

Lecture 2

Today's convex functions

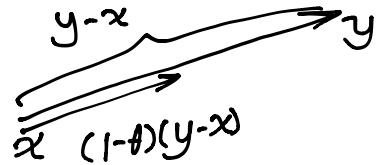
We are interested b/c for a convex function, every local minimum is a global minimum.

Def: A set $\Omega \subseteq E^n$ is convex if $\forall x, y \in \Omega$ and $\theta \in [0, 1]$.

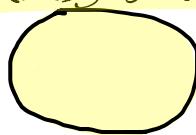
$$\theta x + (1-\theta)y \in \Omega$$

This means that if $x, y \in \Omega$, then the line segment joining x to y is contained in Ω .

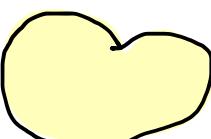
$$\theta x + (1-\theta)y = x + \underbrace{(1-\theta)(y-x)}_{\text{between } 0 \text{ and } 1}$$



Since as picture shows, the set of points $\{fx + (1-\theta)y : 0 \leq \theta \leq 1\}$ is exactly the line segment from x to y .



Yes



No



Yes

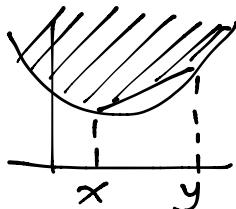
x -axis in $x-y$ coordinate is convex.

A function f on a convex set $\Omega \subseteq E^n$ is convex if for any $x, y \in \Omega$ and $\theta \in [0, 1]$. So $f(\theta x + (1-\theta)y) \leq \theta f(x) + (1-\theta)f(y)$ ~~✓~~
Strictly convex if $f(\theta x + (1-\theta)y) < \theta f(x) + (1-\theta)f(y)$

• f is concave if $-f$ is convex.

strictly concave if $-f$ is strictly convex.

e.g.



f on the line segment joining x and y \leq linear function on line segment that equals f at end pts.

i.e. \curvearrowleft is below \swarrow

Remark: f is a convex function iff $\{x, z \in E^n : z \geq f(x)\}$ is a convex set.

To prove ① Assume the function is convex and show that set is convex. (using def of convex set & convex function).

② Assume set is convex, deduce that function is convex.

Properties of convex functions:

① If f_1 & f_2 are convex functions

(always understood to be defined on a convex set Ω)
Then $f_1 + f_2$ is convex.

I must show that for any x, y in Ω , any $\theta \in [0, 1]$

$$(f_1 + f_2)(\theta x + (1-\theta)y) \leq \theta(f_1 + f_2)(x) + (1-\theta)(f_1 + f_2)(y)$$

True b/c.

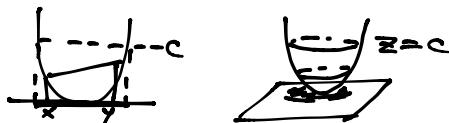
$$\begin{aligned} f_1 + f_2)(\theta x + (1-\theta)y) &= f_1(\theta x + (1-\theta)y) + f_2(\theta x + (1-\theta)y) \\ &\leq \theta f_1(x) + (1-\theta)f_1(y) + \theta f_2(x) + (1-\theta)f_2(y) \\ &= \theta(f_1 + f_2)(x) + (1-\theta)(f_1 + f_2)(y) \end{aligned}$$

- ② If f is convex and $a > 0$, then $a \cdot f$ is convex.
Pf: similar but easier.

Note: by combining the above:

If f_1, \dots, f_k are convex and $a_1, \dots, a_k \geq 0$ then $a_1 f_1 + \dots + a_k f_k$ is convex.

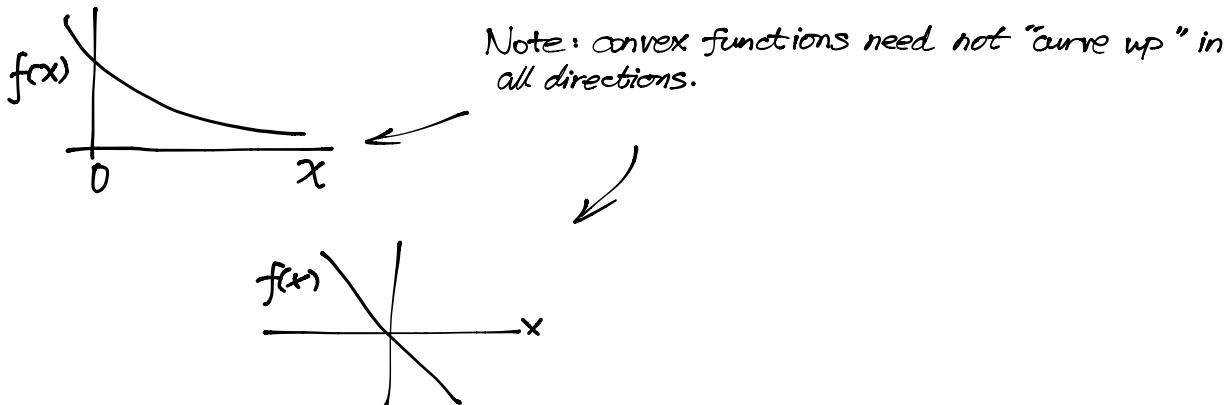
- ③ If f is a convex function on convex set Ω , then for any number c , $\{x \in \Omega : f(x) \leq c\}$ is a convex set.



Proof: Sps $x, y \in \{z \in \Omega : f(z) \leq c\}$
i.e. $f(x) \leq c$ and $f(y) \leq c$

Then for any $\theta \in [0, 1]$, by convexity $f(\theta x + (1-\theta)y) \leq \theta f(x) + (1-\theta)f(y) \leq \theta \cdot c + (1-\theta)c = c$

so $\theta x + (1-\theta)y \in \{z \in \Omega : f(z) \leq c\}$
so this set is convex



- ④ If f is a C' function on a convex set Ω , then f 's convex if
 $f(y) \geq f(x) + \nabla f(x)(y-x), \forall x, y \in \Omega$

Note: If I write $y = x + v$ then above becomes

~~$f(x+v) \geq f(x) + \nabla f(x) \cdot v, \forall x, v \in \Omega$~~

first order Taylor approximation of f near x .
equation for "tangent plane" to f at x (as function of v).



"function \geq every tangent plane"

Proof:

i) Assume f is convex

Fix $x, y \in \Omega$, have to show $\textcircled{4}$

By convexity:

$$f(\theta x + (1-\theta)y) \leq \theta f(x) + (1-\theta)f(y), \forall \theta \in [0, 1]$$

$$\parallel$$

$$f(x + (1-\theta)(y-x))$$

Subtract $f(x)$ from both sides:

$$f(x + (1-\theta)(y-x)) - f(x) \leq (1-\theta)(f(y) - f(x))$$

$$\text{so } \frac{f(x + (1-\theta)(y-x)) - f(x)}{(1-\theta)} \leq f(y) - f(x)$$

$$\lim_{\theta \rightarrow 1} \frac{f(x + (1-\theta)(y-x)) - f(x)}{(1-\theta)} \leq f(y) - f(x)$$

(directional derivative)

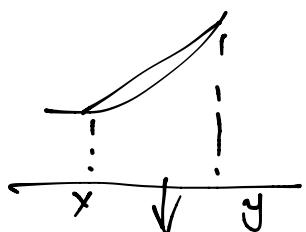
Since not hard to check that

$$\lim_{\theta \rightarrow 1} \frac{f(x + (1-\theta)(y-x)) - f(x)}{1-\theta} = \nabla f(x)(y-x)$$

(check it!)

this proves $\textcircled{4}$

$$\frac{d}{d\theta} \Big|_{\theta=1} f(x + (1-\theta)(y-x))$$



Now we assume $\textcircled{4}$ and try to show that f is convex.

Fix x and $y \in \Omega$ and $\theta \in [0, 1]$.

$$\text{Let } x_\theta = \theta x + (1-\theta)y$$

By condition $\textcircled{4}$

$$f(x) \geq f(x_\theta) + \nabla f(x_\theta)(x - x_\theta) \quad (1)$$

and

$$f(y) \geq f(x_\theta) + \nabla f(x_\theta)(y - x_\theta) \quad (2)$$

$$\text{Also, } x - x_\theta = (1-\theta)(x-y) \text{ and } y - x_\theta = \theta(y-x)$$

$$\text{So: } \theta(x - x_\theta) + (1-\theta)(y - x_\theta) = 0$$

$$\theta(\text{eqn 1}) + (1-\theta)(\text{eqn 2}) \Rightarrow \boxed{\theta f(x) + (1-\theta)f(y) \geq f(x_\theta)}$$

so f is convex.

⑤ If f is a C^2 function on a convex set Ω , then f is convex iff
 $\nabla^T \nabla^2 f(x) v \geq 0, \forall x \in \Omega, \text{ and } v \in E^n$

i.e. $\nabla^2 f$ positive semi-definite.

Proof: ① convexity \Rightarrow ~~property 4~~

Sufficient to show that

if ~~property 4~~ not true $\Rightarrow f$ not convex (contrapositive)

if ~~property 4~~ not true then $\exists x \in \Omega$ and $v \in E^n$ s.t. $\nabla^T \nabla^2 f(x) v < 0$.

By Taylor's Theorem:

$$f(x+hv) = f(x) + h \nabla f(x) v + \frac{1}{2} h^2 v^T \nabla^2 f(x) v + O(h^2 |v|^2)$$

This implies that if h is small enough, $\frac{1}{2} h^2 v^T \nabla^2 f(x) v + O(h^2 |v|^2) < 0$
so $f(x+hv) < f(x) + \nabla f(x)(hv)$

So f is non-convex by property ④

Now assume ~~property 4~~. We'll show that property ④ holds.

Fix x, y . Goal: $f(y) \geq f(x) + \nabla f(x)(y-x)$

Let $g(s) = f(x+s(y-x))$

Then $f(y) = g(1)$

$$f(x) = g(0)$$

By MVT, $\frac{g(1) - g(0)}{1 - 0} = g'(\theta)$ for some $\theta \in (0, 1)$

$$\begin{aligned} g(1) - g(0) &= g'(0) = g'(0) + (g'(\theta) - g'(0)) \\ &= g'(0) + \theta g''(s) \text{ for some } s \in (0, \theta) \end{aligned}$$

then one can check that

$$g'(0) = \nabla f(x)(y-x) \text{ and } g''(s) = (y-x)^T \nabla^2 f(x+s(y-x))(y-x)$$



has the form $v^T \nabla^2 f(z) v$, so ... ≥ 0

Put together to get $f(y) - f(x) \geq \nabla f(x)(y-x)$

Thm 1: If f is a convex function on a convex set Ω , then

- ① $\Gamma = \{x \in \Omega : f(x) = \inf_{\Omega} f\}$ is convex, and
- ② every local min is a global min

Proof: ① Let $c = \inf_{\Omega} f$

$$\text{Then } \Gamma = \{x \in \Omega : f(x) \leq c\}$$



and ↑ this is convex by property ③

Next: ② sufficed to show that if x is not a global min, then x is not a local min, then $\exists y$ s.t. $f(y) < f(x)$.

$f(\theta x + (1-\theta)y) \leq \theta f(x) + (1-\theta)f(y) < f(x), \forall \theta \in [0, 1]$ which implies that x is not a local min.

Thm 2: If f is convex on Ω and x^* is a point where $\nabla f(x^*)^T(y - x^*) \geq 0$ for all $y \in \Omega$, then x^* is a global min.

Proof: If this holds, by property ④
 $f(y) \geq f(x^*) + \nabla f(x^*)^T(y - x^*) \geq f(x^*), \forall y$

Corollary: If $\nabla f(x^*) = 0 \Rightarrow x^*$ global min.

Review of linear algebra :

1). Transpose of matrix

$$(AB)^T = B^T A^T$$

2). linear dependent/in-basis ...

3). determinants, eigenvalues, eigenvectors

$$\det \begin{pmatrix} a & b \\ c & d \end{pmatrix} = ad - bc = \begin{vmatrix} a & b \\ c & d \end{vmatrix}$$

$$\det \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix} = a_{11} \begin{vmatrix} a_{22} & a_{23} \\ a_{32} & a_{33} \end{vmatrix} - a_{12} \begin{vmatrix} a_{21} & a_{23} \\ a_{31} & a_{33} \end{vmatrix} + a_{13} \begin{vmatrix} a_{21} & a_{22} \\ a_{31} & a_{32} \end{vmatrix}$$

Property:

A not invertible $\Leftrightarrow \det A = 0$

$\Leftrightarrow \exists$ some nonzero vector v s.t. $Av = 0$
A number λ and nonzero vector v are eigenvalue & eigenvector if
equivalently $(A - I\lambda)v = 0$ where I = Identity matrix = $\begin{pmatrix} 1 & ? \\ ? & 1 \end{pmatrix}$

Combining above :

λ is an eigenvalue $\Leftrightarrow \det(A - \lambda I) = 0$

n -th-order polynomial in variable λ .

Strategy for finding e-values/vectors.

- ① compute polynomial $\det(A - \lambda I)$
- ② find roots $\lambda_1, \dots, \lambda_k$ these are eigenvalues
- ③ For each λ_i , find all solutions of $Av_i = \lambda_i v_i$.

Def: A matrix S is symmetric if $S^T = S$. as $S = \nabla^2 f(x)$

IMPORTANT FACT:

- if S symmetric, then all eigenvalues are real
- there is an orthonormal basis of eigenvectors.

$$\text{E.g. } S = \begin{pmatrix} 5 & -1 & -1 \\ -1 & 5 & -1 \\ -1 & -1 & 5 \end{pmatrix}$$

Find e-values/vectors

$$\text{eigenvalues: } \det(S - \lambda I) = (5-\lambda)^3 - (5-\lambda) = -(\lambda-3)(\lambda-6)^2$$

Find eigenvectors:

i. $\lambda=3$. must solve $(S-3I)v=0$

$$\text{i.e. } \begin{pmatrix} 2 & -1 & -1 \\ -1 & 2 & -1 \\ -1 & -1 & 2 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$v_1=v_2=v_3=1$$

$$\text{so } v = c \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \text{ where } c \text{ is a constant}$$

ii. $\lambda=6$

$$S-6I = \begin{pmatrix} -1 & -1 & -1 \\ -1 & -1 & -1 \\ -1 & -1 & -1 \end{pmatrix} = -\begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix}$$

$v = \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix}$ is an eigenvector if $v_1+v_2+v_3=0$

i.e. v orthogonal to $\begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$

So any vector v s.t. $v_1+v_2+v_3=0$ is an eigenvector when $\lambda=6$.

But I have to think a bit to find orthogonal eigenvectors.

e.g. $v = \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix}$ & $\begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}$ are e-vectors

but not orthogonal.

But $\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$ & $\begin{pmatrix} 1 \\ 1 \\ -2 \end{pmatrix}$ are orthogonal

orthonormal basis of eigenvectors

$$\frac{1}{\sqrt{3}} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}, \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}, -\frac{1}{\sqrt{6}} \begin{pmatrix} 1 \\ 1 \\ -2 \end{pmatrix}$$

Def: A symmetric matrix S is positive semi-definite if $v^T S v \geq 0$ for all $v \in E^n$.

positive definite if $v^T S v > 0$ for all nonzero $v \in E^n$.

Fact:

• S positive semi-definite \Leftrightarrow all eigenvalues ≥ 0

• S positive definite \Leftrightarrow all eigenvalues > 0

Why? Fix S symmetric & let $\lambda_1, \dots, \lambda_n$ eigenvalues, and $c v_1, \dots, c v_n \Rightarrow$ orthonormal basis of eigenvectors.

$$\text{i.e. } w^T w_k = \delta_{jk} = \begin{cases} 1 & \text{if } j=k \\ 0 & \text{if not} \end{cases}$$

- Any vector $v = a_1 w_1 + \dots + a_n w_n$

e.g. $v = a_1 w_1 + \dots + a_n w_n$

$$so v^T v = (a_1 w_1^T + \dots + a_n w_n^T)(a_1 w_1 + \dots + a_n w_n) = a_1^2 + \dots + a_n^2.$$

$$\begin{aligned} \text{and } v^T S v &= (a_1 w_1^T + \dots + a_n w_n^T) S (a_1 w_1 + \dots + a_n w_n) \\ &= (a_1 w_1^T + \dots + a_n w_n^T) (a_1 S w_1 + \dots + a_n S w_n) \\ &= (a_1 w_1^T + \dots + a_n w_n^T) (a_1 \lambda_1 w_1 + \dots + a_n \lambda_n w_n) \end{aligned}$$

$$v^T S v = \lambda_1 a_1^2 + \dots + \lambda_n a_n^2$$

Recall last week

To find optimal polynomial approximation to a function in g , given $g(x_1), \dots, g(x_m)$, we tried to minimize

$$f(a) = \sum_{k=1}^n (a_0 + a_1 x_k + \dots + a_n x_k^n - g(x_k))^2$$

We rewrite as $f(a) = a^T Q a - 2b^T a - c$ for some matrix Q , vector b , number c

Q: Is this function convex?