

Jan 15th, 2013

Office: BA 6120

Office hour: W 2-4pm or by appt.

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warm-up: $\mathbb{C} = \{a + ib \mid a, b \in \mathbb{R}; i^2 = -1\}$

real part \rightarrow imaginary part

$= \{r(\cos\theta + i\sin\theta) \mid r \geq 0, \theta \in [0, 2\pi]\}$

absolute value \rightarrow argument

$$e^{i\theta} = \cos\theta + i\sin\theta$$

$$e^{i\pi} = 1 + 0i = 1$$

$$(a_1 + ib_1)(a_2 + ib_2) = (a_1 a_2 - b_1 b_2) + i(a_1 b_2 + a_2 b_1)$$

$$(a_1 + ib_1) + (a_2 + ib_2) = (a_1 + a_2) + i(b_1 + b_2)$$

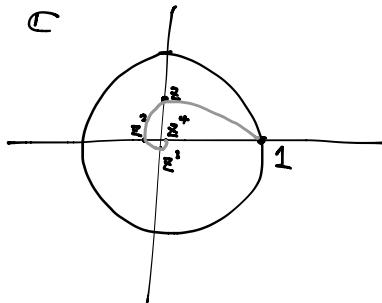
$$\begin{aligned} & * (r(\cos\theta + i\sin\theta))(s(\cos\tau + i\sin\tau)) \\ &= rs(\cos(\theta + \tau) + i\sin(\theta + \tau)) \end{aligned}$$

Why is this true?

$$rs(\cos\theta \cdot \cos\tau - \sin\theta \sin\tau) + i(\sin\theta \cos\tau + \cos\theta \sin\tau)$$

$$z = \frac{i}{2}$$

$$1, z, z^2, z^3, \dots$$



Why do we need \mathbb{C} ?

R_θ = rotation matrix by θ .

$$= \begin{bmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{bmatrix}$$

$$Av = \lambda v \quad \begin{array}{l} \text{eigenvalue} \\ \downarrow \text{eigenvector} \end{array}$$

To find eigenvalues of R_θ we compute roots of

$$p(\lambda) = \det(\lambda I - A)$$

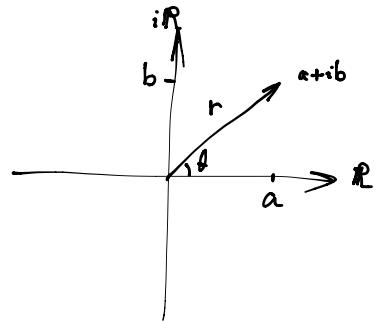
$$= \begin{vmatrix} \lambda - \cos\theta & \sin\theta \\ -\sin\theta & \lambda - \cos\theta \end{vmatrix}$$

$$= (\lambda - \cos\theta)^2 + \sin^2\theta$$

$$= \lambda^2 - 2\cos\theta\lambda + 1$$

$$\text{roots: } \frac{2\cos\theta \pm \sqrt{4\cos^2\theta - 4}}{2}$$

$$= \cos\theta \pm i\sin\theta$$



What are the n^{th} roots of unity?

$$n^{\text{th}} \text{ roots of unity} = \{ z \in \mathbb{C} : z^n = 1 \}$$

$$\text{Ex: } n=4 \quad z=\pm 1, \pm i$$

$$z = r(\cos\theta + i\sin\theta)$$

$$z^n = ? \quad z^n = r^n(\cos n\theta + i\sin n\theta)$$

$$\text{want } r^n(\cos n\theta + i\sin n\theta) = 1$$

$$\Rightarrow r=1 \text{ and } n\theta = 2\pi k$$

$$\Rightarrow r=1 \text{ and } \theta = \frac{2\pi k}{n}$$

$\Rightarrow \{ \cos\left(\frac{2\pi k}{n}\right) + i\sin\left(\frac{2\pi k}{n}\right) \mid k=0, \dots, n-1 \}$ is the n^{th} roots of unity.

Fields:

EXS: Is F a field?

$$\textcircled{1} \quad \mathbb{N} = \{0, 1, 2, \dots\}$$

$$a+(b+c) = (a+b)+c \quad \checkmark$$

No, doesn't have additive identity

$$\textcircled{2} \quad \mathbb{Z} = \{0, \pm 1, \pm 2, \dots\}$$

No, doesn't have multiplicative inverse.

$$\textcircled{3} \quad \mathbb{Q} = \left\{ \frac{m}{n} \mid m, n \in \mathbb{Z} \right\}$$

Yes.

If $\frac{m}{n} \neq 0$ then $\frac{n}{m}$ is its mult. inverse.

$$x(y+z) = xy+xz$$

\textcircled{4} \quad \mathbb{R}. Yes.

\textcircled{5} \quad \mathbb{C}. Yes.

\textcircled{6} \quad \mathbb{R}[x] = polynomial with coefficients in \mathbb{R}. No.

\textcircled{7} \quad \mathbb{R}(x) = \left\{ \frac{f(x)}{g(x)} \mid f(x), g(x) \in \mathbb{R}[x] \right\} Yes.

\textcircled{8} \quad p \text{ prime}.

$$\mathbb{F}_p = \{ \overline{0}, \overline{1}, \dots, \overline{p-1} \}$$

addition: $\overline{a} + \overline{b} = \overline{c}$ where c is the remainder of $\frac{a+b}{p}$

multiplication: $\overline{a} \cdot \overline{b} = \overline{c}$, where c is the remainder of $\frac{ab}{p}$

$$\begin{array}{r} F_3 \\ \hline + & \begin{array}{|ccc|} \hline & \overline{0} & \overline{1} & \overline{2} \\ \hline \overline{0} & \overline{0} & \overline{1} & \overline{2} \\ \hline \end{array} \\ \hline \begin{array}{|cc|} \hline & \overline{1} & \overline{2} \\ \hline \overline{1} & \overline{1} & \overline{2} \\ \hline \end{array} \end{array} \quad \begin{array}{r} \cdot & \begin{array}{|ccc|} \hline & \overline{0} & \overline{1} & \overline{2} \\ \hline \overline{0} & \overline{0} & \overline{0} & \overline{0} \\ \hline \end{array} \\ \hline \begin{array}{|cc|} \hline & \overline{0} & \overline{1} \\ \hline \overline{1} & \overline{0} & \overline{1} \\ \hline \end{array} \end{array}$$

Why do we need p to be prime? Suppose we try to define $\mathbb{F}_6 \dots$
 $\mathbb{F}_6 = \{\bar{0}, \bar{1}, \bar{2}, \bar{3}, \bar{4}, \bar{5}\}$

.	$\bar{0}$	$\bar{1}$	$\bar{2}$	$\bar{3}$	$\bar{4}$	$\bar{5}$
$\bar{5}$						
$\bar{7}$						
$\bar{2}$	$\bar{0}$	$\bar{2}$	$\bar{4}$	$\bar{0}$	$\bar{2}$	$\bar{4}$
$\bar{3}$						
$\bar{4}$						
$\bar{5}$						

$\rightarrow \bar{2}$ doesn't have multi. inverse
which leads to $\bar{1}$.

Ex: Does $f(x) = x^2 + \bar{2}x - \bar{2}$ have roots in \mathbb{F}^3 .

$$f(\bar{0}) = (\bar{0})^2 + \bar{2} \cdot \bar{0} - \bar{2} = -\bar{2} = \bar{1}$$

↑
why? because $\bar{1} + \bar{2} = \bar{0}$ so $\bar{1} = -\bar{2}$

$$f(\bar{1}) = (\bar{1})^2 + \bar{2} \cdot \bar{1} - \bar{2} = \bar{1} + \bar{2} - \bar{2} = \bar{1}$$

$$f(\bar{2}) = (\bar{2})^2 + \bar{2} \cdot \bar{2} - \bar{2} = \bar{1} + \bar{1} - \bar{2} = \bar{0}$$

Alternatively, could compute this $\bar{2}^2 + \bar{2} \cdot \bar{2} - \bar{2} = \bar{2} = \bar{0}$

We consider vector spaces over a field F .

* def is exactly the same as for vector spaces over \mathbb{R} , except scalars must come from F .

$$* F^n = \left\{ \begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix} \mid a_i \in F \right\}$$

* $P_n(F)$ = polynomials of deg $\leq n$ with coeffs in F .

Ex: $V = \mathbb{C}^n$.

1. a vector space over \mathbb{C} .

with basis e_1, \dots, e_n

$$\text{where } e_i = \begin{bmatrix} 0 \\ \vdots \\ 1 \\ 0 \end{bmatrix} \leftarrow i^{\text{th}} \text{ position}$$

why do they span \mathbb{C}^n ? Let $v = \begin{bmatrix} z_1 \\ z_2 \\ \vdots \\ z_n \end{bmatrix} \in \mathbb{C}^n$.

prove span

$$v = z_1 e_1 + \dots + z_n e_n$$

$$\text{Sps } \sum z_i e_i + \cdots + z_n e_n = 0$$

$$\Rightarrow \begin{bmatrix} z_1 \\ \vdots \\ z_n \end{bmatrix} = \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix} \Rightarrow z_i = 0 \text{ for } i=1, \dots, n$$

prove linear independence

Show independence

* Some proof shows \mathbb{F}^n has a standard basis e_1, \dots, e_n .

Ex: $V = \mathbb{C}^2$ vector space over \mathbb{R}

$$v = \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} \in \mathbb{C}^2$$

$$v = \begin{bmatrix} a_1 + ib_1 \\ a_2 + ib_2 \end{bmatrix} \quad v_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad v_2 = \begin{bmatrix} i \\ 0 \end{bmatrix} \quad v_3 = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \quad v_4 = \begin{bmatrix} 0 \\ i \end{bmatrix}$$

$$v = a_1 v_1 + b_1 v_2 + a_2 v_3 + b_2 v_4 \Rightarrow \text{spanning}$$

continue \Rightarrow check linear independence.

$$\text{Note: } \dim_{\mathbb{C}} \mathbb{C}^2 = 2$$

$$\dim_{\mathbb{R}} \mathbb{C}^2 = 4$$