

Instructions for generating plots shown in paper, “The ‘ABC-DA’ system (v1.4): a variational data assimilation system for convective scale research with a study of the impact of a balance constraint”

January 17, 2020

Further guidance on downloading, compiling, and running the software is available in the documentation on github (DOI: 10.5281/zenodo.3531926). The mentioned document also shows how the python plotting code is accessed.

1 Figure 1

This is a schema, and so doesn’t require production of any results.

2 Figure 2

1. This requires the control variable transform (CVT) to first be calibrated. Make directory to contain *CVT.nc* file (call *Master_Calibration*), and enter this directory.
2. Make directory inside *Master_Calibration* (call *Master_Calibration_stage1*) and enter this directory.
3. Generate ensemble to be used for calibrating the CVT from given UM file (*Member001.nc* inside directory */home/data/UMdir* in this example). Run *Master_Calibration.out* with the following namelist file present (*UserOptions.nl*). See documentation, §4.4.1.

```
&UserOptions
! Reading and processing UM data
! -----
A              = 0.02 ,
B              = 0.01 ,
C              = 1.0E4 ,
dt             = 4.0 ,
Adv_tracer     = .TRUE. ,
runlength     = 3600.0 ,
CalibRunStage  = 1 ,
NEns           = 1 ,
EnsDirs(1)    = '/home/data/UMdir' ,
NEnsMems       = 1 ,
NNMC          = 0 ,
Nlats          = 260 ,
latindex(1)   = 11 ,
latindex(2)   = 12 ,
latindex(3)   = 13 ,
latindex(4)   = 14 ,
latindex(5)   = 15 ,
latindex(6)   = 16 ,
latindex(7)   = 17 ,
latindex(8)   = 18 ,
latindex(9)   = 19 ,
latindex(10)  = 20 ,
latindex(11)  = 21 ,
```

latindex (12)	= 22,
latindex (13)	= 23,
latindex (14)	= 24,
latindex (15)	= 25,
latindex (16)	= 26,
latindex (17)	= 27,
latindex (18)	= 28,
latindex (19)	= 29,
latindex (20)	= 30,
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latindex(143)	= 153,
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latindex(148)	= 158,
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latindex(150)	= 160,
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latindex(251)	= 261,
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latindex(253)	= 263,
latindex(254)	= 264,
latindex(255)	= 265,

```

latindex(256)      = 266,
latindex(257)      = 267,
latindex(258)      = 268,
latindex(259)      = 269,
latindex(260)      = 270,
BoundSpread        = 100,
datadirABCfcs       = '.',
datadirCVT          = '..',
CVT_file            = 'CVT.nc',
CVT%CVT_order       = 1,
CVT%CVT_param_opt_gb = 1,
CVT%CVT_param_opt_hb = 1,
CVT%CVT_param_opt_ab = 2,
CVT%CVT_param_opt_reg = 1,
CVT%CVT_vert_opt_sym = 1,
CVT%CVT_stddev_opt  = 2
/

```

4. Make directory inside *Master_Calibration* (call *Master_Calibration_stage2*) and enter this directory.
5. Generate ensemble mean state, and perturbations from this ensemble. Run *Master_Calibration.out* with the following namelist file present (*UserOptions.nl*). See documentation, §4.4.2.

```

&UserOptions
! Generating ensemble perturbations from ensemble forecasts
! _____
CalibRunStage      = 2,
NEns                = 1,
NEnsMems           = 1,
NNMC               = 0,
Nlats              = 260,
datadirABCfcs       = '../Master_Calibration_stage1',
datadirABCperts     = '.',
datadirCVT          = '..',
CVT_file            = 'CVT.nc'
/

```

6. Make directory inside *Master_Calibration* (call *Master_Calibration_stage3*) and enter this directory.
7. Generate vertical regression matrix. Run *Master_Calibration.out* with the following namelist file present (*UserOptions.nl*). See documentation, §4.4.3.

```

&UserOptions
! Generate vertical regression matrix
! _____
CalibRunStage      = 3,
NEns                = 1,
NEnsMems           = 1,
NNMC               = 0,
Nlats              = 260,
datadirRegression   = '.',
datadirABCperts     = '../Master_Calibration_stage2',
datadirCVT          = '..',
CVT_file            = 'CVT.nc'
/

```

8. To plot figure 2(c), edit the python program *PlotRegressionMatrices.py* to set *datadirCVT* to *Master_Calibration*, and run the python program.
9. Make directory inside *Master_Calibration* (call *Master_Calibration_stage4*) and enter this directory.

10. Generate ensemble perturbations in terms of parameters. Run *Master_Calibration.out* with the following namelist file present (*UserOptions.nl*). See documentation, §4.4.4.

```
&UserOptions
! Generate parameter perturbations
! _____
CalibRunStage      = 4,
NEns               = 1,
NEnsMems           = 1,
NNMC               = 0,
Nlats              = 260,
datadirABCperts    = '../Master_Calibration_stage2',
datadirConParams   = '..',
datadirCVT         = '..',
CVT_file           = 'CVT.nc',
/
```

11. To plot Figs. 2(a,b,d), edit the python program *Plot_rp_pre+post_regress.py* to set *data_dir_stage2* to *Master_Calibration/Master_Calibration_stage2* and *data_dir_stage4* to *Master_Calibration/Master_Calibration_stage4* and run the python program.

3 Figure 3

1. Make directory inside *Master_Calibration* (call *Master_Calibration_stage5*) and enter this directory.
2. Generate spatial transform data (the remaining part of the calibration step). Run *Master_Calibration.out* with the following namelist file present (*UserOptions.nl*). See documentation, §4.4.5.

```
&UserOptions
! Calibrate spatial transforms
! _____
CalibRunStage      = 5,
NEns               = 1,
NEnsMems           = 1,
NNMC               = 0,
Nlats              = 260,
datadirABCperts    = '../Master_Calibration_stage2',
datadirConParams   = '../Master_Calibration_stage4',
datadirCVT         = '..',
CVT_file           = 'CVT.nc',
/
```

3. Edit the python program *PlotCVT.py* to set *data_dir_CVT* to *Master_Calibration*, and run the python program.
4. This can be repeated for different experiment configurations to get the different lines in panel (c) of the paper.

4 Figure 4

1. This is also output from *PlotCVT.py* as run for Fig. 3.
2. This can be repeated for different experiment configurations to get the different lines in panel (c) of the paper.

5 Figure 5

1. This is also output from *PlotCVT.py* as run for Fig. 3.

6 Figure 6

1. This plot requires the same data as used for Fig. 5, plus knowledge of the gravity wave speeds (found from a linear analysis). Run a linear analysis of the model by first creating a directory *Master_Linear_Analysis* (in the same place as directory *Master_Calibration*) and enter this directory. Run *Master_Linear_Analysis.out* with the following namelist file present (*UserOptions.nl*). See documentation, §4.3.

```
&UserOptions
! Linear analysis of ABC model equations
! -----
  datadirLinearAnal ,      = '.',
  A                      = 0.02
  B                      = 0.01
  C                      = 1.0E4
/
```

2. Compile the c++ program *RossbyRadius.cpp* (contained in the same directory as the python plotting code, note the libraries that are required):

```
g++ -I/usr/include RossbyRadius.cpp -o RossbyRadius.out -L/usr/lib -lnetcdf_c++ -lnetcdf
```

3. Run this code as follows from the command line inside directory *Master_Linear_Analysis*:

```
./RossbyRadius.out ../Master_Calibration .
```

4. To plot Fig. 6, edit the python program *Plot_horizvars_unbalrho+Rossby.py* to set *CVT_file* to *Master_Calibration* and *lengths_file* to *Master_Linear_Analysis/VerticalModeCharacteristics.dat* and run the python program.

7 Figure 7

1. Make a directory *Master_ImpliedCovs* (in the same place as directory *Master_Calibration*) and enter this directory. Run *Master_ImpliedCov.out* with the following namelist file present (*UserOptions.nl*). See documentation, §4.6.

```
&UserOptions
! Compute implied covariances
! -----
  datadirImpliedCov      = '.',
  datadirCVT             = '../Master_Calibration',
  CVT_file               = 'CVT.nc',
  datadirABCfcs          = '../Master_Calibration/Master_Calibration_stage1',
  LS_file                = 'FC_Ens001_Item001.nc',
  ImplCov_npoints        = 1
  longindex(1)           = 180
  levindex(1)            = 25
/
```

2. To plot panels (a), (b), and (c) of Fig. 7, edit the python program *Plot_Covs.py* to set *plot_raw_covs* to *False*, *plot_implied_covs* to *True*, *data_dir_ImpliedCovs* to *Master_ImpliedCovs*, *longindex* to [179], and *levindex* = [24], and run the python program. Note that the *longindex* and *levindex* are *longindex*(1)-1 and *levindex*(1)-1 respectively.
3. This can be repeated for different experiment configurations to get the rows 2 and 3 of Fig. 7 in the paper.
4. Make directory *Master_RawCov* (in the same place as directory *Master_Calibration*) and enter this directory. Run *Master_RawCov.out* with the following namelist file present (*UserOptions.nl*). See documentation, §4.7.


```

&UserOptions
! Compute raw covariances
! -----
datadirRawCov          = '.'
datadirABCPerts        = '../Master_Calibration/Master_Calibration_stage2'
Nens                   = 1
NensMems               = 1
Nlats                  = 260
ImplCov_npoints        = 1
longindex(1)           = 180
levindex(1)            = 25
/

```

5. To plot panels (j), (k), and (l) of Fig. 7, edit the python program *Plot_Covs.py* to set *plot_raw_covs* to *True*, *plot_implied_covs* to *False*, *data_dir_RawCovs* to *Master_RawCovs*, *Nens* to 1, *NensMems* to 260, *longindex* to [179], and *levindex* = [24], and run the python program. Note that the *longindex* and *levindex* are *longindex*(1)-1 and *levindex*(1)-1 respectively.

8 Figure 8

This is a schema, and so doesn't require production of any results.

9 Figure 9

1. Make an ABC-style initial state (in order to generate synthetic observations and to measure errors from). Make a directory *Master_PrepareABC_InitState* (in the same place as directory *Master_Calibration*) and enter this directory.
2. Run *Master_PrepareABC_InitState.out* with the following namelist file present (*UserOptions.nl*). See documentation, §4.1.

```

&UserOptions
! Master_PrepareABC_InitState
! -----
Init_ABC_opt          = 3
datadirUM             = '/home/data/UMdir'
init_um_file          = 'Member0001.nc'
datadirABC_out        = '.'
init_ABC_file         = 'ABC_InitialConds.nc'
latitude              = 102
Regular_vert_grid     = .TRUE.
Adv_tracer            = .TRUE.
gravity_wave_switch   = .FALSE.
f                    = 1.0E-4
A                    = 0.02
B                    = 0.01
C                    = 1.0E4
BoundSpread          = 100.
press_source_x        = 200
press_source_z        = 6
press_amp             = 0.005
x_scale              = 120
z_scale              = 14
/

```

3. Make a short forecast from this initial state to spin-up characteristics of the ABC model. Make a directory *Master_RunNLModel* (in the same place as directory *Master_Calibration*) and enter this directory.

4. Run *Master_RunNLModel.out* with the following namelist file present (*UserOptions.nl*). See documentation, §4.2.

```
&UserOptions
! Running ABC model
! -----
datadirABC_in           = '.. / Master_PrepABC_InitState'
init_ABC_file           = 'ABC_InitialConds.nc'
datadirABC_out          = '.'
output_ABC_file         = 'Truth.nc'
diagnostics_file        = 'ABC_Diagnostics.dat'
runlength               = 7200.0
ndumps                  = 9
dt                      = 4.0
Lengthscale_diagnostics = .FALSE.
A                       = 0.02
B                       = 0.01
C                       = 1.0E4
Adv_tracer              = .TRUE.
/
```

5. Specify the observation network. Make directory *Master_MakeBgObs_ObsNetwork* (in the same place as directory *Master_Calibration*) and enter this directory.
6. Run *Master_MakeBgObs.out* with the following namelist file present (*UserOptions.nl*). See documentation, §4.8.

```
&UserOptions
! Specification of observation network
! -----
Generate_mode           = 1
ObsSpec%year0           = 2010
ObsSpec%month0          = 1
ObsSpec%day0            = 1
ObsSpec%hour0           = 0
ObsSpec%min0            = 0
ObsSpec%sec0            = 0
ObsSpec%NumBatches      = 7
datadir_ObsSpec         = '.'
ObsSpec_file            = 'ObsSpec.dat'
! -----
ObsSpec%batch(1)        = 1
ObsSpec%seconds(1)      = 0
ObsSpec%ob_of_what(1)   = 4           ! rp
ObsSpec%NumObs_long(1)  = 18
ObsSpec%NumObs_height(1) = 20
ObsSpec%long_min(1)     = 10.0
ObsSpec%long_max(1)     = 530000.0
ObsSpec%height_min(1)   = 1.0
ObsSpec%height_max(1)   = 12000.0
ObsSpec%stddev(1)       = 0.0015
! -----
ObsSpec%batch(2)        = 2
ObsSpec%seconds(2)      = 600
ObsSpec%ob_of_what(2)   = 4           ! rp
ObsSpec%NumObs_long(2)  = 18
ObsSpec%NumObs_height(2) = 20
ObsSpec%long_min(2)     = 10.0
ObsSpec%long_max(2)     = 530000.0
ObsSpec%height_min(2)   = 1.0
```

```

ObsSpec%height_max(2)      = 12000.0
ObsSpec%stddev(2)          = 0.0015
!
ObsSpec%batch(3)           = 3
ObsSpec%seconds(3)         = 1200
ObsSpec%ob_of_what(3)      = 4          ! rp
ObsSpec%NumObs_long(3)     = 18
ObsSpec%NumObs_height(3)   = 20
ObsSpec%long_min(3)        = 10.0
ObsSpec%long_max(3)        = 530000.0
ObsSpec%height_min(3)      = 1.0
ObsSpec%height_max(3)      = 12000.0
ObsSpec%stddev(3)          = 0.0015
!
ObsSpec%batch(4)           = 4
ObsSpec%seconds(4)         = 1800
ObsSpec%ob_of_what(4)      = 4          ! rp
ObsSpec%NumObs_long(4)     = 18
ObsSpec%NumObs_height(4)   = 20
ObsSpec%long_min(4)        = 10.0
ObsSpec%long_max(4)        = 530000.0
ObsSpec%height_min(4)      = 1.0
ObsSpec%height_max(4)      = 12000.0
ObsSpec%stddev(4)          = 0.0015
!
ObsSpec%batch(5)           = 5
ObsSpec%seconds(5)         = 2400
ObsSpec%ob_of_what(5)      = 4          ! rp
ObsSpec%NumObs_long(5)     = 18
ObsSpec%NumObs_height(5)   = 20
ObsSpec%long_min(5)        = 10.0
ObsSpec%long_max(5)        = 530000.0
ObsSpec%height_min(5)      = 1.0
ObsSpec%height_max(5)      = 12000.0
ObsSpec%stddev(5)          = 0.0015
!
ObsSpec%batch(6)           = 6
ObsSpec%seconds(6)         = 3000
ObsSpec%ob_of_what(6)      = 4          ! rp
ObsSpec%NumObs_long(6)     = 18
ObsSpec%NumObs_height(6)   = 20
ObsSpec%long_min(6)        = 10.0
ObsSpec%long_max(6)        = 530000.0
ObsSpec%height_min(6)      = 1.0
ObsSpec%height_max(6)      = 12000.0
ObsSpec%stddev(6)          = 0.0015
!
ObsSpec%batch(7)           = 7
ObsSpec%seconds(7)         = 3600
ObsSpec%ob_of_what(7)      = 4          ! rp
ObsSpec%NumObs_long(7)     = 18
ObsSpec%NumObs_height(7)   = 20
ObsSpec%long_min(7)        = 10.0
ObsSpec%long_max(7)        = 530000.0
ObsSpec%height_min(7)      = 1.0
ObsSpec%height_max(7)      = 12000.0
ObsSpec%stddev(7)          = 0.0015
/

```

7. Now run the cycled data assimilation. Make directory *CycledDA_obs_rp* (in the same place as directory *Master_Calibration*) and enter this directory.

8. Copy the bash script *DACycle001.sh* to this directory and set *EXPERIMENT* to *CycledDA_obs_rp*, *BASE_DIR* to the full path to the parent of this directory appended with */\$EXPERIMENT*, *N_CYCLES* to 30, *N_OUTER_LOOPS* to 1, *N_INNER_LOOPS_MAX* to 100, *DA_WINDOW* to 3600.0, *DA_WINDOW_INT* to 3600, *OBS_NETWORK_DIR* to *\$BASE_DIR/../../Master_MakeBgObs_ObsNetwork*, *INITIAL_TRUTH_DIR* to *\$BASE_DIR/Master_RunNLModel*, *CVT_DIR* to *\$BASE_DIR/../../MasterCalibration*, *CODE_DIR* to the directory containing the main fortran code, *PLOT_CODE_DIR* to the directory containing the python plotting code, *BACKGROUND_ALREADY_COMPUTED* to 0, *A* to 0.02, *B* to 0.01, *C* to 1.0E4, and *PLOT* to 1.
9. Run the back script *DACycle001.sh*.
10. The cost function diagnostics of Fig. 9 should appear inside *\$BASE_DIR/CycledDA_obs_rp/da_cycle_0007/Plots*.

10 Figure 10

The panels of Fig. 10 should also appear inside *\$BASE_DIR/CycledDA_obs_rp/da_cycle_0007/Plots*. as per instructions for Fig. 9.

11 Figure 11

Much of the data shown in Fig. 11 should appear inside *\$BASE_DIR/CycledDA_obs_rp/Plots* as per instructions for Fig. 9. The specific panels of Fig. 11 are made by editing *PlotMultiCycleErrors4paper.py*.

12 Figures 12 and 13

The above steps can be repeated for different options – in particular *CVT%CVT_param_opt_gb* can be set to 3 to turn-off the geostrophic balance constraint in the CVT, and *CVT%CVT_param_opt_reg* can be set to 2 to turn-off the vertical regression step that accompanies the geostrophic balance.