Yulia Yakovleva

Machine Learning Engineer

Amsterdam Netherlands ☑ redslowi@gmail.com ? robolamp in Yulia Yakovleva kotobank.ch/~robolamp/

Main skills

C++ (Eigen), Python (PyTorch, Jupyter, NumPy, Keras, TensorFlow, Sklearn), Git, ROS, Linux, Machine Learning, Deep Learning, HPC, Computer Vision, NLP, LLMs

Experience

November 2022 – Machine learning engineer, Stability.ai, Amsterdam

May 2024 I worked on the following projects:

- Stable-Finetuning (Python, PyTorch, CUDA, diffusion models, HPC): I was mostly focused on whole preprocessing and training algorithm optimization. With my effort, the fine-tuning prosess became multiple times faster while the size of model increased. I managed to "accelerate" SAM to process big batches of images in less than 1 second. To comply with regulation, I managed to build a facial fine-tuning without facial keypoints detection. During the developed process, I was migrating the service between multiple generations of fine-tuned models and backends.
- Stability models API (Python, PyTorch, CUDA, diffusion models, AWS, HPC): Similar effort but without direct involvement into algorithms development.
- o LLM-related project (Python, PyTorch, CUDA, LLMs, axolotl, HPC).

March 2022 – Machine learning engineer, Rainbow.ai, Warsaw

September 2022 O I worked on applying deep learning models for weather forecasting (Python, PyTorch, Weather RADAR data).

November 2021 – Machine learning engineer, Descriptor.ai, Remote/Moscow

February 2022 O I created a few good-performing voice sentiment analysis models (Python, NumPy, TensorFlow, Keras, Audio data).

July 2021 - Machine learning engineer, MediaZona, Remote/Moscow

October 2021 O AI Text Generation (NLP, Python, NumPy, TensorFlow, Keras, Transformers, GPT): I worked on conditional text generation with neural networks. My responsibilities included both engineering/coding and interaction with non-tech employees of MediaZona on translating their non-tech requirements into "tech language", finding the data and getting a feedback on text generators' work.

March 2018 - Software engineer, Yandex Self-Driving Cars, Moscow

- May 2021 O Sensor diagnostics software (ROS, C++, Python, NumPy): I created data quality checking software modules for cameras and LiDARs.
 - Traffic lights recognition software (ROS, C++, Python, NumPy, Tensor-Flow, Keras).
 - I worked on improvement of traffic lights recognition and tracking pipeline,
 - learning data mining, pre-processing and datasets preparation,
 - created, learned and deployed multiple iterations of deep neural networks, which are working now on hundreds of self-driving cars made by Yandex.

October 2015 - Robotics researcher/developer, Institute for Information Trans-August 2017 mission Problems RAS (Kharkevich Institute), Moscow

> (C++, Python, ROS, Eigen, Computer Vision, Kalman filters) I worked on self-driving car prototype positioning and control software including: system launch tool to replace ROSLaunch, positioning and control systems (C++, Python, ROS, Eigen, Computer Vision, Kalman filters).

- O Self-driving car prototype positioning and control software. I created or worked on the following modules:
 - System launch tool to replace ROSLaunch (Python, ROS, Paramiko);
 - Local positioning system (C++, Eigen, Kalman filters);
 - Trajectory control system (C++, ROS);
 - Developers' web-interface (Python, JS (Leaflet.JS, Bootstrap), ROS);
 - Road markup-relied localization system (C++, ROS).
- O Initiative works in deep learning for robotics control (just for fun).

June 2015 – **Junior web-developer**, WETA Group, Remote

October 2015 Full-stack web-development

• Information security system web-interface: I developed two web-applications using Django non-rel backend and JS frontend with MongoDB database;

July 2013 – Junior control systems developer, Modern Signal Processing and June 2015 Control Technologies R&D Laboratory, Chelyabinsk

- Turboshaft engine control system development:
 - I performed Turboshaft math modelling using MATLAB/Simulink,
 - participated in control system design, test stands assembling and commissioning;
- Self-driving car prototype trajectory control system:
 - I proposed control algorithms and performed math modelling using MATLAB/Simulink,
 - implemented these Algorithms (C++, control unit with STM32 and NuttX RTOS),
 - performed HIL testing using Python and NumPy and participated in field tests.
- o I developed UAV test stand software: Scilab, interaction with National Instruments data acquisition system.

Patents

- 2020 Method of and system for determining traffic signal state Artamonov, Kalyuzhny, Yakovleva
 - O US Patent US20210201058A1, application at 2020.09.28, granted.
 - European Patent EP3842996A1, application at 2020.10.14, pending.

Talks

- 2019 Myths about Self-Driving Cars, Presented at WTM Moscow An interactive talk in Russian about self-driving cars architecture, sensors and testing.
- 2019 Traffic Lights in Yandex Self-Driving Cars, Presented at Yandex Self-Driving Meetup 2019, PyLadies Moscow and PyLadies Kazan A short talk in Russian about the difficulties of traffic lights recognition and about Yandex Self-Driving Cars traffic lights recognition pipeline.
- 2020 Data mining in Yandex Self-Driving Cars, Presented at Pytup Moscow

A short talk in Russian about data processing pipeline in Yandex Self-Driving Cars project.

- 2023 How does ChatGPT work?, Presented on a YouTube
 A talk in Russian about how ChatGPT works for tech folks who aren't working in AI.
- 2023 What's going on in AI world, Presented in Warsaw
 A popular talk in Russian abour recent history and trends in AI world for non-tech people.

Education

 $2010-2015 \quad \textbf{National Research South Ural State University};$

Computer Technologies, Control and Radio Electronics Faculty; Automation and Control Department; MEng with honours.

2015–2017 Moscow Institute of Physics and Technology (State University):

Department of Innovation and High Technologies; Cognitive technologies sub-faculty;

MSc in Computer Science.

Volunteering

May 2020 – now Web developer/data analyst, OVD-Info, Remote

OVD-Info is an independent human rights media project. I'm participating in development and support of information collection and analysis systems for OVD Info using SQL. Buthon and Diagram

for OVD-Info using SQL, Python and Django.

Jan 2021 – now **Technical volunteer**, Memorial, Remote

Languages

Russian Native speaker

English Fluent

Dutch Beginner

German Beginner

Tatar Beginner

Pet projects

rTerm, github.com/robolamp/rTerm

Fake JS-based UNIX term for my personal page.

Random three body problem bot, github.com/robolamp/3_body_problem_bot

A program which is simulating the behavior of random three body system multiple times and publishing animation of the most interesting one every 12 hours at Telegram channel.

Interests/hobbies

wildife photography, alpine skiing, cross-country skiing, books, jogging