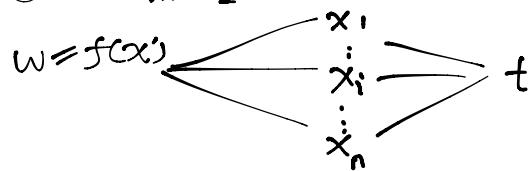


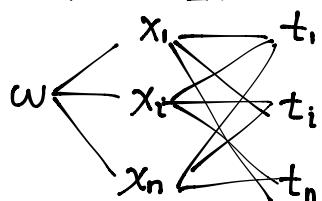
June 6th

Chain Rule I



$$\frac{dw}{dt} = \frac{\partial w}{\partial x_i} \cdot \frac{dx_i}{dt} + \dots + \frac{\partial w}{\partial x_n} \cdot \frac{dx_n}{dt}$$

Chain Rule II



$$f(\vec{x}) = f(x_1, \dots, x_i, \dots, x_n)$$

$$x_i = g_i(t_1, \dots, t_i, \dots, t_m)$$

$$\vec{x} = \vec{g}(t_1, \dots, t_i, \dots, t_m)$$

$$\varphi(\vec{t}) = f \circ \vec{g}(\vec{t})$$

$$g_i : \mathbb{R}^m \rightarrow \mathbb{R}$$

$$\vec{g} : \mathbb{R}^m \rightarrow \mathbb{R}^n$$

$$f : \mathbb{R}^n \rightarrow \mathbb{R}$$

$$\varphi : \mathbb{R}^m \rightarrow \mathbb{R}^n \rightarrow \mathbb{R}$$

at \vec{b}

$$\frac{\partial \varphi}{\partial t_j} = \frac{\partial f}{\partial x_i} \frac{\partial x_i}{\partial t_j} + \dots + \frac{\partial f}{\partial x_n} \frac{\partial x_n}{\partial t_j} = \sum_{i=1}^n \frac{\partial f}{\partial x_i} \frac{\partial x_i}{\partial t_j}$$

If f is diff. at $\vec{b} = \vec{g}(\vec{a})$, \vec{g} is diff. at \vec{a} , then φ is diff. at \vec{a} .
And the above statement is true

- can replace "differentiable" with " C^1 about ". Also True.

Ex: $f(x, y, z) = x^2 y + z$, $x = x(s, t) = s + t$
 $y(s, t) = t^2$
 $z(s, t) = 2s$



$$w : \mathbb{R}^2 \rightarrow \mathbb{R}^3 \rightarrow \mathbb{R}$$

$$\frac{\partial w}{\partial s} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial s} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial s} + \frac{\partial f}{\partial z} \frac{\partial z}{\partial s} = 2xy \Big|_{\substack{x=s+t \\ y=t^2}} \cdot 1 + x^2 \Big|_{x=s+t} \cdot 0$$

$$+ 1 \cdot 2$$

$$= 2(s+t)^2 + 2$$

$$\frac{\partial w}{\partial t} = 2xy \Big|_{\substack{x=s+t \\ y=t^2}} \cdot 1 + x^2 \Big|_{x=s+t} \cdot 2t + 1 \cdot 0 = 2(s+t)t^2 + (s+t)^2 \cdot 2t$$

$w=f(\vec{x})$, $\vec{x}=g(\vec{t})$, $\vec{t}=(t_1, \dots, t_m)$

$w=w(\vec{x})$ also think as $w=w(\vec{t})$

A: $dw = \sum_{i=1}^n \frac{\partial w}{\partial x_i} dx_i$

B: $dw = \sum_{j=1}^m \frac{\partial w}{\partial t_j} dt_j$

But can write, $dx_i = \sum_{j=1}^m \frac{\partial x_i}{\partial t_j} dt_j \leftarrow C$

subbing C into A, $dw = \sum_{i=1}^n \frac{\partial w}{\partial x_i} \left(\sum_{j=1}^m \frac{\partial x_i}{\partial t_j} dt_j \right)$

$$= \sum_{j=1}^m \left(\sum_{i=1}^n \frac{\partial w}{\partial x_i} \frac{\partial x_i}{\partial t_j} \right) dt_j \leftarrow D$$

Saying B \Leftrightarrow D is saying $\frac{\partial w}{\partial t_j} = \sum_{i=1}^n \frac{\partial w}{\partial x_i} \frac{\partial x_i}{\partial t_j}$ \Leftarrow Chain Rule

$f(x(t), y(t), t) = f(x(t), g(t), u(t))$

mixes dep. & indep. in one formula.

$$\frac{dw}{dt} = \frac{\partial f}{\partial x} \frac{dx}{dt} + \frac{\partial f}{\partial y} \frac{dy}{dt} + \frac{\partial f}{\partial u} \cdot \frac{du}{dt}$$

$\downarrow \frac{\partial w}{\partial t}$



$w = f(x, y, t, s)$

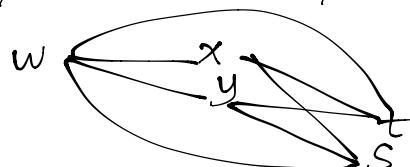
$\uparrow \quad \uparrow \quad \uparrow \quad \uparrow$

dep indep

$x = \phi(s, t)$
 $y = \psi(s, t)$

x, y are dependent on some independent s, t .

$$\frac{\partial w}{\partial s} = \partial_x f \partial x + \partial_y f \partial y + \partial_s f$$

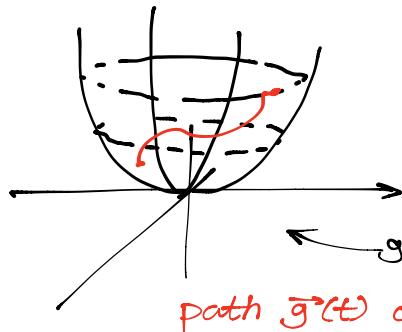


Using numbers removes ambiguities.

Ex: $f(x, y, t, s) = x^2 + ys + t$ - $x(s, t) = s + t$
 $y(s, t) = 2t$

$$\frac{\partial w}{\partial s} = 2x \Big|_{x=s+t} + s \cdot 0 + y \Big|_{y=2t}$$

$F(x, y, z) = 0$ is different from $z = f(x, y)$



$$z - x^2 - y^2 = 0$$

$$F(x, y, z) = z - x^2 - y^2$$

generically a "smooth surface" when F diff.

path $\vec{g}(t)$ on surface

$F(\vec{g}(t)) = 0 \leftarrow$ why? b/c $\vec{g}(t)$ is on the surface.

$$\frac{d}{dt} F(\vec{g}(t)) = 0$$

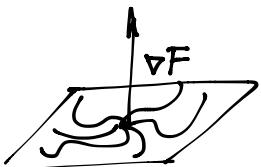
$$\frac{d}{dt} F(\vec{g}(t)) = \nabla F \cdot \vec{g}'(t)$$

via chain rule

so $\nabla F \cdot \vec{g}'(t) = 0 \Rightarrow \nabla F$ is orthogonal to $\vec{g}'(t)$

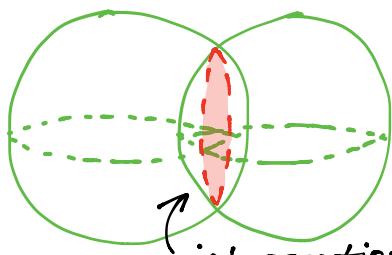
- $\vec{g}'(t)$ is known tangent to the curve given by $\vec{g}(t)$

- as ∇F is \perp for all such $\vec{g}'(t)$, then ∇F as being "normal" to our surface.



- Recall that ∇F is pointing in direction of maximum slope

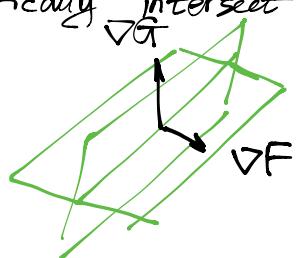
The equation of the tangent plane : $\underbrace{\nabla F \cdot (\vec{x} - \vec{a})}_\text{normal} = 0$



$$\text{For } F(x, y, z) = 0 \\ G(x, y, z) = 0$$

"generically" intersect in a curve

- If ∇F & ∇G are linearly independent, they span the plane \perp to intersection curve.

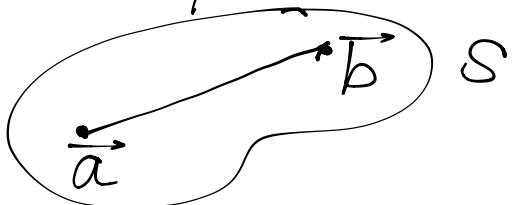


$F(x, y, z) = 0$, $z = f(x, y)$ can't always pull the eqn apart - namely the two eqns are not necessarily equal.

- In 1-D . called "curve"
 - 2-D. "surface"
 - 3-D "hypersurface"
-

Mean Value Theorem § 2.4

Set S - points \vec{a}, \vec{b}



Sps f defined on S , continuous on L , diff. on L , diff. on $L \setminus \{\vec{a}, \vec{b}\}$

$$L = \{\vec{x} \in S \mid \vec{a} + t(\vec{b} - \vec{a}), t \in [0, 1]\}, \exists \vec{c} \in L$$

$$\text{Then } f(\vec{b}) - f(\vec{a}) = \nabla f(\vec{c}) \cdot (\vec{b} - \vec{a})$$

← directional derivative in $(\vec{b} - \vec{a})$ direction (but not normalized)

$$\varphi(t) = f(\vec{a} + t\vec{h}), \vec{h} = \vec{b} - \vec{a}, t \in [0, 1].$$

- so composition of diff. functions on appropriate places

$$\begin{aligned} \varphi'(t) &= \nabla f(\vec{a} + t\vec{h}) \cdot \vec{h} && \leftarrow \text{by chain Rule} \\ &= \nabla f(\vec{a} + t\vec{h}) \cdot (\vec{b} - \vec{a}) \end{aligned}$$

$$\begin{aligned} \varphi(1) &= f(\vec{b}) \\ \varphi(0) &= f(\vec{a}) \end{aligned}$$

$$\exists u \cdot f(\vec{b}) - f(\vec{a}) = \varphi(1) - \varphi(0) = \varphi'(u)(1-0) = \varphi'(u) = \nabla f(\vec{a} + u\vec{h})(\vec{b} - \vec{a})$$

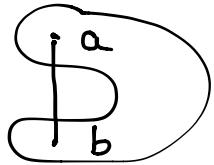
letting $\vec{c} = \vec{a} + u\vec{h}$

from MVT for $R \rightarrow R$

Although MVT doesn't work all the time, it works for two vectors which have a straight line in between.

\Downarrow
CONVEX

Def: A set is convex if $\forall \vec{a}, \vec{b}$ then $L = \{\vec{x} \in \mathbb{R}^n \mid \vec{x} = \vec{a} + t(\vec{b} - \vec{a}), t \in [0, 1]\} \subset S$



not convex

- If convex, surely it's path-connected.

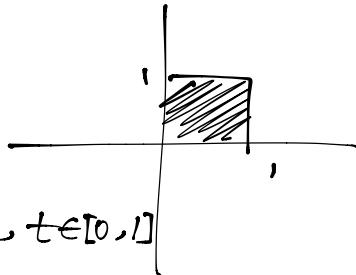
- Proved $B(r, x)$ is convex as we proved it is pathconnected using straight lines.

- likewise for \mathbb{R}^n .

$E_x:$

$$S = \{(x, y) | 0 \leq x \leq 1, 0 \leq y \leq 1\}$$

Claim: S is convex (hence path connected)



Proof: Take $\vec{a}, \vec{b} \in S$ - consider $\vec{a} + t(\vec{b} - \vec{a})$, $t \in [0, 1]$

$$\begin{aligned} \text{want } \vec{x} \in S \forall t, 0 \leq (1-t)a_1 + tb_1 \leq (1-t) \cdot 1 + t \cdot 1 = 1 \\ 0 \leq (1-t)a_2 + tb_2 \leq (1-t) + t = 1 \end{aligned}$$

$$\Rightarrow \vec{x} \in S \Rightarrow S \text{ is convex}$$

Thm: Let S be open & convex, f diff on S . Suppose $|\nabla f| \leq M$
then $|f(\vec{b}) - f(\vec{a})| \leq M |\vec{b} - \vec{a}|$

Proof: Mean Value Theorem $\Rightarrow \exists \vec{c} \in S$ s.t.

$$f(\vec{b}) - f(\vec{a}) = \nabla f(\vec{c}) \cdot (\vec{b} - \vec{a})$$

$$\text{Then } |f(\vec{b}) - f(\vec{a})| \leq |\nabla f(\vec{c})| |\vec{b} - \vec{a}| \leq M |\vec{b} - \vec{a}|$$

Cauchy-Schwarz

Corollary: If f diff. on open convex sets and $\nabla f = 0$ everywhere in S then S is constant on S .

$$\text{MVT} \Rightarrow \exists \vec{c}, f(\vec{b}) - f(\vec{a}) = \nabla f(\vec{c}) \cdot (\vec{b} - \vec{a}) = 0$$

$$\Rightarrow f(\vec{b}) = f(\vec{a}) \quad \forall a, b \in S$$

Thm: If f is diff on open, connected set S , then f constant.

Proof: Take S_1 as a disconnection of S .

$$S_1 = \{x | f(x) = f(a)\} \text{ after choosing some } a \in S.$$

$$S_2 = \{x | f(x) \neq f(a)\}$$

(S_1, S_2) must fail to be a disconnection for some property of a disconnection.

- $a \in S_1 \Rightarrow S_1 \neq \emptyset \checkmark$ trivially
- $S_1 \cup S_2 = S \checkmark$ as $f(x) =$ or $\neq f(a)$ exhausts possibilities
- Claim: $\overline{S_1} \cap S_2 = S_1 \cap \overline{S_2} = \emptyset$
- $\Rightarrow S_2 = \emptyset$
- $S_2 = \emptyset \Rightarrow S_1 = S \Rightarrow f(x) = f(a) \forall x \in S \Rightarrow f$ is constant.

Lemma: Sps A, B open, $A \cap B = \emptyset$, then $\overline{A} \cap B = \emptyset$, $\overline{B} \cap A = \emptyset$.

Proof: WLOG, say $x \in A \cap B$. As B open, $\exists r . B(r, x) \subset B$ as $x \in A$
 $\Rightarrow \forall r'$, in particular $r', B(r', x) \cap A^c \Rightarrow B(r', x) \not\subset B$ ■

If I can proof $S_2 \& S_1$ open as $S_1 \cap S_2 = \emptyset$, satisfies Lemma
 $\Rightarrow \overline{S}_1 \cap \overline{S}_2 = S_1 \cap \overline{S}_2 = \emptyset$

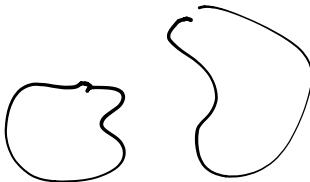
- S_2 is open, as: $\mathbb{R}^n \setminus \{f(a)\}$ is open as singleton sets are closed.
as f is diff, it is cont. $\Rightarrow f^{-1}(\text{open})$ is open $\Rightarrow S_2$ is open (as intersecting with S open stays open)

Can't do the same trick for S_1 as closed & open is ambiguous.

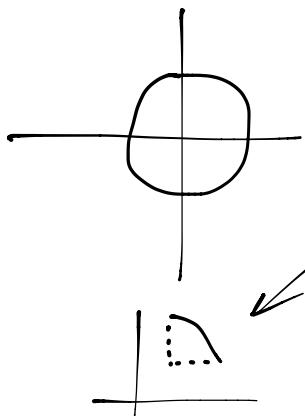
Instead for $x \in S$, $\exists B(r, x)$ s.t. $B(r, x) \subset S$. However, as $B(r, x)$ is convex, open, f is diff. & $\nabla f = 0$. $\Rightarrow f$ is constant on $B(r, x)$ by previous corollary.
 $\Rightarrow B(r, x) \subset S_1 \Rightarrow S_1$ is open. ■

$$S = S_1 \cup S_2$$

$$f(x) = \begin{cases} 1, & x \in S_1 \\ 0, & x \in S_2 \end{cases}$$



Counterexample to show why connected is needed.

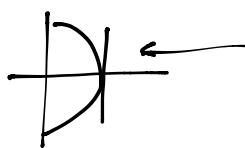


$$x^2 + y^2 = 1$$

- not a function it fails vertical line test

But take a portion - it passes the test
 $y = \sqrt{1-x^2}$

There is not a single function describes the whole part of $x^2 + y^2 = 1$.



always fails vertical test here. (and, the opposite point)

So for all points except $(1, 0), (-1, 0)$ can represent a portion of curve about a point. as the graph of a function

- Can generalize, except for problems in the derivative

dep $F(x_1, \dots, x_n, y) = 0$, F is diff.
When can we write $y = g(x_1, \dots, x_n)$?
Answer : Given by Implicit Function Theorem