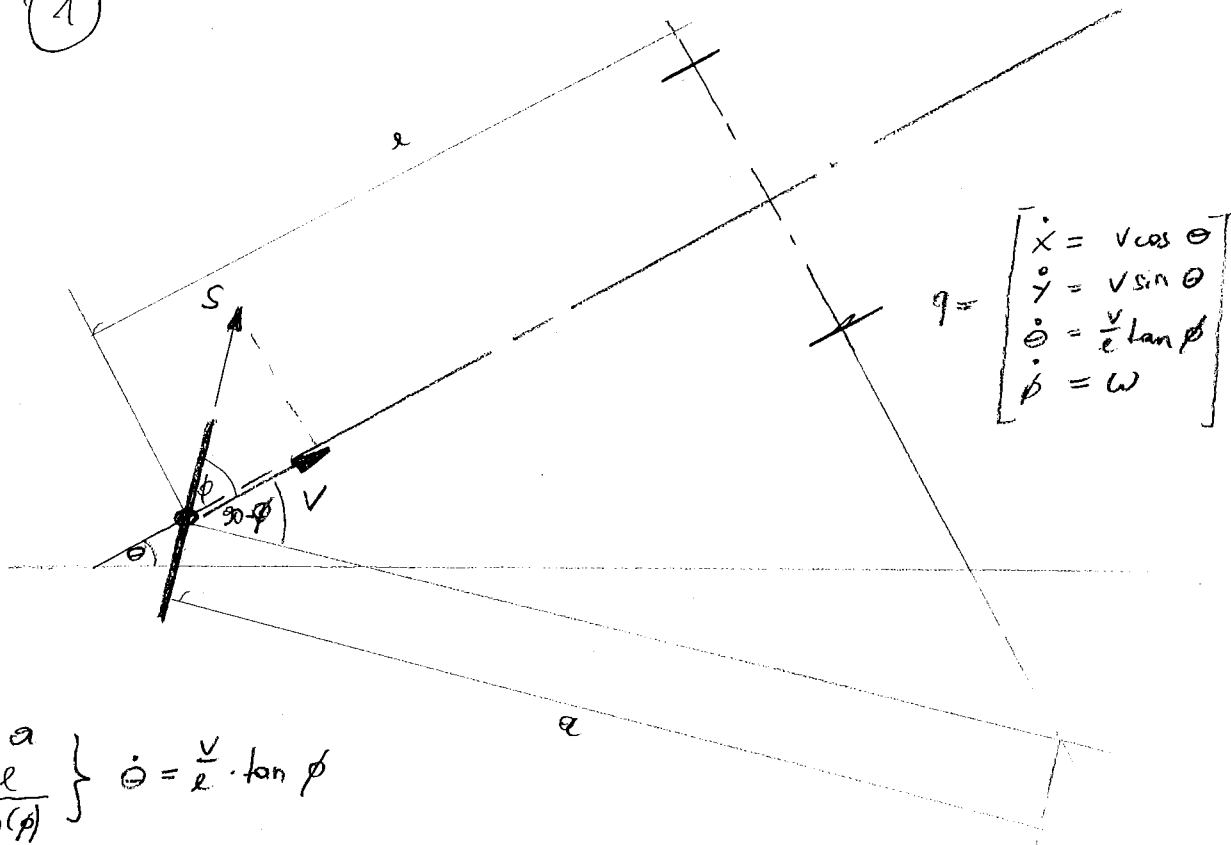


(1)

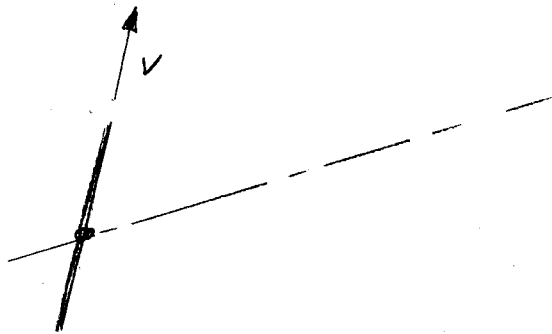


$$q = \begin{bmatrix} \dot{x} = v \cos \theta \\ \dot{y} = v \sin \theta \\ \dot{\theta} = \frac{v}{l} \tan \phi \\ \dot{\phi} = \omega \end{bmatrix}$$

$$\left. \begin{aligned} s &= \dot{\theta} \cdot a \\ a &= \frac{l}{\sin(\phi)} \end{aligned} \right\} \dot{\theta} = \frac{v}{l} \cdot \tan \phi$$

$\hookrightarrow \cos(90 - \phi) = \frac{l}{a}$

(2)



$$q = \begin{bmatrix} \dot{x} = v \cos \phi \cos \theta \\ \dot{y} = v \cos \phi \sin \theta \\ \dot{\theta} = \frac{v}{l} \sin \phi \\ \dot{\phi} = \omega \end{bmatrix}$$