Yulia Yakovleva

Software engineer

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Experience

March 2022 – Machine learning engineer, Rainbow.ai, Warsaw

Now O Weather prediction using deep learning models (Python, PyTorch, Image processing, Weather data)

November 2021 – Machine learning engineer, Descriptor.ai, Remote/Moscow

February 2022 O I created a few good-performing voice sentiment analysis models (Python, NumPy, TensorFlow, Keras, Voice data).

July 2021 - Machine learning engineer, MediaZona, Remote/Moscow

October 2021 • AI Text Generation (NLP, Python, NumPy, TensorFlow, Keras, Transformers, GPT): I worked on conditional text generation with neural networks. My responsibilities included both engineering/coding and interaction with non-tech employees of MediaZona on translating their non-tech requirements into "tech language", finding the data and getting a feedback on text generators' work.

March 2018 - Software engineer, Yandex Self-Driving Cars, Moscow

May 2021 • Sensor diagnostics software (ROS, C++, Python, NumPy): I created

- data quality checking software modules for cameras and LiDARs.
- o Traffic lights recognition software (ROS, C++, Python, NumPy, Tensor-Flow, Keras).
 - I worked on improvement of traffic lights recognition and tracking pipeline,
 - learning data mining, pre-processing and datasets preparation,
 - created, learned and deployed multiple iterations of deep neural networks, which are working now on hundreds of self-driving cars made by Yandex.

August 2017 - Software engineer, Unemployed/Self-employed, Moscow March 2018

October 2015 - Robotics researcher/developer, Institute for Information Trans-August 2017 mission Problems RAS (Kharkevich Institute), Moscow

- O Self-driving car prototype positioning and control software. I created or worked on the following modules:
 - System launch tool to replace ROSLaunch (Python, ROS, Paramiko);
 - Local positioning system (C++, Eigen, Kalman filters);
 - Trajectory control system (C++, ROS);
 - Developers' web-interface (Python, JS (Leaflet.JS, Bootstrap), ROS);
 - Road markup-relied localization system (C++, ROS).
- O Initiative works in deep learning for robotics control (just for fun).

June 2015 – **Junior web-developer**, WETA Group, Remote

October 2015 Full-stack web-development

• Information security system web-interface: I developed two web-applications using Django non-rel backend and JS frontend with MongoDB database;

July 2013 – Junior control systems developer, Modern Signal Processing and June 2015 Control Technologies R&D Laboratory, Chelyabinsk

- O Turboshaft engine control system development:
 - I performed Turboshaft math modelling using MATLAB/Simulink,
 - participated in control system design, test stands assembling and commissioning;
- Self-driving car prototype trajectory control system:
 - I proposed control algorithms and performed math modelling using MATLAB/Simulink,
 - implemented these Algorithms (C++, control unit with STM32 and NuttX RTOS),
 - performed HIL testing using Python and NumPy and participated in
- o I developed UAV test stand software: Scilab, interaction with National Instruments data acquisition system.

September 2012 – Laboratory assistant, South Ural State University, Chelyabinsk June 2015 Control systems research.

Talks

Traffic Lights in Yandex Self-Driving Cars, Presented at Yandex Self-Driving Meetup 2019, PyLadies Moscow and PyLadies Kazan A short talk in Russian about the difficulties of traffic lights recognition and about Yandex Self-Driving Cars traffic lights recognition pipeline.

Myths about Self-Driving Cars, Presented at WTM Moscow An interactive talk in Russian about self-driving cars architecture, sensors and testing.

Data mining in Yandex Self-Driving Cars, Presented at Pytup Moscow

A short talk in Russian about data processing pipeline in Yandex Self-Driving Cars project.

Volunteering

May 2020 – now

Web developer/data analyst, OVD-Info, Remote/Moscow OVD-Info is an independent human rights media project. I'm participating in development of information collection and analysis system for OVD-Info

using SQL, Python and Django.

Education

2010–2015 National Research South Ural State University;

Computer Technologies, Control and Radio Electronics Faculty;

Automation and Control Department;

MEng with honours.

2015–2017 Moscow Institute of Physics and Technology (State University);

Department of Innovation and High Technologies;

Cognitive technologies sub-faculty;

MSc in Computer Science.

Languages

Russian Native speaker

English Fluent

German Beginner

Tatar Beginner

Skills

Main:

C++ (Eigen), Python (Jupyter, NumPy, Keras, Sklearn), Git, ROS, Linux, Machine Learning, Computer Vision.

Experience with:

Bash, C, OpenCV, JS (some outdated frameworks), Django, Docker, LATEX, Dynamic systems math modelling, Matlab/Simulink.

Pet projects

rTerm, github.com/robolamp/rTerm

Fake JS-based UNIX term for my personal page.

Random three body problem bot, github.com/robolamp/3_body_problem_bot

A program which is simulating the behavior of random three body system multiple times and publishing animation of the most interesting one every 12 hours at Telegram channel.

Interests

Space, alpine skiing, cross-country skiing, bicycling.