac{x \ \mathbf{fresh}}{\Phi \vdash \langle \delta, \mathbf{while} \ (s_1) \ \mathbf{do} \ \{s_2\} \rangle \rightarrow \langle \delta, \mathbf{let} \ x : \{z : \mathbf{bool} \mid \top\} = s_1 \ \mathbf{in} \ \mathbf{if} \ x \ \mathbf{then} \ (s_2; \mathbf{while} \ (s_1) \ \mathbf{do} \ \{s_2\}) \ \mathbf{else} \ () \rangle} \text{REDUCE_WHILE} \\
\frac{}{\Phi \vdash \langle \delta, \mathbf{assert} \ \phi \ \mathbf{in} \ v \rangle \rightarrow \langle \delta, v \rangle} \text{REDUCE_ASSERT1} \\
\frac{\Phi \vdash \langle \delta, s_1 \rangle \rightarrow \langle \delta', s_2 \rangle}{\Phi \vdash \langle \delta, \mathbf{assert} \ \phi \ \mathbf{in} \ s_1 \rangle \rightarrow \langle \delta', \mathbf{assert} \ \phi \ \mathbf{in} \ s_2 \rangle} \text{REDUCE_ASSERT2} \\
\boxed{\Phi \vdash \langle \delta_1, s_1 \rangle \xrightarrow{*} \langle \delta_2, s_2 \rangle} \quad \text{Multi-step reduction} \\
\frac{\Phi \vdash \langle \delta_1, s_1 \rangle \rightarrow \langle \delta_2, s_2 \rangle}{\Phi \vdash \langle \delta_1, s_1 \rangle \xrightarrow{*} \langle \delta_2, s_2 \rangle} \text{REDUCE_MANY_SINGLE_STEP} \\
\frac{\Phi \vdash \langle \delta_1, s_1 \rangle \rightarrow \langle \delta_2, s_2 \rangle \quad \Phi \vdash \langle \delta_2, s_2 \rangle \xrightarrow{*} \langle \delta_3, s_3 \rangle}{\Phi \vdash \langle \delta_1, s_1 \rangle \xrightarrow{*} \langle \delta_3, s_3 \rangle} \text{REDUCE_MANY_MANY_STEP}
\end{array}$$

2.6 Machine configuration check

$$\boxed{\Theta \vdash \delta \sim \Delta}$$

$$\begin{array}{c}
\frac{}{\Theta \vdash \cdot \sim \cdot} \text{CHECK_STORE_EMPTY} \\
\frac{u \notin \text{dom}(\Delta) \quad \Theta \vdash \delta \sim \Delta}{\Theta; \cdot; \cdot \vdash v \Leftarrow \tau} \text{CHECK_STORE_CONS} \\
\frac{}{\Theta \vdash \delta[u \mapsto v] \sim \Delta, u : \tau} \text{CHECK_STORE_CONS}
\end{array}$$

$$\boxed{\Theta; \Phi; \Delta \vdash (\delta, s) \Leftarrow \tau}$$

$$\begin{array}{c}
\frac{\Theta \vdash \delta \sim \Delta \quad \Theta; \Phi; \cdot; \cdot; \Delta \vdash s \Leftarrow \tau}{\Theta; \Phi; \Delta \vdash (\delta, s) \Leftarrow \tau} \text{CHECK_CONFIG_CONFIG}
\end{array}$$

Definition rules: 160 good 0 bad
Definition rule clauses: 465 good 0 bad