

Feb 5th

Last time

DEF: $T: V \rightarrow W$ is invertible if there is $S: W \rightarrow V$ such that $ST = I_V$ and $TS = I_W$

- Exs: ① $I: V \rightarrow V$ is invertible and $I^{-1} = I$
② $0: V \rightarrow V$ not invertible
③ $R_f: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ is invertible $R_f^{-1} = R_g$
④ $T: V \rightarrow F^n$ (V vector space over F)
 $T(v) = [v]_a$ is invertible

and $T^{-1} \left(\begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix} \right) = a_1 v_1 + \dots + a_n v_n$

⑤ $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ when is A invertible? when $\det A \neq 0$.

DEF: 1. $T: V \rightarrow W$ is an isomorphism if T is invertible

2. V, W are isomorphic if there exists some isomorphism $T: V \rightarrow W$ intuition "isomorphism" = "the same"

Ex: 1. Is $P_{n-1}(\mathbb{R})$ isomorphic to \mathbb{R}^n ?

$$T: \mathbb{R}^n \rightarrow P_{n-1}(\mathbb{R})$$

$$T \left(\begin{bmatrix} a_0 \\ a_1 \\ \vdots \\ a_{n-1} \end{bmatrix} \right) = a_0 + a_1 x + \dots + a_{n-1} x^{n-1}$$
$$S(a_0 + a_1 x + \dots + a_{n-1} x^{n-1}) = \begin{bmatrix} a_0 \\ \vdots \\ a_{n-1} \end{bmatrix}$$

$$ST = I_{\mathbb{R}^n}, TS = I_{P_{n-1}}$$

Ex: $SM_3(\mathbb{R})$ vector space of 3×3 symm matrices $A^T = A$

Q: Is SM_3 isom to \mathbb{R}^n for some n ?

What's $\dim SM_3$?

$$\dim SM_3 = 6$$

Claim: SM_3 isomorphic to \mathbb{R}^6

Pf: $T: \mathbb{R}^6 \rightarrow SM_3$

$$T \left(\begin{bmatrix} a \\ b \\ c \\ d \\ e \\ f \end{bmatrix} \right) = A$$

$TM: V, W$ fd vector spaces over F . Then V iso to W iff $\dim V = \dim W$.

Proof: \Rightarrow Suppose V is isomorphic to W
 Then let $T: V \rightarrow W$ be an invertible linear transformation
 Therefore T is a bijection
 So T is onto $\Rightarrow \dim V \geq \dim W$
 T is one-to-one $\Rightarrow \dim W \geq \dim V$
 So $\dim V = \dim W$
 (Although we could also show that T invertible $\Rightarrow T(\text{basis of } V) = (\text{basis of } W)$)

$\Leftarrow \dim W = \dim V = n$
 Let $\{v_1, \dots, v_n\}$ be a basis of V
 $\{w_1, \dots, w_n\}$ be a basis of W
 Define $T: V \rightarrow W$ by $T(v_i) = w_i$
 linear trans $V \rightarrow W$ is invertible iff its basis of V
 match basis of W

$T: V \rightarrow W$ invertible α basis of V β basis of W

$$[T^{-1}]_{\beta}^{\alpha} = ([T]_{\alpha}^{\beta})^{-1}$$

Proof: need to check that $[T]_{\alpha}^{\beta} [T^{-1}]_{\beta}^{\alpha} = I_n$

$$[T]_{\alpha}^{\beta} [T^{-1}]_{\beta}^{\alpha} = [TT^{-1}]_{\beta}^{\alpha} = [I_w]_{\beta}^{\alpha}$$

$$\begin{aligned} & [I_w]_{\beta}^{\alpha} \\ & I_w(w_j) = w_j \\ & \Rightarrow [I_w]_{\beta}^{\alpha} = I_n \end{aligned}$$

Change of Basis

V f.d. vector space of dim n
 α, β two basis
 Want: A $n \times n$ matrix s.t. for $v \in V$
 $A[v]_{\alpha} = [v]_{\beta}$
 A is called a change of basis matrix what's A ?

Recall: $T: V \rightarrow V$
 $[T]_{\alpha}^{\beta}([v]_{\alpha}) = [T(v)]_{\beta}$

take $T = I$ then $[I]_{\alpha}^{\beta}([v]_{\alpha}) = [v]_{\beta}$

Ex: $V = \mathbb{R}^2$, $\alpha = \left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \end{bmatrix} \right\}$

$$\beta = \left\{ \begin{bmatrix} 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right\}$$

$$[I]_{\alpha}^{\beta} \quad \begin{bmatrix} 1 \\ 1 \end{bmatrix} = 2 \begin{bmatrix} 2 \\ 1 \end{bmatrix} + 3 \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 \\ -1 \end{bmatrix} = - \begin{bmatrix} 2 \\ 1 \end{bmatrix} \Rightarrow [I]_{\alpha}^{\beta} = \begin{bmatrix} 2 & 3 \\ -1 & 1 \end{bmatrix}$$

$$V = \begin{bmatrix} 5 \\ 3 \end{bmatrix} \in \mathbb{R}^2 \quad [v]_{\alpha} = \begin{bmatrix} 1 \\ 4 \end{bmatrix}$$

$$[v]_{\beta} = \begin{bmatrix} 2 & 0 \\ 3 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 4 \end{bmatrix} = \begin{bmatrix} 2 \\ -1 \end{bmatrix}$$

Ex: $V = \mathbb{R}^n$, $\alpha = \{v_1, \dots, v_n\}$

$\beta = \{e_1, \dots, e_n\}$ st. basis

$$V = \mathbb{R}^2 \quad Q = \left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 1 \\ 3 \end{bmatrix} \right\}$$

$$[v]_{\alpha} = \begin{bmatrix} 3 \\ 2 \end{bmatrix}, \text{ what's } v?$$

$$v = 2 \begin{bmatrix} 1 \\ 2 \end{bmatrix} + 2 \begin{bmatrix} 1 \\ 3 \end{bmatrix} = \begin{bmatrix} 10 \\ -2 \end{bmatrix}$$

Prop: $T: V \rightarrow V$, α, β basis

$$A[T]_{\alpha}^{\alpha} A^{-1} = [T]_{\beta}^{\beta}$$

$$\text{where } A = [I]_{\alpha}^{\beta}$$

$$\text{proof: } A[T]_{\alpha}^{\alpha} A^{-1} = [I]_{\alpha}^{\beta} [T]_{\alpha}^{\alpha} ([T]_{\alpha}^{\beta})^{-1} = [I]_{\alpha}^{\beta} [T]_{\alpha}^{\alpha} [I]_{\beta}^{\alpha} = [T]_{\beta}^{\beta}$$

Ex: $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ has matrix

$$\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \text{ relative to basis } \alpha = \left\{ \begin{bmatrix} 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 5 \\ 3 \end{bmatrix} \right\}$$

What's matrix of T in standard basis β ?

$$[I]_{\alpha}^{\beta} = \begin{bmatrix} 2 & 5 \\ 1 & 3 \end{bmatrix} \text{ is from } \alpha \rightarrow \text{standard basis}$$

$$[I]_{\beta}^{\alpha} = \begin{bmatrix} 3 & -5 \\ -1 & 2 \end{bmatrix}$$

$$\Rightarrow [T]_{\beta}^{\beta} = \begin{bmatrix} 2 & 5 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} 3 & -5 \\ -1 & 2 \end{bmatrix} \begin{bmatrix} 3 & -5 \\ -1 & 2 \end{bmatrix} =$$

Ex: when $V = \mathbb{R}^n$, α, β basis of V

$$\text{want: } [I]_{\alpha}^{\beta}$$

Method: $\gamma = \{e_1, \dots, e_n\}$ standard basis

$$[I]_{\alpha}^{\beta} = [I]_{\gamma}^{\beta} [I]_{\alpha}^{\gamma}$$

DEF: A, B $n \times n$ matrices

A is similar to B if there is an invertible X st.

$$XAX^{-1} = B$$

$$\text{Ex: } [T]_{\alpha}^{\alpha} \text{ similar to } [T]_{\beta}^{\beta}$$

Prop: 1. Is A similar to itself?

$$IAI^{-1} = A \text{ so yes}$$

2. If A sim to B , is B sim to A ?

$$A \text{ sim to } B \text{ then } XAX^{-1} = B \Rightarrow X^{-1}BX = A \Rightarrow B \text{ sim to } A$$

3. If A sim to B and B sim to C is A sim to C ?

$$XAX^{-1} = B \quad YBY^{-1} = C$$

$$YXAX^{-1}Y^{-1} = YBY^{-1} = C$$

DEF: $T: V \rightarrow V$

If $T(v) = \lambda v$ and $v \neq 0$ then we say λ is a eigenvalue and v is a eigenvector

Exs: 1. $V = \mathbb{C}(R)$ $T = \frac{d}{dx}$, $\lambda \in R$

want eigenvector $f \in V$ of eigenvalue λ .

$$T(f) = \lambda f$$

$$f' = \lambda f \quad f = e^{\lambda x} + c$$

2. $V = (\mathbb{Z}_3)^2$

$$T = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix}, \quad v = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \Rightarrow T(v) = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

and so v is an eigenvector with eigenvalue $0 \in \mathbb{Z}_3$

3. Does $R_{\mathbb{Z}_3}$ have an e vector?

No, if we are over \mathbb{R} , but on \mathbb{C} , yes!

