

Lekan Molu

AI | Robotics | Control Systems

Full Legal Name: [Olalekan Ogunmolu](#).

CV: [Addendum](#).

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Publications

Recent preprints

Lekan Molu, Generative Modeling of Continuous-time Continuous-States Diffusion Processes. Submitted to *International Conference on Learning Representations*, Rio de Janeiro, 2026.

Promise Ekpo, El Claver Methvin, **Lekan Molu**, and Angelique Taylor. When Should Agents Share Fairly? The MARLHospital Environment and FairSkill Multiagent Reinforcement learning.

Lekan Molu, Abulikemu Abuduweili, Dean Fortier, Jun Takamatsu, Elise van der Pol, Naoki Wake, and Katsu Ikeuchi. [A Universal Model for Collision-free Planning: Efficient Illusory Representation and Memory Storage via Incremental Mapping](#).

Lekan Molu, Haoxiang You, and Ian Abraham. [Computing Reachable Sets via Nonconvex Optimization of Viscous Hamilton-Jacobi PDEs](#). 2025.

Lekan Molu, Namhoon Lee, and Venkatraman Renganathan. [Hopf-Lax Nonconvex Optimization of Reachable Sets on Non-viscous Hamilton-Jacobi PDEs](#). 2025.

Haoxiang You, **Lekan Molu**, and Ian Abraham. [Is the Bellman Equation Enough for Learning Control?](#) 2025.

Published and Recently accepted

Lekan Molu. [Fast Whole-Body Strain Regulation in Continuum Robots](#). *IEEE American Control Conference*, Denver, Co. July 2025.

Lekan Molu. [LevelSetPy: A GPU-Accelerated Package for Resolving Hyperbolic Hamilton-Jacobi Partial Differential Equations](#). *ACM Transactions on Mathematical Software*. March 2025.

Lekan Molu. [The Python LevelSet Toolbox \(LevelSetPy\)](#). *IEEE Conference on Decision and Control (CDC)*. Milan, Italy. December 2024.

Anurag Koul*, Shivakanth Sujit*, Shaoru Chen, Ben Evans, Lili Wu, Byron Xu, Rajan Chari, Yonathan Efroni, Miro Dudik, **Lekan Molu**, John Langford, Alex Lamb. [PCLAST: Discovering Plannable Latent States](#). *International Conference on Machine Learning (ICML)*, Vienna, Austria, July 2024.

Lekan Molu and Shaoru Chen. [Structural Properties and Control of Soft Robots Modeled as Discrete Cosserat Rods](#). *IEEE Conference on Decision and Control (CDC)*, Milan, Italy. December 2024.

Shaoru Chen, **Lekan Molu**, and Mahyar Fazlyab. [Verification-aided Learning Neural Network Barrier Functions with Termination Guarantees](#). *American Control Conference (ACC)*, 2023.

Alex Lamb, Riashat Islam, Yonathan Efroni, Aniket Didolkar, Dipendra Misra, Dylan Foster, **Lekan Molu**, Rajan Chari, Akshay Krishnamurthy, John Langford. [Guaranteed Discovery of Control-Endogenous Latent States with Multi-Step Inverse Models](#). *Transactions in Machine Learning Research*. February 2023.

Lekan Molu. [Mixed H2/H-Infinity Policy Learning Synthesis](#). *World Congress, International Federation of Automatic Control*, Yokohama, Japan. July 2023.

Tengyang Xie, Akanksha Saran, Dylan J Foster, **Lekan Molu**, Ida Momennejad, Nan Jiang, Paul Mineiro, and John Langford. [Interaction-Grounded Learning with Action-inclusive Feedback](#). *Neural Information Processing Systems (Neurips)*., New Orleans, La. May 2022.

Azar Sadeghnejad Barkousaraie, **Olalekan Ogunmolu**, Steve Jiang, and Dan Nguyen. [A Fast Deep Learning Approach for Beam Orientation Selection Using Supervised Learning with Column Generation on IMRT Prostate Cancer Patients](#). *The International Journal of Medical Physics Research and Practice*, 2020.

Olalekan Ogunmolu, Michael Folkerts, Dan Nguyen, Nicholas Gans, and Steve Jiang. [Deep BOO: Automating Beam Orientation Selection in Intensity Modulated Radiation Therapy](#). *Algorithmic Foundations of Robotics XIII, International Workshop (WAFR)*, Mérida, Mexico. December 2018.

Olalekan Ogunmolu, Xinmin Liu, Nicholas Gans, and Rodney Wiersma, [Mechanism and Model of a Soft Robot for Head Stabilization in Cancer Radiation Therapy](#). *IEEE International Conference on Robotics and Automation (ICRA 2020)*, 2020.

Azar Sadeghnejad Barkousaraie, **Olalekan Ogunmolu**, Steve Jiang, and Dan Nguyen. [Using Supervised Learning and Guided Monte Carlo Tree Search for Beam Orientation Optimization in Radiation Therapy](#). Appeared in *Artificial Intelligence in Radiation Therapy (AIRT). Lecture Notes in Computer Science, vol 11850. Springer Cham*, Presented at *International Conference on Medical Image Computing and Computer Assisted Intervention, XXII (MICCAI)*, Shenzhen, China. 2019.

Olalekan Ogunmolu, and Rodney Wiersma. [A Real-Time Patient Head Motion Correction Mechanism for MRI-Linac Systems](#). (*AAPM/COMP Meeting*). July 2020.

Olalekan Ogunmolu, Xinmin Liu, and Rodney Wiersma. [Paths Replanning for Head and Neck Motion Correction in Robotic Stereotactic Radiosurgery](#). *AAPM/COMP Meeting*. July 2020.

Olalekan Ogunmolu, [A Multi-DOF Soft Robot Mechanism for Patient Motion Correction and Beam Orientation Selection in Cancer Radiation Therapy](#). *PhD Thesis, University of Texas at Dallas, UT Southwestern Medical Center* 2019.

Olalekan Ogunmolu, Nicholas Gans, and Tyler Summers. [Minimax Iterative Dynamic Game: Application to Nonlinear Robot Control Tasks](#). *IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*, Madrid, Spain. October 2018. DOI: 10.1109/IROS.2018.8594037.

Olalekan Ogunmolu, Adwait Kulkarni, Yonas Tadesse, Xuejun Gu, Steve Jiang, and Nick Gans. [Soft-NeuroAdapt: A 3-DOF Neuro-Adaptive Pose Correction System For Frameless and Maskless Cancer Radiotherapy](#). *IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*, Vancouver, BC, Canada. September 2017. DOI: 10.1109/IROS.2017.8206211.

Olalekan Ogunmolu, Xuejun Gu, Steve Jiang, and Nick Gans. [Vision-based control of a soft-robot for Maskless Cancer Radiotherapy](#). *IEEE Conference on Automation Science and Engineering (CASE)*, Fort-Worth, Texas, August 2016. DOI: 10.1109/CoASE.2016.7743378.

Olalekan Ogunmolu, Xuejun Gu, Steve Jiang, and Nick Gans. [A Real-Time Soft-Robotic Patient Positioning System for Maskless Head-and-Neck Cancer Radiotherapy](#). *IEEE Conference on Automation Science and Engineering (CASE)*, Gothenburg, Sweden, August 2015. DOI: 10.1109/CoASE.2015.7294318.

Olalekan Ogunmolu, Dan Nguyen, Xun Jia, Weiguo Lu, Nick Gans, and Steve Jiang. [Automating Beam Orientation Optimization for IMRT Treatment Planning: A Deep Reinforcement Learning Approach](#). *60th Annual Meeting of the American Association of Physicists in Medicine*, Nashville, TN (*AAPM*). July 2018.

Yara Almubarak, Joshi Aniket, **Olalekan Ogunmolu**, Xuejun Gu, Steve Jiang, Nicholas Gans, and Yonas Tadesse, [Design and Development of Soft Robots for Head and Neck Cancer Radiotherapy](#). *SPIE: Smart Structures + Nondestructive Evaluation*, Denver, CO, U.S.A. March 2018.

Technical Reports

Olalekan Ogunmolu, Nicholas Gans, and Tyler Summers. [Robust Zero-Sum Deep Reinforcement Learning](#). *arxiv PrePrints*, *arxiv ID:1710.00491*, Oct 2017.

Olalekan Ogunmolu, Xuejun Gu, Steve Jiang, and Nicholas Gans. [Nonlinear Systems Identification Using Deep Dynamic Neural Networks](#). *arxiv PrePrints*, *arxiv ID:1610.01439*, Oct 2016.

Abstracts

Olalekan Ogunmolu, Xinmin Liu, and Rodney Wiersma. [Paths Replanning for Head and Neck Motion Correction in Robotic Stereotactic Radiosurgery](#). Accepted to the *AAPM/COMP Meeting*. July 2020.

Azar Sadeghnejad Barkousaraie, **Olalekan Ogunmolu**, Steve Jiang, and Dan Nguyen. [A Fast Deep Learning Approach for Beam Orientation Selection Using Supervised Learning with Column Generation on IMRT Prostate Cancer Patients](#). *Medical Physics (AAPM)* 46 (6), E237-E237, San Antonio, TX, July 2019.

Olalekan Ogunmolu, Azar Sadeghnejad Barkousaraie, Nicholas Gans, Steve Jiang, and Dan Nguyen. [An Approximate Policy Iteration Scheme for Beam Orientation Selection in Radiation Therapy](#). *Medical Physics (AAPM)* 46 (6), E386-E386 San Antonio, TX, July 2019.

Azar Sadeghnejad Barkousaraie, **Olalekan Ogunmolu**, Steve Jiang, and Dan Nguyen. [A Reinforcement Learning Application of Guided Monte Carlo Tree Search Algorithm for Beam Orientation Selection in Radiation Therapy](#). *Medical Physics (AAPM)* 46 (6), E236-E236, San Antonio, TX, July 2019.

Olalekan Ogunmolu, Nicholas Gans, and Tyler Summers. [Minimax Iterative Dynamic Game: Application to Nonlinear Robot Control Tasks](#). *IEEE International Conference on Robotics and Automation. Machine Learning for Planning and Control Workshop Extended Abstract (ICRA 2018)*, Madrid, Spain. October 2018.

Olalekan Ogunmolu, Nicholas Gans, and Tyler Summers. [Minimax Iterative Dynamic Game: Application to Nonlinear Robot Control Tasks](#). *IEEE International Conference on Robotics and Automation, Late Breaking Result Abstract* Brisbane, Australia, May 2018.

Yara Almubarak, Joshi Aniket, **Olalekan Ogunmolu**, Xuejun Gu, Steve Jiang, Nicholas Gans, and Yonas Tadesse. [Design and Development of Soft Robots for Head and Neck Cancer Radiotherapy](#). *SPIE: Smart Structures + Nondestructive Evaluation*, Denver, CO, U.S.A. March 2018.

Tyler Summers, **Olalekan Ogunmolu**, and Nicholas Gans. [Robustness Margins and Robust Guided Policy Search for Deep Reinforcement Learning](#). *IROS 2017 Abstract Only Track*, Vancouver, BC, Canada. September 2017.

Olalekan Ogunmolu, Nick Gans, Steve Jiang, and Xuejun Gu. [An Image-Guided Soft Robotic Patient Positioning System for Maskless Head-And-Neck Cancer Radiotherapy: A Proof-of-Concept Study](#). *American Association of Physicists in Medicine (AAPM) Annual Meeting*, Anaheim, CA, USA. July 2015.

Invited Talks and Organized Workshops

Cornell Tech [Towards Safe Autonomous Systems: Between Bellman and Isaacs](#).
Cornell Tech, New York, New York. 2025.

Princeton [Numerical algorithms for verification in autonomous systems..](#)
University Princeton, New Jersey. 2025.

Microsoft [A Collision-Free Engine for Autonomous Systems](#).
Research Microsoft Research Annual TechFest (Project Green) Lead Workshop Organizer, Redmond,
(Global) Greater Seattle Area, 2025.

McGill [Emerging mathematical modeling and control tools for deformable robots and animated characters..](#)
University MILA and McGill University. Nov 2024.

- Microsoft Research (Global) [Towards structured representations in deep models and policies: symmetries, compactness, and vector homomorphisms.](#)
Microsoft Research Annual TechFest (Project Green) Lead Workshop Organizer, Redmond, Greater Seattle Area, 2024.
- Yale University [Mixed \$H_2/H_\infty\$ stochastic RL policy optimization analysis..](#)
Yale University, New Haven, Conn, USA. Nov 2023.
- Open Robotics [Soft-Robotic Position Correction Mechanisms in Intensity-Modulated Radiation Therapy.](#)
Open Robotics Foundation, Mountain View, CA, USA. January 2019.
- Stanford University [Robotic Radiotherapy: Automating Position Correction in Intensity-Modulated Radiation Therapy.](#)
Department of Energy Resources Engineering, **Stanford University**, Stanford, CA, USA. November 2018.
- UChicago [Robotic Radiotherapy: Automating Position Correction in Intensity-Modulated Radiation Therapy.](#)
Department of Radiation and Cellular Oncology, **The University of Chicago**, Chicago, IL, USA. November 2018.
- ATR CNS Labs [Minimax Iterative Dynamic Game.](#)
Department of Brain Robot Interface, **Computational Neuroscience Labs, ATR**, Osaka, Japan. August 2018.
- Preferred Networks [Neural Networks and Adaptive Control.](#)
Preferred Networks Tech. Talk, Chiyoda-ku, Tokyo. Japan. August 2018.
- Google [SoftNeuroAdapt: A 3-DoF Neuro-Adaptive Healthcare System.](#)
Work presented by Nick Gans, **Google Robotics**, Mountain View, CA. USA. September 2017.
- UTARI, Fort Worth, TX [A Wearable Soft Robotic Modular System for Head and Neck Motion Correction in Intensity-Modulated Radiation Therapy.](#)
University of Texas at Arlington Research Institute, Fort Worth, Texas, USA. May 2019.
- EFSC'17 Vancouver, BC [Soft Robotic Modules as Position Correcting Mechanisms in Cancer RT.](#)
3rd Entrepreneurship Forum & Start-up Competition, EFSC'17, Vancouver, BC, Canada. September 2017.
- UTSW, Dallas, TX [A 3-DOF Neuro-Adaptive Patient Pose Correcting System For Frameless and Maskless Cancer Radiotherapy.](#)
Physics Research Seminar Series, Radiation Oncology Department, UT Southwestern Medical Center, Dallas, TX, USA. March 2017.
- IEEE Arlington, TX [Towards automated accurate patient positioning in maskless cancer radiotherapy.](#)
IEEE Computational Intelligence Society, UT Arlington, TX, USA. December 2015.

Patents

Microsoft Patent Award. [Controllable Latent Space Discovery Using Multi-Step Inverse Model. 2022.](#) Alex Lamb, Riashat Islam, Yonathan Efroni, Aniket Didolkar, Dipendra Misra, Dylan Foster, **Olalekan Ogunmolu**, Rajan Chari, Akshay Krishnamurthy, John Langford.

Research Mentoring

Postdoctoral Scholars at MSR

- 2024 - 2025 Taylor Webb, Princeton Neuroscience PhD, UCLA and MSR Postdoc. Resuming as Assistant Professor at University de Montreal, 2025.
- 2023 - 2024 Shaoru Chen (UPenn ECE PhD co-advised by George Pappas); advised as MSR Postdoc. Now Senior Machine Learning Engineer at LinkedIn, 2024 - Present.
- 2023 - 2024 Anurag Koul (Oregon State PhD); advised as MSR Postdoc. Now Senior Applied Scientist II at Amazon NYC, 2024 - Present.

- 2022 - 2024 Akanksha Saran (UT Austin CS PhD); advised as MSR Postdoc. Now Research Scientist at Sony AI, Bay Area.
- 2022 - 2023 Hosein Hasanbeig (Oxford PhD advised by Alessandro Abate); advised as MSR postdoc. Now Senior Researcher at Microsoft Experiences+Devices Management, Washington D.C.

Research Interns at MSR

- Summer 2024 Abulikemu Abuduweili, CMU Robotics PhD Student. Incoming Research Scientist at Reliant Robotics, Bay Area.
- Summer 2022 Leilei Cui, NYU PhD Student. Now Postdoctoral scholar at Massachusetts Institute of Technology (MIT).
- Summer 2023 Harley Wiltzer, McGill PhD Student; advised by Marc Bellemare and David Meager.
- Summer 2023 Thomas C.K. Zhang, UPenn 5th-year PhD Student advised by Nikolai Matni.
- Summer 2023 Etiosa Omeike, Princeton CS BA, MSR undergraduate intern; now PhD student with Prof. Marynel Vázquez at Yale.

External PhD Students

- 2024 - Will Sharpless, UCSD Mechanical and Aerospace Engineering PhD Student; advised by Prof. Sylvia Herbert.
- 2023 - Gilbert Bahati, Caltech Mechanical Engineering PhD student, advised by Prof. Aaron Ames.
- 2024 - Haoxiang You, Yale Mechanical Engineering PhD Student; advised by Prof. Ian Abraham.
- 2025 - Promise Ekpo, Princeton Masters student; now PhD student at CornellTech Airlab (advised by Prof. Angelique Taylor).

General Engineering Mentoring

- 2017 - 2018 Adwait Kulkarn. UT Dallas Mechanical Engineering Masters student. Currently Vice President of Engineering at Drov Technologies, MN.
- 2017 - 2018 Ajith Venkateswaran. UT Dallas Computer Engineering Masters student. Senior Robotics Software Engineer, Samsung Research, America; Now Software Tech Lead Embedded Automotive Platforms, Wayve, Bay Area.
- 2017 - 2019 Rachael Thompson. Plano High School Student. Currently an undergrad at MIT's CSAIL. Class of 2021. Now PhD Student at Brown.

Select Leadership

Professional Organizations

- 2020 - NYAS, *The New York Academy of Sciences*, Member
- 2017 - IEEE RAS, *The IEEE Robotics and Automation Society*, Member
- 2017 - IEEE CSS, *The IEEE Control Systems Society*, Member
- 2020-2021 AAPM, *The American Association of Physicists in Medicine*, Junior Member, Member
- 2020-2021 ASTRO, *The American Society for Radiation Oncology*, Member

Research community leadership and activities

- 2017-Present **Journals and Conference Papers Reviewing Activities**, ASME, ICML, ICLR, IEEE ICRA, IROS, ACM, ACC, CDC, and IFAC publications are top journals and proceedings in the fields of Mechanical Engineering, Machine Learning, Electrical Engineering, Computing machinery, and Automatic Control Engineering respectively, known for disseminating bleeding-edge research and cutting-edge technological advancements in robotics, machine learning and control systems
- '20 ICLR, *The International Conference of Learning Representations*, A 1% publication avenue for cutting-edge research on all aspects of deep learning used in the fields of artificial intelligence, statistics and data science, as well as important application areas such as machine vision, computational biology, speech recognition, text understanding, gaming, and robotics
- '19 JBHI, *An IEEE Journal of Biomedical and Health Informatics Access*
- '19 External Grants Reviewer, AI for Species Discovery, *National Geographic Society*

- '18,'19 **Automatica**, *The International Federation of Automatic Control (IFAC)*
- '17, '18, '19 **Access**, *IEEE Access Journal*
- '17, '18, '19 **NCAA**, *Springer's Neural Computing and Applications*
- '17 - **ICML**, *International Conference on Machine Learning*
- '18 - **CDC**, *IEEE International Conference on Decision and Control*, Flagship Control and Decision-Making Control Conference Proceedings in the World
- 2017 - **DSCC**, *American Society of Mechanical Engineers (ASME) Dynamic Systems and Control Conference*, Conference Proceedings
- '17 - **ICRA**, *IEEE International Conference on Robotics and Automation*, Flagship IEEE Robotics and Automation Society Conference in the World
- '17 - **IROS**, *IEEE/Robotics Society of Japan (RSJ) International Conference on Intelligent Robots and Systems*, Flagship IEEE/RSJ Conference on Robotics
- '17 - **ACC**, *IEEE American Control Conference*, Premiere American Control Conference Venue
- '17 - **The IFAC World Congress**, *The International Federation of Automatic Control*, A worldwide, interdisciplinary congress of scientists and engineers to share up-to-date, complete and universal view of control and analysis techniques

Miscellaneous

- 2017 – Now **Member**, **IEEE Control Systems Society**
- 2017 – Now **Member**, **IEEE Robotics and Automation Society**
- 2016–Now **Member**, *IEEE Boston*, Greater Boston, USA
- 2015 – 2016 **Science instructor**, *IEEE Dallas Shoulder of Giants Workshops*, Dallas, TX
Participant at IEEE Dallas Young Professionals community outreaches in promoting STEM education and awareness in the Dallas/Fort-Worth Metroplex.
- 2015 **Summer Science Program**, *University of Texas at Dallas*, Richardson, TX
Trained high-school kids in basic robots control and programming with the Berkeley Snap! kit and arduino.
- 2012 **Workshop participant**, *ILA Berlin Airshow*, Berlin, Germany
Selected by Cassidian (an EADS company) for the *Aerospace Systems Engineering* workshop.
- 2012 **Workshop participant**, *Farnborough International Airshow*, NE Hampshire, England
Selected by Airbus (an EADS company) among participants at the *UAV and Fighter Aircraft* workshop.

Awards and honors

- 2011 PTDF Overseas Scholarship, £25,500+ for one year. (~1.7% acceptance).
- Oct. 2018 Google AI Travel and Conference Grant.
- August 2018 IEEE RAS/IROS 2018 Travel Award.
- August 2017 Finalist at the [3rd Entrepreneurship Forum and Startup Competition](#).
Sponsored by IEEE Robotics and Automation Society, KUKA AG, and Univ. Hamburg
- August 2017 [NSF Doctoral Consortium Award \(IROS 2017\)](#).
- August 2017 Mary and Richard Templeton Graduate Fellowship.
- July 2017 ROSCon Scholarship (Open Software for Robotics Foundation).
- Nom. Feb '17 President's Teaching Excellence Award.
- Dec. 2016 Golden Key International Honour Society.
- August 2016 IEEE RAS/ISAM Travel Award (CASE 2016).
- 2015 - 2016 Ericsson Graduate Fellowship.
- 2014 - 2015 Jonsson Scholarship.

Languages

English Reads, writes, and speaks fluently.

Lived in Nigeria, United Kingdom and United States.

References

Referees Professional and character referees available upon request.



Lekan Molu (lekanmolu)

SENIOR RESEARCHER (Reports to Akshay Krishnamurthy)

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^ Keep doing ... (6)

PERSPECTIVE

From : **Ogbemi Ekwejunor-Etchie** on Jun 02, 2025

Here's something I think you do really well and hope you keep doing:

As I've onboarded into MSR you've serviced as an open resource as I've navigated my new charter. You've been a great embodiment of the One Microsoft culture making sure self available to drive progress in my area. Please continue representing ONE Microsoft!

Here's a suggestion for how you could leverage this strength further:

No response

From : **Sergio Valcarcel Macua** on May 31, 2025

Here's something I think you do really well and hope you keep doing:

You did a fantastic job leading both proposals for our Project Green workshops. I really appreciated how you proactively brought in collaborators, energized the process, and ensured we met our deadlines. In the second proposal, where I was more involved, I especially valued your openness to different perspectives—even when they challenged your initial ideas. You also created space for others to take initiative and ownership, which fostered a collaborative environment where everyone could contribute, experiment, and iterate. That leadership helped make the workshop a real success

Here's a suggestion for how you could leverage this strength further:

Given the number of co-organizers involved, it was understandable that coordination was a bit challenging at the start. I really appreciate how you took ownership to submit the first version of the proposal by the deadline. With a bit more upfront planning, I think your leadership could shine even more—helping ensure smooth communication and clarity for everyone involved.

From : **Taylor Webb** on May 23, 2025

Here's something I think you do really well and hope you keep doing:

Lekan has been a very helpful mentor over the past year. He has made a significant effort to connect me with various people that are relevant to my research, and in particular to help me make connections in the Montreal ML research community that will be very helpful in my new role at Mila. I have also enjoyed our discussions over the past year and have appreciated hearing Lekan's perspective on research at MSR and the future of ML/robotics.

Here's a suggestion for how you could leverage this strength further:

No response

^ View more ()

^ Re-think ... (6)

PERSPECTIVE

From : **Ogbemi Ekwejunor-Etchie** on Jun 02, 2025

Here's something you may want to re-think:

No response

Here's an example to consider for doing it another way:

No response

From : **Sergio Valcarcel Macua** on May 31, 2025

Here's something you may want to re-think:

No response

Here's an example to consider for doing it another way:

No response

From : **Taylor Webb** on May 23, 2025

Here's something you may want to re-think:

No response

Here's an example to consider for doing it another way:

No response

View more ()

^ Additional thoughts ... (6)

PERSPECTIVE


From : **Ogbemi Ekwejunor-Etchie** on Jun 02, 2025

The thing I most value about working with you is:

No response

Here are some other thoughts I have that you may want to consider:

No response

 Say thanks to Ogbemi Ekwejunor-Etchie ([https://teams.microsoft.com/l/entity/57e078b5-6c0e-44a1-a83f-45f75b030d4a/MyAssist?context={\"subEntityId\":\"\\\\\"PageUrl\\\\\"/Perso](https://teams.microsoft.com/l/entity/57e078b5-6c0e-44a1-a83f-45f75b030d4a/MyAssist?context={\)


From : **Sergio Valcarcel Macua** on May 31, 2025

The thing I most value about working with you is:

You bring a lot of energy and openness to your interactions, and your willingness to engage in dialogue really helps move things forward.

Here are some other thoughts I have that you may want to consider:

No response

 Say thanks to Sergio Valcarcel Macua ([https://teams.microsoft.com/l/entity/57e078b5-6c0e-44a1-a83f-45f75b030d4a/MyAssist?context={\"subEntityId\":\"\\\\\"PageUrl\\\\\"/Persona](https://teams.microsoft.com/l/entity/57e078b5-6c0e-44a1-a83f-45f75b030d4a/MyAssist?context={\)

PERSPECTIVE


From : **Taylor Webb** on **May 23, 2025**

The thing I most value about working with you is:

No response

Here are some other thoughts I have that you may want to consider:

No response

 Say thanks to Taylor Webb ([https://teams.microsoft.com/l/entity/57e078b5-6c0e-44a1-a83f-45f75b030d4a/MyAssist?context={\"subEntityId\":\"\\\\\"PageUrl\\\\\"/PersonalApp/Hom](https://teams.microsoft.com/l/entity/57e078b5-6c0e-44a1-a83f-45f75b030d4a/MyAssist?context={\)

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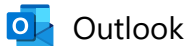
Learning

Career Resources (<https://aka.ms/career>)
Disability Inclusion Hub (<https://microsoft.sharepoint.com/teams/DisabilityInclusionPlaybook>)
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Connects

About Performance (<https://aka.ms/PDPhilosophy>)
Sample Connects (<https://microsoft.sharepoint.com/sites/HRweb/SitePages/sampleconnects.aspx>)





Outlook

Thank you for participating in the ASME ATS/ES TC Networking Sessions

From Block, Brian <block.168@buckeyemail.osu.edu>

Date Mon 7/14/2025 2:54 PM

To Shobhit Gupta <shobhit.2.gupta@gm.com>; Ruiting Wang <rtwang@berkeley.edu>; Jackson Fogelquist <jbfogelquist@ucdavis.edu>

Hi all,

I hope you all had a nice time in Denver at ACC! I would like to extend our thanks for being a part of our student networking special session. Much of the success of this event is due to all of your participation, and it would not be possible without you. Talking to some of the students afterwards, they seemed to really enjoy the session and found it helpful, so hopefully you all did as well.

This is the second time our technical committees have worked together on an event of this kind, and we hope to hold more of these sessions at future conferences. If you have any comments on what went well or what we could improve on, please let us know, we would really value your feedback.

On behalf of the ASME Automotive and Transportation Systems Technical Committee and the ASME Energy Systems Technical Committee, thank you once again!

ASME ATS TC

Brian Block, Dr. Shobhit Gupta

ASME ESTC

Jackson Fogelquist, Ruiting Wang



THE OHIO STATE UNIVERSITY

Brian Block

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PhD Candidate | Center for Automotive Research (CAR)

Visiting Scholar | DIBRIS, University of Genova

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