SPRING 2023 ECE 60146 – Homework 8

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3.1 Sentiment Analysis with own GRU

To implement the own GRU network a GRU module is implemented using the main equations of GRU logic on Slide 59 of Prof. Kak's week – 12 lecture as below.

```
\begin{array}{lcl} \mathbf{z}_t & = & \sigma(W_z \mathbf{x}_t \ + \ U_z \mathbf{h}_{t-1}) \\ \mathbf{r}_t & = & \sigma(W_r \mathbf{x}_t \ + \ U_r \mathbf{h}_{t-1}) \\ \tilde{\mathbf{h}}_t & = & \tanh(W_h \mathbf{x}_t \ + \ U_h (\mathbf{r}_t \odot \mathbf{h}_{t-1})) \\ \mathbf{h}_t & = & (1 - \mathbf{z}_t) \odot \mathbf{h}_{t-1} \ + \ \mathbf{z}_t \odot \tilde{\mathbf{h}}_t \end{array}
```

Similar to the equations an update gate and reset gate are initialized whose main role is to control the amount of information to retain for the input (update function z) and how much to forget (reset function r) that is not relevant to the context for the input generated. A candidate hidden state is dependent on the current value of input sequence and the previous value of the hidden state. This ensures that the current input can be combined with previous contextual information. Further using this candidate hidden state and previous hidden state along with the update gate, the hidden state for the current update is computed. The own implementation is an exact computation of the equations above as seen in Figure 1.

This GRU is wrapped and used in RNN network where the hidden state is computed and further used to compute the next output. A logsoftmax function is used to attain shape of output that can be compared with sentiment label during loss calculation as shown in Figure 2.

We can say that gating mechanism can successfully reduce the vanishing gradient problem by forgetting/resetting the information that is not relevant/context based for generating the next output in sequence. This way only the necessary dependencies are retained while the not very relevant dependencies are reset leading to less learnable parameters and thus reduction in vanishing gradients.

```
#Own GRU module
class GRU(nn.Module):
    def __init__(self, input_size, hidden_size):
        super(GRU, self).__init__()
        self.input_size = input_size
        self.hidden_size = hidden_size
        # update gate parameters
        self.Wz = nn.Linear(input_size, hidden_size)
        self.Uz = nn.Linear(hidden_size, hidden_size)
        # reset gate parameters
        self.Wr = nn.Linear(input_size, hidden_size)
        self.Ur = nn.Linear(hidden_size, hidden_size)
        # candidate hidden state parameters
        self.Wh = nn.Linear(input_size, hidden_size)
        self.Uh = nn.Linear(input_size, hidden_size)
        self.Uh = nn.Linear(hidden_size, hidden_size)
```

```
def forward(self, x, h):
        # compute update gate and reset cate
        z = torch.sigmoid(self.Wz(x) + self.Uz(h))
        r = torch.sigmoid(self.Wr(x) + self.Ur(h))
        # compute candidate hidden state
        h_tilda = torch.tanh(self.Wh(x) + self.Uh(r * h))
        # compute new hidden state
        h new = (1 - z) * h + z * h tilda
        return h new
#implemented similar to the basic RNN network (from net sources and Prof Kak' codes)
class RNN(nn.Module):
    def __init__(self, input_size, hidden_size, output_size):
        super(RNN, self). init ()
        self.hidden_size = hidden_size
        self.gru = GRU(input_size, hidden_size)
        self.fc = nn.Linear(hidden size, output size)
        self.logsoftmax = nn.LogSoftmax(dim=1)
    def forward(self, x):
        h = torch.zeros(1, self.hidden_size) # initialize hidden state with zeros
        for i in range(x.shape[0]):
            h = self.gru(x[i], h)
        out = self.fc(h)
        out = self.logsoftmax(out)
        return out
```

Figure 1: Own GRU code block

The plot of loss vs iterations for the own GRU implementation can be seen in Figure 2 and the results attained can be seen in Figure 3.

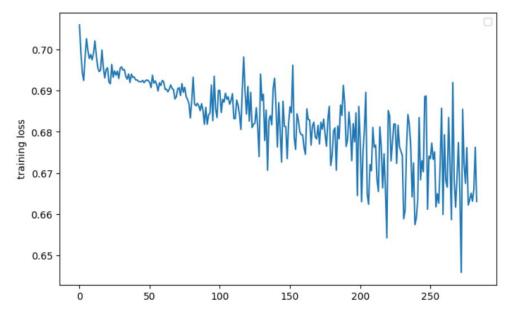


Figure 2: Plot of loss vs iterations for the own GRU

```
Confusion matrix:
[[ 468 1184]
[ 164 1747]]
Accuracy of the network on the test data: 62 %
```

Figure 3: Confusion matrix and accuracy attained using own GRU

3.2 Sentiment Analysis using torch.nn.GRU

The other two RNN networks implemented are using nn.torch.GRU, one of which is implemented by giving the hyperparameter 'bidirectional = True'. The plots of loss vs iterations for these two networks can be seen in Figure 4 and Figure 6, while the quantitative results can be seen in Figure 5 and Figure 7.

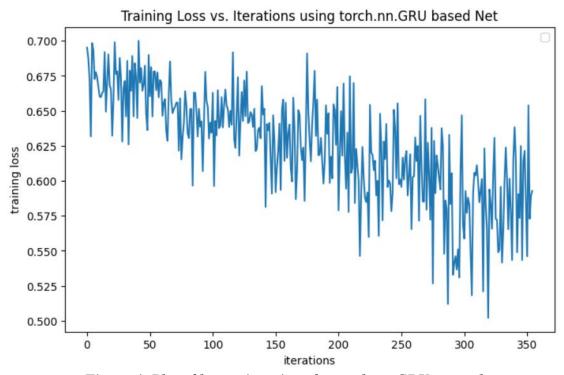


Figure 4: Plot of loss vs iterations for torch.nn.GRU network

```
Confusion matrix using nn.GRU based network:
[[1159 493]
[ 626 1285]]
Accuracy of the nn.GRU based network on the test data: 68 %
```

Figure 5: Confusion matrix and accuracy attained using torch.nn.GRU network

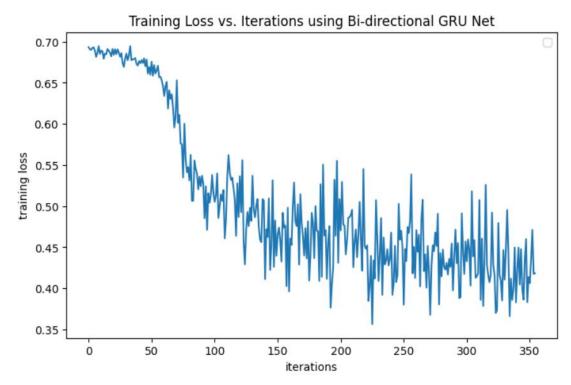


Figure 6: Plot of loss vs iterations for bidirectional torch.nn.GRU network

```
Confusion matrix of b-directional GRU:
[[1339 313]
[ 442 1469]]
Accuracy of the bi-directional GRU network on the test data: 78 %
```

Figure 7: Confusion matrix and accuracy attained using bidirectional torch.nn.GRU network

Comparing the three GRUs implemented above:

We can observe that the bi-directional GRU attained the maximum accuracy of 78% among the three RNN networks implemented, with the second-best accuracy attained as 68% by non-bidirectional torch.nn.GRU based network. We can also observe a curved loss decrease in the training of bi-directional network while the others had steady increase/decrease in reducing loss. An interesting observation is the vanilla GRU which attained accuracy of 62% predicted more true negatives than the bidirectional GRU however, bi-directional GRU stood in better position comparatively. We can say that the bi-directional GRU domination in performance can be due to the fact of considering both the past and future contexts i.e., both directions of sequence context being considered in prediction leading to better predictions. All these GRUs' performance can still be improved by using much deeper and advanced configuration of networks.

SOURCE CODE:

```
# -*- coding: utf-8 -*-
"""HW8.ipynb
Automatically generated by Colaboratory.
Original file is located at
   https://colab.research.google.com/drive/1ZnkwP4s80qlxcei_m-Fg_xYz58fHhOvn
# Commented out IPython magic to ensure Python compatibility.
#import libraries required
import gzip
import pickle
# %matplotlib inline
from pycocotools.coco import COCO
import numpy as np
import matplotlib.pyplot as plt
import skimage.io as io
import random
import os
import zipfile
from shutil import copyfile
import sys
import copy
import torch
from torch.utils.data import Dataset
from torch.utils.data import DataLoader
from PIL import Image
import pandas as pd
import torchvision
import torchvision.transforms as tvt
import torch.nn as nn
import torch.nn.functional as F
import torch.optim as optim
#give paths
path to saved embeddings = '/content/drive/MyDrive/Purdue/HW8/'
root_dir = '/content/drive/MyDrive/Purdue/HW8/data/'
dataset_file_train = 'sentiment_dataset_train_400.tar.gz'
dataset file test = 'sentiment dataset test 400.tar.gz'
```

```
#create dataset and dataloader
class SADataset(Dataset):
    #intializations
    def init (self, root dir, dataset file, train or test,
path_to_saved embeddings = None):
        super(). init ()
        self.path to saved embeddings = path to saved embeddings
        self.train or test = train or test
        self.root dir = root dir
        f = gzip.open(root dir + dataset file, 'rb')
        dataset = f.read()
        if path to saved embeddings is not None:
            import gensim.downloader as genapi
            from gensim.models import KeyedVectors
            if os.path.exists(path to saved embeddings + 'vectors.kv'):
                self.word vectors = KeyedVectors.load(path to saved embeddings +
'vectors.kv')
            else:
                print("""\n\nSince this is your first time to install the
word2vec embeddings, it may take"""
                      """\na couple of minutes. The embeddings occupy around
3.6GB of your disk space.\n\n""")
                self.word vectors = genapi.load("word2vec-google-news-
300")
                ## 'kv' stands for "KeyedVectors", a special datatype used by
gensim because it
                ## has a smaller footprint than dict
                self.word vectors.save(path to saved embeddings + 'vectors.kv')
        if train or test == 'train':
            if sys.version info[0] == 3:
                self.positive reviews train, self.negative reviews train,
self.vocab = pickle.loads(dataset, encoding='latin1')
                self.positive_reviews_train, self.negative_reviews_train,
self.vocab = pickle.loads(dataset)
            self.categories = sorted(list(self.positive reviews train.keys()))
            self.category sizes train pos = {category :
len(self.positive reviews train[category]) for category in self.categories}
            self.category_sizes_train_neg = {category :
len(self.negative_reviews_train[category]) for category in self.categories}
```

```
self.indexed dataset train = []
            for category in self.positive reviews train:
                for review in self.positive_reviews_train[category]:
                    self.indexed dataset train.append([review, category, 1])
            for category in self.negative reviews train:
                for review in self.negative reviews train[category]:
                    self.indexed_dataset_train.append([review, category, 0])
            random.shuffle(self.indexed dataset train)
        elif train or test == 'test':
            if sys.version info[0] == 3:
                self.positive reviews test, self.negative reviews test,
self.vocab = pickle.loads(dataset, encoding='latin1')
            else:
                self.positive_reviews_test, self.negative_reviews_test,
self.vocab = pickle.loads(dataset)
            self.vocab = sorted(self.vocab)
            self.categories = sorted(list(self.positive_reviews_test.keys()))
            self.category sizes test pos = {category :
len(self.positive_reviews_test[category]) for category in self.categories}
            self.category sizes test neg = {category :
len(self.negative_reviews_test[category]) for category in self.categories}
            self.indexed dataset test = []
            for category in self.positive reviews test:
                for review in self.positive_reviews_test[category]:
                    self.indexed dataset test.append([review, category, 1])
            for category in self.negative_reviews_test:
                for review in self.negative reviews test[category]:
                    self.indexed dataset test.append([review, category, 0])
            random.shuffle(self.indexed dataset test)
    def review to tensor(self, review):
        list of embeddings = []
        for i,word in enumerate(review):
            if word in self.word vectors.key to index:
                embedding = self.word vectors[word]
                list_of_embeddings.append(np.array(embedding))
            else:
                next
        review tensor = torch.FloatTensor( list of embeddings )
        return review tensor
    def sentiment to tensor(self, sentiment):
        Sentiment is ordinarily just a binary valued thing. It is 0 for negative
```

```
sentiment and 1 for positive sentiment. We need to pack this value in a
        two-element tensor.
        sentiment tensor = torch.zeros(2)
        if sentiment == 1:
            sentiment tensor[1] = 1
        elif sentiment == 0:
            sentiment tensor[0] = 1
        sentiment tensor = sentiment tensor.type(torch.long)
        return sentiment tensor
    def __len__(self):
       if self.train_or_test == 'train':
            return len(self.indexed dataset train)
        elif self.train or test == 'test':
            return len(self.indexed dataset test)
    def __getitem__(self, idx):
        sample = self.indexed dataset train[idx] if self.train or test == 'train'
else self.indexed dataset test[idx]
       review = sample[0]
        review category = sample[1]
        review sentiment = sample[2]
        review sentiment = self.sentiment to tensor(review sentiment)
        review tensor = self.review to tensor(review)
        category index = self.categories.index(review category)
        sample = {'review'
                             : review tensor,
                  'category'
                                : category index, # should be converted to
tensor, but not yet used
                  'sentiment' : review_sentiment }
        return sample
train data 400 = SADataset(root_dir, dataset_file_train, 'train',
path to saved embeddings)
test data 400 = SADataset(root dir, dataset file test, 'test',
path to saved embeddings)
len(test_data_400)
# Set device to GPU if available, otherwise use CPU
device = torch.device("cuda" if torch.cuda.is available() else "cpu")
print(device)
batch_size = 1
num workers = 2
```

```
#create dataloader
train_data_loader = DataLoader(train_data_400, batch_size = batch_size, shuffle =
True, num workers=num workers)
test_data_loader = DataLoader(test_data_400, batch_size = batch_size, shuffle =
True, num workers=num workers)
data = next(iter(test_data_loader))
print(data['review'].shape)
count = 0
for i, data in enumerate(train_data_loader):
    review_tensor,category,sentiment = data['review'], data['category'],
data['sentiment']
    count += 1
print(count)
#Own GRU module
class GRU(nn.Module):
    def __init__(self, input_size, hidden_size):
        super(GRU, self).__init__()
        self.input_size = input_size
        self.hidden_size = hidden_size
        # update gate parameters
        self.Wz = nn.Linear(input_size, hidden_size)
        self.Uz = nn.Linear(hidden size, hidden size)
        # reset gate parameters
        self.Wr = nn.Linear(input_size, hidden_size)
        self.Ur = nn.Linear(hidden size, hidden size)
        # candidate hidden state parameters
        self.Wh = nn.Linear(input size, hidden size)
        self.Uh = nn.Linear(hidden_size, hidden_size)
    def forward(self, x, h):
        # compute update gate and reset cate
        z = torch.sigmoid(self.Wz(x) + self.Uz(h))
        r = torch.sigmoid(self.Wr(x) + self.Ur(h))
        # compute candidate hidden state
        h_tilda = torch.tanh(self.Wh(x) + self.Uh(r * h))
        # compute new hidden state
        h_{new} = (1 - z) * h + z * h_{tilda}
        return h new
#implemented similar to the basic RNN network (from net sources and Prof Kak'
```

```
class RNN(nn.Module):
    def init (self, input size, hidden size, output size):
        super(RNN, self).__init__()
        self.hidden size = hidden size
        self.gru = GRU(input_size, hidden_size)
        self.fc = nn.Linear(hidden_size, output_size)
        self.logsoftmax = nn.LogSoftmax(dim=1)
    def forward(self, x):
        h = torch.zeros(1, self.hidden_size) # initialize hidden state with zeros
        for i in range(x.shape[0]):
            h = self.gru(x[i], h)
        out = self.fc(h)
        out = self.logsoftmax(out)
        return out
#training
hidden_size = 100
net2 = RNN(input_size = 300, hidden_size=128, output_size=2)
net2 = copy.deepcopy(net2)
net2 = net2.to(device)
net2.train()
## Note that the GRUnet now produces the LogSoftmax output:
criterion = nn.NLLLoss()
optimizer = optim.Adam(net2.parameters(), lr=1e-3, betas=(0.9, 0.999))
training_loss_tally_own = []
for epoch in range(epochs):
    print("")
    running loss = 0.0
    for i, data in enumerate(train_data_loader,0):
        review_tensor,category,sentiment = data['review'], data['category'],
data['sentiment']
        review tensor = review tensor.to(device)
        sentiment = sentiment.to(device)
        optimizer.zero_grad()
        output = net2(review tensor)
```

```
loss = criterion(output, torch.argmax(sentiment, 1))
        running_loss += loss.item()
        loss.backward()
        optimizer.step()
        if i % 200 == 199:
            avg_loss = running_loss / float(200)
            training loss tally own.append(avg loss)
            print("[epoch:%d iter:%4d] loss: %.5f" % (epoch+1,i+1,avg_loss))
            running loss = 0.0
print("\nFinished Training\n\n")
#plotting
plt.figure(figsize=(8,5))
plt.title("Training Loss vs. Iterations")
plt.plot(training loss tally own)
plt.xlabel("iterations")
plt.ylabel("training loss")
plt.legend()
plt.savefig("training loss.png")
plt.show()
#testing
from sklearn.metrics import confusion_matrix
# Set the network to evaluation mode
net2.eval()
# Initialize variables for the confusion matrix
all predictions = []
all_targets = []
with torch.no_grad():
    for data in test_data_loader:
        review_tensor, category, sentiment = data['review'], data['category'],
data['sentiment']
        review_tensor = review_tensor.to(device)
        sentiment = sentiment.to(device) # Move sentiment tensor to GPU
        output, hidden = net2(review tensor)
```

```
_, predicted = torch.max(output.data, 1)
        all_predictions.extend(predicted.cpu().numpy())
        all targets.extend(torch.argmax(sentiment, 1).cpu().numpy())
# Compute the confusion matrix
cm = confusion matrix(all targets, all predictions)
# Print the confusion matrix
print("Confusion matrix:")
print(cm)
# Compute the overall accuracy
overall accuracy = 100 * cm.trace() / cm.sum()
print('Accuracy of the network on the test data: %d %%' % overall_accuracy)
#implementation using torch.nn.GRU
class GRU_Net(nn.Module):
    def init (self, input size, hidden size, output size, num layers,
drop prob=0.2):
        super(). init ()
        self.hidden_size = hidden_size
        self.num layers = num layers
        self.gru = nn.GRU(input size, hidden size, num layers)
        self.fc = nn.Linear(hidden_size, output_size)
        self.relu = nn.ReLU()
        self.logsoftmax = nn.LogSoftmax(dim=1)
    def forward(self, x, h):
        out, h = self.gru(x, h)
        out = self.fc(self.relu(out[:,-1,:]))
        out = self.logsoftmax(out)
        return out, h
    def init hidden(self, batch size):
        weight = next(self.parameters()).data
        hidden = weight.new(self.num_layers, batch_size,
self.hidden size).zero ()
        return hidden
#training
epochs = 5
filename for out = "performance numbers " + str(epochs) + ".txt"
```

```
FILE = open(filename for out, 'w')
net1 = GRU_Net(input_size=300, hidden_size=100, output_size=2, num_layers=2)
net1 = copy.deepcopy(net1)
net1 = net1.to(device)
net1.train()
## Note that the GRUnet now produces the LogSoftmax output:
criterion = nn.NLLLoss()
optimizer = optim.Adam(net1.parameters(), lr=1e-3, betas=(0.9, 0.999))
training loss tally GRU INI = []
for epoch in range(epochs):
    print("")
    running_loss = 0.0
    for i, data in enumerate(train_data_loader):
        review_tensor,category,sentiment = data['review'], data['category'],
data['sentiment']
        review tensor = review tensor.to(device)
        sentiment = sentiment.to(device)
        optimizer.zero grad()
        hidden = net1.init_hidden(review_tensor.shape[1]).to(device)
        output, hidden = net1(review_tensor, hidden)
        loss = criterion(output, torch.argmax(sentiment, 1))
        running loss += loss.item()
        loss.backward()
        optimizer.step()
        if i % 200 == 199:
            avg_loss = running_loss / float(200)
            training_loss_tally_GRU_INI.append(avg_loss)
            print("[epoch:%d iter:%4d] loss: %.5f" % (epoch+1,i+1,avg_loss))
            FILE.write("%.5f\n" % avg_loss)
            FILE.flush()
            running_loss = 0.0
print("\nFinished Training\n\n")
```

```
#plotting
plt.figure(figsize=(8,5))
plt.title("Training Loss vs. Iterations using torch.nn.GRU based Net")
plt.plot(training loss tally GRU INI)
plt.xlabel("iterations")
plt.ylabel("training loss")
plt.legend()
plt.savefig("training_loss_GRU.png")
plt.show()
#Evaluation
from sklearn.metrics import confusion_matrix
# Set the network to evaluation mode
net1.eval()
# Initialize variables for the confusion matrix
all predictions = []
all_targets = []
# Iterate over the test data and predict the sentiment for each review
with torch.no grad():
    for data in test data loader:
        review_tensor, category, sentiment = data['review'], data['category'],
data['sentiment']
        review tensor = review tensor.to(device)
        sentiment = sentiment.to(device)
        hidden = net1.init_hidden(batch_size=1).to(device)
        list of outputs = []
        for k in range(review_tensor.shape[1]):
            output, hidden =
net1(torch.unsqueeze(torch.unsqueeze(review tensor[0, k], 0), 0), hidden)
            list of outputs.append(output)
        output = list_of_outputs[-1]
        _, predicted = torch.max(output.data, 1)
        all_predictions.extend(predicted.cpu().numpy())
        all_targets.extend(torch.argmax(sentiment, 1).cpu().numpy())
# Compute the confusion matrix
cm = confusion_matrix(all_targets, all_predictions)
# Print the confusion matrix
```

```
print("Confusion matrix using nn.GRU based network:")
print(cm)
# Compute the overall accuracy
overall_accuracy = 100 * cm.trace() / cm.sum()
print('Accuracy of the nn.GRU based network on the test data: %d %%' %
overall accuracy)
#Implementation of Bi-directional GRU
class GRU_Net_Bi(nn.Module):
    def __init__(self, input_size, hidden_size, output_size, num_layers,
drop prob=0.2, bidirectional=True):
        super(). init ()
        self.hidden size = hidden size
        self.num layers = num layers
        self.bidirectional = bidirectional
        self.num directions = 2 if bidirectional else 1
        self.gru = nn.GRU(input_size, hidden_size, num_layers, batch_first=True,
bidirectional=bidirectional)
        self.fc = nn.Linear(hidden size*self.num directions, output size)
        self.relu = nn.ReLU()
        self.logsoftmax = nn.LogSoftmax(dim=1)
    def forward(self, x, h):
        out, h = self.gru(x, h)
        if self.bidirectional:
            out = self.fc(self.relu(torch.cat((out[:, -1, :self.hidden_size],
out[:, 0, self.hidden_size:]), dim=1)))
        else:
            out = self.fc(self.relu(out[:,-1,:]))
        out = self.logsoftmax(out)
        return out, h
    def init hidden(self, batch size):
        weight = next(self.parameters()).data
        hidden = weight.new(self.num layers*self.num directions, batch size,
self.hidden size).zero ()
        return hidden
#training
epochs = 5
filename_for_out = "performance_numbers_" + str(epochs) + ".txt"
FILE = open(filename_for_out, 'w')
```

```
net = GRU Net Bi(input size=300, hidden size=100, output size=2, num layers=2,
bidirectional=True)
net = copy.deepcopy(net)
net = net.to(device)
net.train()
## Note that the GRUnet now produces the LogSoftmax output:
criterion = nn.NLLLoss()
optimizer = optim.Adam(net.parameters(), lr=1e-5, betas=(0.9, 0.999))
training_loss_tally_GRU = []
for epoch in range(epochs):
    print("")
    running_loss = 0.0
    for i, data in enumerate(train_data_loader):
        review_tensor,category,sentiment = data['review'], data['category'],
data['sentiment']
        review tensor = review tensor.to(device)
        sentiment = sentiment.to(device)
        optimizer.zero_grad()
        hidden = net.init hidden(review tensor.shape[0]).to(device)
        output, hidden = net(review_tensor, hidden)
        print(output.shape)
        loss = criterion(output, torch.argmax(sentiment, 1))
        running loss += loss.item()
        loss.backward()
        optimizer.step()
        if i % 200 == 199:
            avg_loss = running_loss / float(200)
            training loss tally GRU.append(avg loss)
            print("[epoch:%d iter:%4d] loss: %.5f" % (epoch+1,i+1,avg_loss))
            FILE.write("%.5f\n" % avg_loss)
            FILE.flush()
            running_loss = 0.0
print("\nFinished Training\n\n")
```

```
#plotting
plt.figure(figsize=(8,5))
plt.title("Training Loss vs. Iterations using Bi-directional GRU Net")
plt.plot(training loss tally GRU)
plt.xlabel("iterations")
plt.ylabel("training loss")
plt.legend()
plt.savefig("training loss GRU BiDirectional.png")
plt.show()
#testing
from sklearn.metrics import confusion_matrix
# Set the network to evaluation mode
net.eval()
# Initialize variables for the confusion matrix
all predictions = []
all_targets = []
# Iterate over the test data and predict the sentiment for each review
with torch.no grad():
    for data in test data loader:
        review_tensor, category, sentiment = data['review'], data['category'],
data['sentiment']
        review_tensor = review_tensor.to(device)
        sentiment = sentiment.to(device) # Move sentiment tensor to GPU
        hidden = net.init_hidden(batch_size=1).to(device)
        list of outputs = []
        for k in range(review_tensor.shape[1]):
            output, hidden = net(torch.unsqueeze(torch.unsqueeze(review_tensor[0,
k], 0), 0), hidden)
            list_of_outputs.append(output)
        output = list_of_outputs[-1]
        _, predicted = torch.max(output.data, 1)
        all_predictions.extend(predicted.cpu().numpy())
        all_targets.extend(torch.argmax(sentiment, 1).cpu().numpy())
# Compute the confusion matrix
cm = confusion_matrix(all_targets, all_predictions)
# Print the confusion matrix
```

```
print("Confusion matrix of b-directional GRU:")
print(cm)

# Compute the overall accuracy
overall_accuracy = 100 * cm.trace() / cm.sum()
print('Accuracy of the bi-directional GRU network on the test data: %d %%' %
overall_accuracy)
```
