

Generating Random Variables

MC integration
 iid sample X_1, \dots, X_n from $f(x; \theta)$, approx $\mu = E[h(X)]$ by sample average $\hat{\mu} = \frac{1}{n} \sum_{i=1}^n h(X_i) \rightarrow f(x; \theta)$ (based on $L \sim N$)
 $\hat{\sigma}_n^2 = \frac{1}{n-1} \sum_{i=1}^n (h(X_i) - \hat{\mu})^2$

Prob inverse transform
 X has a continuous cdf $F_X(x) = Y$, then Y is uniformly distributed on $(0, 1)$. $P(F_X^{-1}(y) = x) = y$
 $X = F_X^{-1}(Y)$

Revision
 $T \sim \chi^2$, $U = \frac{Z^2}{\chi^2} \sim \chi^2_1$

Thm 2: U_1, \dots, U_n iid & $U_i \sim \chi^2_1$ then $\sum_{i=1}^n U_i \sim \chi^2_n$

Thm 3: $Z \sim \mathcal{N}(0, 1)$, $U \sim \chi^2_n$, $Z \perp U \Rightarrow T = \frac{Z}{\sqrt{U/n}} \sim t_n$

Thm 4: $U \sim \chi^2_m$, $V \sim \chi^2_n$, $U \perp V \Rightarrow W = \frac{U/m}{V/n} \sim F(m, n)$

Thm 5: $X_1, \dots, X_n \stackrel{iid}{\sim} \mathcal{N}(\mu, \sigma^2)$ $\Rightarrow 1. \bar{X} \sim \mathcal{N}(\mu, \sigma^2/n)$ 2. \bar{X} & S^2 are independent 3. $\frac{(n-1)S^2}{\sigma^2} \sim \chi^2_{n-1}$

Thm 6: $\frac{\bar{X} - \mu}{S/\sqrt{n}} \sim t_{n-1}$

unbiasedness: $\hat{\theta} = T(X_1, \dots, X_n)$, $E[T(X)] = \theta$, $\text{bias}(\hat{\theta}) = E[T(X)] - \theta$

MSE: $MSE[\hat{\theta}] = E[(\hat{\theta} - \theta)^2] = V(\hat{\theta}) + \text{bias}(\hat{\theta})$
consistency: $\hat{\theta}$ is weakly consistent if $P(|\hat{\theta} - \theta| > \epsilon) \rightarrow 0$ as $n \rightarrow \infty$ $\forall \epsilon > 0$.

By Chebyshev's inequality: $P(|\hat{\theta} - \theta| > \epsilon) \leq \frac{1}{\epsilon^2}[V(\hat{\theta}) + \text{bias}(\hat{\theta})]^2$. Thus $V(\hat{\theta}) \rightarrow 0$ & $\text{bias}(\hat{\theta}) \rightarrow 0 \Rightarrow$ consistency.

MVUE (minimum variance unbiased estimator) for $T(\theta)$. If unbiased $E[T^*] = T(\theta)$

& any other T with $E[T] = T(\theta)$ we have $V(T^*) \leq V(T)$.

(Also, it is the most efficient one!)

Cramér-Rao Ineq. [lower bound] r.v. X_1, \dots, X_n wrt. $f(x; \theta)$ where θ is a scalar para. let

$T = t(X_1, \dots, X_n)$ be an unbiased est. for $T(\theta)$, then under certain regularity conditions:
 $\text{Var}(T) \geq \frac{1}{I(\theta)} = \left\{ \frac{\partial}{\partial \theta} \log f(x; \theta) \right\}^{-1} I(\theta)$

$n(i(\theta))$: expected Fisher Information.

$I(\theta) = E\left[\left(\frac{\partial \log f(x; \theta)}{\partial \theta}\right)^2\right] = -E\left[\frac{\partial^2 \log f(x; \theta)}{\partial \theta^2}\right]$

Cramér-Rao Ineq. Extended. $\text{Var}(T(X)) \geq \frac{\left[\frac{\partial}{\partial \theta} E[T(X)] \right]^2}{E\left[\left(\frac{\partial}{\partial \theta} \log f(x; \theta) \right)^2 \right]} = \frac{\left[\frac{\partial}{\partial \theta} E[T(X)] \right]^2}{I(\theta)}$
if unbiased $E[T(X)] = T(\theta) \Rightarrow \text{Var}(T(X)) \geq \frac{1}{I(\theta)}$

iid $\Rightarrow \text{Var}(T(X)) \geq \left[T'(\theta) \right]^2 / n(i(\theta))$

Regularity conditions: ① $\frac{\partial}{\partial \theta} \log f(x; \theta)$ exists $\forall x \in \Theta$. ② Interchange of integration & differentiation is permissible. ③ $I(\theta) = E\left[\left(\frac{\partial}{\partial \theta} \log f(x; \theta)\right)^2\right] < \infty \forall \theta \in \Theta$.

Corollary (id case): regularity conditions hold, $T(X)$ is an unbiased estimator for $T(\theta)$ and we have $X_1, \dots, X_n \stackrel{iid}{\sim} f(x; \theta) \Rightarrow \text{Var}(T(X)) \geq \frac{1}{n} E[T(X)]^2 = \frac{1}{n} \left[T'(\theta) \right]^2 I(\theta)^{-1}$

Fisher Information
 $I(\theta) = E\left[\left(\frac{\partial}{\partial \theta} \log f(x; \theta)\right)^2\right] = -E\left[\left(\frac{\partial}{\partial \theta} \log f(x; \theta)\right)^2\right] = \frac{n E\left[\left(\frac{\partial}{\partial \theta} \log f(x; \theta)\right)^2\right]}{n(i(\theta))} = \frac{n(i(\theta))}{n(i(\theta))} I(\theta)$
one data: $i(\theta)$; iid data: $n(i(\theta)) = I(\theta)$

#**Sufficiency Principle:** $T(X_1, \dots, X_n)$ is a sufficient statistic for θ , then any inference about θ should be on the sample \vec{X} only through $T(X_1, \dots, X_n)$

#**Sufficiency:** A statistic $T(X_1, \dots, X_n)$ is sufficient for θ if the conditional distribution of sample X_1, \dots, X_n given $T(X_1, \dots, X_n)$ does not depend on θ . i.e. $P(X_1=x_1, \dots, X_n=x_n | T(X_1, \dots, X_n))$ does not depend on θ .

#**the factorization thm:** Sps $X_1, \dots, X_n \sim f(x; \theta)$, then $T(\vec{X})$ is a sufficient statistic for θ iff \exists two non-negative function K_1 & K_2 st. the likelihood $L(\theta; \vec{x})$ can be written

$$f(\vec{x}; \theta) = L(\theta; \vec{x}) = K_1[T(\vec{x}); \theta] \cdot K_2[\vec{x}]$$

If there exist multiple θ s as $\vec{\theta}$, then \exists $\vec{t}(\vec{x})$ multiple statistics which are sufficient.

#**Minimal Sufficient:** A sufficient statistic $T(\vec{X})$ is called a minimal sufficient statistic if, for any other sufficient statistic $T'(\vec{X})$, $T'(\vec{X})$ is a function of $T(\vec{X})$. (Not easy to find one with such definition.)

#**Lemma:** Let $f(\vec{x}; \theta)$ be pdf or pmf of a sample \vec{X} . Sps \exists a function $T(\vec{X})$ st. for every two sample points \vec{x} & \vec{y} the ratio

$$\frac{L(\theta; \vec{x})}{L(\theta; \vec{y})} \text{ is constant as function of } \theta \text{ iff } T(\vec{x}) = T(\vec{y}) \text{ or a vector}$$

Then $T(\vec{x})$ is a minimal sufficient statistic.

Any 1-1 function of a minimal sufficient statistic is also minimal sufficient. (So not unique)

#**Rao-Blackwell Thm:** W be any unbiased estimator of $T(\theta)$, T be a sufficient statistic for θ .

Define $\phi(T)=E[W|T]$, then $E[\phi(T)]=T(\theta)$, $V[\phi(T)] \leq V[W]$

If we have unbiased estimator & condition it on a sufficient statistic, our new statistic $\phi(T)$ has the same or smaller variance!

↳ also unbiased

Note: ① $E[X]=E[E[X|Y]]$; ② $V[X]=V[E(X|Y)]+E[V(X|Y)]$

"Better estimator", key idea is sufficiency.

#**Complete Statistics:** $f_{\vec{T}}(t; \theta)$ be a family of pdfs or pmfs for a statistic $T(\vec{x})$. The family of prob. distributions is called complete if

$$E[h(T)] = \int h(t) f_{\vec{T}}(t) dt = 0 \text{ for all } \theta \Rightarrow P(h(T)=0)=1 \quad \forall \theta.$$

#**Lehman-Scheffe Thm:** X_1, \dots, X_n r.sample from dist. with pdf $f(x; \theta)$. If $T=T(\vec{X})$ is a complete & sufficient statistic, and $\phi(T)$ is an unbiased estimator of $T(\theta)$, then $\phi(T)$ is the unique MVUE of $T(\theta)$.

#**How to find MVUEs?**

- ① a. Find or construct a sufficient & complete statistic T
 - b. Find unbiased estimator W for $T(\theta)$
 - c. Compute $\phi(T)=E[W|T]$, then $\phi(T)$ is MVUE.
- ② b' Find a func $h(T)$ s.t. $E[h(T)]=T(\theta)$
- c' $h(T)$ is the MVUE.

#**Exponential Families:** a.r.v. in k-parameter expo. family of dist. if its pdf is

$$f(x; \vec{\theta}) = \exp\left(\sum_{j=1}^k A_j(\vec{\theta})B_j(\vec{x}) + C(\vec{x}) + D(\vec{\theta})\right) \text{ or } C^*(x) D^*(\vec{\theta}) \exp\left(\sum_{j=1}^k A_j(\vec{\theta})B_j(x)\right)$$

#**canonical form:** Let $\phi=(\phi_1, \dots, \phi_k)=A(\vec{\theta})=[A_1(\theta), \dots, A_k(\theta)] \Rightarrow f(x; \theta)=\exp\left(\sum_{j=1}^k \phi_j B_j(x) + C(x) + D(\phi)\right)$ with $\theta=A^{-1}(\phi)$, $D(\phi)=D[A^{-1}(\phi)]$.

#**expo. family sufficiency:** Under regularity condition, a vector of k sufficient statistics \vec{T} exists for a vector of parameters $\vec{\theta}$ iff the dist. of \vec{X} belong to the k-para expo. family.

LEMMA: \vec{T} is also minimal sufficient.

LEMMA: \vec{T} is also complete.

$$\sum_{k=0}^{\infty} \frac{z^k}{k!} = e^z$$

#Point Estimation

#MOM: $\hat{\mu}_k = \bar{E}_{\theta}(X^k)$, $\hat{\mu}_k = \frac{1}{n} \sum_{i=1}^n x_i^k$, $k=1, \dots, K$.

#Central moment $\hat{\mu}'_k = \bar{E}_{\theta}(\{X - E_{\theta}(X)\}^k)$, $\hat{\mu}'_k = \frac{1}{n-1} \sum_{i=1}^n (x_i - \bar{x})^k$, $k=2, \dots, K$. $\hat{\mu}_1 = \hat{\mu}'_1 = \bar{x}$

↳ generalization:

$$E_{\theta}(g_1(X)) = \frac{1}{n} \sum_{i=1}^n g_1(x_i), \dots, E_{\theta}(g_k(X)) = \frac{1}{n} \sum_{i=1}^n g_k(x_i) \quad \text{if } g_i(x) = x^i \Rightarrow \text{MOM}$$

#MLE $\hat{\theta} \rightarrow \text{maximizes } L(\theta; x) = L(\theta; x_1, \dots, x_n) = f(x_1, \dots, x_n; \theta)$

check $L' < 0$.

log-likelihood $l(\theta) = \log[L(\theta)]$, $|\theta| \rightarrow \infty$, $l(\theta) \rightarrow 0$,

Score Function is the gradient of $l(\theta)$: $U(\theta) = \frac{\partial l}{\partial \theta} = l'(\theta)$

#with right censoring X_1, \dots, X_m obs. X_{m+1}, \dots, X_n censored

$$L(\theta) = \prod_{i=1}^m f_X(x_i; \theta) \prod_{i=m+1}^n (1 - F_X(T; \theta))$$

#general checking: (3 hcl)

① First order partial derivatives at $\hat{\theta}_1, \hat{\theta}_2 = 0$: $\frac{\partial}{\partial \theta_1} H(\theta_1, \theta_2) \Big|_{\theta_1=\hat{\theta}_1, \theta_2=\hat{\theta}_2} = 0 = \frac{\partial}{\partial \theta_2} H(\theta_1, \theta_2) \Big|_{\theta_1=\hat{\theta}_1, \theta_2=\hat{\theta}_2} = 0$...

② At least one of the second-order derivs is negative.

③ The determinant of the matrix of 2nd order partial derivs is positive.

$$\begin{vmatrix} \frac{\partial^2}{\partial \theta_1^2} & \frac{\partial^2}{\partial \theta_1 \partial \theta_2} \\ \frac{\partial^2}{\partial \theta_2 \partial \theta_1} & \frac{\partial^2}{\partial \theta_2^2} \end{vmatrix} \Big|_{\theta_1=\hat{\theta}_1, \theta_2=\hat{\theta}_2} > 0$$

$$\textcircled{1} U = l'(\theta / \bar{x}), H(\theta) = l''(\theta / \bar{x}), \theta_1, \hat{\theta}$$

$$\textcircled{2} U(\theta) = U(\theta_0) + (\theta - \theta_0) H(\theta_0) + \dots$$

$$\textcircled{3} \text{At } \theta = \hat{\theta}, U(\hat{\theta}) = 0 = U(\theta_0) + (\hat{\theta} - \theta_0) H(\theta_0) + \dots$$

$$\textcircled{4} \hat{\theta} = \theta_0 - H'(\theta_0) U(\theta_0)$$

$$\textcircled{5} \text{update: } \theta_1 = \theta_0 - H'(\theta_0) U(\theta_0) \dots$$

$$\textcircled{6} \text{until } \theta_k \text{ converges to } \theta \text{ real.}$$

#MLE computations

#Newton-Raphson (N-R) method

(also applicable for multivariate)

#Method of scoring
Hessian $H(\vec{\theta})$ is replaced by its expectation $E[H(\vec{\theta})] = -I(\vec{\theta})$

$$\text{so } \vec{\theta}_{t+1} = \vec{\theta}_t + I^{-1}(\vec{\theta}_t) U(\vec{\theta}_t)$$

EM: $E\{l(\theta; y_{obs}, y_{miss})/\theta^{(t)} | y_{obs}\} = \int [\dots] k(y_{miss}|y_{obs}, \theta) dy_{miss}$. M step: maximize previous value w.r.t. θ , set $\hat{\theta}^{(t+1)}$ to be the maximized. # invariance property if $\hat{\theta}$ is MLE of θ , $\hat{g}(\hat{\theta})$ is MLE of g , when $g(x), \theta = h(x)$, $g \circ \theta$ are 1-1 functions

MLE asymptotics: $\hat{\theta} = \frac{1}{n} l'(\theta; \bar{x}) \xrightarrow{D} N(\theta, I(\theta)) \otimes \sqrt{n}(\hat{\theta} - \theta) \xrightarrow{D} N(0, I(\theta)^{-1})$ ③ $\sqrt{n}(\hat{\theta} - \theta) \xrightarrow{D} N(0, \sigma^2) \Rightarrow \sqrt{n}(g(\hat{\theta}) - g(\theta)) \xrightarrow{D} N(0, \sigma^2[g'(\theta)]^2)$ ④ $T(\theta)$ is a cont. $T(\hat{\theta}) \sim N(I(\theta), \frac{I'(\theta)}{I(\theta)})$ # Type I error: Reject H_0 when it's true. := in rejection region under H_0 . # Type II error: do not reject H_0 when it's false fall outside CR under H_1 . # α : prob(type I error) # Power $\gamma(\theta) = 1 - P(\text{Type II error}) = P(X \in C|H_1)$ P-value = $P(T(\theta) > t(\theta)|H_0)$

Neyman-Pearson, $H_0: \theta = \theta_0, H_1: \theta = \theta_1, \lambda(\theta) = \frac{L(\theta_1; x)}{L(\theta_0; x)}$. test $C = \{T(\theta) \leq k\}$ For a given α , we could compare the power $\gamma(\theta) \Rightarrow$ find a UMP test std. $\hat{g}(\hat{\theta}) \geq g(\theta_0)$ NP \Rightarrow UMP. # MLRT: not UMP. $\lambda(\hat{\theta}) = \frac{\max_{\theta \in \Omega} L(\theta; \bar{x})}{\max_{\theta \in \Omega \setminus \{\theta_0\}} L(\theta; \bar{x})}$, test ...

LRT asymptotics Thm: under H_0 , $n \rightarrow \infty, -2\log[\lambda(\hat{\theta})] \xrightarrow{D} \chi^2_1 \Rightarrow$ find with $P(-2\log[\lambda(\theta)] > k^*) = 0.05$

When more than 1 constraints $-2\log[\lambda] \xrightarrow{D} \chi^2_k$ # The Score Test $t(\theta) = (\frac{\partial l}{\partial \theta_1}, \dots, \frac{\partial l}{\partial \theta_k})^T, H_0: \theta = \theta_0, H_1: \theta = \theta_1, TS: t(\theta)^T I(\theta)^{-1} t(\theta) \sim \chi^2_k$ # Wald Test: $TS: (\hat{\theta} - \theta_0)^T I(\hat{\theta})^{-1} (\hat{\theta} - \theta_0) \sim \chi^2_k$

Hypothesis & interval est. $X_i \stackrel{iid}{\sim} N(\mu, \sigma^2)$, test $H_0: \mu = \mu_0$ vs $H_1: \mu \neq \mu_0$. $C = \left\{ \frac{|X_i - \mu_0|}{\sigma} \geq \frac{Z_{1-\alpha/2}}{2} \right\} \Rightarrow P(C) \leq \frac{Z_{1-\alpha/2}}{2} \leq Z_{1-\alpha} \Rightarrow P(C) \leq \alpha \Rightarrow$ PC $\approx 1 - \alpha$

pivotal quantity: $P(g_i \leq g(X_i) \leq g_0) = 1 - \alpha, P(g(X_i) \leq g_0) = 1 - \alpha, \hat{\theta} \sim N(\theta, I(\theta)^{-1}), \frac{\hat{\theta} - \theta}{\sqrt{I(\theta)}} \sim N(0, 1)$, asymptotic $[\hat{\theta} - \theta \pm \frac{1}{\sqrt{I(\theta)}}, \hat{\theta} + \frac{1}{\sqrt{I(\theta)}}]$

Similarly $T(\hat{\theta}) \sim N(I(\theta), \frac{I'(\theta)}{I(\theta)^2}, \sqrt{\frac{I'(\theta)}{I(\theta)}}) \sim N(0, 1) \Rightarrow$ asymptotic $[T(\hat{\theta}) - \frac{Z_{1-\alpha/2}}{\sqrt{I(\theta)}}, T(\hat{\theta}) + \frac{Z_{1-\alpha/2}}{\sqrt{I(\theta)}}]$

Bayesian $p(\theta|x) = \frac{p(x|\theta)p(\theta)}{p(x)}$ $\propto p(x|\theta)p(\theta)$ = likelihood \times prior. Posterior mean of θ (mean of function $T(\theta)$): $\hat{\theta}_B = E[\theta|x] = \int_{\theta} \theta p(\theta|x)d\theta, \hat{T}(\theta_B) = E[T(\theta)|x] = \int_{\theta} T(\theta) p(\theta|x)d\theta$

conjugate: prior & posterior in the same class. Some common pairs (likelihood, posterior/prior) (N, N), (exp(Gamma)/ χ^2 , Gamma), (Geo/Bin, Beta).

Bayesian testing: reject H_0 if $P(\theta \in \Theta_1|x) > P(\theta \in \Theta_0|x)$

Bayes factor & testing: $X_1, \dots, X_n \stackrel{iid}{\sim} N(\theta, \sigma^2), \theta \sim N(\mu, T)$, $H_0: \theta \leq \theta_0$ vs $H_1: \theta > \theta_0$. $[|\theta|/x] \sim N\left(\frac{\sigma^2 \mu + n \bar{x}}{\sigma^2 + n T}, \frac{\sigma^2}{\sigma^2 + n T}\right)$. Check $\int_{\theta_0}^{\infty} p(\theta|x)d\theta$ vs $\int_{\theta_0}^{\infty} p(\theta|x)d\theta$

Take $\beta = \theta - \theta_0$ as Bayes factors. Compare M_1 vs M_2 . $M_1: y_i = \alpha + \varepsilon_i, \varepsilon_i \sim N(0, \sigma^2), \theta_1 = (\alpha, \sigma^2)$, $M_2: y_i = \alpha + \beta x_i + \varepsilon_i, \varepsilon_i \sim N(0, \sigma^2), \theta_2 = (\alpha, \beta, \sigma^2)$

posterior $\pi(M_1|x) = \frac{f(x|M_1)p(M_1)}{f(x|M_2)p(M_2)}, f(x|M_1) = \int f(x|\alpha, \theta_1) \pi(\theta_1|M_1)d\theta_1, p(M_1) = \sum_{\alpha} f(x|\alpha, \theta_1) \pi(\theta_1|M_1), \frac{\pi(M_1|x)}{\pi(M_2|x)} = \frac{f(x|M_1)}{f(x|M_2)} \times \frac{\pi(M_1)}{\pi(M_2)} = BF(M_2; M_1) \times \frac{\pi(M_2)}{\pi(M_1)}$ (if $BF > 3.2$ reject H_0)

Bayesian Interval Estimation Find C s.t. $P_{\pi}(\theta|X) \subset C = \int_{\theta} \pi(\theta|x)d\theta = 1 - \alpha$.

① Equal-tailed $\int_{\theta_L}^{\theta_U} \pi(\theta|x)d\theta = \frac{\alpha}{2}, \int_{\theta_0}^{\infty} \pi(\theta|x)d\theta = \frac{\alpha}{2}$ ② Smallest length: minimize $\theta_U - \theta_L$ ③ HPD, $\theta \in C$ & $\pi(\theta|x) > \pi(\theta_0|x) \Rightarrow \theta_0 \in C$

Bayesian sufficient: $T(\bar{X})$ is sufficient for θ iff $\theta|T(\bar{X})$ is the same as $\theta|X$.

Risk function $R(\theta, \delta|\bar{X}) = \int L(\theta, \delta|\bar{X}) L(\theta, \bar{X}) d\theta$. inadmissible $\delta_1, \exists \delta_2$ s.t. $R(\theta, \delta_1) \geq R(\theta, \delta_2) \forall \theta$.

-minimax: minimize the $\max_{\theta} R(\theta, \delta)$.

Bayes Risk: $\int R(\theta, \delta)p(\theta)d\theta$ minimized $\Rightarrow \int p(\theta) [\int_{\theta} L(\theta, \delta)p(\theta|x)d\theta] dx$ minimize posterior expected loss

Simple loss functions: ① zero-one loss $L(\theta, \delta = \hat{\theta}) = \int 0$ when $|\theta - \hat{\theta}| < b$ ② Absolute error loss: $L(\theta, \delta = \hat{\theta}) = a|\theta - \hat{\theta}|$, $\hat{\theta}_{\text{min}} = \text{median}$ ③ Squared error loss $L(\theta, \delta = \hat{\theta}) = a(\theta - \hat{\theta})^2$ a when $|\theta - \hat{\theta}| \geq b$ and $a > 0$

Non-parametric

Empirical dist: $F_{\text{obs}} = \frac{1}{n} \sum_{i=1}^n \mathbb{I}(x_i = x)$, $F_{\text{pred}} = p(x) = \frac{1}{n} \sum_{i=1}^n F(x_i)$. $E[\hat{F}(x)] = \frac{1}{n} \sum_{i=1}^n F(x_i) = \frac{n_x}{n} \leftarrow * \text{ of observed less than or equal to } x. V(\hat{F}) = V(\frac{n_x}{n}) = \frac{1}{n^2} n p(1-p) = \frac{1}{n} F(0)(1-F(0))$

Bootstrap dist: $\hat{B}_{\text{obs}} = E_p\{ \hat{O}(\hat{F}^*) - O(\hat{F}) \}, \hat{V}_{\text{obs}} = E_p\{ (\hat{O}(\hat{F}^*))^2 - [E_p\{ \hat{O}(\hat{F}^*) \}]^2 \}$. After resampling: estimate $\hat{\theta}_b = O(\hat{F}_b^*) \Rightarrow$ instead of normal.

$\hat{\theta}_B \approx \frac{1}{B} \sum_{b=1}^B \hat{\theta}_b^* - \bar{\theta}, \hat{V}_B = E_p\{ (\hat{O}(\hat{F}^*))^2 \} \approx \frac{1}{B-1} \sum_{b=1}^B (\hat{\theta}_b^* - \frac{1}{B} \sum_{b=1}^B \hat{\theta}_b^*)^2, \hat{\sigma}_B^2 = \sqrt{\frac{1}{B-1} (\hat{V}_B - \bar{\theta}^2)}$ Bootstrap interval est. $[\bar{\theta} \pm \frac{Z_{1-\alpha/2}}{\sqrt{B}} \hat{\sigma}_B]$, for small sample, use t-dist quant.

BS test: Draw B samples of size $N = n+m$ with replacement from $\bar{z} = \{y_1, \dots, y_n, x_1, \dots, x_m\}$, the first n obs. := \bar{y}^* , remaining m obs. := \bar{x}^* . Evaluate TS $t(\bar{y}^*, \bar{x}^*, \bar{y}^* - \bar{x}^*)$.

Approx. p-value = $\# \{t(\cdot) \geq t_{\text{obs}}\}/B$.

Inverse CDF sample generating: ① $T = -\beta \sum_{j=1}^n \log(U_j) \sim \text{gamma}(\alpha, \beta)$ ② $\beta = 2, T = -2 \sum_{j=1}^n \log(U_j) \sim \chi^2_{2n}$ ③ $T = \frac{\sum_{j=1}^n \log(U_j)}{\sum_{j=1}^n \log(U_j)} \sim \text{Beta}(\alpha, \beta)$

$\chi^2_1 \sim N(0, 1)$? Box-Muller Algorithm: $U_1, U_2 \sim \text{Unif}(0, 1)$, set $R = \sqrt{-2 \log(U_1)}, \theta = 2\pi U_2, X = R \cos(\theta), Y = R \sin(\theta)$, then $X \sim \mathcal{N}(0, 1), Y \sim \mathcal{N}(0, 1)$.

Discrete dist. generating: y_1, \dots, y_k . $P(F_{\text{pred}}(y_i) < u \leq F_{\text{pred}}(y_{i+1})) = P(Y_i < u)$. stepwise function.

Accept/Reject Algorithm: $T \sim f_T(y), V \sim f_V(y)$, densities have common support & $M = \sup_{y \in \text{common support}} \frac{f_T(y)}{f_V(y)} < \infty$. Want to sample from T , able to sample from V .

① Generate $U \sim U(0, 1)$, $V \sim f_V$ independently ② if $U < \frac{f_T(y)}{M f_V(y)}$, set $T = V$, otherwise return to step ① NB envelope = $M f_V(y) \geq f_T(y)$

Metropolis Hastings, $T \sim f_T(y), V \sim f_V(y)$ have the same support. Then to generate $T \sim f_T(y)$.

① set $z_0 = c$, any starting value, could draw a y^* from $f_V(y)$

② For $i = 1, \dots$:

②.1 Generate $T_i^* \sim f_V$ and $U_i \sim U(0, 1)$ and calculate:

$$\rho_i = \min\left\{\frac{f_T(T_i^*)}{f_T(z_{i-1})} \times \frac{f_V(z_{i-1})}{f_V(T_i^*)}, 1\right\}$$

②.2 Set $z_i = \begin{cases} T_i^* & \text{if } U_i \leq \rho_i \\ z_{i-1} & \text{if } U_i > \rho_i \end{cases}$

as $i \rightarrow \infty, z_i \xrightarrow{D} T$

* intuition, $r > 1$, accept T^*
 $r \leq 1$, accept T^* at rate r .

* common symmetric proposal dist. $f_V(T_i^*|z_{i-1}) = U(z_{i-1} - \delta, z_{i-1} + \delta)$

$$f_V(T_i^*|z_{i-1}) = \mathcal{N}(z_{i-1}, \sigma^2)$$

δ & σ are customized size of "jump".

Example of Decision Theory $\delta_3: L_3(\theta, \delta_3) \geq L_3(\theta, \delta_j) \quad j=1, 2, \forall \theta \Rightarrow \delta_3$ is inadmissible.

$\delta_1 = 0, \delta_2 = 5, \delta_3 = 3$, $\Pi(\theta_1) = 0.2, \Pi(\theta_2) = 0.3, \Pi(\theta_3) = 0.5$

minimize $\sum_{\theta} L_3(\theta, \delta_j) p(\theta)$, pick the minimum.

$\delta_3 = 1, 0, 1$ (no data) $\min_{\theta} \max_{\delta} R(\theta, \delta) = \min_{\theta} \max_{\delta} L_3(\theta, \delta)$