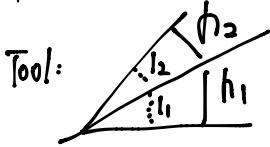
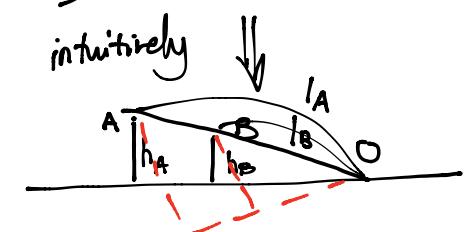


Lecture 3
Recall: (Last time)

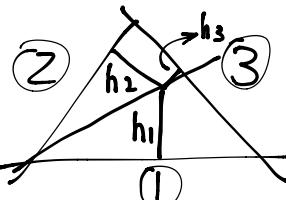
Tool:  $\frac{h_1}{h_2} = d = \frac{l_1}{l_2} = \dots$ similarity of Δ s



$$\frac{h_A}{h_B} = \frac{l_A}{l_B} = d$$

两点共线的结论

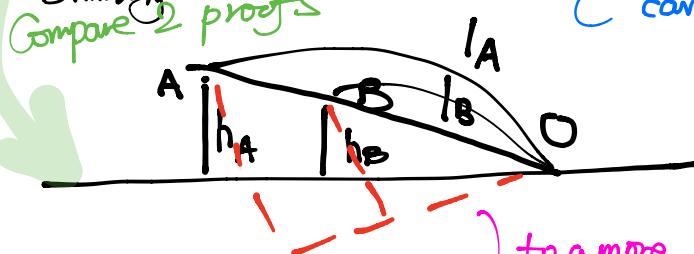
There are infinitely many lines passing O

 三点共线的充要条件

$$\frac{h_1}{h_2} = d_1, \frac{h_2}{h_3} = d_2, \frac{h_3}{h_1} = d_3$$

whether $h_1 h_2 h_3$ pass 1 point? iff $d_1 d_2 d_3 = 1$

Similarity
Compare 2 proofs



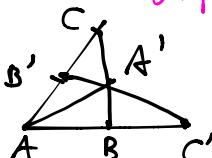
C can be on any line passing pt. O.

$$\frac{h_A}{h_B} = d_1, \frac{h_B}{h_C} = d_2, \frac{h_C}{h_A} = d_3$$

they coincide $\Leftrightarrow d_1 d_2 d_3 = 1$

to a more complicated case 3 pts

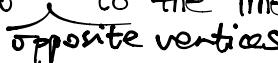
Note: $\frac{C'A}{C'B} = d_1$



$$\frac{C'A}{C'B} = d_1, \frac{B'C}{B'A} = d_2, \frac{A'C}{A'B} = d_3$$

$$\frac{h_A}{h_B} = \frac{h_B}{h_C}, \frac{h_C}{h_A} = \frac{h_A}{h_B}$$

$$d_1 d_2 d_3 = 1 \Leftrightarrow B', A', C' \text{ on one line}$$

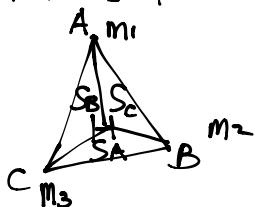
The necessary/sufficient condition for two points on the same line:
ratio of distances from two  to the line = segment ratio on the line

BY SIMILAR TRIANGLE

So if we want to prove 3 pts on the same line then we should have 3 those conditions.

Assume we have a ΔABC , How to find COM exactly on H.

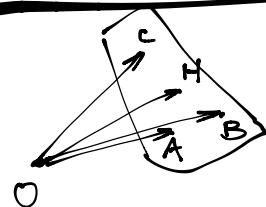
$$m_1 + m_2 + m_3 = 1$$



Recall using area to prove Ceva.

$$S_A + S_B + S_C = S$$

$$\text{Claim } m_B = \frac{S_B}{S}, m_C = \frac{S_C}{S}, m_A = \frac{S_A}{S}$$



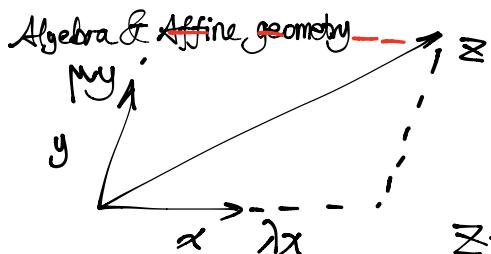
$$\vec{H} = m_1 \vec{A} + m_2 \vec{B} + m_3 \vec{C}$$

$$m_1 + m_2 + m_3 = 1$$

e.g. solve for m_1 , use Cramer's rule.

$$m_1 = \frac{\det(H, B, C)}{\det(A, B, C)}$$

actually this
is equivalent
to Cramer's
rule

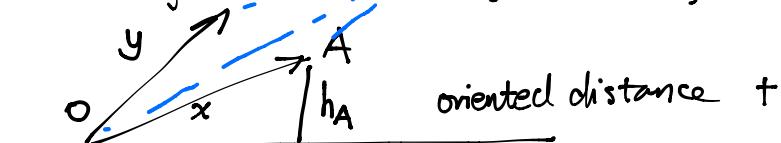


basis
 x, y can be any non-zero vector, we just need to change coordinates λ, μ .

linear function: $f(\lambda a + \mu b) = \lambda f(a) + \mu f(b)$

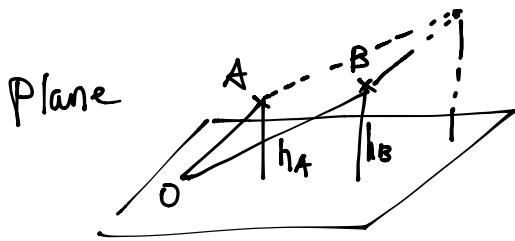
$$\text{so } f(z) = f(\lambda x + \mu y) = \lambda f(x) + \mu f(y)$$

$$\text{and } f(z) = f(\lambda_1 x_1 + \dots + \lambda_n x_n) = \lambda_1 f(x_1) + \dots + \lambda_n f(x_n)$$



$$\text{claim } h(x+y) = h(x) + h(y) \rightarrow \text{linear function}$$

Distance is a linear function if it is oriented.

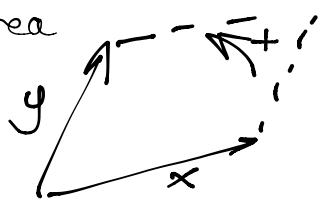


+ half plane so oriented.

$$\text{So } S(x, y) = -S(y, x)$$

Still holds as a linear function

Area



Consider oriented area (with + direction positive)

$$S(x, y)$$

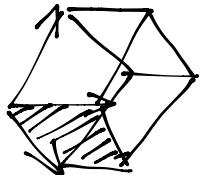
is also linear

$$S(x, \lambda y_1 + \mu y_2) = \lambda S(x, y_1) + \mu S(x, y_2)$$

$$S(x, y) = \text{length } x \cdot \text{height of } y$$

Volume

$$\text{Vol}(x, y, z)$$



$$\text{Vol}(x, y, z) = \text{length } x \cdot \text{height of } y \cdot \text{height of } z.$$

$$x = \begin{pmatrix} a_{11} \\ a_{21} \end{pmatrix} \quad y = \begin{pmatrix} a_{12} \\ a_{22} \end{pmatrix} \quad \det(x, y) = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} = a_{11}a_{22} - a_{21}a_{12}$$

$$x = a_{11}e_1 + a_{12}e_2$$

$$\begin{aligned} S(x, y) &= S(x, a_{11}e_1 + a_{21}e_2) = a_{11}S(x, e_1) + a_{21}S(x, e_2) \\ &= a_{11}a_{12}S(e_1, e_1) + a_{12}a_{21}S(e_2, e_1) \\ &= -a_{12}a_{21} + a_{11}a_{22} \end{aligned}$$

proved

$$S(e_1, e_1) = 0 \quad S(e_1, e_2) = 1$$

$$S(e_2, e_1) = -1 \quad S(e_2, e_2) = 0$$

Proof of

Cramer's Rule:

given x, y, z , find λ, μ s.t. $\lambda x + \mu y = z$

original: $\det(x, y)$

$$\text{consider } \det(z, y) = \det(\lambda x + \mu y, y) = \lambda \det(x, y) + \mu \underbrace{\det(y, y)}_{=0}$$

$$\text{so } \frac{\det(z, y)}{\det(x, y)} = \lambda$$

$$\text{consider } \det(x, z) = \mu \det(x, y)$$

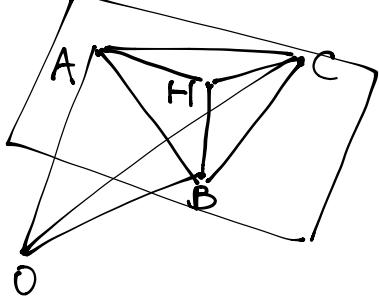
$$\text{so } \frac{\det(x, z)}{\det(x, y)} = \mu$$

For 3dim space, $x, y, z - w = \lambda x + \mu y + \nu z$

$$\frac{\det(w, y, z)}{\det(x, y, z)} = \lambda \text{ due to the same reason ...}$$

$$\text{and } \frac{\det(x, w, z)}{\det(x, y, z)} = \mu, \quad \frac{\det(x, y, w)}{\det(x, y, z)} = \nu$$

Back to Ceva :



$$\begin{aligned}\lambda + \mu + \nu &= 1 \\ \lambda A + \mu B + \nu C &= H \\ (1, 0, 0) &= A \\ (0, 1, 0) &= B \\ (0, 0, 1) &= C\end{aligned}$$

$$\begin{aligned}\lambda &= \frac{\det(H, B, C)}{\det(A, B, C)} \\ &= \frac{S(H, B, C)}{S(A, B, C)}\end{aligned}$$