

Jan 29th

$[V]_\alpha$ What does this mean?

V vector space over field F with basis $\alpha = \{v_1, \dots, v_n\}$
 $v \in V$, the coordinates of v w.r.t. α is

$$[v]_\alpha = \begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix} \in F^n \text{ where } v = a_1 v_1 + a_2 v_2 + \dots + a_n v_n$$

$$\underline{\text{Ex}}: V = \mathbb{R}^2 \\ \alpha = \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\} \\ \begin{bmatrix} 0 \\ 1 \end{bmatrix}_\alpha = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$\underline{\text{Ex}}: V = M_2(\mathbb{R}) \\ \alpha = \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 1 \end{bmatrix} \right\} \\ v = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix}$$

$$\&: [v]_\alpha = \\ \begin{cases} 1 = a+c \\ 2 = a+b \\ 2 = c+d \\ -1 = b+d \end{cases} \Rightarrow \left[\begin{array}{cccc|c} 1 & 0 & 1 & 0 & 1 \\ 1 & 1 & 0 & 0 & 2 \\ 0 & 0 & 1 & 1 & 2 \\ 0 & 1 & 0 & 1 & -1 \end{array} \right]$$

$T: V \rightarrow W$ lin trans.

V has basis $\alpha = \{v_1, \dots, v_n\}$

W has basis $\beta = \{w_1, \dots, w_m\}$

The matrix associated to T is $[T]_\alpha^\beta$ or $[T]_{\alpha\beta}$

$$\text{Given by: } T(v) = \sum_{i=1}^m a_{ij} \cdot w_i$$

Then $[T]_\alpha^\beta = [a_{ij}]$ an $m \times n$ matrix.

$\underline{\text{Ex}}: V = C^1(K) = \text{diff. function } \mathbb{R}^2 \rightarrow \mathbb{R}^3$

$T: V \rightarrow V : T(f) = f'$

$W \subset V, W = \text{span}\{f \cos \theta, f \sin \theta\}$

W is a 2 digit space w/ basis given by $f \cos \theta, f \sin \theta = \alpha$

$$T|_W: W \rightarrow W$$

$$T|_W \rightarrow W \\ \&: [T]_\alpha = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$$

$$T(\cos \theta) = -\sin \theta \\ T(\sin \theta) = \cos \theta$$

$\underline{\text{Ex}}: R_\theta: \mathbb{R}^2 \rightarrow \mathbb{R}^2$
 rotation by θ

$$[R_\theta]_\alpha = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

$$d = \{e_1, e_2\}, R_\theta(e_1) = \cos \theta e_1 + \sin \theta e_2$$

$$R_\theta(e_2) = -\sin \theta e_1 + \cos \theta e_2$$

Theorem: $T: V \rightarrow W$ lin. trans.

$\alpha = \{v_1, \dots, v_n\}$ basis of V

$\beta = \{w_1, \dots, w_m\}$ basis of W

$$v \in V \quad [T(v)]_\beta = [T]_\alpha^\beta [v]_\alpha$$

$$v \in V \quad v = a_1 v_1 + \dots + a_n v_n \quad \text{Evaluate } [v]_\alpha = \begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix} \in F^n$$

$$[T]_\alpha^\beta = [b_{ij}] ; T(v_i) = \sum_{j=1}^m b_{ij} w_j$$

$$\begin{aligned} T(v) + a_1 T(v_1) + \dots + a_n T(v_n) &= \sum_{k=1}^n a_k T(v_k) \\ &= \sum_{k=1}^n a_k T(v_k) = \sum_{k=1}^n a_k \left(\sum_{i=1}^m b_{ik} w_i \right) = \sum_{i=1}^m \left(\sum_{k=1}^n b_{ik} a_k \right) w_i \end{aligned}$$

$$[T(v)]_\beta = [b_{ij}] \begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix} = [T]_\alpha^\beta [v]_\alpha$$

Dim Theorem

$$T: V \rightarrow W \quad \dim V = \dim \ker(T) + \dim \text{im } T.$$

In matrix language: A m x n

$$n = \text{rank } A + \text{nullity } A$$

Assuming finite dim.

Corollaries

V, W finite dimensional vector space $T: V \rightarrow W$. If T is surjective then $\dim V \geq \dim W$

On the other hand, if T is injective $\dim V \leq \dim W$

§ 2.5 Composition

$$U \xrightarrow{S} V \xrightarrow{T} W$$

$\underbrace{T \circ S}_{TS}$

DEF: $TS(u) = T(S(u))$
"Composition of lin. trans."

Lemma: ST lin. trans. then TS is also.

$$\begin{aligned} \text{Proof: } TS(u_1 + u_2) &= T(S(u_1 + u_2)) \\ &= T(S(u_1) + S(u_2)) \\ &= T(S(u_1)) + T(S(u_2)) \\ &= TS(u_1) + TS(u_2) \quad \text{also scalar multi} \end{aligned}$$

Ex:

- ① $R_\theta \cdot R_\tau = R_{\theta+\tau}$
- ② $\text{Proj}_x: \mathbb{R}^2 \rightarrow \mathbb{R}^2$
 $\text{Proj}_y: \mathbb{R}^2 \rightarrow \mathbb{R}^2$
 $\text{Proj}_y \cdot \text{Proj}_x = 0$

- ③ $T: V \rightarrow V$
 $I \cdot T = T$
- ④ $T = R_{\pi/2}$ $S = \text{reflection about } y\text{-axis}$
 $S \cdot T(e_1) = S(e_2) = e_2$
 $T \cdot S(e_1) = T(-e_1) = -e_2$
 $S \cdot T \neq TS$

⑤ If S, T injective, is ST also inj.?

$$V \xrightarrow{T} W \xrightarrow{S} U$$

Look at $\ker ST$

$$\begin{aligned} v \in \ker ST &\Rightarrow ST(v) = 0 \\ &\Rightarrow T(v) = 0 \\ &\Rightarrow v = 0 \\ &\Rightarrow \ker ST = \{0\} \end{aligned}$$

Properties of compositions

① $T(SR) = (TS)R$

$$U \xrightarrow{R} V \xrightarrow{S} W \xrightarrow{T} X$$

② $U \xrightarrow{R,S} V \xrightarrow{T} W$

$$T(R+S) = TR + TS$$

③ $U \xrightarrow{R} V \xrightarrow{S,T} W$
 $(S+T)R = SR + TR$

Ihm: $U \xrightarrow{S} V \xrightarrow{T} W$

U has basis $\alpha = \{u_1, \dots, u_r\}$
 V has basis $\beta = \{v_1, \dots, v_m\}$
 W has basis $\gamma = \{w_1, \dots, w_n\}$

$$[TS]^\gamma_\alpha = [T]^\gamma_\beta [S]^\beta_\alpha$$

\uparrow composition \uparrow matrix mult.

Proof: $S(u_j) = \sum_{i=1}^m a_{ij} v_i$

$$\text{so } [S]^\beta_\alpha = [a_{ij}]$$

$$\cdot T(v_s) = \sum_{r=1}^n b_{rs} w_r \text{ so } [T]_s^r = [b_{rs}]$$

$$TS(u_j) = \sum_{r=1}^m c_{rj} w_r$$

$$[TS]_j^r = [c_{rj}]$$

$$\text{WANT: } [c_{rj}] = [b_{rs}] [a_{ij}]$$

$$\boxed{\text{i.e. } c_{rj} = \sum_{i=1}^m b_{ri} a_{ij}}$$

$$TS(u_j) = T(S(u_j)) = T\left(\sum_{i=1}^m a_{ij} v_i\right) = \sum_{i=1}^m a_{ij} T(v_i) = \sum_{i=1}^m a_{ij} \left(\sum_{r=1}^n b_{ri} w_r\right)$$

$$= \sum_{r=1}^n \left(\sum_{i=1}^m b_{ri} a_{ij} \right) w_r$$

$$\Rightarrow c_{rj} = \sum_{i=1}^m b_{ri} a_{ij} \quad \blacksquare$$

Ex: V vector space over \mathbb{F} of dim n . $\alpha = \{v_1, \dots, v_n\}$

Def: The dual of V^* is $V^{**} = L(V, \mathbb{F}) = \{T: V \rightarrow \mathbb{F}\}$

Recall: given $T: V \rightarrow W$ is determined by $T(v_i)$ for $i=1, 2, \dots, n$. in particular when $W=\mathbb{F}$ then T is determined by n numbers $T(v_1), \dots, T(v_n)$

Q: dim V^* ? Basis?

$$v_i^*: V \rightarrow \mathbb{F} \quad v_i^*(v_j) = \begin{cases} 1 & i=j \\ 0 & \text{else} \end{cases}$$

Claim: $\{v_1^*, \dots, v_n^*\}$ is a basis of V^* .

Proof: Sps $T \in V^*$, i.e. $T: V \rightarrow \mathbb{F}$. and let $a_i = T(v_i)$. Then $T = a_1 v_1^* + \dots + a_n v_n^*$ since $(a_1 v_1^* + \dots + a_n v_n^*)(v_i) = a_1 v_1^*(v_i) + \dots + a_n v_n^*(v_i) = a_i$

This shows $\{v_1^*, \dots, v_n^*\}$ span V^* . For lin. ind. sps $a_1 v_1^* + \dots + a_n v_n^* = 0$

$$\begin{aligned} a_i &= 0 \\ \Rightarrow &\text{ indep.} \end{aligned}$$

