



SAIR

Spatial AI & Robotics Lab

CSE 473/573-A

L12: RANSAC

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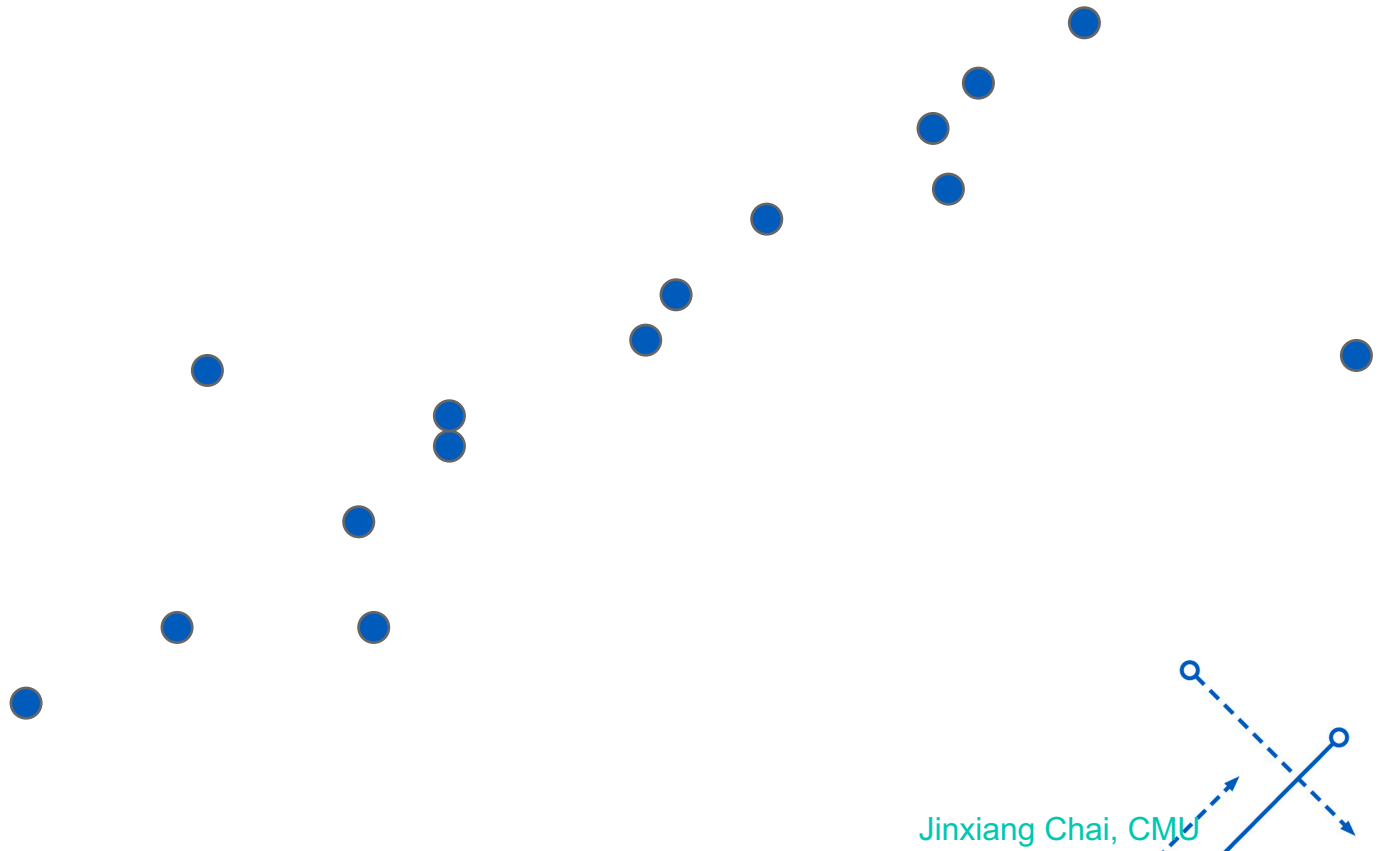
Spatial AI & Robotics Lab

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 **University at Buffalo** The State University of New York

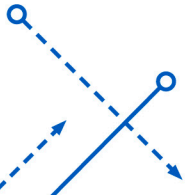
Problem: Line Fitting

- Not all data may be representative
- There may be “outliers”
- If you use them, your result may not be accurate



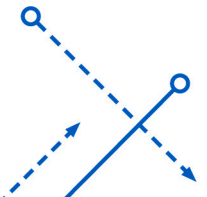
Solutions?

- Least Squares Fit?
 - Closed form solution...
 - Sensitive to outliers
- Hypothesize and Test
 - Try out as many lines as we want
 - Keep the best lines
 - But which are the best?



RANSAC

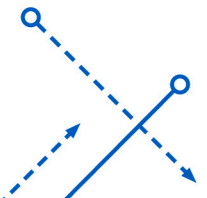
- **RAN**dom **S**ample **C**onsensus
 - An iterative method for estimating a mathematical model from a data set that contains outliers.
- Motivation: we want to avoid the impact of outliers, so let's look for “inliers”, and use those only.
- Idea: if an outlier is chosen to compute the current model, then the model won't have much support from rest of the points.



RANSAC

RANSAC loop:

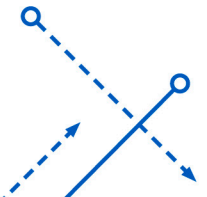
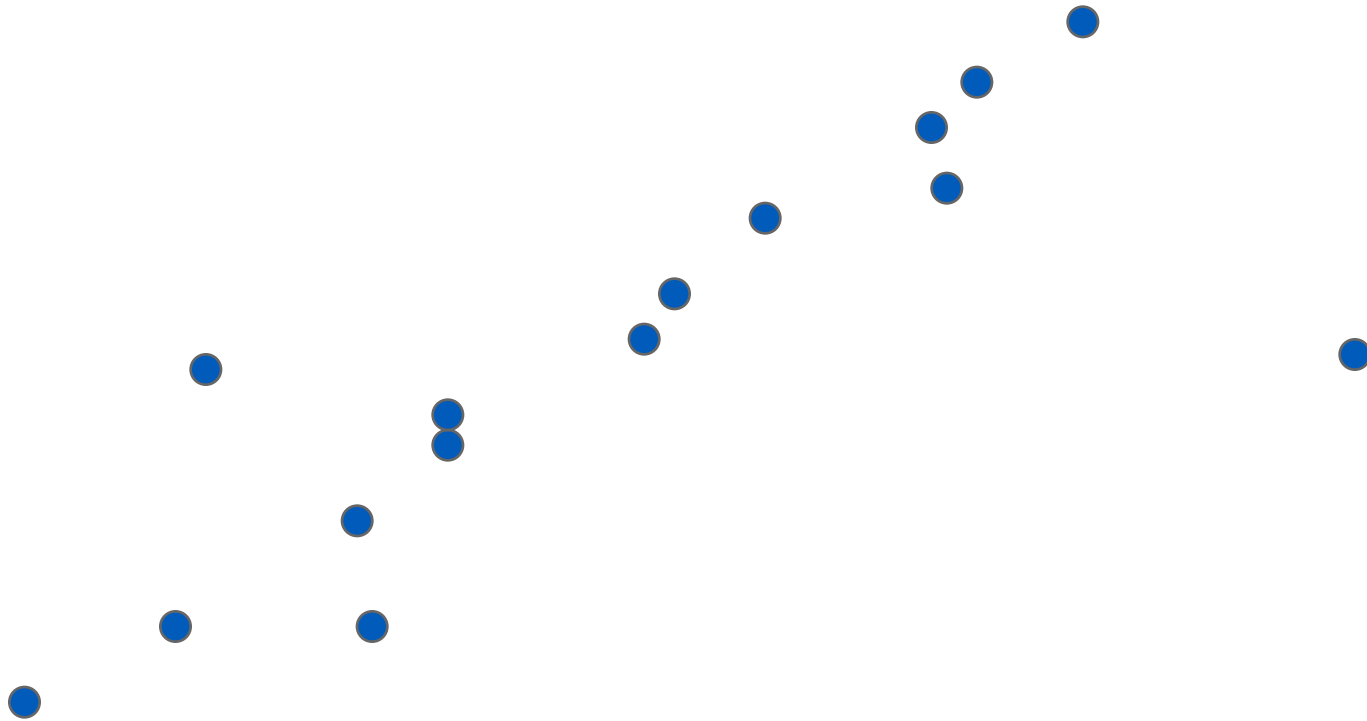
1. Randomly select a **seed group** of points on which to base transformation estimate (e.g., a group of matches)
 2. Compute transformation (**model**) from seed group
 3. Find **inliers** to this transformation
 4. If the number of inliers is sufficiently large, re-compute least-squares estimate on all inliers.
- Keep the model with the **largest number of inliers**.



RANSAC Line Fitting Example

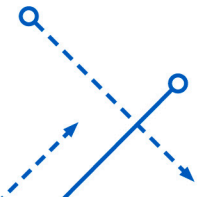
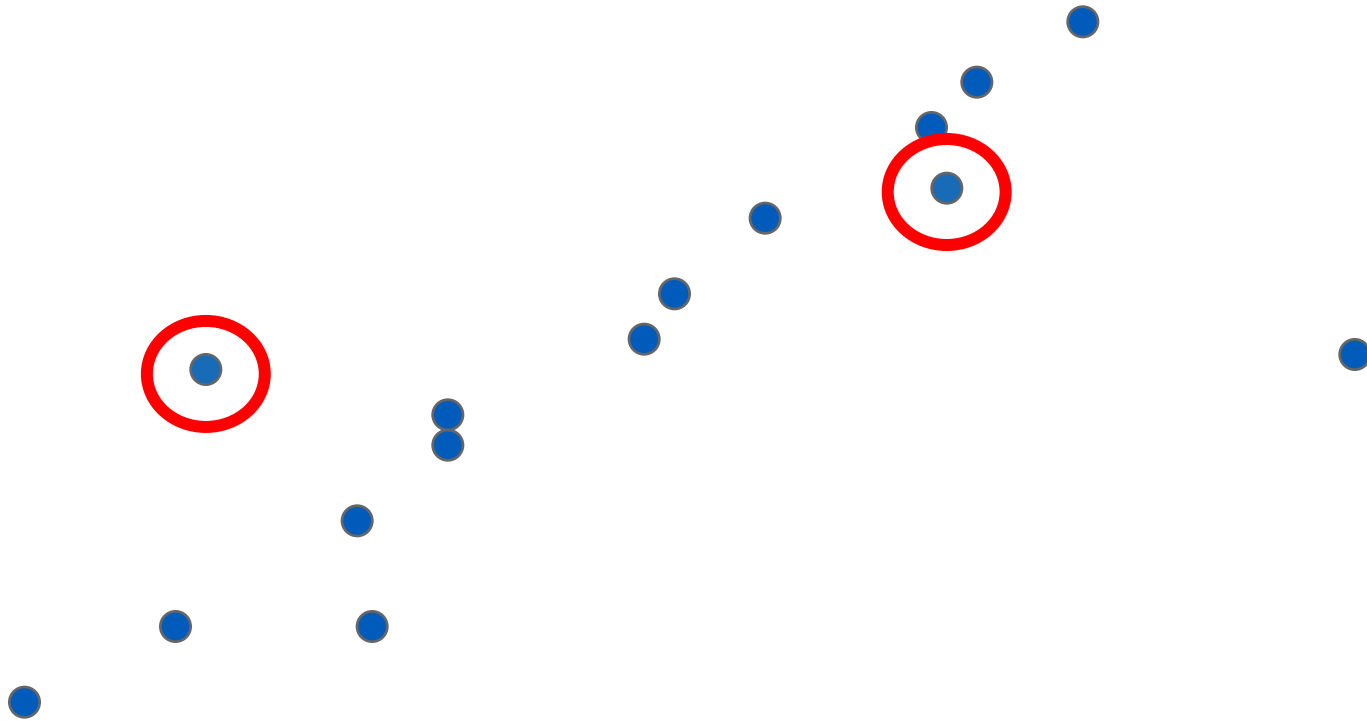
Task:

Estimate best line



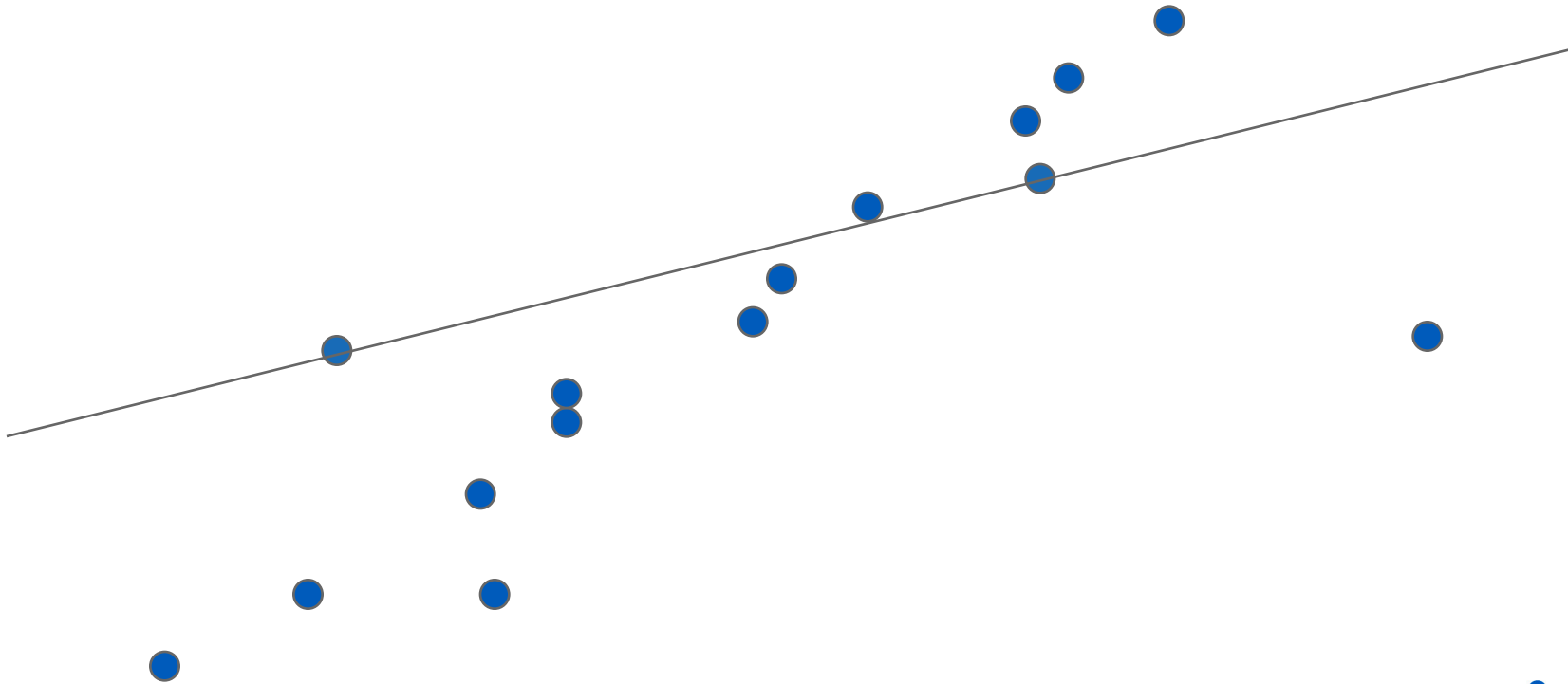
RANSAC Line Fitting Example

Sample two points



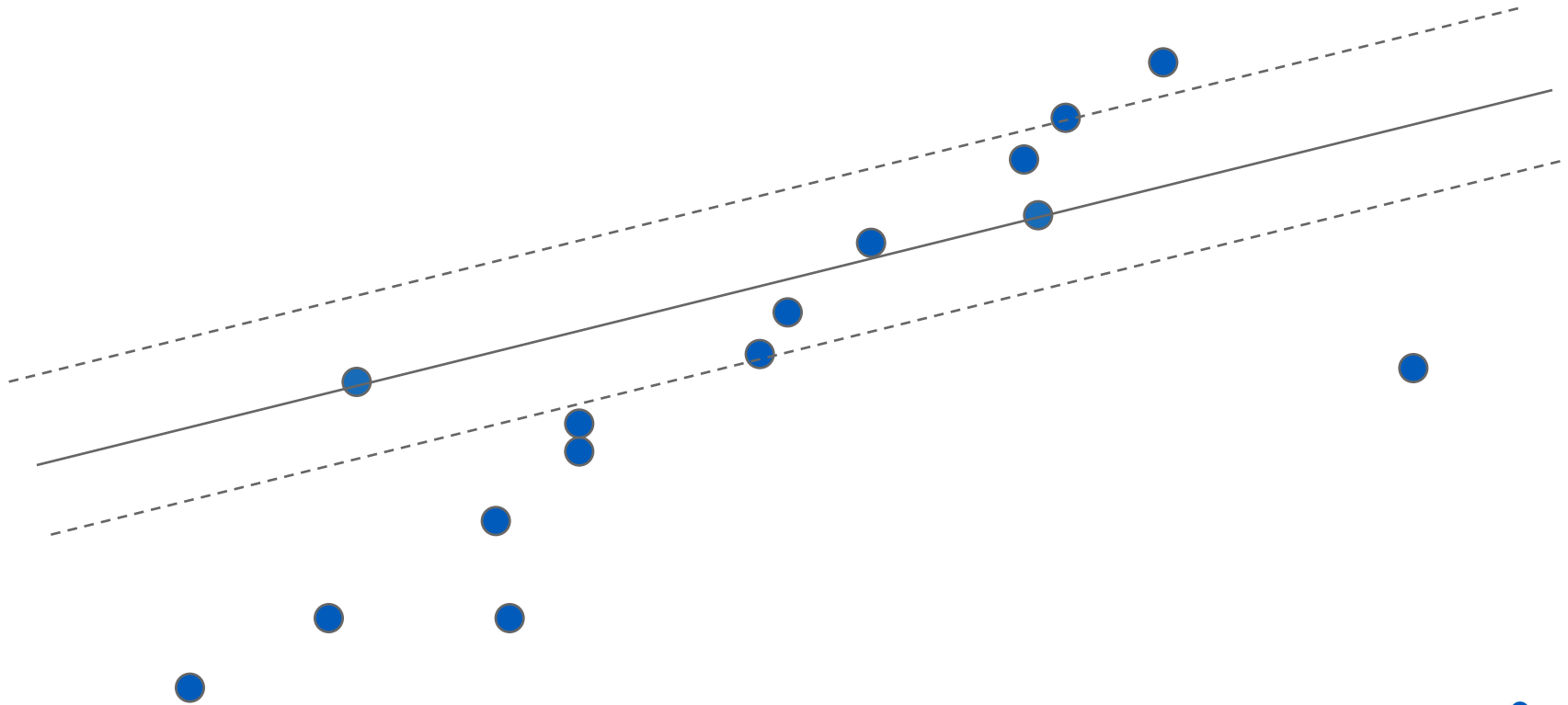
RANSAC Line Fitting Example

Fit Line



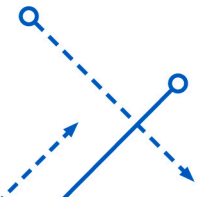
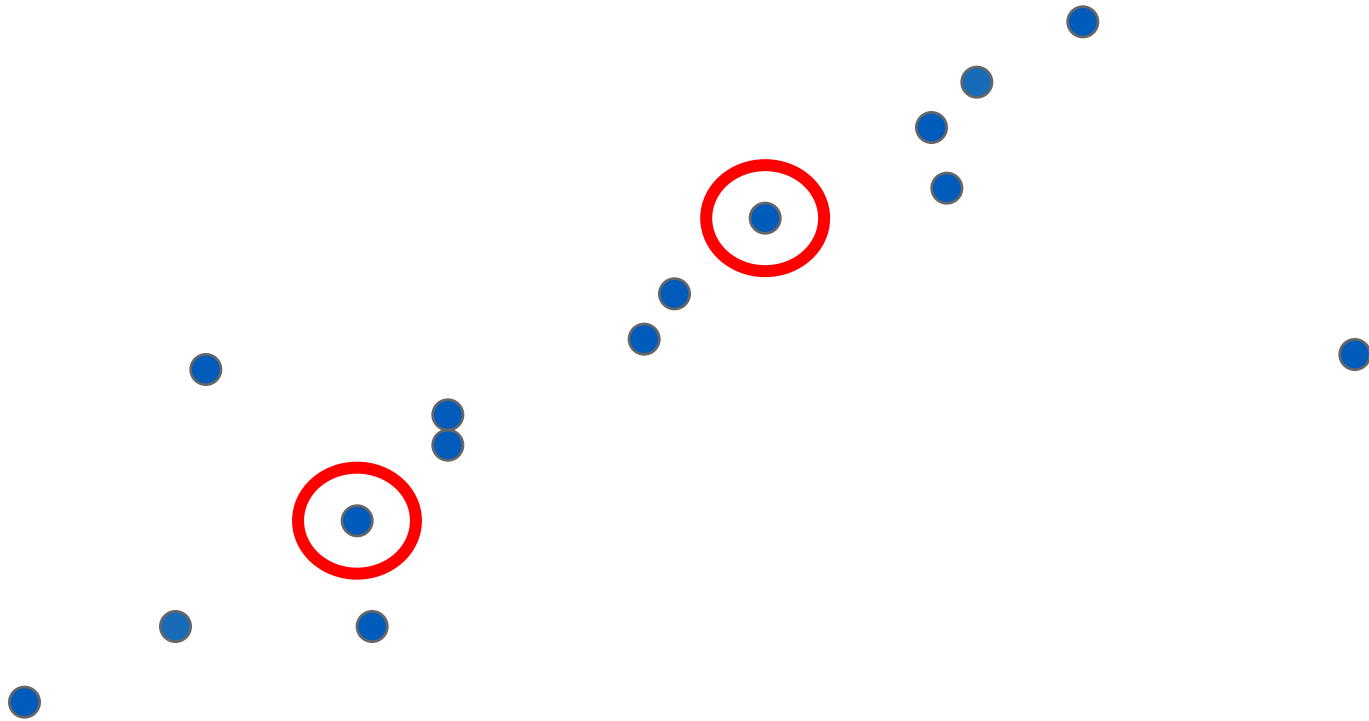
RANSAC Line Fitting Example

Total number of points within a threshold of line.



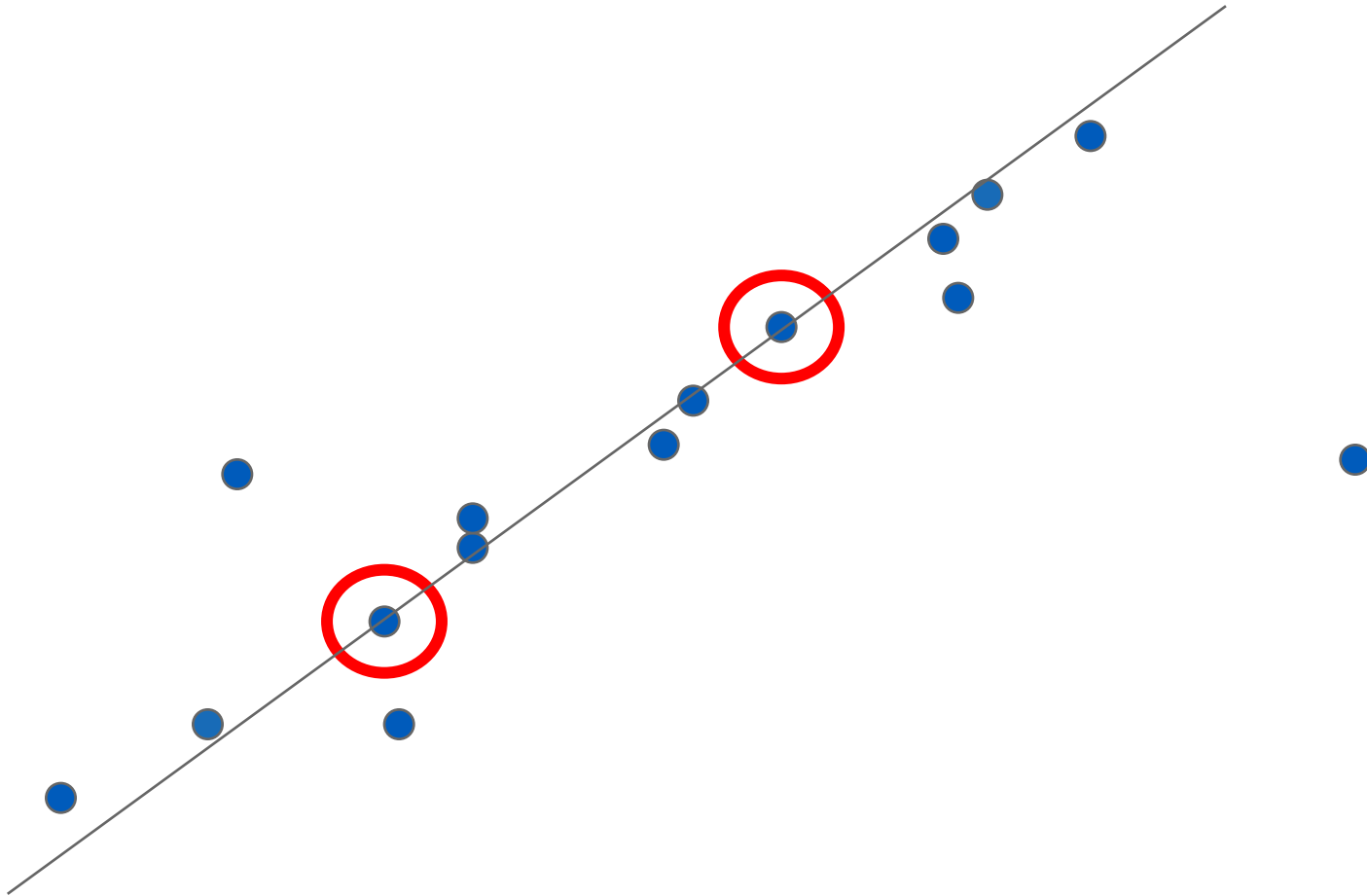
RANSAC Line Fitting Example

Repeat, until get a good result



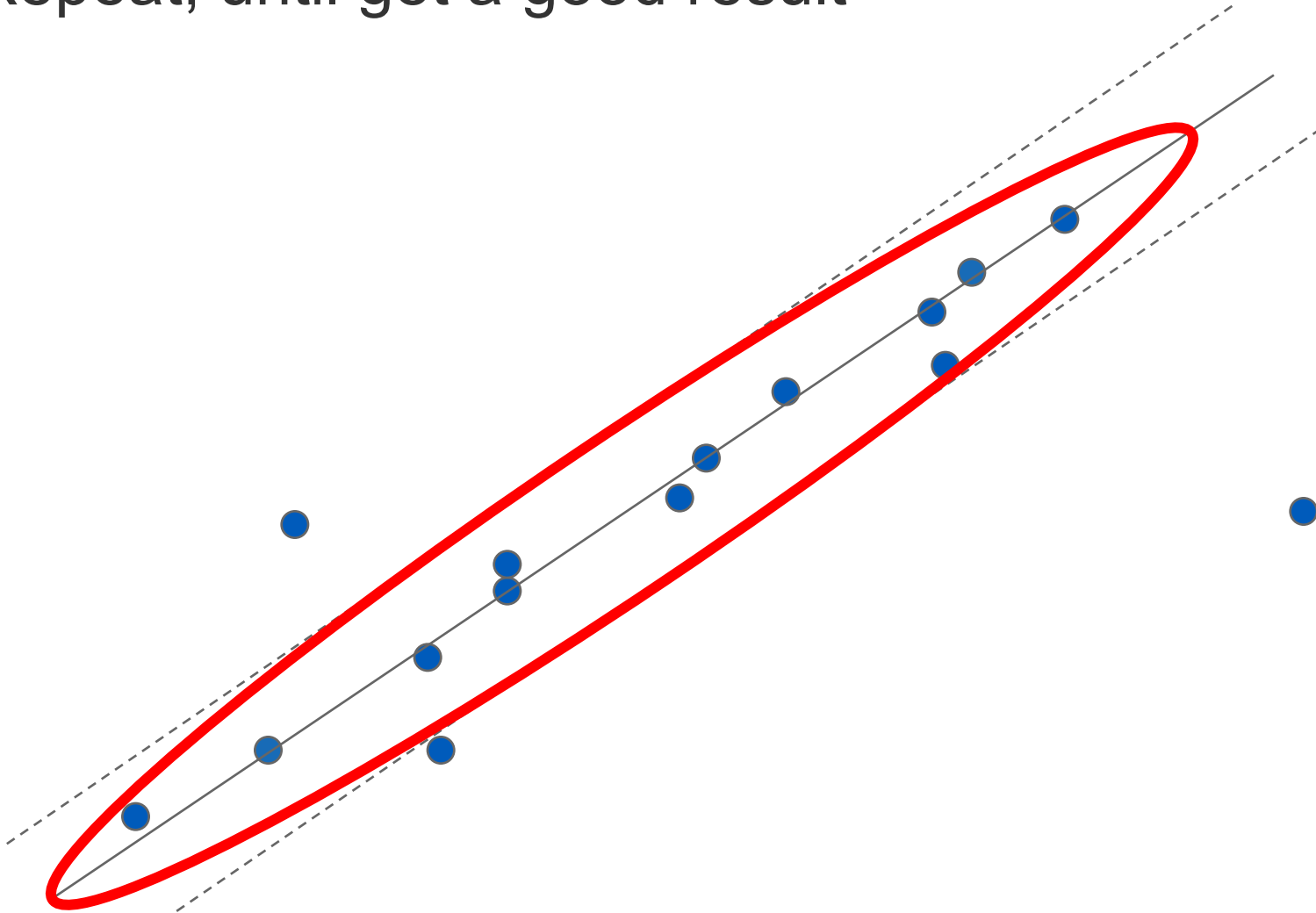
RANSAC Line Fitting Example

Repeat, until get a good result



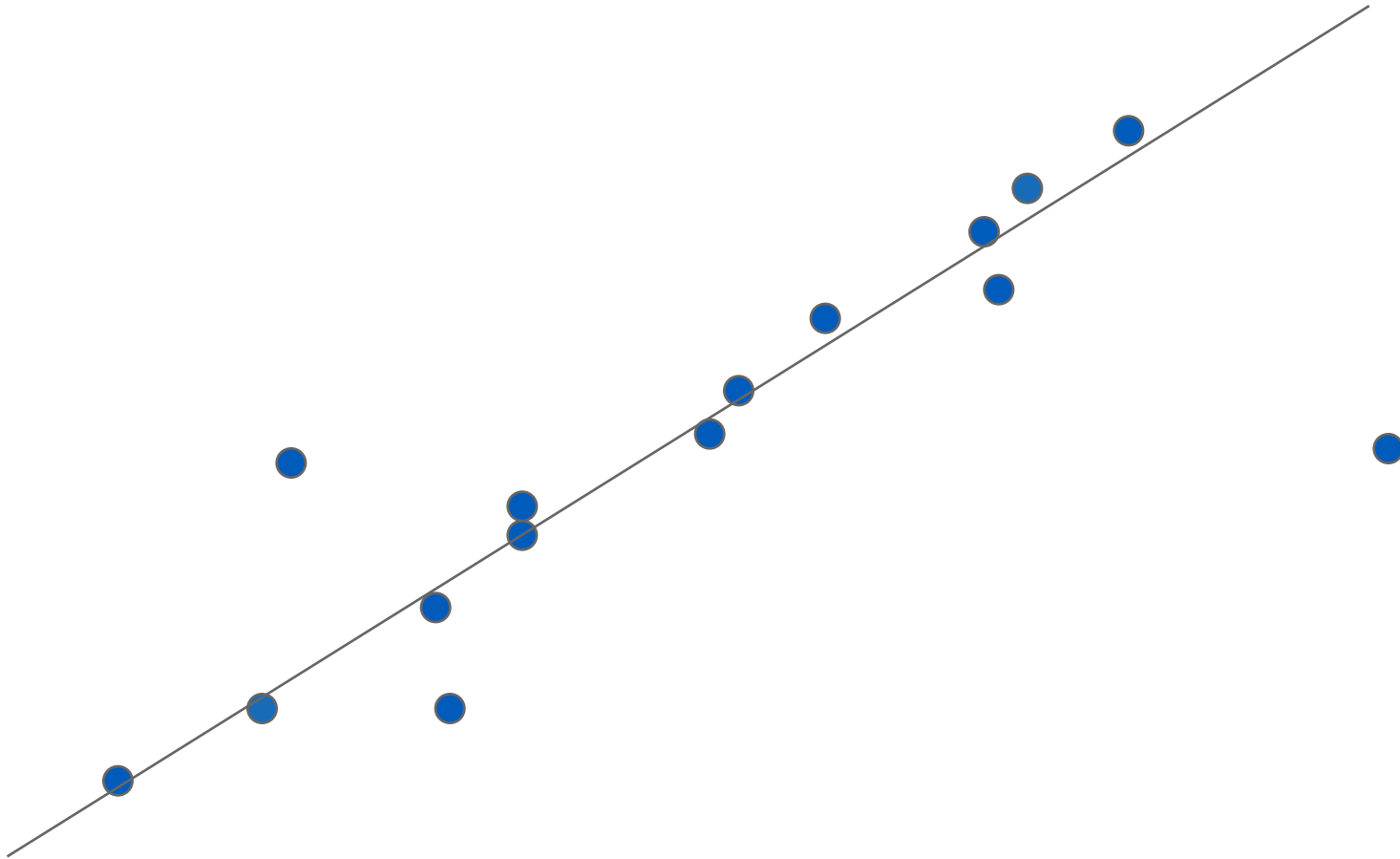
RANSAC Line Fitting Example

Repeat, until get a good result



RANSAC Line Fitting Example

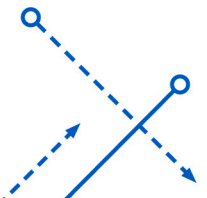
Repeat, until get a good result



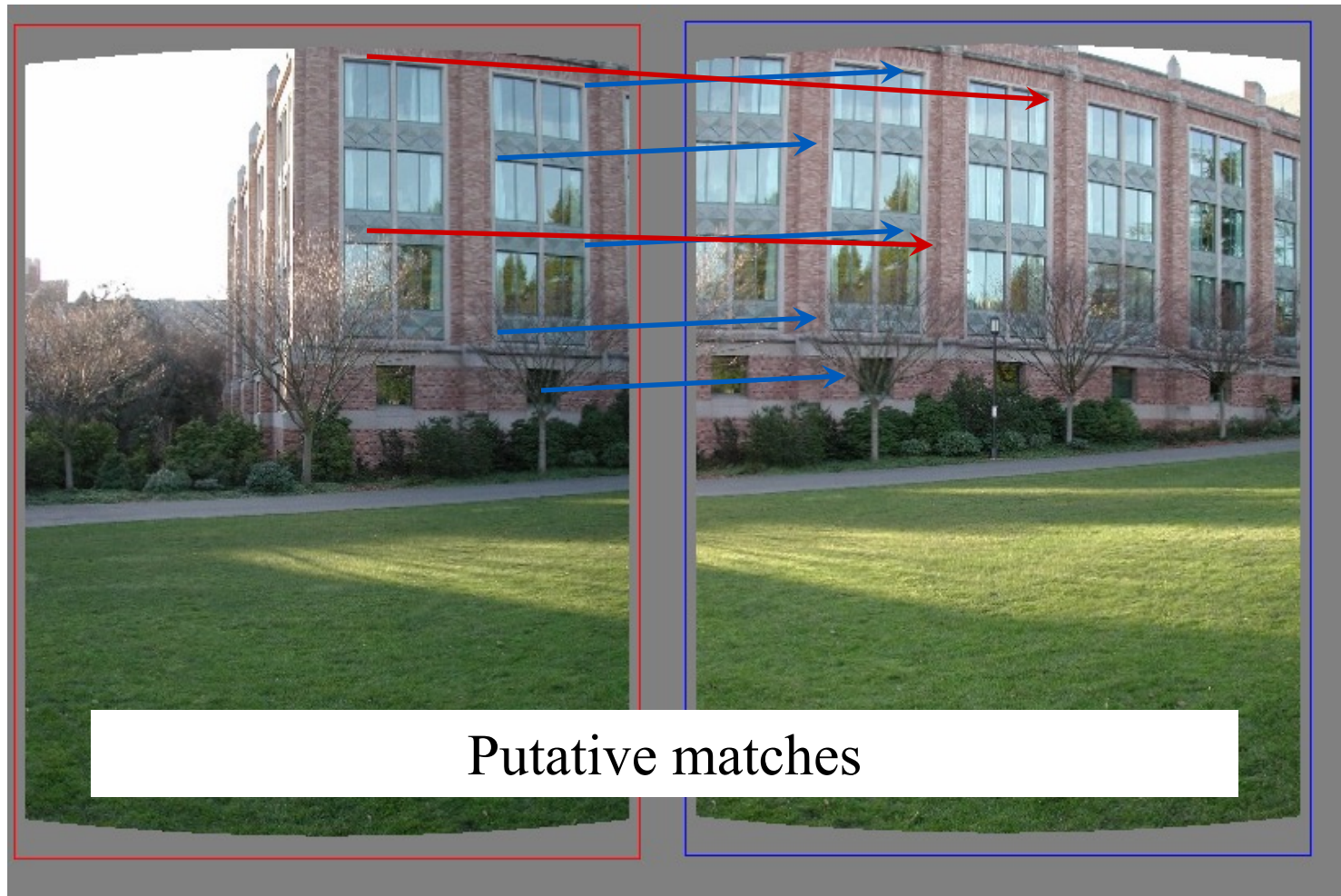
How to choose parameters?

- Number of sampled points n : minimum points to fit a model.
- Inlier threshold δ .
 - Choose δ so that a good point with noise is likely within threshold.
- To determine the number of iterations K .
 - Desired probability of success (p): at least one useful result.
 - Let w be the probability of choosing an inlier when selecting a point.
 - w = number of inliers in data / number of points in data
 - n points selected independently for estimating a model.
 - w^n : the probability that all n points are inliers.
 - $1 - w^n$: probability of at least one of the n points is an outlier.
 - $(1 - w^n)^k$: after k iterations, never select a set of n inlier points.
 - $1 - p = (1 - w^n)^K$
 - $K = \frac{\log(1-p)}{\log(1-w^n)}$

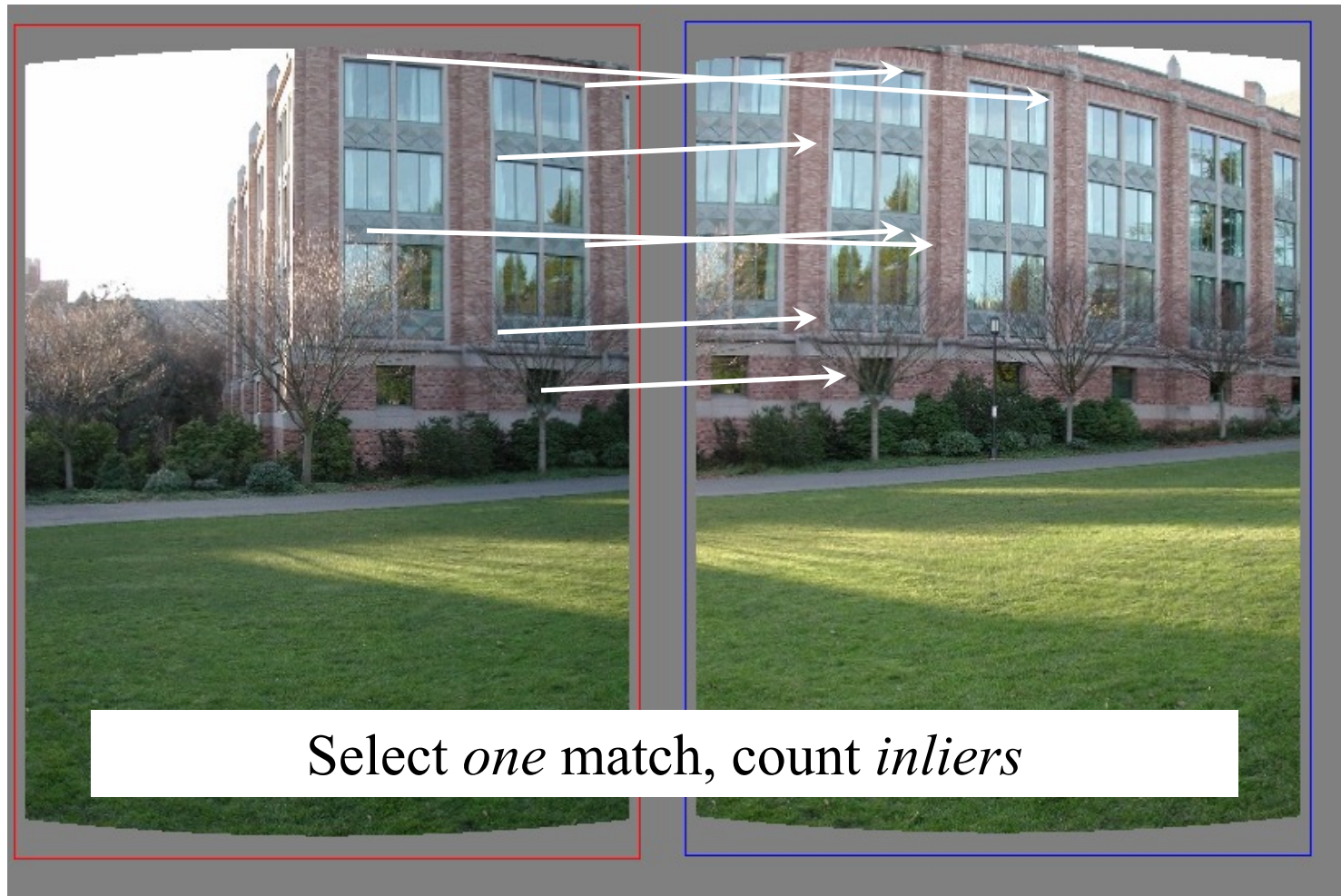
$p = 0.99$, proportion of outliers $(1 - w)$							
n	5%	10%	20%	25%	30%	40%	50%
2	2	3	5	6	7	11	17
3	3	4	7	9	11	19	35
4	3	5	9	13	17	34	72
5	4	6	12	17	26	57	146
6	4	7	16	24	37	97	293
7	4	8	20	33	54	163	588
8	5	9	26	44	78	272	1177



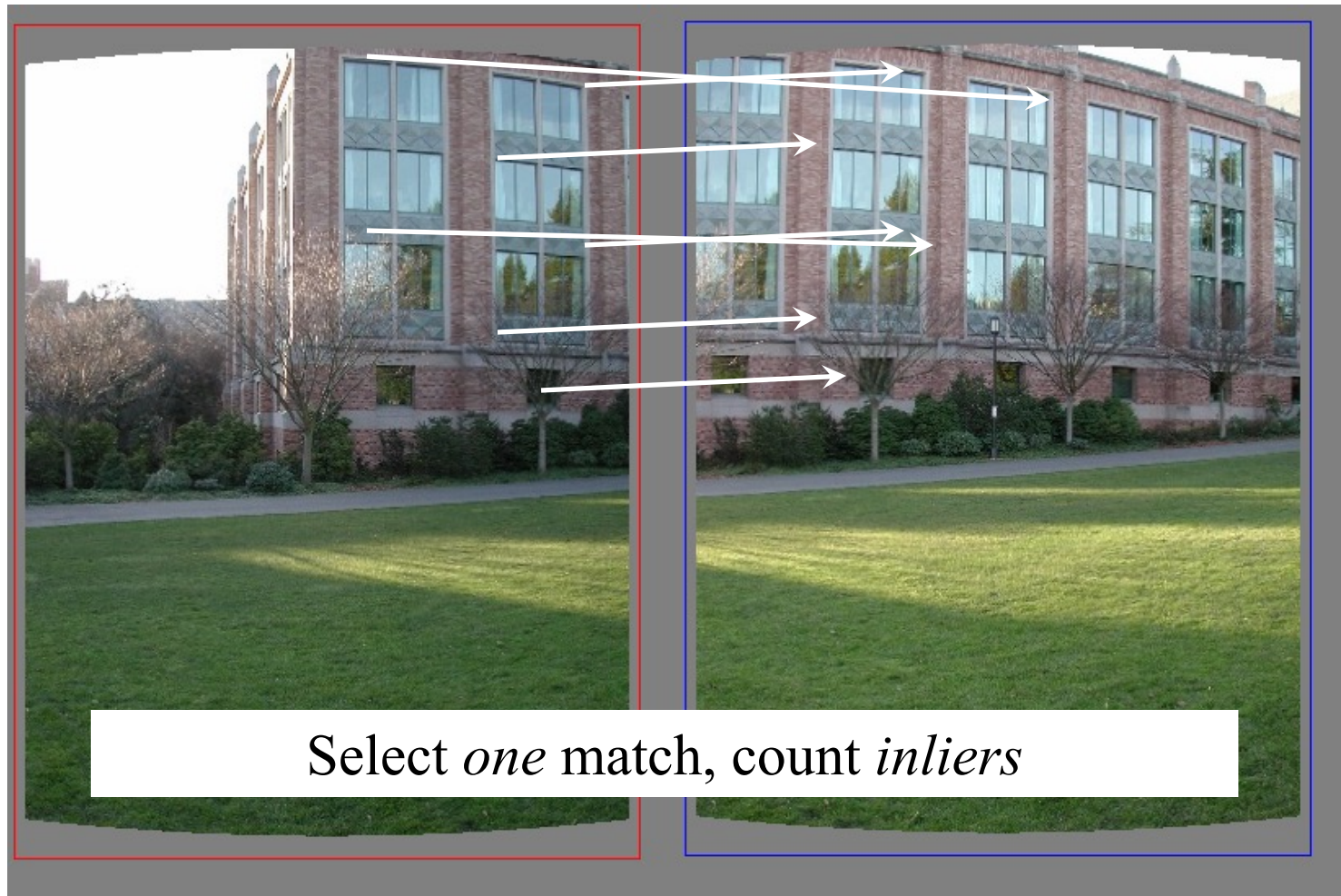
RANSAC example: Translation



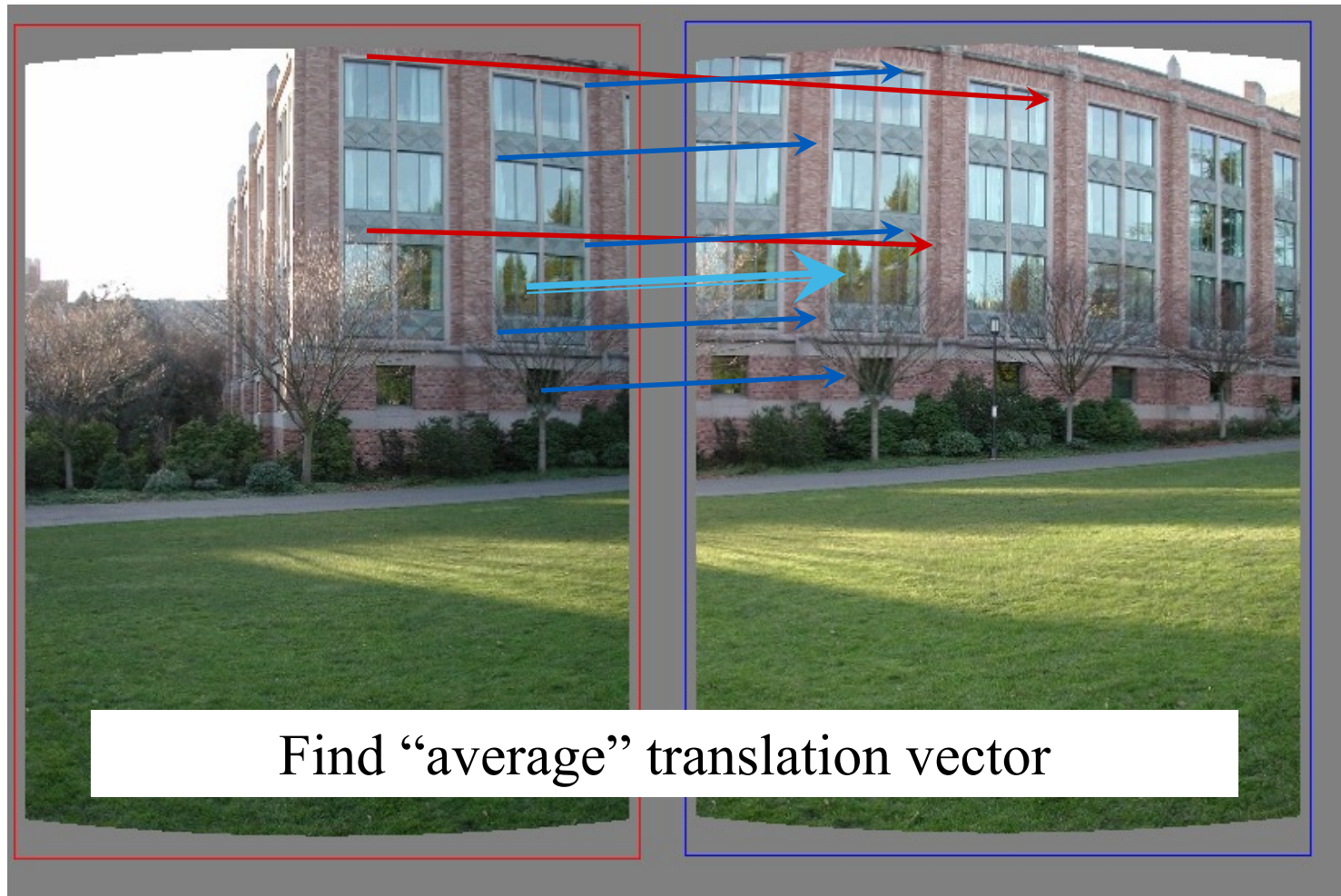
RANSAC example: Translation



RANSAC example: Translation

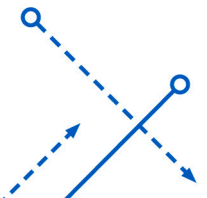


RANSAC example: Translation



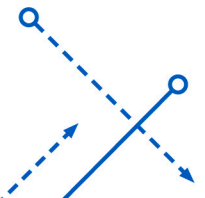
Summary

- Choose:
 - Inlier threshold
 - Related to the amount of noise we expect
 - Number of rounds
 - Related to the percentage of outliers we expect
 - Related to the probability of success we are hoping for.



RANSAC ALGORITHM

- Input:
 - Data: a set of observed data points
 - Model: a model to fit the data
 - Threshold: a threshold to determine inliers
- Output: BestModel: the model with the most inliers
- Repeat for a fixed number of iterations:
 - 1. Select a random subset of data
 - 2. Fit the model to the data points in the subset
 - 3. Determine the inliers by comparing the fitted model to data
 - 4. If the number of inliers exceeds the threshold
 - re-estimate the model using all the inliers
 - 5. Store the model if it has the most inliers seen so far
- Return BestModel



RANSAC Algorithm

Given:

- data – A set of observations.
- model – A model to explain the observed data points.
- n – The minimum number of data points required to estimate the model parameters.
- k – The maximum number of iterations allowed in the algorithm.
- t – A threshold value to determine data points that are fit well by the model (inlier).
- d – The number of close data points (inliers) required to assert that the model fits well to the data.

Return:

- bestFit – The model parameters which may best fit the data (or null if no good model is found).

```
iterations = 0
bestFit = null
bestErr = something really large // This parameter is used to sharpen the model parameters to the best data fitting as iterations goes on.
```

```
while iterations < k do
```

```
    maybeInliers := n randomly selected values from data
    maybeModel := model parameters fitted to maybeInliers
```

```
    confirmedInliers := empty set
```

```
    for every point in data do
```

```
        if point fits maybeModel with an error smaller than t then
            add point to confirmedInliers
```

```
        end if
```

```
    end for
```

```
    if the number of elements in confirmedInliers is > d then
```

```
        // This implies that we may have found a good model.
```

```
        // Now test how good it is.
```

```
        betterModel := model parameters fitted to all the points in confirmedInliers
```

```
        thisErr := a measure of how well betterModel fits these points
```

```
        if thisErr < bestErr then
```

```
            bestFit := betterModel
```

```
            bestErr := thisErr
```

```
        end if
```

```
    end if
```

```
    increment iterations
```

```
end while
```

```
return bestFit
```


RANSAC Properties

Good

- Robust to outliers
- Applicable for larger number of model parameters than Hough transform.
- Optimization parameters are easier to choose than Hough transform.
 - Lines with normal form works for Hough, but slope-intercept form not.

Bad

- Computational time grows quickly with outliers and parameters
 - While Hough transform grows quickly with number of parameters.
- Not good for getting multiple fits
 - Hough transform can fit multiple lines simultaneously.

More applications

- Computing a homography (e.g., image stitching)
- Estimating fundamental matrix (relating two views)

