

# Neyman Pearson Detector for Variance Detection

Sai Krishna Charan Dara(20171140)

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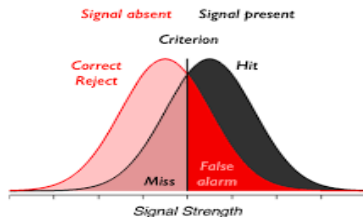
# False Alarm and Missed detection?

## False Alarm

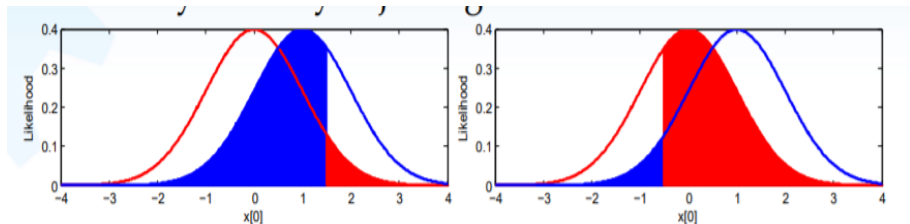
- Also called Type-I Error.  $H_0$  is true but we decide  $H_1$ .
- Raising an alarm that signal is present even it is not there, hence **False Alarm**.

## Missed Detection

- Also called Type-II Error.  $H_1$  is true but we decide  $H_0$ .
- Missed signal detection even if signal is present, hence **Missed Detection**.



# Trade Off between False Alarm and Missed Detection



## Left One

- Large threshold; small probability of false match (red), but a lot of misses (blue). Less  $P_{FA}$  and less  $P_D(1-P_{MD})$ .

## Right One

- Small threshold; only a few missed detections (blue), but a huge number of false matches. (red). More  $P_{FA}$  and more  $P_D(1-P_{MD})$ .

**Ideally: Less  $P_{FA}$  and more  $P_D$ !!**

# Neyman-Pearson Theorem

- Since  $P_{FA}$  and  $P_D$  depend on each other, we would like to maximize  $P_D$  subject to given maximum allowed  $P_{FA}$ .
- Neyman Pearson theorem provides a region with **maximum**  $P_D$  for a given  $P_{FA}$

## Theorem

$$L(\underline{x}) = \frac{p(\underline{x}; H_1)}{p(\underline{x}; H_0)} > \gamma,$$

where the threshold  $\gamma$  is found by

$$P_{FA} = \int_{R_1: L(\underline{x}) > \gamma} p(\underline{x}; H_0) d\underline{x} = \alpha \text{ then } P_D = \int_{R_1: L(\underline{x}) > \gamma} p(\underline{x}; H_1) d\underline{x}$$

# Proof..

We can use Lagrangian multipliers to maximize  $P_D$  for a given  $P_{FA}$ .  
Forming the Lagrangian

## Optimization Problem

$$\begin{aligned} F &= P_D + \lambda(P_{FA} - \alpha) \\ &= \int_{R_1} p(\underline{x}; H_1) d\underline{x} + \lambda \left( \int_{R_1} p(\underline{x}; H_0) d\underline{x} - \alpha \right) \\ &= \int_{R_1} (p(\underline{x}; H_1) + \lambda p(\underline{x}; H_0)) d\underline{x} - \lambda \alpha \end{aligned} \tag{1}$$

To maximize equation we should include  $\underline{x}$  in  $R_1$  if that integrand is positive for that value of  $\underline{x}$  or if  $p(\underline{x}; H_1) + \lambda p(\underline{x}; H_0) > 0$ .

$$L(\underline{x}) = \frac{p(\underline{x}; H_1)}{p(\underline{x}; H_0)} > -\lambda \Rightarrow L(\underline{x}) = \frac{p(\underline{x}; H_1)}{p(\underline{x}; H_0)} > \gamma \text{ with } \gamma > 0$$

# Neyman Pearson Detector for detection of variance

## Real Case Scenario: Problem Statement

There are two air crafts present in space and there is a base station present on earth. There is a condition that only one of the two air crafts will be in the region specified by the base station. If **aircraft ①** is present, it sends a sample from normally distributed distribution with mean 0 and variance  $\sigma_0^2 = 1$  and when **aircraft ②** is present, it sends a sample from same distribution but with variance  $\sigma_1^2 = 4$ . It is observed that near base station at  $t = 0s$ ,  $t = 2s$  and  $t = 4s$ , we received three samples 0.5, 1 and -3. Test which air crafts are possibly present at  $t = 0s$ ,  $t = 2s$  and  $t = 4s$ . Assume Probability of False Alarm = 0.4.

# Problem solving approach

- $H_0 : x[0] \sim \mathcal{N}(0, \sigma_0^2)$ . Null Hypothesis
- $H_1 : x[0] \sim \mathcal{N}(0, \sigma_1^2)$ . Alternative Hypothesis

By using Neyman Pearson approach,

$$L(\underline{x}) = \frac{p(\underline{x}; H_1)}{p(\underline{x}; H_0)} > \gamma,$$

$$p(x[0]; H_0) = \frac{1}{\sqrt{2\pi\sigma_0^2}} \exp\left(-\frac{x[0]^2}{2\sigma_0^2}\right) \quad p(x[0]; H_1) = \frac{1}{\sqrt{2\pi\sigma_1^2}} \exp\left(-\frac{x[0]^2}{2\sigma_1^2}\right)$$

Solving, we finally get  $x[0]^2 > (2 \log_e \gamma + \log \frac{\sigma_1^2}{\sigma_0^2}) / (\frac{1}{\sigma_0^2} - \frac{1}{\sigma_1^2}) = \gamma^1$

So we decide  $R_1$  when  $|x[0]| > \sqrt{\gamma^1}$  where  $\gamma^1$  can be calculated from given  $P_{FA} = 0.4$ .  $P_{FA} = \int_{R_1: |x[0]| > \sqrt{\gamma^1}} p(x[0]; H_0) dx[0] = \alpha = 0.4$ .

$$2Q\left(\frac{\sqrt{\gamma^1}}{\sigma_0}\right) = \alpha \Rightarrow \gamma^1 = \sigma_0^2 (Q^{-1}(\alpha/2))^2$$



# Probability of detection

$P_D$

- Probability of detection  $P_D = \int_{R_1: |x[0]| > \sqrt{\gamma^1}} p(x[0]; H_1) dx[0] = 2Q\left(\frac{\sqrt{\gamma^1}}{\sigma_1}\right)$

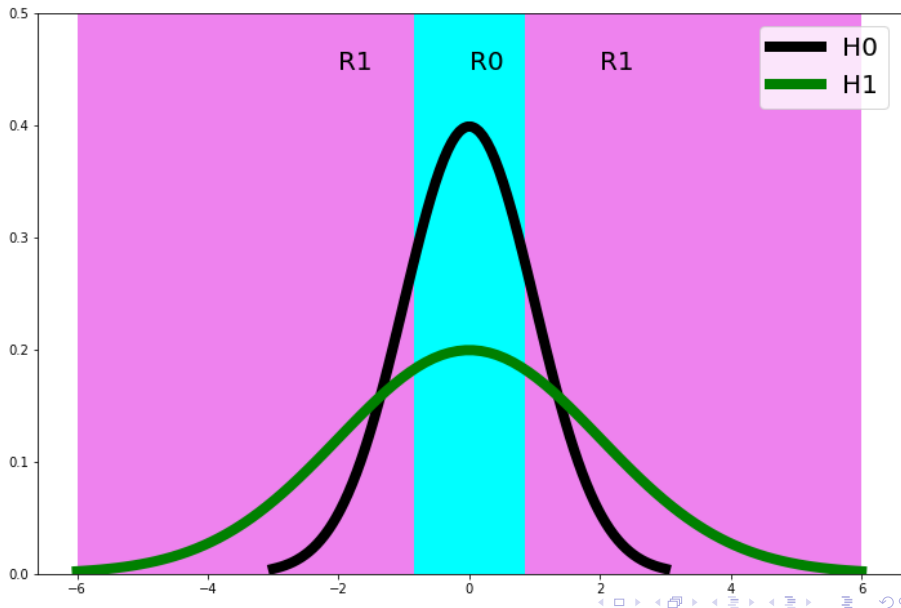
## Given Parameter substitution

- Calculated  $\gamma^1 = 0.7083263008007937$
- Calculated  $P_D = 0.8333513498891151$

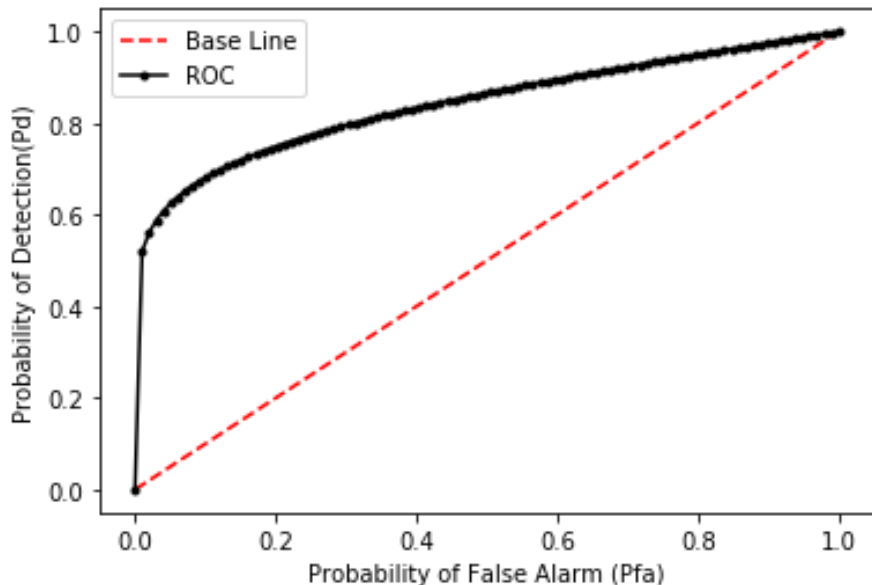
## Testing given Sample Points

- We accept Hypothesis  $H_1$  when  $|x[0]| > \sqrt{\gamma^1}$  else accept Hypothesis  $H_0$
- So sample 0.5 belongs to  $H_0$ . (Accepting Null Hypothesis).
- So sample 1 belongs to  $H_1$ . (Rejecting Null Hypothesis).
- So sample -3 belongs to  $H_1$ . (Rejecting Null Hypothesis).

# Looking Graphically



# Receiver Operating Characteristics (ROC)



# Neyman Pearson Detector for detection of variance

## Real Case Scenario 2: Problem Statement

There are two air crafts present in space and there is a base station present on earth. There is a condition that only one of the two air crafts will be in the region specified by the base station. If **aircraft ①** is present, it sends  $N=1000$  samples from normally distributed distribution with mean 0 and variance  $\sigma_0^2=1$  and when **aircraft ②** is present, it sends 1000 samples from same distribution but with variance  $\sigma_1^2=4$ . It is observed that at time  $t_{sec}$ , 1000 samples are detected by base station. Test which air craft is present at given time. Assume Probability of False Alarm is 0.3.

# Problem solving approach

- $H_0 : x[n] \sim \mathcal{N}(0, \sigma_0^2)$ . Null Hypothesis
- $H_1 : x[n] \sim \mathcal{N}(0, \sigma_1^2)$ . Alternative Hypothesis

By using Neyman Pearson approach,

$$L(\underline{x}) = \frac{p(\underline{x}; H_1)}{p(\underline{x}; H_0)} > \gamma,$$

$$p(\underline{x}; H_0) = \prod_{n=0}^{N-1} \frac{1}{\sqrt{2\pi\sigma_0^2}} \exp\left(\frac{-x[n]^2}{2\sigma_0^2}\right) \quad p(\underline{x}; H_1) = \prod_{n=0}^{N-1} \frac{1}{\sqrt{2\pi\sigma_1^2}} \exp\left(\frac{-x[n]^2}{2\sigma_1^2}\right)$$

Solving, we finally get  $T(\underline{x}) = \sum_{n=0}^{N-1} \frac{x[n]^2}{\sigma_0^2} > \gamma^1 \Rightarrow$  We decide  $H_1$

- $H_0 : T(\underline{x}) \sim \chi^2(N).$
- $H_1 : T(\underline{x}) \sim \Gamma(k = N/2, \theta = 2 * \frac{\sigma_1^2}{\sigma_0^2})$  where  $k$  is the shape parameter and  $\theta$  is the scale parameter.
- $P_{FA} = \int_{R_1: T(\underline{x}) > \gamma^1} p(T(\underline{x}); H_0) d\underline{x} = \alpha = 0.3.$  So  $\gamma^1$  is  $\chi^2_{N,\alpha}$
- $P_D = \int_{R_1: T(\underline{x}) > \gamma^1} p(T(\underline{x}); H_1) d\underline{x}$

## Testing Hypothesis

- Reject  $H_0$  when :  $T(\underline{x}) > \chi^2_{N,\alpha}$
- So we compute  $T(\underline{x})$  from the samples from aircraft and compare with  $\chi^2_{N,\alpha}$  to test hypothesis.

# Numerical Calculations

## Solved Numericals

- Calculated  $\chi^2_{N,\alpha}$  is 1022.9598734718893
- Calculated  $P_D$  is 1.0 for a given  $P_{FA}=0.3$

## Testing Given Samples

- For testing purpose I generated 1000 random samples from normal distribution of mean 0 and standard Deviation 2.
- Calculated test statistic value is 3814.087438239313.
- So we reject Null Hypothesis and Accept Alternative hypothesis  $H_1$ .

# Looking Graphically

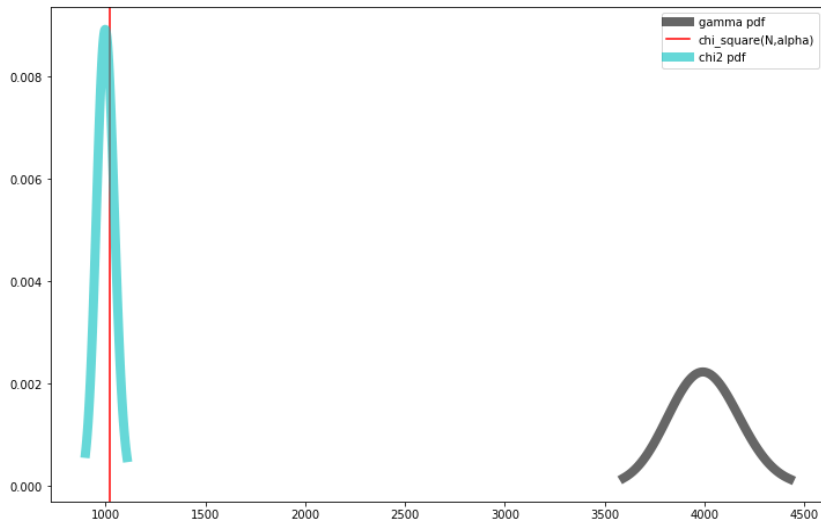


Figure: Regions H1 and H0; H0 is chi2 H1 is gamma



# Receiver Operating Characteristics

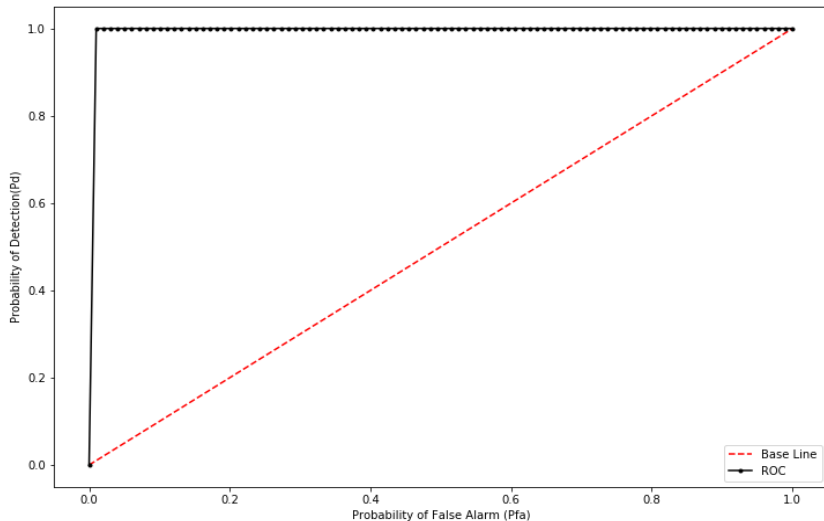


Figure: ROC curve

## Applications

- Useful in electronics engineering, namely in the design and use of radar systems, digital communication systems, and in signal processing systems
- Economics of land value (the land parcel with the largest utility, whose price is at most his budget).
- Applied to the construction of analysis-specific likelihood-ratios.

# References



Steven M. Kay *Fundamentals of statistical signal processing Volume-II Detection theory*



Wikipedia *Neyman–Pearson lemma*

Thank you