

# Leapfrog Layers

A Trainable Framework for Effective Topological Sampling

**Sam Foreman\***, Xiao-Yong Jin, James C. Osborn

July, 2021

\*[foremans@anl.gov](mailto:foremans@anl.gov)

[arXiv:2105.03418](https://arxiv.org/abs/2105.03418)

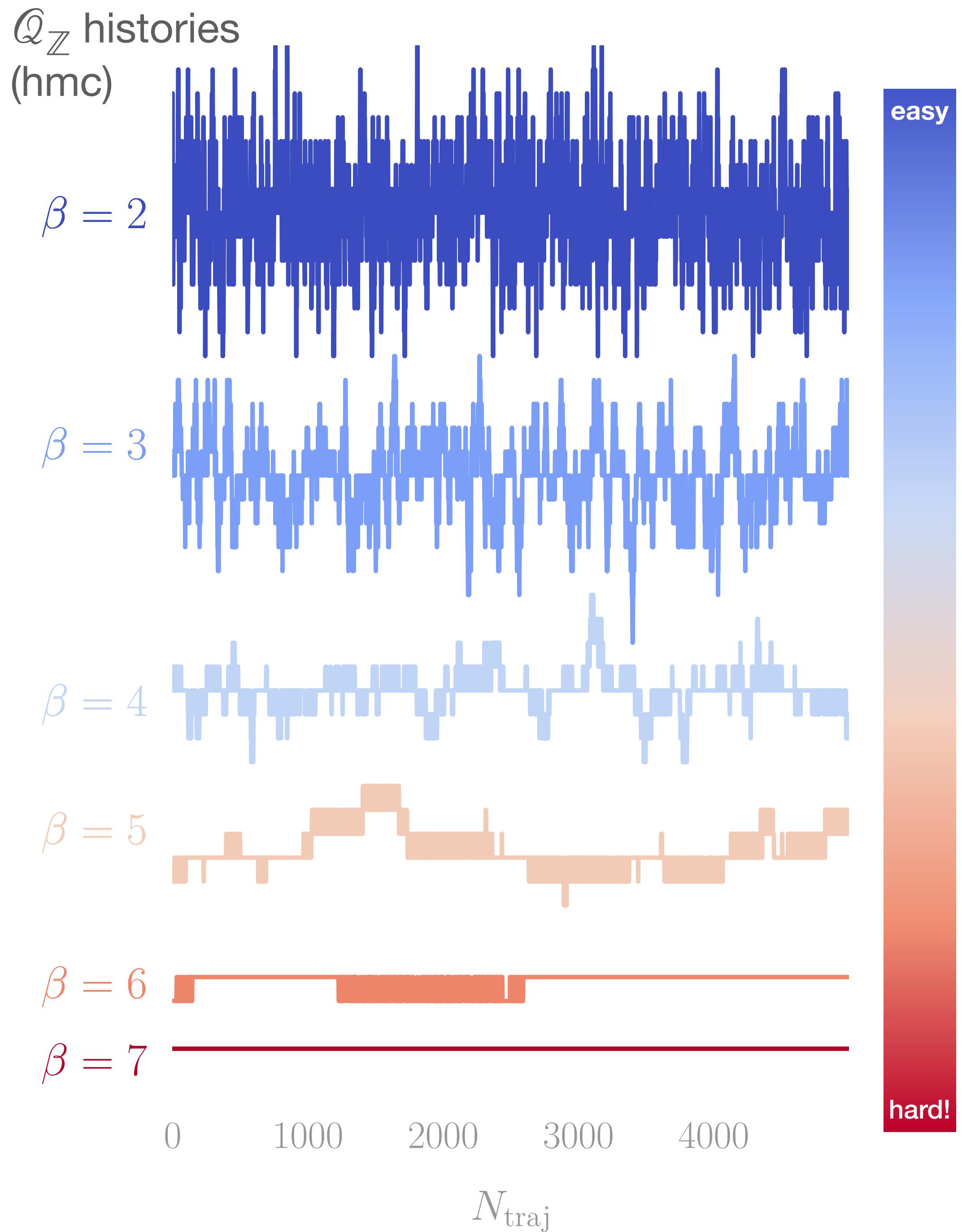
[bit.ly/12hmc-lattice21](https://bit.ly/12hmc-lattice21)

[bit.ly/12hmc-surprise](https://bit.ly/12hmc-surprise)

[github.com/saforem2/12hmc-qcd](https://github.com/saforem2/12hmc-qcd)

# Critical Slowing Down

- Goal: Draw *independent samples* from target distribution  $p(x)$ .
  - Generating independent gauge configurations is a *major bottleneck* for LatticeQCD.
- **Topological Freezing**
  - As we approach the continuum limit  $\beta \rightarrow \infty$ , the MCMC updates get stuck in sectors of fixed gauge topology.
    - Number of trajectories needed to adequately sample different topological sectors **increases exponentially**



# Hamiltonian Monte Carlo (HMC)

- Introduce  $v \sim \mathcal{N}(0, \mathbb{I})$ , then the target becomes:

$$p(x, v) = p(x) \cdot p(v) = e^{-Sx} \cdot e^{-v^T v / 2}$$

- Evolve the joint  $\xi \equiv (x, v)$  system using Hamilton's equations along  $H = \text{const}$ :

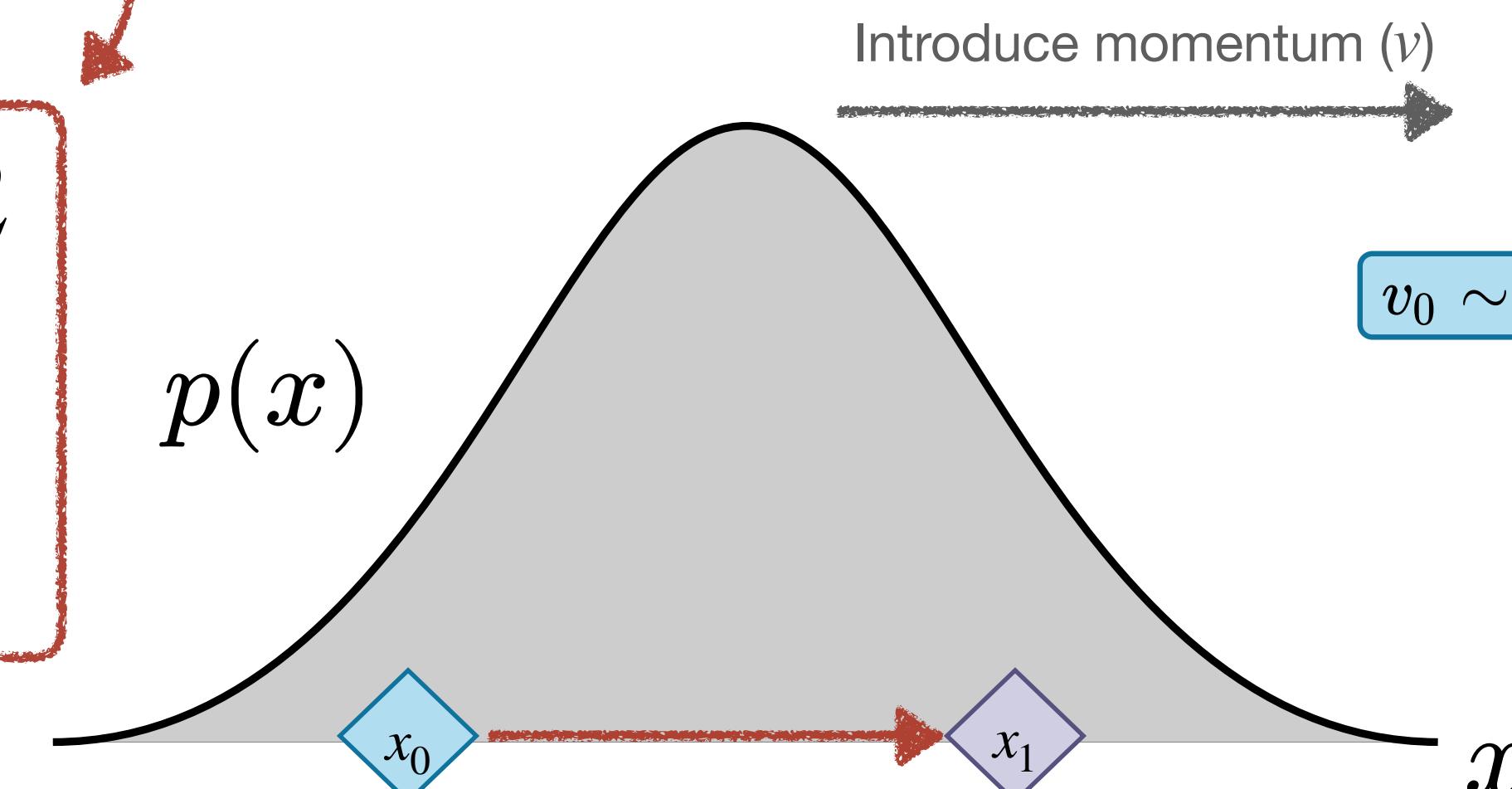
$$\dot{x} = \frac{\partial H}{\partial v}, \quad \dot{v} = -\frac{\partial H}{\partial x}$$

- Leapfrog Integrator:**

```

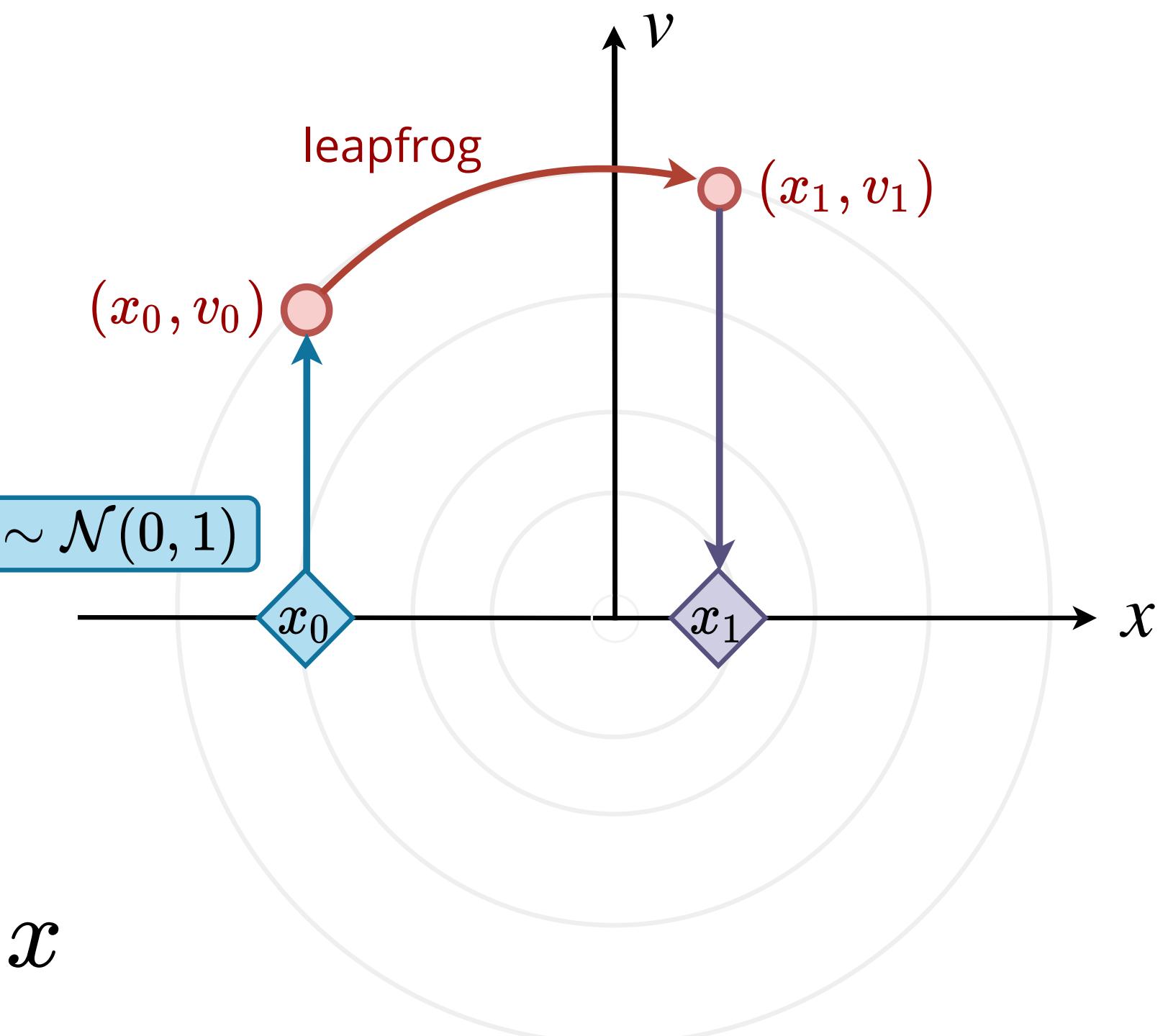
1.  $\tilde{v} \leftarrow v - \varepsilon \cdot \partial_x S(x) / 2$ 
2.  $x' \leftarrow x + \varepsilon \tilde{v}$ 
3.  $v' \leftarrow \tilde{v} - \varepsilon \partial_x S(x') / 2$ 

```



- Accept / reject proposal  $x'$  using MH:

$$x_{i+1} \leftarrow \begin{cases} x' & \text{w/prob. } A(\xi' | \xi) = \min \left\{ 1, \frac{p(\xi')}{p(\xi)} \left| \frac{\partial \xi'}{\partial \xi} \right| \right\}, \\ x_i & \text{w/prob. } 1 - A(\xi' | \xi) \end{cases}$$

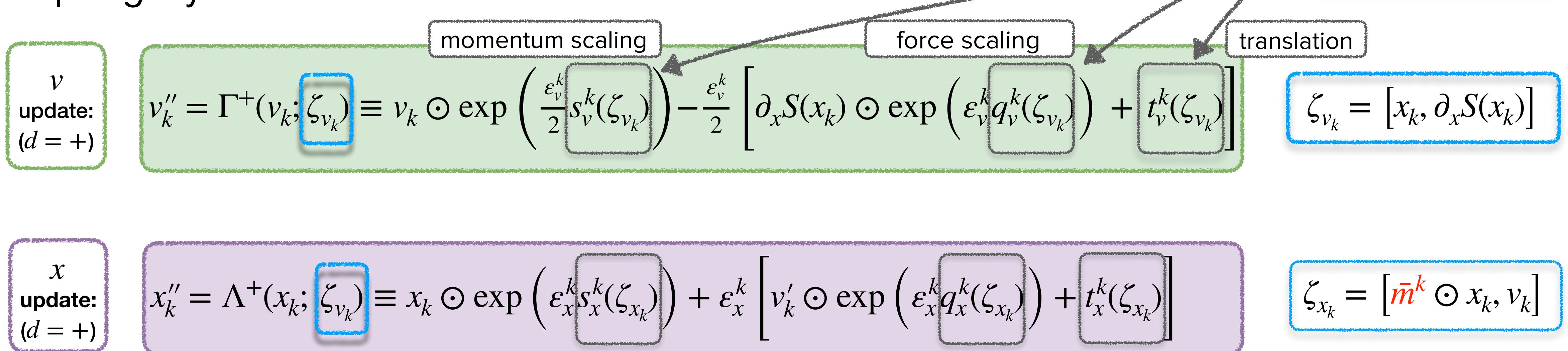


# Leapfrog Layer

- Introduce persistent direction  $d \sim \mathcal{U}(+, -)$  (*forward, backward*).
- **Target distribution:**  $p(\xi) = p(x) \cdot p(v) \cdot p(d)$
- **$k^{\text{th}}$ -Leapfrog Layer:**  $\xi_k \equiv (x_k, v_k, \pm) \rightarrow (x''_k, v''_k, \pm) \equiv \xi_{k+1}$

(input)  $\xi_0 \rightarrow \xi_1 \rightarrow \dots \rightarrow \xi_k \rightarrow \xi_{k+1} \rightarrow \dots \rightarrow \xi_{N_{\text{LF}}} \equiv \xi''$  (proposal)

- Construct a *trajectory* by passing  $\xi_k$  through  $k \in \{1, 2, \dots, N_{\text{LF}}\}$  leapfrog layers.



# I2hmc: Generalized Leapfrog

- **Leapfrog Step:**  $\xi_k \rightarrow \xi''_k$

1. Half-step  $v$  update:

$$v'_k = \Gamma^\pm(v_k; \zeta_{v_k})$$

2. Full-step, **half-** $x$  update:

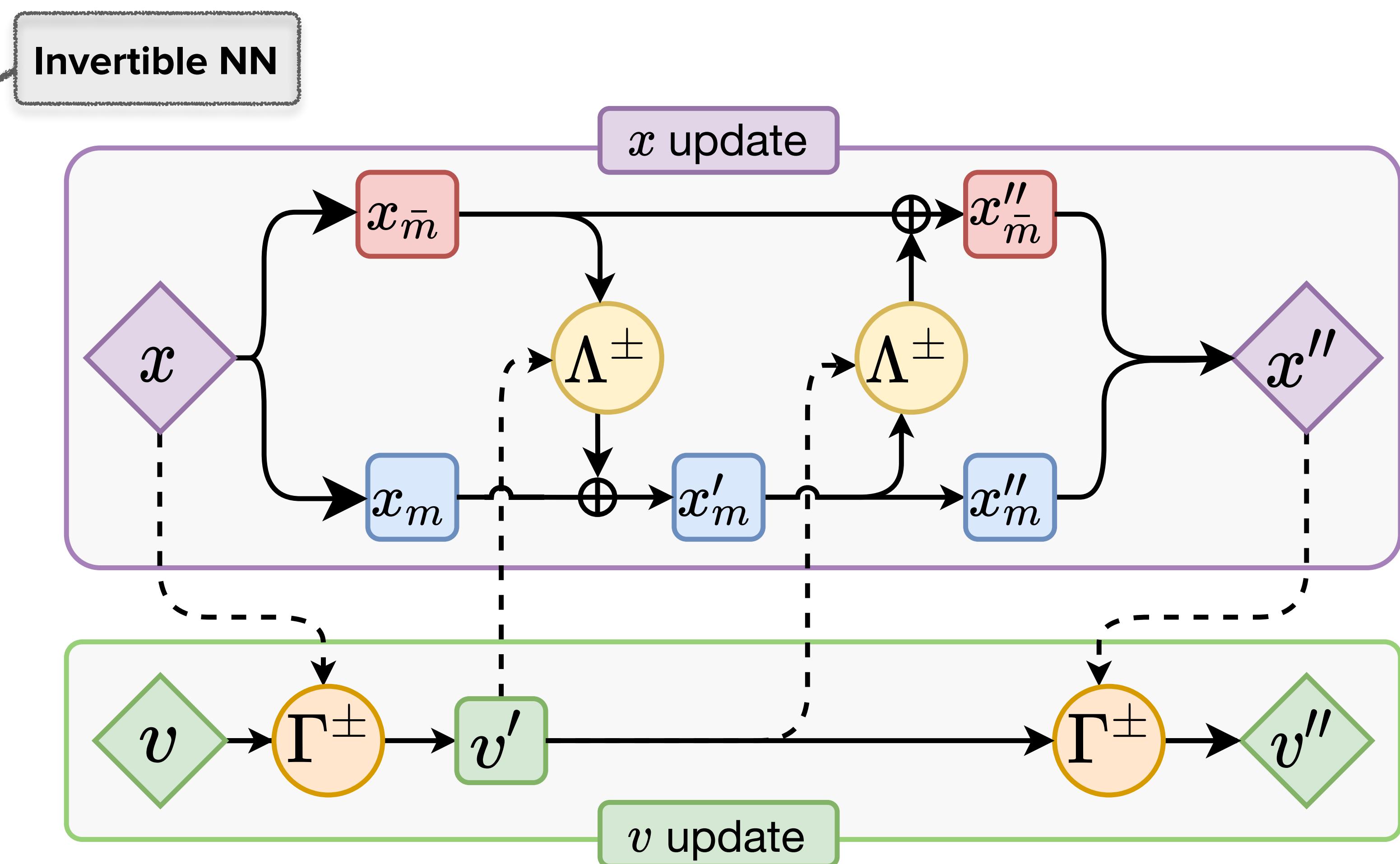
$$x'_k = m^k \odot x_k + \bar{m}^k \odot \Lambda^\pm(x_k; \zeta_{x_k})$$

3. Full-step, **half-** $x$  update:

$$x''_k = \bar{m}^k \odot x'_k + m^k \odot \Lambda^\pm(x'_k; \zeta_{x'_k})$$

4. Half-step  $v$  update:

$$v''_k = \Gamma^\pm(v'_k; \zeta_{v_k})$$



# I2hmc: Generalized Leapfrog

- **Leapfrog Step:**  $\xi_k \rightarrow \xi''_k$

1. Half-step  $v$  update:

$$v'_k = \Gamma^\pm(v_k; \zeta_{v_k})$$

2. Full-step, **half-** $x$  update:

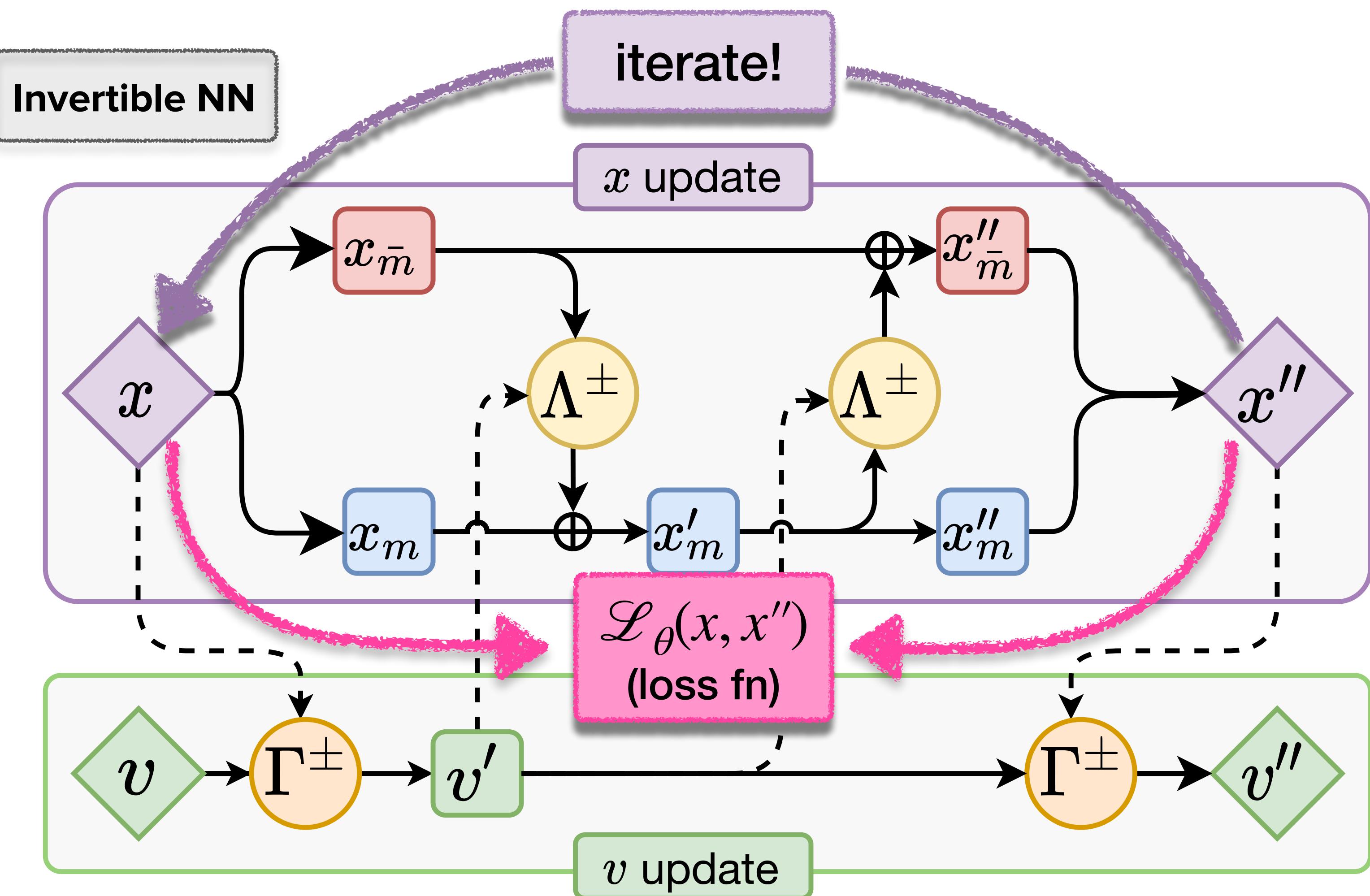
$$x'_k = m^k \odot x_k + \bar{m}^k \odot \Lambda^\pm(x_k; \zeta_{x_k})$$

3. Full-step, **half-** $x$  update:

$$x''_k = \bar{m}^k \odot x'_k + m^k \odot \Lambda^\pm(x'_k; \zeta_{x'_k})$$

4. Half-step  $v$  update:

$$v''_k = \Gamma^\pm(v'_k; \zeta_{v_k})$$



# 2D $U(1)$ Lattice Gauge Theory

- Link variables  $U_\mu(n) = e^{ix_\mu(n)} \in U(1)$ ,

with  $x_\mu(n) \in [-\pi, \pi]$ .

- Wilson action:**

- $S_\beta(x) = \beta \sum_P 1 - \cos x_P$ ,

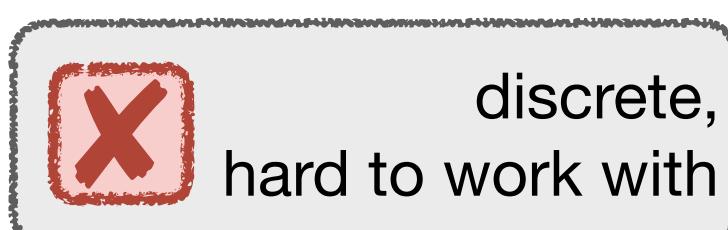
- $x_P = x_\mu(n) + x_\nu(n + \hat{\mu}) - x_\mu(n + \hat{\nu}) - x_\nu(n)$

- Topological charge:**

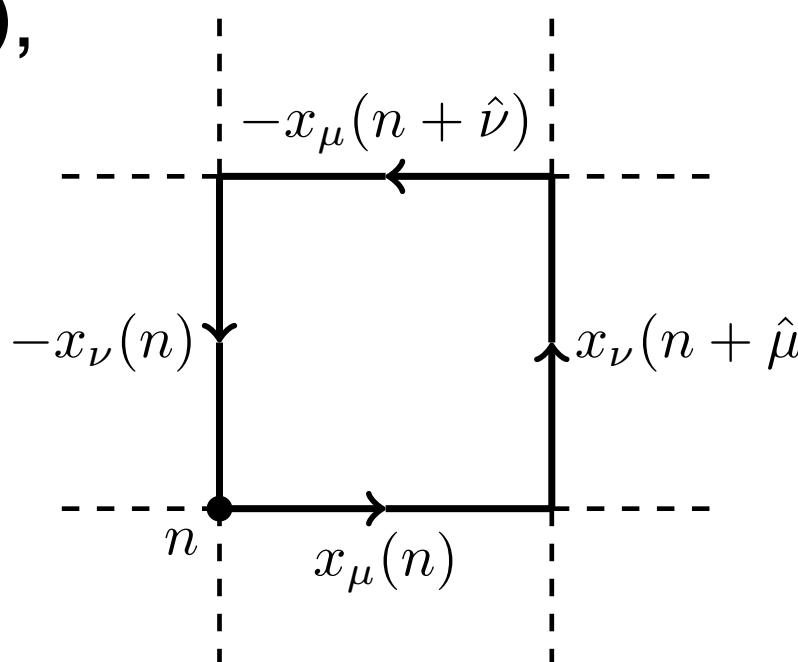
- $\mathcal{Q}_{\mathbb{R}} = \frac{1}{2\pi} \sum_P \sin x_P \in \mathbb{R}$



- $\mathcal{Q}_{\mathbb{Z}} = \frac{1}{2\pi} \sum_P \lfloor x_P \rfloor \in \mathbb{Z}$



$$\lfloor x_P \rfloor = x_P - 2\pi \left\lfloor \frac{x_P + \pi}{2\pi} \right\rfloor$$



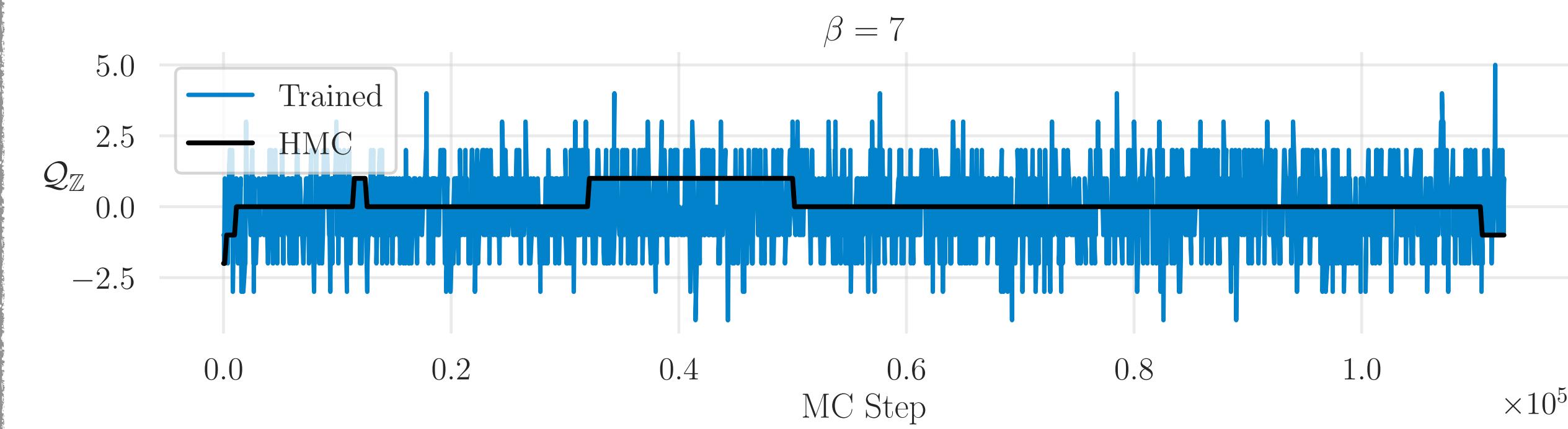
# Loss function, $\mathcal{L}(\theta)$

- We maximize the *expected squared charge difference*:

- $$\mathcal{L}(\theta) = \mathbb{E}_{p(\xi)} [-\delta\mathcal{Q}_{\mathbb{R}}^2(\xi', \xi) \cdot A(\xi' | \xi)]$$

- $$\delta\mathcal{Q}_{\mathbb{R}}^2(\xi', \xi) = (\mathcal{Q}_{\mathbb{R}}(\xi') - \mathcal{Q}_{\mathbb{R}}(\xi))^2$$
 (squared charge diff.)

- $$A(\xi' | \xi) = \min \left\{ 1, \frac{p(\xi')}{p(\xi)} \left| \frac{\partial \xi'}{\partial \xi^T} \right| \right\}$$
 (acceptance prob.)



# Simulated Annealing

- Introduce an **annealing schedule** during the training phase:

- $\{\gamma_t\}_{t=0}^N = \{\gamma_0, \gamma_1, \dots, \gamma_{N-1}, \gamma_N\},$

ex: {0.1, 0.2, 0.3, ..., 0.9, 1.0}

- $\gamma_0 < \gamma_1 < \dots < \gamma_N \equiv 1,$
- $\delta_\gamma \equiv \|\gamma_{t+1} - \gamma_t\| \ll 1$

increasing

varied slowly

- For  $\|\gamma_t\| < 1$ , this helps to rescale (*shrink*) the energy barriers between isolated modes
  - Allows sampler to explore previously inaccessible regions of the target distribution.
- Target distribution becomes:

- $p_t(x) \propto e^{-\gamma_t S_\beta(x)}, \text{ for } t = 0, 1, \dots, N$

# Training Algorithm

**input :**

1. Loss function,  $\mathcal{L}_\theta(\xi', \xi, A(\xi'|\xi))$
2. Batch of initial states,  $x$
3. Learning rate schedule,  $\{\alpha_t\}_{t=0}^{N_{\text{train}}}$
4. Annealing schedule,  $\{\gamma_t\}_{t=0}^{N_{\text{train}}}$
5. Target distribution,  $p_t(x) \propto e^{-\gamma_t S_\beta(x)}$

Initialize weights  $\theta$

**for**  $0 \leq t < N_{\text{train}}$  :

resample  $v \sim \mathcal{N}(0, \mathbb{I})$   
resample  $d \sim \mathcal{U}(+, -)$   
construct  $\xi_0 \equiv (x_0, v_0, d_0)$

re-sample  
momentum  
+ direction  
**construct**  
trajectory

**for**  $0 \leq k < N_{\text{LF}}$  :

| propose (leapfrog layer)  $\xi'_k \leftarrow \xi_k$

Compute loss  
+ backprop

compute  $A(\xi'|\xi) = \min \left\{ 1, \frac{p(\xi')}{p(\xi)} \left| \frac{\partial \xi'}{\partial \xi^T} \right| \right\}$

Metropolis-Hastings  
accept/reject

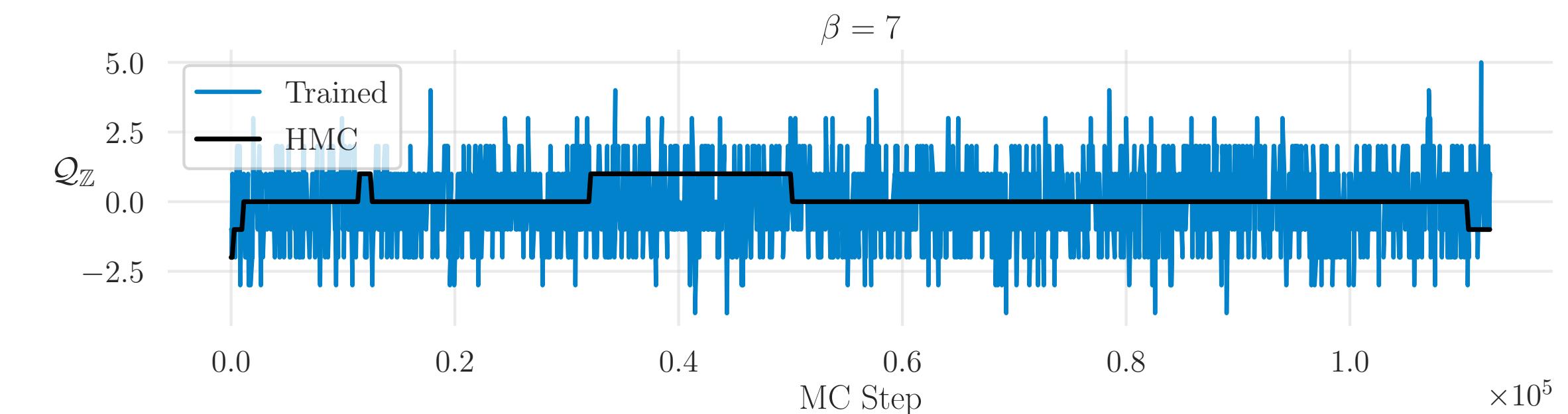
update  $\mathcal{L} \leftarrow \mathcal{L}_\theta(\xi', \xi, A(\xi'|\xi))$

backprop  $\theta \leftarrow \theta - \alpha_t \nabla_\theta \mathcal{L}$

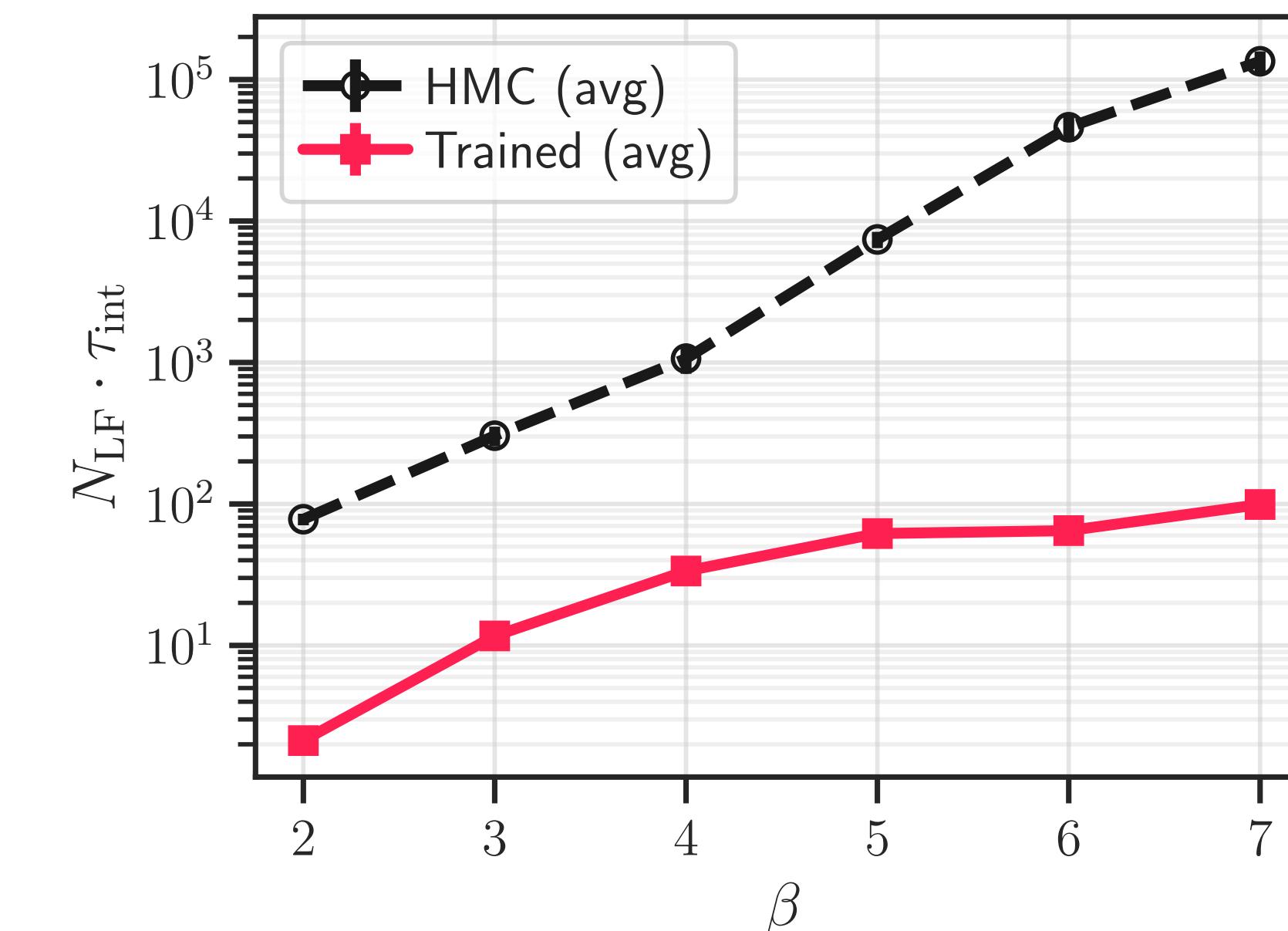
assign  $x_{t+1} \leftarrow \begin{cases} x' & \text{with probability } A(\xi'|\xi) \\ x & \text{with probability } (1 - A(\xi'|\xi)). \end{cases}$

# Results

- Want to calculate  $\langle \mathcal{O} \rangle \propto \int [\mathcal{D}x] \mathcal{O}(x) e^{-S(x)}$
- If we had *independent* configurations, we could approximate by
  - $\langle \mathcal{O} \rangle \simeq \frac{1}{N} \sum_{n=1}^N \mathcal{O}(x_n) \rightarrow \sigma^2 = \frac{1}{N} \text{Var} [\mathcal{O}(x)]$
- Accounting for *autocorrelation*:  $\sigma^2 = \frac{\tau_{\text{int}}^{\mathcal{O}}}{N} \text{Var} [\mathcal{O}(x)]$
- We measure the performance of our model by looking at the *integrated autocorrelation time*,  $\tau_{\text{int}}$  of the topological charge  $\mathcal{Q}_{\mathbb{Z}}$ .
- For generic HMC, it is known that  $\tau_{\text{int}}$  grows exponentially as  $\beta \rightarrow \infty$  (**critical slowing down**)



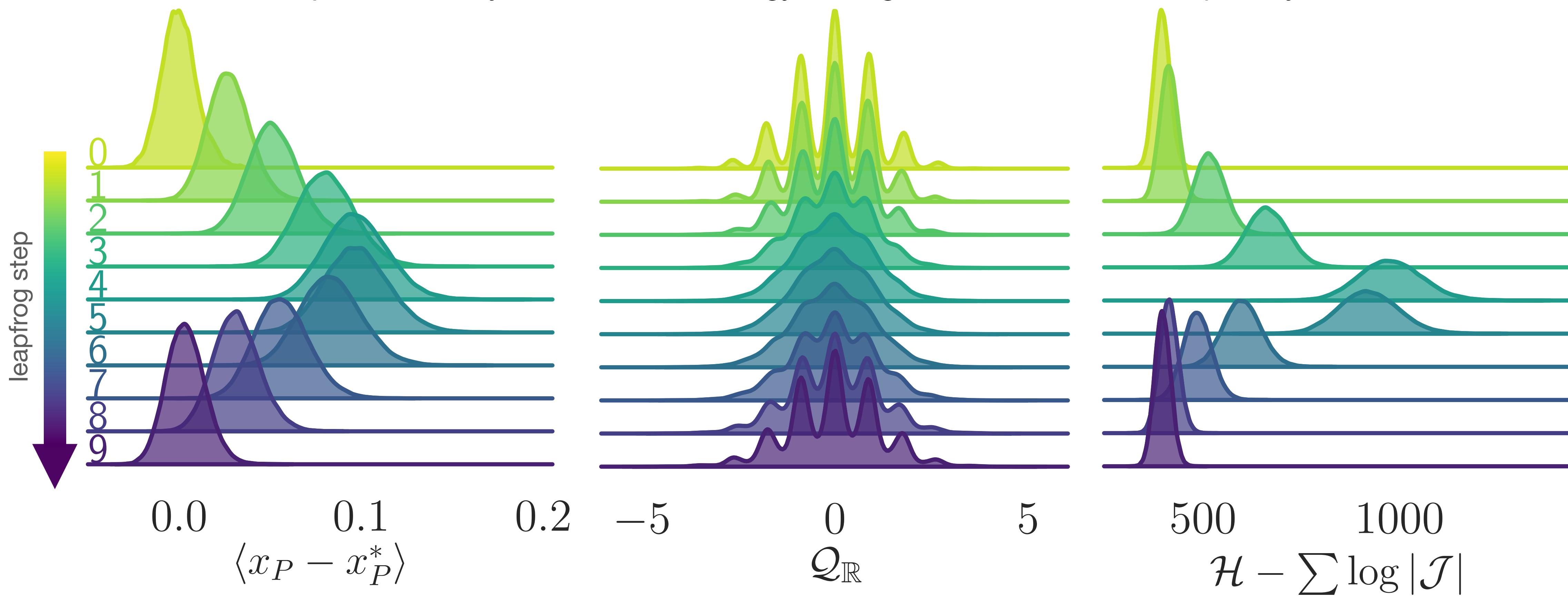
(d.) Plot of the topological charge history  $\mathcal{Q}_{\mathbb{Z}}$  vs MC Step



(c.) Estimate of the integrated autocorrelation time  $\tau_{\text{int}}$  vs  $\beta$  for both the trained model and generic HMC.

# Interpretation

- Look at how different quantities evolve over the course of a trajectory ( $N_{\text{LF}}$  leapfrog layers)
  - ▶ See that the sampler artificially *increases the energy* during the first half of the trajectory

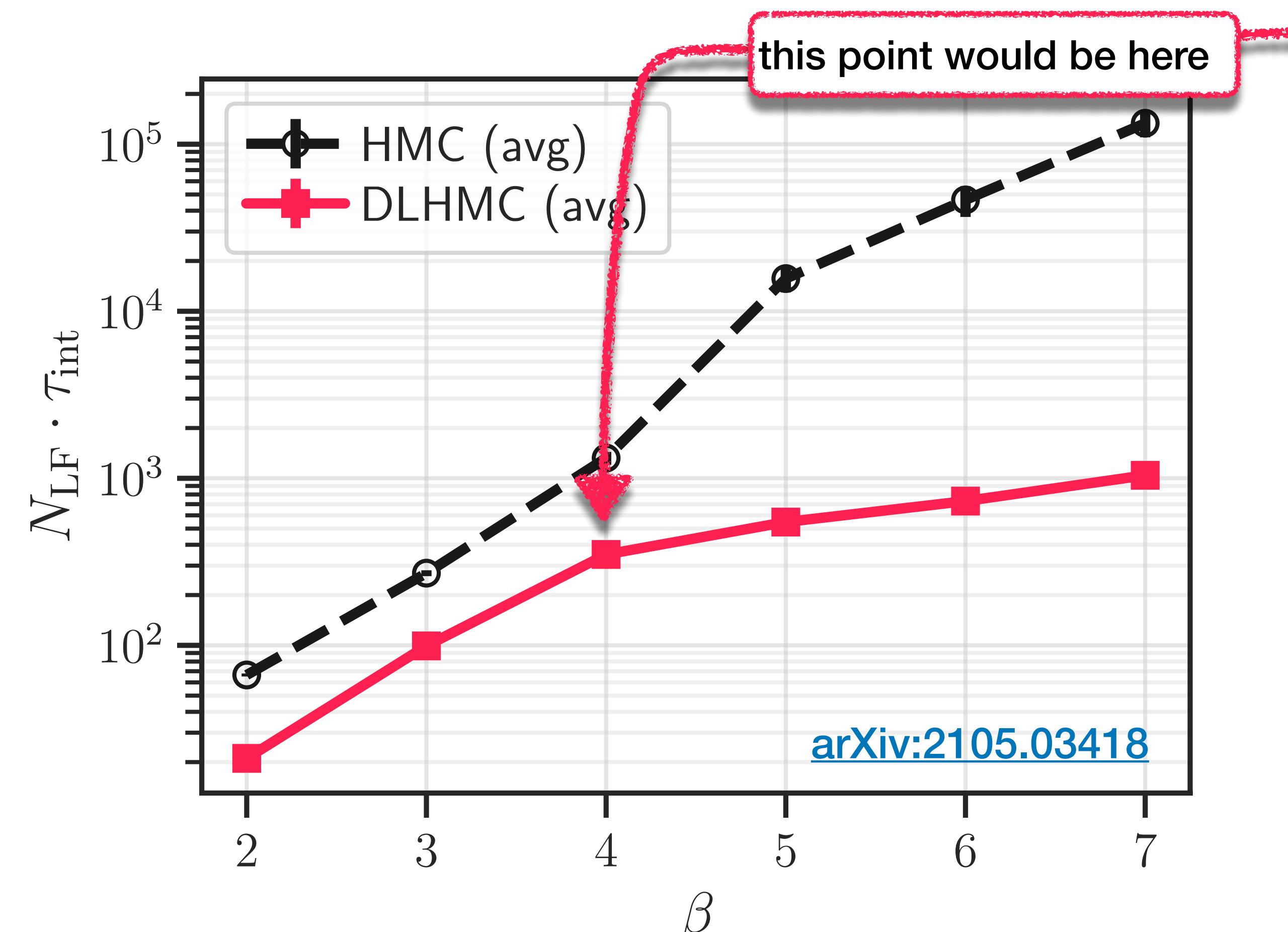


**(a.)** Deviation in the average plaquette,  $x_P$

**(b.)** Evolution of the continuous charge  $Q_{\mathbb{R}}$

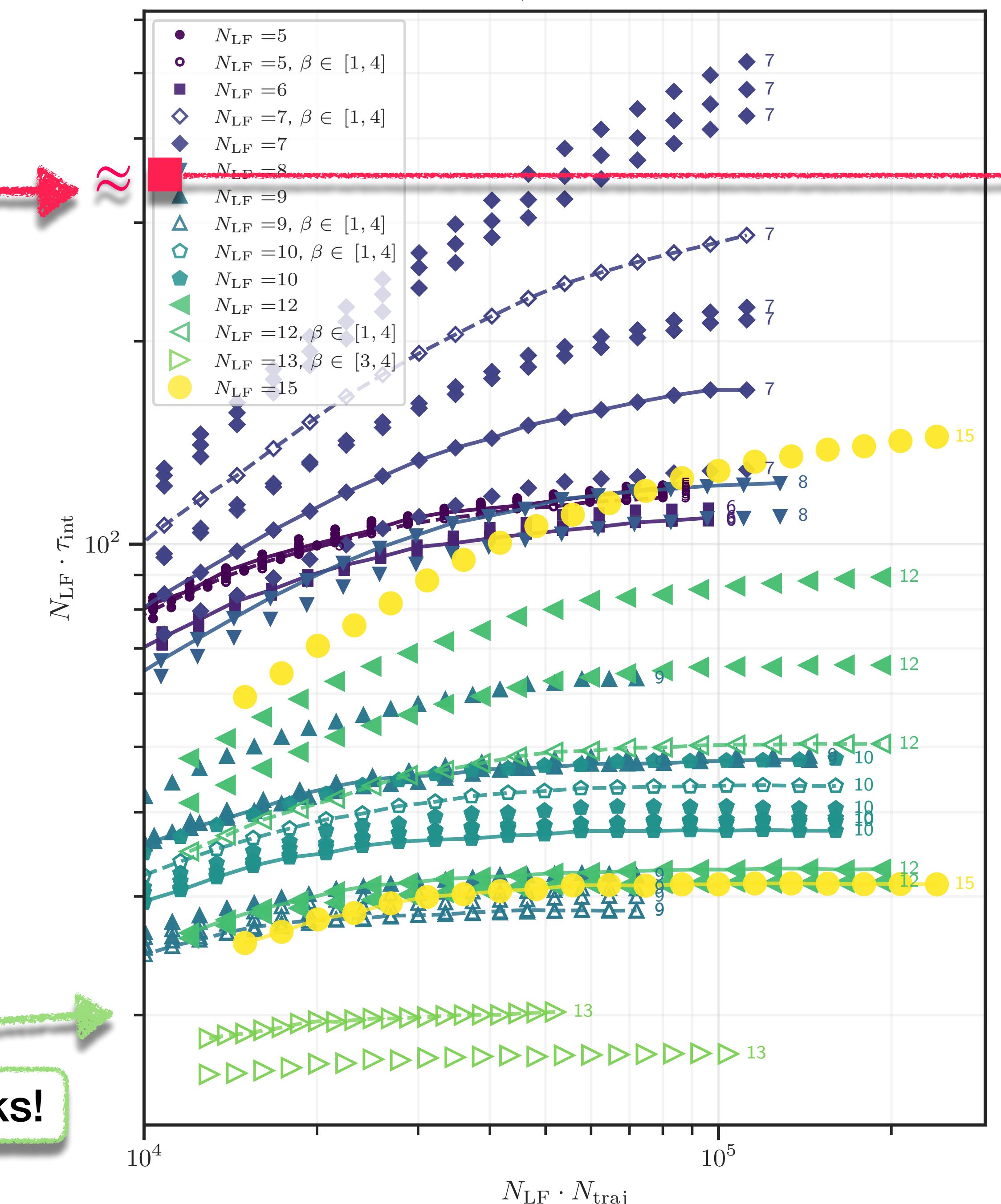
**(c.)** Evolution of the effective energy

# New Results



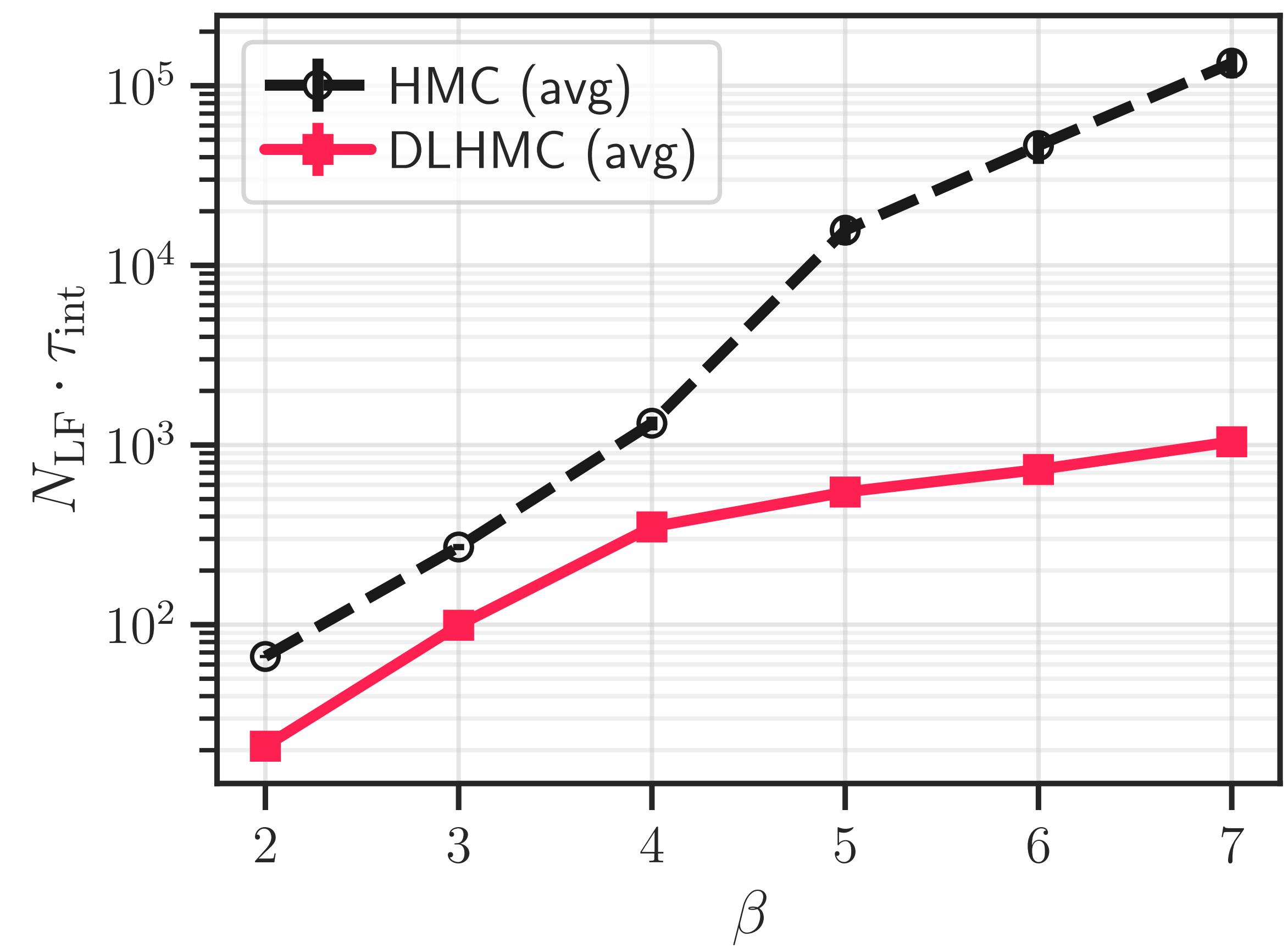
• Better performance:  $\approx 10 \times$  previous results

New networks!

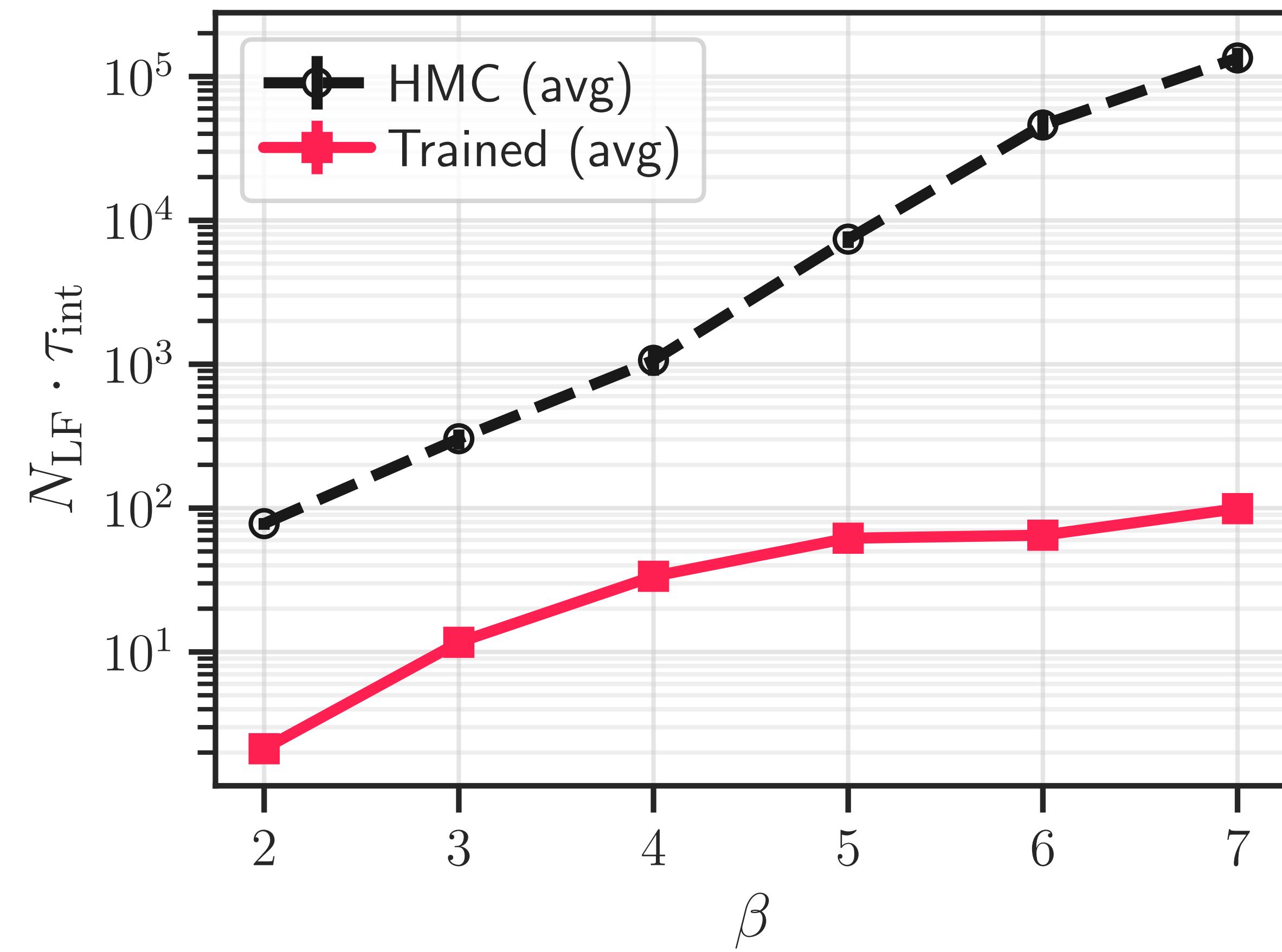


# Comparison

previous (from [arXiv:2105.03418](https://arxiv.org/abs/2105.03418))



new (preliminary)



# Acknowledgements

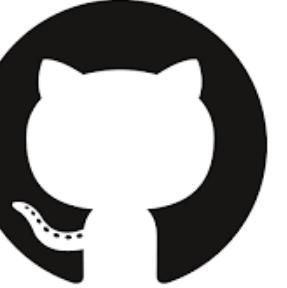
- **Collaborators:**
  - ▶ Xiao-Yong Jin,
  - ▶ James C. Osborn
- Huge thank you to:
  - ▶ Yannick Meurice
  - ▶ Peter Boyle
  - ▶ Norman Christ
  - ▶ Taku Izubuchi
  - ▶ Akio Tomiya
  - ▶ Critical Slowing Down group (ECP)
  - ▶ Luchang Jin
  - ▶ ALCF Staff + Datascience group
  - ▶ Chulwoo Jung



This research used resources of the Argonne Leadership Computing Facility, which is a DOE Office of Science User Facility supported under Contract DE-AC02-06CH11357.



# l2hmc-qcd



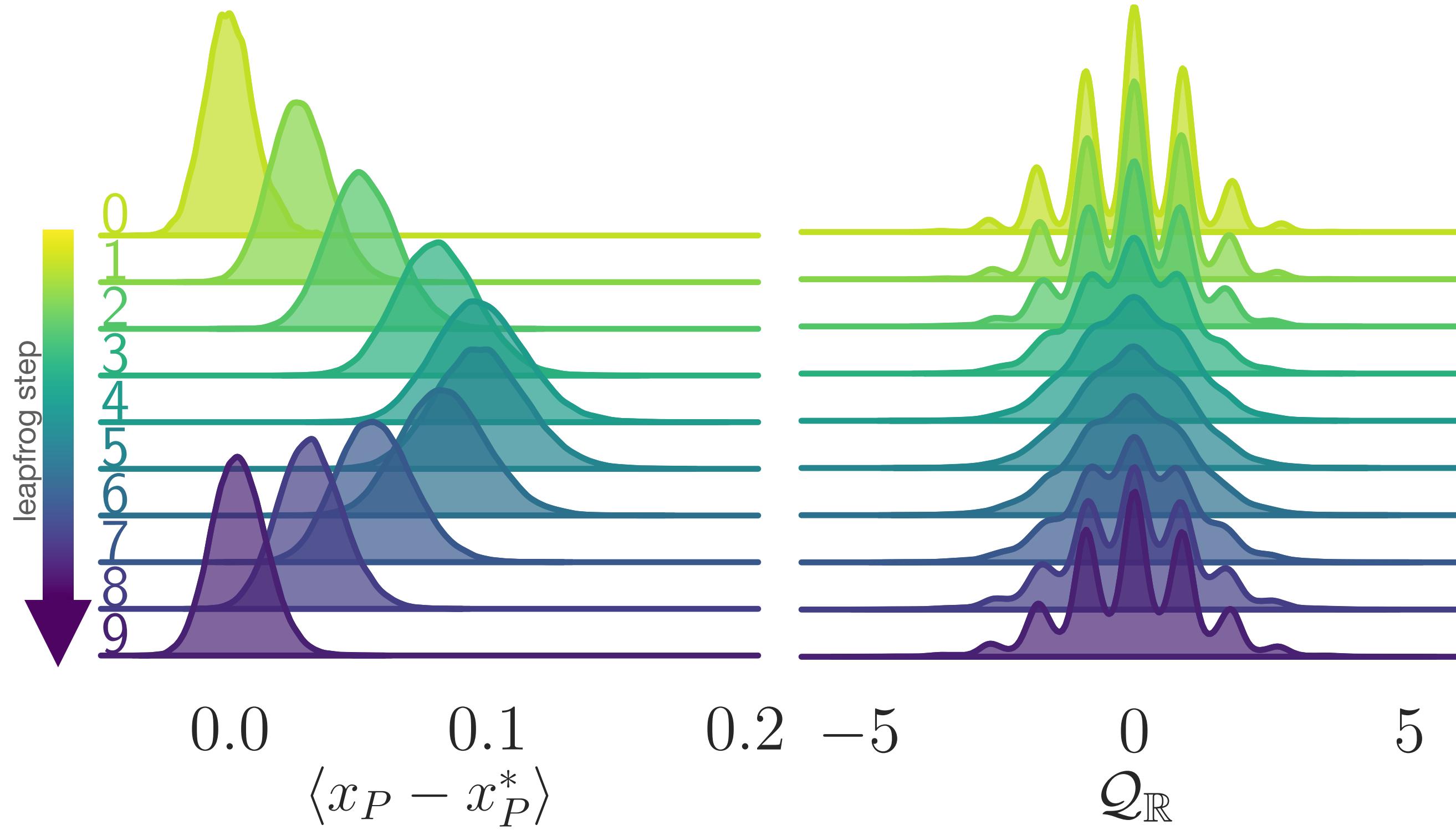
Sam Foreman\*, Xiao-Yong Jin, & James C. Osborn

A trainable framework for accelerating HMC on lattice gauge models.

[arXiv:2105.03418](https://arxiv.org/abs/2105.03418)

[bit.ly/l2hmc-lattice21](https://bit.ly/l2hmc-lattice21)

[github.com/saforem2/l2hmc-qcd](https://github.com/saforem2/l2hmc-qcd)



(a.) Deviation in the average plaquette,  $x_P$  over a single trajectory.

(b.) Evolution of  $Q_R = \frac{1}{2\pi} \sum_P \sin x_P \in \mathbb{R}$

