SAQIB UR REHMAN BCSF20A510

ASSIGNMENT NO. 2 COMPUTER VISION

Question No 1:

(a)

```
function f = Gaussian_Generator(w,sigma)
  s = 2 *sigma*sigma;% 2 sigma square
  GKernel = zeros(w,w);
  low = floor(w/2);
  for i = -low:low
    for j = -low : low
      r = sqrt(i*i+j*j);
      GKernel(i+low+1,j+low+1) = ((exp(-(r*r)/s))/(3.14 * s));
    end
  end
  f = (GKernel);
End
Input:
a = imread('im_q1.tif');
b = Gaussian_Generator(3,1);
c = conv2(a,b);
imshow(uint8(a));
(b)
     9x9
 0 0 0
          0 0
                   0 0 0 0
    0 0 0
  0
               0
                  0 0 0 0
  0 0 1 3
             5
                 3 1
                         0 0
  0 0 3 15 25 15 3 0 0
  0 0 5 25 41 25 5 0 0
  0 0 3 15 25 15 3 0 0
  0 0 1 3
               5
                  3 1 0 0
  0 0 0 0
               0 0 0 0 0
```

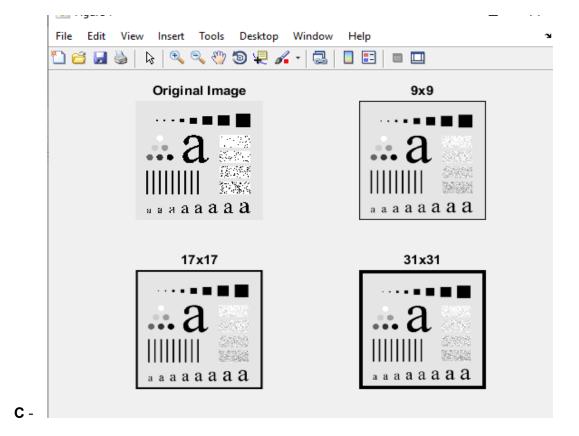
 $0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0$

17 x 17

15 25 5 25 3 15 25

31 x 31

Very large matrix to show here.



Question No 2:

(a)

Both the above filters are linear because we know that any filter that performs sliding sum of products with the image pixels and they involve derivatives are linear.

(b)

The gradient of an image **measures how it is changing**. It provides two pieces of information. The magnitude of the gradient tells us how quickly the image is changing, while the direction of the gradient tells us the direction in which the image is changing most rapidly. We will observe no change in the output if gradient filter is applied first And then averaging filters.

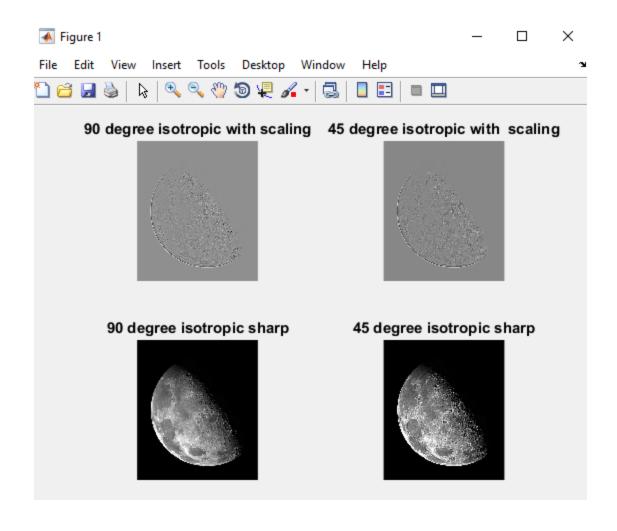
(c) _

The S filter can be obtained by multiplying the B and G and then adding G to the result . Then, the resultant matrix will be a sobel filter which finds derivatives in x direction.

Question No 3:

```
(A) (B) and (C) part
img = imread('im q3.tif');
img = double(img);
lap_filter_90 = [0 1 0; 1 - 4 1; 0 1 0];
lap filter 45 = [1 \ 1 \ 1; 1 \ -8 \ 1; 1 \ 1 \ 1];
unscaled result1 = conv2(img,lap filter 90,'same');
unscaled result2 = conv2(img,lap filter 45,'same');
% perform scaling of result 1
min value = min(result1(:));
result1 = result1 - min value;
% now normalize
max value = max(result1(:));
result1 = result1./max value;
result1 = result1 * 255;
% perform scaling of result 2
min value1 = min(result2(:));
result2 = result2 - min value1;
% now normalize
max value1 = max(result2(:));
result2 = result2./max_value1;
result2 = result2 * 255;
%Now sharpen result 1 & result2
sharp image1 = img - unscaled result1;
sharp image2 = img - unscaled result2;
subplot(2,2,1);imshow(uint8(result1));title('90 degree isotropic with scaling');
subplot(2,2,2);imshow(uint8(result2));title('45 degree isotropic with scaling');
subplot(2,2,3);imshow(uint8(sharp image1));title('90 degree isotropic sharp');
subplot(2,2,4);imshow(uint8(sharp image2));title('45 degree isotropic sharp');
```

Output:



Original Image:



END OF ASSIGNMENT