

Lekan Molu

AI | Robotics | Control Systems

Full Legal Name: [Olalekan Ogunmolu](#).

Rerum Cognoscere Causas: To know the causes of things.

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Preamble *First-class, productivity-oriented* research scientist, engineer, and roboticist with experience at the intersection of machine learning, control systems, and robotics for automated decision-making in physical and virtual systems. Experience in companies and universities (United States, Europe, Asia, and Africa) across disciplines and industries to create business processes, address organizational issues and drive technical innovation. Closely collaborating and managing through positive influence with partnership teams (e.g. cross-geographic/cross-organization research, engineering, technical program managers, product teams, supply chain), and external vendors by optimizing technological/product innovation for volume scale-up.

Technical Skills

Software 2.0 Software infrastructure build-up for large research/product projects; subsystems testing and calibration methodology via (quick) prototype, test, refine cycle (as part of overall systems development). Experience with multi-node, multi-gpu deployment of large and deep foundation models: testing, refinement, probing, and utilities (GPT-4o, o1, Google Gemini etc.) for automation problems. Cloud computing (Azure blob container system, MSFT's Amulet and Pytoch's DDP); interprocess threads optimization; scaling distributed training via consistent maximization of GPU utilization across inter-geographic cloud clusters.

OS OSX, Debian, Ubuntu, Windows, Raspian.

Programming C++, Python, Mathematica, MATLAB, LabVIEW.

Learning Deep networks, Azure cloud (blob storage, k8s) with tools internal to Microsoft Research, PyTorch, and CuPy. Foundation models evaluation including GPT-4o, GPT-4o1, Transformers, recurrent networks, convolutional neural networks, Gaussian Processes, computer vision (SAM, DINO etc), ML object detection etc.

CAD Solid Works, AutoDesk Inventor, Blender, Adobe Illustrator, Adobe After Effects.

ROS Robot operating system (ROS 1) distros up to Melodic (ROSCpp and ROSPy); and ROS 2 systems including Bouncy Bolson, Ubuntu Kame and Mate embedded distros.

Libraries Point Cloud, OpenCV, Eigen, Docker, PyTorch, Numpy, CuPy, SciPy, Scikit-Learn, C++11/14/17.

Web HTML (beginner), Markdown (proficient).

Prototyping Experience in components selection (including design and control of soft actuators, programmable linear actuators, robot mechanism design, harmonic drives, 3D custom parts printing), sensors (MEMs, line and RGB-D cameras, and optical systems) selection and integration, microcontrollers integration (National Instruments, Raspberry Pi's, Arduinos), components specifications, schematic design.

Embedded Systems Experience with design of embedded systems, completing board layouts, assembling, testing, debugging, and integrating designs into opto-electro-mechanical systems. Communication protocols (e.g. TCP/IP, UDP, SPI, I²C – in C/C++, and python), Linux/Python scripting, and bash. Enjoy being hands-on in the lab, rapid software prototyping; enjoy being in the details (soldering, oscilloscopes, data acquisition) and a thriving gusto for engineering.

Patents

Alex Lamb, Riashat Islam, Yonathan Efroni, Aniket Didolkar, Dipendra Misra, Dylan Foster, **Olalekan Ogunmolu**, Rajan Chari, Akshay Krishnamurthy, John Langford. [Controllable Latent Space Discovery Using Multi-Step Inverse Model](#), Nov. 2022.

Professional Experience

May '21 - **Senior Researcher**, Machine Learning Group, [Microsoft Research](#), New York, NY, USA.

Present

- Part of the NYC RL group that drove state representation reinforcement learning research efforts for decision-making: Contributed to the team's fiscal year 2022 DTR presentation to company's senior leadership; co-authored papers which were presented at ICLR, ICML, and Neurips with NYC Research and Engineer colleagues; earned one Microsoft patent award.
- Successfully led, coordinated, and executed back-to-back global research meetings in Redmond, WA (2023 – 2024) that unified research workstreams (reinforcement learning, agentic LLMs, AI4Science, robotics) across different company organizations – spanning Amsterdam, Madrid (Spain), Cambridge (UK), Redmond, and Montreal.
- Consistent contributor to advancing the state of research efforts across machine learning, robotics and control theory with publications at the flagship conferences at these venues: ICRA, IROS, Neurips, ICLR, ICML, CDC, ACC etc. Proven leader with consistent invitation at the biggest venues to lead efforts surrounding safety and control of nonlinear dynamical systems.
- Mentoring junior researchers including postdocs, interns, and external PhD candidates. Proven track record with former interns, postdocs, and externally mentored PhDs now assistant professor at UMontreal, postdoctoral scholar at MIT, PhD student at Yale, Cornell Tech, Caltech, research scientist at Reliant Robotics (Bay Area), Embodied AI engineer at Wayve Technologies Ltd etc.
- Member of the global robotics steering team (spanning Redmond, Beijing, NYC, Cambridge, Zurich) driving a new robotic foundation model for bimanual objects retrieval in MSFT datacenters.

Summer '18 **Research Intern**, Robotics Team, [Preferred Networks](#), Otemachi, Chiyoda-ku, Tokyo, Japan.

- Developed and implemented a stable imitation learning policy of nonlinear trajectory tracking on the Tokyo Robotics manipulation arm.
- Introduced the deep learning robotics team to nonlinear backstepping control methods for data-driven robot behavior enhancement.
- Made two technical presentations about my work to company senior leadership.

Fall '17 - **Research Assistant**, Medical Artificial Intelligence and Automation Laboratory, Division of
Spring '19 Medical Physics and Engineering, Radiation Oncology Department, UT Southwestern Medical Center.

Research Assistant for Dr. Steve Jiang, Barbara Crittenden Professor of Cancer Research, UTSW Department of Radiation Oncology.

Developed a multidisciplinary approach (spanning Deep learning, optimal control, dynamic programming, and game theory) in order to solve the classic beam orientation optimization (BOO) problem.

Summer - **Research Assistant**, Dr. Tyler Summers, Mechanical Engineering, UT Dallas.

Fall '17 *Dynamic Programming, Decision Theoretic Control, Machine/Reinforcement Learning.*

Developed a game-theoretic controller for mitigating the lack of robustness in multi-stage decision policies on physical robots (P3DX).

Fall '14 - **Research Assistant**, Dr. Nick Gans, Electrical Engineering, University of Texas at Dallas.

Spring 19 *Control Systems, Systems Identification, State Estimation and Computer Vision.*

Conceived the prototypical testbed, procured hardware, integrated components to simulate soft robot compensating systems for patients in intensity modulated radiotherapy.

- Summer '16 **Hardware Integration Intern**, Amazon Robotics LLC.
SLAM, Software and Hardware Integration Intern for Tye Brady, Chief Technology Officer.
 Helped integrate the hardware and software for the P3-DX robot used as a recreational robot in the Amazon Robotics' North Reading, MA office. Collaborated closely as a team member within the robotic manipulation team: helped with emerging fulfillment centers end-of-arm-tooling (EOAT) design reviews, amazon robotics 2016 challenge problems design, helped other interns on their projects etc.
- Spring '16 **Hardware Integration Intern**, Advanced Robotics Lab, Amazon Robotics LLC.
Hardware Integration Intern for Dr. Andy Stubbs, Senior Hardware Systems Engineer.
 Computer vision (point cloud, depth, and RGB) integration for objects sorting, and pick and place line scanners at a prototype fulfillment center (later adopted for the Cataret, NJ fulfillment center).
- Miscellaneous**
- 2009–2011 **Supply Chain Manager, Apapa Plant**, *Coca-Cola Bottling Company*, Lagos, Nigeria.
 Minimized glass breakages by 40%, assured efficiency in supply chain operations by coordinating with the Ikeja/Head Office Logistics teams, supervised 3 Coca-Cola mega warehouse managers leading to a reduction in waste by 35% after a 9-month stint at Apapa mega-plant. Introduced new standard operating procedures company-wide and country-wide to formalize waste minimization processes, and improve production supply chain processes. This led to the Apapa plant being the highest selling plant for all Coca-Cola products for two consecutive quarters
- 01/2020 - 11/2021 **Adjunct Instructor, RBOT 250- Robot manipulation, planning and control**, *Brandeis University*
 Designing course outlines and teaching.
- Fall '14 - '16 **Teaching Assistant, Introduction to Robotics**, *University of Texas at Dallas*
 Guided students during laboratories in programming the Robai Cyton 300R2 Robot and graded homework.
- Spring '15 **Teaching Assistant, Linear Systems (M.S. Class)**, *University of Texas at Dallas*
 Responsible for helping Masters students with linear control theory applications; graded homework and midterms.

Education

- 2019 - 2021 **Postdoctoral Scholar**, [The University of Pennsylvania](#), Philadelphia, PA, USA.
 Design, build, and control of a soft robot for assisted MRI-based cancer radiation therapy.
- 2014 - 2019 **PhD in Electrical and Computer Engineering**, *University of Texas at Dallas*, Richardson, USA. "[A Multi-DOF Soft Robot Mechanism for Patient Motion Correction and Beam Orientation Selection in Cancer Radiation Therapy](#)"
- 2011 - 2013 **Master of Science in Engineering in Control Systems**, *The University of Sheffield*, Sheffield, United Kingdom. "[Autonomous Navigation of a Rotorcraft Unmanned Aerial Vehicle using Machine Vision](#)"

Addendum

- Epilogue Please consult the attached addendum for a full delineation of up-to-date publications, invited workshops, awards and honors, community service and community leadership.