

```

from __future__ import print_function
import numpy as np
import copy
import Queue
from pylab import *
import time
from PIL import Image
from scipy.misc import imread, imresize, imsave

```

```

# a = [[[[] for i in range(6)] for j in range(6)] for k in range(6)]
INF = 100000000.0
eps = 0.000001
dx = [1, 0, -1, 0, 1, 1, -1, -1]
dy = [0, 1, 0, -1, -1, 1, 1, -1]
edge = [1.0, 1.0, 1.0, 1.0, np.sqrt(2.0), np.sqrt(2.0), np.sqrt(2.0), np.sqrt(2.0)]

```

```

unit = 10
limit = 1 * unit
def dcmp(x):
    if np.fabs(x) < eps:
        return 0
    if x > 0:
        return 1
    return -1

```

```

class spfa():
    def __init__(self, _mp, _n, _m, _s_x, _s_y, _e_x, _e_y):
        self.mp = _mp
        self.n = _n
        self.m = _m
        self.checkmp = np.zeros((self.n, self.m))
        self.s_x = int(_s_x * unit)
        self.s_y = int(_s_y * unit)
        self.e_x = int(_e_x * unit)
        self.e_y = int(_e_y * unit)
        self.dist = np.zeros((self.n, self.m))
        self.inq = np.zeros((self.n, self.m), dtype=int32)
        self.fax = np.zeros((self.n, self.m), dtype=int32)
        self.fay = np.zeros((self.n, self.m), dtype=int32)
        self.q = Queue.Queue(maxsize = self.n * self.m)
        self.ans = []
        for i in range(self.n):
            for j in range(self.m):
                if self.mp[i][j] == 1:

```

已经放进去了，只是
放进去去了，是最优
（每个格子相等）

取样本还是原地图
取最短路的散
的地图

基于此的
spfa
取最短
路

```

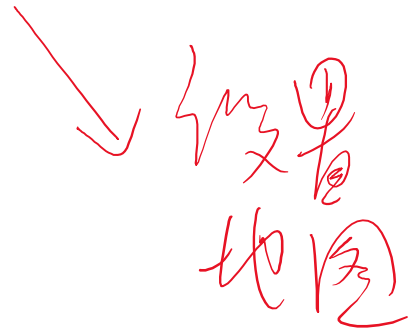
        for kx in range(int(-0.3*unit), int(0.3*unit)):
            for ky in range(int(-0.3*unit), int(0.3*unit)):
                if i+kx >= 0 and i+kx < self.n and j+ky >= 0 and j + ky <
self.m:
                    self.checkmp[i + kx][j + ky] = 1

# x = np.random.random((self.n, self.m, 3))
# for i in range(self.n):
#     for j in range(self.m):
#         if self.mp[i][j] == 1:
#             print('111111')
#             x[i][j][0] = 1.0
#         else:
#             x[i][j][0] = 0.0
# plt.imshow(x)
# plt.show()
# self.showmp(self.mp)

# time.sleep(10000000)
for i in range(self.n):
    for j in range(self.m):
        self.dist[i][j] = INF
        if i == self.s_x and j == self.s_y:
            self.dist[i][j] = 0
            self.inq[i][j] = 1
            self.q.put([i, j])
def showmp(self, a):
    tmp = np.zeros((self.n, self.m))

    for i in range(self.n):
        for j in range(self.m):
            tmp[i][j] = a[self.n - 1 - i][j]
    plt.imshow(tmp)
    plt.show()
def check(self, x, y):
    if x >= 0 and x < self.n and y >= 0 and y < self.m:
        if self.mp[x][y] == 0 and self.checkmp[x][y] == 0:
            return True
        return False
    else:
        return False
def run(self):
    print('start')

```



```

tim = 0
while(self.q.empty() == False):
    tim += 1
    # print('now', str(tim))
    t = self.q.get()
    x = t[0]
    y = t[1]
    # print("??", x, y)
    self.inq[x][y] = 0
    for k in range(8):
        nx = x + dx[k]
        ny = y + dy[k]
        # print('????', x, y, nx, ny)
        # time.sleep(0.5)
        d = edge[k]
        if self.check(nx, ny) == False:
            continue
        if dcmp(self.dist[x][y] + d - self.dist[nx][ny]) < 0:
            self.dist[nx][ny] = self.dist[x][y] + d
            # print('1111', type(x), x, y, nx, ny, self.fax[nx][ny], self.fay[nx][ny])
            self.fax[nx][ny] = x
            self.fay[nx][ny] = y
            # print('ffffuck', type(x), x, y, nx, ny, self.fax[nx][ny], self.fay[nx][ny])
            # time.sleep(1)
            # if y < 0:
            #     # print('????????')
            if self.inq[nx][ny] == 0:
                self.inq[nx][ny] = 1
                self.q.put([nx, ny])

t_x = self.e_x
t_y = self.e_y

print("over")
print('start', self.dist[self.e_x][self.e_y], self.e_x, self.e_y, self.s_x, self.s_y,
self.fax[t_x][t_y], self.fay[t_x][t_y])
print('????')
while((t_x == self.s_x and t_y == self.s_y) == False):
    # print(t_x, t_y, self.dist[t_x][t_y])
    # time.sleep(1)
    self.ans.append([t_x, t_y])
    n_x = self.fax[t_x][t_y]
    n_y = self.fay[t_x][t_y]
    t_x = n_x
    t_y = n_y

```

→ 找最短
路

→ 记录路
径是什么

```

print('another over')

def getKey(self):
    if self.checkmp[self.s_x][self.s_y] == 1 or self.checkmp[self.e_x][self.e_y] == 1:
        return 1.0 * ((self.s_x - self.e_x) * (self.s_x - self.e_x) + (self.s_y - self.e_y) * (self.s_y
- self.e_y)) / unit, 1.0 * self.e_x / unit, 1.0 * self.e_y / unit

    self.run()
    # self.showPath()
    g_x = 1.0 * self.e_x / unit
    g_y = 1.0 * self.e_y / unit
    for i, var in enumerate(self.ans):
        t_x = var[0]
        t_y = var[1]
        if self.dist[t_x][t_y] <= limit:
            g_x = 1.0 * t_x / unit
            g_y = 1.0 * t_y / unit
            break
    return 1.0 * self.dist[self.e_x][self.e_y] / unit, g_x, g_y
def drawBigPoint(self, data, x, y, num):
    for k in range(8):
        nx = x + dx[k]
        ny = y + dy[k]
        if nx >= 0 and nx < self.n and ny >= 0 and ny < self.m:
            data[nx][ny] = num
def showPath(self):
    print('draw')
    data = np.zeros((self.n, self.m))
    for i in range(self.n):
        for j in range(self.m):
            data[i][j] = self.mp[i][j]
    self.drawBigPoint(data, self.s_x, self.s_y, 3)
    for i, var in enumerate(self.ans):
        t_x = var[0]
        t_y = var[1]
        self.drawBigPoint(data, t_x, t_y, 2)
    self.showmp(data)
    # plt.imshow(data)
    # plt.show()

if __name__ == '__main__':
    N = int(6.6 * unit + 10)
    M = int(9.9 * unit + 10)

```

找到下一个未访问的位置

```

mp = np.zeros((int(6.6 * unit + 10), int(9.9 * unit + 10)))
for i in range(int(4.5*unit),int( 6.60*unit + 1)):
    for j in range(int(0*unit),int( 1.90*unit + 1)):
        mp[i][j] = 1
for i in range(int(6.00*unit),int( 6.60*unit + 1)):
    for j in range(int(2.80*unit),int( 5.00*unit + 1)):
        mp[i][j] = 1
for i in range(int(2.30*unit),int( 3.70*unit + 1)):
    for j in range(int(3.15*unit),int( 3.45*unit + 1)):
        mp[i][j] = 1
for i in range(int(3.70*unit),int( 4.10*unit + 1)):
    for j in range(int(9.10*unit),int( 9.90*unit + 1)):
        mp[i][j] = 1
for i in range(int(1.60*unit),int( 3.40*unit + 1)):
    for j in range(int(8.50*unit),int( 9.90*unit + 1)):
        mp[i][j] = 1
for i in range(int(0*unit),int( 1.00*unit + 1)):
    for j in range(int(0*unit),int( 3.30*unit + 1)):
        mp[i][j] = 1
for i in range(int(0*unit),int( 1.00*unit + 1)):
    for j in range(int(4.40*unit),int( 5.80*unit + 1)):
        mp[i][j] = 1
for i in range(int(0*unit),int( 1.40*unit + 1)):
    for j in range(int(6.10*unit),int( 7.90*unit + 1)):
        mp[i][j] = 1
myspfa = spfa(mp, N, M, 3, 1.5, 3, 7)
myspfa.run()
myspfa.showPath()

```